

# CS 301

## Lecture 23 – Time complexity

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# Complexity

**Computability** What languages are decidable? (Equivalently, what decision problems can we solve with a computer?)

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**Computability** What languages are decidable? (Equivalently, what decision problems can we solve with a computer?)

**Complexity** How long does it take to check if a string is in a **decidable** language? (Equivalently, how long does it take to answer a decision question about an instance of a problem?)

## Running time

The **running time** of a decider  $M$  is a function  $t : \mathbb{N} \rightarrow \mathbb{N}$  where  $t(n)$  is the maximum number of steps  $M$  takes to accept/reject any string of length  $n$

This is the worst-case time: If  $M$  can accept/reject every string of length 5 except aabaa in 15 steps, but aabaa takes 4087 steps, then  $t(5) = 4087$

## Big-O review

If  $f, g : \mathbb{N} \rightarrow \mathbb{R}^+$ , we say  $f(n) = O(g(n))$  to mean there exist  $N, c > 0$  such that for all  $n \geq N$ ,  $f(n) \leq c \cdot g(n)$

### Examples

Constant  $c = O(1)$  for any  $c \in \mathbb{R}^+$

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**Exponential bound**  $2^{O(n^\delta)}$  for  $\delta > 0$

## Little-O review

If  $f, g : \mathbb{N} \rightarrow \mathbb{R}^+$ , we say  $f(n) = o(g(n))$  to mean

$$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$$

Equivalently, there exist  $N, c > 0$  such that for all  $n \geq N$ ,  $f(n) < c \cdot g(n)$

## Analyzing running time of deciders

It's too much work to be precise (we don't want to think about states)

For implementation-level descriptions of TMs, we can use big-O to describe the running time

## Example

Consider the TM  $M_1$  which decides  $A = \{0^n 1^n \mid n \geq 0\}$

$M_1$  = "On input  $w$ ,

- ① Scan across the tape and *reject* if a 0 is found to the right of a 1
- ② Repeat if both 0s and 1s remain on the tape
- ③ Scan across the tape, crossing off a single 0 and a single 1
- ④ If any 0 or 1 remain uncrossed off, then *reject*; otherwise *accept*"

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Each time through the loop takes  $O(n) + O(n) = O(n)$  time and the loop happens at most  $n/2$  times

The total running time is  $O(n) + (n/2)O(n) + O(n) = O(n^2)$

## Time complexity class

Let  $t : \mathbb{N} \rightarrow \mathbb{R}^+$  be a function. The **time complexity class**  $\text{TIME}(t(n))$  is the set of languages that are decidable by an  $O(t(n))$ -time TM

### Example

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Sipser gives a more clever TM  $M_2$  that decides  $A$  in time  $O(n \log n)$  by crossing off every other 0 and every other 1 each time through the loop

Thus,  $A \in \text{TIME}(n \log n)$  (this is the best we can do on a single-tape TM)

## What about a 2-TM?

With a 2-TM, we can decide  $A$  in linear ( $O(n)$ ) time

$M_3$  = "On input  $w$ ,

- 1 Scan right and *reject* if any 0 follows a 1
- 2 Return the beginning of the first tape
- 3 Scan right to the first 1, copying the 0s to the second tape
- 4 Scan right on the first tape and left on the second, crossing off a 0 for each 1, if there aren't enough 0s, then *reject*
- 5 If more 0s remain, then *reject*; otherwise *accept*"

Steps 1 and 2 each take  $O(n)$ ; together, steps 3, 4, and 5 constitute a single pass over the input so  $O(n)$

Total running time:  $O(n) + O(n) + O(n) = O(n)$

## Time complexity of a language depends on our model of computation

$M_1$  decides  $A$  in time  $O(n^2)$

$M_2$  decides  $A$  in time  $O(n \log n)$

$M_3$  decides  $A$  in time  $O(n)$  but uses a 2-TM

# Relationships between models of computation

Recall from computability that the following are equivalent

- Single tape TM
- $k$ -tape TM
- Nondeterministic TM

The situation for complexity is different



# Simulating a $k$ -TM

## Theorem

Let  $t : \mathbb{N} \rightarrow \mathbb{R}^+$  where  $t(n) \geq n$ . Every  $t(n)$ -time  $k$ -TM has an equivalent  $O(t^2(n))$ -time single-tape TM

## Proof

Recall that we simulated a  $k$ -TM  $M$  with a single-tape TM  $S$  by writing the  $k$  tapes separated with  $\#$  and dots representing the heads; e.g.,

$M$ :

a	b	b	a	a	b		
---	---	---	---	---	---	--	--



a	b	a	b	a	b	b	
---	---	---	---	---	---	---	--



a	b	b					
---	---	---	--	--	--	--	--



$S$ :

#	a	b	<span style="color:red">•</span> b	a	a	b	#	a	b	a	b	a	<span style="color:red">•</span> b	b	#	<span style="color:red">•</span> a	b	b		#	
---	---	---	------------------------------------	---	---	---	---	---	---	---	---	---	------------------------------------	---	---	------------------------------------	---	---	--	---	--



first tape

second tape

third tape

## Proof continued

If  $M$  runs in time  $t(n)$ , then it uses at most  $t(n)$  tape cells on each tape so  $S$  will use at most  $k \cdot t(n) + k + 1 = O(t(n))$  cells

Simulating one step of  $M$  required scanning across the tape twice and performing up to  $k$  shifts [why?]

Thus, each step of  $M$  takes  $O(t(n))$  time for  $S$  to simulate

Since there are  $t(n)$  steps and each takes  $O(t(n))$  time, the running time for  $S$  is  $t(n) \cdot O(t(n)) = O(t^2(n))$  □

# Simulating a $k$ -TM with a 2-TM

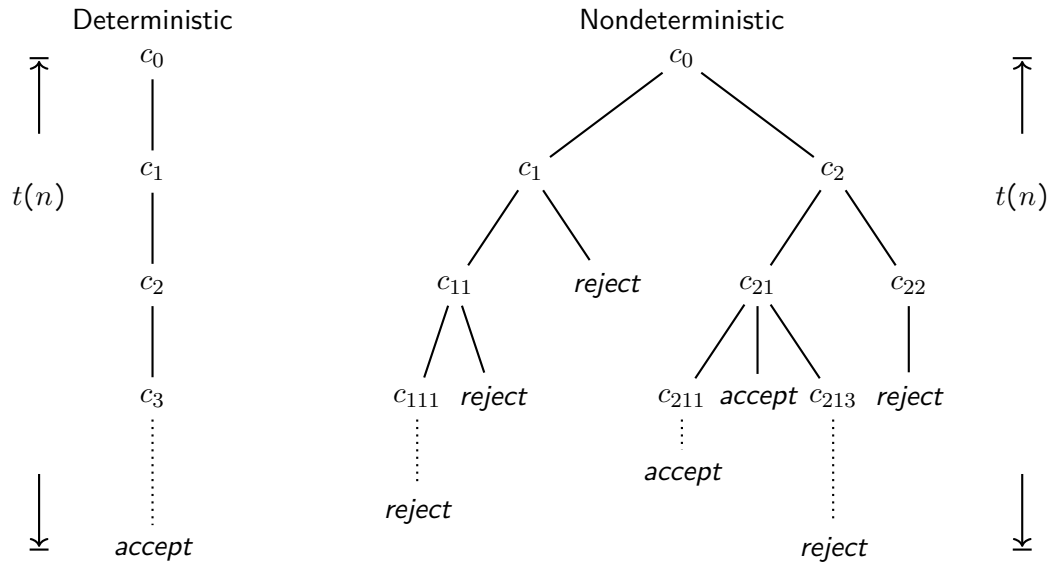
Just for your own edification:

## Theorem

*Every  $k$  tape TM that runs in time  $t(n)$  for  $t(n) \geq n$  can be simulated by a 2-tape TM in time  $O(t(n) \log t(n))$*

# Running time for NTMs

Let  $N$  be a nondeterministic TM that is a decider. The **running time** of  $N$  is a function  $t : \mathbb{N} \rightarrow \mathbb{N}$  where  $t(n)$  is the maximum number of steps that  $N$  uses on *any* branch of computation on any input of length  $n$



# Simulating an NTM

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*Every  $t(n)$ -time NTM where  $t(n) \geq n$  has an equivalent deterministic  $2^{O(t(n))}$ -time TM*

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## Proof idea

Our simulation of an NTM used a 3-TM and it performed a breadth first search of the configuration tree

The height of the tree is  $t(n)$  and if the maximum number of choices at each step is  $b$ , then the tree has  $O(b^{t(n)})$  total nodes

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For each node, we simulate from the root to the node which takes  $O(t(n))$  time

The running time of the 3-TM is  $O(t(n)) \cdot O(b^{t(n)}) = 2^{O(t(n))}$

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We can simulate the 3-TM with a TM in time  $\left(2^{O(t(n))}\right)^2 = 2^{O(t(n))}$



## Polynomial time

Note that the time to decide a language with a TM takes only a polynomial (a square) of the time it takes to decide with a  $k$ -TM

All *reasonable* deterministic models of computation are **polynomially equivalent**; that is, you can simulate any of them with any other with only a polynomial slow down

As we saw, nondeterminism seems fundamentally different

From this point, we're not going to be concerned with polynomial differences in time; e.g., the difference between  $O(n \log n)$  and  $O(n^{105})$  won't matter: Both are  $n^{O(1)}$

# The class P

P is the class of languages that are decidable in polynomial time on a deterministic TM,

$$P = \bigcup_{k=0}^{\infty} \text{TIME}(n^k)$$

P is a useful class because membership in P doesn't depend on (reasonable) deterministic models of computation

A problem that can be solved in polynomial time on a computer can be solved in polynomial time on a TM (even though the polynomial for one may be much larger than for the other)

# The class EXPTIME

EXPTIME is the class of languages that are decidable in exponential time on a deterministic TM

$$\text{EXPTIME} = \bigcup_{k=0}^{\infty} \text{TIME}(2^{n^k})$$

Note that EXPTIME is the same for any polynomially-equivalent models of computation

If language  $A$  takes time  $2^{O(n^k)}$  under one model, then it'll take  $(2^{O(n^k)})^c = 2^{c \cdot O(n^k)} = 2^{O(n^k)}$  time under a polynomially-equivalent model

# Tractable and intractable problems

We say that problems that can be solved in polynomial time are **tractable**: We can solve them with computers

We say that problems that take exponential time (or longer) are **intractable**: We can only solve very small instances of them with computers

$P$  = tractable

$EXPTIME$  = intractable

Lots of interesting problems are in  $P$ !

# Graphs

Recall: A **graph**  $G$  is a pair  $G = (V, E)$  where  $V$  is the set of vertices and  $E \subseteq V \times V$  is the set of edges

- For an **undirected graph** edge  $(a, b) = (b, a)$  (sometimes we write  $\{a, b\}$ )
- For a **directed graph** edge  $(a, b)$  is different from edge  $(b, a)$  (unless  $a = b$ )

In an algorithms class (e.g., CS 401), we would care about run times of algorithms in terms of  $m = |V|$  and  $n = |E|$

But since  $n \leq m^2$  and we don't care about polynomial differences, we'll talk about graph algorithm run times in terms of  $m$  alone

That is, we're going to phrase problems involving graphs as languages (of course) and we're going to ask questions like is the language in P?

## PATH $\in$ P

Define  $\text{PATH} = \{\langle G, s, t \rangle \mid G \text{ is a directed graph and there's a path from } s \text{ to } t\}$ .

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We can give a TM  $M$  to decide PATH

$M =$  "On input  $\langle G, s, t \rangle$  where  $G = (V, E)$  and  $s, t \in V$ ,

- ① Mark  $s$
- ② Repeat until no new nodes are marked,
- ③ For each  $(x, y) \in E$ , if  $x$  is marked and  $y$  is not, mark  $y$
- ④ If  $t$  is marked, then *accept*; otherwise *reject*"

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The loop in step 2 happens at most  $m = |V|$  times and there are at most  $n = |E| \leq m^2$  edges to check each time. Therefore, the running time is polynomial in  $m$  and thus polynomial in the size of the input

## What about on a computer?

Implementing this algorithm on a computer would take  $O(mn)$  time since it is looping over each of the  $n$  edges at most  $m$  times

There's a more clever algorithm that takes time  $O(m + n)$  but since both of these are polynomials, we don't need to be any more clever

# Boolean formulae

A **boolean formula** is an expression containing boolean variables and operations ( $\wedge$ ,  $\vee$ , and  $\neg$ )

Example:  $\phi = (\neg x \wedge y) \vee (x \wedge \neg z)$

As a shorthand, we write  $\bar{x}$  for  $\neg x$  so  $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$

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A boolean formula is in **conjunctive normal form** (CNF) if it consists of conjunctions (ANDs) of disjunctions (ORs)

- $(a \vee \bar{b} \vee \bar{c}) \wedge (\bar{d} \vee e \vee f)$
- $(a \vee b) \wedge c$
- $a \vee b$  [Why is this in CNF?]
- $a$

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**$k$ -CNF** A formula in CNF where each clause contains exactly  $k$  literals

Example 2-CNF formula

$$\phi = \underbrace{(a \vee b)}_{\text{clause}} \wedge (\bar{a} \vee c) \wedge (\bar{b} \vee \bar{c})$$

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**Satisfiable** A formula is satisfiable if there is an assignment of truth values ( $T/F$  or  $1/0$ ) to the variables that makes the whole formula true  
 $\phi$  is satisfiable by setting  $a = T$ ,  $b = F$ , and  $c = T$



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$\phi$  is satisfiable by setting  $a = T$ ,  $b = F$ , and  $c = T$

**Unsatisfiable** A formula is unsatisfiable if every assignment of truth values to the variables makes the whole formula false

$\psi = (a \vee \bar{b}) \wedge (\bar{a} \vee b) \wedge (\bar{a} \vee \bar{b}) \wedge (a \vee b)$  is unsatisfiable because every assignment makes one of the four clauses false

## 2-SAT

Define  $2\text{-SAT} = \{\langle \phi \rangle \mid \phi \text{ is a satisfiable boolean formula in 2-CNF}\}$

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2-SAT is decidable

$M_1 =$  “On input  $\langle \phi \rangle$ ,

- ① For each assignment of truth values to variables in  $\phi$ ,
- ② If the assignment satisfies  $\phi$ , then *accept*
- ③ Otherwise, *reject*”

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If there are  $n$  variables, then there are  $2^n$  combinations of assignments to try so  $2\text{-SAT} \in \text{EXPTIME}$ . Can we do better?

# Implications

Recall that the logical implication  $a \rightarrow b$  is equivalent to  $\bar{a} \vee b$

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From a formula in 2-CNF, we can produce a set of implications which are all simultaneously satisfiable if the formula is

$$\phi = (a \vee b) \wedge (\bar{a} \vee c) \wedge (\bar{b} \vee \bar{c})$$

$$\psi = (a \vee \bar{b}) \wedge (\bar{a} \vee b) \wedge (\bar{a} \vee \bar{b}) \wedge (a \vee b)$$

$$\bar{a} \rightarrow b$$

$$\bar{b} \rightarrow a$$

$$\bar{a} \rightarrow \bar{b}$$

$$b \rightarrow a$$

$$a \rightarrow c$$

$$\bar{c} \rightarrow \bar{a}$$

$$a \rightarrow b$$

$$\bar{b} \rightarrow \bar{a}$$

$$b \rightarrow \bar{c}$$

$$c \rightarrow \bar{b}$$

$$a \rightarrow \bar{b}$$

$$b \rightarrow \bar{a}$$

$$\bar{a} \rightarrow b$$

$$\bar{b} \rightarrow a$$

Recall that implications are transitive: If  $x \rightarrow y$  and  $y \rightarrow z$ , then  $x \rightarrow z$

## Satisfiability of implications

If there is a chain of implications  $x \rightarrow a \rightarrow \dots \rightarrow \bar{x}$ , then  $x = F$

If there is a chain of implications  $\bar{x} \rightarrow b \rightarrow \dots \rightarrow x$ , then  $x = T$

If both chains of implications exist, then the set of implications is not satisfiable  
(because a literal cannot be both true and false)

Thus, if we start with a formula in 2-CNF and write out the set of equivalent implications and find  $x \rightarrow \bar{x}$  and  $\bar{x} \rightarrow x$  for some variable  $x$ , then the formula is not satisfiable

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In fact, this condition is necessary, not merely sufficient for a formula to be unsatisfiable (harder to prove (Krom 1967))

That is, a formula is unsatisfiable iff  $x \rightarrow \bar{x}$  and  $\bar{x} \rightarrow x$  for some variable  $x$



# Turning a formula into a directed graph

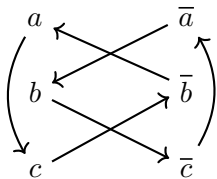
If the formula has  $m$  clauses and  $n$  variables, then we can construct the formula's **implication graph** which has  $2n$  vertices and  $2m$  edges

Let the vertices of the graph be each variable and its negation (i.e.,  $x$  and  $\bar{x}$  are vertices for each variable  $x$ )

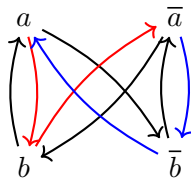
Let  $(x, y)$  be a directed edge in the graph for each implication  $x \rightarrow y$

There's a path from  $x$  to  $y$  in the graph iff there is a chain of implications  
 $x \rightarrow a \rightarrow \dots \rightarrow y$

$$\phi = (a \vee b) \wedge (\bar{a} \vee c) \wedge (\bar{b} \vee \bar{c}):$$



$$\psi = (a \vee \bar{b}) \wedge (\bar{a} \vee b) \wedge (\bar{a} \vee \bar{b}) \wedge (a \vee b):$$



$$a \rightarrow b \rightarrow \bar{a} \quad \bar{a} \rightarrow \bar{b} \rightarrow a$$

## 2-SAT $\in$ P

Now we can use our polynomial-time decider for PATH to decide 2-SAT in polynomial time

Let  $R$  decide PATH and construct  $D$  to decide 2-SAT

$D =$  "On input  $\langle \phi \rangle$ ,

- ① Construct the implication graph  $G$  for  $\phi$
- ② For each variable  $x$  in  $\phi$ ,
- ③     Run  $R$  on  $\langle G, x, \bar{x} \rangle$  and  $\langle G, \bar{x}, x \rangle$ ; if  $R$  accepts both, then *reject*
- ④ Otherwise *accept*"

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$\langle \phi \rangle \notin$  2-SAT iff  $\phi$  is unsatisfiable iff there is some variable  $x$  such that there is a path from  $x$  to  $\bar{x}$  and a path from  $\bar{x}$  to  $x$  in the implication graph iff  $D$  rejects

Since PATH  $\in$  P,  $R$  runs in time polynomial in its input  $\langle G, s, t \rangle$  which has size polynomial in the size of  $\langle \phi \rangle$

Constructing  $G$  takes polynomial time in the size of  $\langle \phi \rangle$  and  $R$  is run a polynomial number of times (twice per variable) so  $D$  runs in polynomial time. Therefore, 2-SAT  $\in$  P

## Why is constructing the graph polynomial time?

Remember, if  $\phi$  has  $m$  clauses and  $n$  variables, then  $G$  has  $2n$  vertices and  $2m$  edges

For example, we could use the adjacency matrix representation which would be a  $2n \times 2n$  matrix

## Recap

PATH  $\in P$  because we were able to give a polynomial time decider for it

By naïvely enumerating all  $2^n$  possible truth values, we showed 2-SAT  $\in EXPTIME$

By being more clever and constructing a graph corresponding to formulae in 2-CNF, we showed 2-SAT  $\in P$

# Can we always be more clever?

Sadly, no.  $P \not\subseteq \text{EXPTIME}$

That is, there are problems (equivalently languages) that require exponential time to decide

Here's one:  $A = \{\langle M, w, 1^k \rangle \mid M \text{ is a TM that accepts } w \text{ in at most } 2^k \text{ steps}\}$

$A \in \text{EXPTIME}$ : Simulate running  $M$  on  $w$  for  $2^k$  steps takes exponential time

$A \notin P$ : Harder to prove, but true