

	<b>Semester 1</b>	
	<b>Supervisor</b>	Prof. Christopher Freeman
	<b>Student</b>	Yi Farn Lim
<b>Phase</b>	<b>Task</b>	<b>% Completion</b>
<b>Literature Review</b>	Industrial Demand and Limitation	100%
	Review of All Controllers Approaches	100%
	ILC Approaches	100%
<b>Learning (Technical)</b>	MATLAB Crash Course	100%
	Revise Control Theory	100%
	Simulink & Simscape Tutorial	100%
<b>MATLAB</b>	Controller Performance for Gantry axis	66%
	Controller Performance for Grasper	0%
<b>Simulink Model</b>	Construct Gantry Model (3 axis)	100%
	Controller Applied onto Gantry	33%
	Construct Grasper Model	0%
	Controller Applied onto Grasper	0%
<b>Others</b>	Progress Report	100%
	Buffer (To complete unfinished task)	NIL

<b>Legend</b>	
	Completed
	Unfinished
	Untouched
	Deadline

**NOTE** Unfinished/untouched tasks will be attempted to be completec

[illegible]

d during christmas break/exam week

[illegible]

[illegible]