## Orientability of product smooth manifolds

Marc Fares Stefano Rocca

University of Bonn

Lean Project, January 2025

## Table of Contents

Orientability of smooth manifolds

Main theorem

## Orientation of vector spaces

Let V be a real finite-dimensional vector space, and  $\mathcal{B}$  and  $\mathcal{B}'$  two (ordered) bases of V. There exists a unique linear map

$$f: V \rightarrow V$$

sending  $\mathcal{B}$  to  $\mathcal{B}'$  and its associated matrix  $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(f)$  is the usual **change-of-basis matrix**.

#### Definition

 $\mathcal{B}$  and  $\mathcal{B}'$  are said to be **coherently oriented** if  $det \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(f) > 0$ .

This induces an equivalence relation

$$\mathcal{B} \sim \mathcal{B}' \iff \mathcal{B} \text{ and } \mathcal{B}' \text{ are coherently oriented.}$$

- $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}} = id_n$  (reflexivity)
- ullet  $\mathcal{M}^{\mathcal{B}}_{\mathcal{B}'}=(\mathcal{M}^{\mathcal{B}'}_{\mathcal{B}})^{-1}$  (symmetry)
- $\bullet \ \mathcal{M}_{\mathcal{B}}^{\mathcal{B}''} = \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}''} \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'} \ (\mathsf{transitivity})$

And this gives two equivalence classes on the set of bases of V.

#### Definition

An orientation for V is the choice of one such equivalence class.  $(V, [\mathcal{B}])$  is an **oriented vector space**.

In the same vein, given two oriented vector spaces of the same dimension,  $(V, [\mathcal{B}_V])$  and  $(W, [\mathcal{B}_W])$ .

#### **Definition**

A linear map  $f:V\to W$  is said to be **orientation preserving** if  $detF_{\mathcal{B}_{V}}^{\mathcal{B}_{W}}>0$  and **orientation reversing** if  $detF_{\mathcal{B}_{V}}^{\mathcal{B}_{W}}<0$ .

# Orientation and smooth maps in $\mathbb{R}^n$

Let  $\alpha: U \subseteq \mathbb{R}^n \to V \subseteq \mathbb{R}^n$ . This induces a linear map on tangent spaces at each point  $p \in U$ ,

$$d_p\alpha:T_pU\to T_{\alpha(p)}V$$

called the differential of  $\alpha$  at p.

Now, choosing a base for  $T_pU$  and  $T_{\alpha(p)}V$ , the matrix associated to  $d_p\alpha$  is  $Jac_p(\alpha)$  and it is called the **Jacobian matrix** of  $\alpha$  at p.

#### Definition

We say that  $\alpha$  is orientation preserving (resp. reversing) at p if  $detJac_p(\alpha)>0$  (resp.  $\alpha$  is orientation preserving (resp. reversing) if it is so at every  $p\in U$ .

## Orientation of smooth manifolds

Let M be a (nice) topological space.

#### Definition

A **oriented smooth atlas**  $\mathcal{A}^o$  on M is a collection of charts  $(U_i, \varphi_i : U_i \to V_i \subseteq \mathbb{R}^n)$  such that:

- each  $\varphi_i$  is an homeomorphism.
- $\forall p \in M$ ,  $\exists (U_i, \varphi_i)$  such that  $p \in U_i$ .
- $\forall (U_i, \varphi_i), (U_j, \varphi_j)$  there are smooth transition maps

$$\varphi_i \circ \varphi_j^{-1} : \varphi_j(U_i \cap U_j) \to \varphi_i(U_i \cap U_j)$$

•  $detJac(\varphi_i \circ \varphi_j^{-1}) > 0$  i.e. the transition maps are orientation preserving.

We call  $(M, A^o)$  an oriented smooth manifold.



### Main theorem

We are ready to state the theorem we proved in our project:

#### Theorem

Let M and N be two oriented smooth manifolds of dimension m and n respectively. Then  $M \times N$  is a oriented smooth manifold of dimension n+m.

# **Proof strategy**

We have to show that  $\mathcal{A}_M \times \mathcal{A}_N := \{ \varphi_i \times \psi_j : U_i \times V_j \to \mathbb{R}^m \times \mathbb{R}^n \}$  is an oriented smooth atlas.

- $\varphi_i \times \psi_j$  are homeomorphisms because are componentwise homeomorphisms.
- Any point  $(p, q) \in M \times N$  is covered by charts, since p is covered in  $A_M$  and q is covered in  $A_N$ .
- Transition functions are smooth since  $(\varphi \times \psi) \circ (\varphi' \times \psi')^{-1} = (\varphi \circ \varphi'^{-1}) \times (\psi \circ \psi'^{-1})$  which is componentwise smooth.

Hence  $A_M \times A_N$  is a smooth atlas.



 $\mathcal{A}_M \times \mathcal{A}_N$  is also oriented.

•  $d_{(p,q)}(\varphi \circ \varphi'^{-1} \times \psi \circ \psi'^{-1}) : \mathbb{R}^m \times \mathbb{R}^n \to \mathbb{R}^m \times \mathbb{R}^n$  gives that

$$Jac_{(p,q)}((\varphi \circ \varphi'^{-1}) \times (\psi \circ \psi'^{-1})) = \begin{pmatrix} Jac_p(\varphi \circ \varphi'^{-1}) & 0 \\ 0 & Jac_q(\psi \circ \psi'^{-1}) \end{pmatrix}$$

•  $det \begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix} = detA \cdot detB$  hence

$$\begin{aligned} & \det Jac_{(p,q)}((\varphi \circ \varphi'^{-1}) \times (\psi \circ \psi'^{-1})) = \\ & = \det Jac_p(\varphi \circ \varphi'^{-1}) \cdot \det Jac_q(\psi \circ \psi'^{-1}) > 0 \end{aligned}$$



10 / 10

Fares, Rocca Orientability of the product Jan '25