Steven Carr

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Postdoctoral researcher at the Oden Institute for Computational Engineering and Sciences within the University of Texas at Austin. My research focus is on the intersection of control and learning in autonomous systems. Looking for exciting opportunities in how to apply emerging artificial intelligence research to ensured decision-making for autonomous systems.

Education

The University of Texas at Austin

2016 - 2022

Doctor of Philosophy (Aerospace Engineering) - Task-Aware Planning and Learning in Partially Observable Environments Subject Areas: Autonomous Systems, Artificial Intelligence, Robotics, Formal Methods, Reinforcement Learning Master of Science Engineering (Aerospace Engineering) | Coursework: Convex Optimization, Game Theory, Optimal Control

The University of Sydney

2010 - 2014

Bachelor of Engineering (Aeronautical Space)/ Bachelor of Science (Advanced Mathematics/Physics) Honours I Coursework: Aircraft Systems, Aircraft Design, Astrophysics, Mathematics (Advanced) | Graduated with Distinction

Recent Academic Papers

Safe Reinforcement Learning via Shielding for POMDPs. arXiv preprint arXiv:2204.00755

Task-aware Verifiable RNN-based Policies for Partially Observable Markov Decision Processes. JAIR 72: 819-847.

Decentralized Classification with Assume-Guarantee Planning. Intelligent Robots and Systems (IROS).

Safe Policies for Factored Partially Observable Stochastic Games. Robotics: Science and Systems (RSS).

2021

Professional Experience

Oden Institute for Computational Engineering and Sciences - Postdoctoral Fellow

2022-2023

- Coordinated research teams on emerging applications in autonomy with an emphasis on assured reinforcement learning.
- ♦ Collaborated and consulted with technical experts from academia, industry and government including NASA and DARPA.

The University of Texas at Austin - *Graduate Research Assistant*

2016-2022

- Published and presented academic research papers on topics in machine learning, controls and robotics.
- Validated theoretical results on hardware and high fidelity simulation using Python and Robotic Operating System (ROS).

Skygrid - Applied Research Intern

2018

- Designed and implemented an information sharing algorithm for a team of UAV agents to provably converge to a consensus.
- ⋄ Modified a D* algorithm to build a scalable multi-agent path planning solution for air traffic management.

The University of Texas at Austin - Teaching Assistant for ASE 361K/361L Aircraft Design I/II

2016-2018

- ♦ Taught a systems engineering-based approach for designing, building, flight testing a UAV to meet mission requirements.
 ♦ Lectured undergraduate students on UAV control systems and implementing a ground control autopilot using Ardunilot.
- ♦ Lectured undergraduate students on UAV control systems and implementing a ground control/autopilot using Ardupilot Mission Planner with specific instruction on tuning for hardware-in-the-loop controllers.

Department of Defence (Australia) - Technology Analyst

2015-2016

- Utilized engineering, physics and mathematical skills to create technical assessments for government decision-makers.
- Collaborated with Five Eyes Defense partners to produce concept documents for future defense capabilities.

Australian Centre for Field Robotics (ACFR) - Optimization Researcher

2014-2015

- Explored path planning for multiple robotic agents in a stochastic environment, using optimization methods.
- Participated in a team environment to develop a simulation process for UAVs using Python.

Silicon Controls - Systems Engineer (2013-2014) and Hardware Tester (2011-2013)

2011-2014

- Applied Bayesian statistics principles to extract significant information from large data sets using SQL.
- Implemented a new field operation for faulty units based upon the company framework.

Skills & Interests

Technical SkillsSoftware Libraries
Have used before
Personal Interests
Python, C++, Tensorflow, Excel, LaTeX, Robotic Operating System (ROS), Carla Simulator, Unity
Formal Methods (PRISM, storm) | Learning (Pytorch, OpenAl Gym) | Optimization (Gurobi, CVX)
Node.js. JavaScript, FORTRAN95, Solidworks CAD, Altium, SQL, Mission Planner
Basketball, Soccer, Tennis, Travel.

References

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