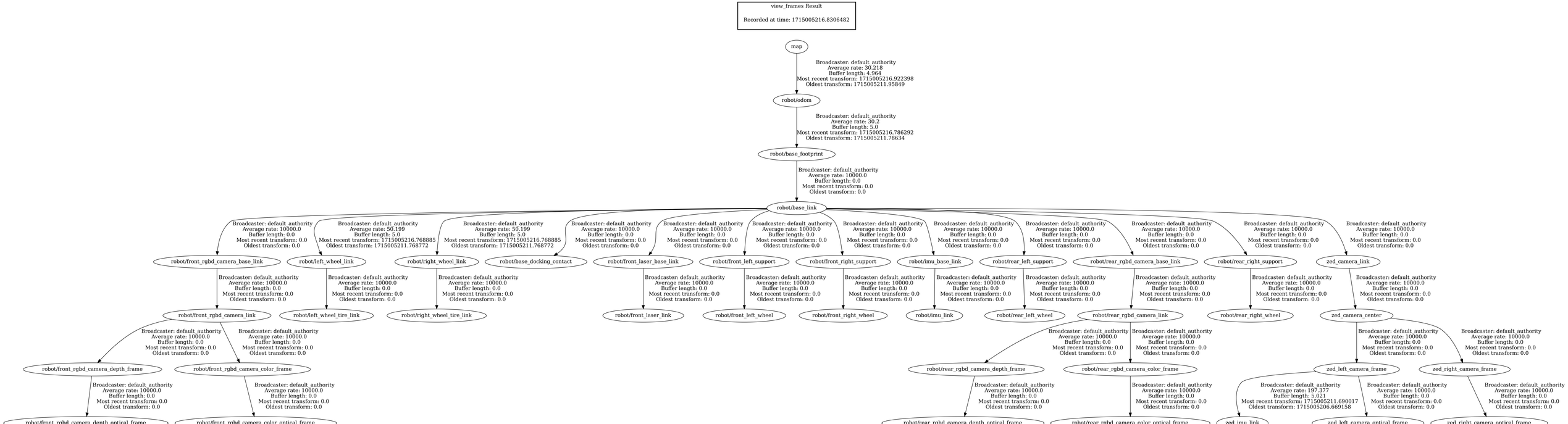
view_frames Result
Recorded at time: 1715005216.8306482
map
Broadcaster: default_authority
Average rate: 30.218
Buffer length: 4.964
Most recent transform: 1715005216.922398
Oldest transform: 1715005211.95849
robot/odom
Broadcaster: default_authority
Average rate: 30.2
Buffer length: 5.0
Most recent transform: 1715005216.786292
Oldest transform: 1715005211.78634
robot/base_footprint
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
robot/base_link
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
robot/front_rgbd_camera_base_link
Broadcaster: default_authority
Average rate: 50.199
Buffer length: 5.0
Most recent transform: 1715005216.768885
Oldest transform: 1715005211.768772
robot/left_wheel_link
Broadcaster: default_authority
Average rate: 50.199
Buffer length: 5.0
Most recent transform: 1715005216.768885
Oldest transform: 1715005211.768772
robot/right_wheel_link
robot/base_docking_contact
robot/front_laser_base_link
robot/front_left_support
robot/front_right_support
robot/imu_base_link
robot/rear_left_support
robot/rear_rgbd_camera_base_link
robot/rear_right_support
zed_camera_link
robot/front_rgbd_camera_link
robot/left_wheel_tire_link
robot/right_wheel_tire_link
robot/front_laser_link
robot/front_left_wheel
robot/front_right_wheel
robot/imu_link
robot/rear_left_wheel
robot/rear_rgbd_camera_link
robot/rear_right_wheel
zed_camera_center
robot/front_rgbd_camera_depth_frame
robot/front_rgbd_camera_color_frame
robot/rear_rgbd_camera_depth_frame
robot/rear_rgbd_camera_color_frame
zed_left_camera_frame
zed_right_camera_frame
robot/front_rgbd_camera_depth_optical_frame
robot/front_rgbd_camera_color_optical_frame
robot/rear_rgbd_camera_depth_optical_frame
robot/rear_rgbd_camera_color_optical_frame
zed_imu_link
Broadcaster: default_authority
Average rate: 197.377
Buffer length: 5.021
Most recent transform: 1715005211.690017
Oldest transform: 1715005206.669158
zed_left_camera_optical_frame
zed_right_camera_optical_frame