

청소로봇용 LDROBOT社 LD06 2D LiDAR (d-ToF) BM

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중국 모듈 업체인 LDROBOT 홈페이지
→ Ultrasonic, d-ToF 등의 Line-up 보유

visionICs 업체 0D Single SPAD 사용

WI-XP-002



LD22 Ultrasonic Sensor

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DTOF LiDAR LD06

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Datasheet - VI4300

ToF Range-finder

Features

- Optical properties
 - Active area: $264 \mu\text{m} \times 264 \mu\text{m}$
 - SPAD PDE: 8% @ 905 nm
- Distance measurement
 - Range: 0.05 m ~ 12 m
 - Range resolution: 1.5 cm
 - Measurement accuracy: $\pm 1\%$
- On-chip calibration
 - Background light compensation
 - System-level calibration for non-linear signal distortions
- Digital interface
 - Configuration: I²C, up to 400 kHz
 - ToF output: SPI, up to 37.5 MHz
- Optimized optical package
 - PLCC / OPLGA / QFN / OCQFN / LGA
 - 4.5 mm × 4.5 mm × (0.9 ~ 1.5) mm
- Operating temperature: -20 °C to 65 °C

Applications

- SLAM for robotic vacuum
- Location and proximity sensing
- Altimeter and collisions avoidance for UAV
- Optical sensor for LiDAR

General description

The VI4300 is a time-of-flight laser ranging SoC. This sensor provides a compact solution for the miniature ToF sensing applications. With the self-developed SPAD (single-photon avalanche diode) and unique ToF acquisition and processing technology, the VI4300 can achieve an accurate distance measurement up to 12 meters. The measurement data and system configuration are transferred via SPI and I²C interfaces.

The sensor module consists of an optional integrated laser source (Class 1), a ToF ranging SoC and customized optics. It enables high ambient light suppression and can be used for distance measurement in the outdoor sunlight environment.



DTOF LiDAR LD19

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Triangulation LiDAR LD08

[Further exploration >](#)



Triangulation LiDAR LD14

[Further exploration >](#)



Solid state LiDAR

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LD06 TOF Coaxial radar is a laser radar device developed by Shenzhen LDRobot Co., Ltd. This LiDAR can realize 360° laser ranging scan, measuring visual point cloud information, which can be widely used in map construction (SLAM), robot positioning and navigation applications, as well as intelligent equipment obstacle avoidance.

SPECIFICATIONS:







Dimensions: 38*38*34.3mm
 Detection range: 0.02~12m
 Angular resolution: 0.2°~1.0°
 The laser wavelength: 905nm
 Measurement frequency: 4500Hz
 Sweep frequency: 5~13Hz
 Protection grade: IPX-4
 Measuring Angle: 0°~360°

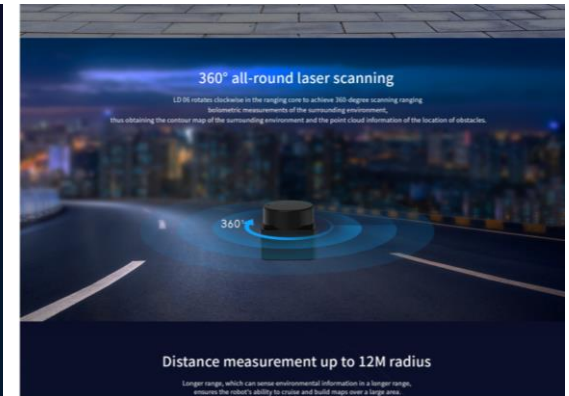
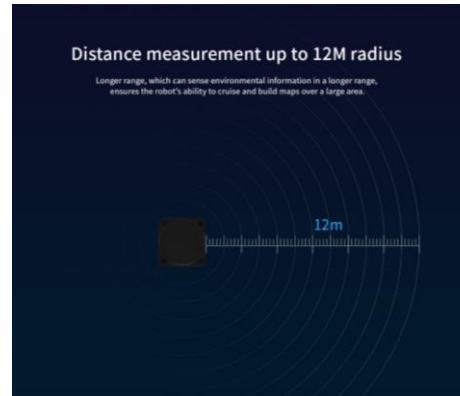
Application field

Education
 Scientific research
 Algorithm
 Robot obstacle avoidance
 Autonomous navigation
 Navigation and positioning

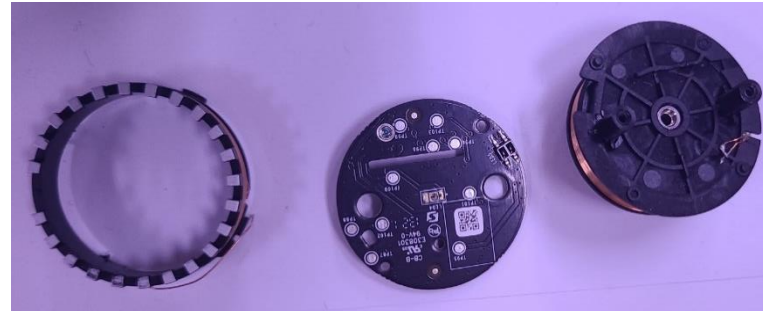


DTOF LiDAR LD06

 Distance measuring range 0.02-12m	 Ranging frequency 4500Hz
 Scanning frequency 5-13Hz	 Scanning angle 360°
 Ranging accuracy ±45mm	 Size 38.59*38.59*33.50mm



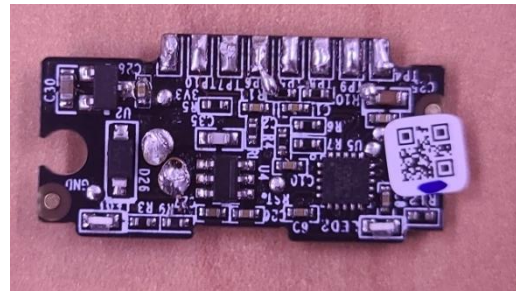
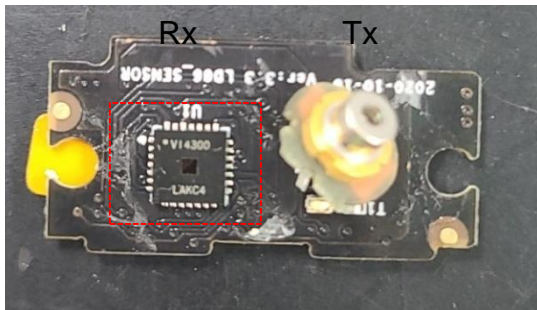
VCM 회전 모터 방식 → 360도 Scan



Tx : EEL (0D) TO-Can 구조

Rx : 중국 Evisonics社 VI4300 (0D) SPAD

EEL TO-Can

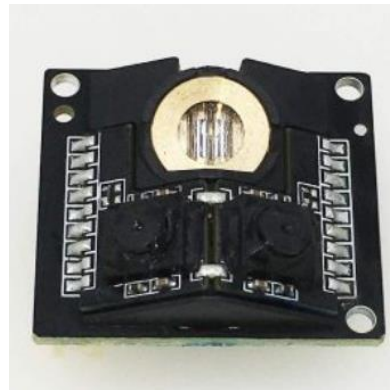


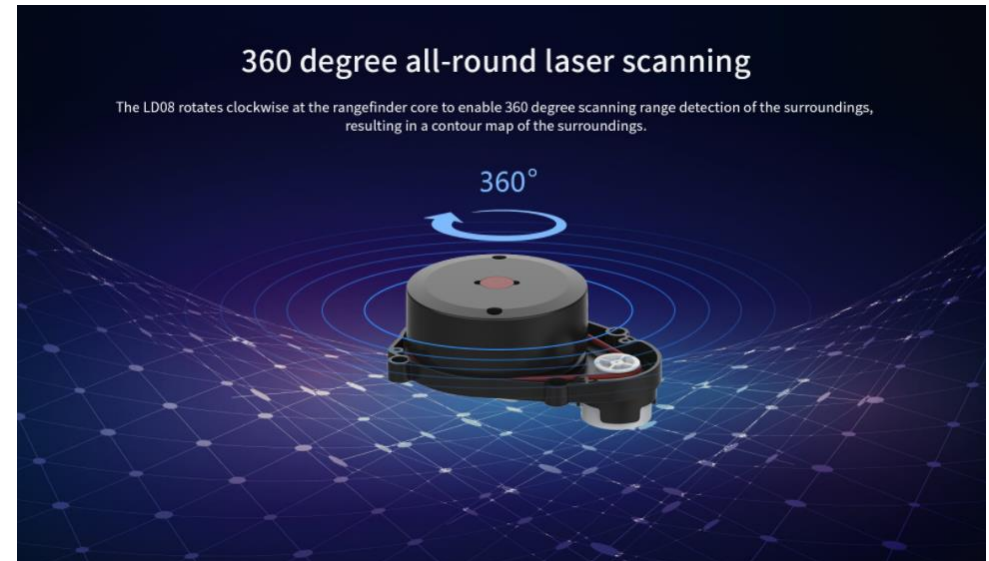
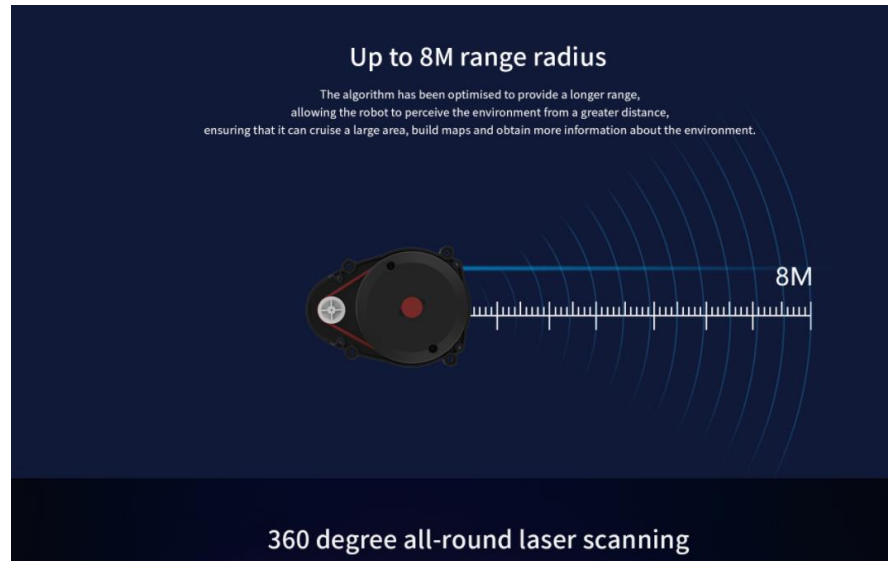
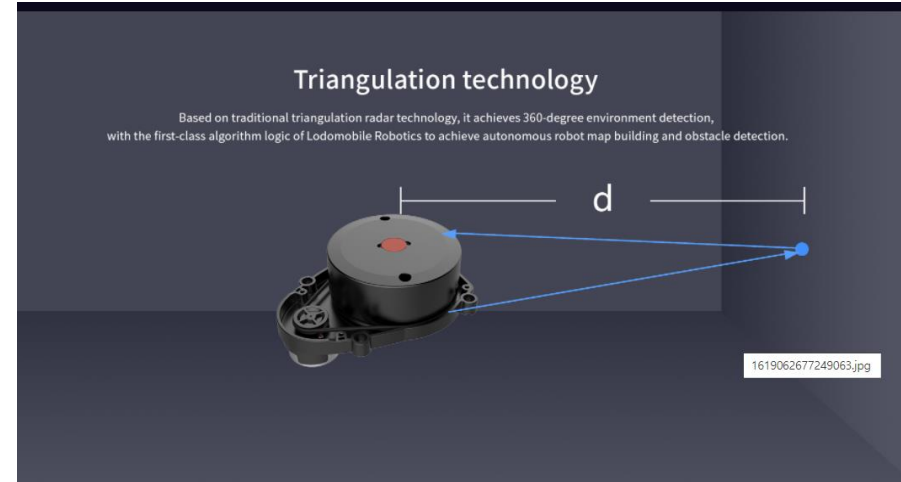
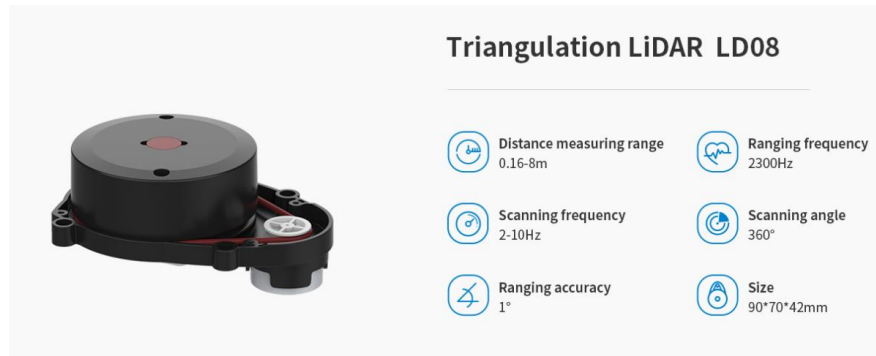
Dimensions: 19.7*24*15.3mm
Detection range : 2cm~30cm
Angular resolution: 0.5°
The standard deviation: 1mm
Measurement frequency: 30Hz
Hardware interface: UART
Accuracy of measurement: 1%
Obstacle avoidance horizontal field angle: 90°

LD07 line structured light radar is a solid-state lidar is developed by Shenzhen LDROBOT Co., Ltd.

This LiDAR can scan and measure visual point-cloud signal in 90 degree of laser scanning , be widely applied in map construction (SLAM), robot positioning and navigation device.

For robots device, LD07 has shown an excellent 3D obstacle avoidance and 3D edge-along ability, the angular resolution of LD07 Lldar can reach 0.5 degree at minimum, and recognize objects as small as 5mm in width; In terms of 3D edge along performance, LD07 covers 90 degree of viewing angle and can walk precisely along obstacles with height of 5mm at minimum. LD07 has greatly improved customer experience in minor obstacles recognition and avoidance ,as well as edge-along performance.





DTOF LiDAR LD19



Distance measuring range
0.03-12m



Ranging frequency
4500Hz



Scanning frequency
5-13Hz



Scanning angle
360°



Ranging accuracy
±45mm



Size
38.59*38.59*34.8mm

Time-of-flight ranging technology

Using time-of-flight ranging technology, the distance is measured according to the flight time of the laser pulse. Within the effective detection range of 12m, the radar ranging accuracy will not change with the distance, and the average ranging accuracy of ±45mm can be achieved. With the first-class algorithm logic of LDROBOT, it can realize the robot's 360-degree environmental detection, autonomous mapping and obstacle detection.



360° all-round laser scanning

The LD 19 rotates clockwise in the rangefinder core, enabling 360 degree scanning and range detection of the surrounding environment. This results in a contour map of the surrounding environment and a point cloud of information on the location of obstacles.

