

# Steven Rivadeneira

6114 Peregrine Avenue – Orlando, FL | C: (786) 227-4198 | Email: stevenrr@gatech.edu

## Education

---

Georgia Institute of Technology	08/2019 – 12/2021
<i>M.S in Aeronautics and Astronautics – GPA: 4.0/4.0</i>	<i>Distance Learning</i>

Massachusetts Institute of Technology	08/2013 - 06/2017
<i>B.S in Aeronautics and Astronautics</i>	<i>Cambridge, MA</i>

- Relevant Coursework: Intro to Comp Sci, Feedback Control Systems, Automatic Control, Astrodynamics, Dynamics

## Experience

---

Lockheed Martin Corporation	03/2019 - Present
<i>Guidance Navigation and Control Engineer</i>	<i>Orlando, FL</i>

- Lead guidance navigation control standup for the hypersonic missiles: ARRW and TBG in C++ and Simulink.
- Lead ARRW software development of guidance and control algorithms.
- Lead development and implementation of the Air Data Estimator for ARRW using Kalman Filter, C++ and Linux.

Binera, Inc.	08/2017 – 03/2019
<i>Aerospace Engineer / NASA Consultant</i>	<i>Rockville, MD</i>

- Sole developer of crew time model– data munge & analysis used to estimate crew time demands for Mars missions.
- Lead developer of logistics model – uses rates to calculate crew logistics requirements to the nearest kilogram.
- Directly supported NASA Langley and HQ in initial design & assessment of Mars human reference architectures.

MIT Senior Design Project – Flight Vehicle Engineering	09/2016 – 06/2017
<i>Undergraduate Student in the Structures Team</i>	<i>Cambridge, MA</i>

- Designed wing spar and joiner through detailed structural analysis, primarily using SolidWorks FEM software
- Tested wing structure for modularity and long endurance, redesigned the wing structure as required.
- Delivered PDR and CDR presentations to our client, Lincoln Laboratory, iteratively improving design over time.

Massachusetts Institute of Technology – Quadcopter Control	09/2016 – 06/2017
<i>Undergraduate Student in Feedback Control Systems course</i>	<i>Cambridge, MA</i>

- Used linear control techniques such as Kalman Filter, LQG, LQR to control and maneuver quadcopter for stable flight
- Implemented and extensively tested the behavior of linear control techniques via Matlab/Simulink, Linux, and C++

MIT Department of Earth Planetary and Atmospheric Sciences	01/2015 – 03/2015
<i>Undergraduate Researcher</i>	<i>Cambridge, MA</i>

- Analyzed orbital trajectory options for cube satellites in LEO using STK as primary software aid
- Performed orbital analysis trade studies to narrow down trajectory options. Primarily used Mathematica.

## Skills

- 
- Proficient knowledge of Python, C++, Javascript, MATLAB/Simulink atica and SolidWorks
  - English and Spanish: Native/Bilingual proficiency. French: Full professional proficiency

## Recognitions, Leadership & Memberships

- 
- Phi Beta Lambda National Statistics Competition – *First Place Winner* (National)