Steven Carr

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|---|---|---|
| Austin. My research | al intelligence researcher at the Oden Institute for Computational Engineering and Science focus is on the intersection of reinforcement learning and formal methods for autonomous systrunities in providing assurances for emerging artificial intelligence research for decision-mak | tems. Look- |
| Education | | |
| Subject Areas: Auto Master of Science E The University of Bachelor of Enginee | y (Aerospace Engineering) - Task-Aware Planning and Learning in Partially Observable Env nomous Systems, Artificial Intelligence, Robotics, Formal Methods, Reinforcement Learning ingineering (Aerospace Engineering) Coursework: Machine Learning, Game Theory, Optim | g al Control 010 – 2014 <i>I</i> |
| | | |
| Safe Reinforcement Dynamic Certification Task-aware Verifiabl Decentralized Classi | Learning via Shielding for POMDPs. AAAI 2023 on for Autonomous Systems e RNN-based Policies for Partially Observable Markov Decision Processes. JAIR 72: 819-84 fication with Assume-Guarantee Planning. Intelligent Robots and Systems (IROS). etored Partially Observable Stochastic Games. Robotics: Science and Systems (RSS). | 2023 2022 47. 2021 2021 2021 |
| Professional Ex | nerience | |
| Oden Institute for Coordinated reseat Researched mode Mutli Al - Artificial | Computational Engineering and Sciences - Postdoctoral Fellow arch teams on emerging applications in autonomy with an emphasis on assured reinforceme I-based improvements to ensuring safety while learning in policy gradient methods (PPO, Stantelligence Research Consultant models and crafted solutions (using constrained MCTS) for autonomous decision-making with | AC). 2022-2023 |
| The University of | Texas at Austin - Graduate Research Assistant esented numerous academic research papers on topics in machine learning, controls and robe learning libraries (Tensorflow and PyTorch) to formally verify an agent controlled by an R | 2016-2022 ootics. |
| | Research Intern lemented an information sharing algorithm for a team of UAV agents to provably converge to gorithm to build a scalable multi-agent path planning solution for air traffic management. | 2018 a consensus. |
| ♦ Taught a systems♦ Lectured undergrade | Texas at Austin - Teaching Assistant for ASE 361K/361L Aircraft Design I/II engineering-based approach for designing, building, flight testing a UAV to meet mission readuate students on UAV control systems and implementing a ground control/autopilot using vith specific instruction on tuning for hardware-in-the-loop controllers. | • |
| Utilized engineering | fence (Australia) - Technology Analyst ng, physics and mathematical skills to create technical assessments for government decision Five Eyes Defense partners to produce concept documents for future defense capabilities. | 2015-2016 n-makers. |
| Explored path pla | for Field Robotics (ACFR) - Optimization Researcher nning for multiple robotic agents in a stochastic environment, using optimization methods. team environment to develop a simulation process for UAVs using Python. | 2014-2015 |
| | Systems Engineer (2013-2014) and Hardware Tester (2011-2013) statistics principles to detect faulty units information from large data sets using SQL. | 2011-2014 |
| Skills & Interes Technical Skills Software Libraries | Python, C++, Tensorflow, PyTorch LaTeX, Robotic Operating System (ROS), TensorF Learning (OpenAI Gym, Gymnasium, JAX, Stable Baselines) Formal Methods (PRISM | |
| References Ufuk Topcu Suda Bharadwaj Nils Jansen | Professor, Department of Aerospace Engineering and Engineering Mechanics, UT Austin [utopcut] Head of Research and Development, Skygrid [sbharadwaj@skygrid.com] Associate Professor, Department of Software Science (SWS), Radboud University Nijmegen [n.jan] | - |