CSCI 210: Computer Architecture
Lecture 31: Data Hazards

Stephen Checkoway
Oberlin College
Dec. 20, 2021
Slides from Cynthia Taylor

Announcements

- Problem Set 10 due Sunday, January 2
- Lab 8 due Sunday, January 2
- Office Hours tomorrow 13:30–14:30

Data Hazards in ALU Instructions

- Consider this sequence:

```
sub $2, $1,$3
and $12,$2,$5
or  $13,$6,$2
add $14,$2,$2
sw  $15,100($2)
```

- We can resolve hazards with forwarding
  - How do we detect when to forward?

Forwarding

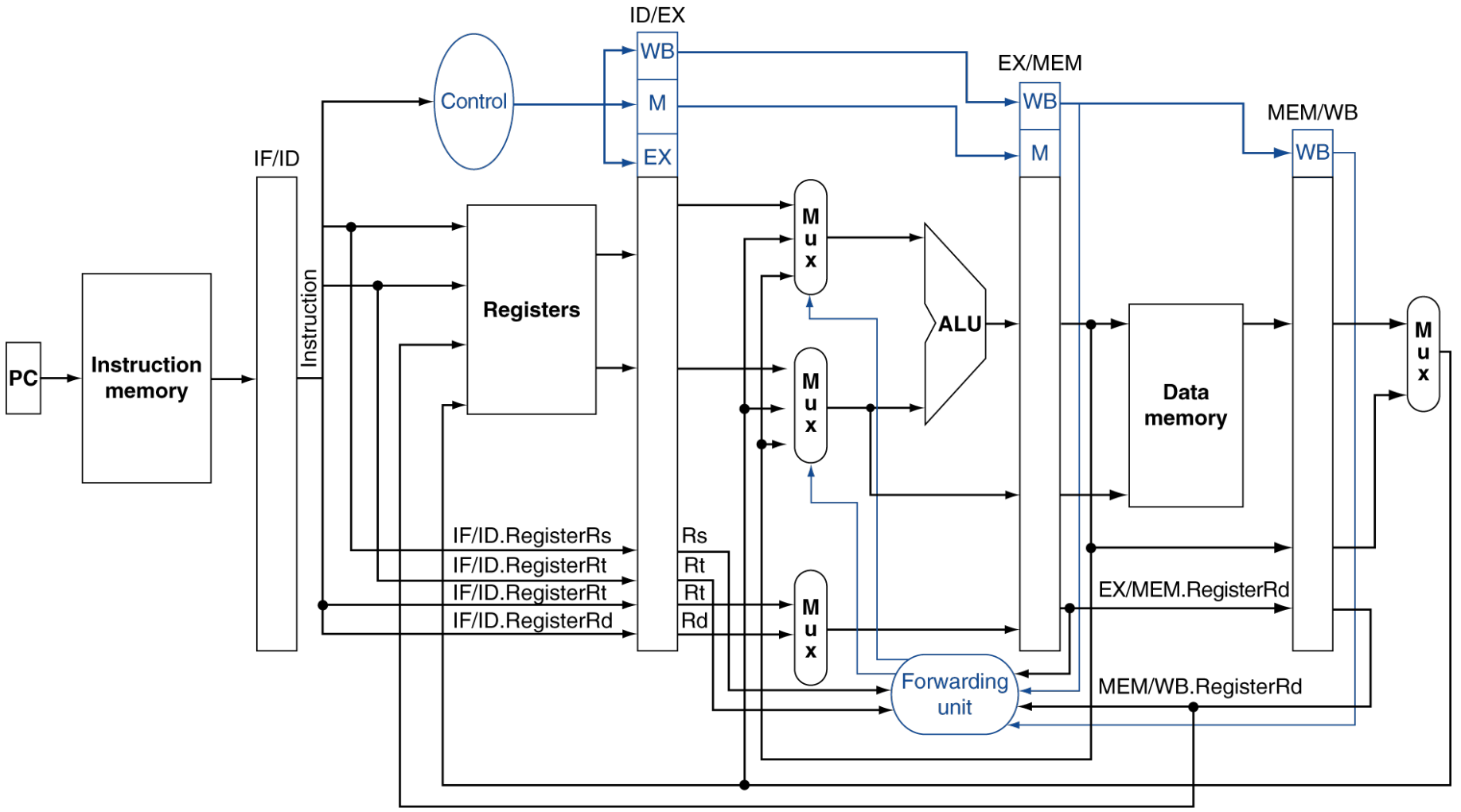
Datapath

- Connect the outputs of EX and MEM stages to both ALU inputs controlled by muxes

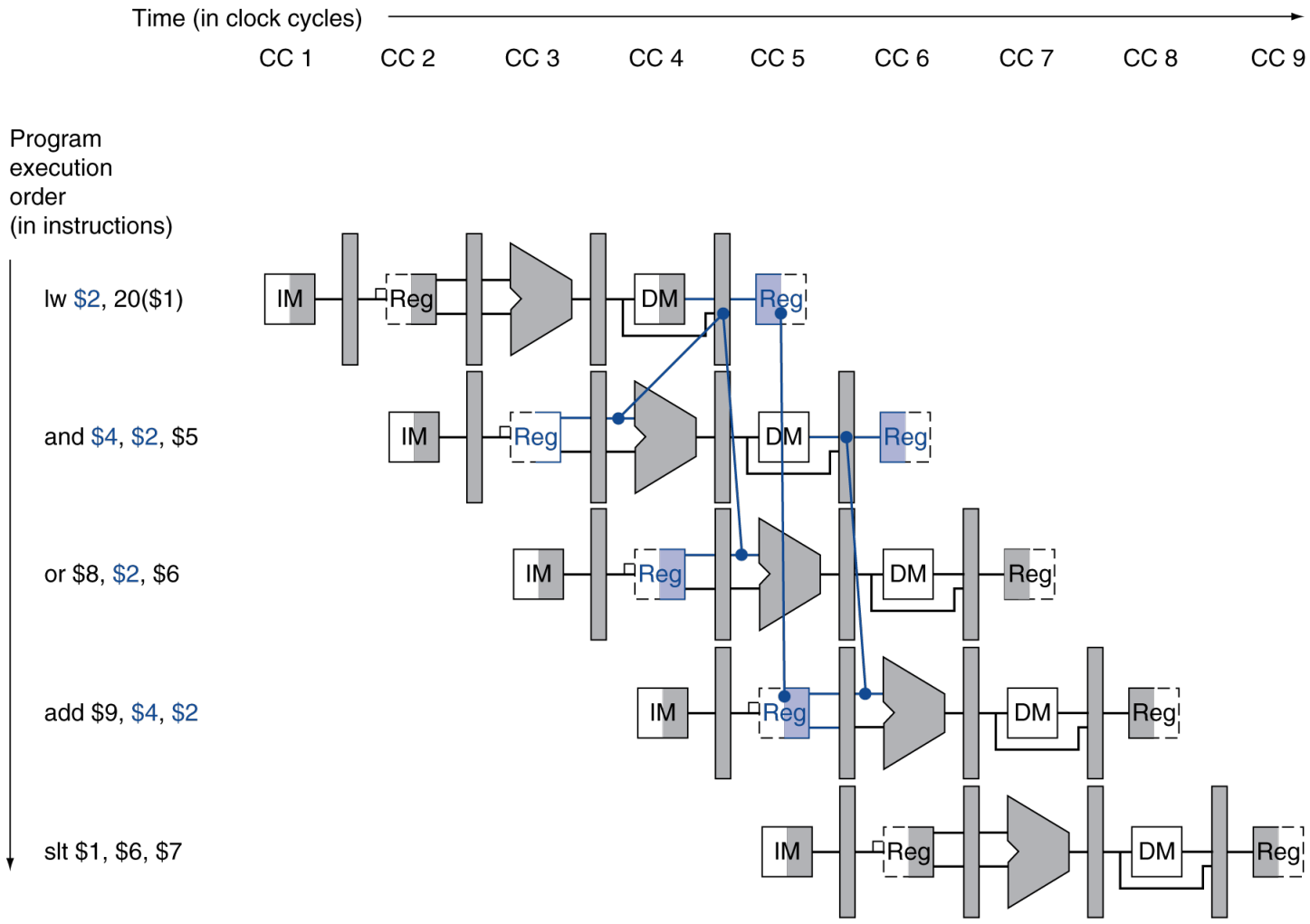
Control path

- Pass rs, rt, and rd register numbers through the pipeline registers
- Add a forwarding unit to control the muxes
  - Depends on RegWrite and rs/rt/rd from various stages

Datapath with Forwarding



Load-Use Data Hazard



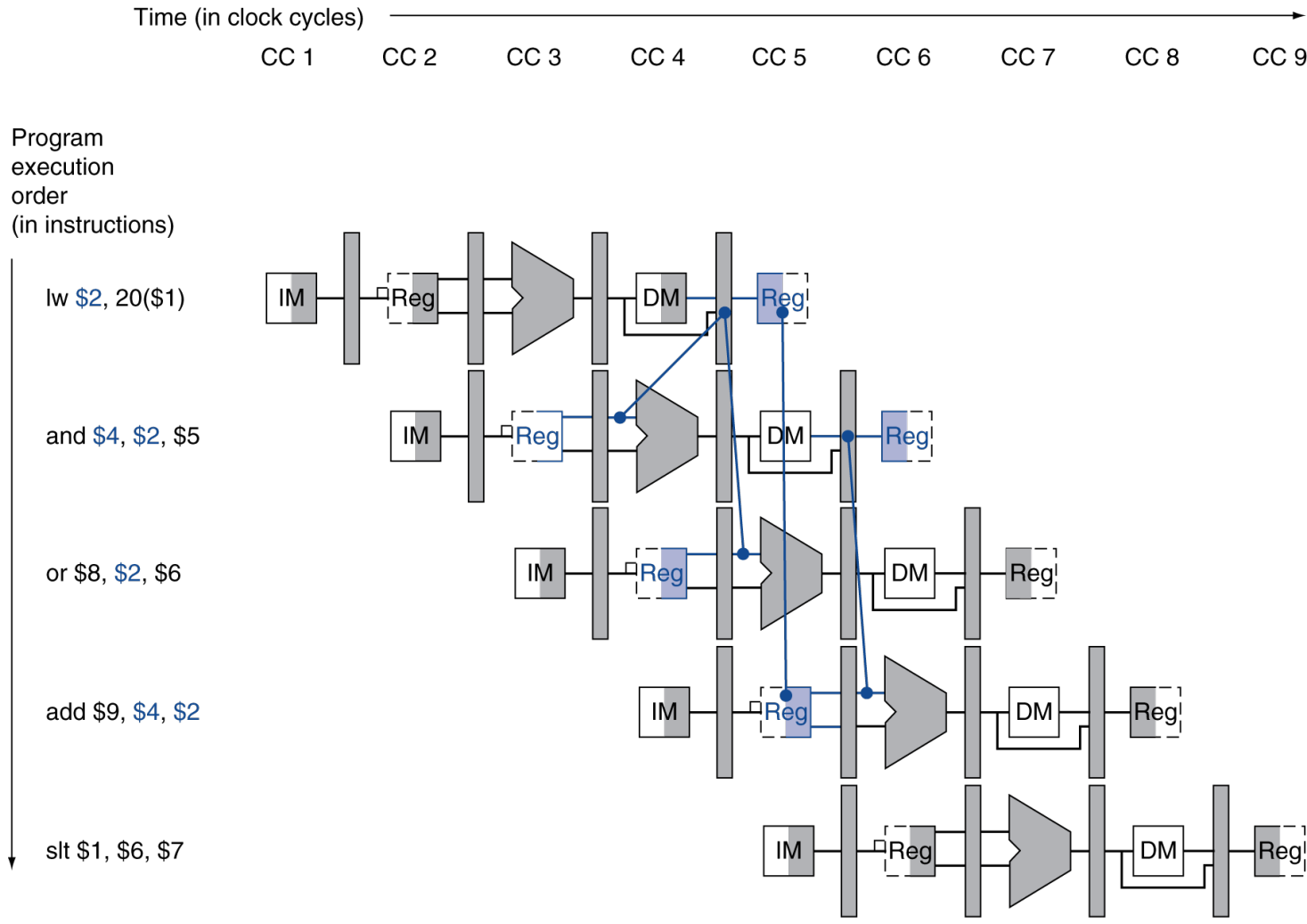
We can BEST solve these data hazards

A. By stalling.

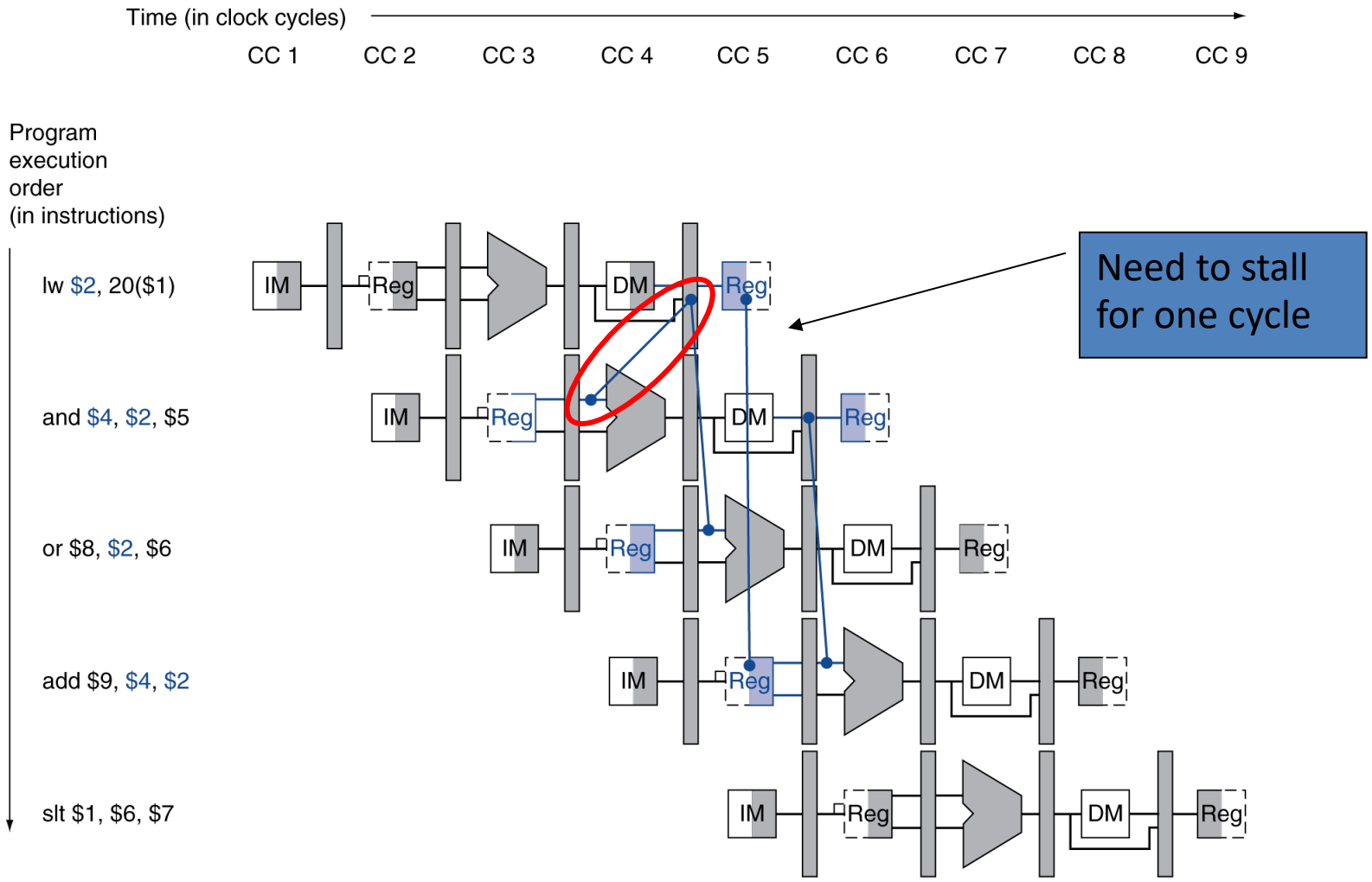
B. By forwarding.

C. By combining forwards and stalls.

D. By doing something else.



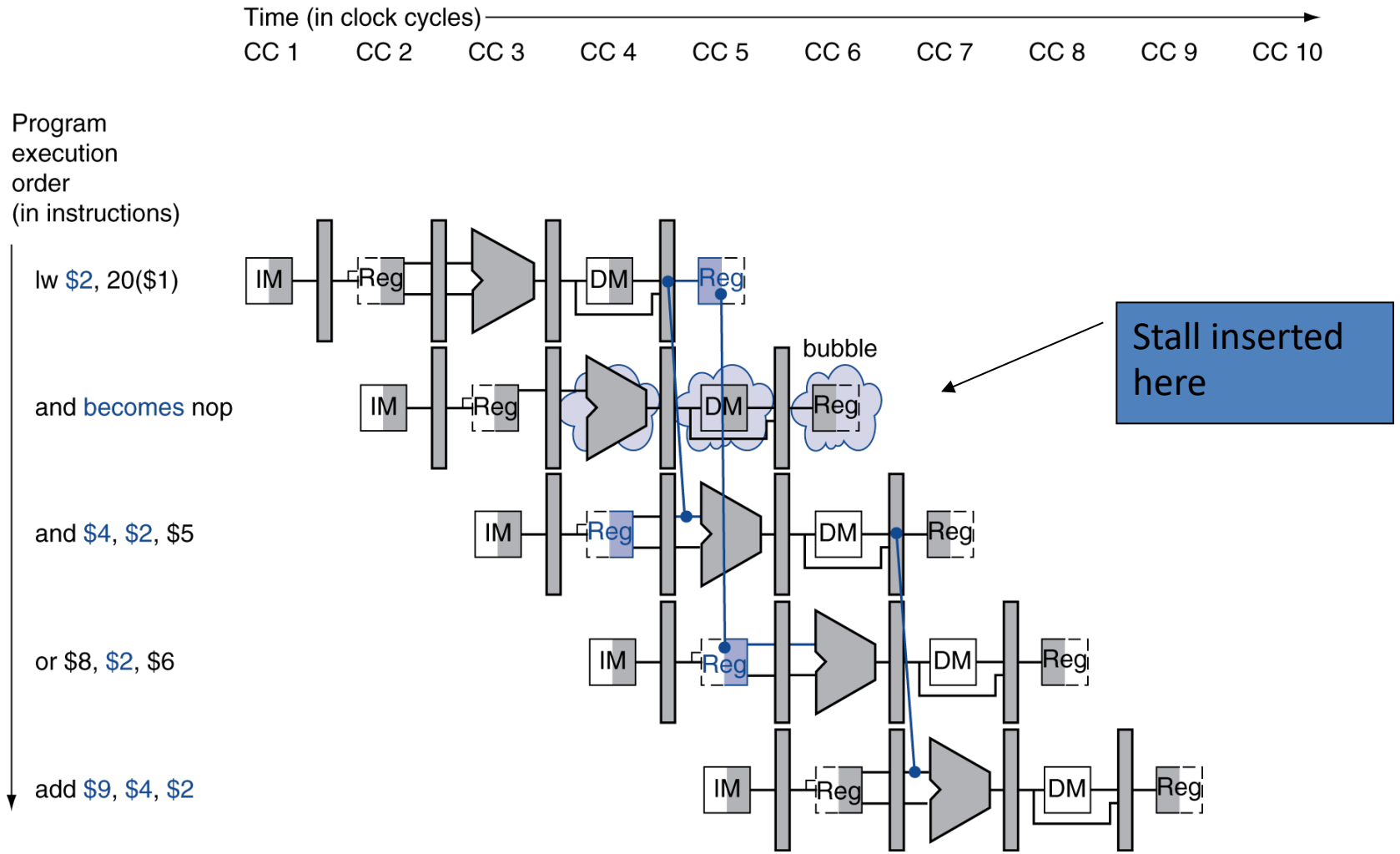
Load-Use Data Hazard



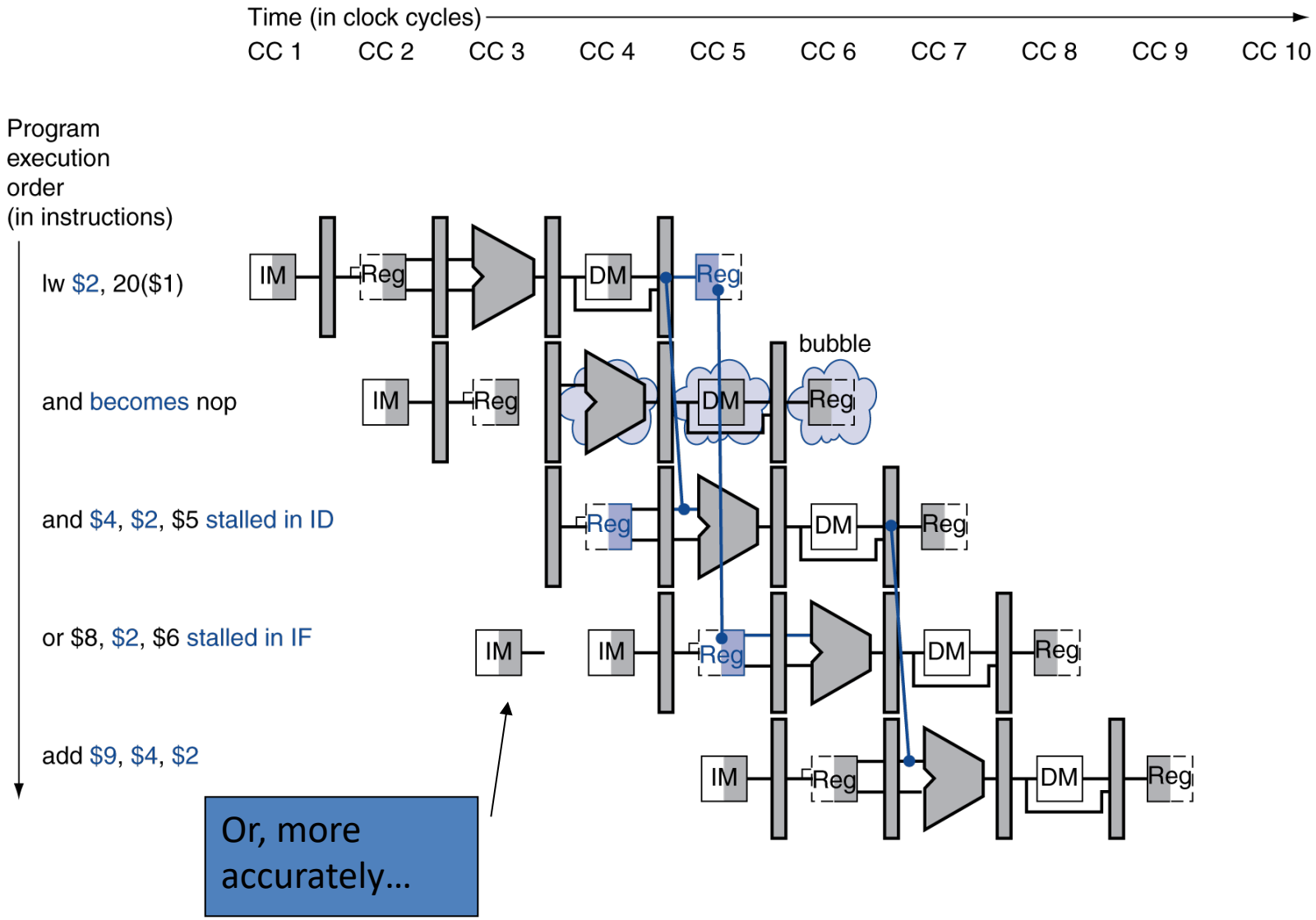
How to Stall the Pipeline

- Detect hazard in ID stage using Hazard detection unit
  - Check if instruction in EX stage is load with destination rs or rt
- Force control values in ID/EX register to 0
  - EX, MEM and WB do nop (no-operation)
- Prevent update of PC and IF/ID register
  - Instruction with dependency is decoded again
  - Following instruction is fetched again
  - 1-cycle stall allows MEM to read data for lw
    - Can subsequently forward to EX stage

Stall/Bubble in the Pipeline



Stall/Bubble in the Pipeline

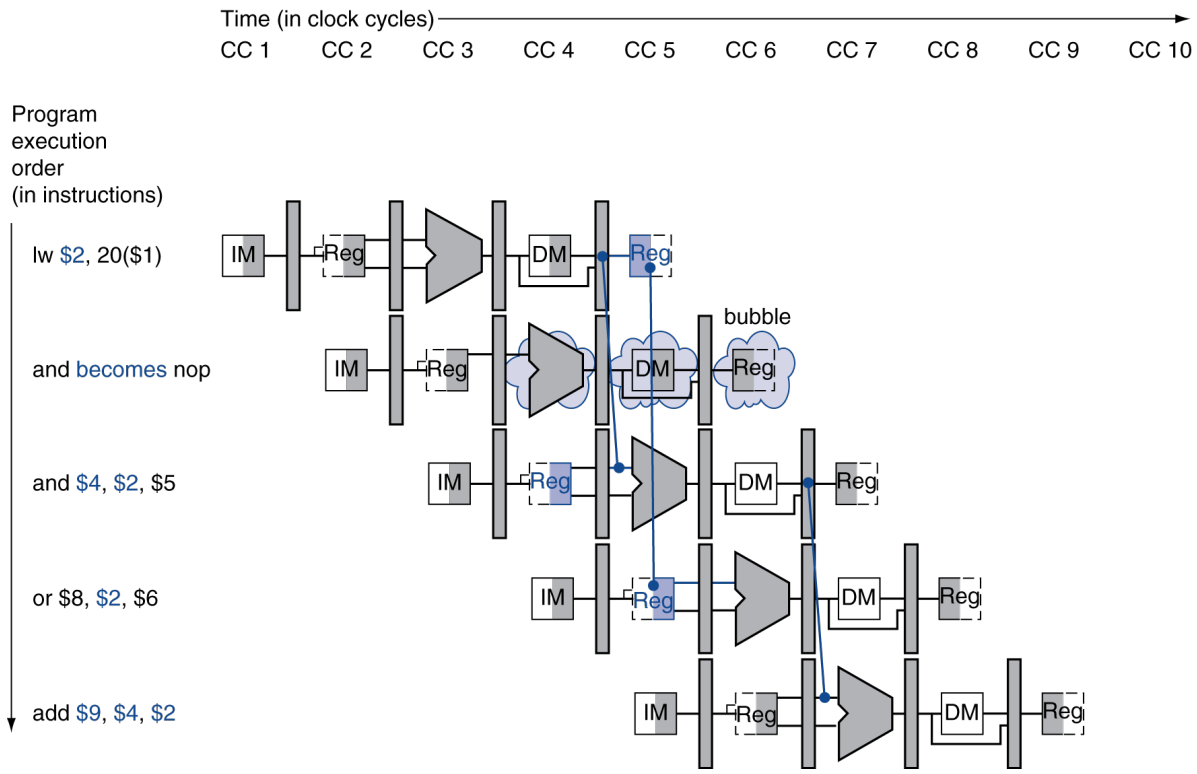


After we add the stall

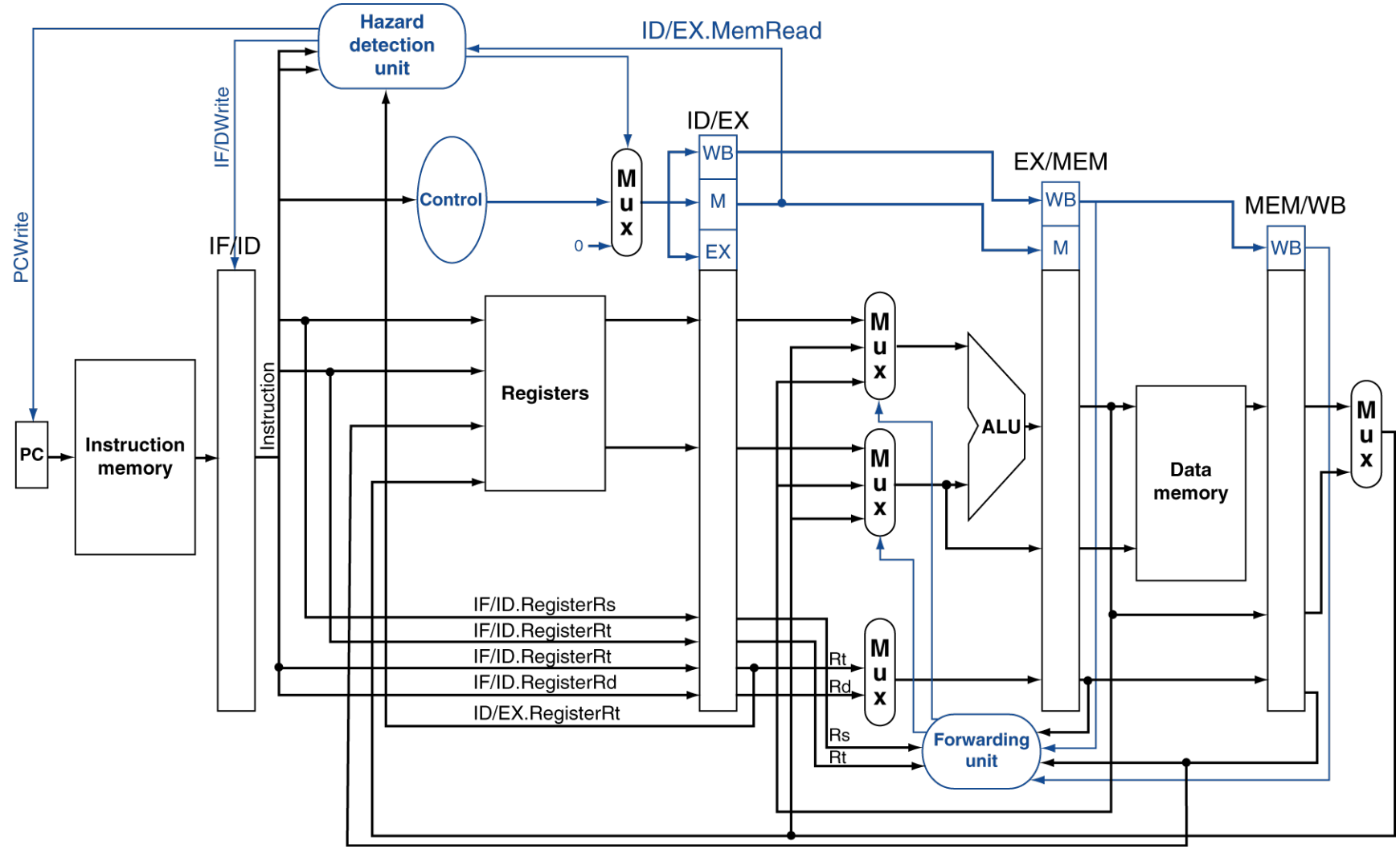
A. Everything works with our existing forwarding

B. We need to forward between the register files to solve the 2nd hazard

C. We need to do something else



Datapath with Hazard Detection



Reading

- Next lecture: Control Hazards
  - Section 5.9

- Problem Set 10 due Friday

- Lab 8 due Monday