



Calibration Software Package [pr-cal-3-4]

pmdtechnologies ag – 2019-05-16

Outline

- Background information
- pmd provides a complete python software package, which consists of:
 - Hardware bring-up package
 - Depth calibration package
 - iCM calibration package
 - Validation package
 - Performance analysis package
- An API is provided for the frame grabber and the linear translation stage
- Explanations for implementation are given
- Roles and Responsibilities

Background

Today situation:

- pmd / IFX gives example software to explain the functionality of the calibration steps
- The implementation is done at ODM side in building their own software scripts
 - pmd / IFX supports on implementation

New situation:

- pmd gives calibration package
- ODM only needs to implement custom frame grabber functions
 - pmd / IFX supports on implementation

Disadvantages:

- Custom frame grabber functions need to be implemented into the wrapper
 - Wrapper of the software package needs to be used

Advantages:

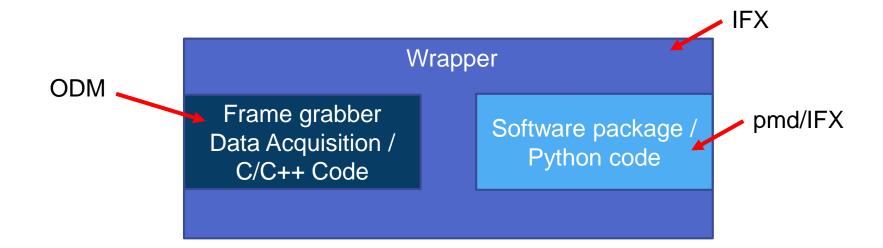
- Custom frame grabber functions need to be implemented into the wrapper
 - Functions for frame grabber need to be implemented anyhow, only small efforts to be done at ODM
- Flow and functions are written by pmd / IFX
 - No additional code writing necessary at ODM side
- Bring-up of new modules
 - Much easier as basic ODM functions most probably stay the same
- Error handling during production
 - pmd / IFX can support much better and faster as same software scripts are used
- calibration package updates:
 - Update installers are provided by pmd
 - Only installation needs to be done at ODM side
 - No code writing necessary at ODM side (except Wrapper changes)

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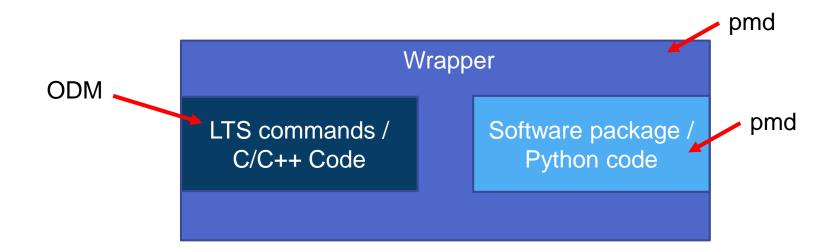
Imager configurations

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- Usage of animator wrapper
 - ODM to implement all required framegrabber functions in C/C++
 - Python software packages communicate with frame grabber via wrapper
- > ODM frame grabber functions only have to be implemented once
- Update of software package does not result in ODM/IFX/pmd efforts



- Usage of custom LTS wrapper
 - ODM to implement all required linear translation stage functions in C/C++
 - Python software packages communicate with linear translation stage via wrapper
- > ODM LTS functions only have to be implemented once
- Update of software package does not result in ODM/IFX/pmd efforts



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Software usage

- Win 7 / Win 10 pc needs to be available
- Installer for calibration package is provided by pmd
 - Information about installer will be send additionally
- Installation of Newport power meter needs to be done (iCM calibration)
- Frame grabber wrapper needs to be implemented
 - please see slide 8
- LTS wrapper needs to be implemented
 - please see slide 9
- Example executable (.bat) files are included in the package
 - Information about execution of the different sub-packages can be found later in this document

Frame grabber implementation

- Software required by ODM: Compiler (C++) and SWIG
- Header files and Swig file can be found in the software package:
 - wrapper\animator*
- According to the header files, basic functions of the frame grabber need to be written and connected to the wrapper (open, i2cwrite, i2cread, spiwrite, spiread, getnextbuffer, ...)
- After running SWIG and compilation the following files should be generated⁽¹⁾:
 - _animator.pyd (generated by Compiler)
 - animator.py (generated by SWIG)
- These files and the additional linked frame grabber binaries need to be copied into one folder
- This folder can then be used in the config .ini files for bring-up, production and verification (frame_grabber_path = "path_to_this_folder")

(1) cmake, Visual Studio 2017 and build_wrapper.bat can do the compilation:

CMakeLists.txt

- SWIG_EXECUTABLE_DIR
- FRAMEGRABBER INCLUDE DIR
- FRAMEGRABBER_LINK_DIR

build_wrapper.bat

- Path to Visual Studio 2017
- Path to cmake.exe

Run build_wrapper.bat from VS command prompt

LTS implementation

- Software required by ODM: Compiler (C++) and SWIG
- Header files and Swig file can be found in the software package.
 - Scripts\subfunctions_ch\custom_lts\custom_lts_wrapper\
- According to the header files, basic functions of the LTS need to be written and connected to the wrapper (open, moveRef, moveAbs, getPosition, ...)
- After running SWIG and compilation the following files should be generated⁽¹⁾:
 - _Custom_LTS.pyd (generated by Compiler)
 - Custom_LTS.py (generated by SWIG)
- These files and the additional linked LTS binaries need to be copied into the following folder:
 - Scripts\subfunctions_ch\custom_lts\

(1) cmake, Visual Studio 2017 and build_wrapper.bat can do the compilation:

CMakeLists.txt

- SWIG EXECUTABLE DIR
- CUSTOM LTS INCLUDE DIR
- CUSTOM_LTS_LINK_DIR

build_wrapper.bat

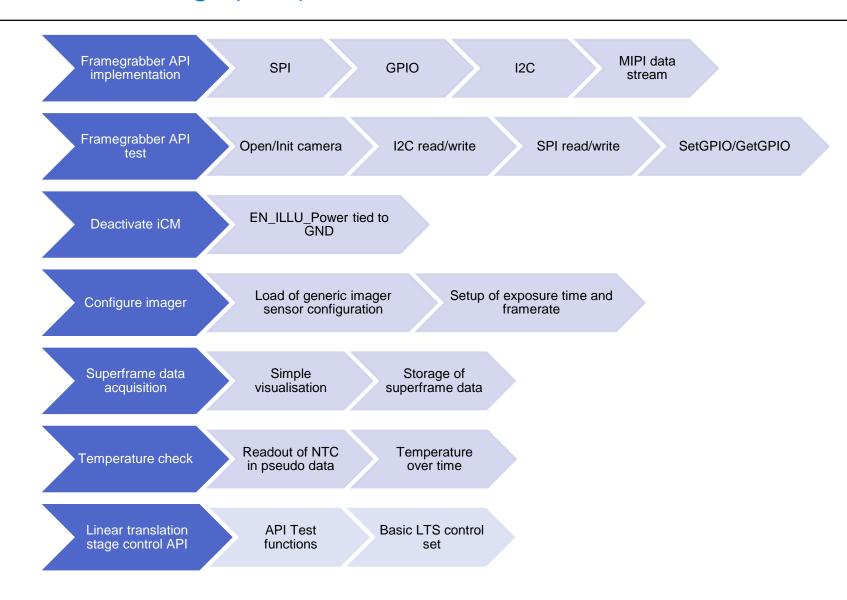
- Path to Visual Studio 2017
- Path to cmake.exe

Run build_wrapper.bat from VS command prompt

Comment: The readback during iCM calibration happens after Final MID flash. This means that the module can be fail but has already the final MID. The OQC clearance has to take care of this situation.

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Hardware bring-up steps



Hardware bring-up package (1)

- Frame grabber API test
 - Update and run .bat:

framegrabber_test_run.bat

```
--frame_grabber_path ""
--outdir ""
```

Output (in outdir):

Framegrabber_test.log

Pass/Fail for each test

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Hardware bring-up package (2)

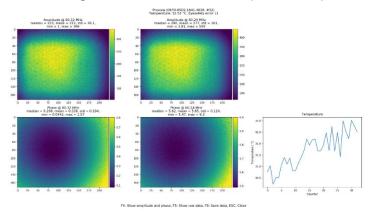
- Superframe data acquisition and temperature check
 - Update and run .bat:

any_quick_view.ini
Parameter file (additional Docu)

Quick_view_run.bat

--config_file "path to any_quick_view.ini"

A window should appear showing the measured amplitude, phase and temperature:



Press F8 to save data to the OutBaseDir given in the .ini file

0000-0000-0000-0000_VIEW.png

0000-0000-0000-0000_VIEW.pickle

0000-0000-0000 VIEW.rds

PNG Picture

Picture in Pickle format for Python import

Raw data

0000-0000-0000-0000_VIEW_temperatures.npy

Python array with temperature values

Closing the window will close the application and store:

log.log

Log information

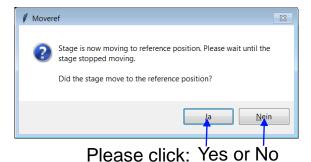
Hardware bring-up package (3)

- Linear translation stage API test
 - Update and run .bat:

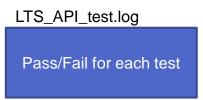
LTS API test run.bat



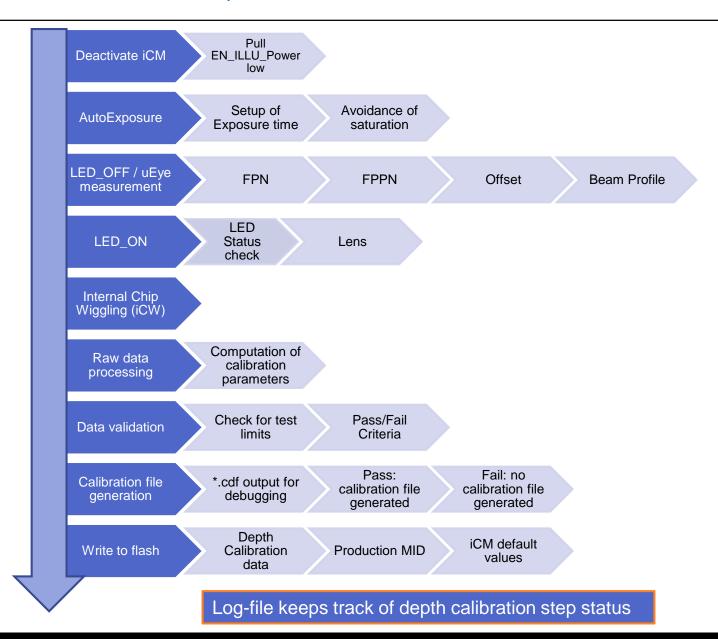
Several windows will appear for user interaction to check if the LTS is doing as expected:



Output (in outdir):



Depth calibration steps

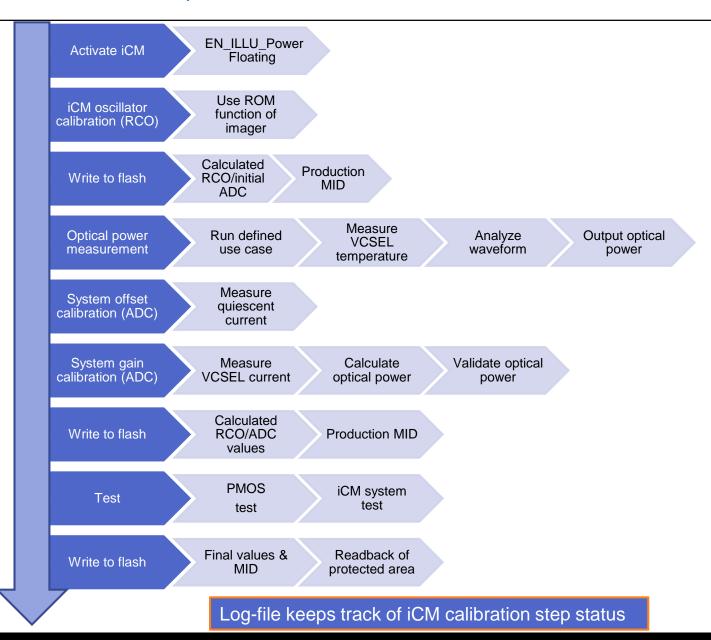


Depth calibration package

Update and run .bat: any_LED.ini calib_config.ini pmd depth calibration run.bat Parameter file (additional Docu) Parameter and test file (additional Docu) --config_file "path to any LED.ini" Output in folder 0000-0000-0000 LED: Phase 01 LEDsON.rds Phase 02 LEDsOFF.rds Phase 03 iCW.rds Raw data with LED on Raw data with LED off Raw data for iCW any_LED.ini log.log ueye.npy Ini file used for calibration Ueye image in python file Log file calib out 0000-0000-0000-0000.zwetschge 0000-0000-0000-0000.cdf Calibration data written on flash Calibration data for debuging log_out 0000-0000-0000-0000.db Log file with Test results

- If successful the calibration will be directly written on the module flash
- If not successful, no data will be written on the module flash and an error code (3) will be given as feedback

iCM calibration steps



iCM calibration package

Update and run .bat:

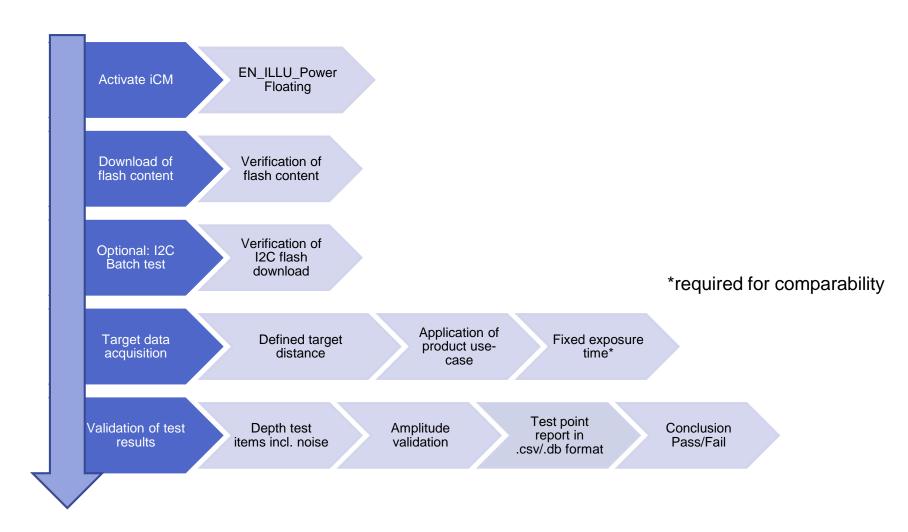
any_Sphere.ini icm_calib_run.bat

Parameter file (additional Docu) --config_file "path to any_Sphere.ini"

Output in folder 0000-0000-0000-0000_Sphere:

 0000-0000-0000-0000...iCM_calib.log
 samples.txt
 samples.npy

 Log file
 raw data power meter waveform
 raw data power meter waveform python



Log-file keeps track of validation step status

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Validation package

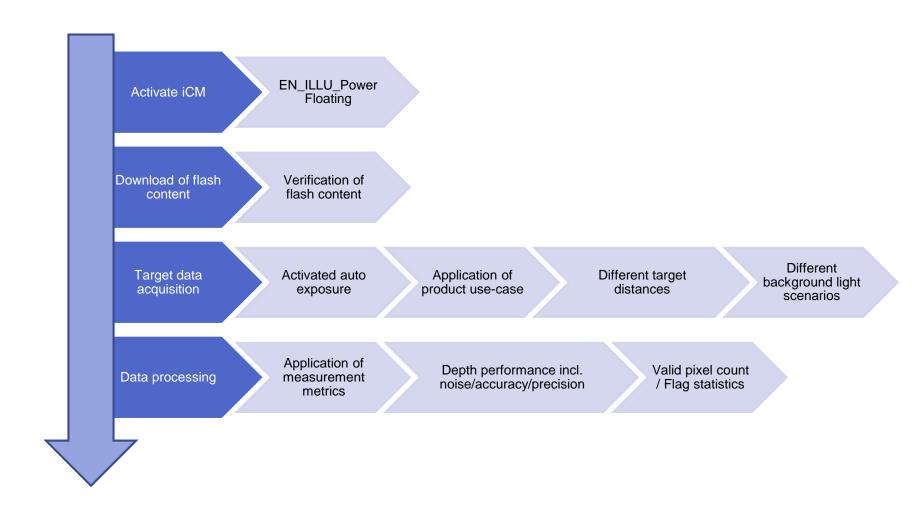
Update and run .bat:



Output in folder 0000-0000-0000_VAL:



If one of the tests fails, an error code (3) will be given back



Log-file keeps track of performance step status

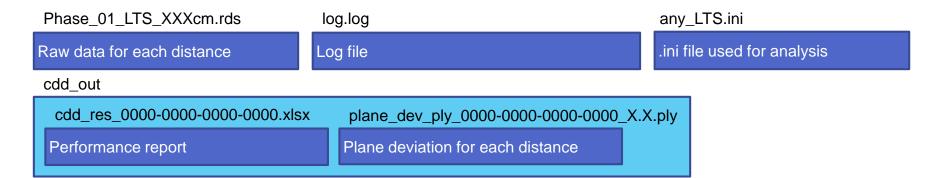
Performance analysis package

Update and run .bat:

any_LTS.ini processing_config.json pmd_depth_calibration_run.bat

Parameter file (additional Docu) Processing File (additional Docu) --config_file "path to any_LTS.ini"

Output in folder 0000-0000-0000-0000_LTS:



Roles & Responsibilities with regard to work with the calibration software package

pmd:

- Provides software package
- Supports on software package implementation
- Supports on linear translation stage wrapper
- Supports on depth calibration, validation and performance analysis topics

IFX:

- Supports on frame grabber wrapper implementation
- Provides imager configurations
- Supports on iCM calibration topics

ODM:

- Provides PC with Win 7 / 10
- Implements software package into production line
- Implements C++ frame grabber wrapper
- Implements C++ linear translation stage wrapper
- Installation of Newport power meter software

Roles and Responsibilities

 pmdtechnologies ag does support in the design process and provides consulting support in form of design and specification reviews. pmdtechnologies ag is not responsible for the final product of the customer. Reference designs are recommendations and may not be suitable for a claim of completeness.

Document History

Document: Performance Evaluation [pr-se-3-2]

Revi	ision	Origin of Change	Submission Date	Description of Change
0		MRe	2019-03-18	New presentation
1		MRe	2019-05-16	Updates with regard to wrapper changes
2		SSo	2019-05-16	Adding of Roles and Responsibility and Document History

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