

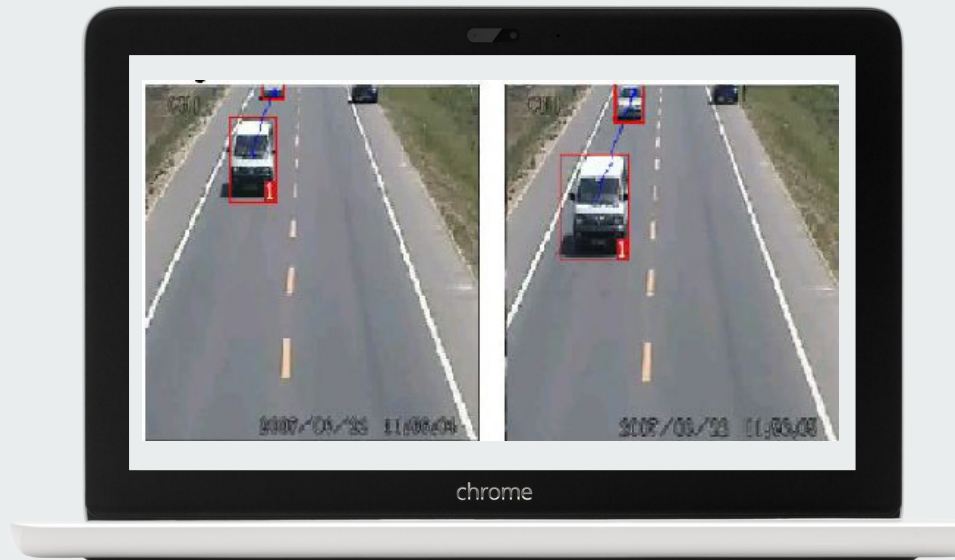
Object Tracking with Kernelized Correlation Filters (KCF)

Group Members :

Nan Zhou

Lingzhuo Zhao

Yanjie Chen



Outline

The Problem

Method

Results

Future work

The Problem

-Given a series of video frames, it is required to track at least one object in the video. We are required to develop one algorithm and test it in different datasets.

Method

- *Kernelized Correlation Filters (KCF)*

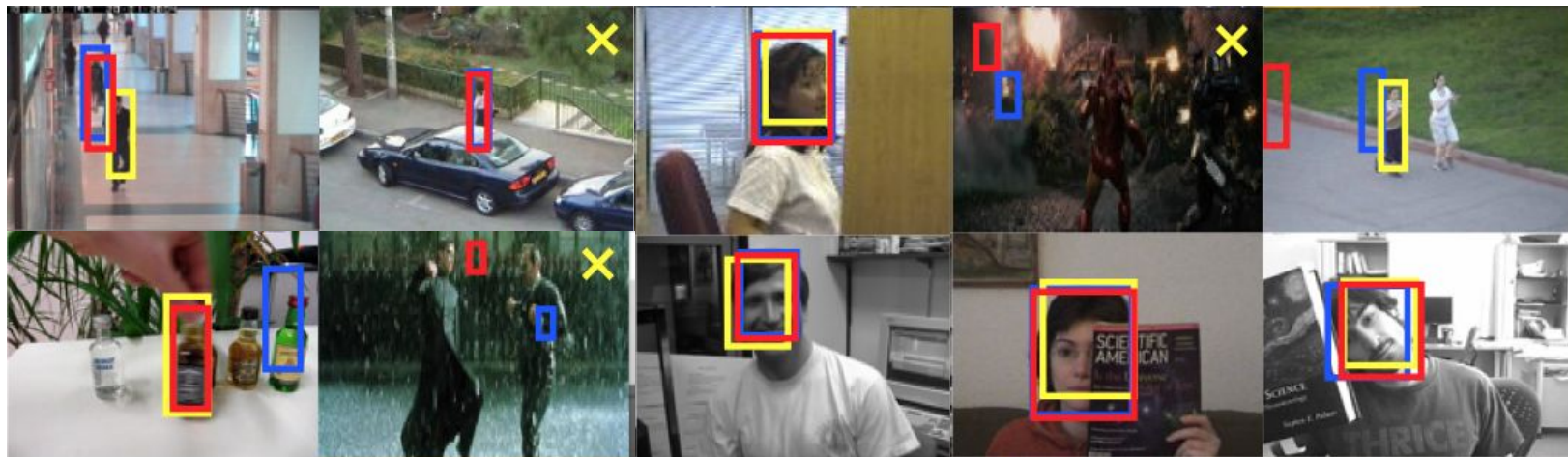


KCF

Kernelized Correlation Filter (KCF):

- Traditional correlational filter
- Kernel trick
- Circulant matrices
- HOG

Comparison with TLD & Struck



Kernelized Correlation Filter (proposed)

TLD

Struck



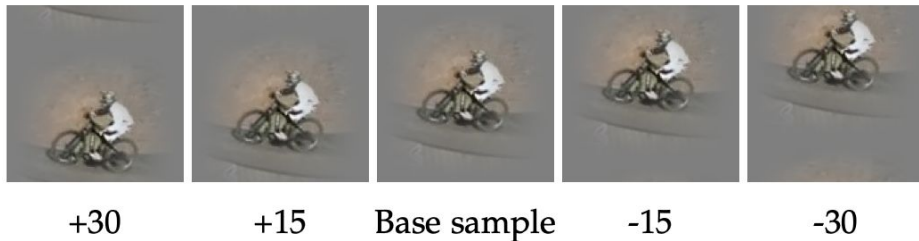
Equations

1. Ridge Regression: $\min_{\mathbf{w}} \sum_i (f(\mathbf{x}_i) - y_i)^2 + \lambda \|\mathbf{w}\|^2$
2. Analytical solution: $\mathbf{w} = (X^T X + \lambda I)^{-1} X^T \mathbf{y}$
3. Circulant Matrix: $X = F \text{diag}(\hat{\mathbf{x}}) F^H$
4. Solution in Frequency Domain: $\hat{\mathbf{w}} = \frac{\hat{\mathbf{x}}^* \odot \hat{\mathbf{y}}}{\hat{\mathbf{x}}^* \odot \hat{\mathbf{x}} + \lambda}$

Circulant Matrix

$$C(\text{sample}) = \begin{bmatrix} \text{Base sample} \\ \text{Shifted by 1 element} \\ \text{Shifted by 2 elements} \\ \vdots \\ \text{Shifted by } n-1 \text{ elements} \end{bmatrix}$$

$$X = C(\mathbf{x}) = \begin{bmatrix} x_1 & x_2 & x_3 & \cdots & x_n \\ x_n & x_1 & x_2 & \cdots & x_{n-1} \\ x_{n-1} & x_n & x_1 & \cdots & x_{n-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ x_2 & x_3 & x_4 & \cdots & x_1 \end{bmatrix}$$



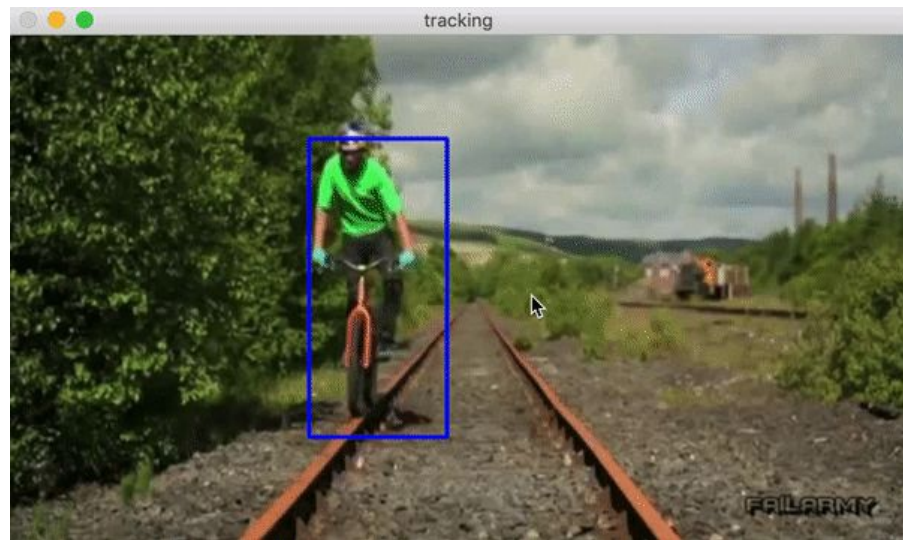
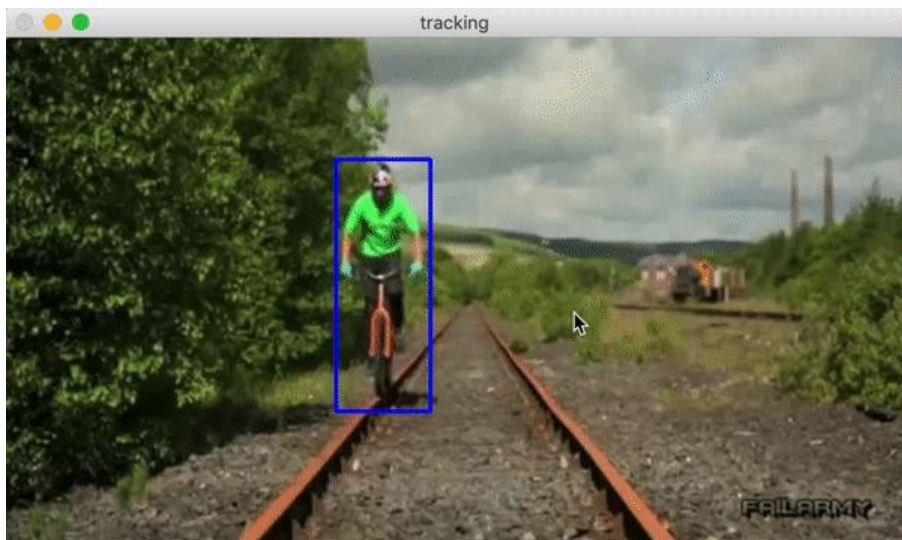


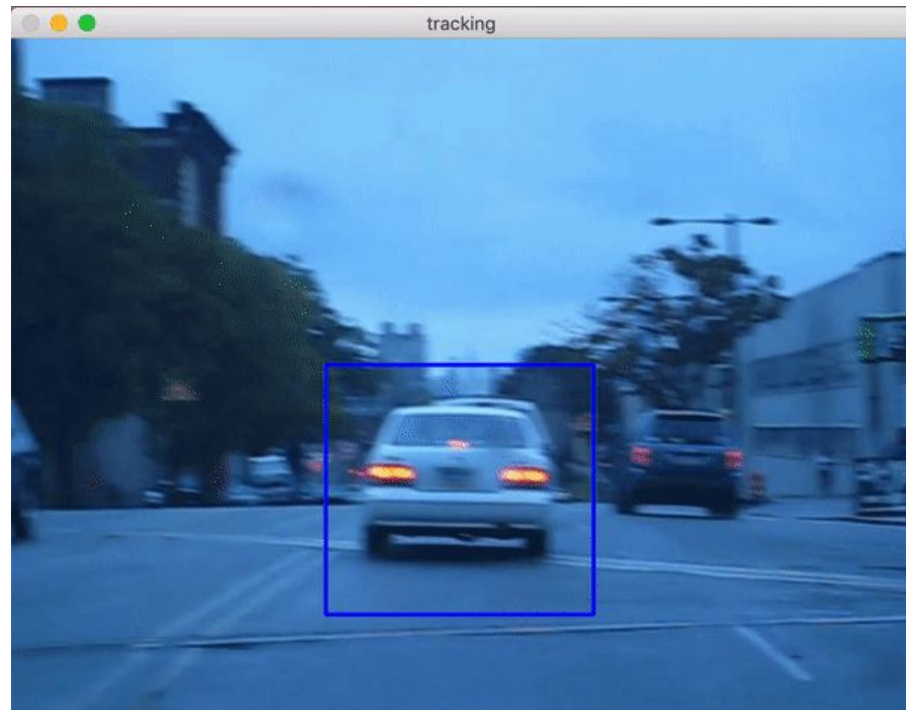
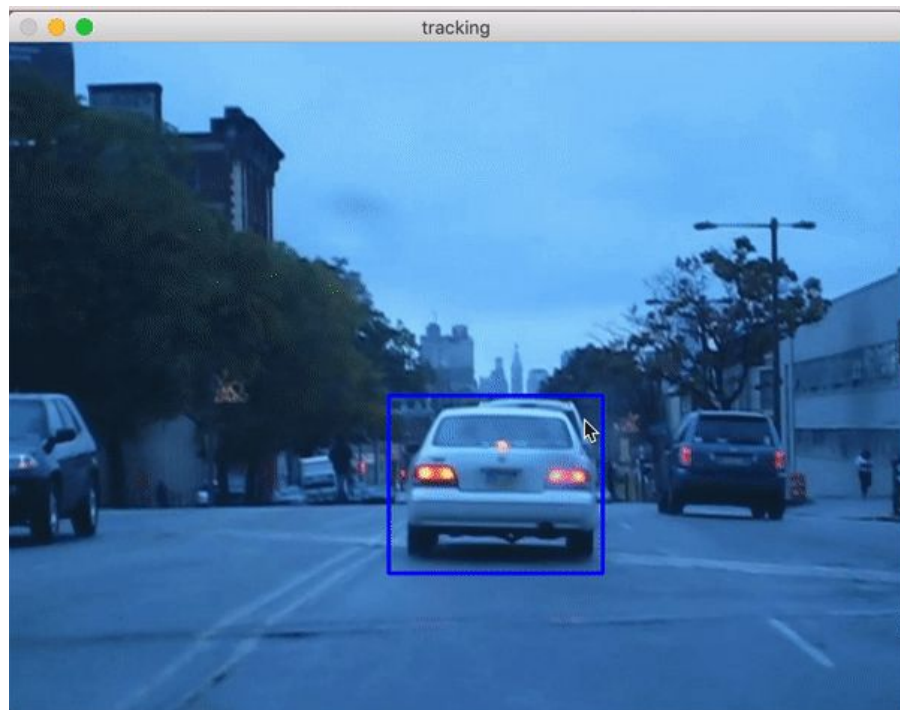
Performance

Algorithm	Feature	Mean precision (20 px)	Mean FPS
KCF	Raw pixels	56.0%	154
KCF	HOG	73.2%	172

Results

- The initial size of bounding box affects results significantly*
- Different dataset behaves differently*
- Some parameter need to be adjusted for each dataset*





Fail to Track



Future Work

- Certain parameters need to be improved
- Test in more datasets
- Develop automatic tracking program without initial bounding box
- Multi-object Tracking

Thank you!



References

1. Henriques, J., Caseiro, R., Martins, P., Batista, J.: Exploiting the circulant structure of tracking-by-detection with kernels. In: ECCV. pp. 702–715 (2012)
2. J. F. Henriques, R. Caseiro, P. Martins and J. Batista, "High-Speed Tracking with Kernelized Correlation Filters," in IEEE Transactions on Pattern Analysis and Machine Intelligence, vol. 37, no. 3, pp. 583-596, 1 March 2015, doi: 10.1109/TPAMI.2014.2345390.
3. K. Zhang, L. Zhang, Q. Liu, D. Zhang, and M.-H. Yang. Fast visual tracking via dense spatio-temporal context learning. In Proceedings of the European Conference on Computer Vision, 2014.



Github Repository

<https://github.com/zlz1996/CS585FinalProject>