

Making choices in multi-dimensional parameter spaces

PhD thesis defence

Steven Bergner

Model adjustment at different levels

- **User-driven experimentation:** Use cases for *paraglide*
- **Criteria optimization:** Lighting design
- **Theoretical analysis:** Sampling in volume rendering
- **Discretizing a region:** Lattices with rotational dilation
- Summary and conclusion



Data acquisition and visualization

Turning code into data

- Computer simulation code
- Function abstraction
 - ▶ Variables: input, output, and algorithm specific
 - ▶ Deterministic code



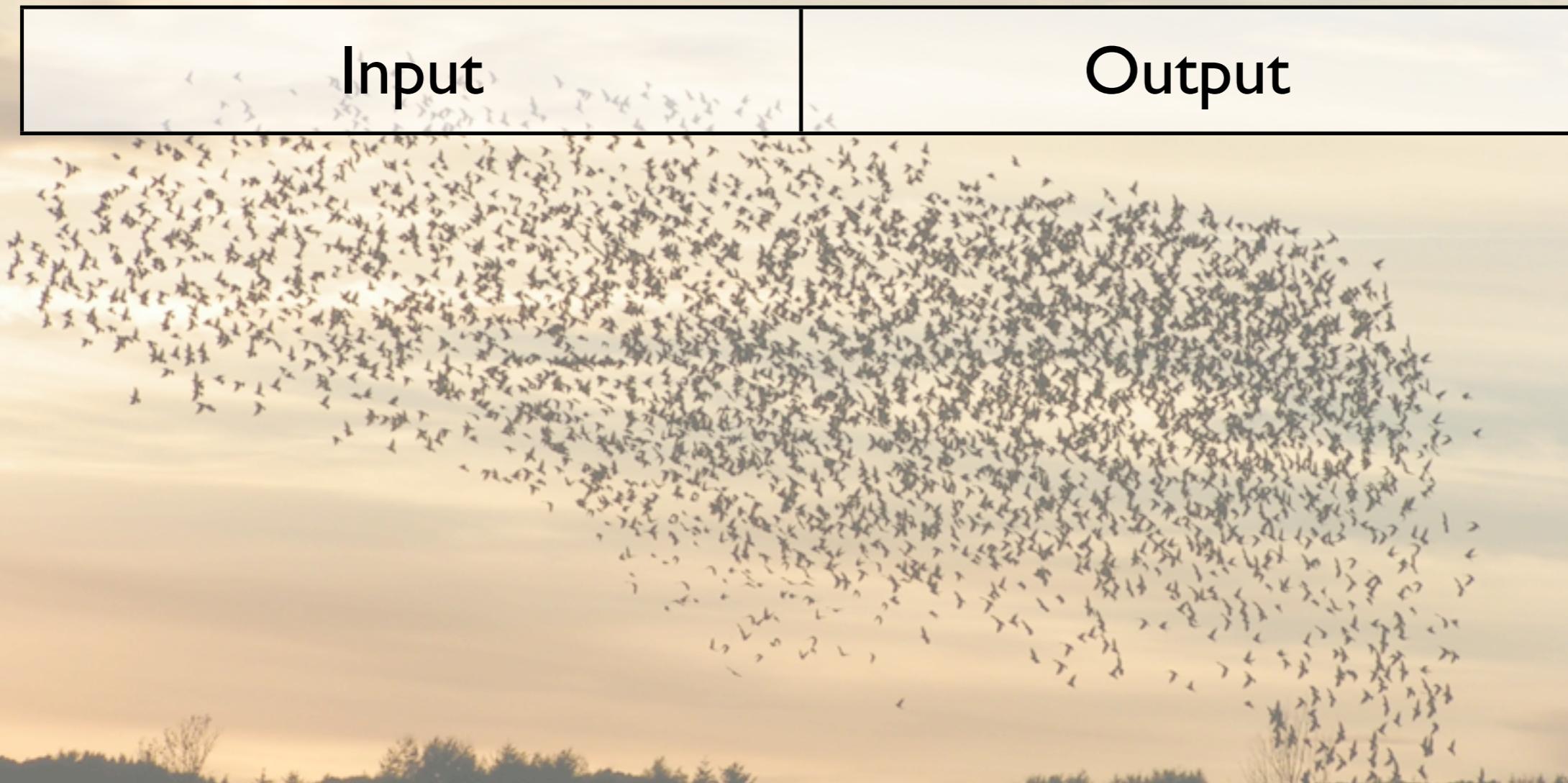
Biological aggregations



(c) Sareh Nabi Abdolyousefi



Biological aggregations



Input

Output

(c) Sareh Nabi Abdolyousefi

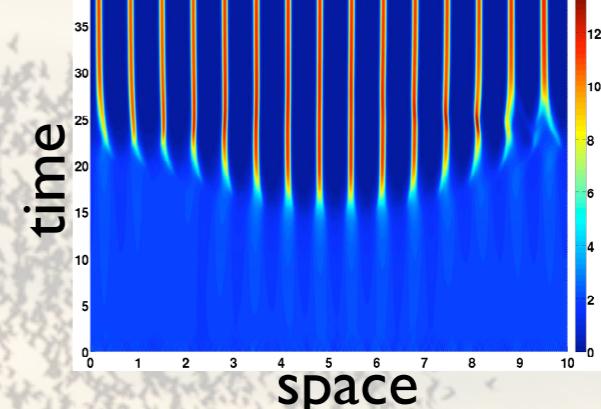
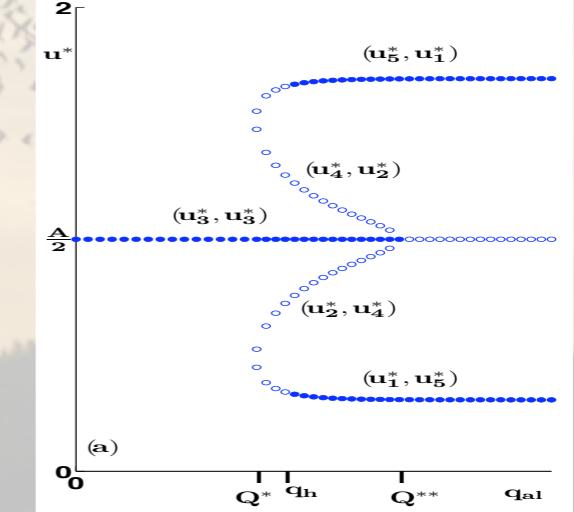


Biological aggregations

Input	Output
<p>1D+time model</p> <p>14 parameters</p> <ul style="list-style-type: none">•attraction, repulsion, and alignment coefficients•turning rates <p><i>internal:</i></p> <ul style="list-style-type: none">•space-time resolution influences cost	 A photograph showing a massive flock of birds, likely starlings or similar, silhouetted against a bright, orange and yellow sunset. The birds are densely packed and moving in complex, swirling patterns across the sky.

(c) Sareh Nabi Abdolyousefi

Biological aggregations

Input	Output
<p>1D+time model</p> <p>14 parameters</p> <ul style="list-style-type: none">•attraction, repulsion, and alignment coefficients•turning rates <p><i>internal:</i></p> <ul style="list-style-type: none">•space-time resolution influences cost	<p>patterns:</p>  <p>steady state bifurcation and stability:</p> 

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More cases

- Parameter space segmentation
- Bio-medical imaging algorithm
- Fuel cell design
- Scene lighting configuration
- Raycasting step size parameter



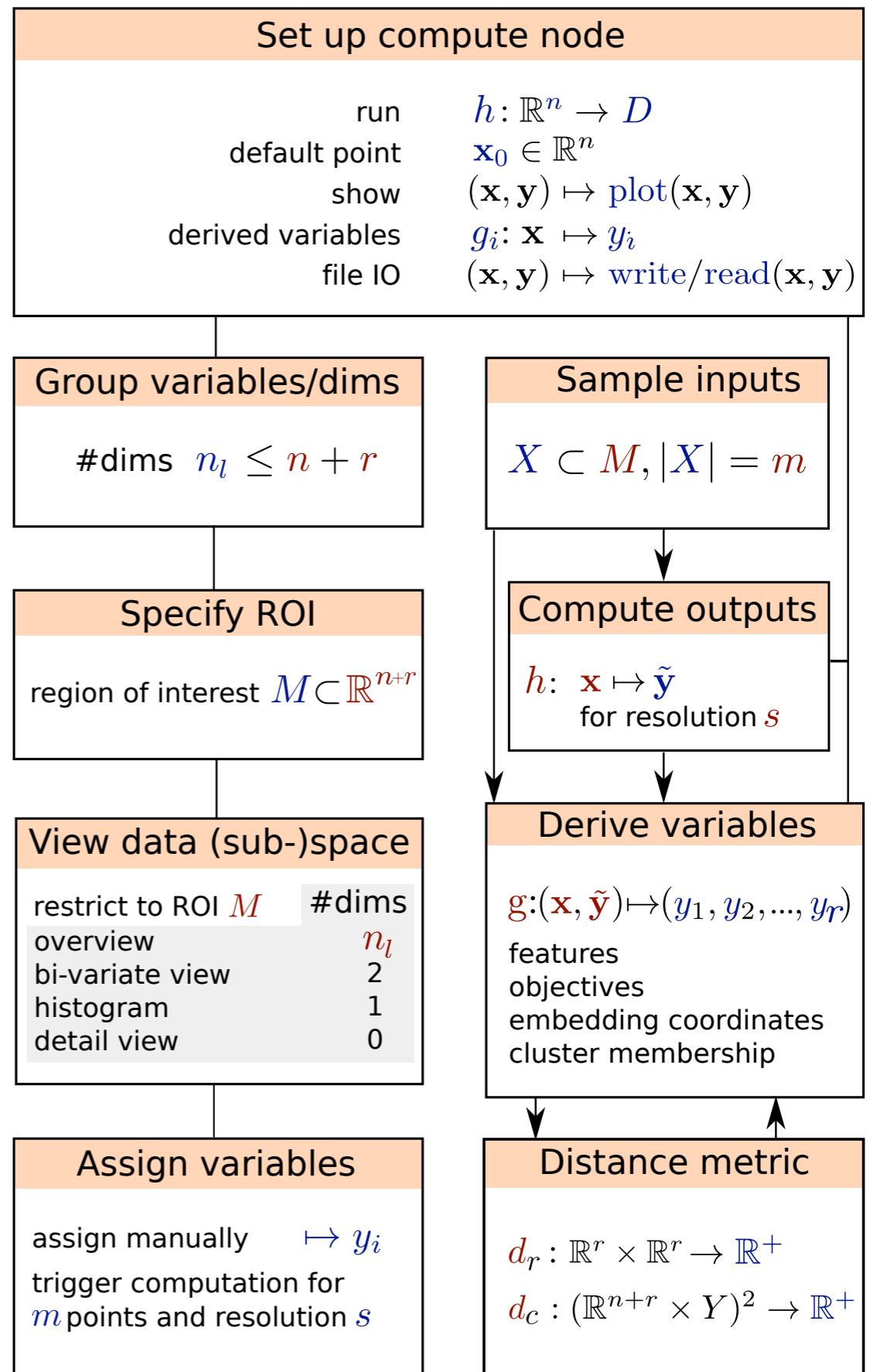
Paraglide design



Paraglide design

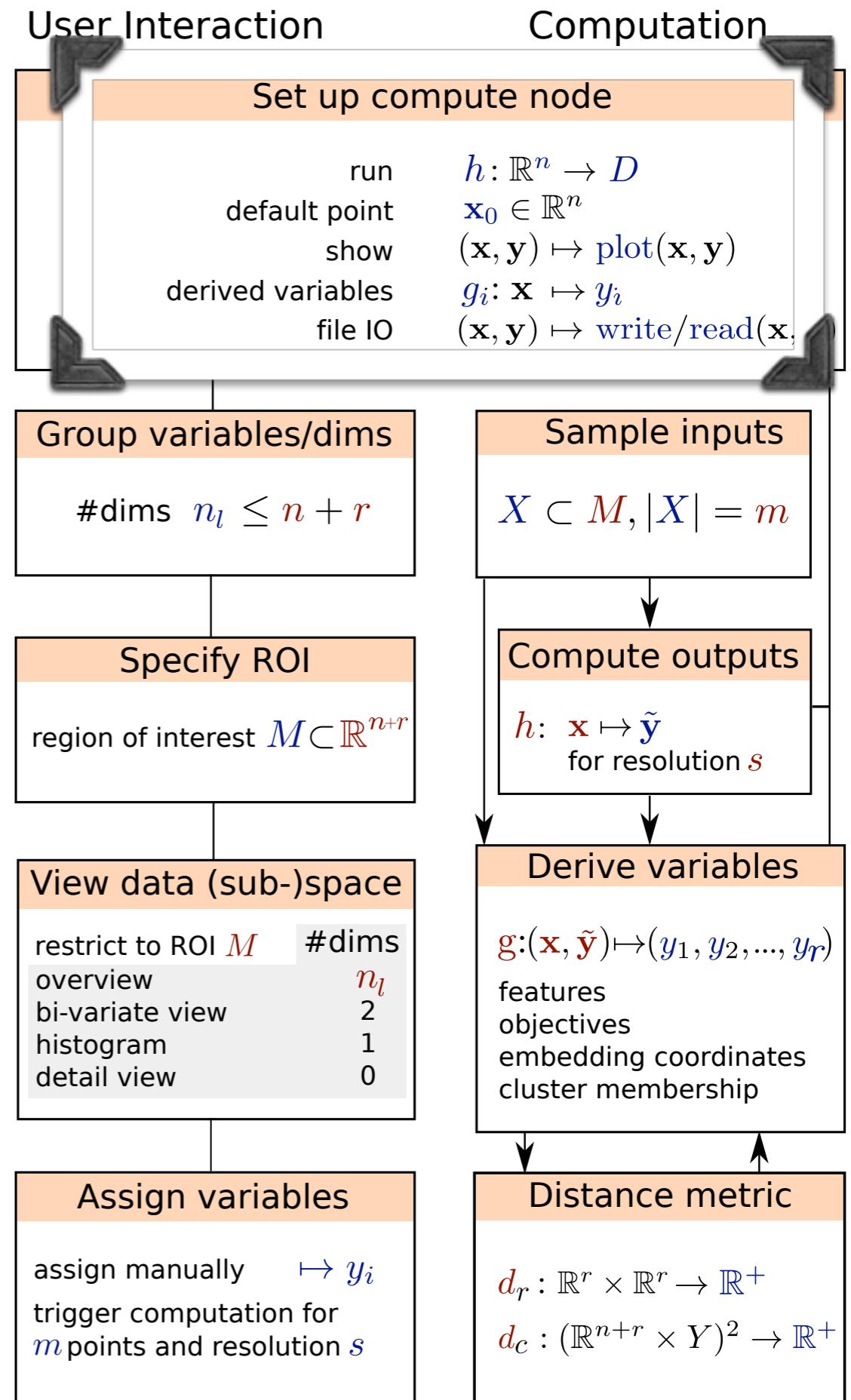
User Interaction

Computation



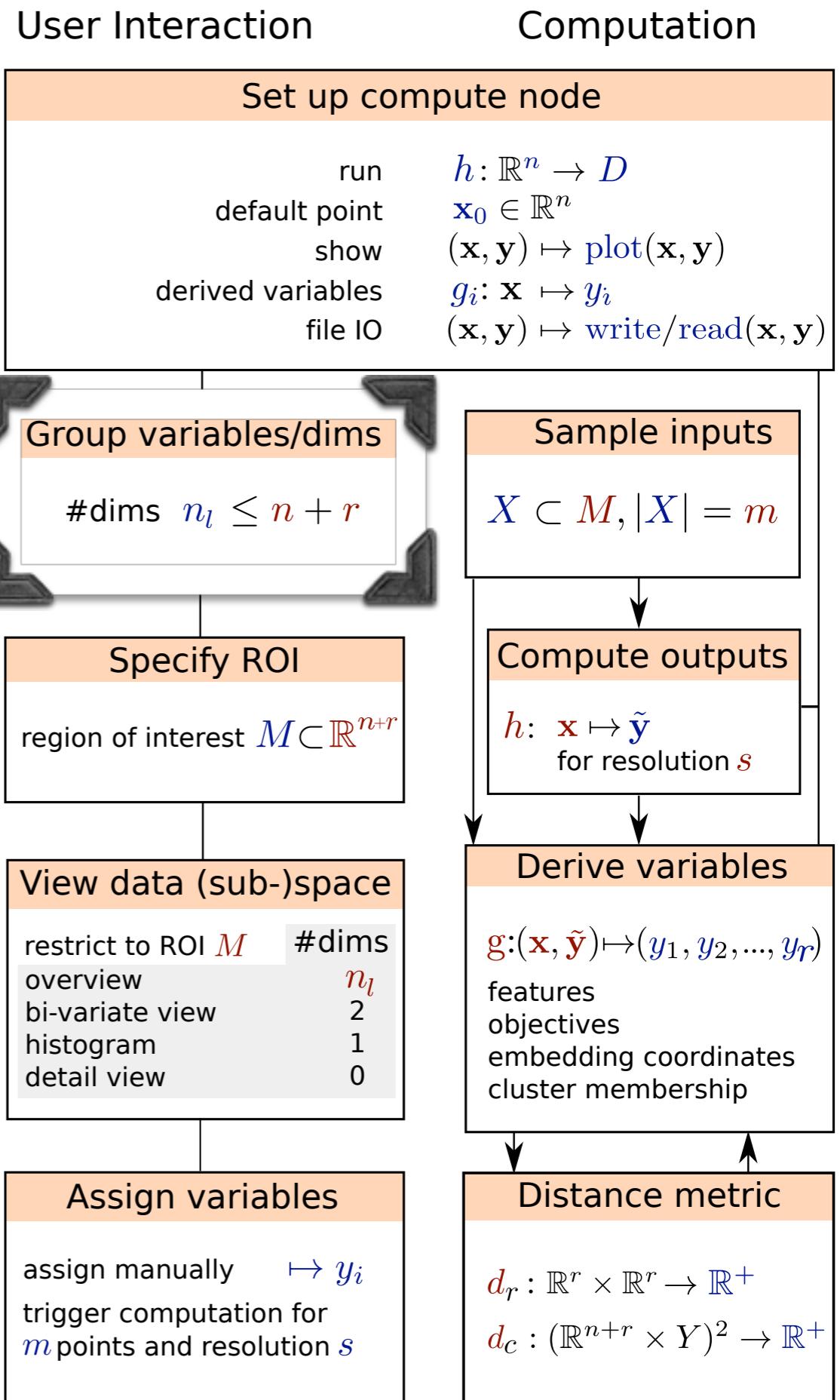
Paraglide design

- Setup compute node



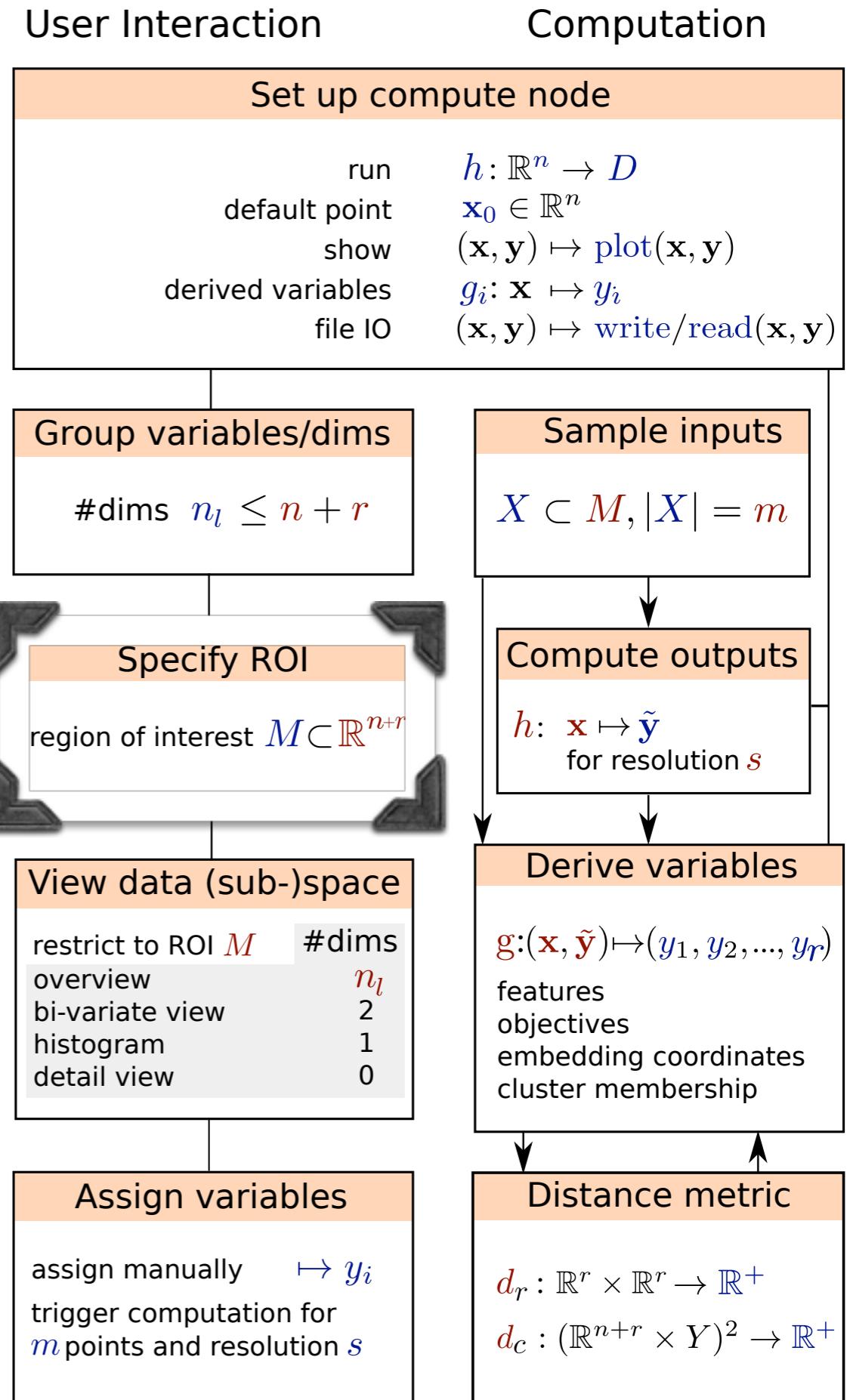
Paraglide design

- Setup compute node
- Choose variables



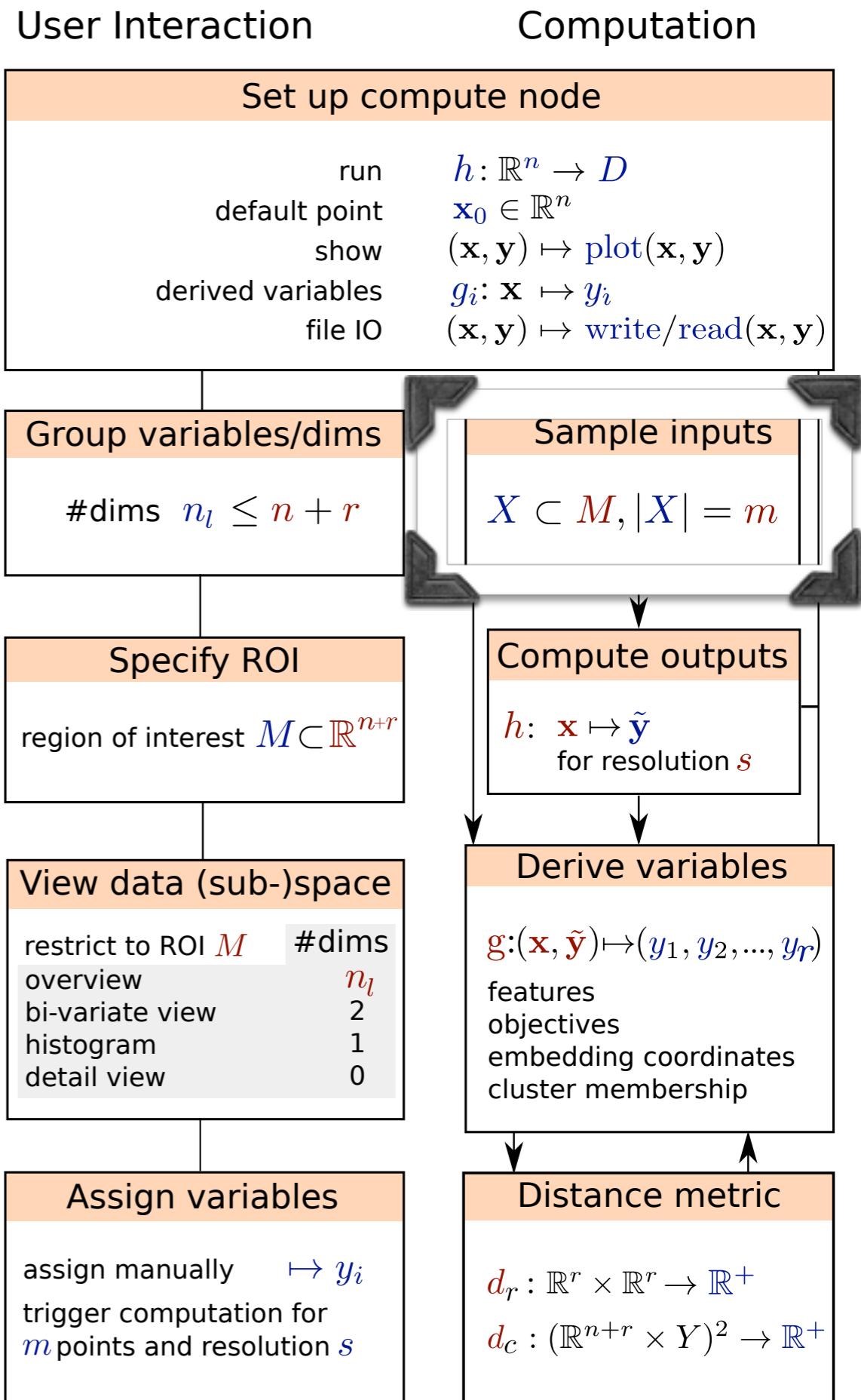
Paraglide design

- Setup compute node
 - Choose variables
 - Choose region



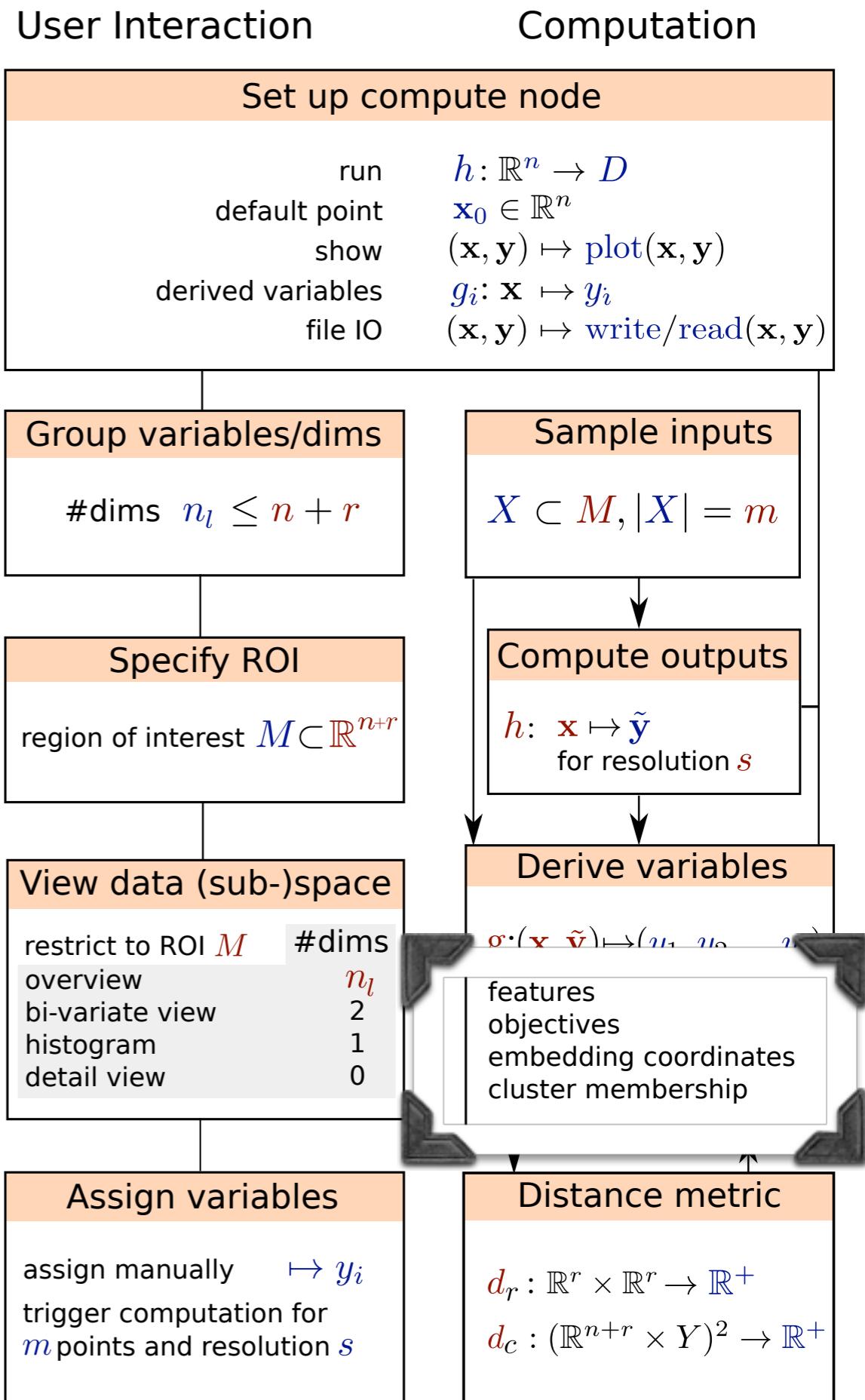
Paraglide design

- Setup compute node
- Choose variables
- Choose region
- Sample and compute



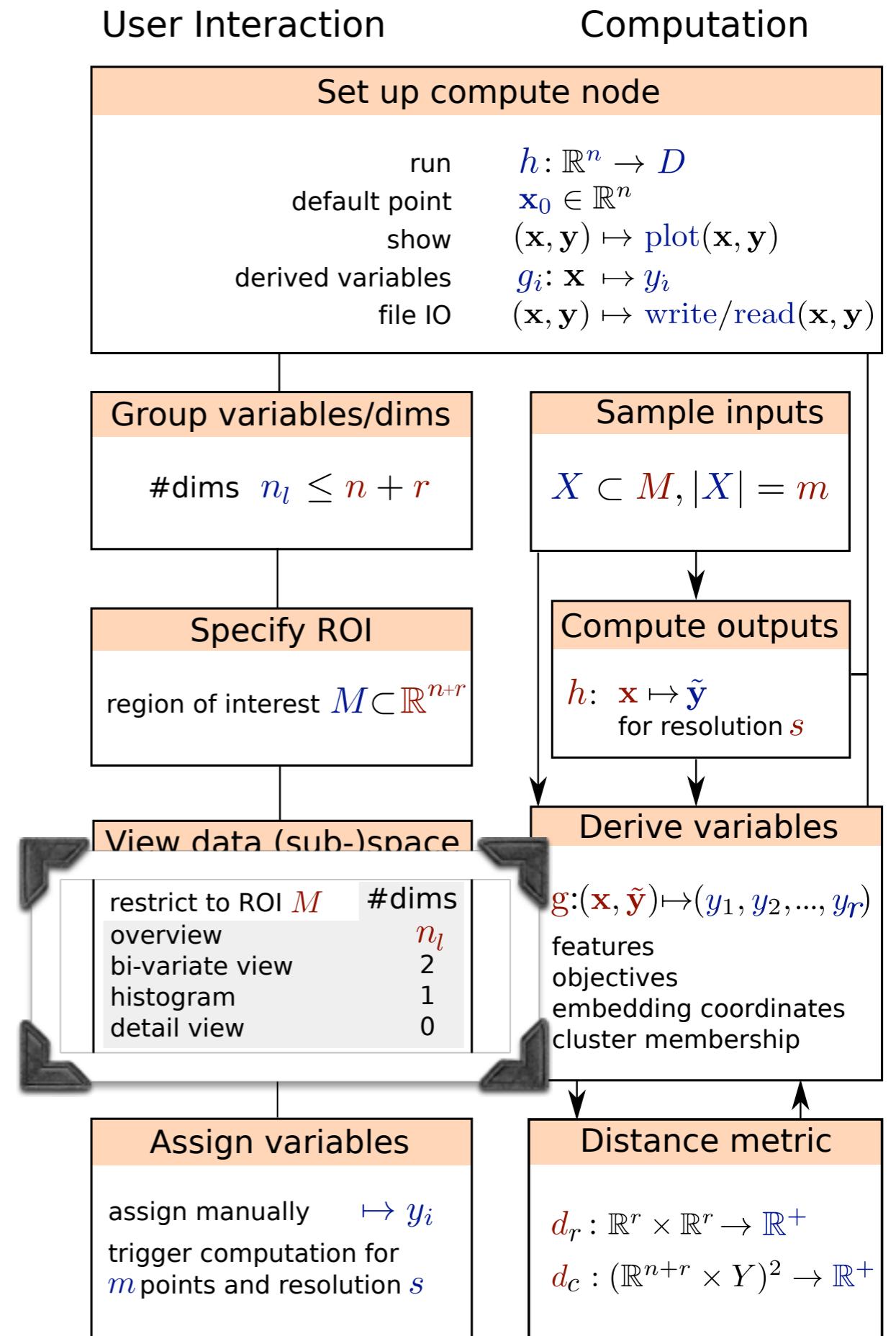
Paraglide design

- Setup compute node
- Choose variables
- Choose region
- Sample and compute
- Compute features



Paraglide design

- Setup compute node
- Choose variables
- Choose region
- Sample and compute
- Compute features
- View, predict, diagnose



Sampling the region of interest



Sampling the region of interest

- Tensor product of value levels for each dimension
 - ▶ Nested *for*-loops
 - ▶ Cost is exponential in #dims



Sampling the region of interest

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- Separate range specification from sample generation



Sampling the region of interest

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 - ▶ Nested *for-loops*
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Paraglide summary

- Longitudinal study showed use of parameter space partitioning
- Requirements informed follow-up projects
- Alternative user interaction
 - ▶ Dimensionally reduced slider embedding
 - ▶ Mixing board
- Video demo



Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
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Model adjustment at different levels

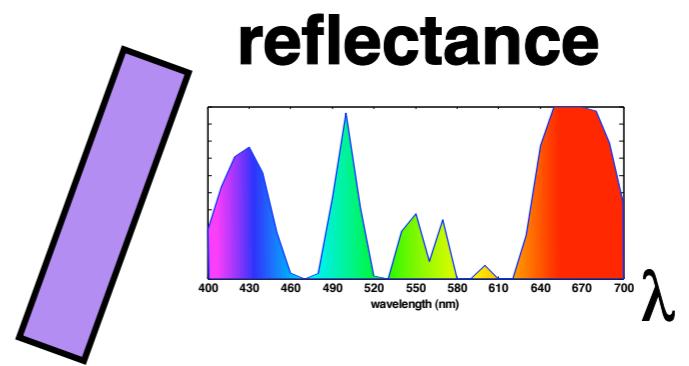
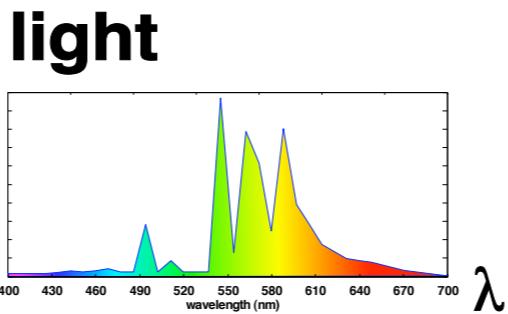
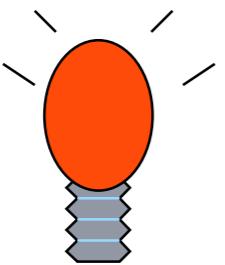
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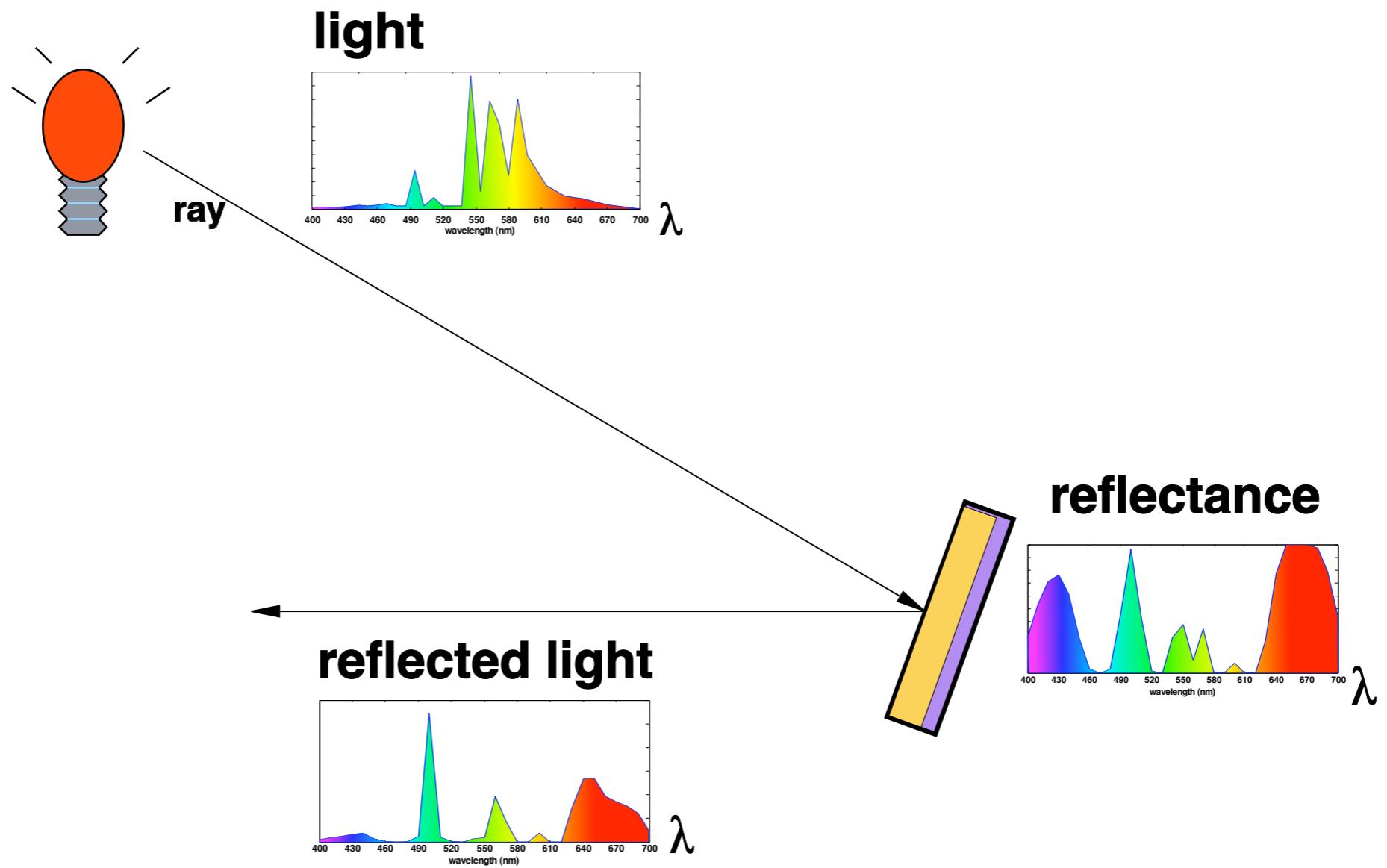
Roadmap

- From light to colour
- Efficient light model
- Designing spectra for lights and materials
- Evaluation
- Applications

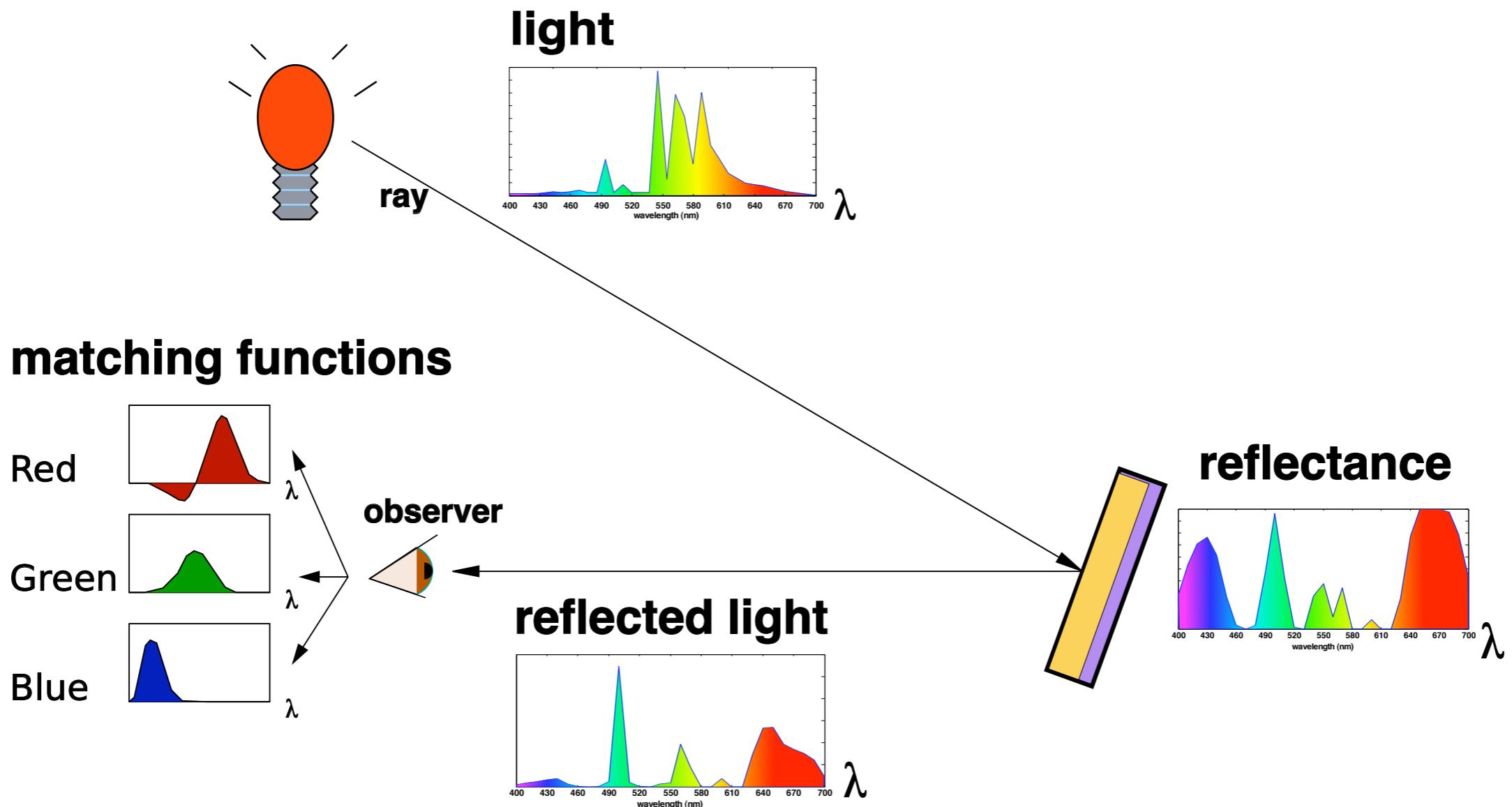
From Light to Colour



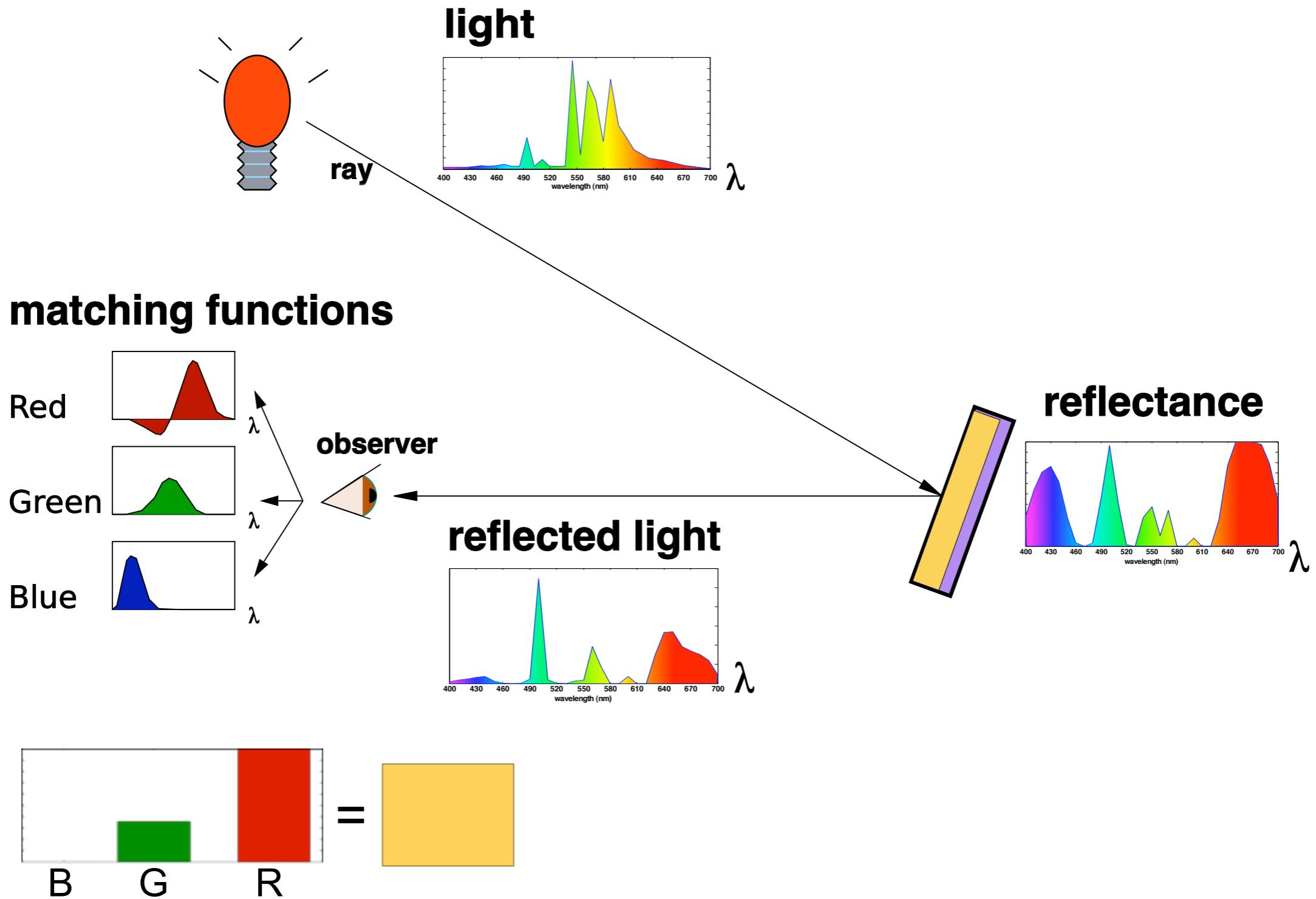
From Light to Colour



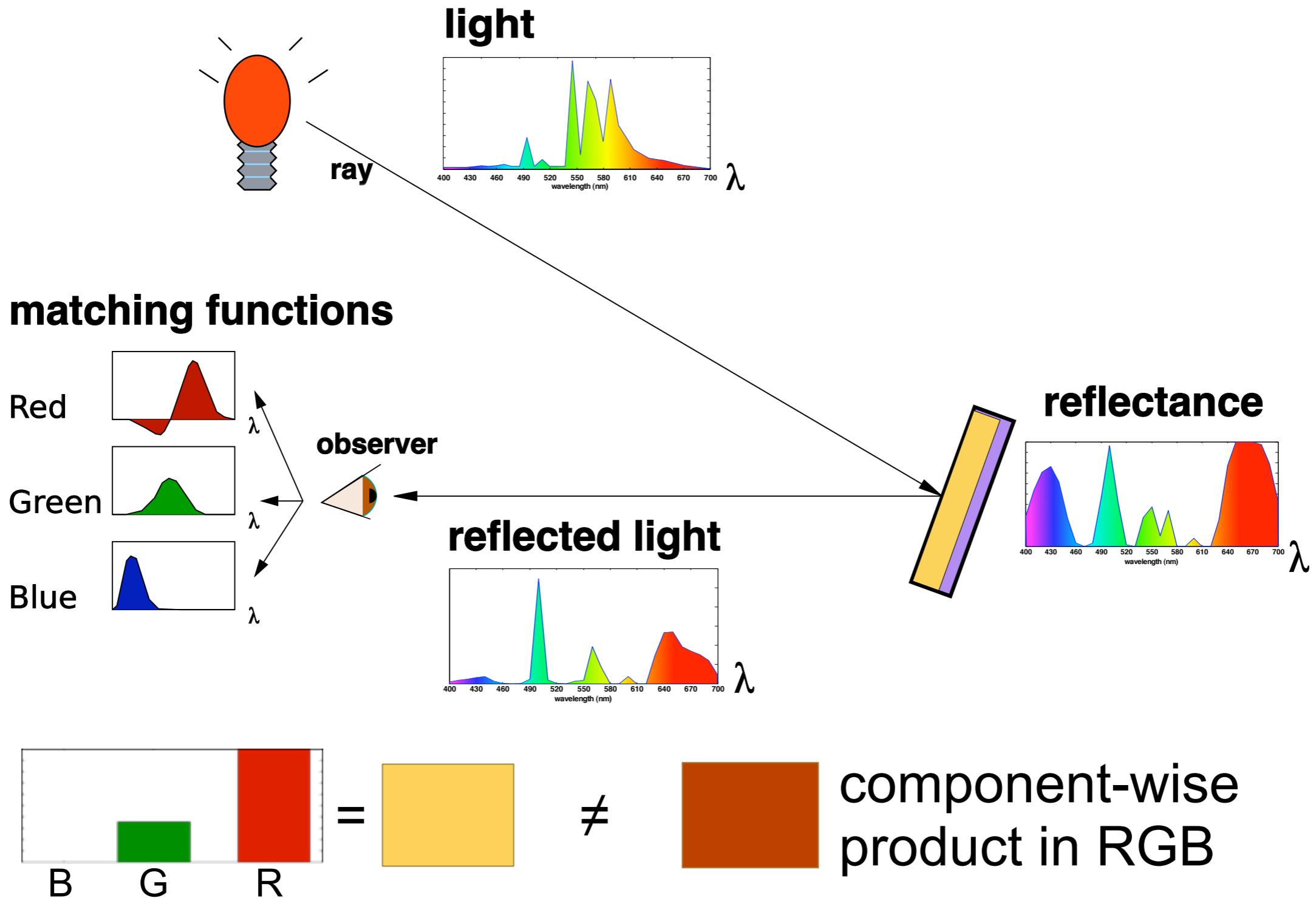
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From Light to Colour



From Light to Colour

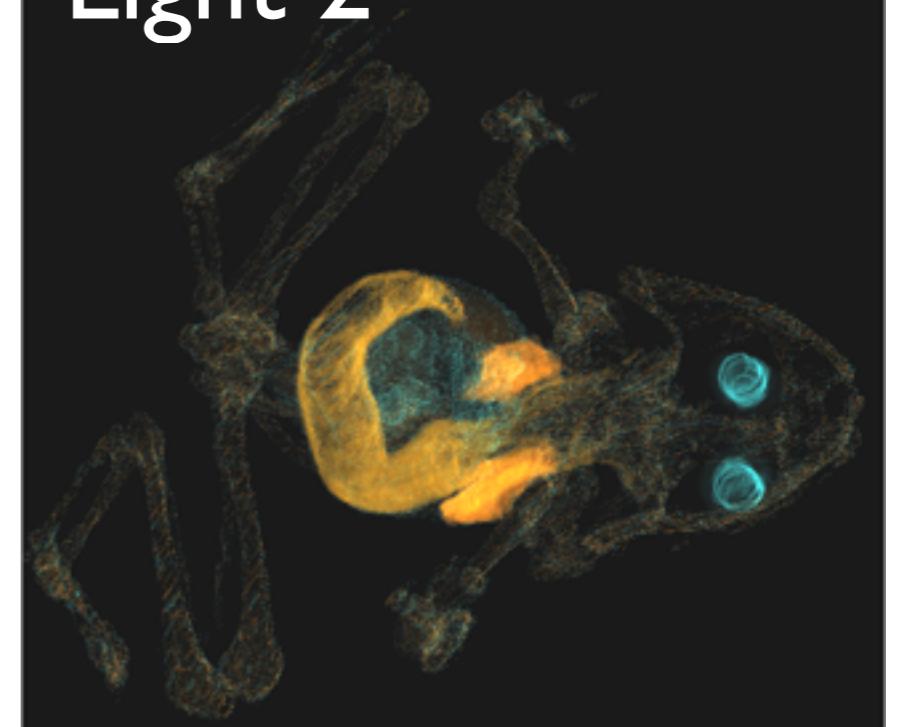


Use for Visualization

Light 1

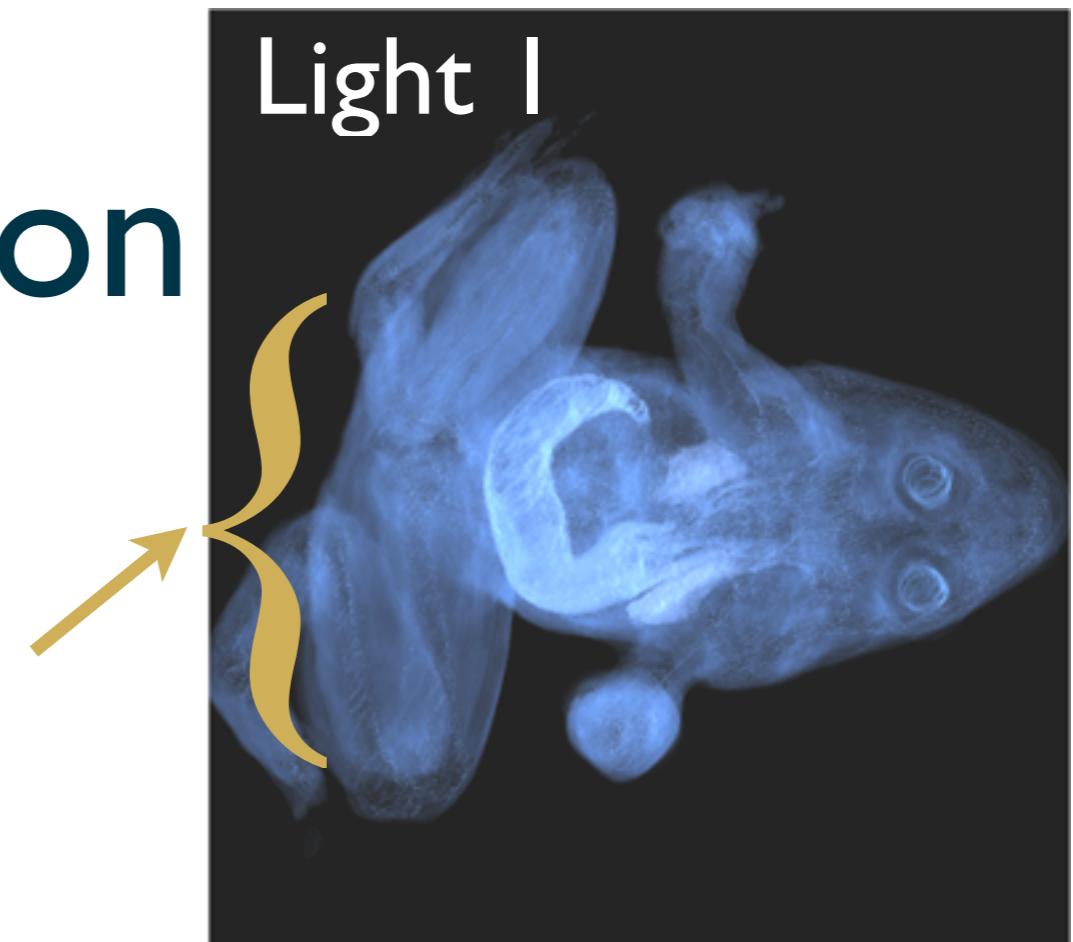


Light 2

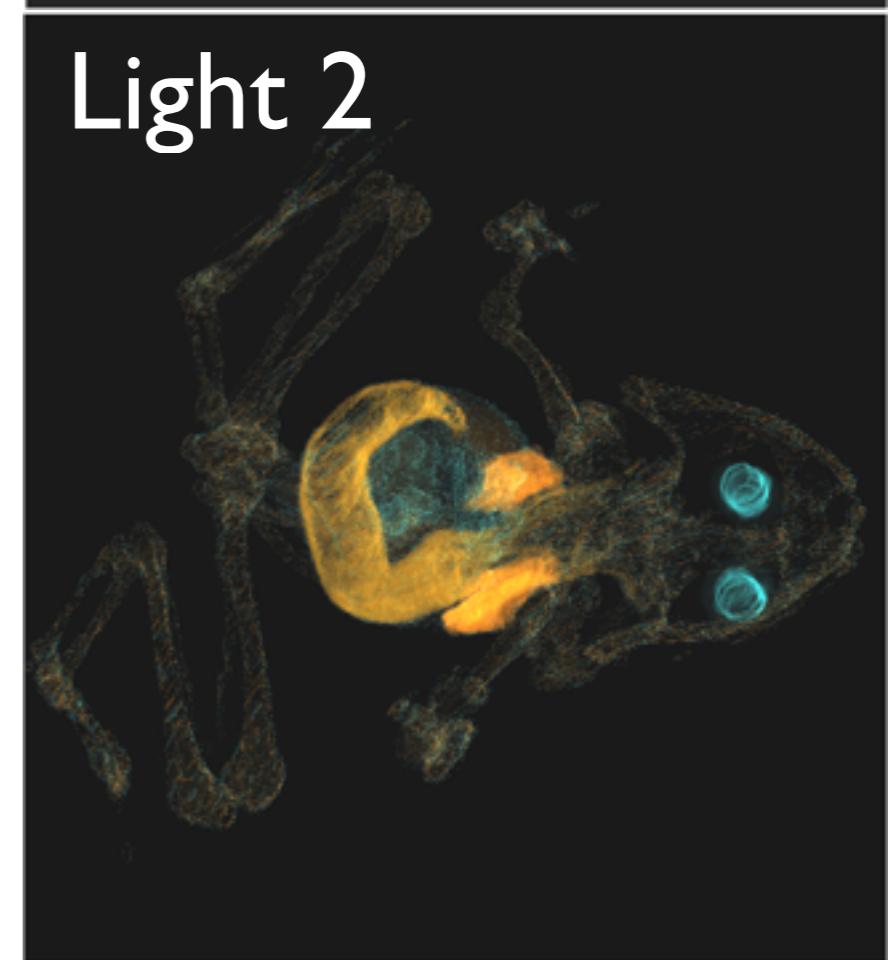


Use for Visualization

- Metamers
 - ▶ Different Spectra give same RGB



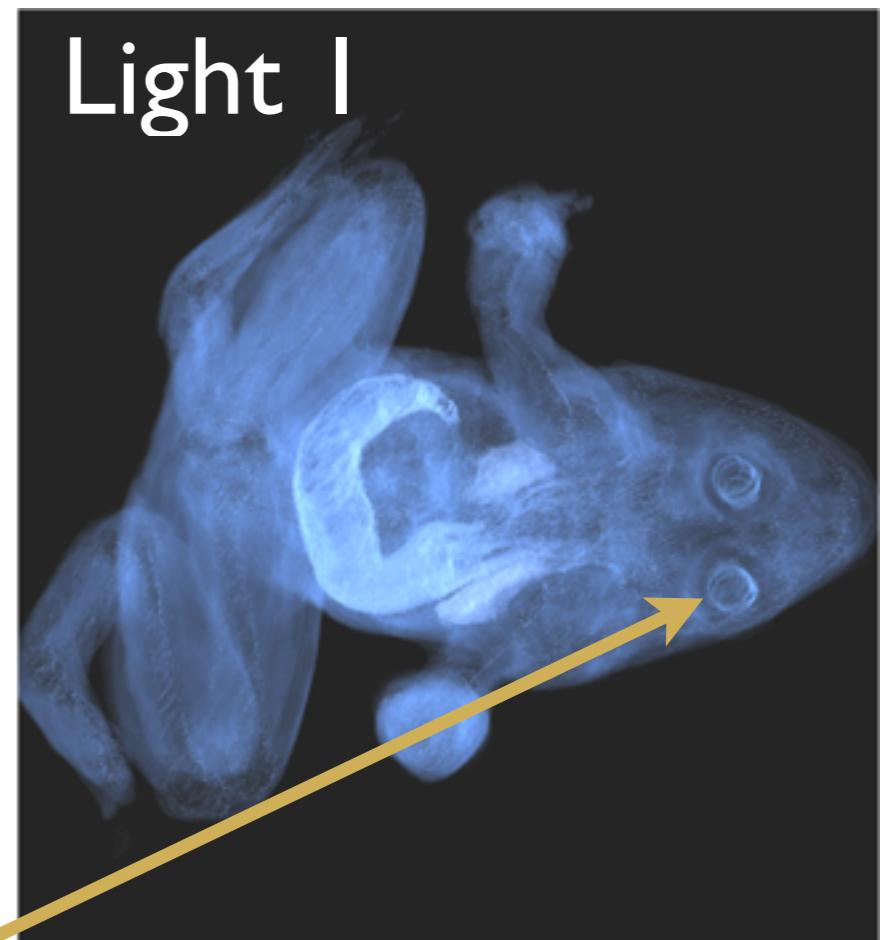
Light 1



Light 2

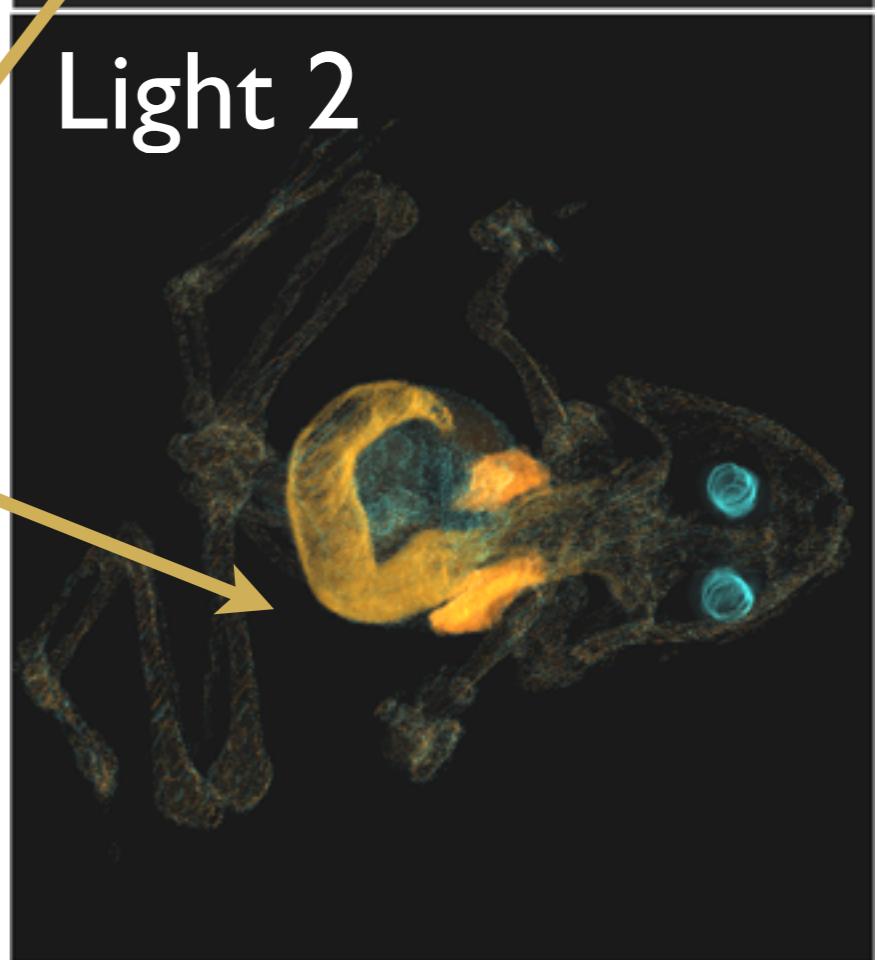
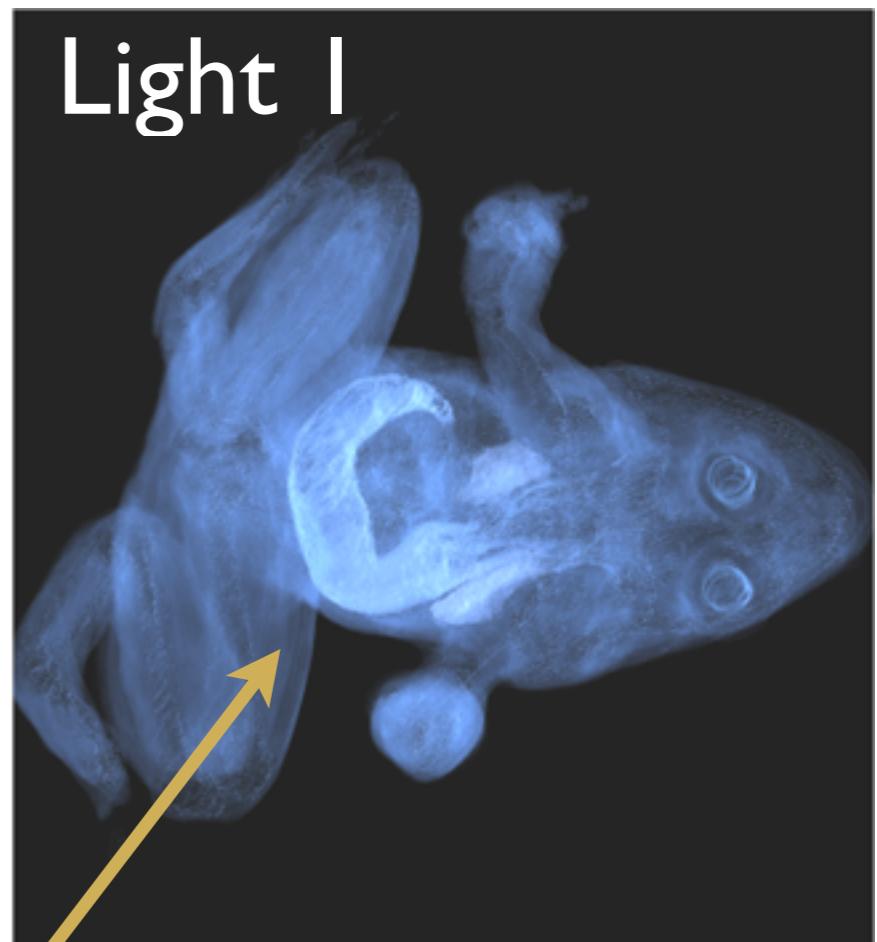
Use for Visualization

- Metamers
 - ▶ Different Spectra give same RGB
- Constant Colours
 - ▶ Metamers under changing light

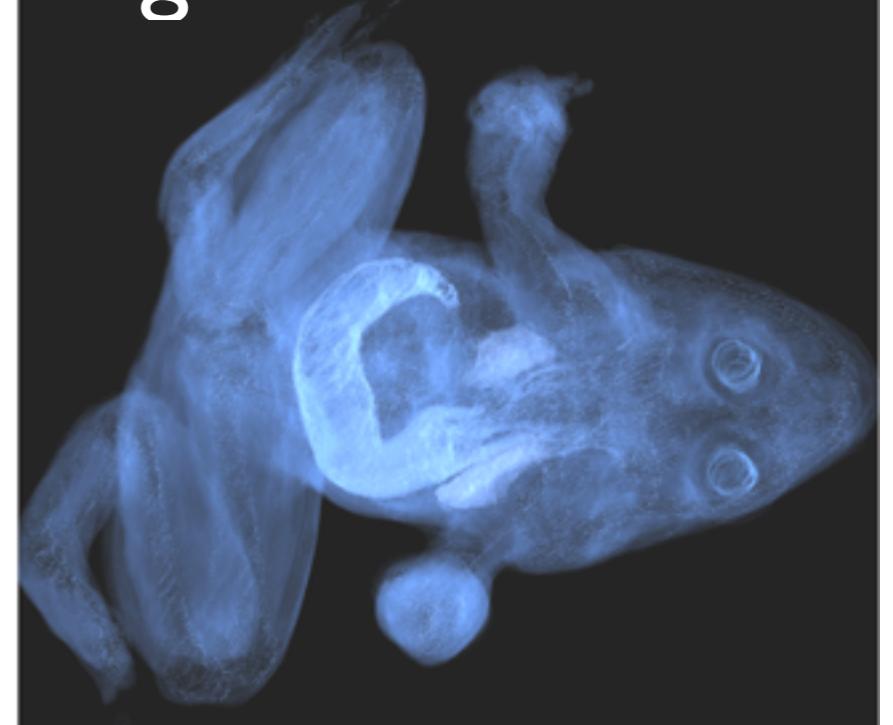


Use for Visualization

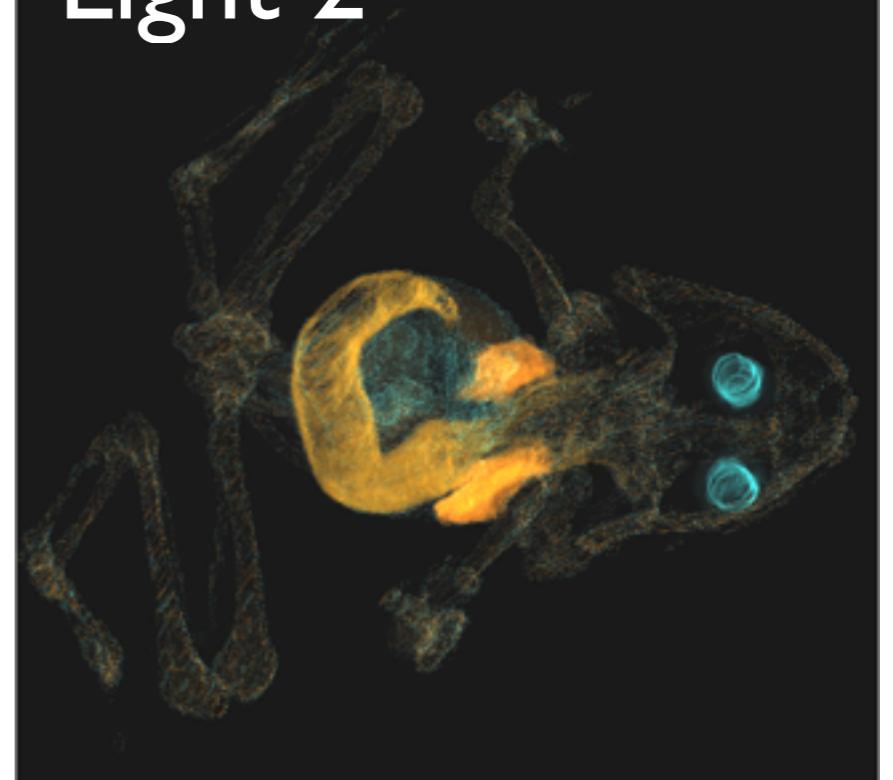
- Metamers
 - ▶ Different Spectra give same RGB
- Constant Colours
 - ▶ Metamers under changing light
- Metameric Blacks
 - ▶ Spectra give RGB triple = 0



Light I



Light 2



Use for Visualization

- Metamers
 - ▶ Different Spectra give same RGB
- Constant Colours
 - ▶ Metamers under changing light
- Metameric Blacks
 - ▶ Spectra give $\text{RGB triple} = 0$
- Effective choice of light & material palette needed!

Roadmap

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Illumination Dependent Colour Picker



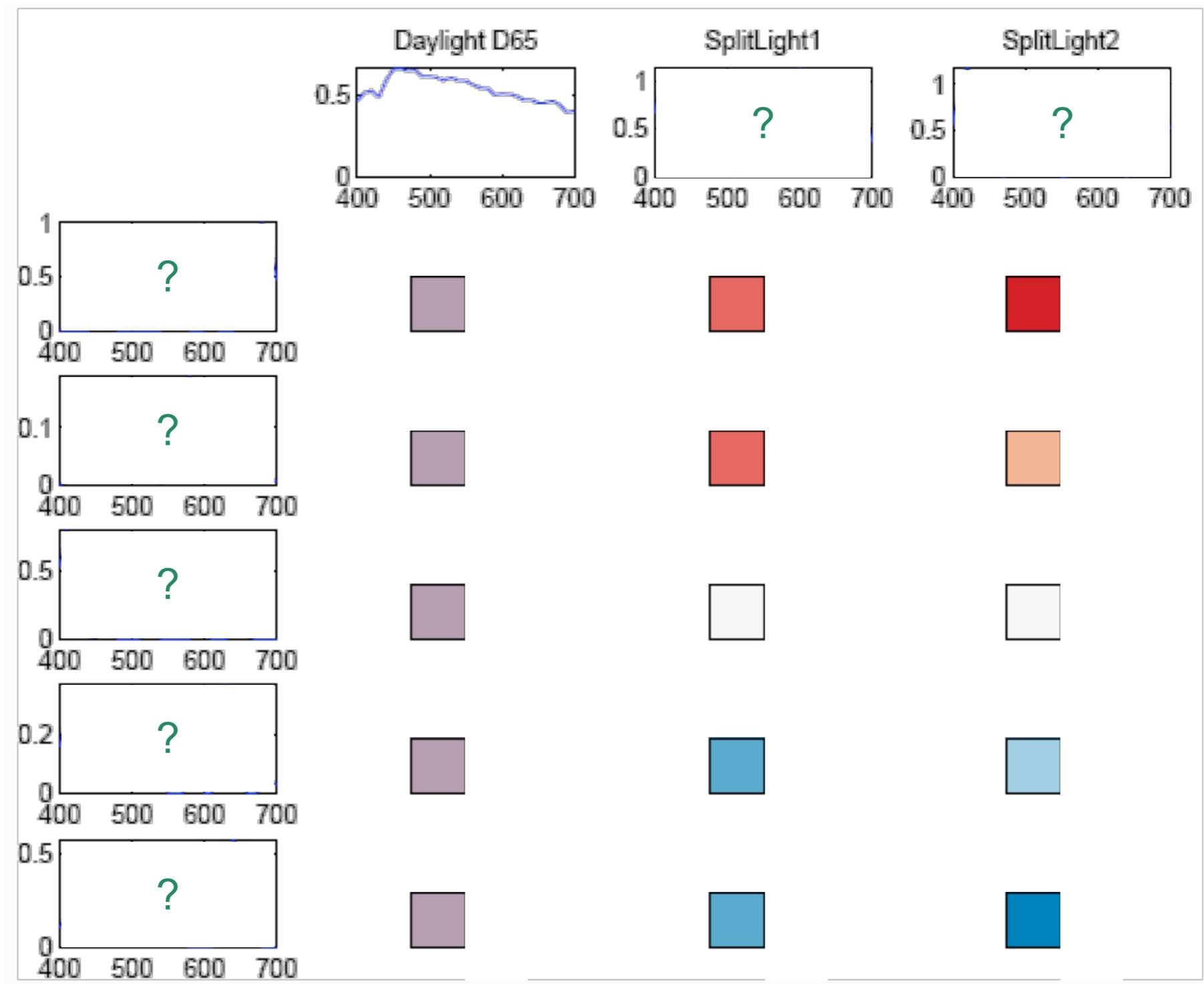
Illumination Dependent Colour Picker



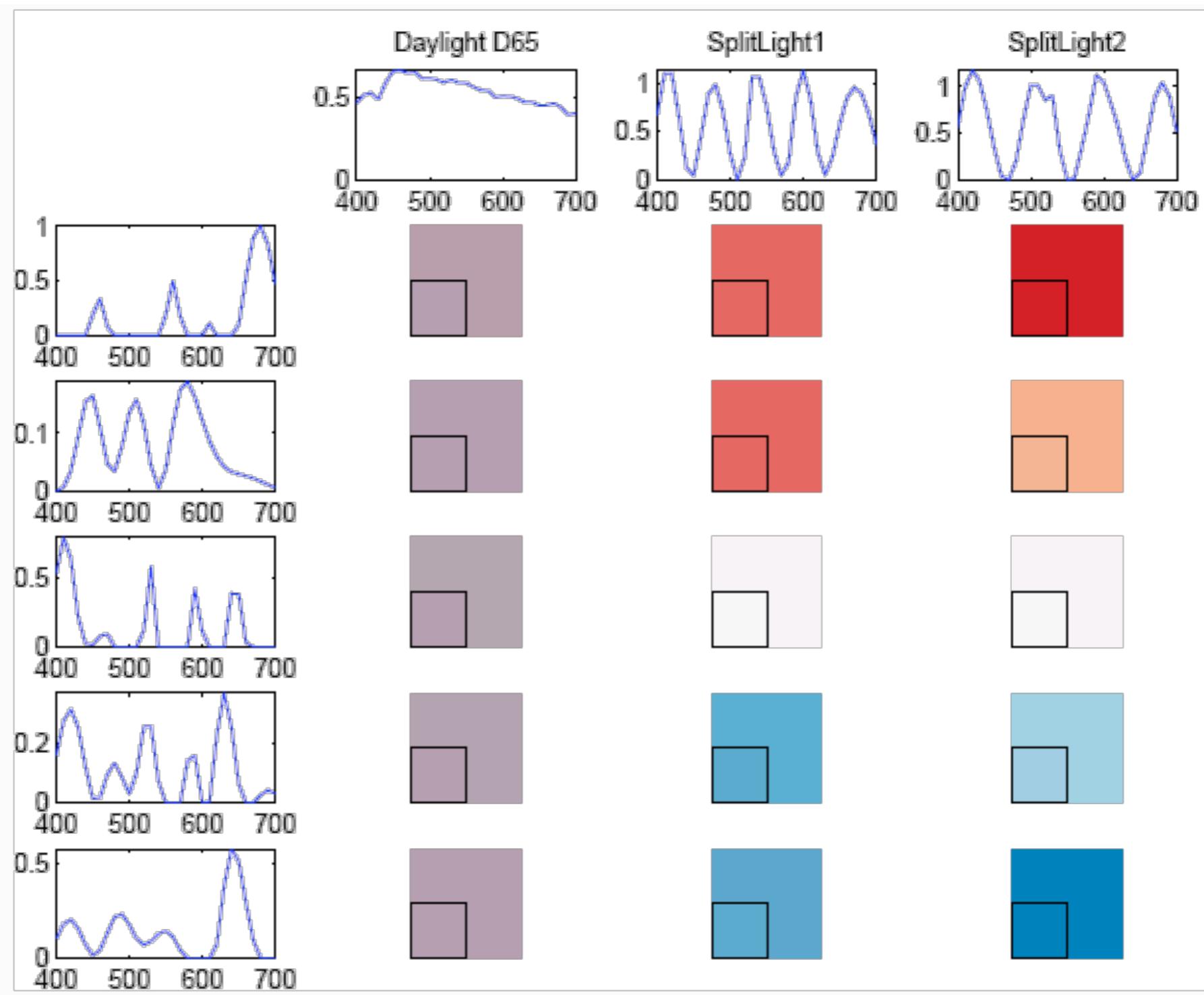
Illumination Dependent Colour Picker



Illumination Dependent Colour Picker



Illumination Dependent Colour Picker



Quality Criteria

- Colour
 - Fit the desired colour or metamer
- Smoothness
 - Regularize solution and reduce extrema
- Minimal error in linear model
 - Minimal colour difference when illumination bounce is computed in linear subspace
- Positivity
 - Produce physically plausible spectra

Quality Criteria

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- Instead of equation system $\mathbf{M}\vec{x} = \vec{y}$ for spectrum \vec{x}
Solve normal equation $\operatorname{argmin}_{\vec{x}} \|\mathbf{M}\vec{x} - \vec{y}\|$

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— Colour: $\operatorname{argmin}_{\vec{x}} \left\| \begin{bmatrix} \mathbf{m}_{red} \\ \mathbf{m}_{green} \\ \mathbf{m}_{blue} \end{bmatrix} \operatorname{diag}(\vec{S}) \vec{x} - \begin{bmatrix} c_r \\ c_g \\ c_b \end{bmatrix} \right\|$

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— Smoothness: $\operatorname{argmin}_{\vec{x}} \left\| \begin{bmatrix} -1 & 2 & -1 & 0 & \dots & 0 \\ 0 & -1 & 2 & -1 & \dots & 0 \\ & & \ddots & & & \\ 0 & 0 & \dots & -1 & 2 & -1 \end{bmatrix} \vec{x} - \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right\|$

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- Weight the criteria and combine as stacked matrix
 - Global minimum error solution via pseudo-inverse of \mathbf{M}
 - Positivity through quadratic programming

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Materials and lighting

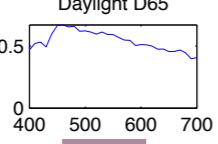


Materials and lighting

Given: Output	Goal: Input



Materials and lighting

Given: Output			Goal: Input
<p>Daylight D65</p>  <p>reflectances</p> <p>lights</p> <p>?</p> <ul style="list-style-type: none">• 3x5 combination colours with 3 components each	?	?	



Materials and lighting

Given: Output			Goal: Input			
	reflectances	lights		Daylight D65	SplitLight1	SplitLight2
?			?			
?			?			
?			?			
?			?			
?			?			
?			?			

- 3x5 combination colours with 3 components each
- 7x3 1 component SPDs



Image based re-lighting

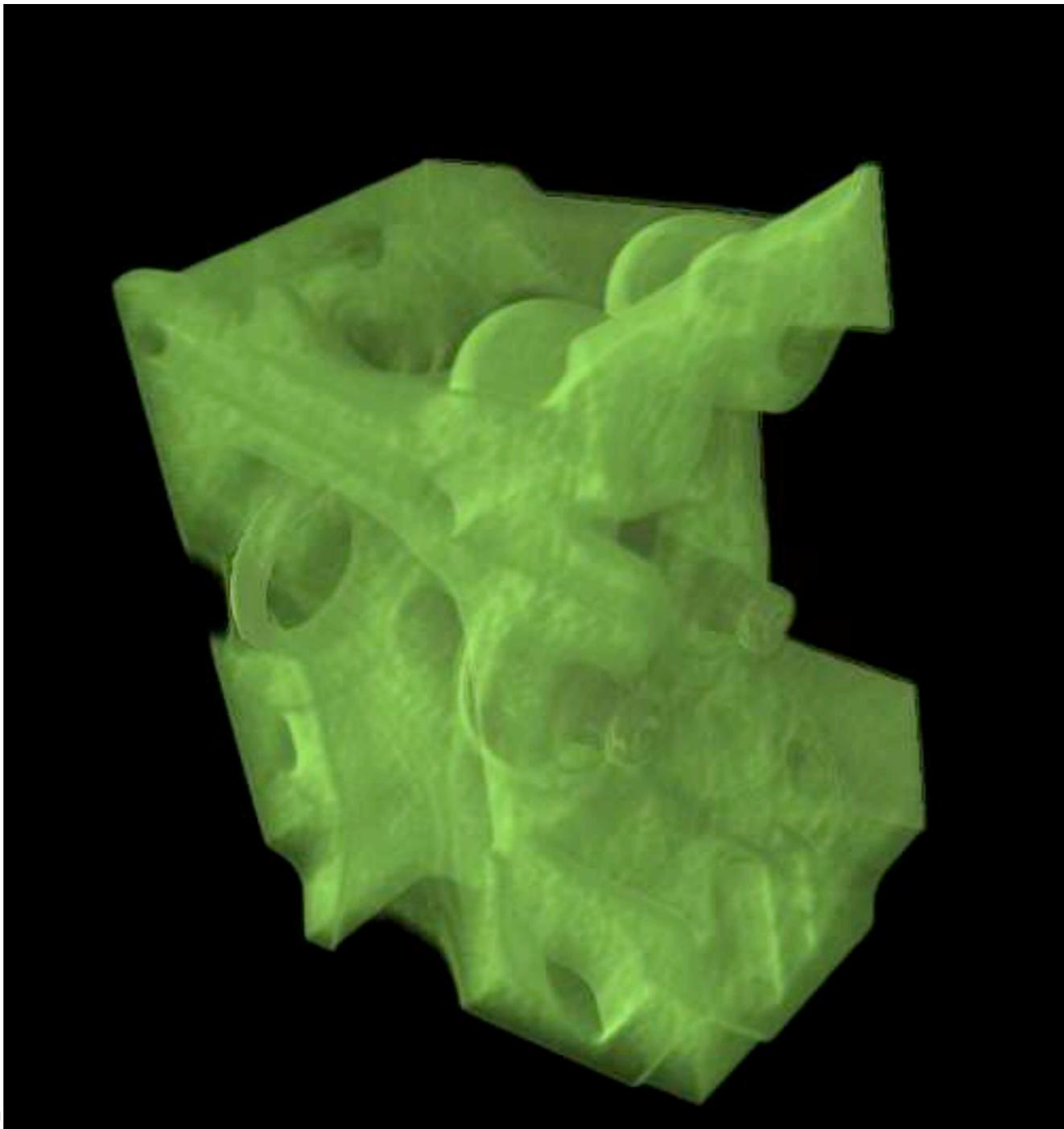


Image based re-lighting

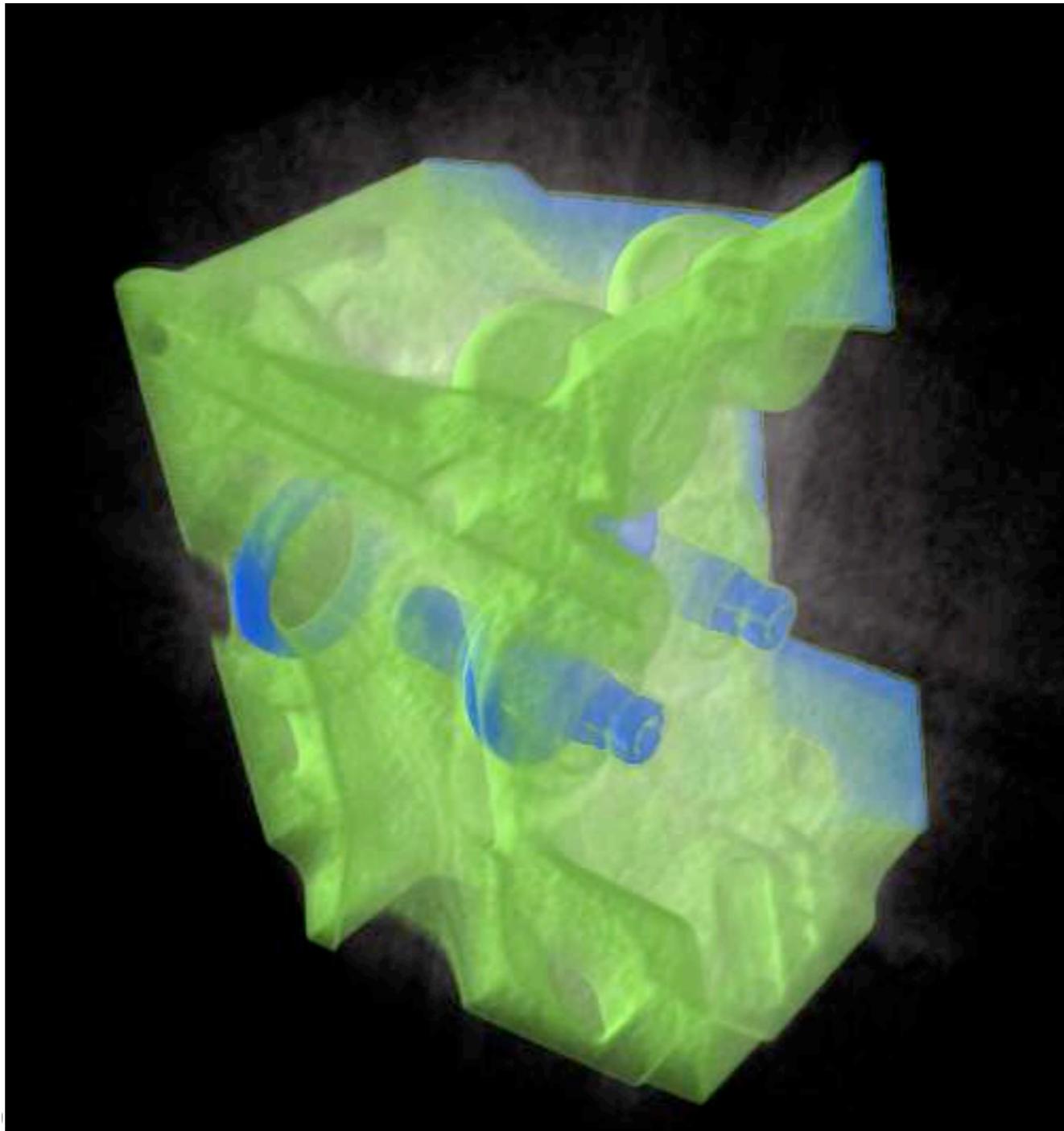
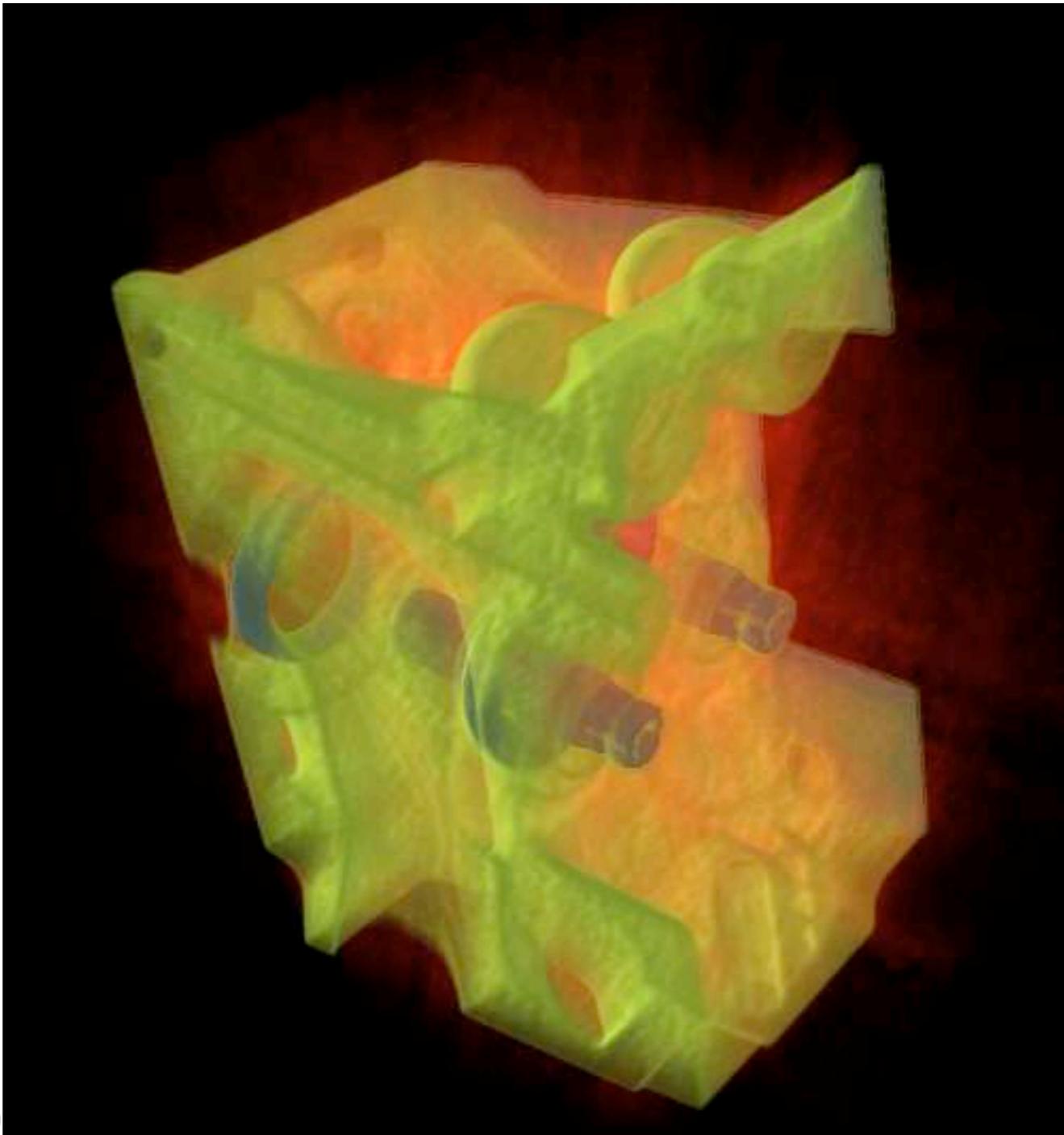
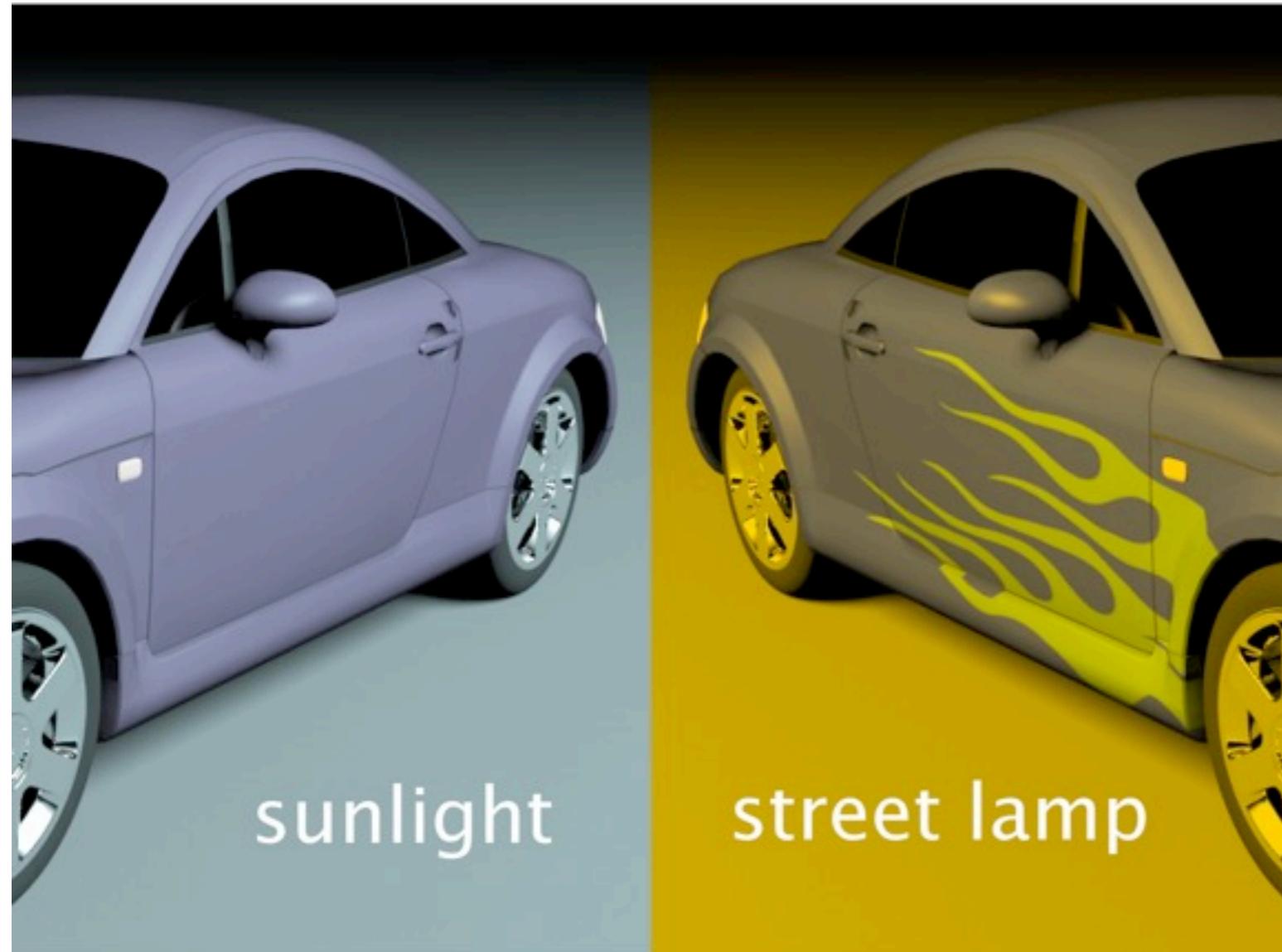


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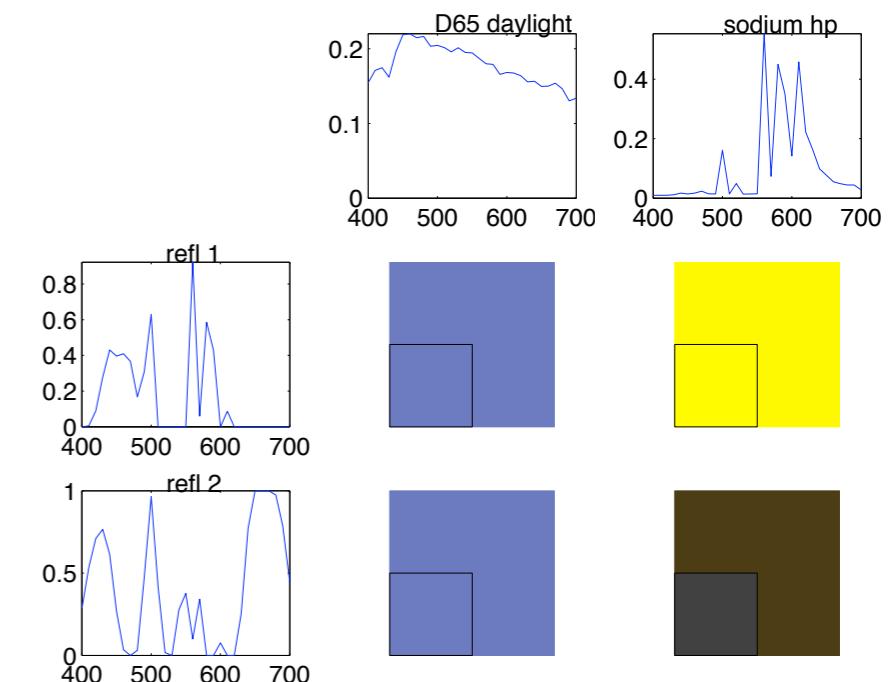


Applications in Graphics and Visualization



sunlight

street lamp



- Additional texture details appear under changing illumination

Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
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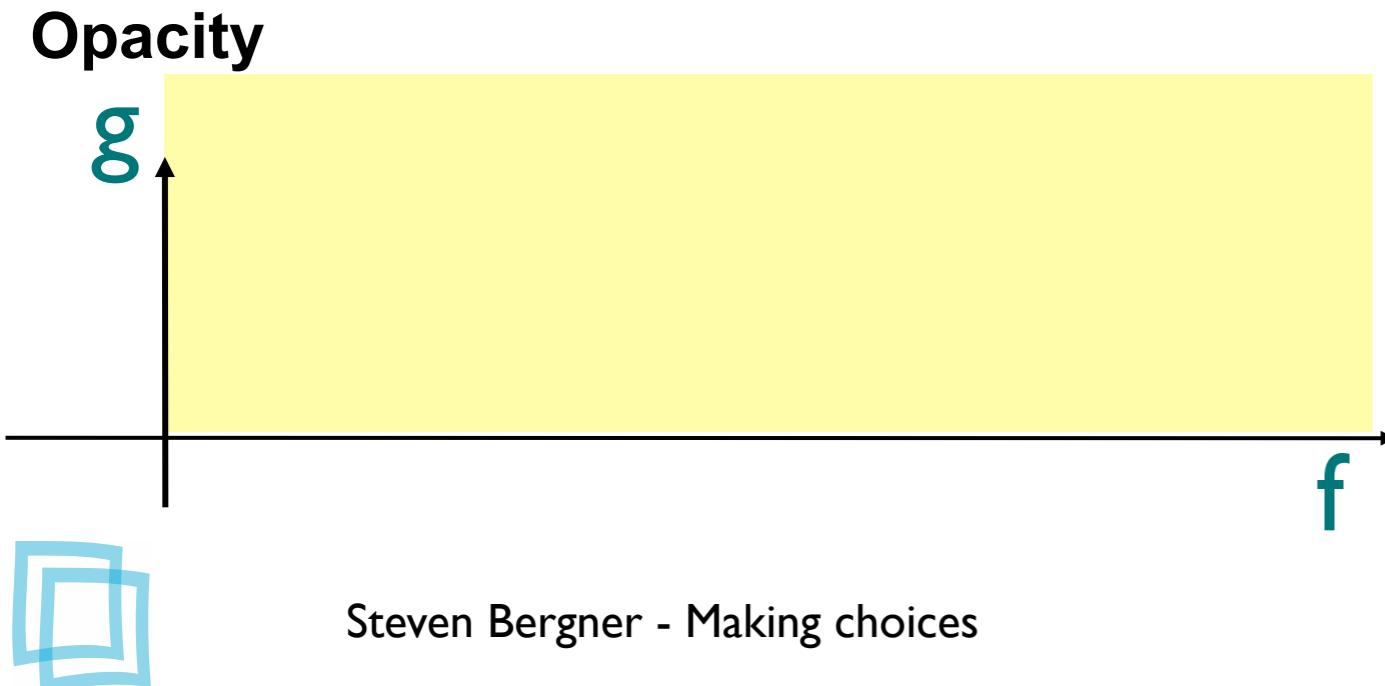


Volume Rendering

- Map data value f to optical properties using a transfer function $g(f(x))$

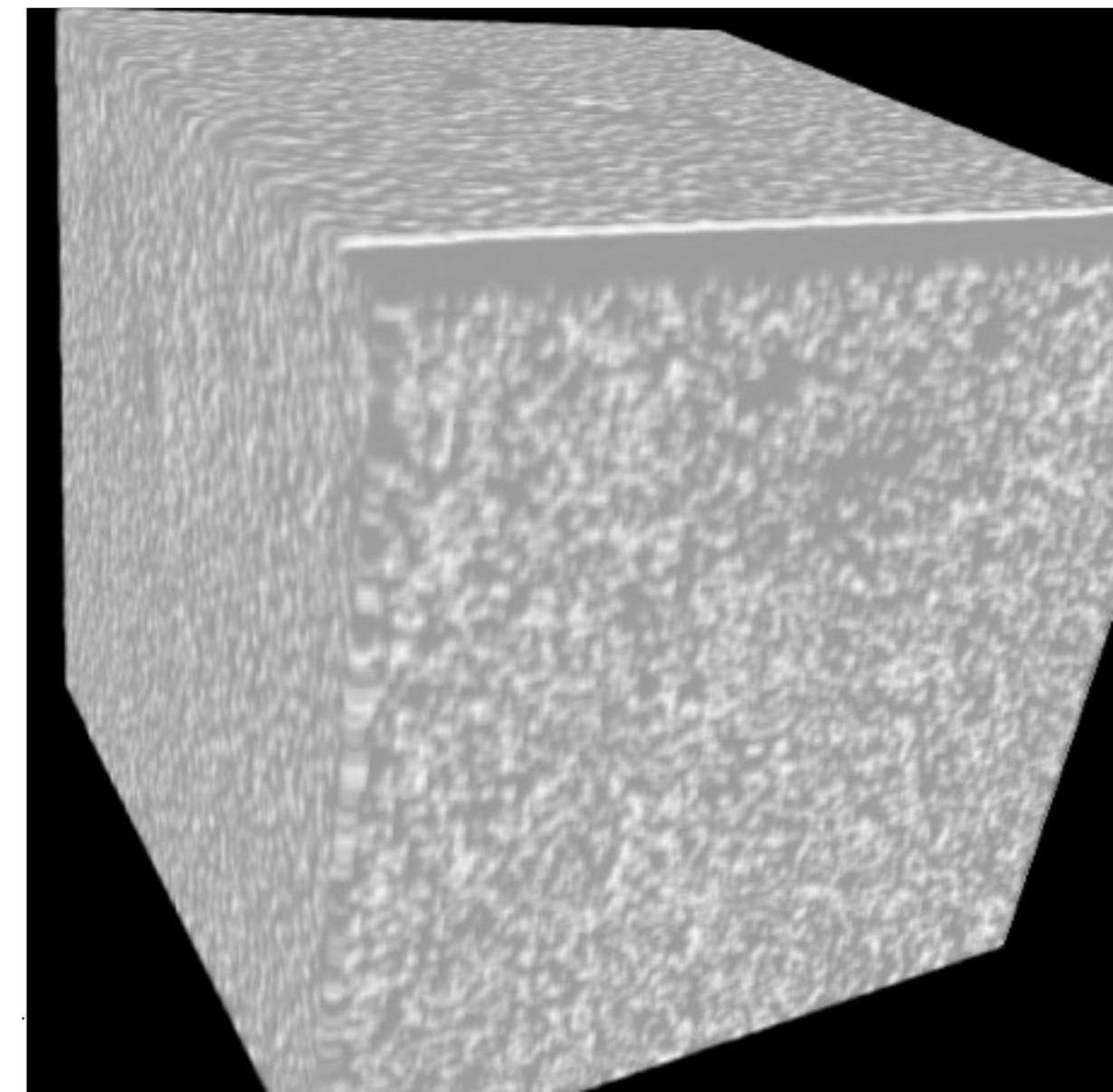
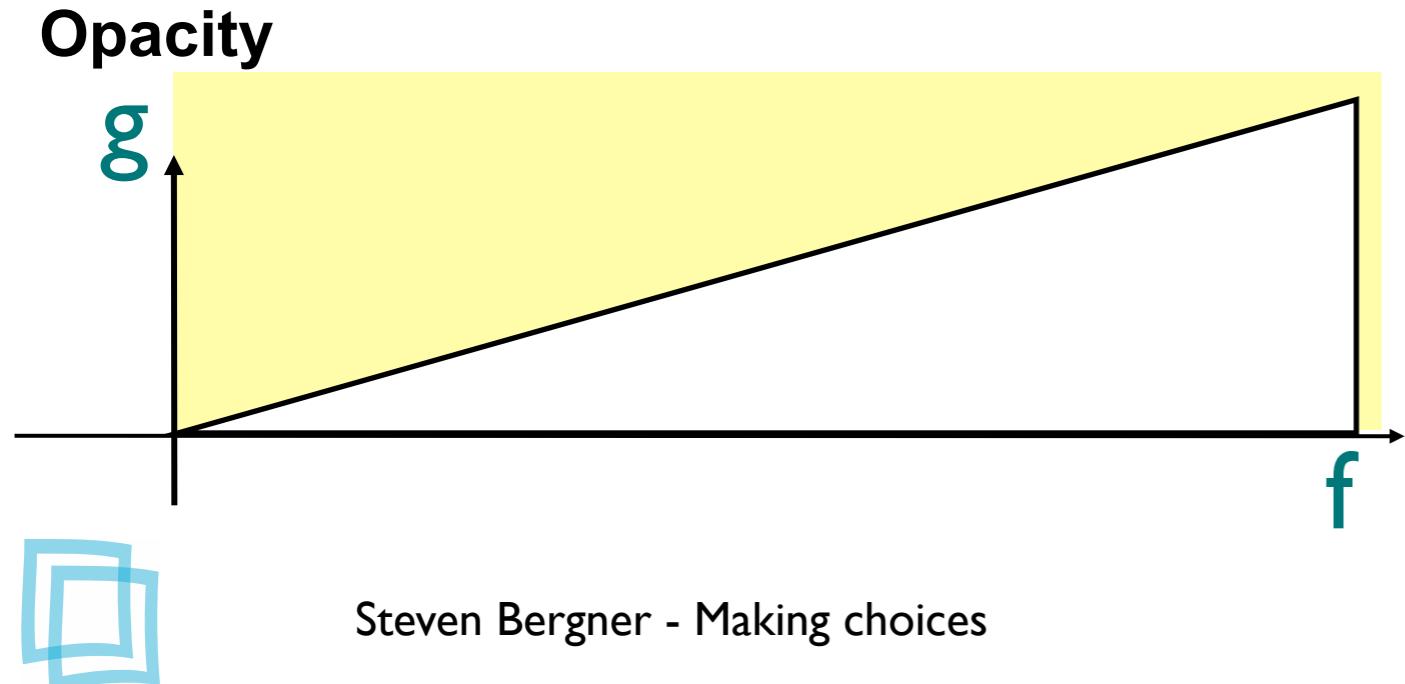
Volume Rendering

- Map data value f to optical properties using a transfer function $g(f(x))$
- Then shading+compositing



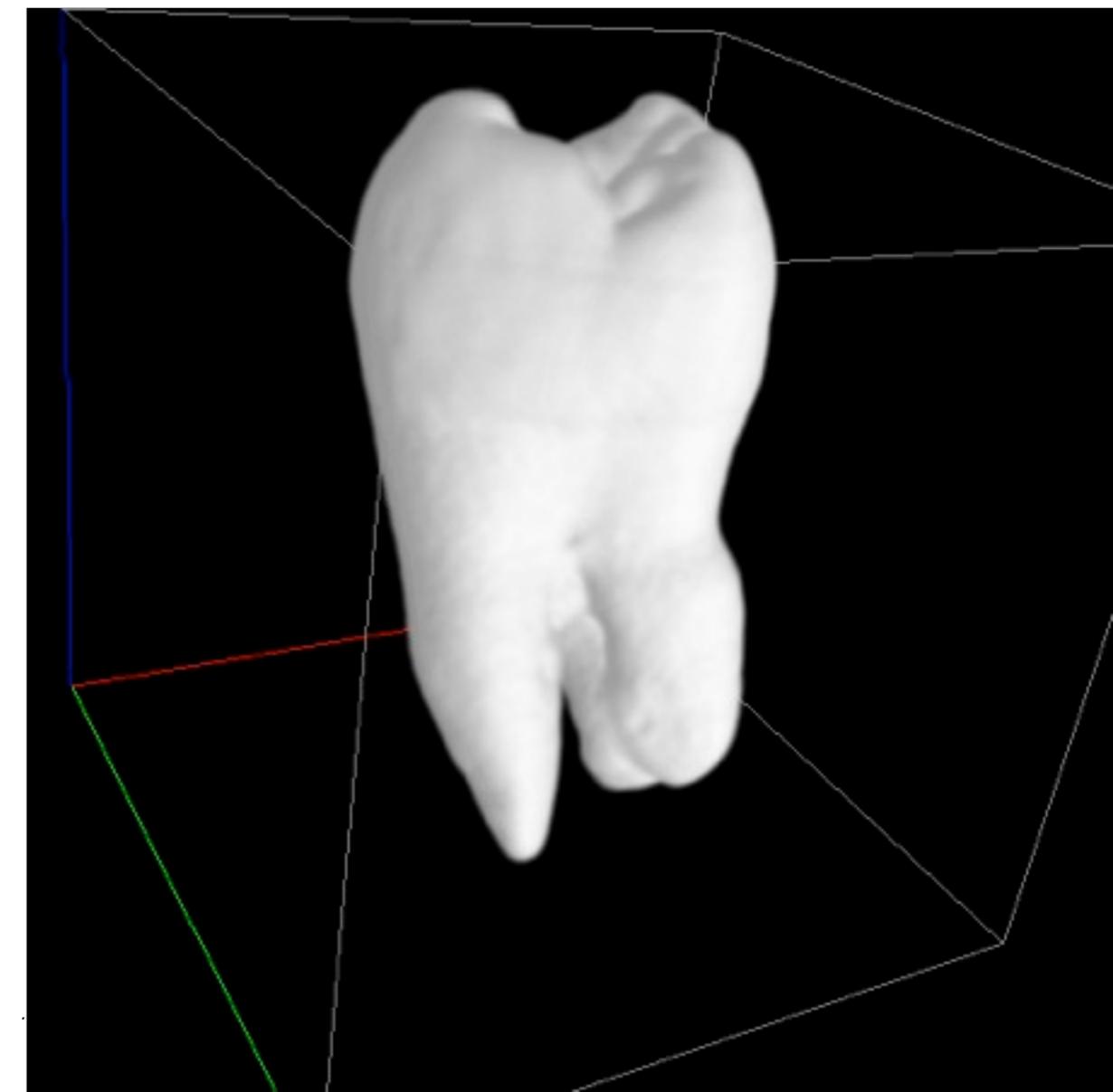
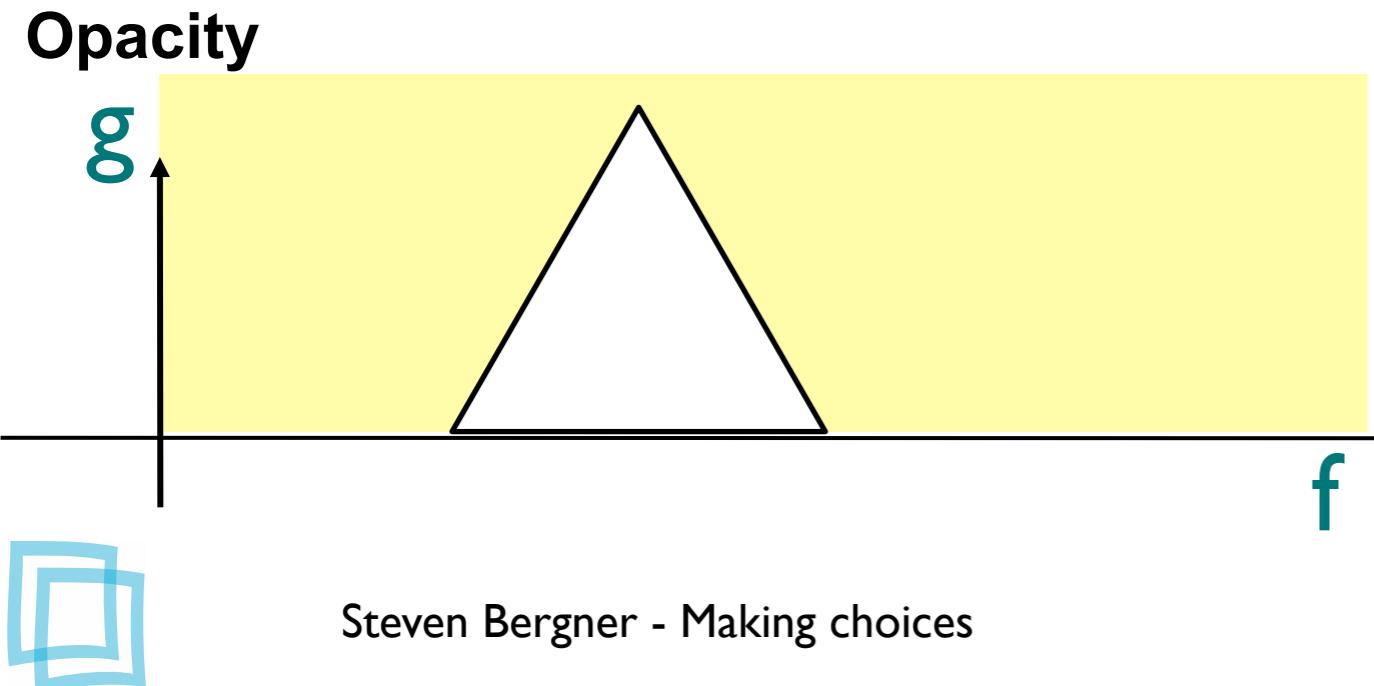
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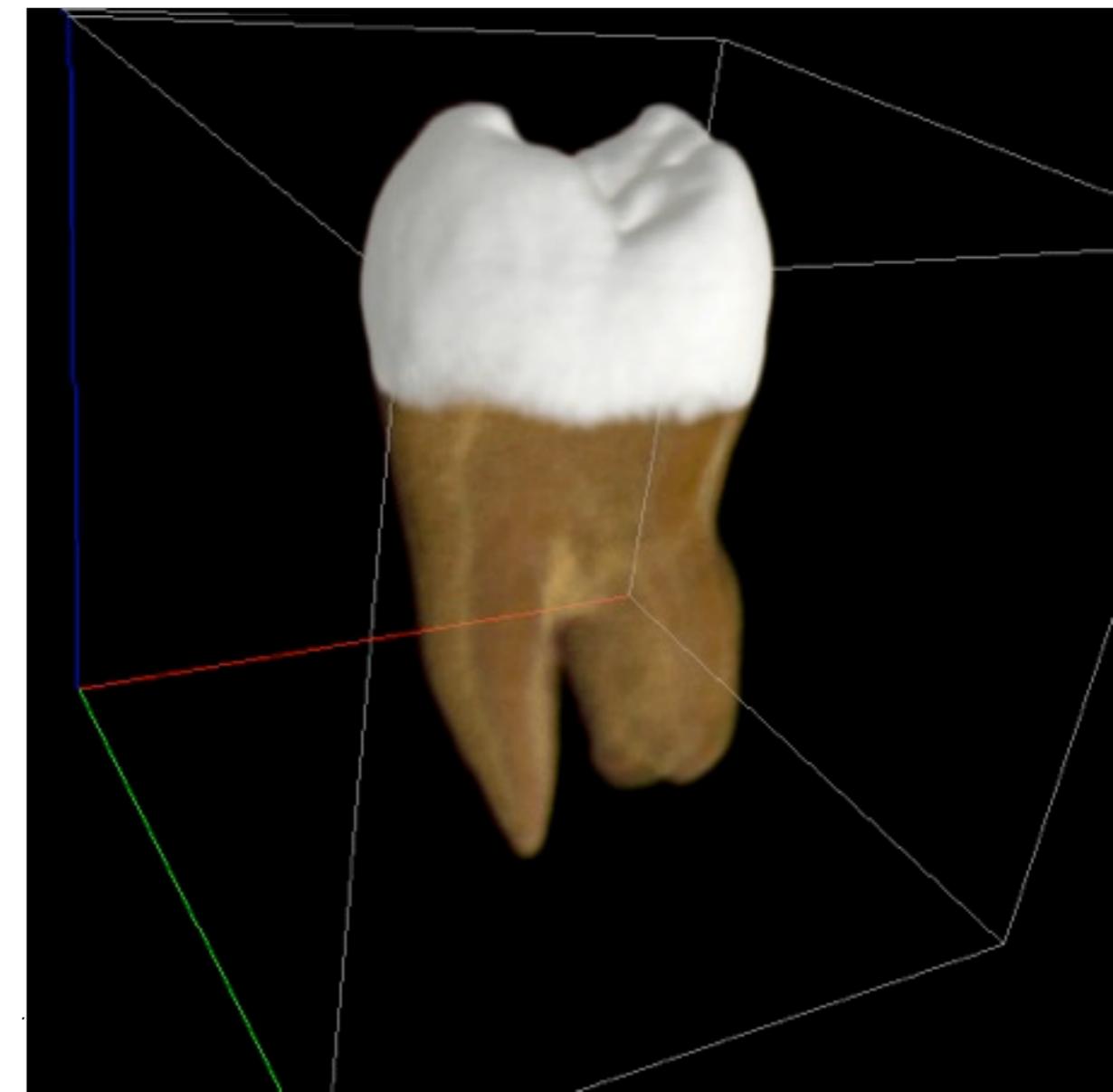
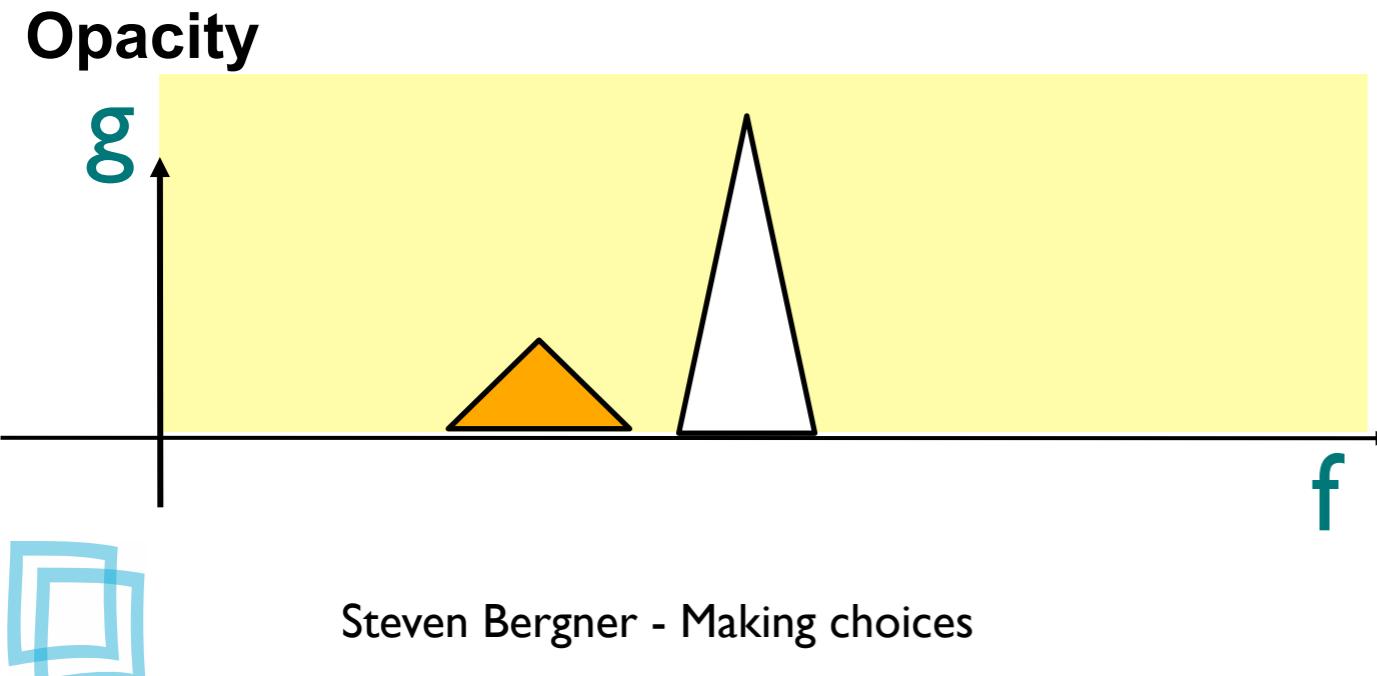
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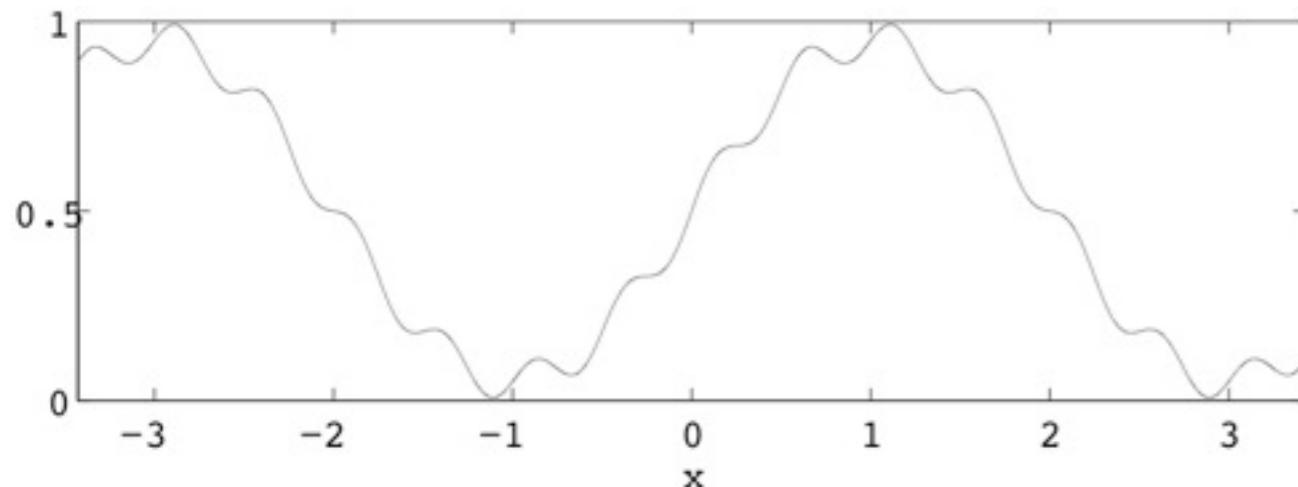
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Example of $g(f(x))$



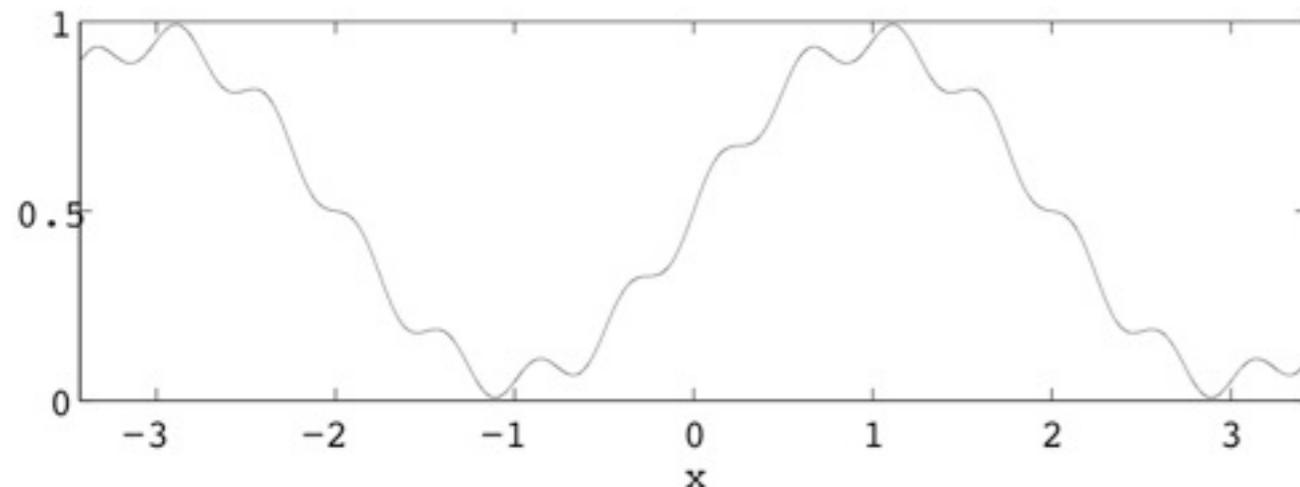
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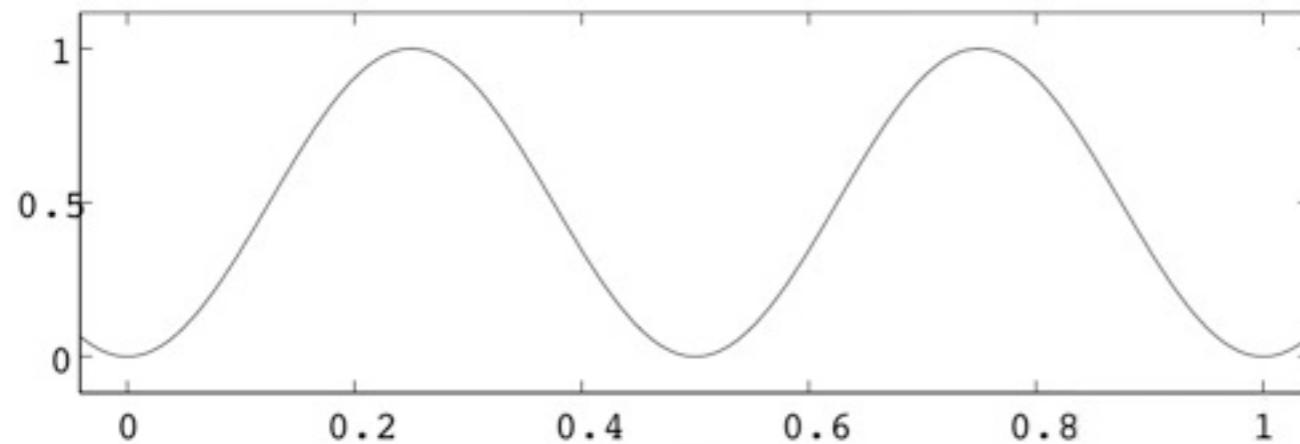
Original function $f(x)$



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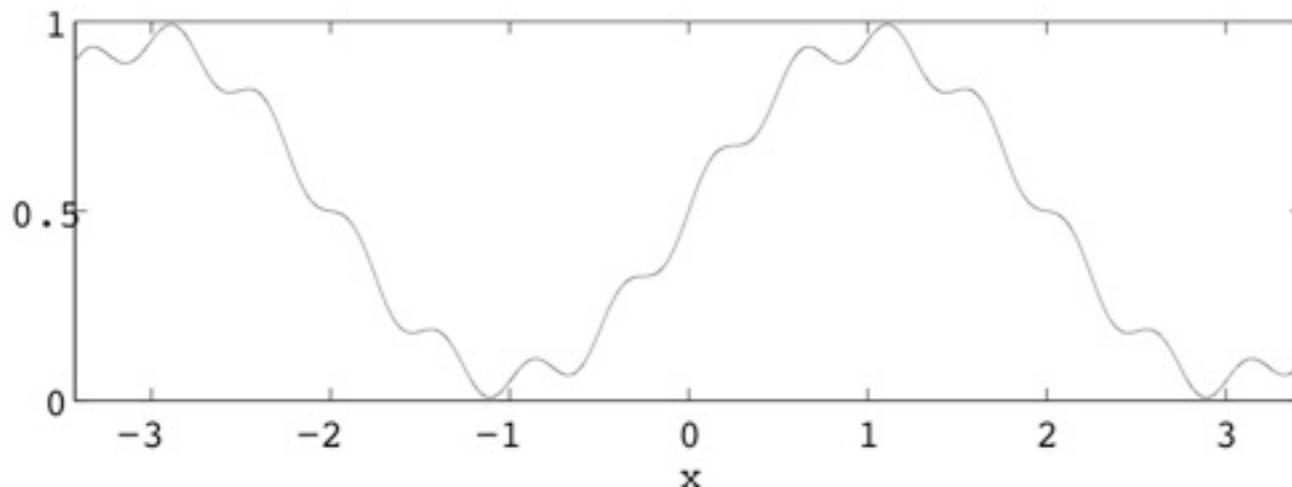
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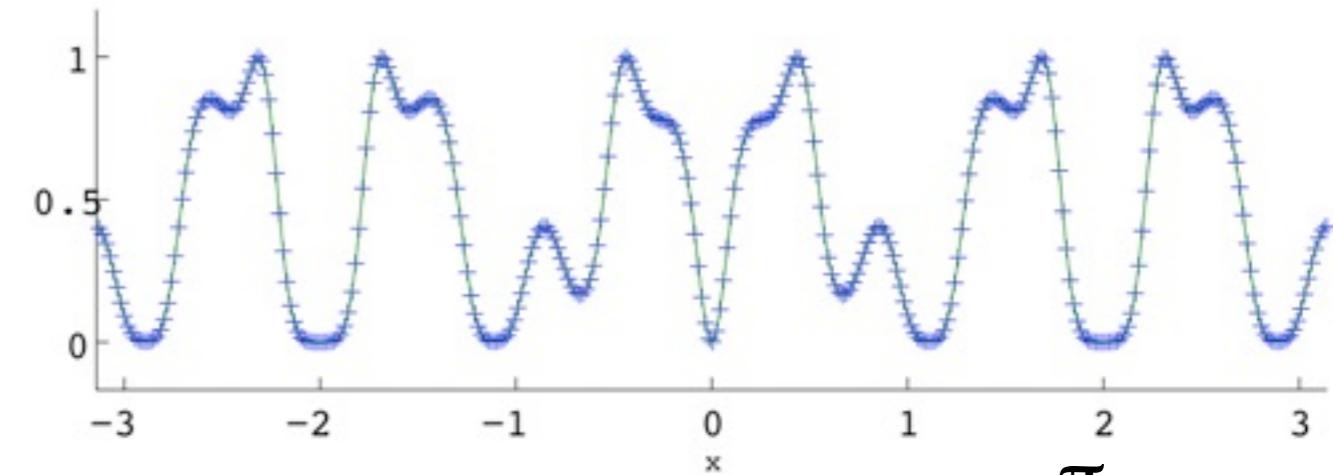
Transfer function $g(y)$



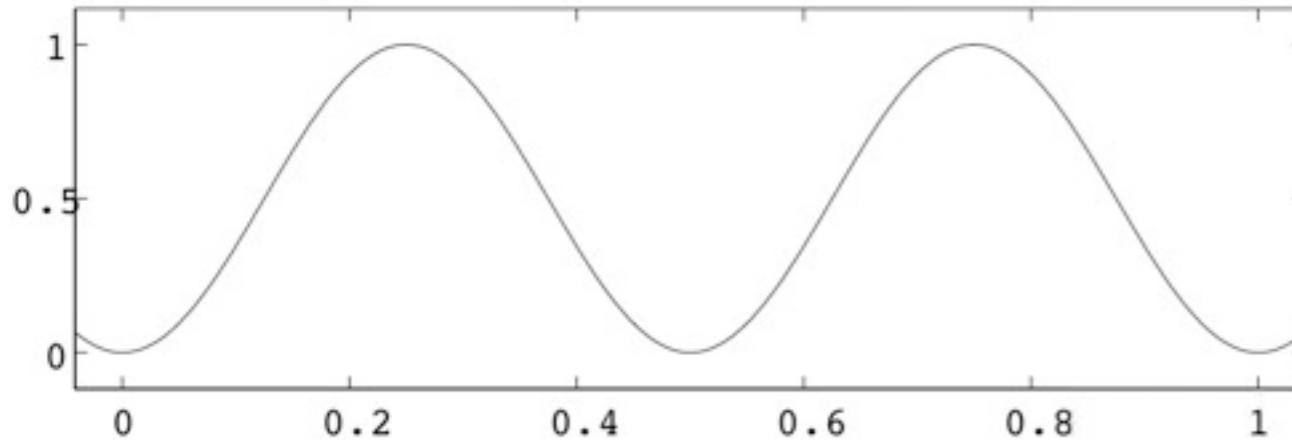
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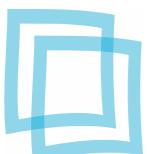
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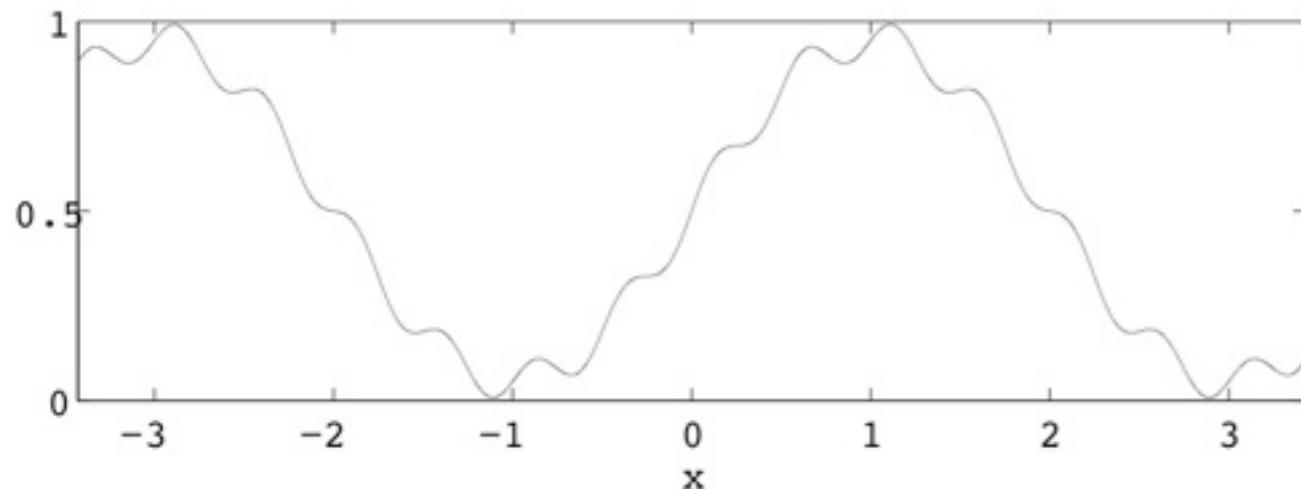
$g(f(x))$ sampled by $\frac{\pi}{2} v_f v_g$



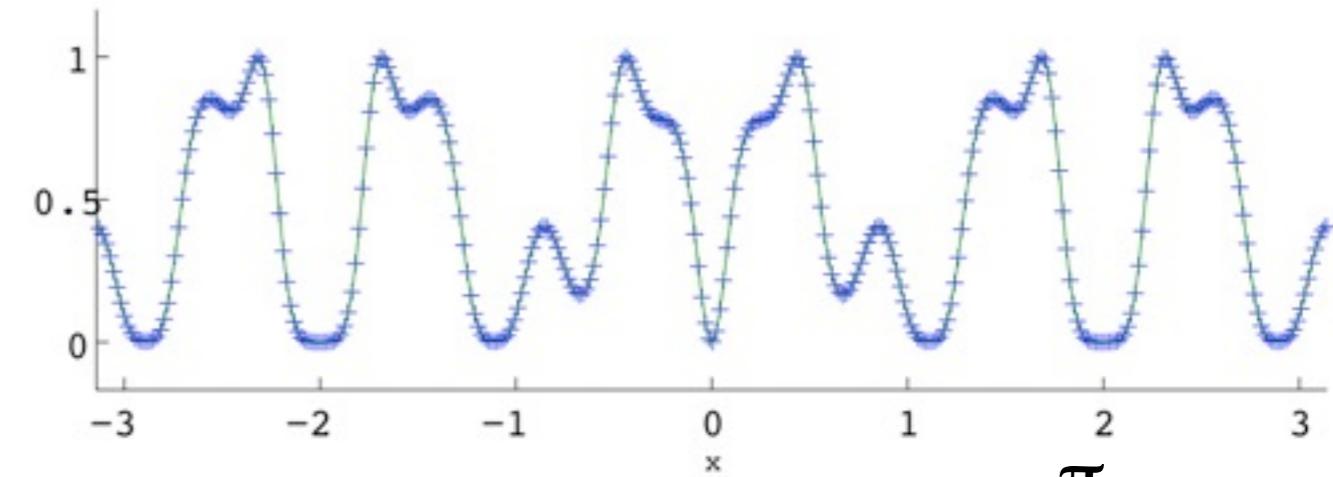
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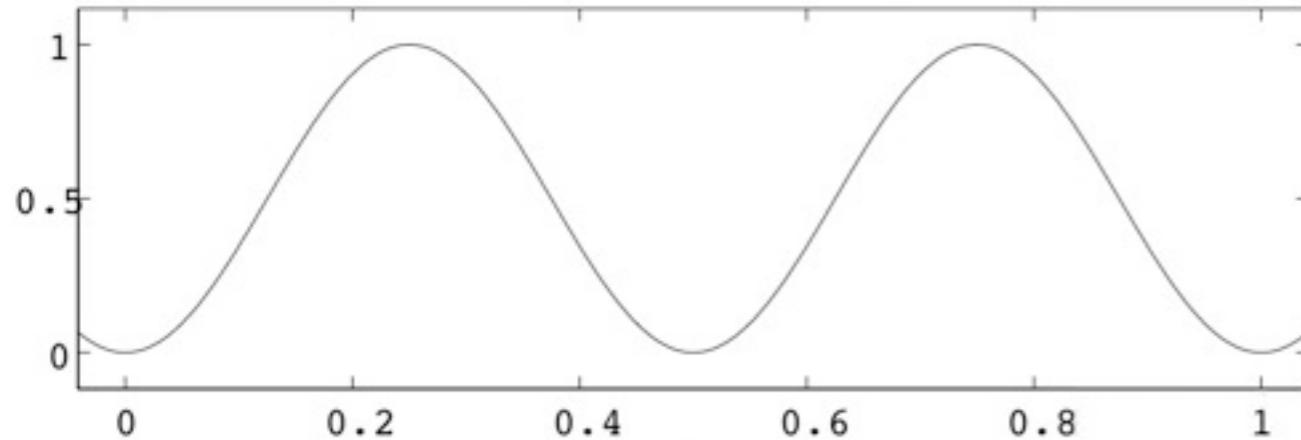
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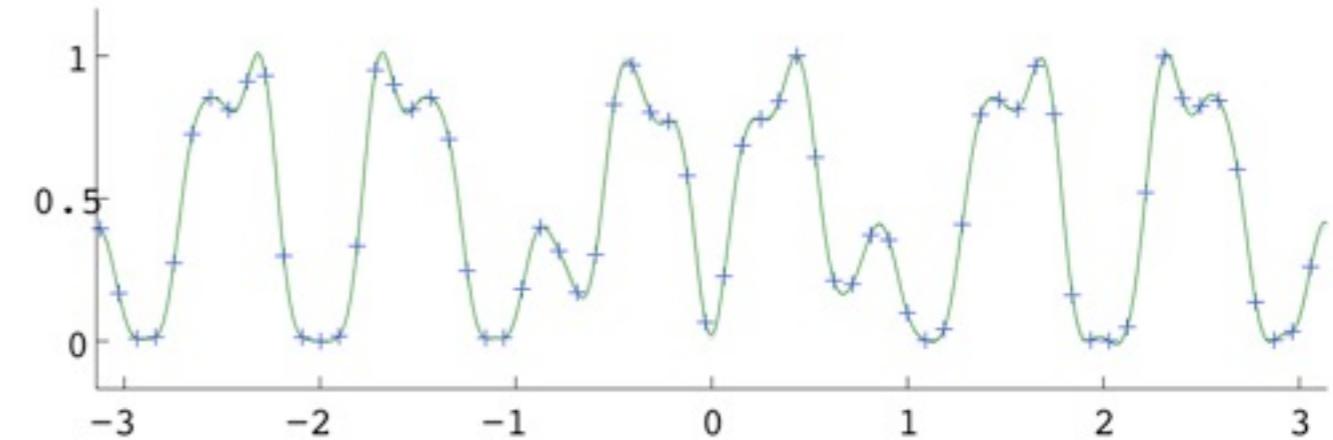
Original function $f(x)$



$g(f(x))$ sampled by $\frac{\pi}{2} v_f v_g$



Transfer function $g(y)$



$g(f(x))$ sampled by $\max |f'| v_g$



Composition in Frequency Domain

$$g(\mathbf{y}) = \frac{1}{\sqrt{2\pi}} \int_R G(l) e^{il \cdot \mathbf{y}} dl$$



Composition in Frequency Domain

$$h(x) = g(f(x)) = \frac{1}{\sqrt{2\pi}} \int_R G(l) e^{il \cdot f(x)} dl$$



Composition in Frequency Domain

$$h(x) = g(f(x)) = \frac{1}{\sqrt{2\pi}} \int_R G(l) e^{il \cdot f(x)} dl$$

$$H(k)$$

$$\int_R G(l) e^{il \cdot f(x)} dl$$



Composition in Frequency Domain

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$$P(k, l) = \int_R e^{i(l \cdot f(x) - k \cdot x)} dx$$



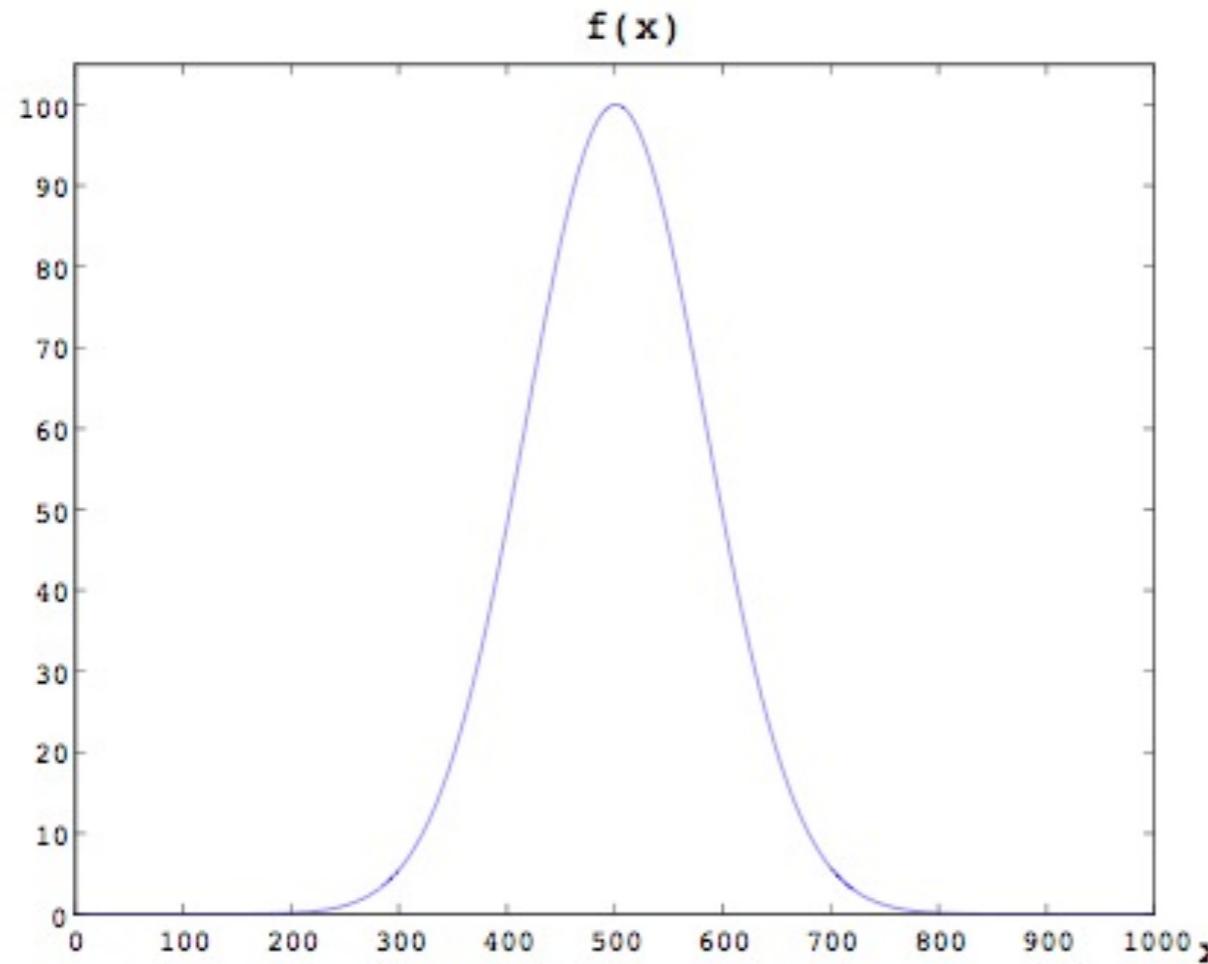
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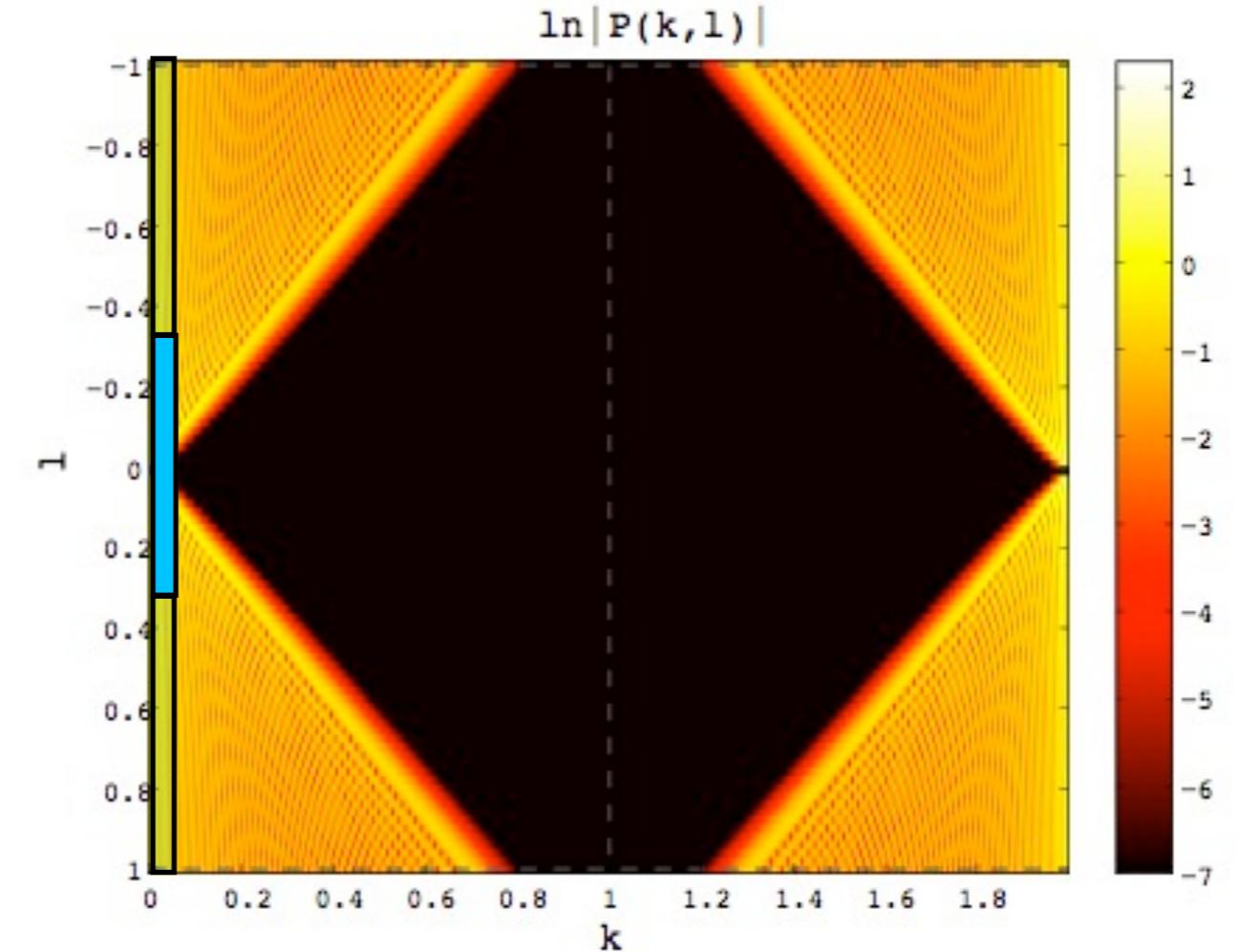
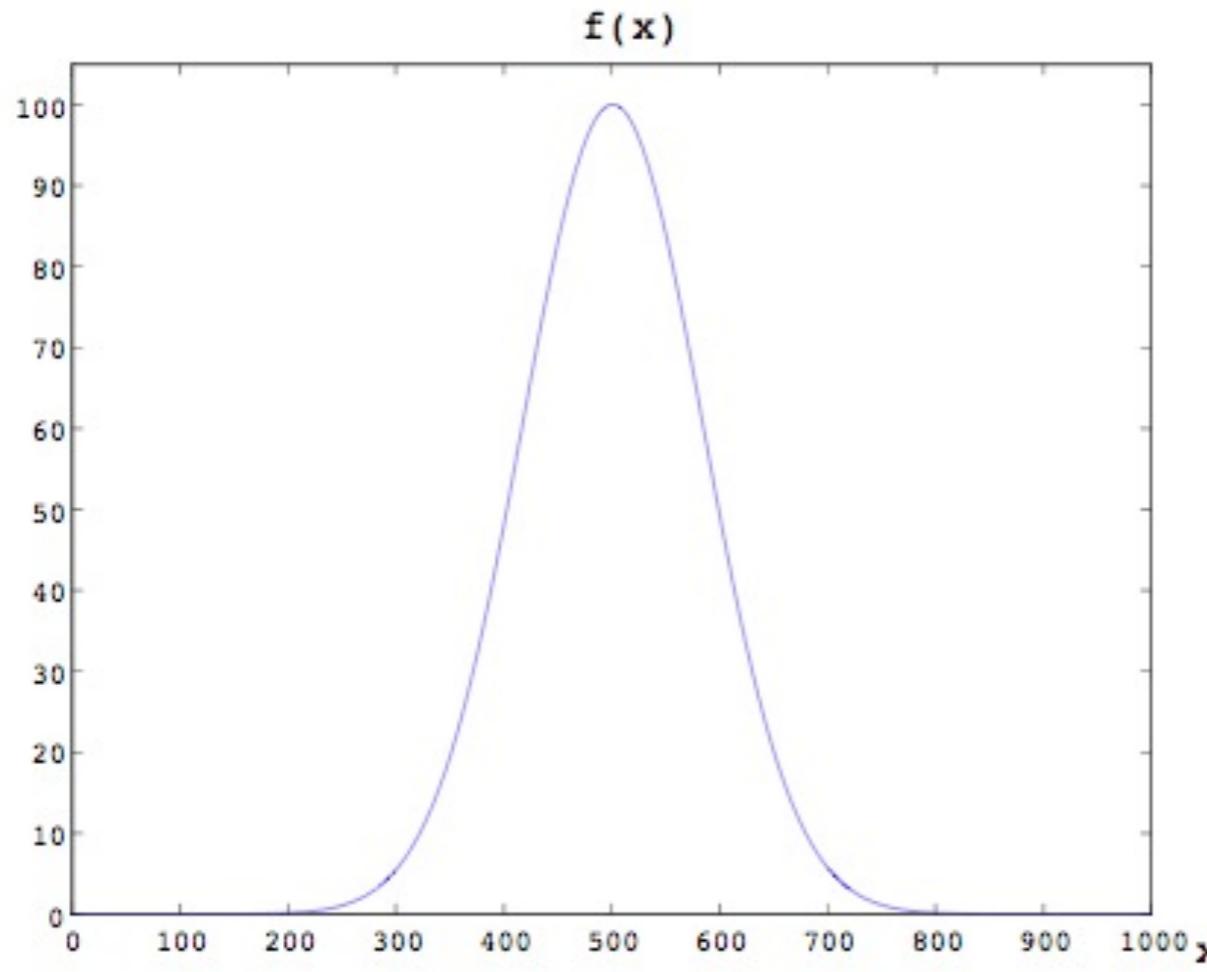
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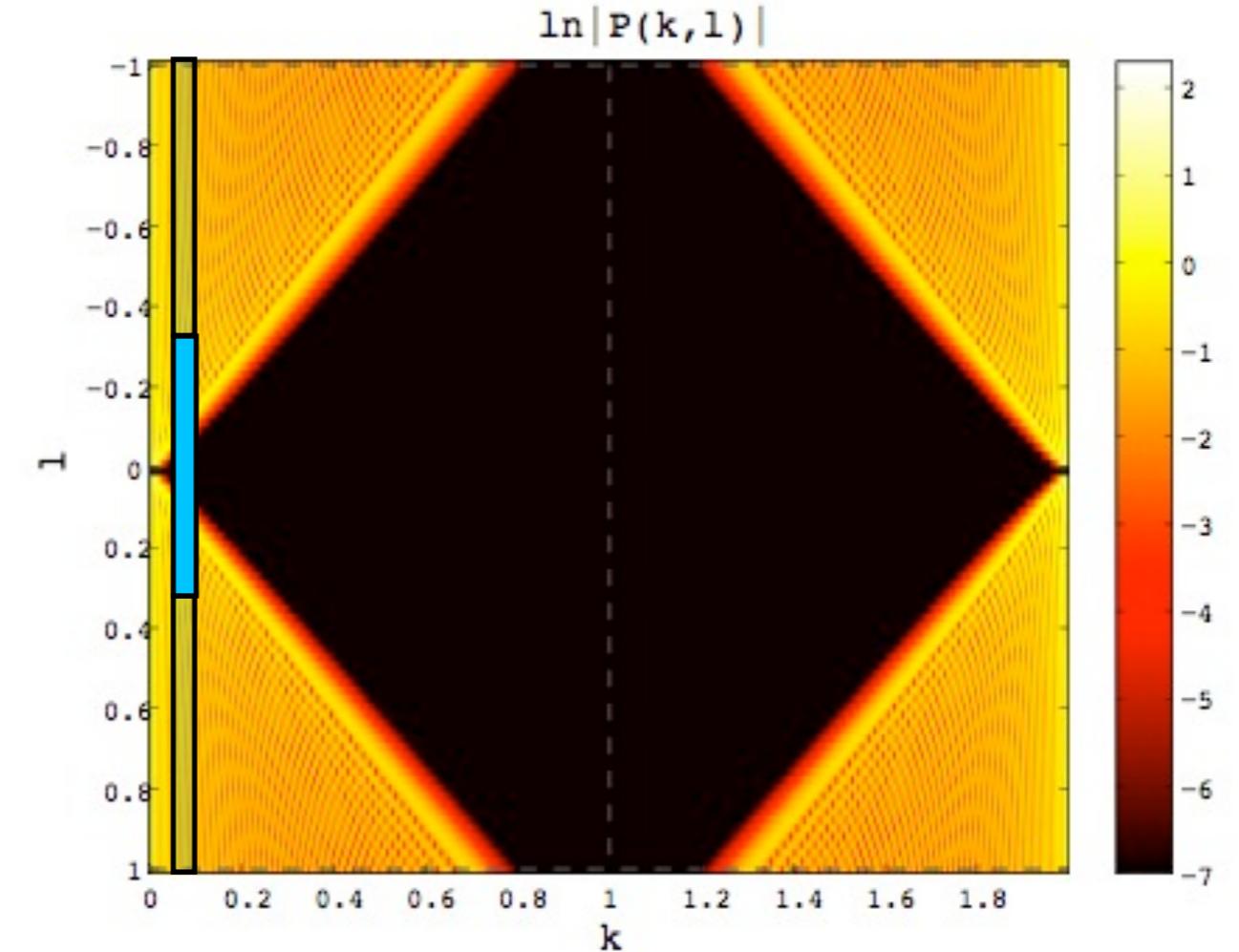
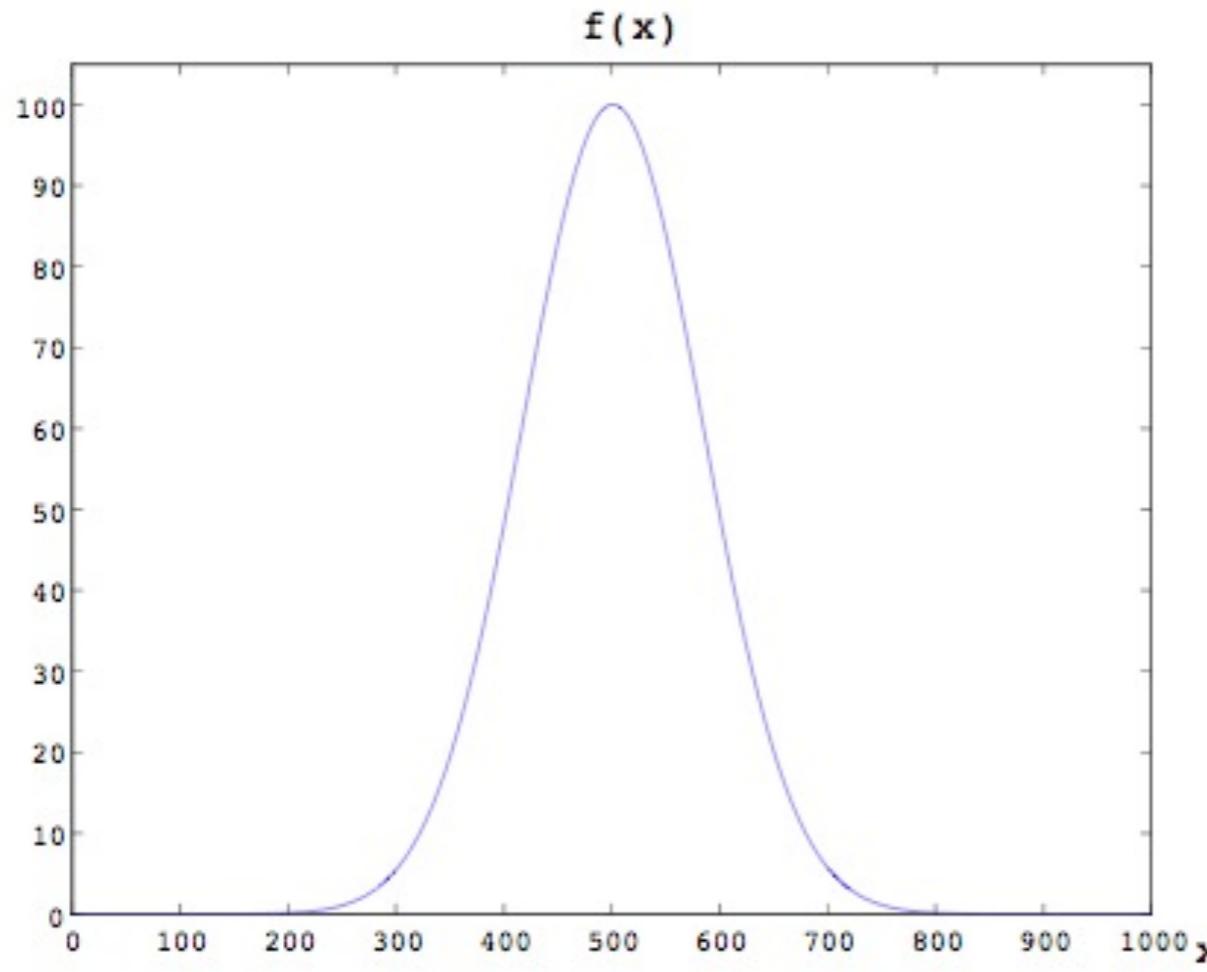
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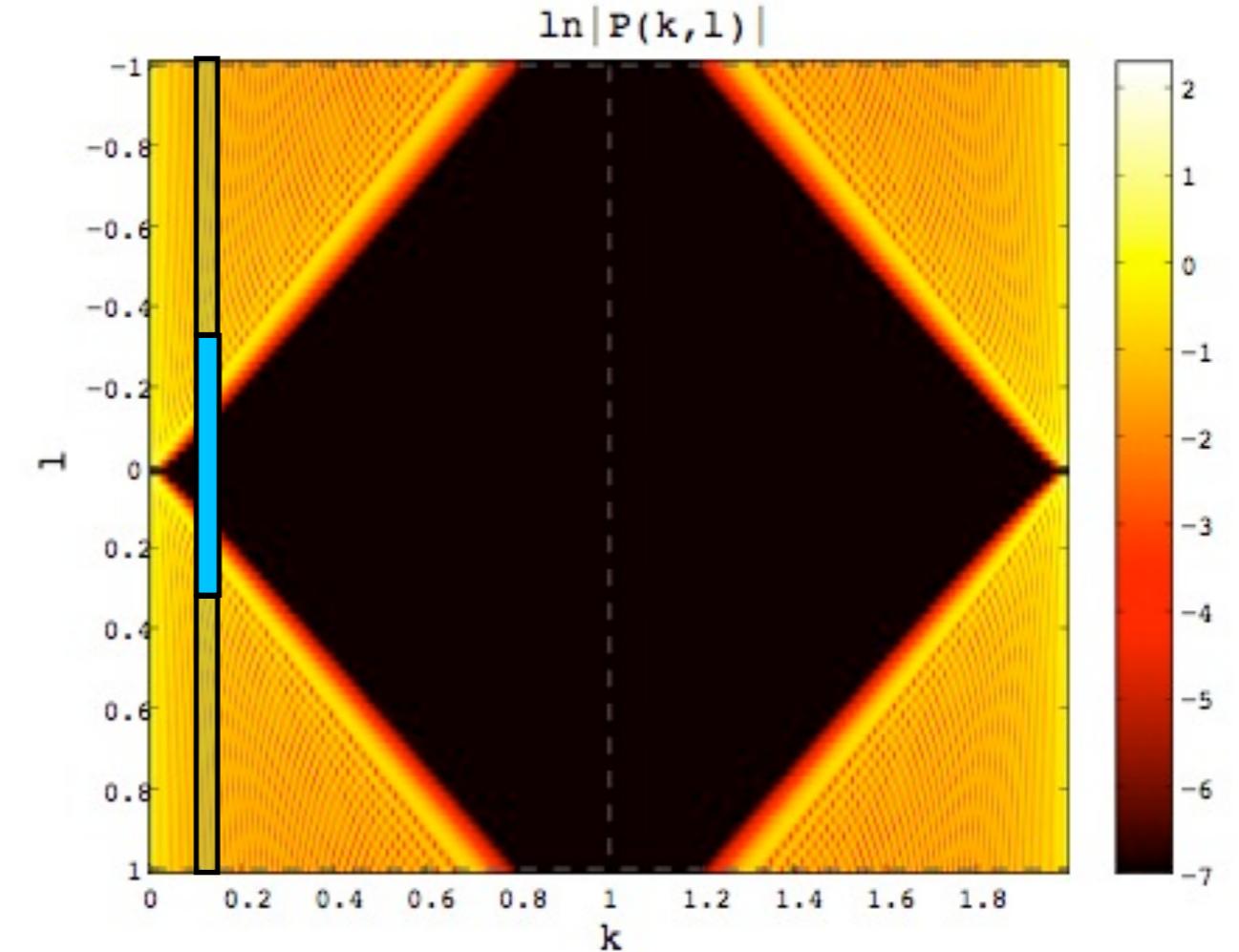
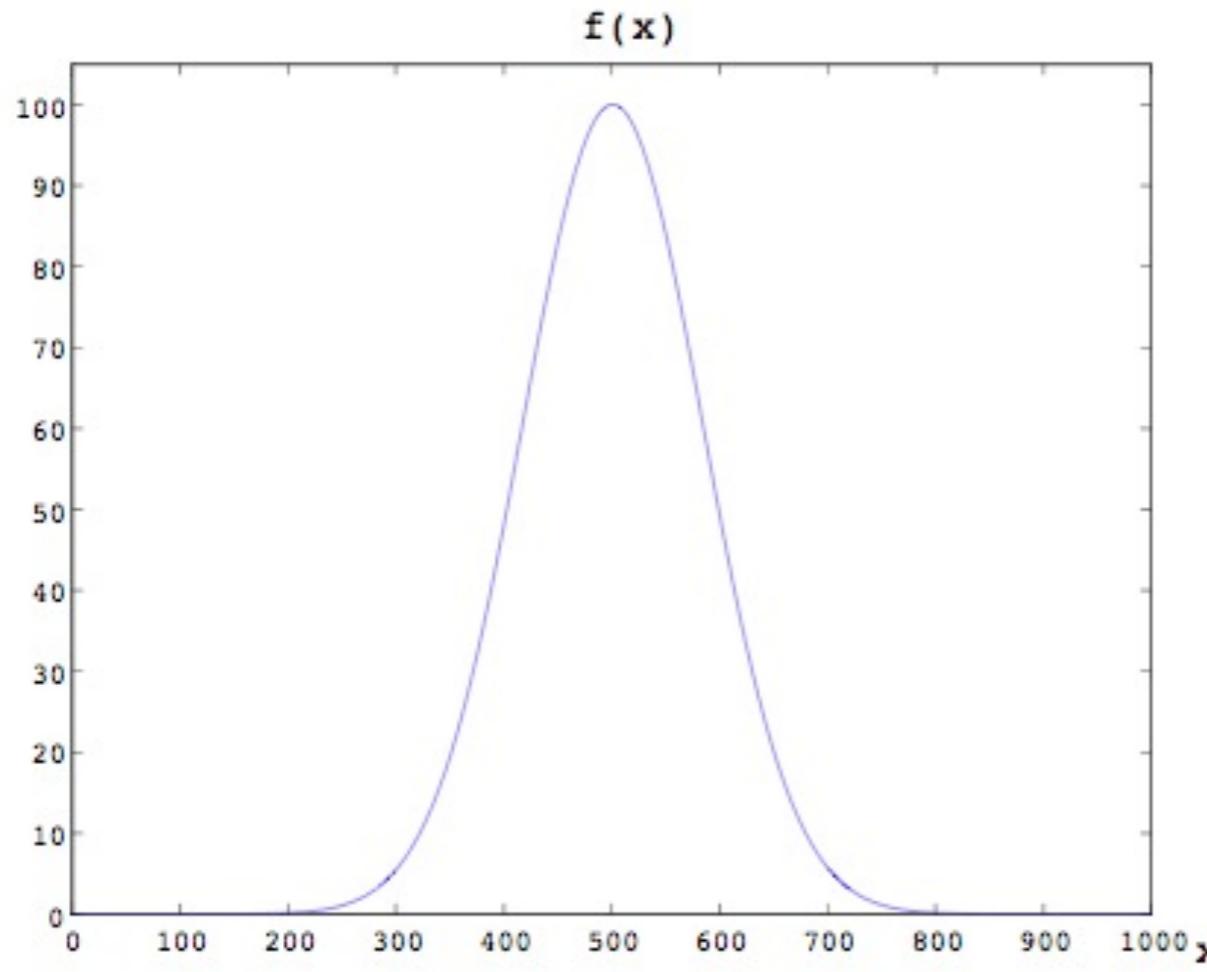
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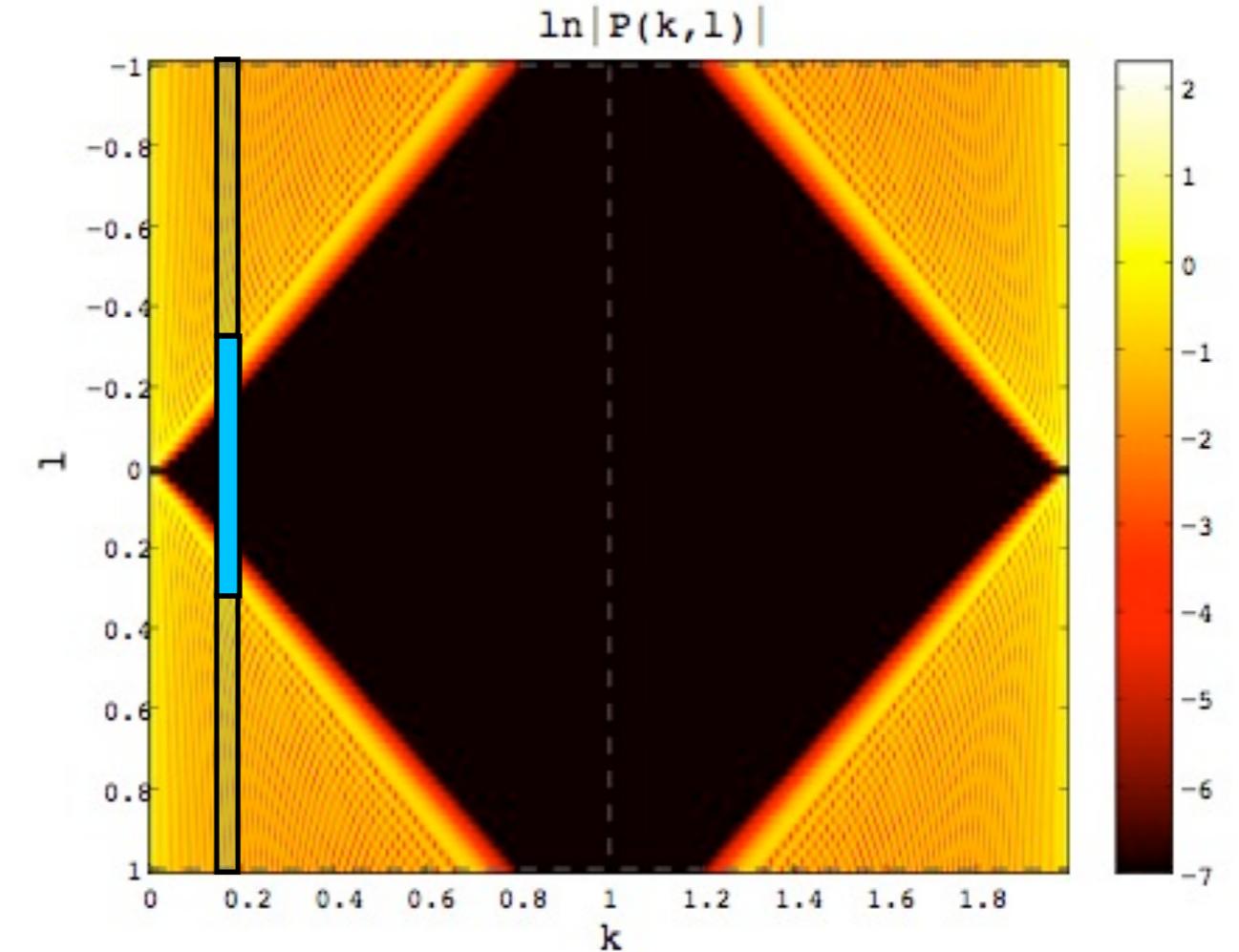
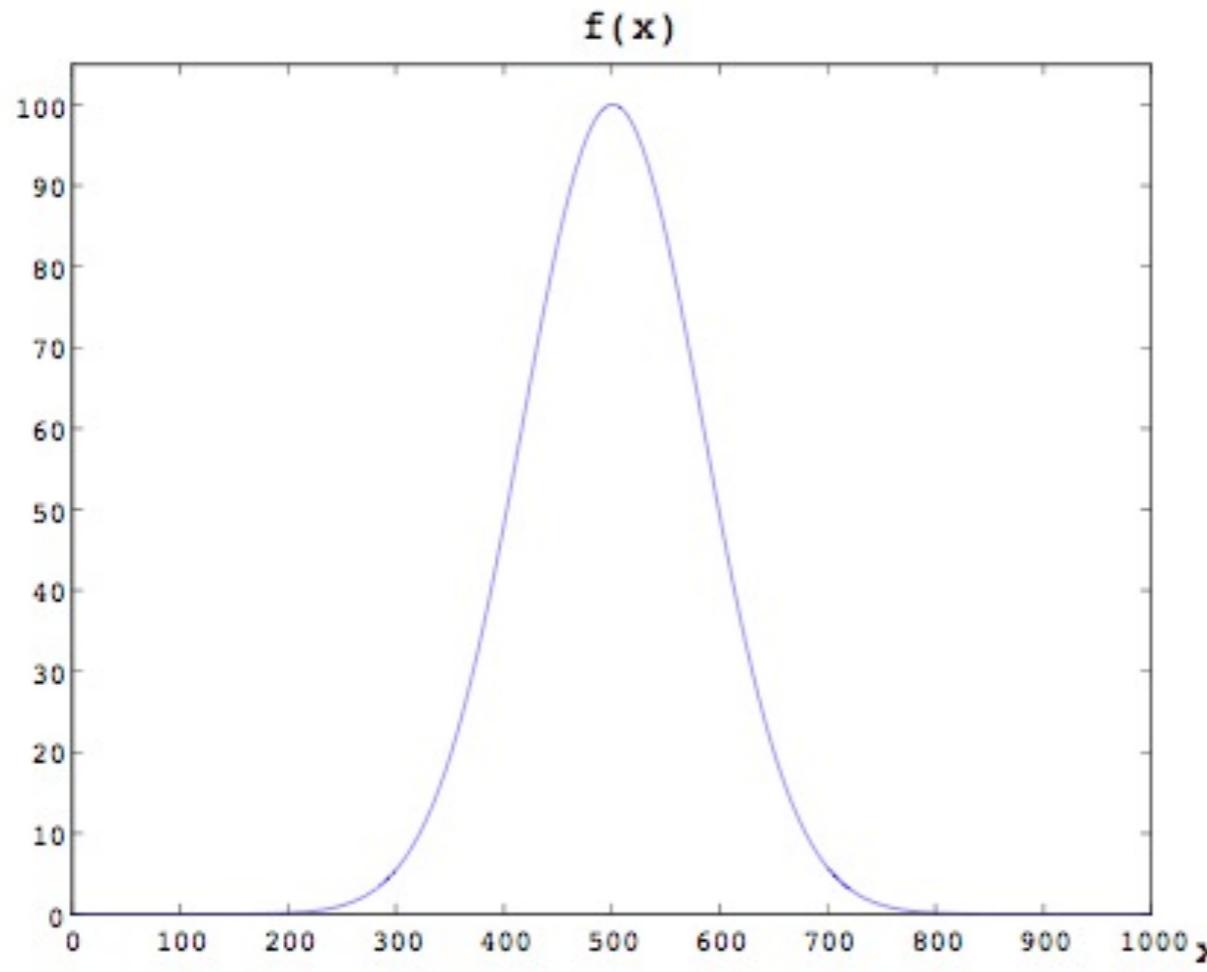
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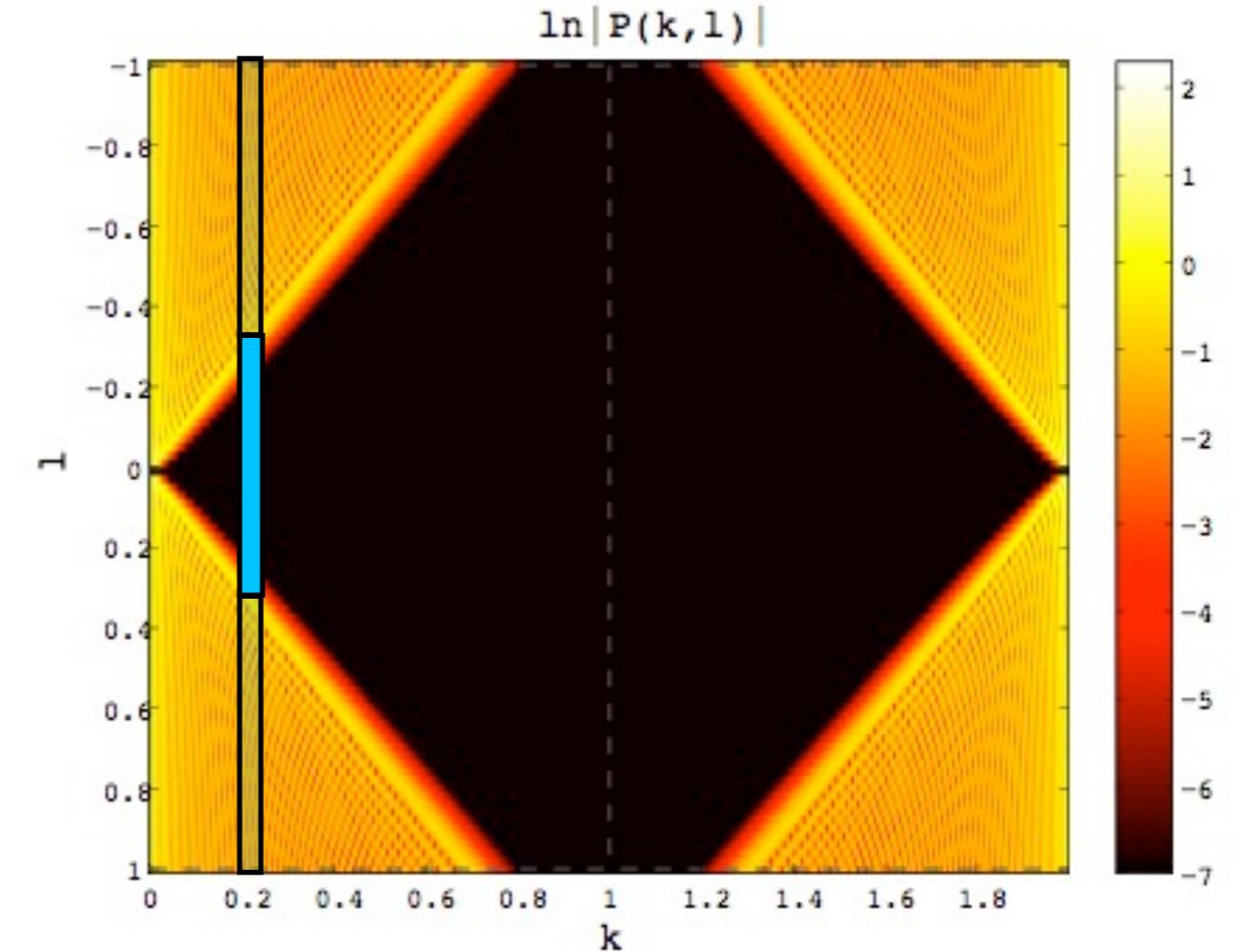
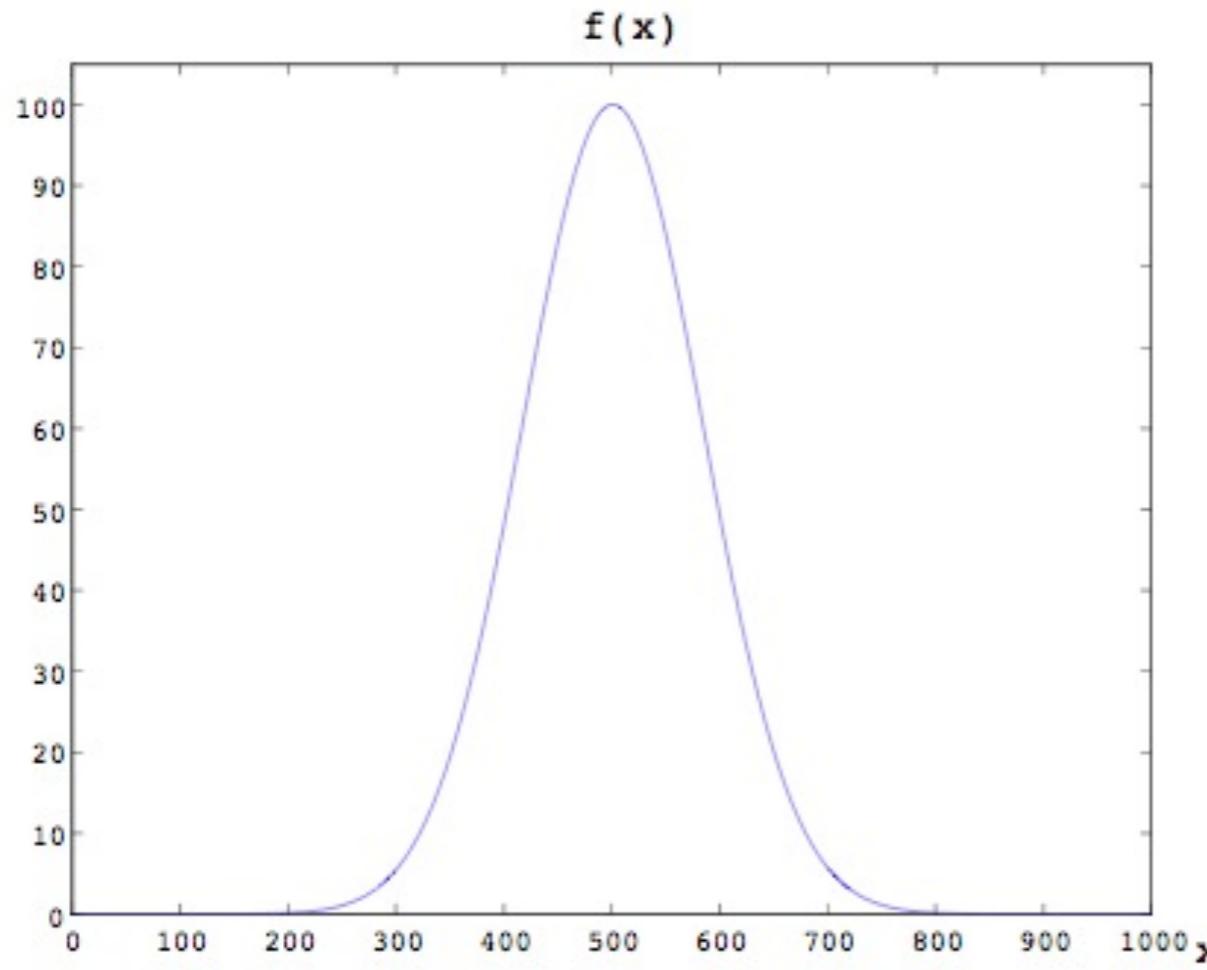
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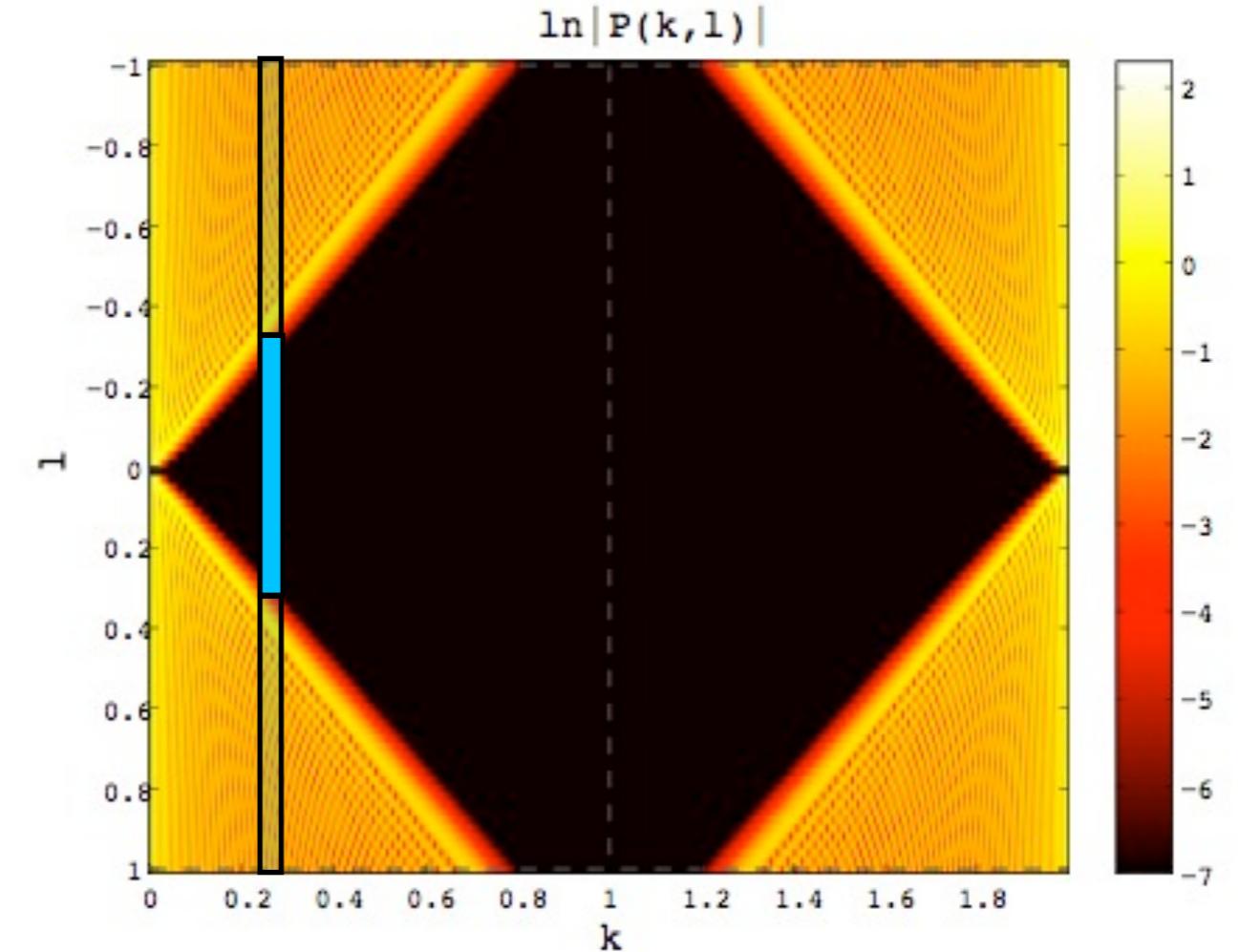
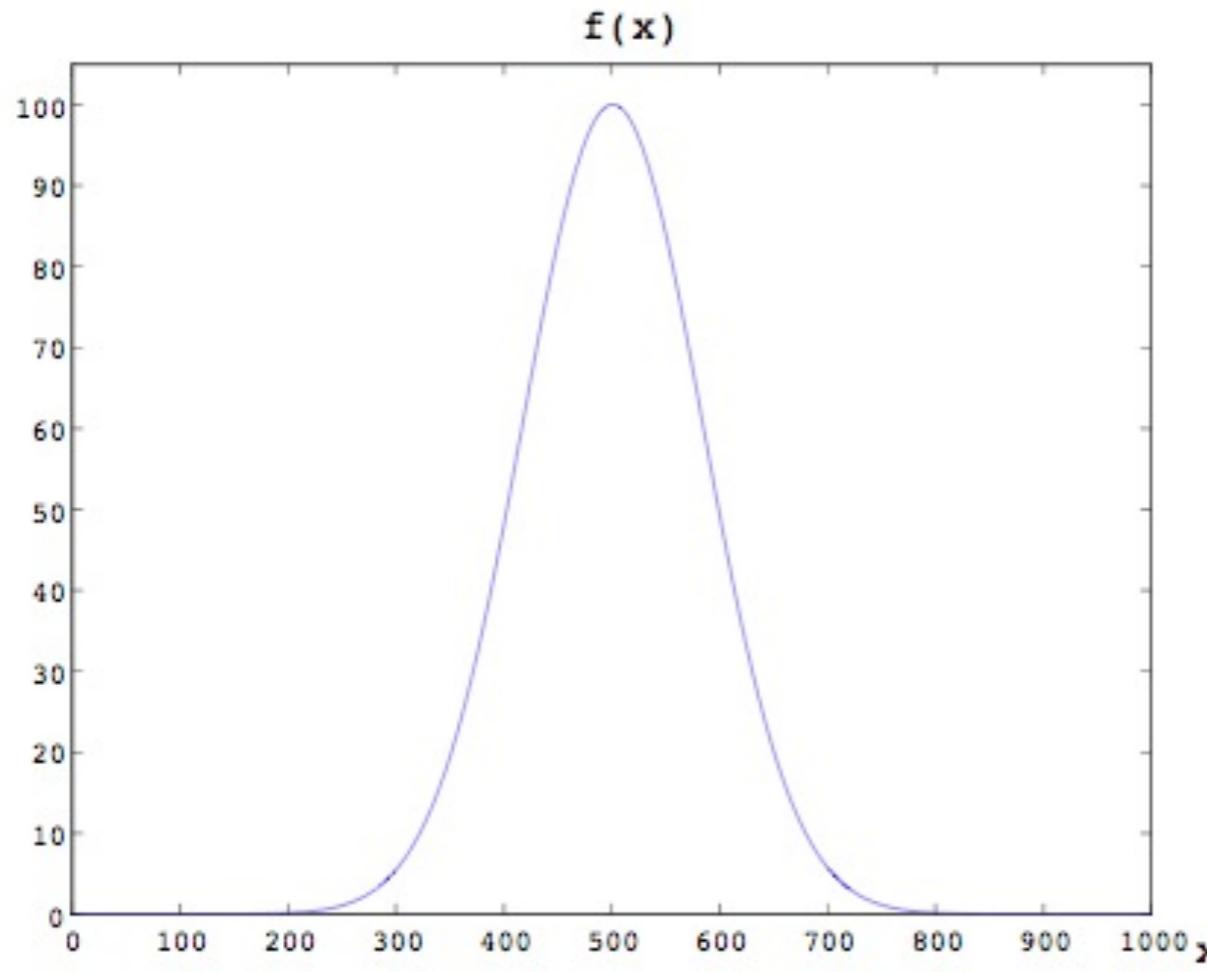
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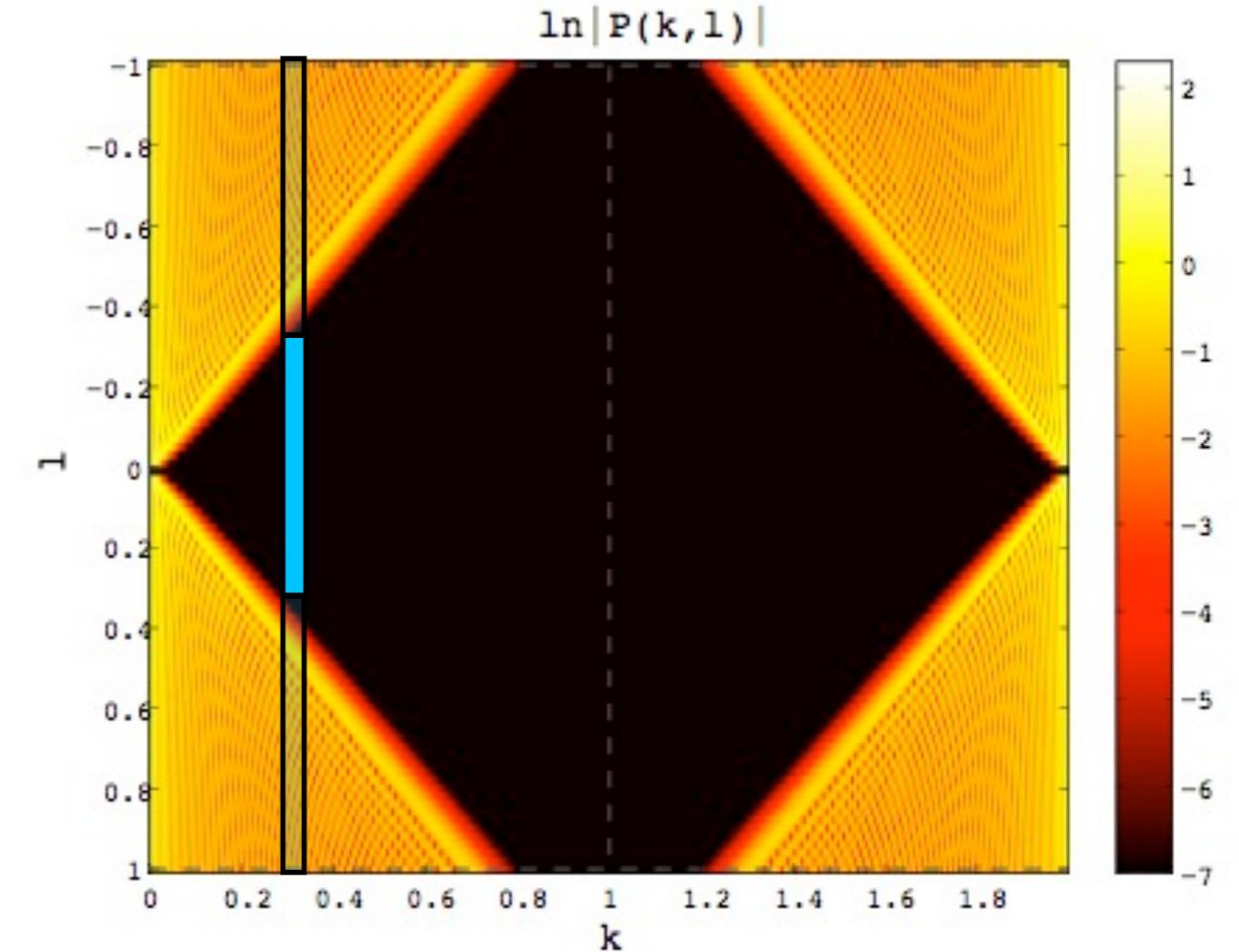
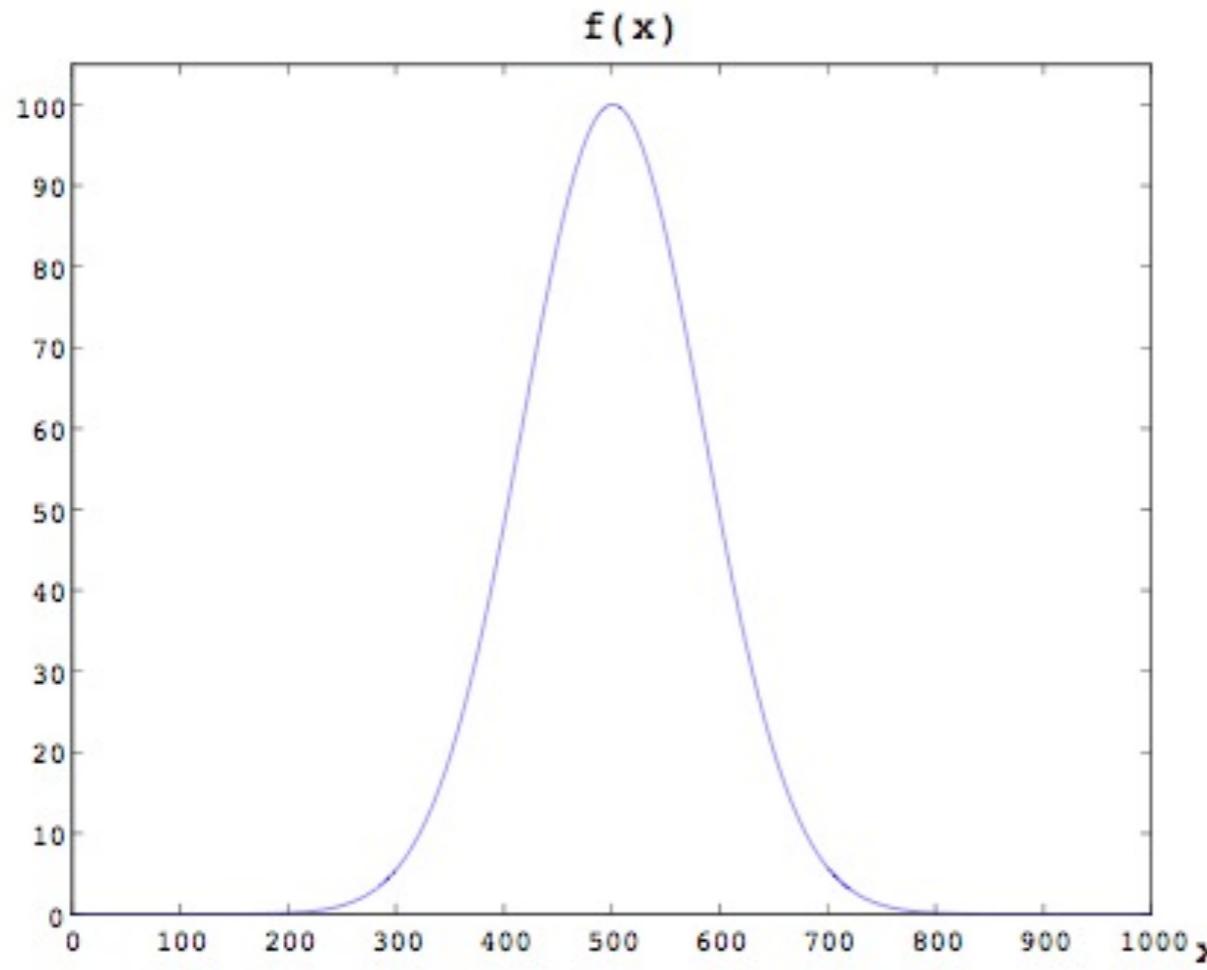
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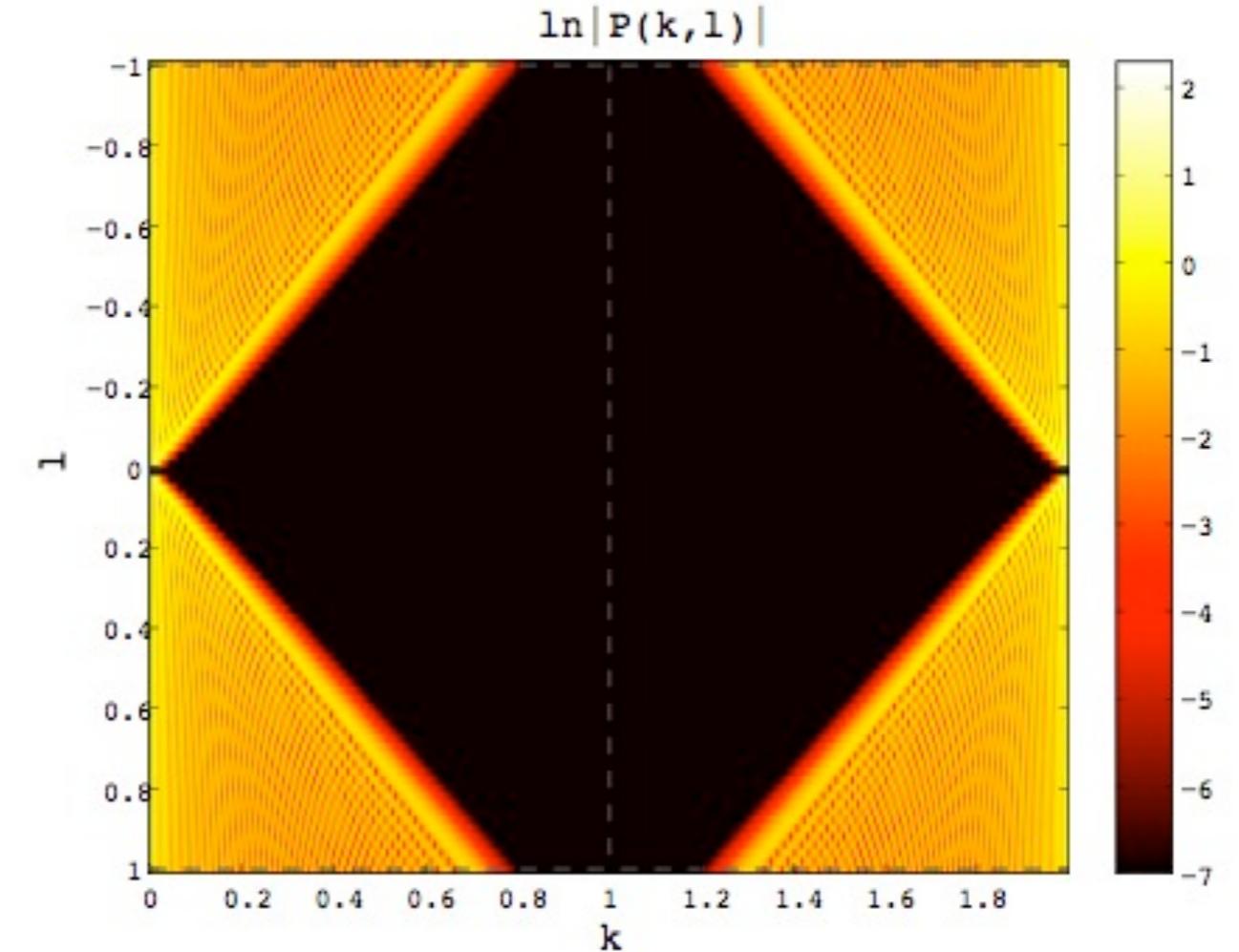
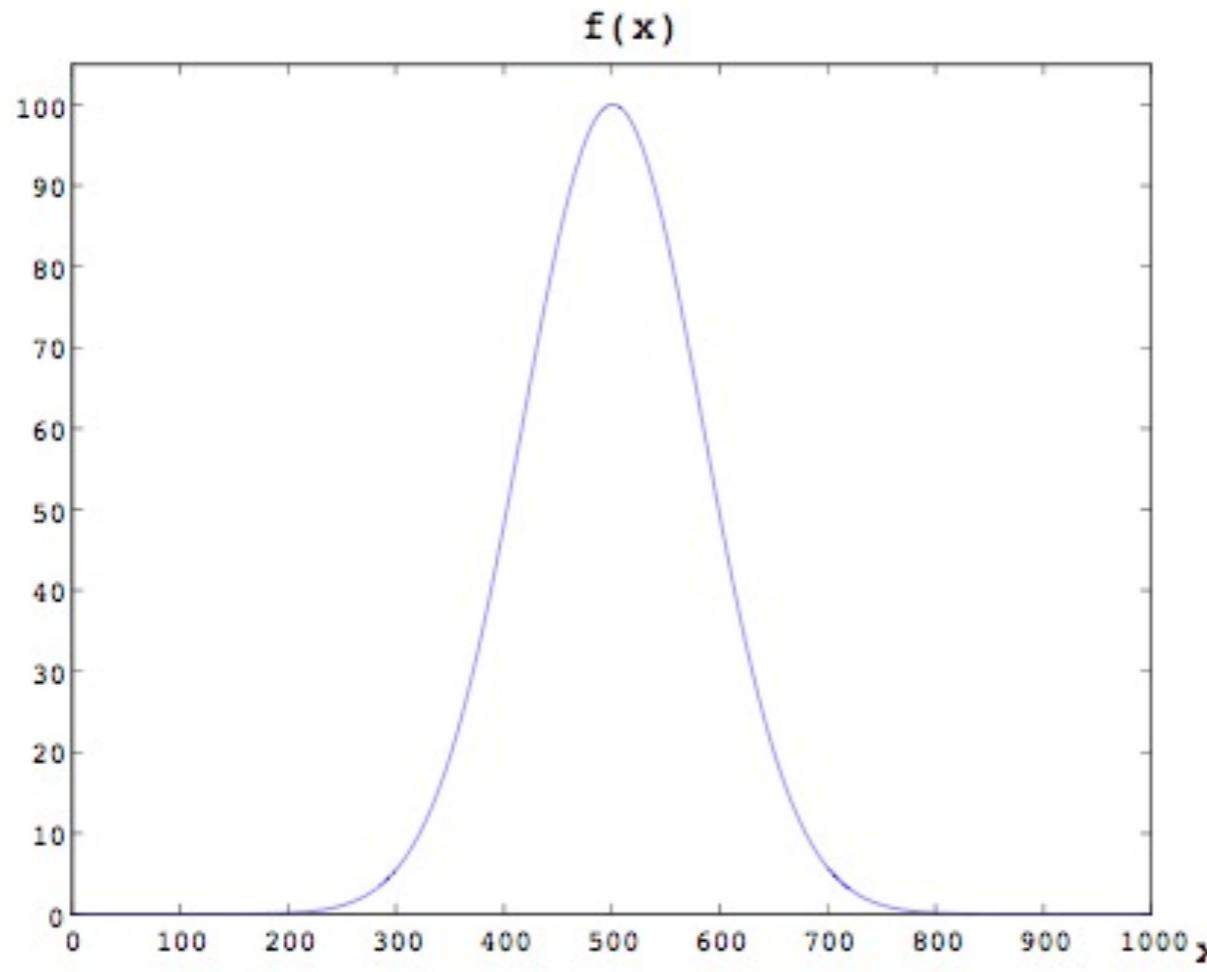
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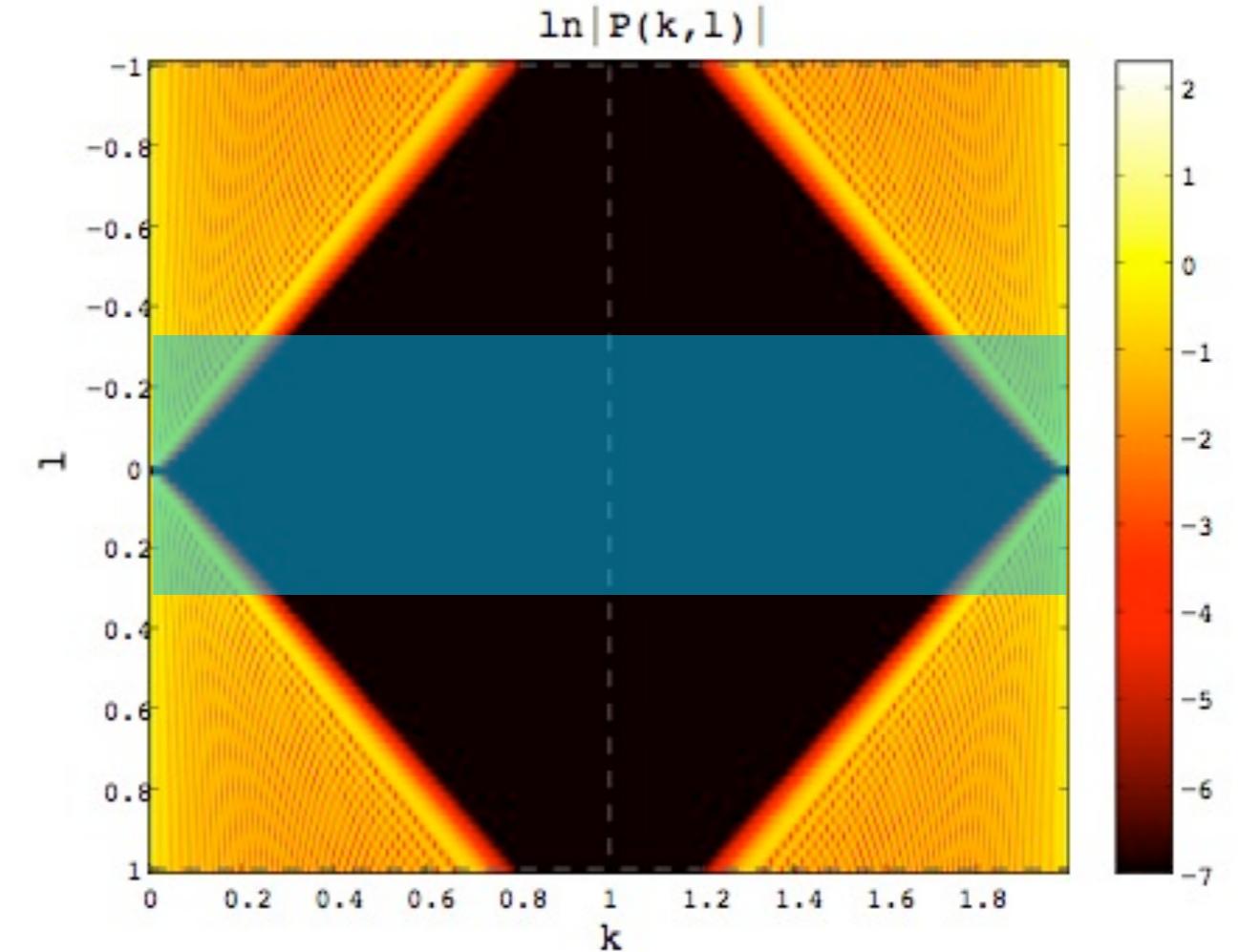
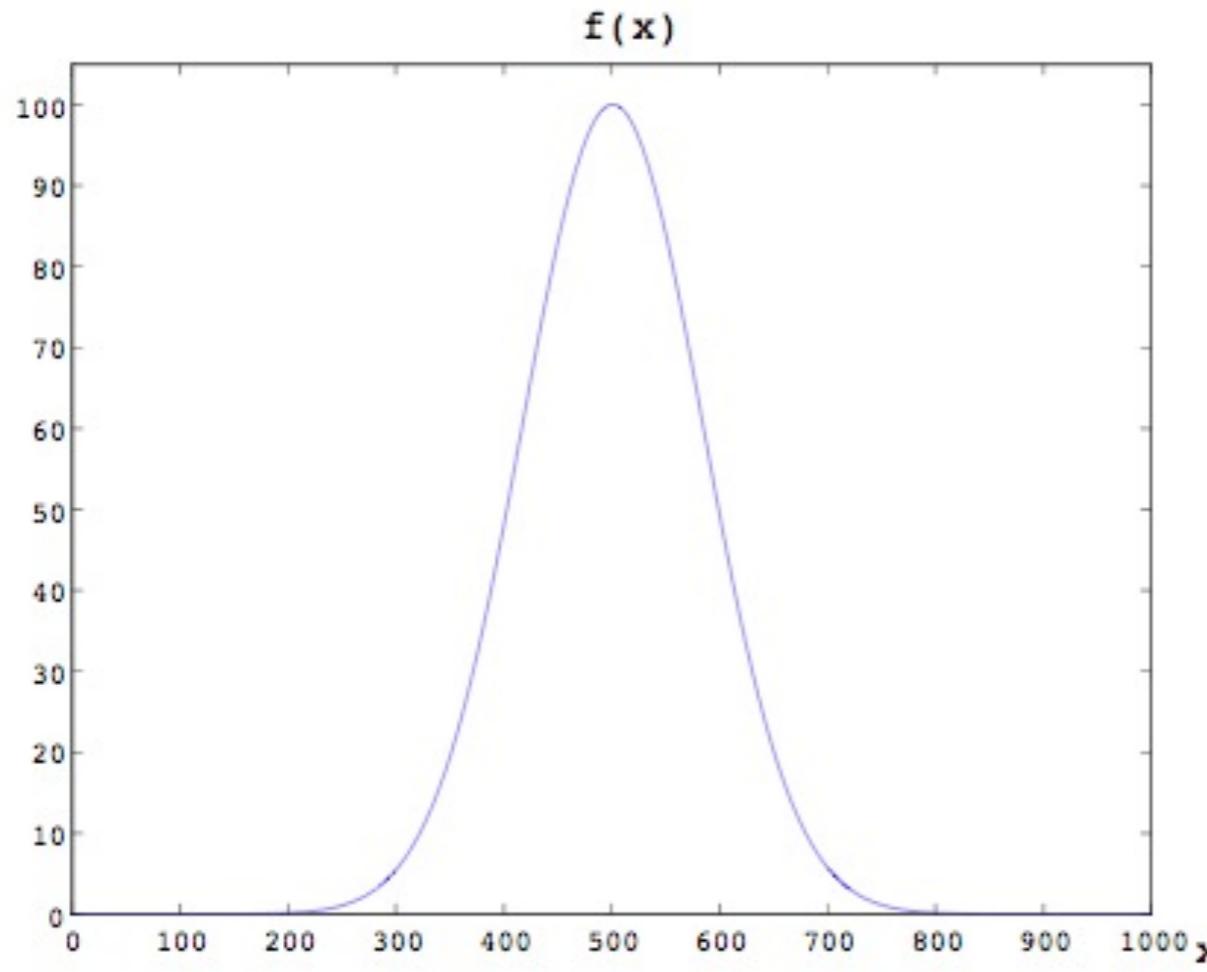
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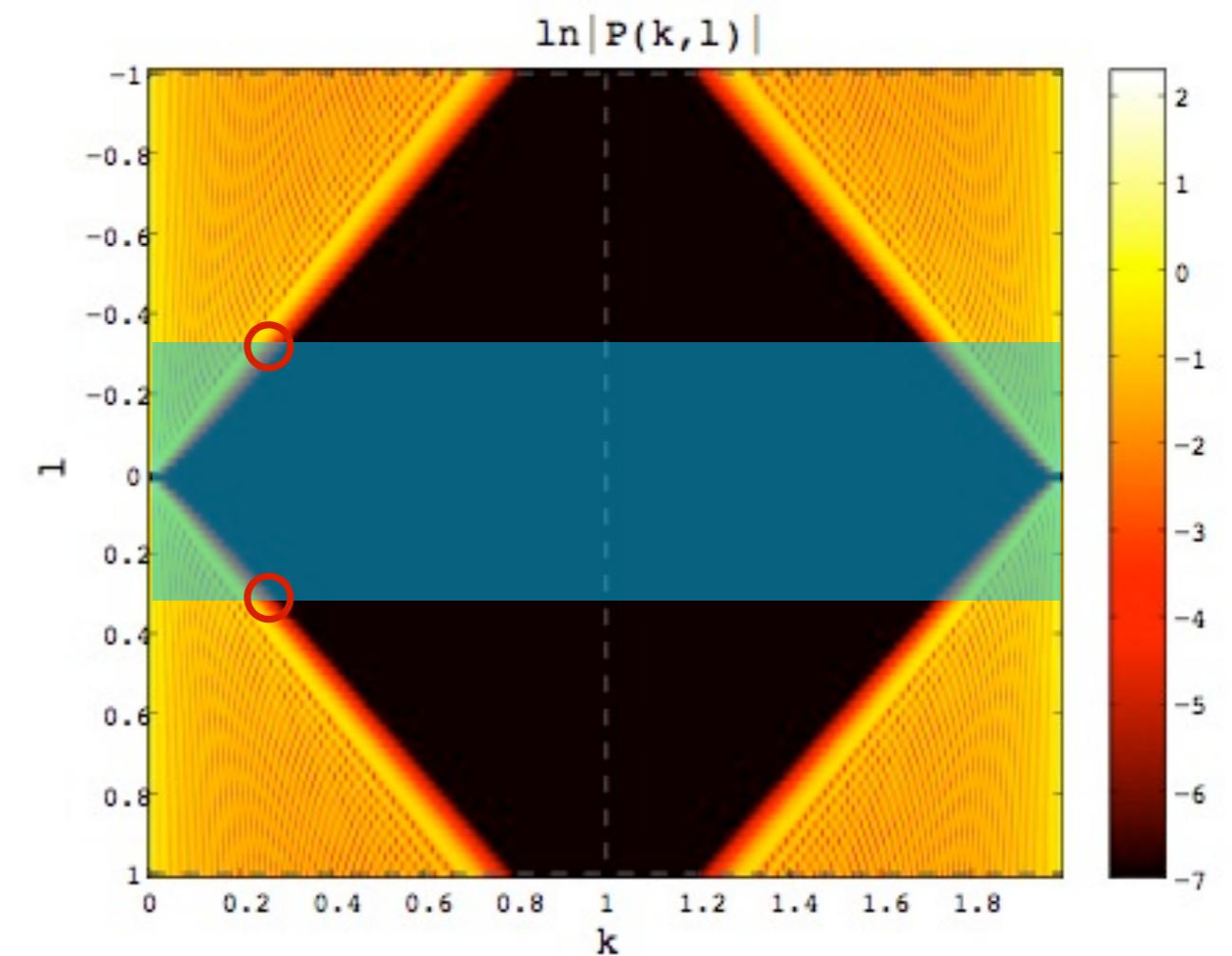
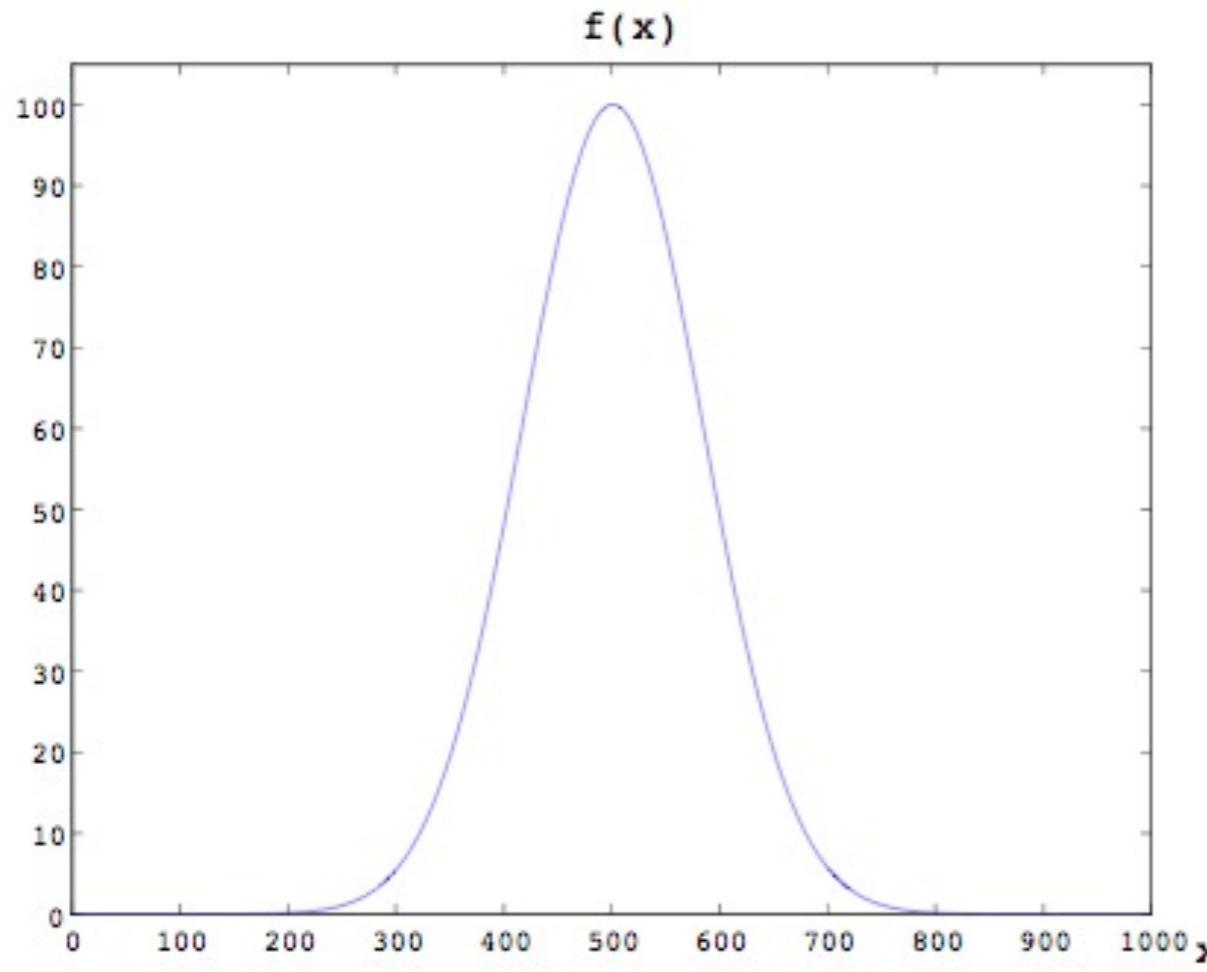
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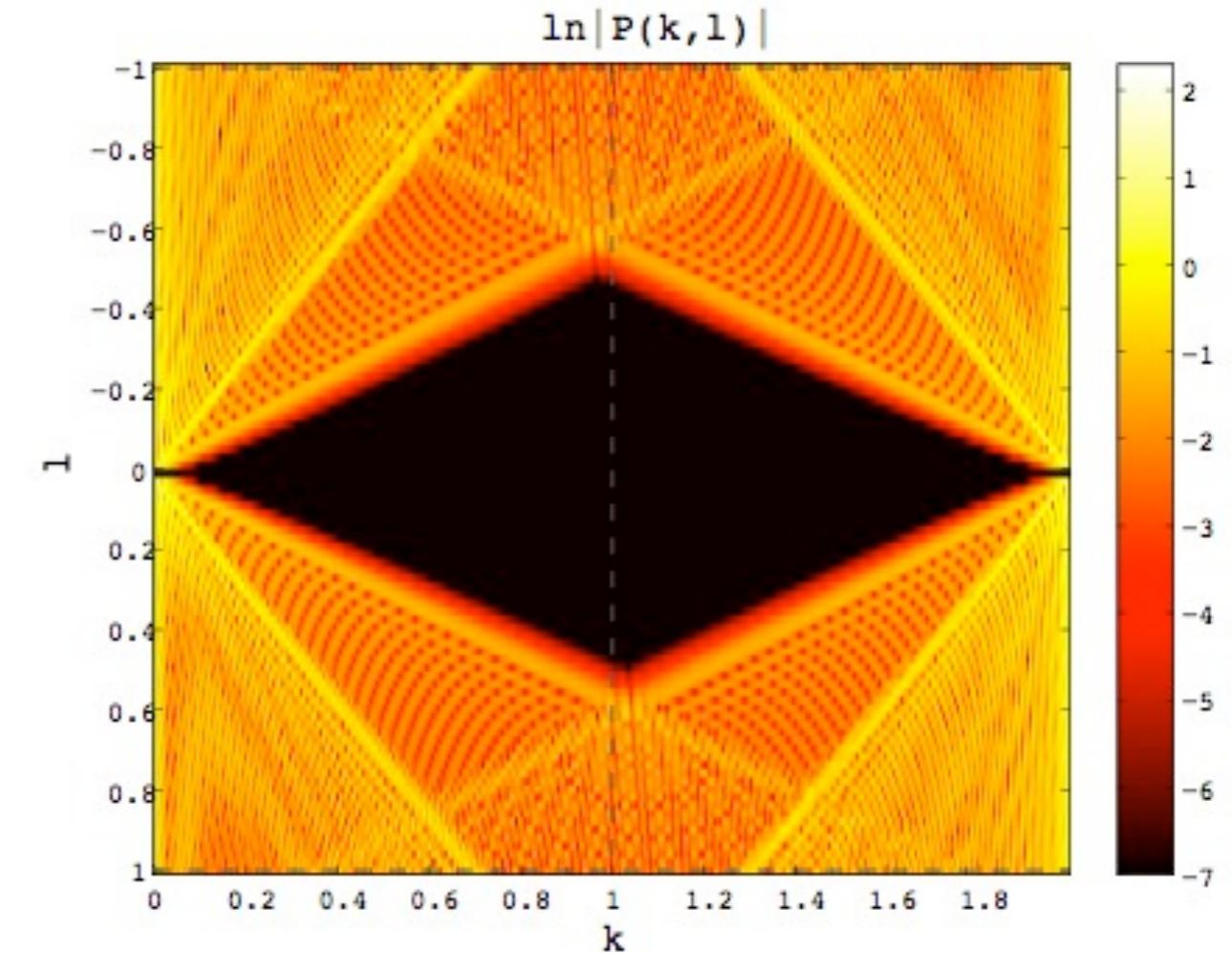
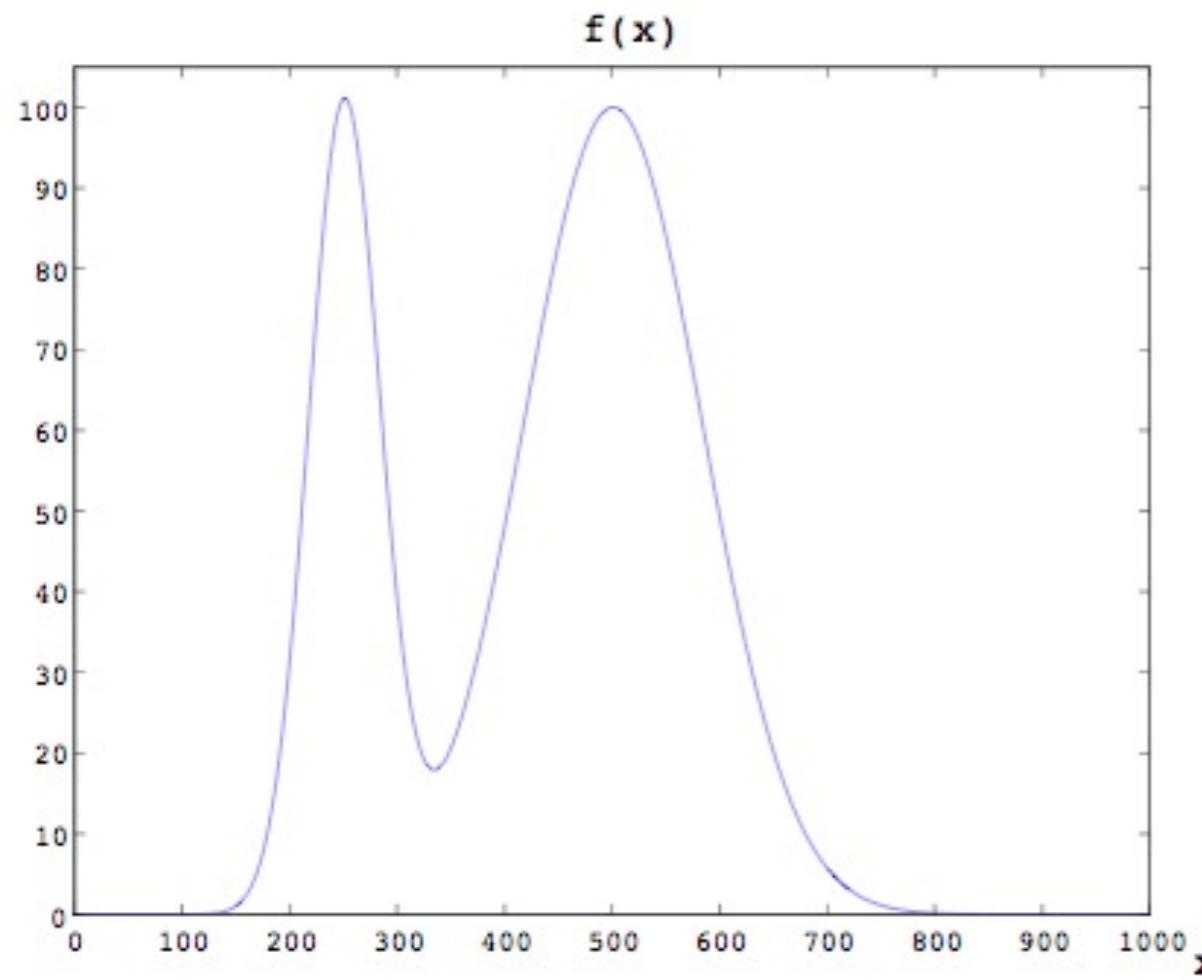


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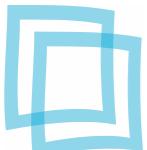
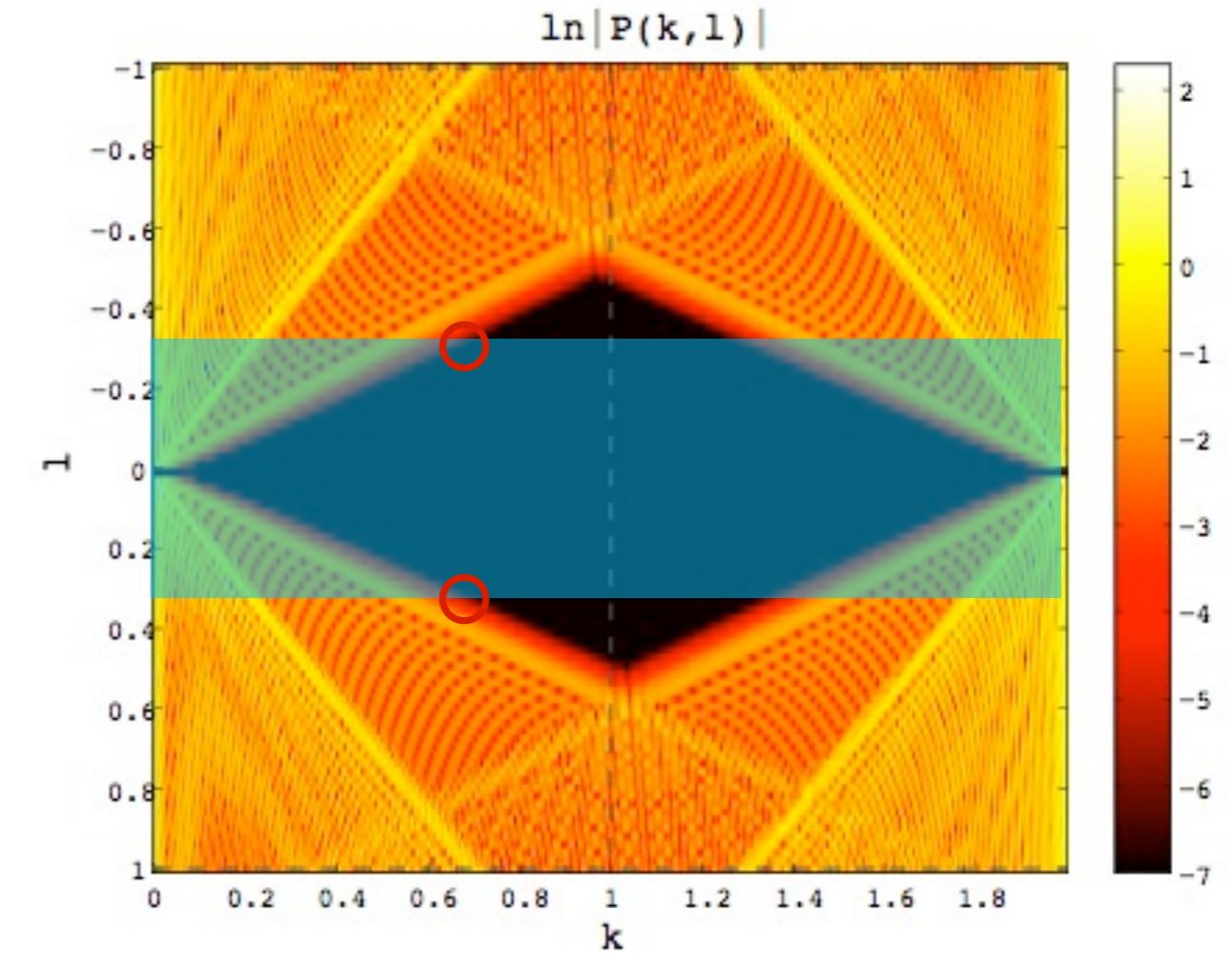
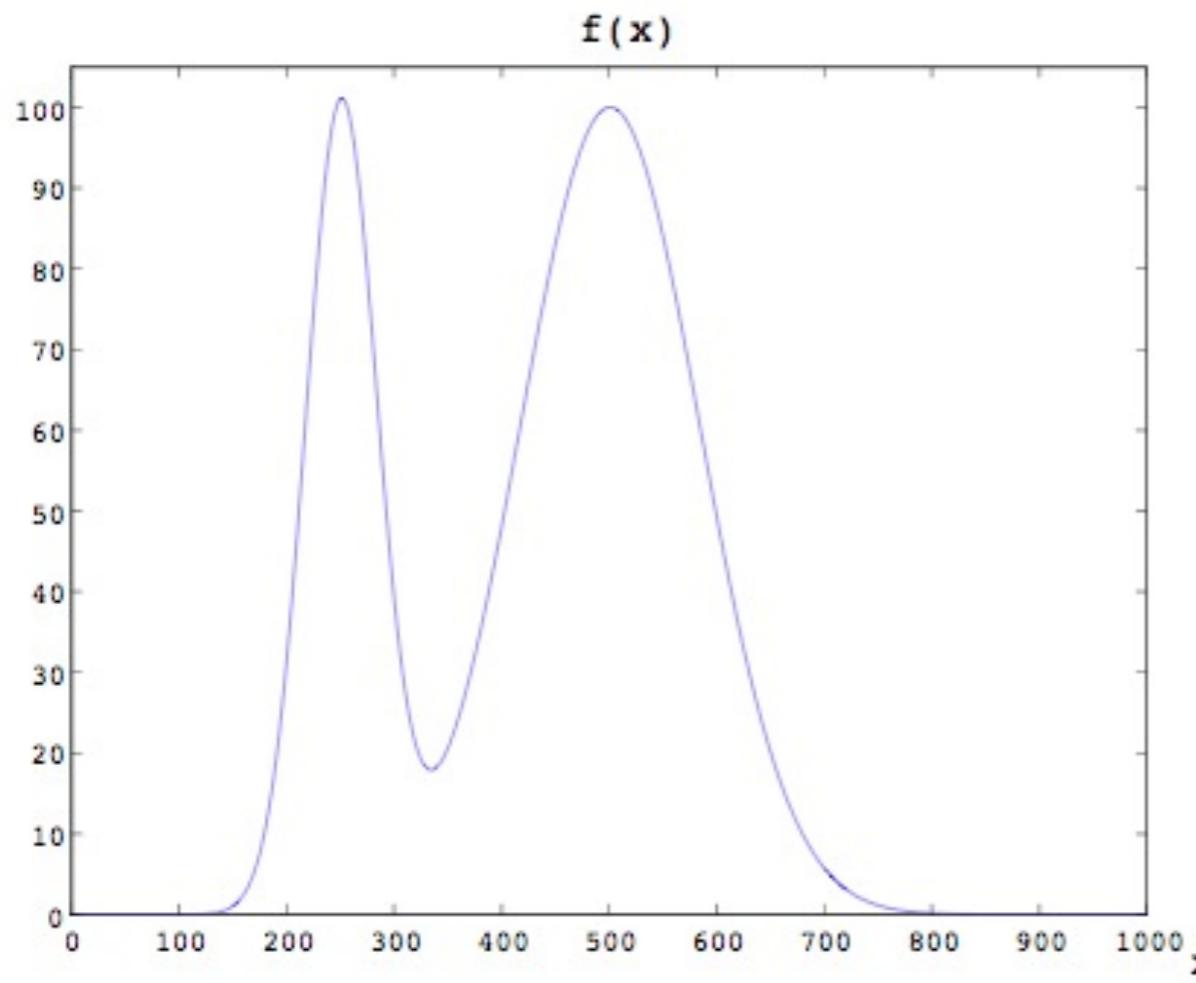
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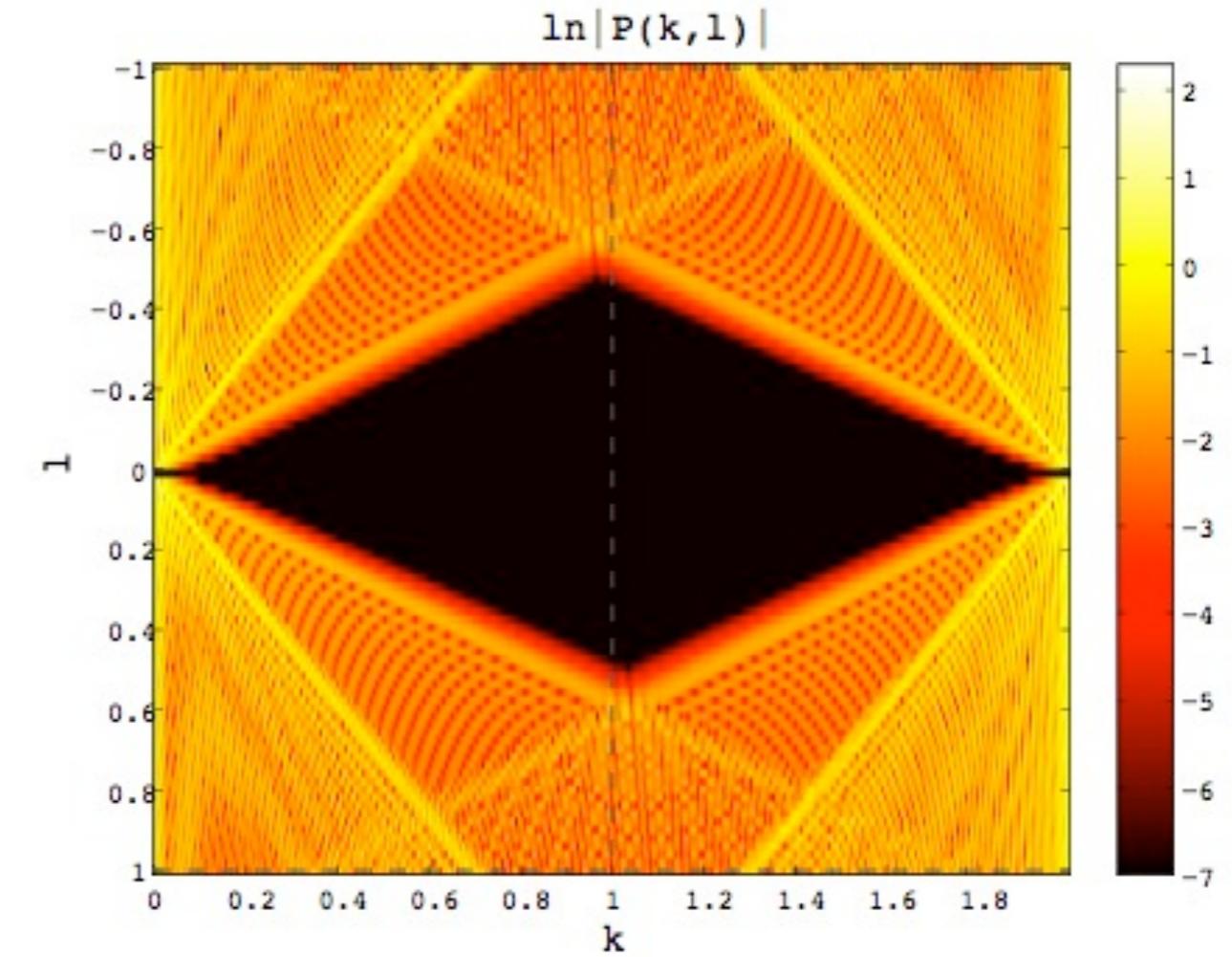
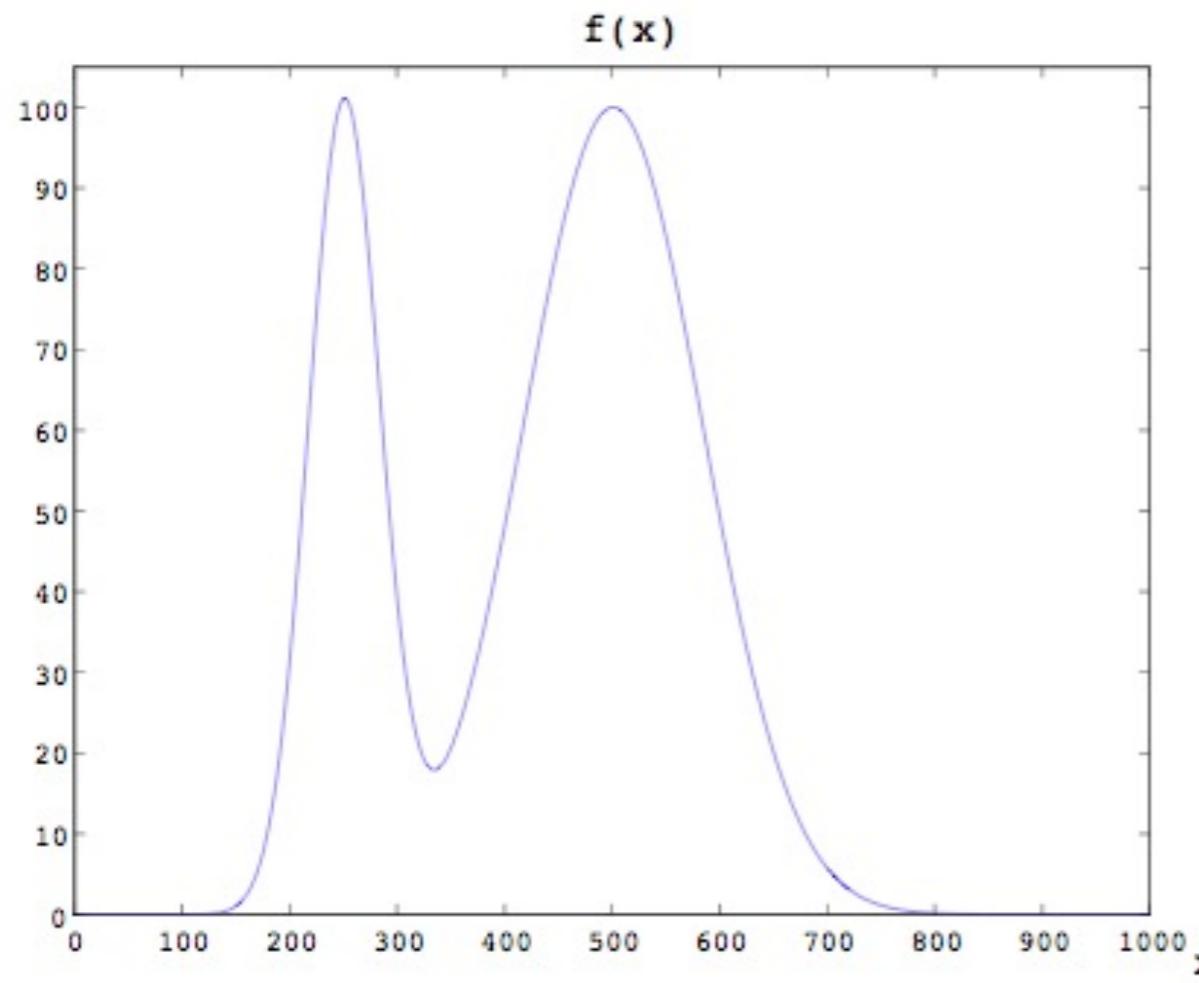
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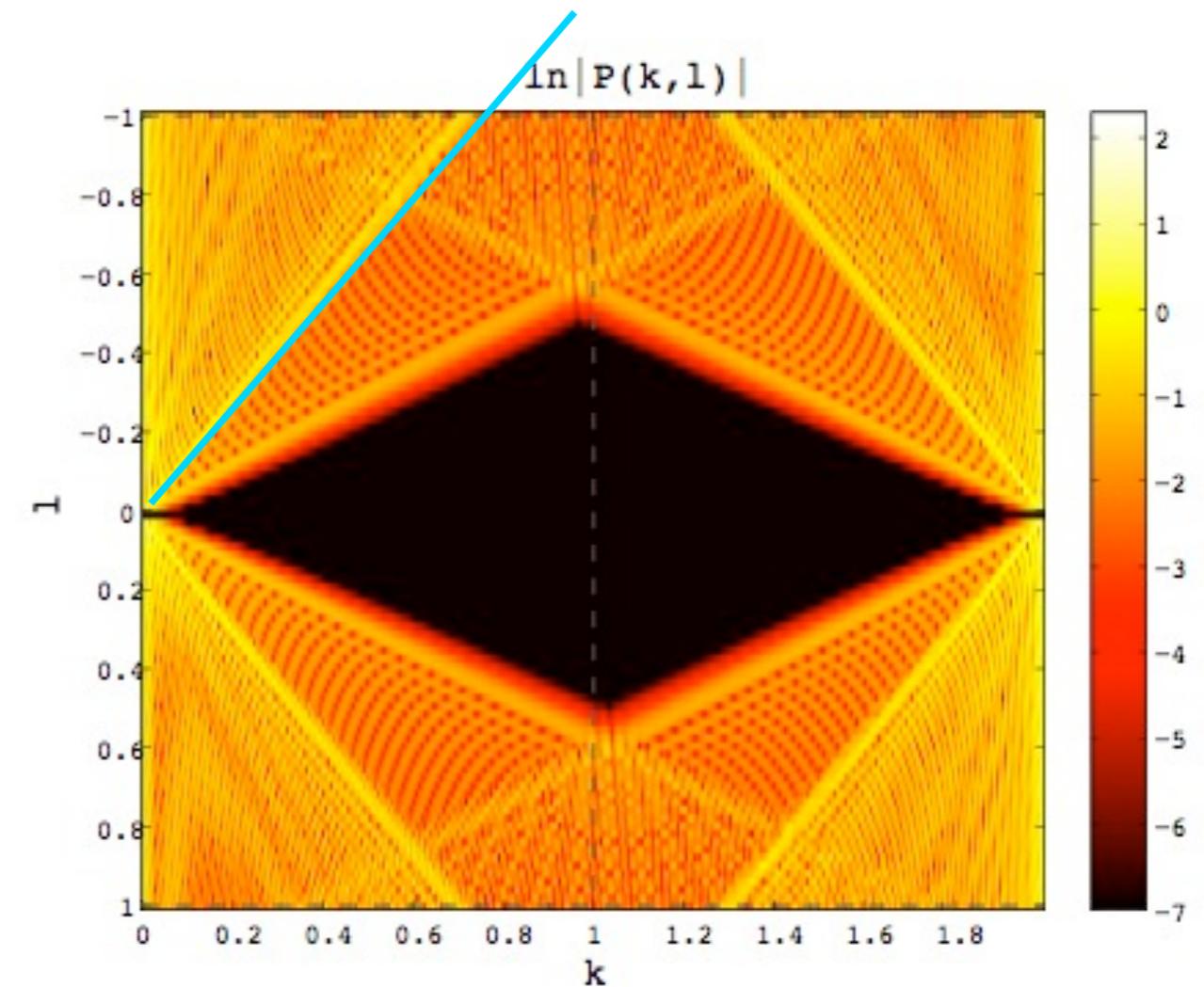
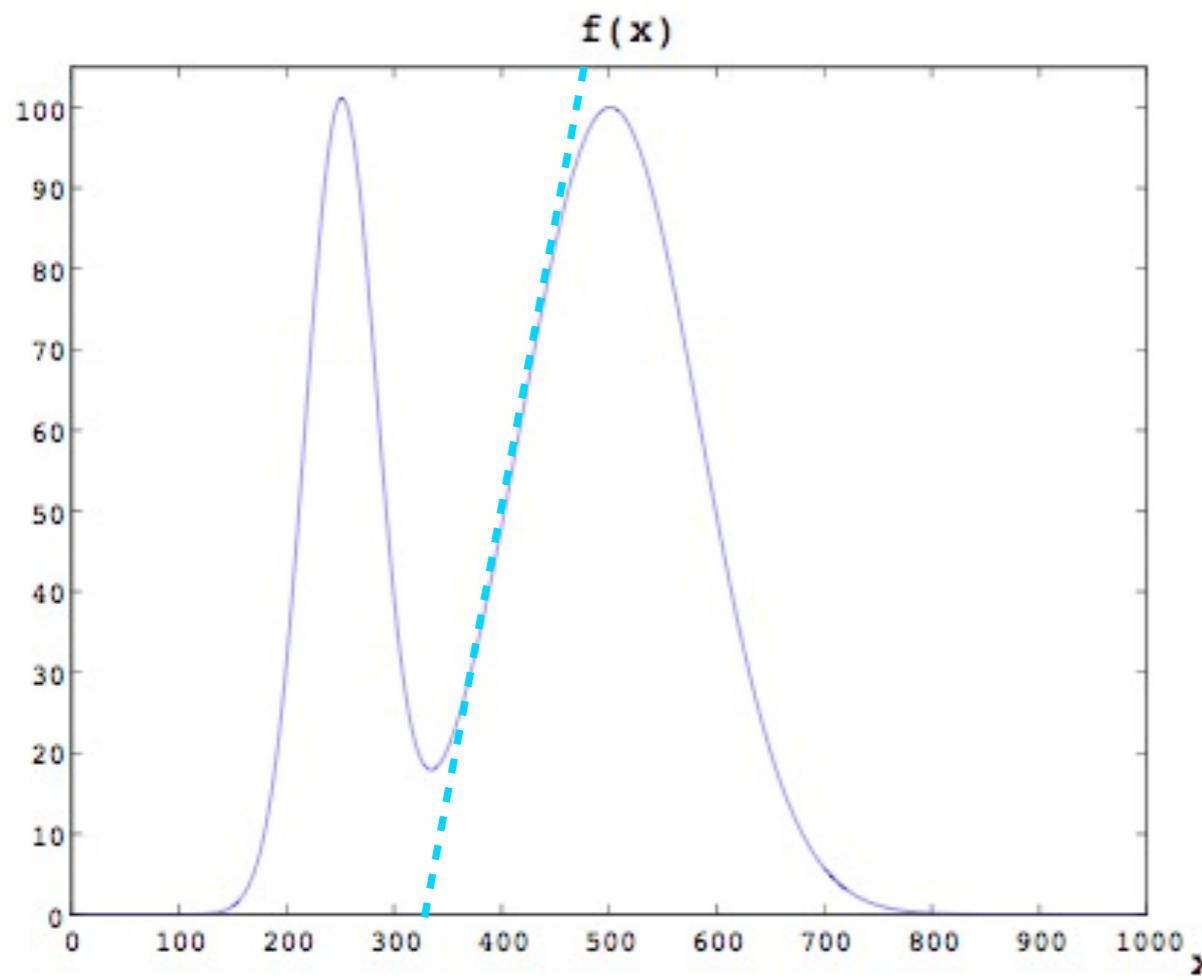


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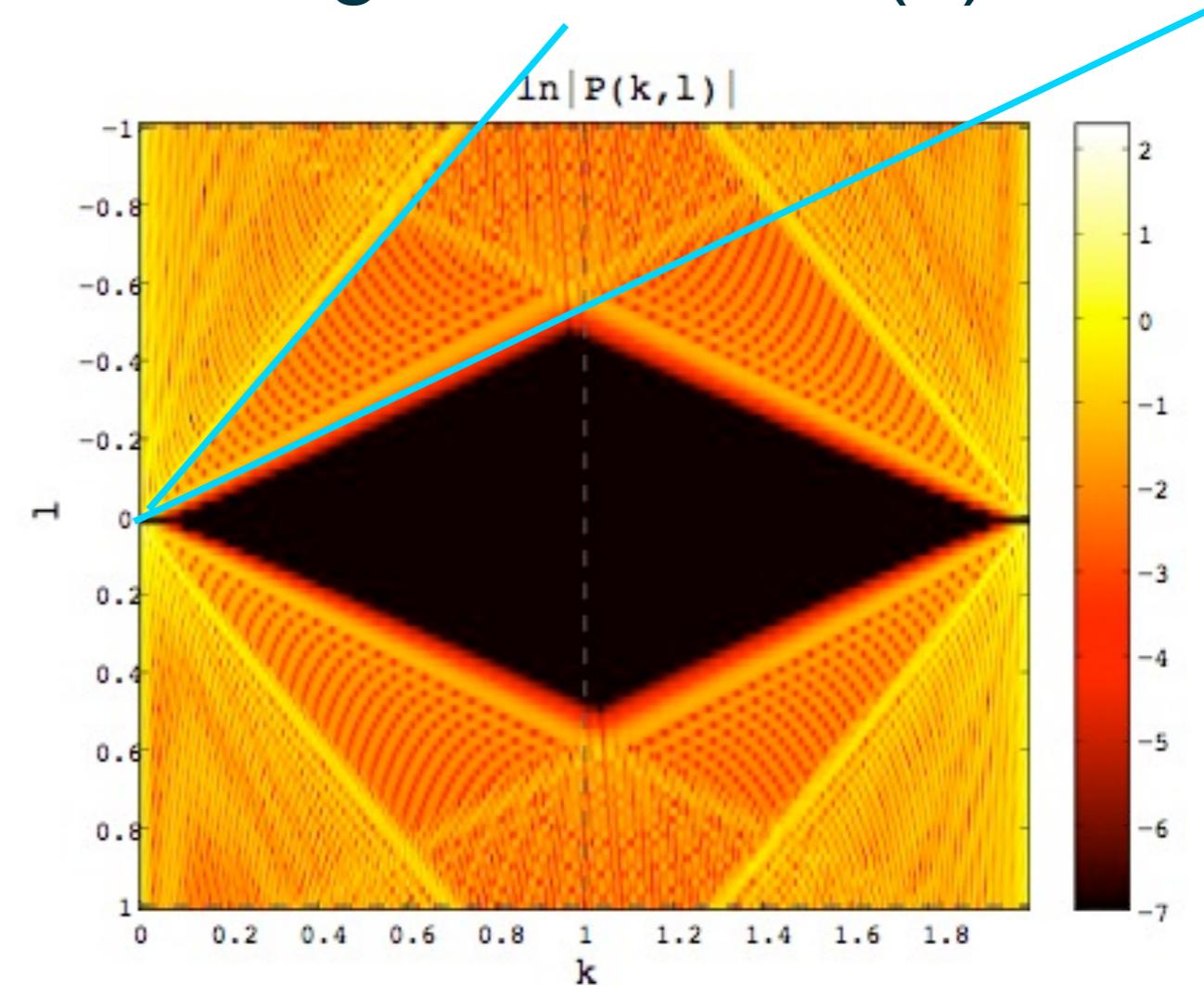
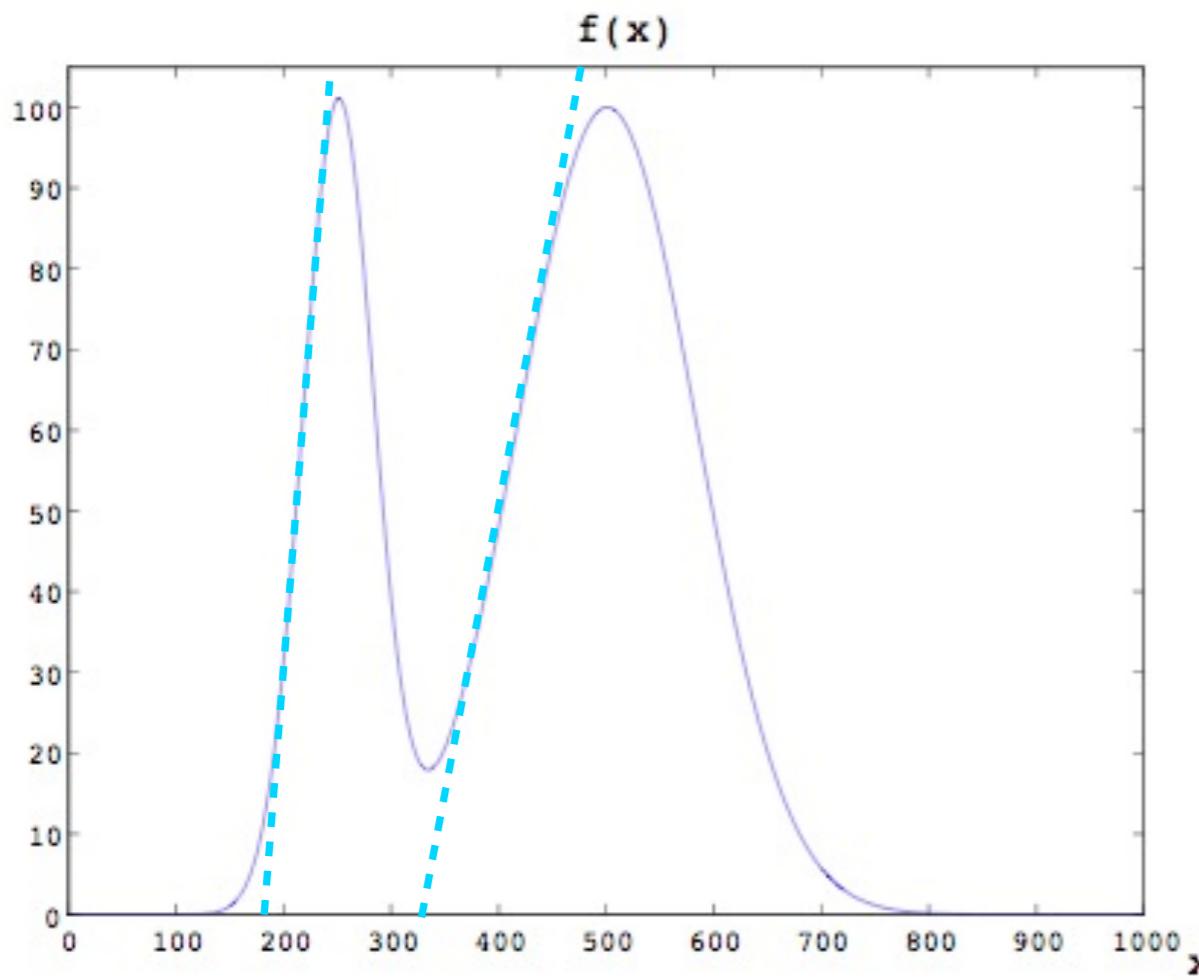
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- Slopes of lines in $P(k,l)$ are related to $1/f'(x)$



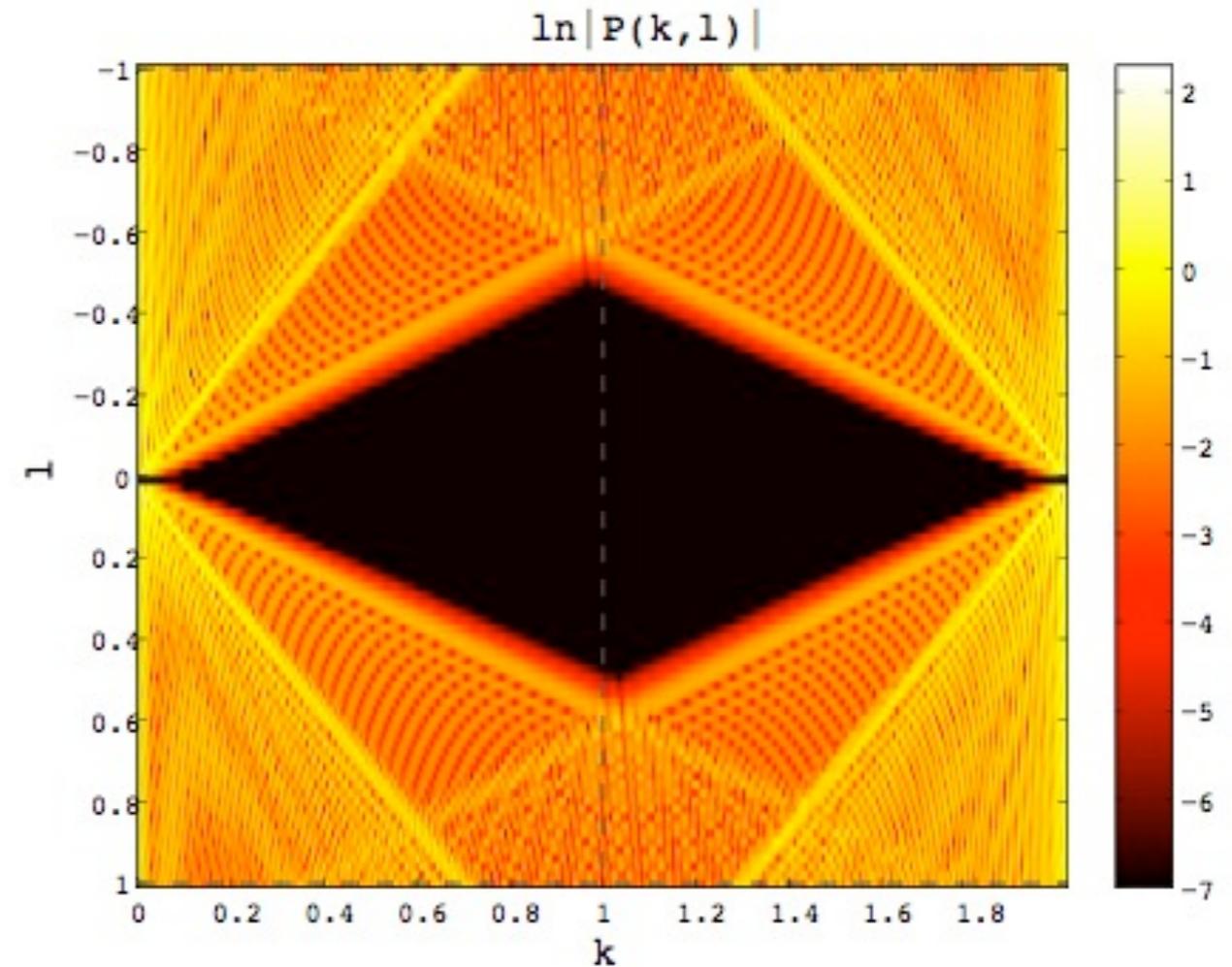
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- Slopes of lines in $P(k,l)$ are related to $1/f'(x)$
- Extremal slopes bounding the wedge are $1/\max(f')$



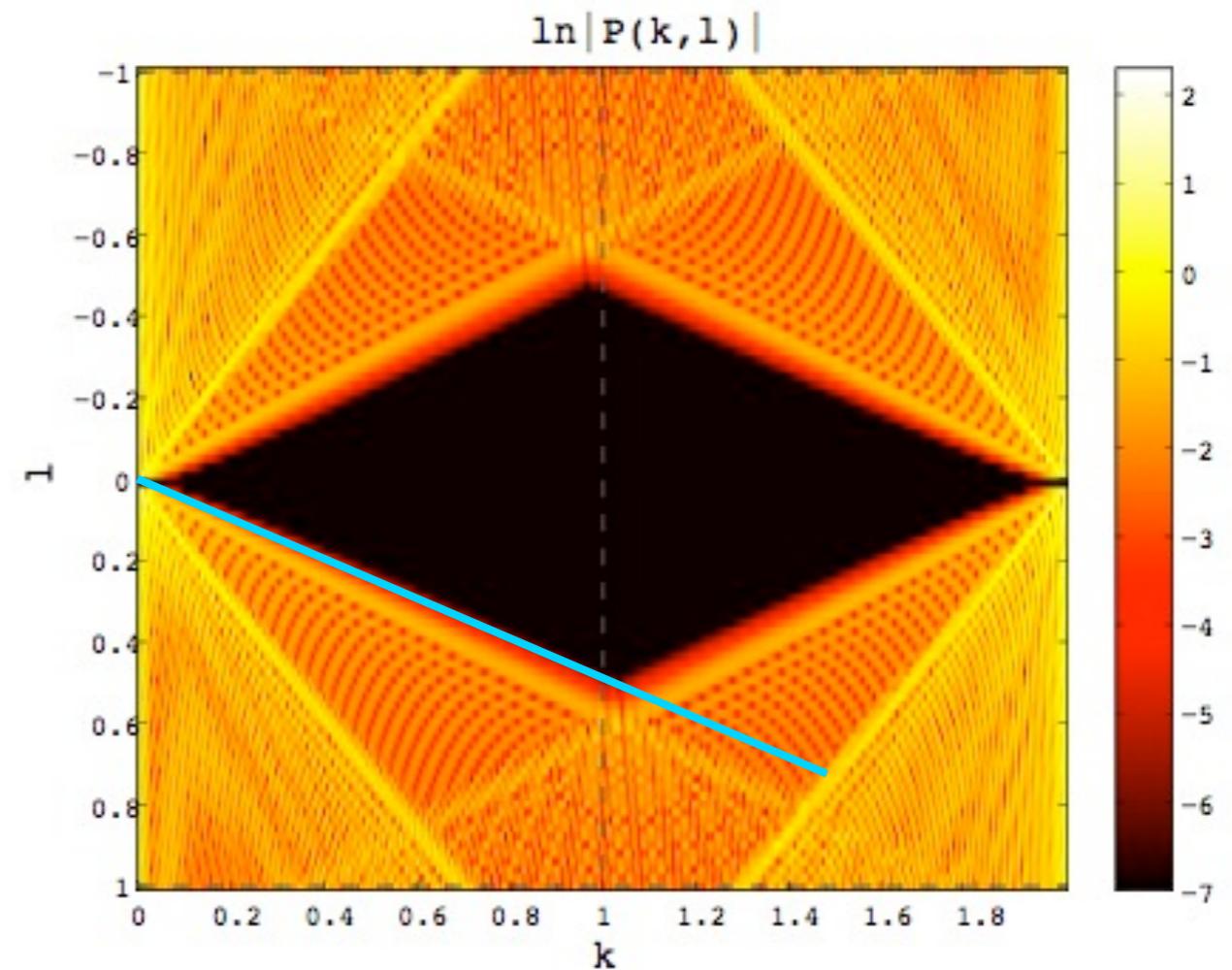
Method of stationary phase

$$P(k, l) = \int_R e^{i(l \cdot f(x) - k \cdot x)} dx$$



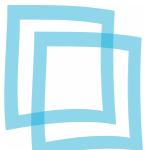
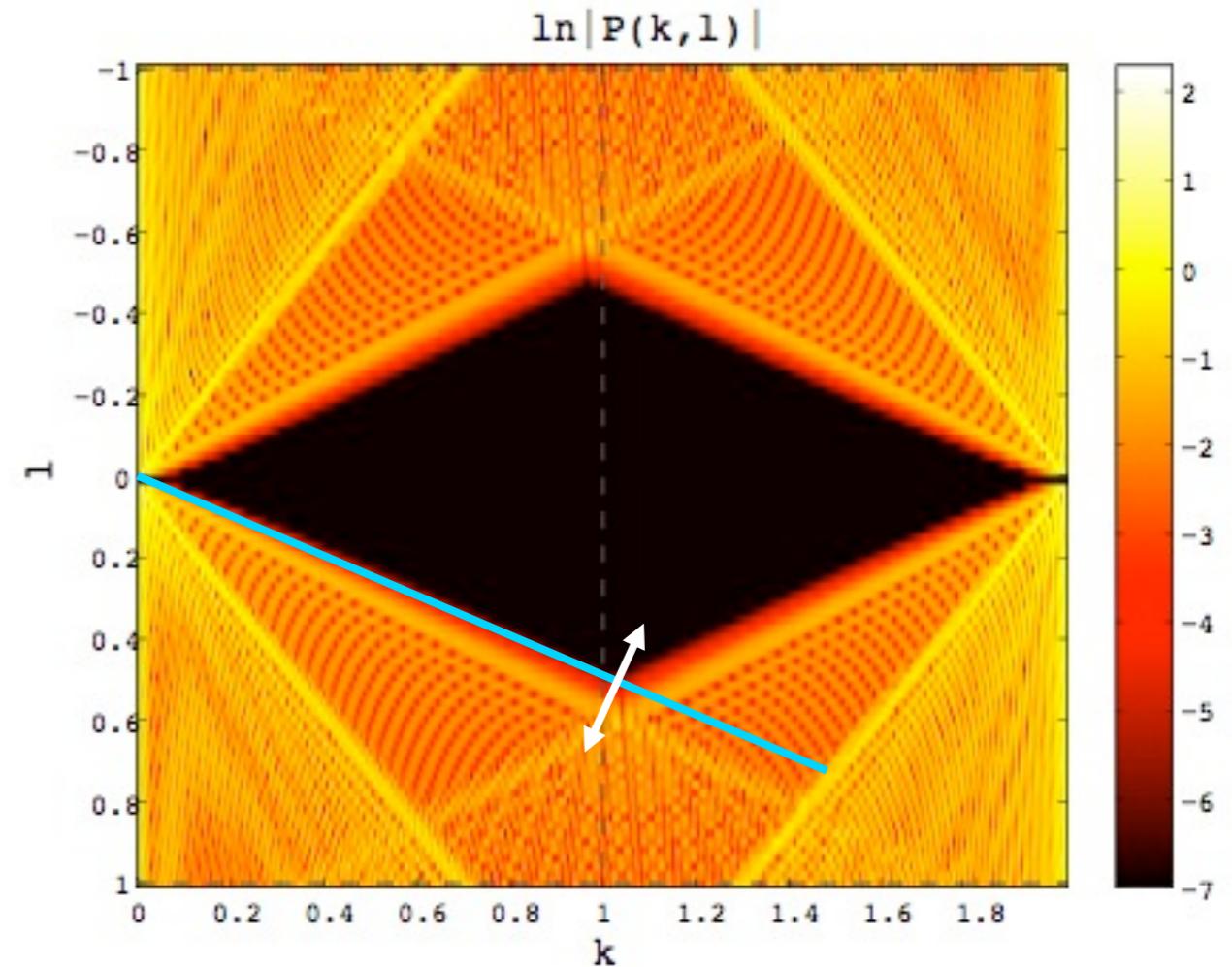
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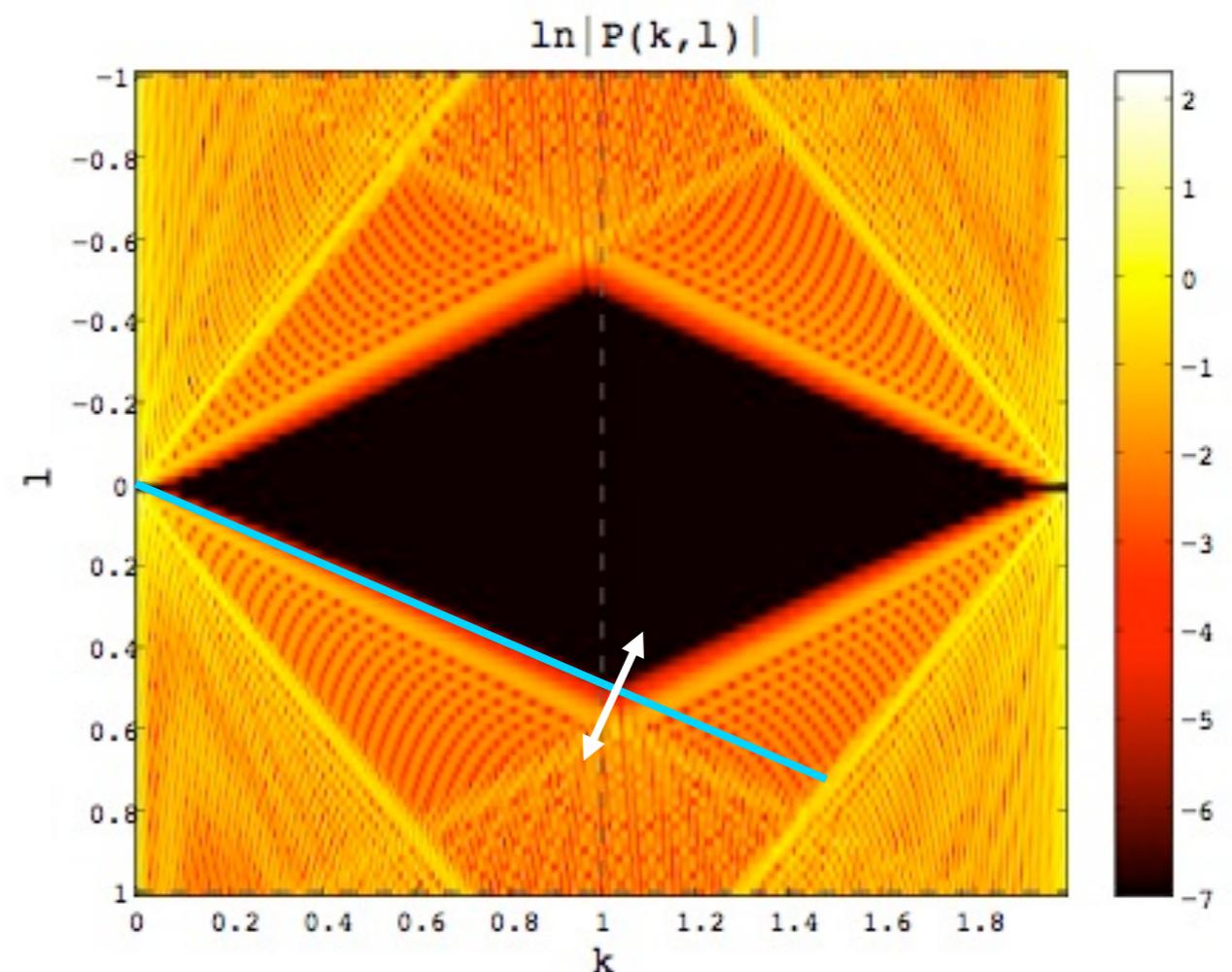
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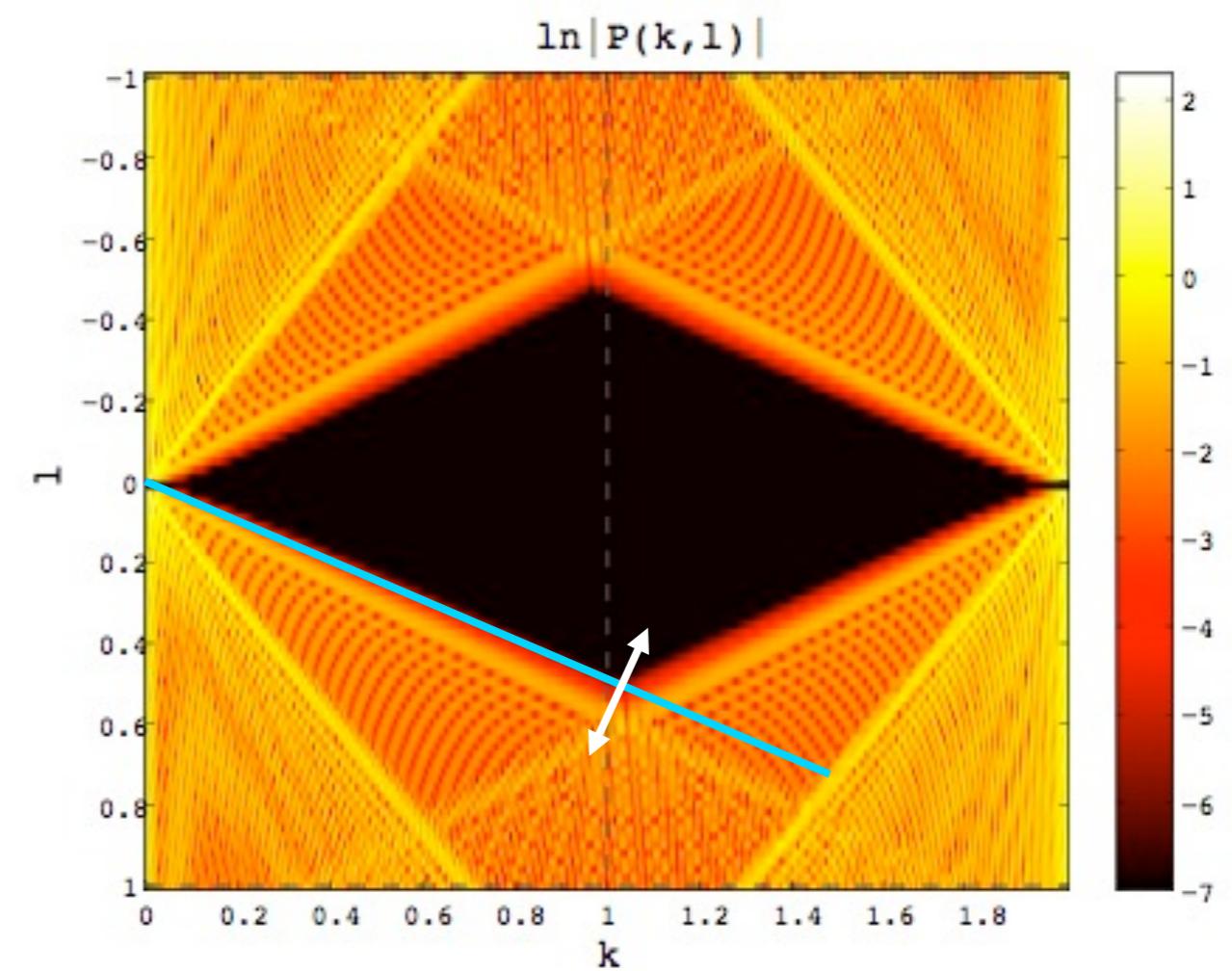
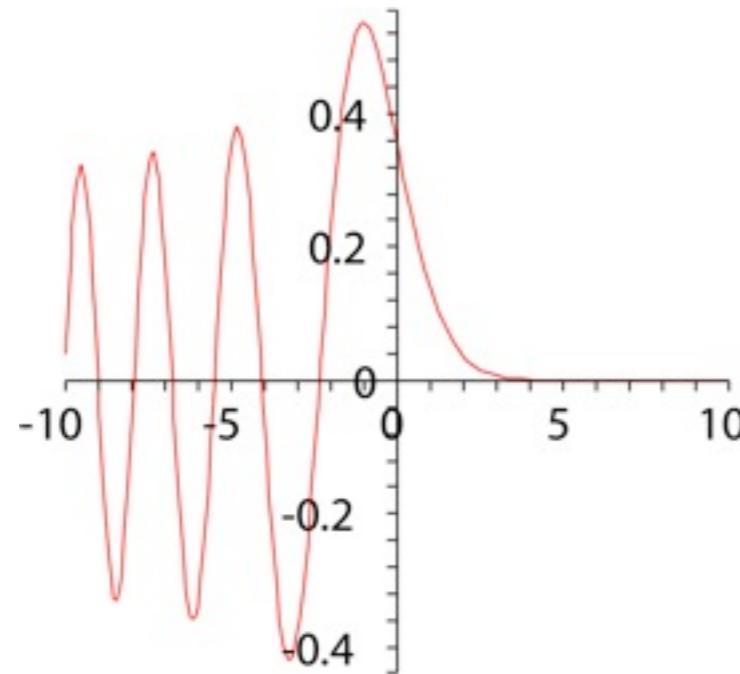
- Taylor expansion around points of stationary phase
- Exponential drop-off at maximum $l \cdot \max |f'| = k$



Method of stationary phase

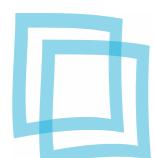
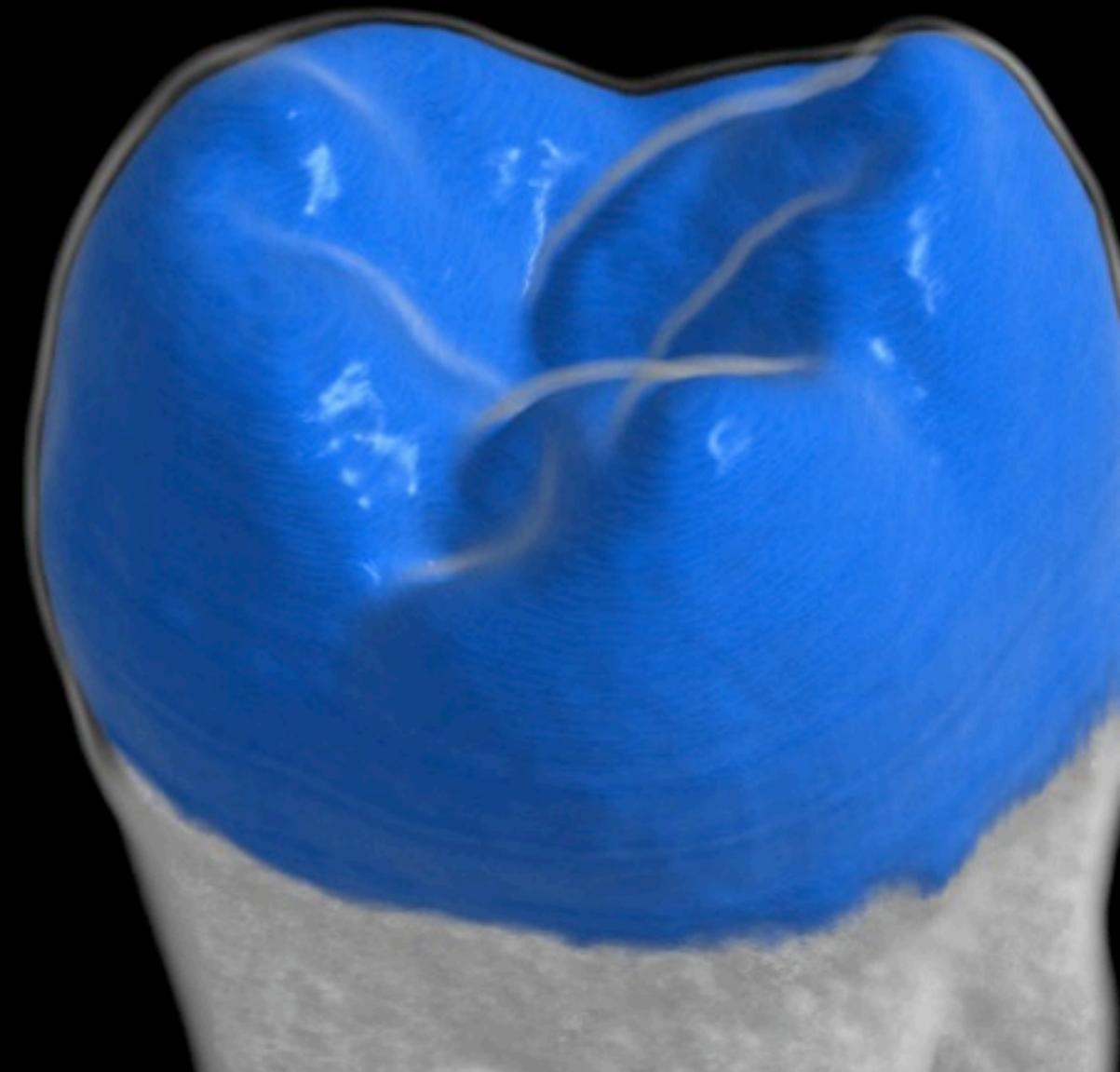
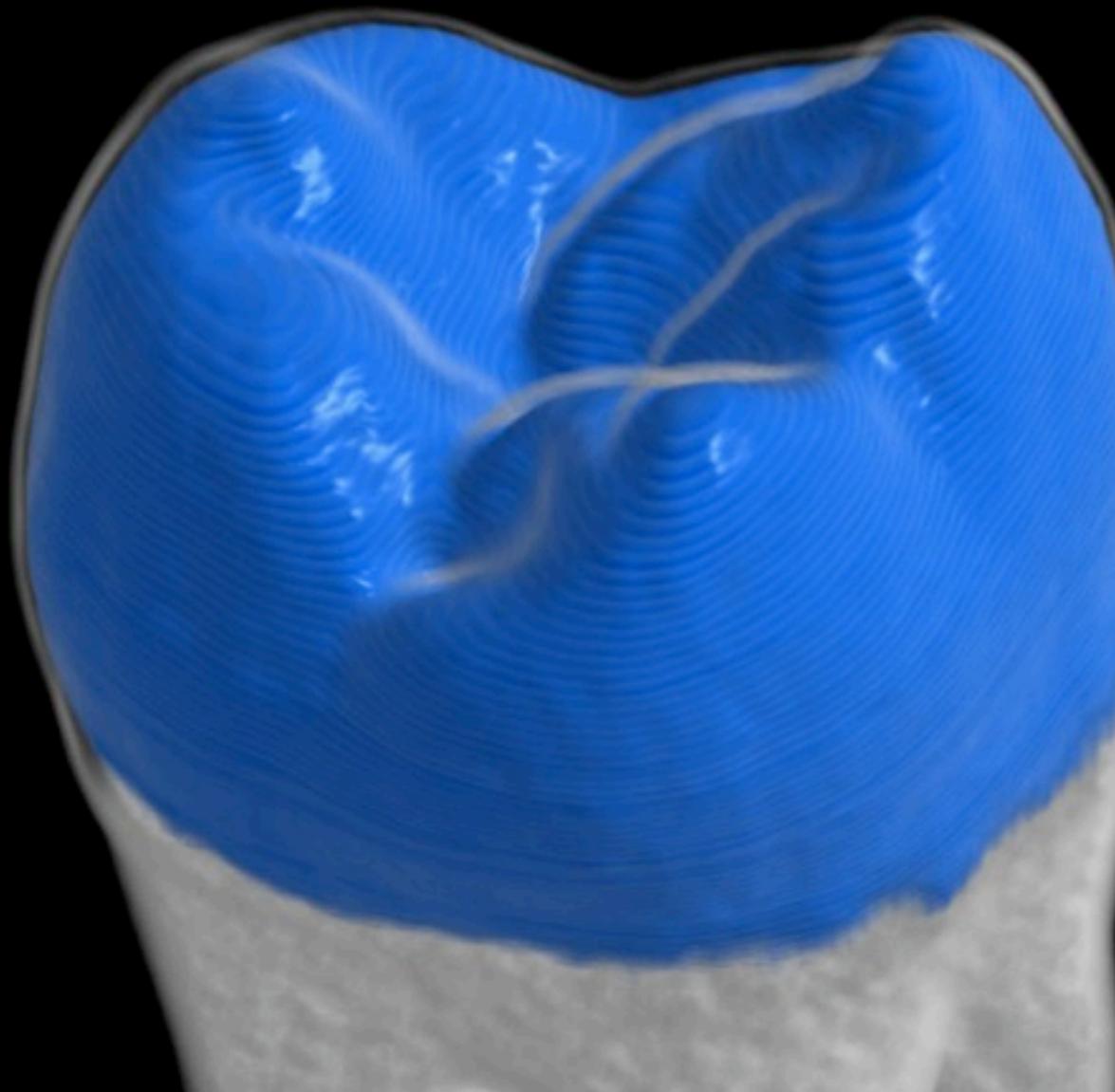
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Adaptive Raycasting

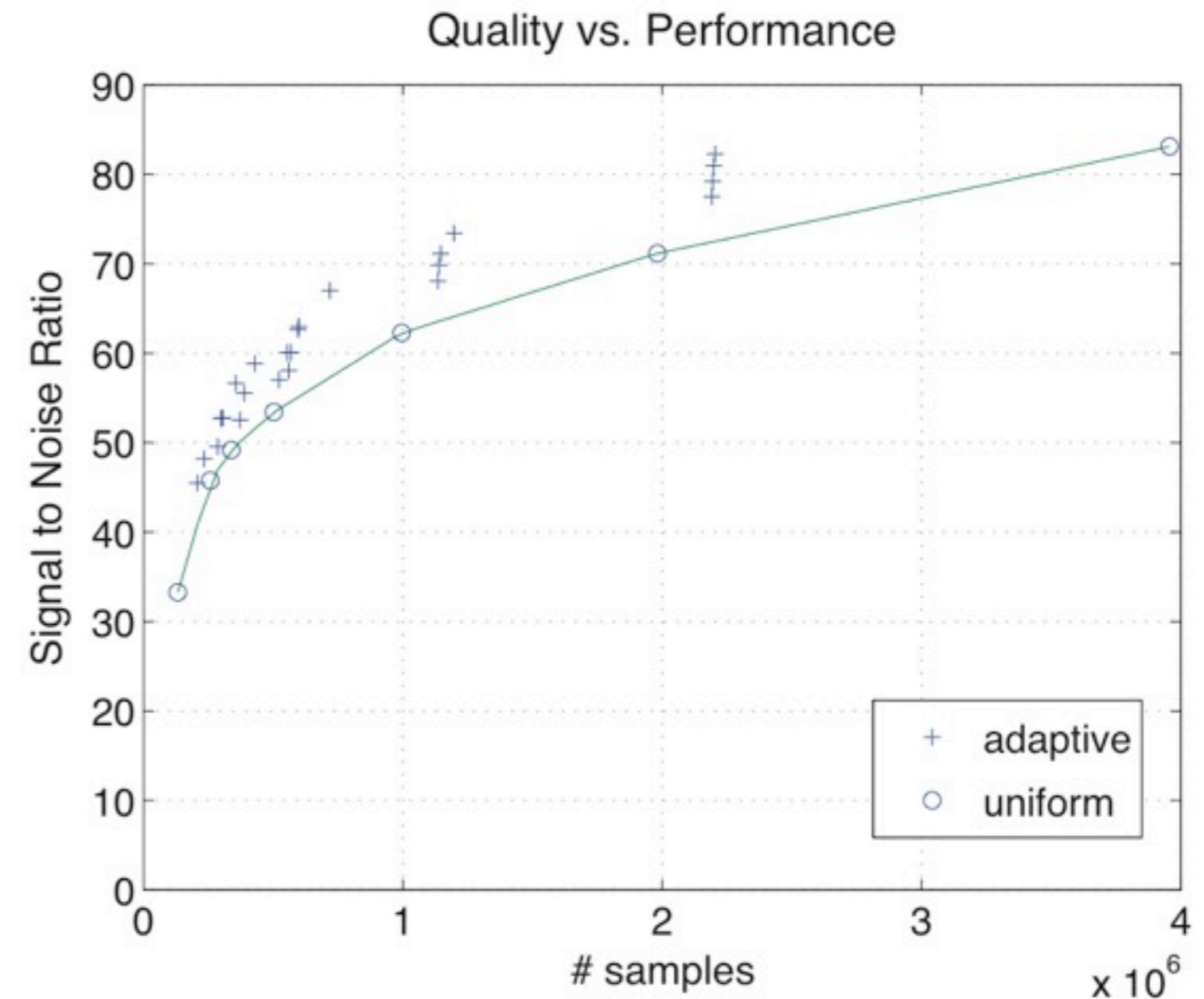
Same number of samples



Adaptive Raycasting

SNR

Ground-truth:
computed at a fixed
sampling distance
of 0.06125



Summary

- Proper sampling of combined signal $g(f(x))$:

$$v_h = \max(||f'||) \cdot v_g$$

- Solved a fundamental problem of rendering
- Composition is a general data processing operation



Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
- Theoretical analysis: Sampling in volume rendering
- Filling a region: Lattices with rotational dilation
- Summary and conclusion



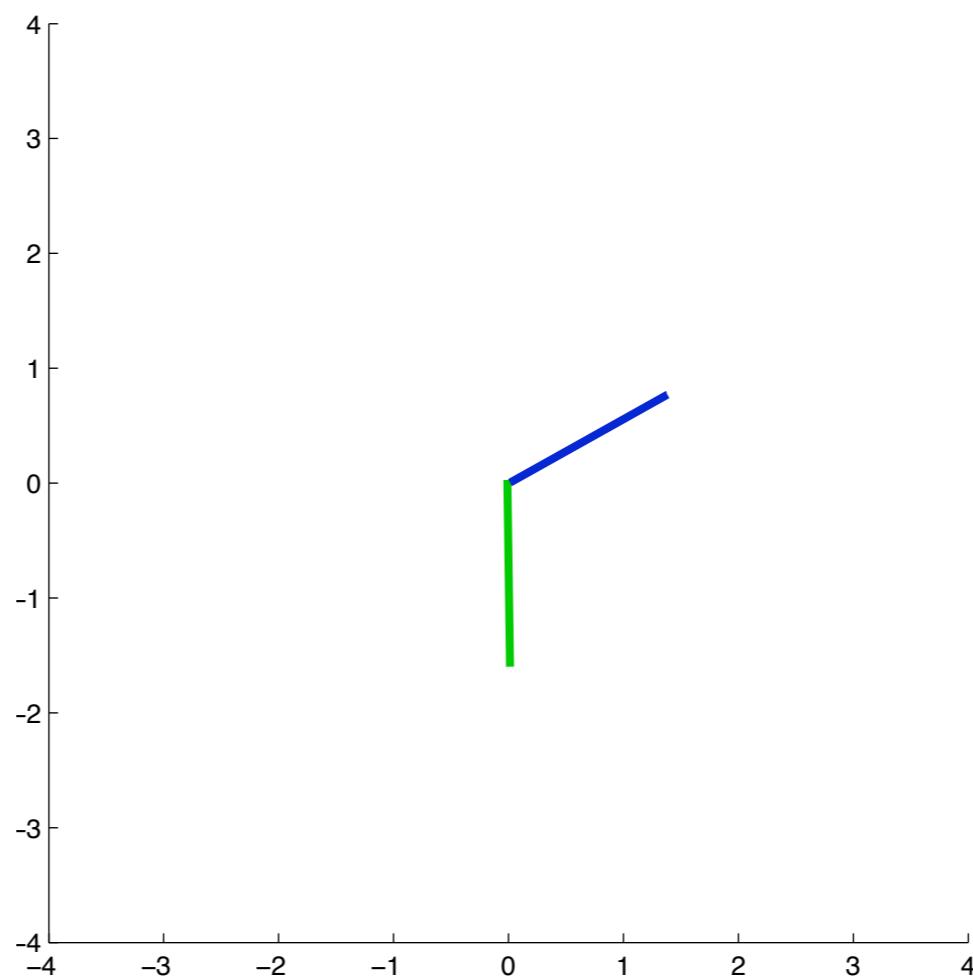
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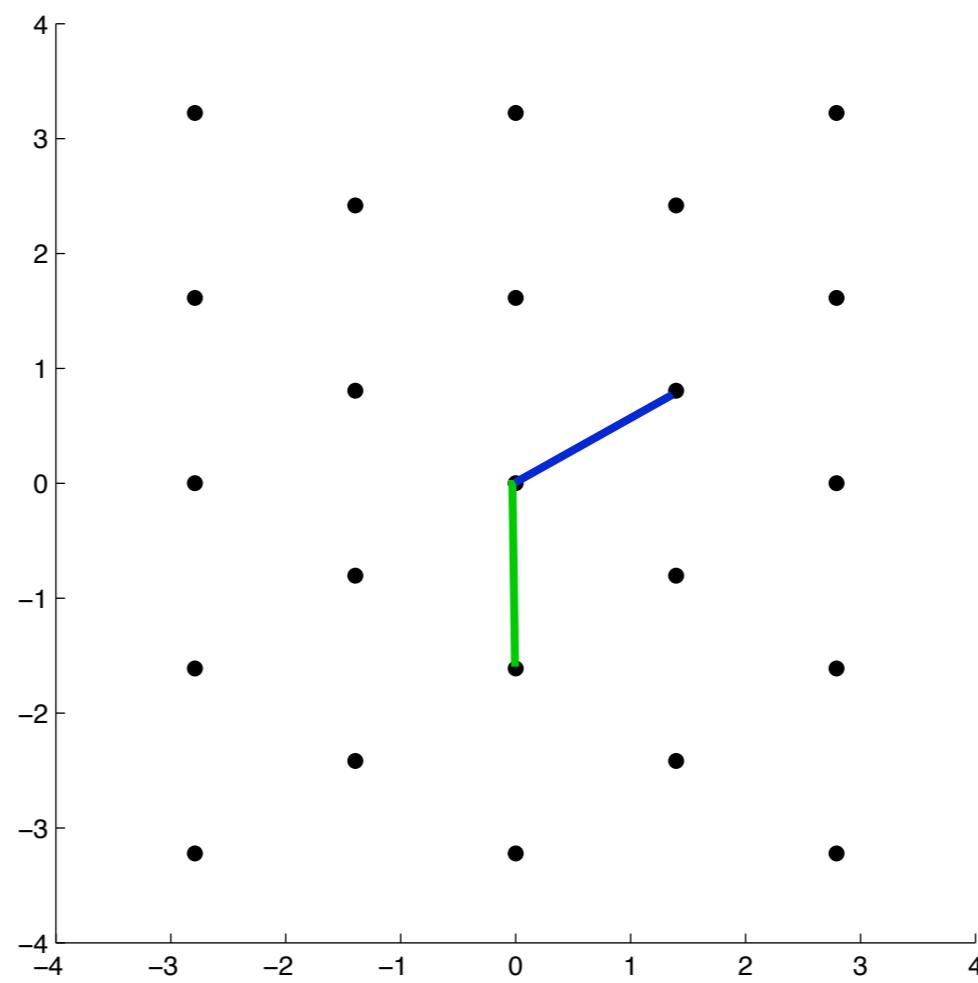
Point lattices

- Definition via basis R

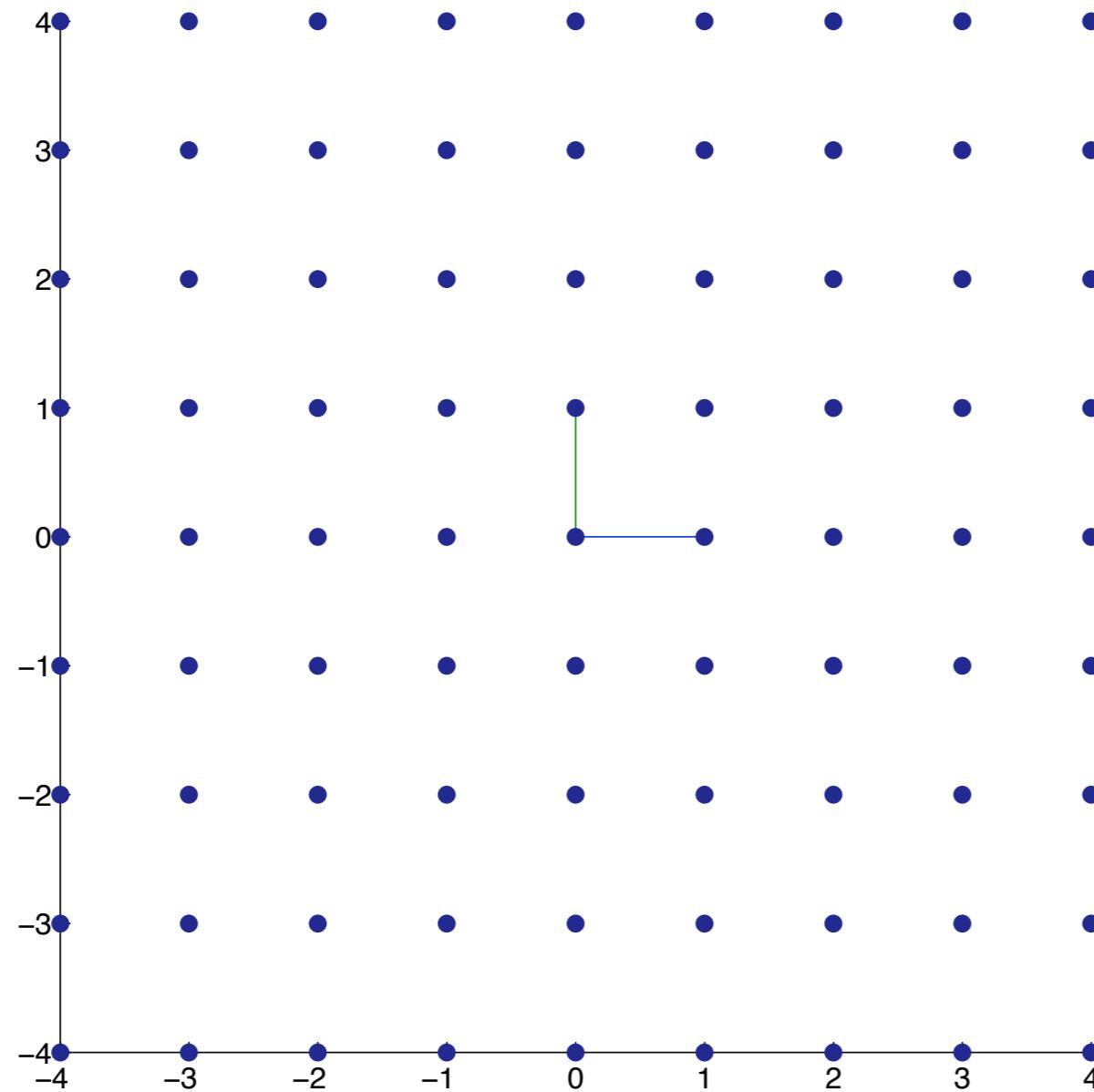


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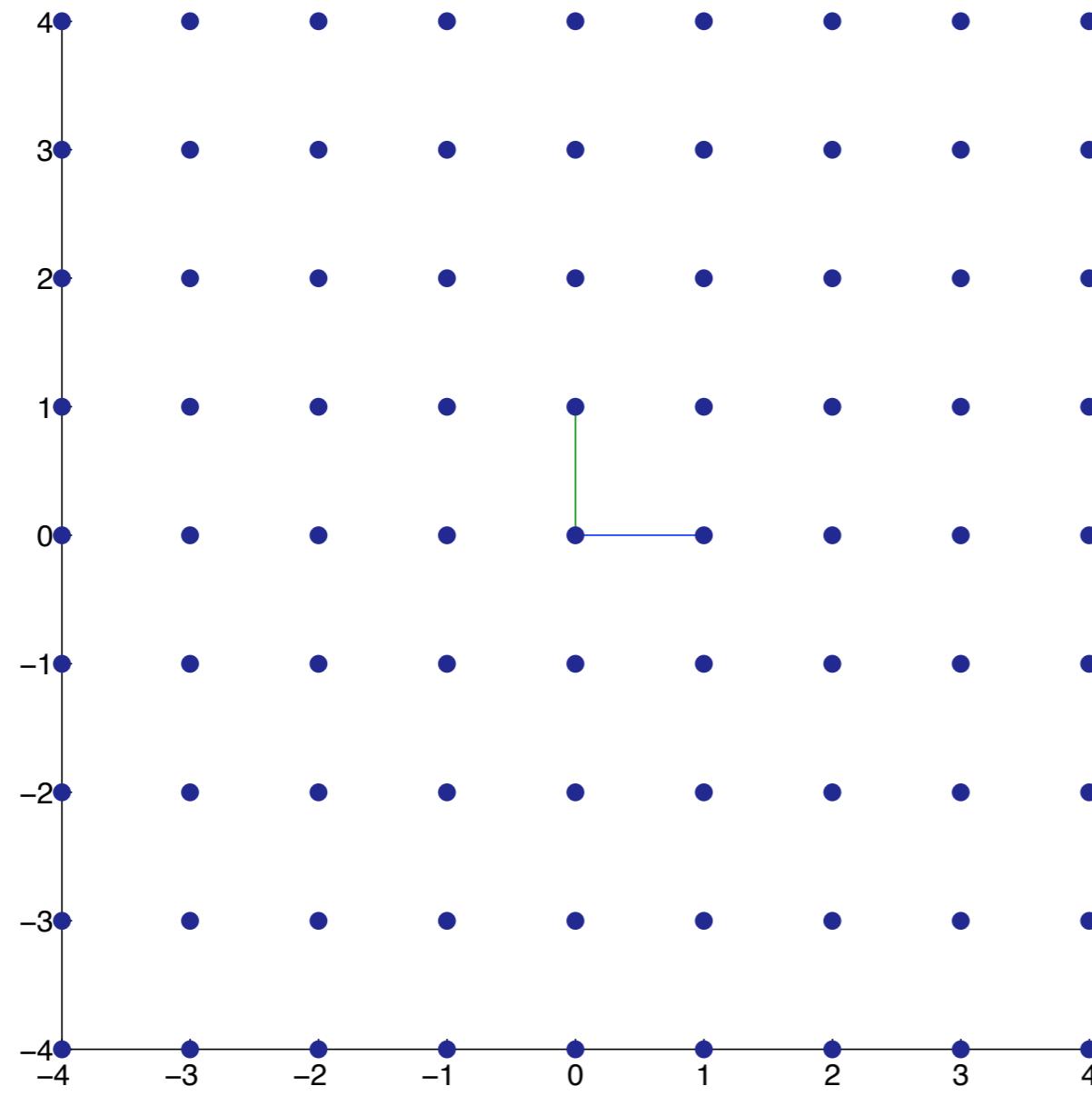
- Definition via basis $\{\mathbf{R}k : k \in \mathbb{Z}^n\}$



$$\mathbf{R} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



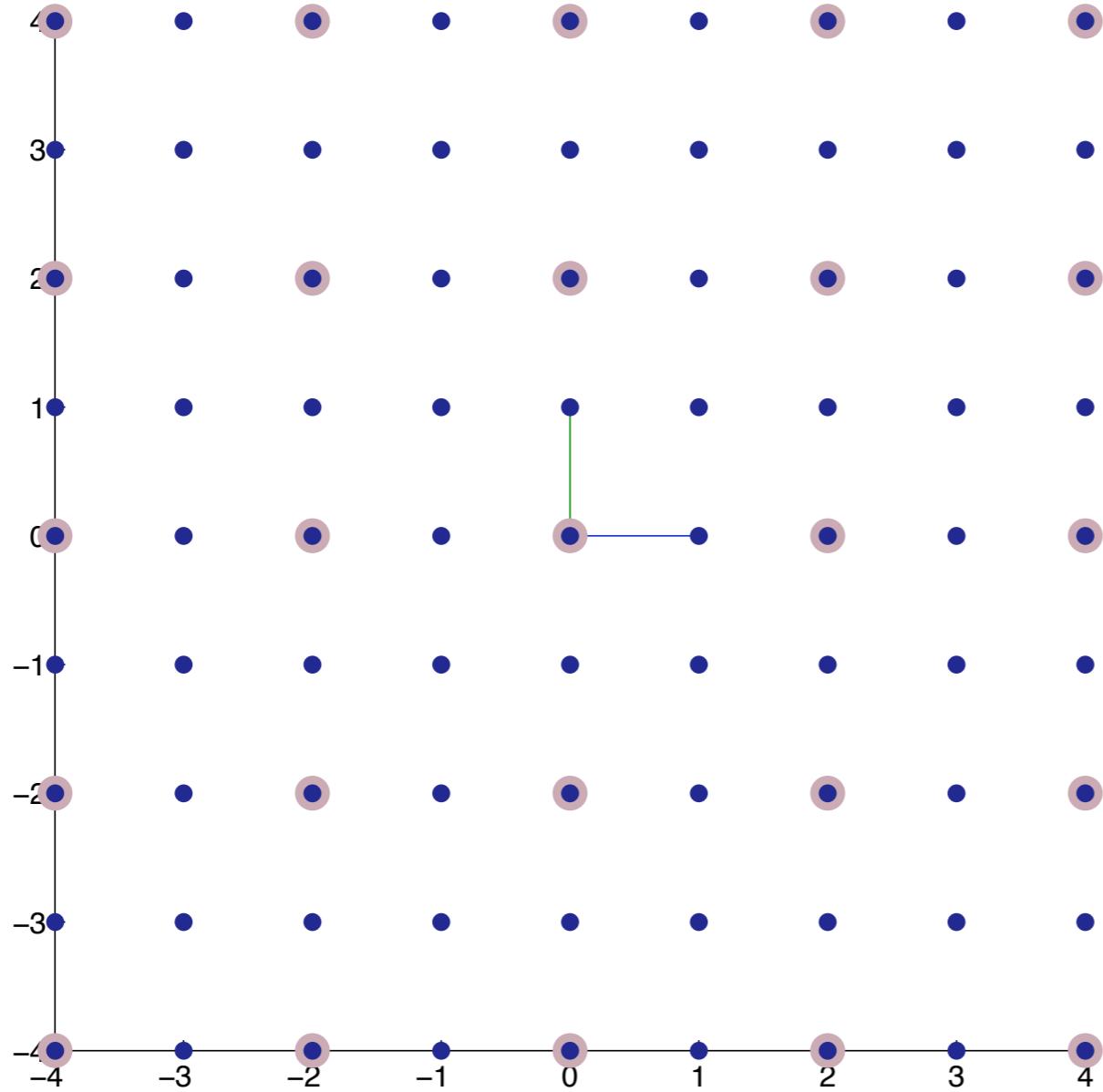
$$\mathbf{R} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \mathbf{K} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = 2\mathbf{I} \quad \det \mathbf{K} = 2^n = 4$$



dyadic subsampling



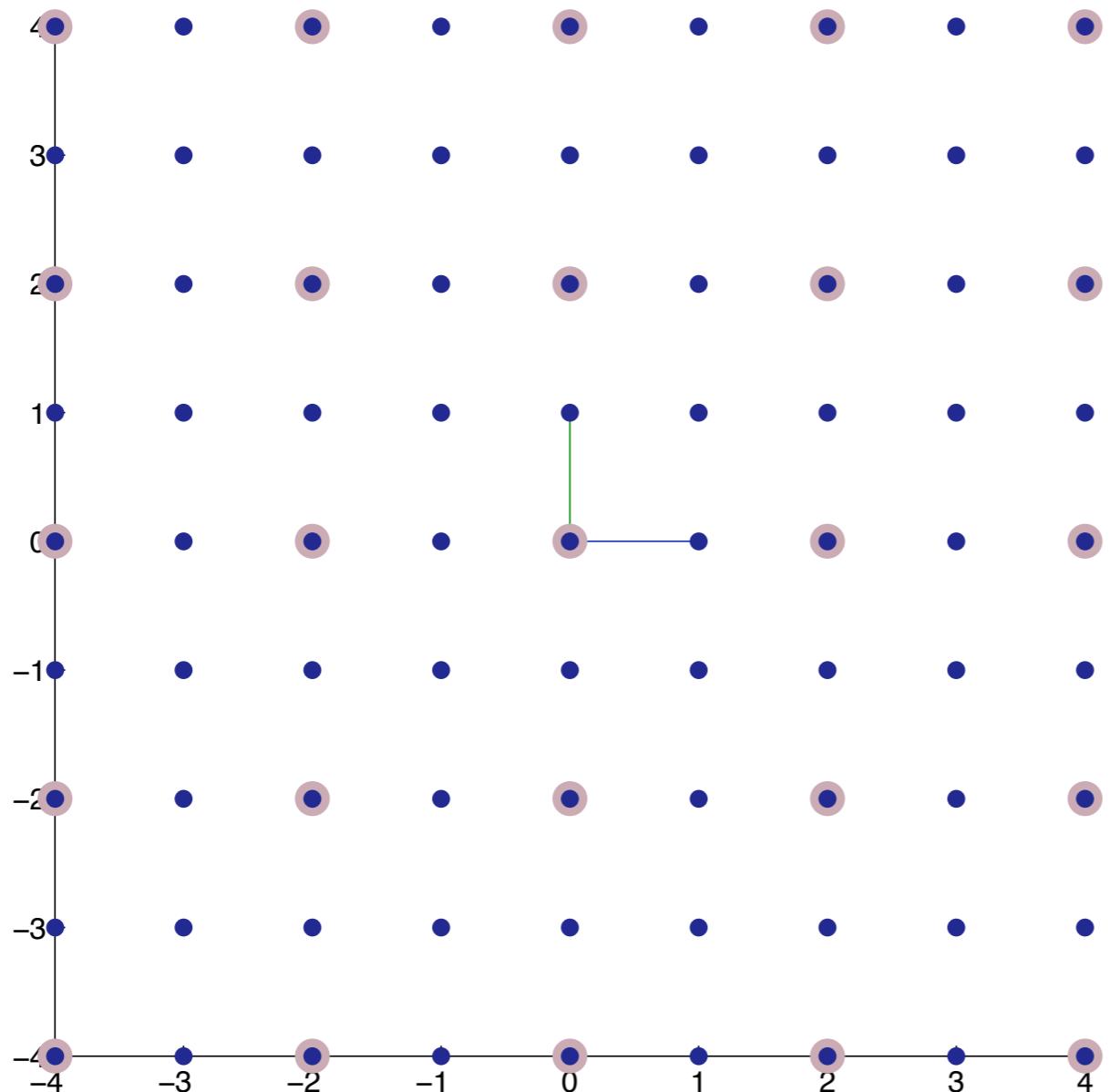
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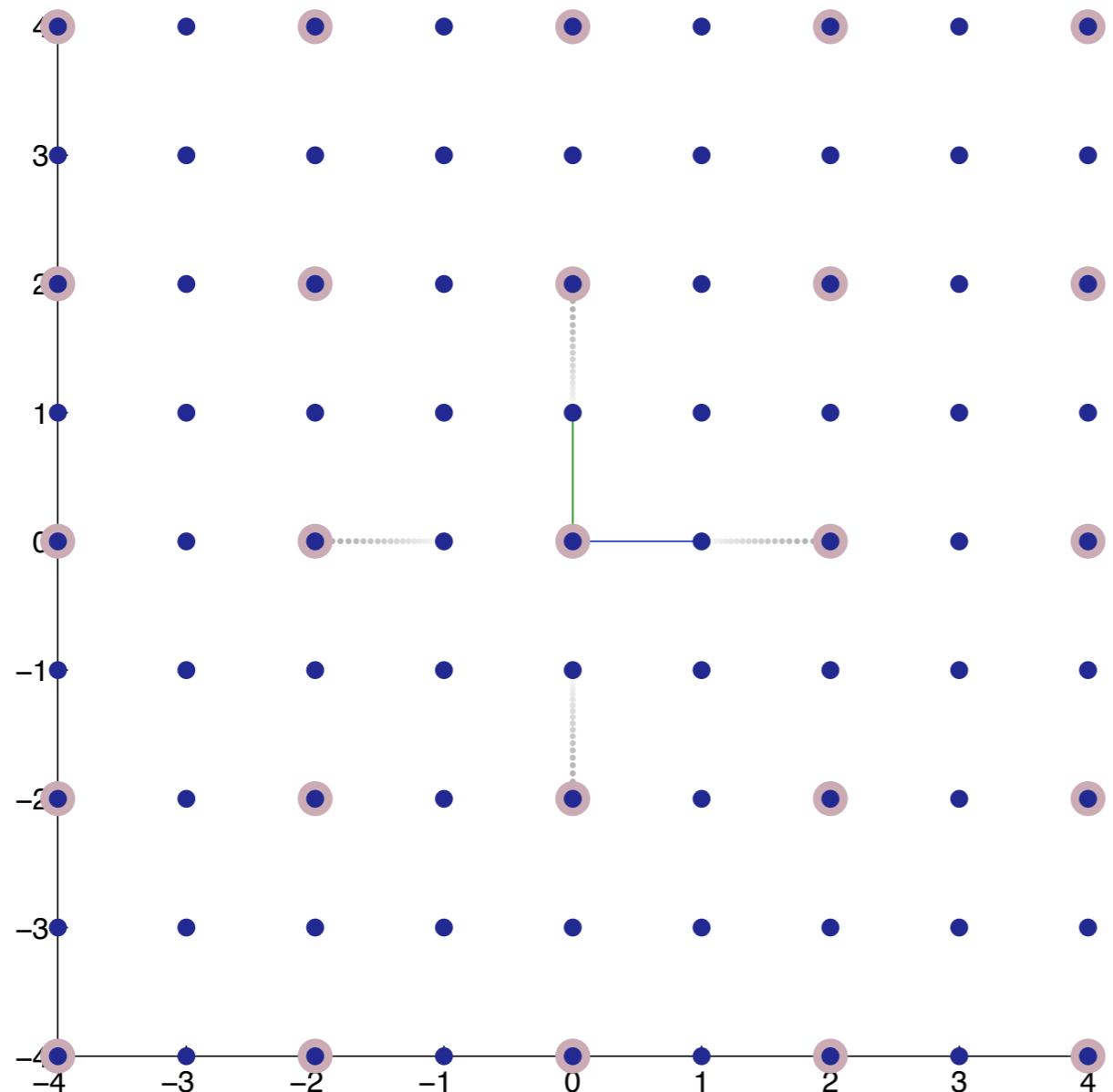


**Reduction factor
is exponential in n**

dyadic subsampling



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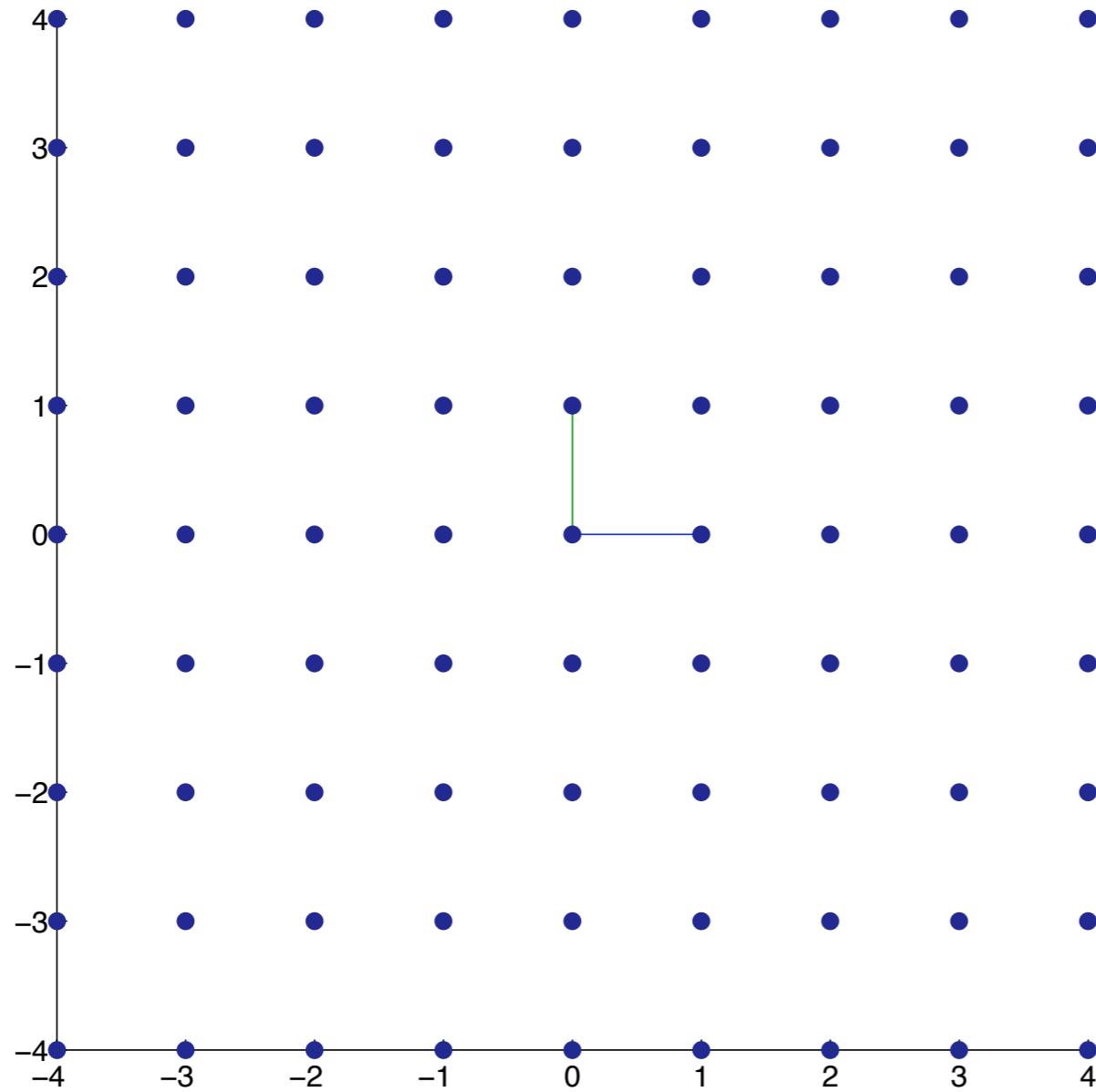


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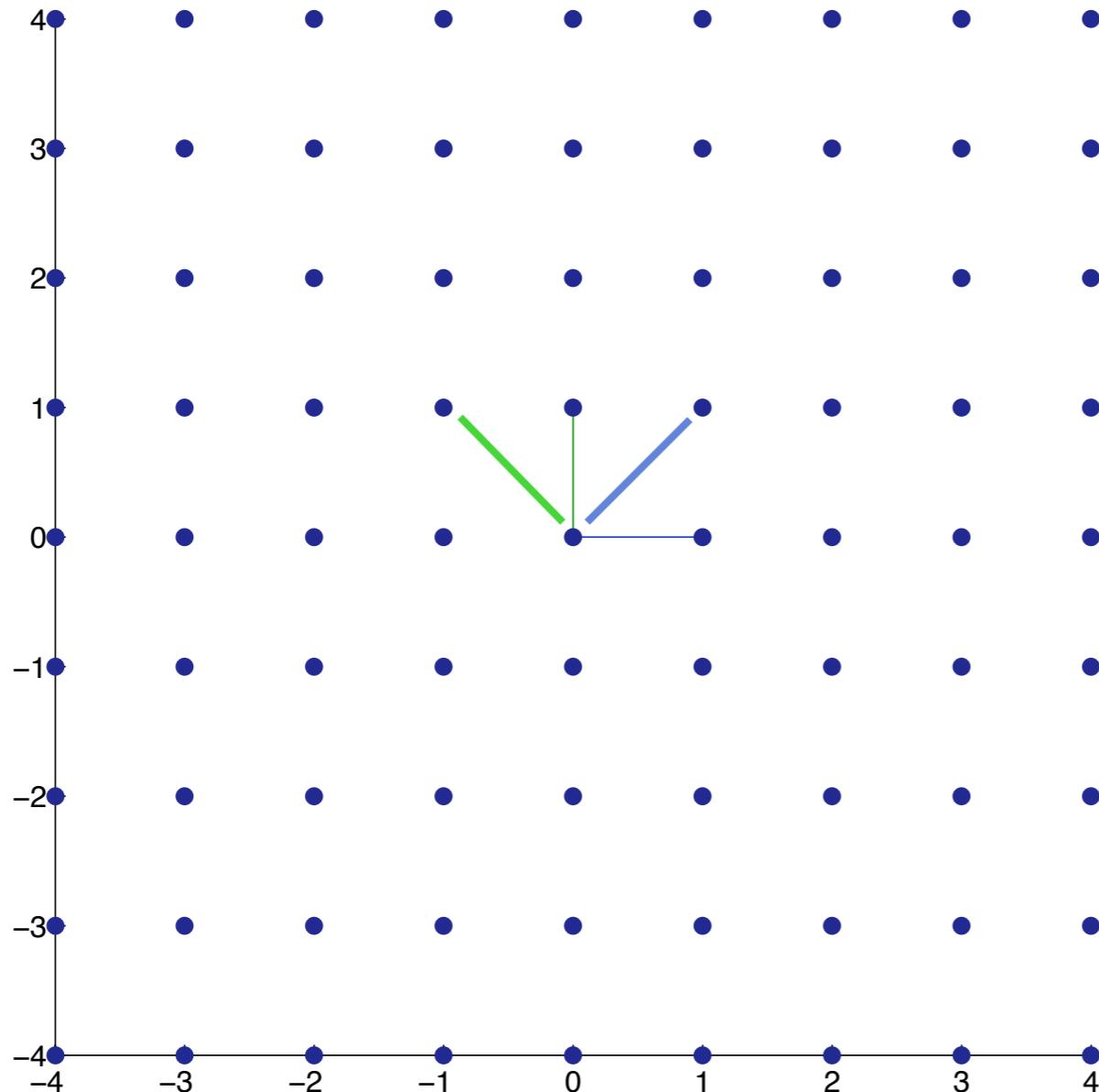
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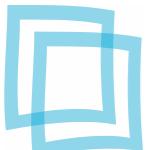
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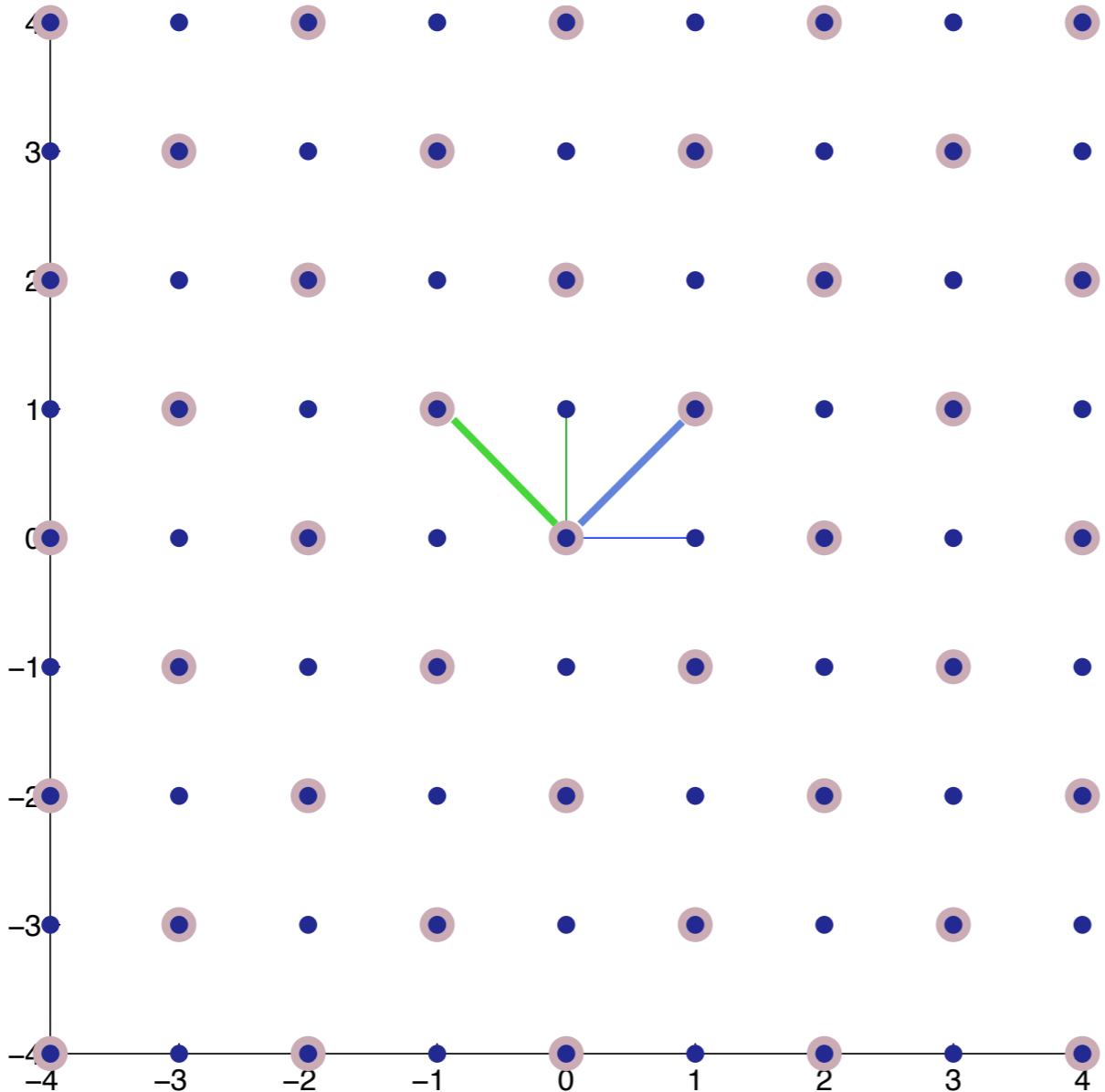
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quincunx subsampling



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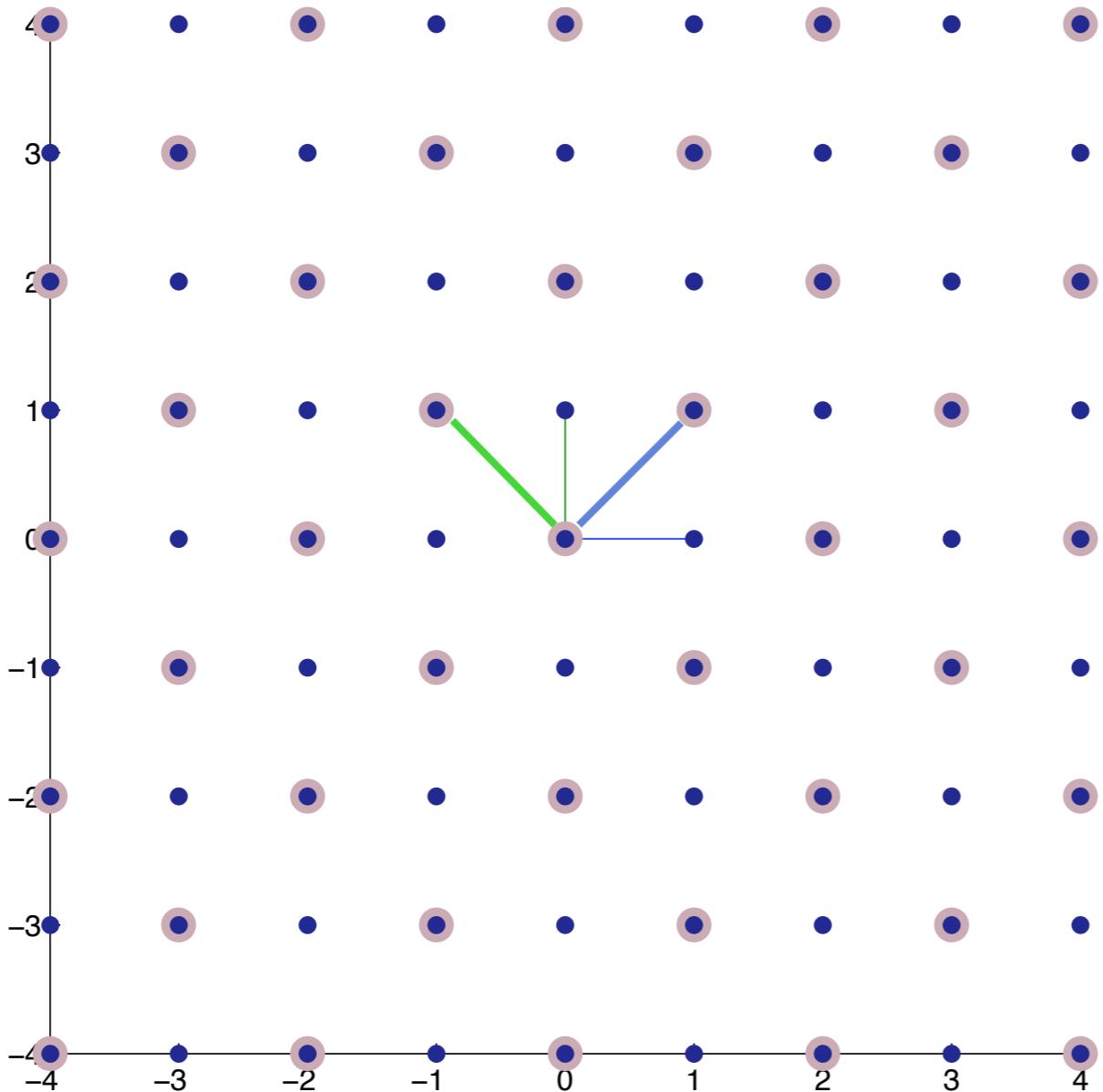


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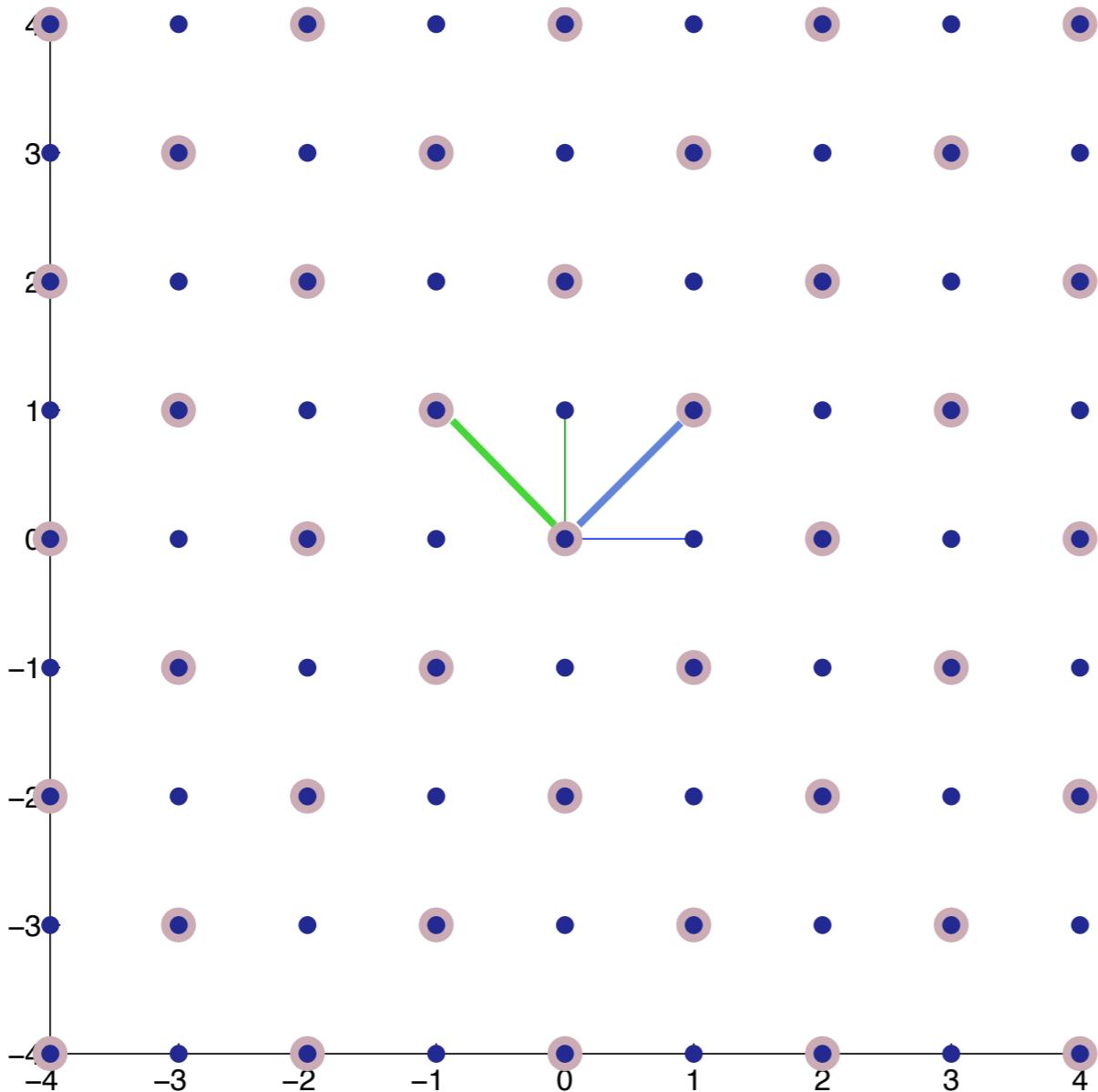
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 [Van De Ville, Blu, Unser, SPL 05]

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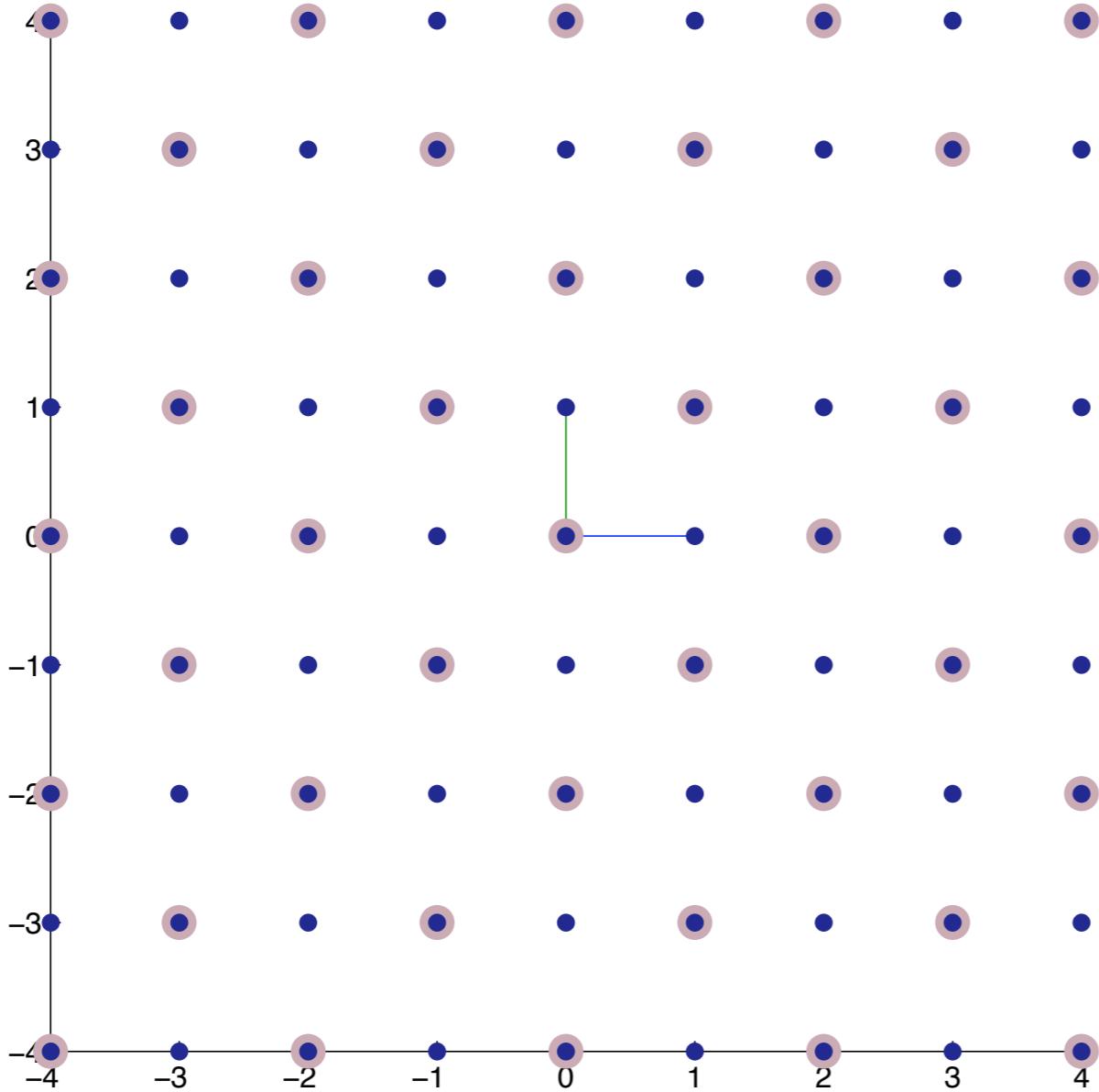
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However,
 possible for
 irrational \mathbf{R} !

quincunx subsampling



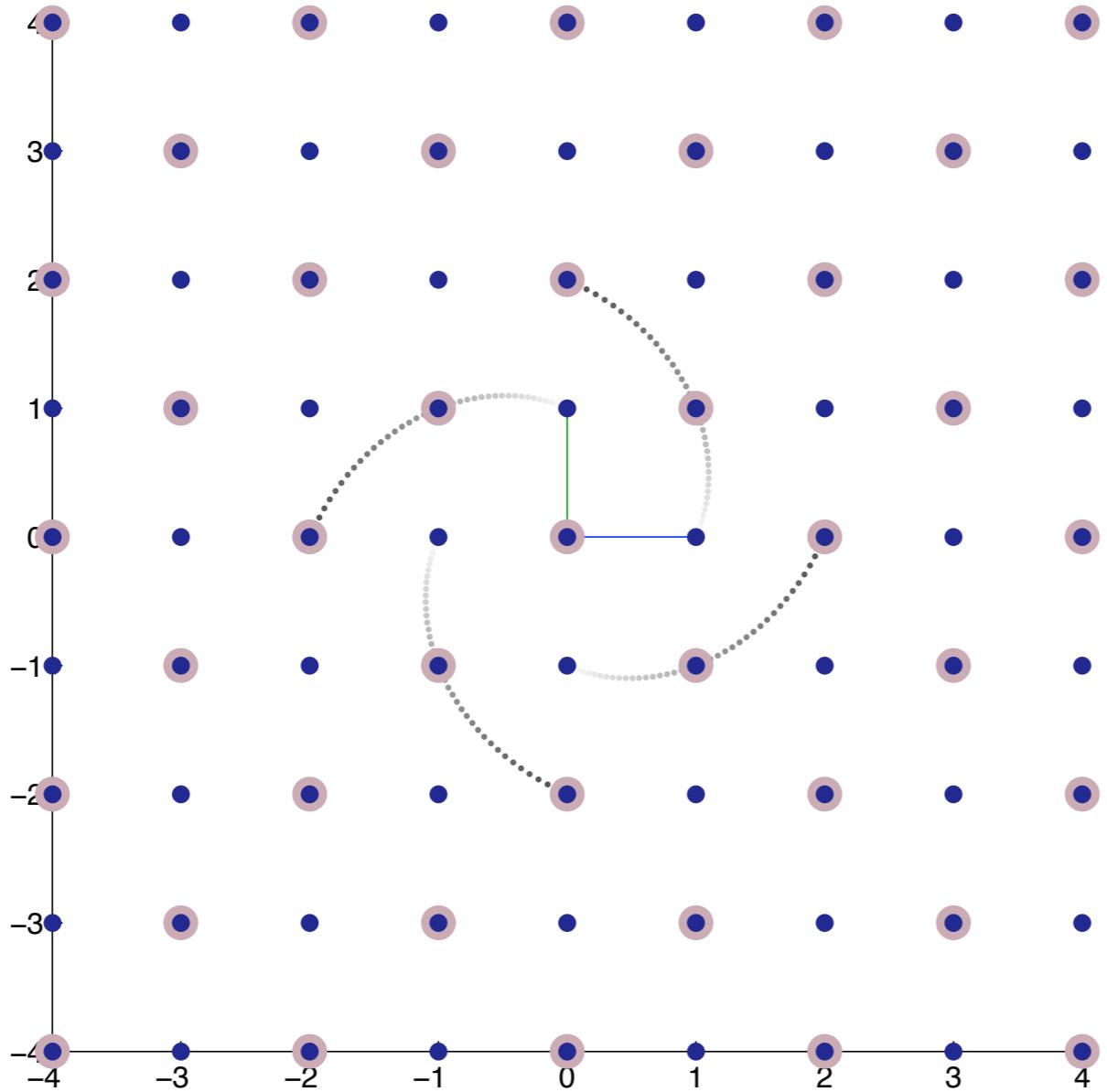
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quincunx subsampling



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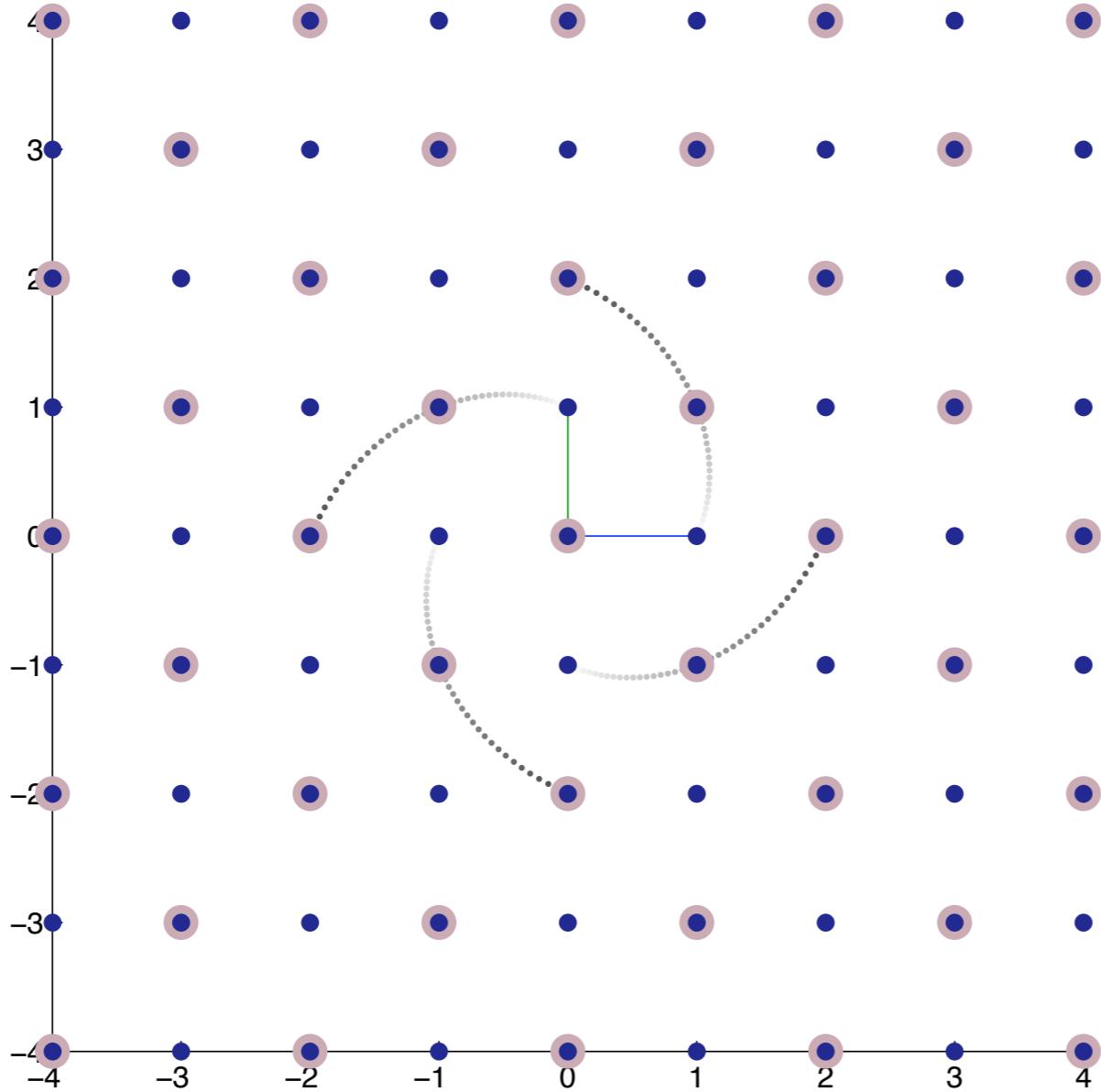
fractional subsampling

\mathbf{RK}^s for $s = 0..2$

quincunx subsampling



$$\mathbf{R} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \mathbf{K} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \quad \det \mathbf{K} = 2$$



fractional subsampling

\mathbf{RK}^s for $s = 0..2$

acts like a scaled
rotation \mathbf{QR}

with $\mathbf{Q}^T \mathbf{Q} = \alpha^2 \mathbf{I}$

quincunx subsampling



Construction

Similarity of Q and K

$$QR = RK \text{ with } Q^T Q = \alpha^2 I$$



Similarity of Q and K

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$$R^{-1} QR = K$$



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and thus agree in eigenvalues and determinant.



Diagonalizing rotation Q

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ j & -j \end{bmatrix} \begin{bmatrix} e^{j\theta} & 0 \\ 0 & e^{-j\theta} \end{bmatrix} \begin{bmatrix} 1 & j \\ 1 & -j \end{bmatrix}$$
$$= \mathbf{J}_2^{-1} \Delta \mathbf{J}_2$$



Diagonalizing rotation Q

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ j & -j \end{bmatrix} \begin{bmatrix} e^{j\theta} & 0 \\ 0 & e^{-j\theta} \end{bmatrix} \begin{bmatrix} 1 & j \\ 1 & -j \end{bmatrix}$$
$$= \mathbf{J}_2^{-1} \Delta \mathbf{J}_2$$

Different eigenvalue structure for even and odd dimensionality

$$\Delta = \begin{bmatrix} e^{j\theta_1} & & & \\ & e^{-j\theta_1} & & \\ & & e^{j\theta_2} & \\ & & & e^{-j\theta_2} \\ & & & \ddots \end{bmatrix} \quad \Delta = \begin{bmatrix} 1 & & & \\ & e^{j\theta_1} & & \\ & & e^{-j\theta_1} & \\ & & & \ddots \end{bmatrix}$$

With analogue block-wise construction of \mathbf{J}_n

Diagonalizing rotation Q

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ j & -j \end{bmatrix} \begin{bmatrix} e^{j\theta} & 0 \\ 0 & e^{-j\theta} \end{bmatrix} \begin{bmatrix} 1 & j \\ 1 & -j \end{bmatrix}$$
$$= \mathbf{J}_2^{-1} \Delta \mathbf{J}_2$$

Different eigenvalue structure for even and odd dimensionality restricts characteristic polynomial:

- n even: $d(\lambda) = \lambda^n + C\lambda^{\frac{n}{2}} + \alpha^n$ with $C^2 < 4\alpha^n$
- n odd: $d(\lambda) = \lambda^n - \alpha^n$



Finding suitable K



Finding suitable K

- Fulfill conditions implied by $QR = RK$



Finding suitable K

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- Exhaustive search over range of $K \in \mathbb{Z}^{n \times n}$



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- Companion matrix $K = \begin{bmatrix} 0 & & & -c_0 \\ 1 & 0 & & -c_1 \\ & 1 & 0 & \vdots \\ & \ddots & \ddots & -c_{n-2} \\ & & 1 & -c_{n-1} \end{bmatrix}$



Finding suitable K

- Fulfill conditions implied by $QR = RK$
- Exhaustive search over range of $K \in \mathbb{Z}^{n \times n}$

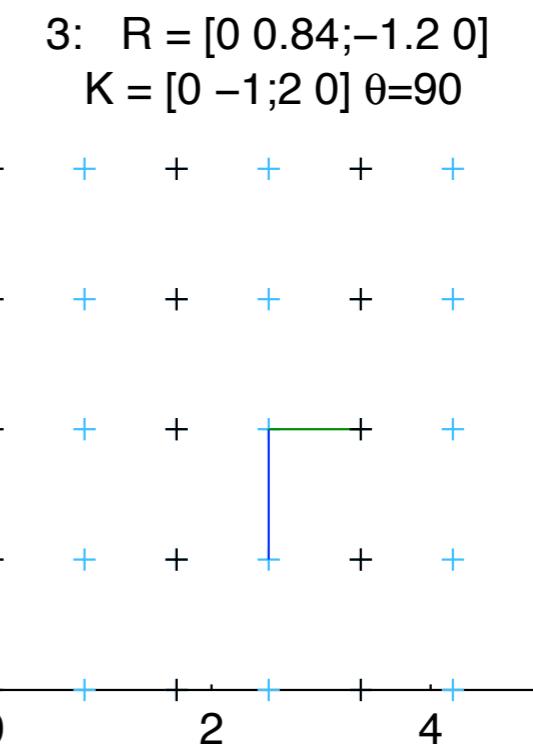
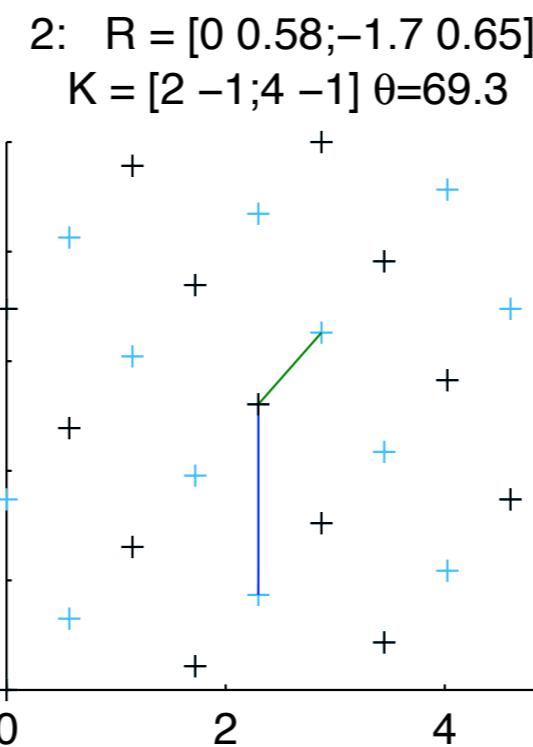
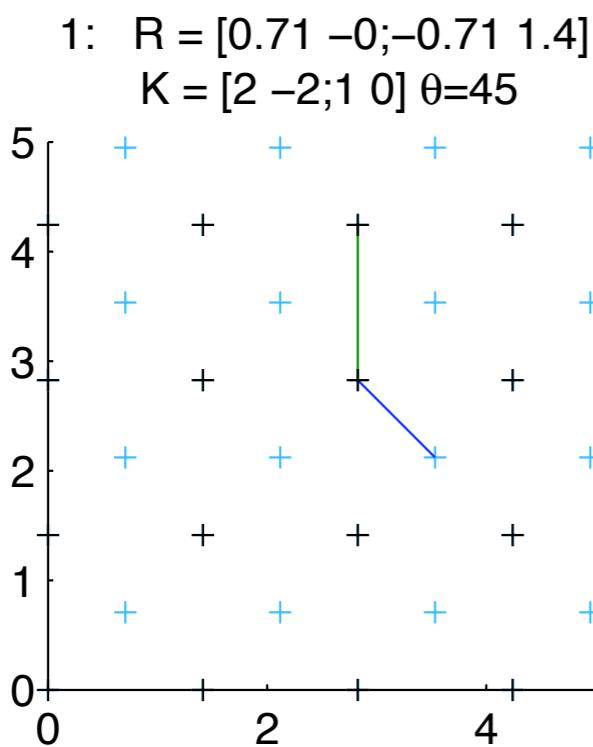
- Companion matrix $K = \begin{bmatrix} 0 & & & -c_0 \\ 1 & 0 & & -c_1 \\ & 1 & 0 & \vdots \\ & \ddots & \ddots & -c_{n-2} \\ & & 1 & -c_{n-1} \end{bmatrix}$
- More with *unimodular similarity transforms*

$$K_T = T^{-1}KT \text{ with } \det T = 1 \text{ and } T \in \mathbb{Z}^{n \times n}$$



Results

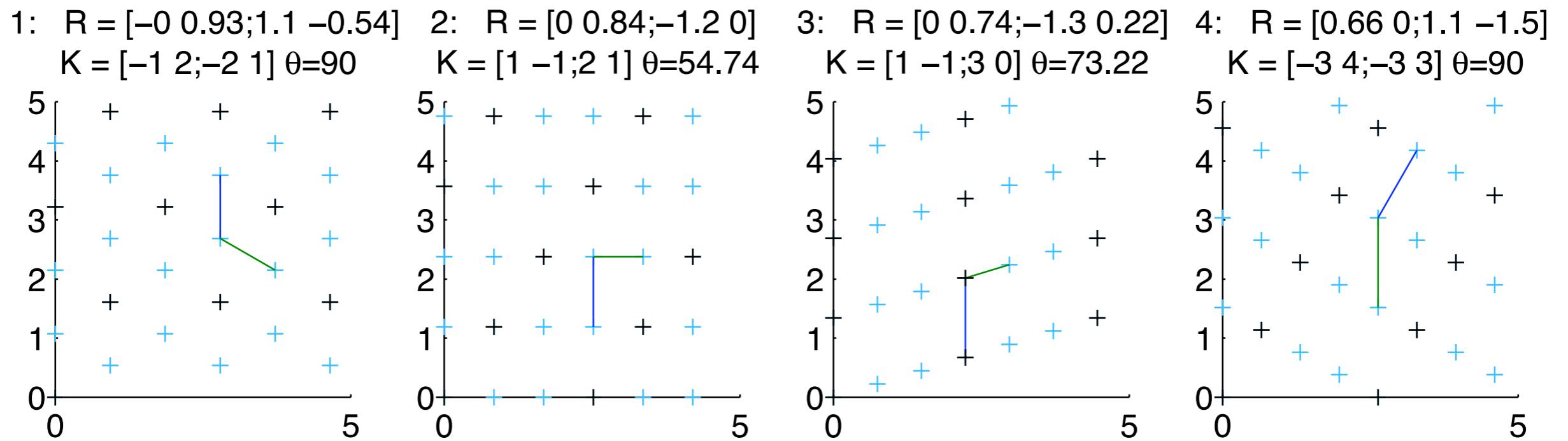
2D



Dilation factor $|\det K| = 2$



2D



Dilation factor $|\det K| = 3$



Rotational grid summary

- First time low-rate admissible dilation matrices are available for $n > 2$
- Additional degrees of freedom in the design enable further optimization
- Current results allow optimized constructions up to $n = 9$



Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
- Theoretical analysis: Sampling in volume rendering
- Filling a region: Lattices with rotational dilation
- Summary and conclusion



Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
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Data taxonomy

- *primary*: field measurements
- *secondary*: synthetic data or human input
- *tertiary*: rules provided by theoretical study or statistical inference



Model adjustment at different levels

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
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Model adjustment at different levels

User input

- User-driven experimentation: Use cases for *paraglide*
- Criteria optimization: Lighting design
- Theoretical analysis: Sampling in volume rendering
- Filling a region: Lattices with rotational dilation

Theoretical input



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Thank you! Questions?

