# Homework 3

## Shao-Ting Chiu (UIN:433002162)

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## **Homework Description**

• Course: ECEN649, Fall2022

Problems from the Book

6.3

6.5

6.7

7.1

7.10

6.12 (coding assignment)

Problems 6.3-6.5 are worth 10 points each, Problem 7.10 and the coding assignment are worth 20 points each.

## **Computational Environment**

#### Libraries

```
import numpy as np
import tensorflow as tf
import sys
```

### **V**ersions

```
print(np.__version__)
print(tf.__version__)
print (sys.version)
print(sys.executable)

1.23.4
2.10.0
3.9.12 (main, Apr 5 2022, 01:52:34)
[Clang 12.0.0 ]
/Users/stevenchiu/miniconda/bin/python
```

### Problem 6.3

Show that the decision regions produced by a neural network with k threshold sigmoids in the *first* hidden layer, no matter what nonlinearities are used in succeeding layers, are equal to the intersection of k half-spaces, i.e., the decision boundary is piecewise linear

Hint: All neurons in the first hidden layer are perceptrons and the output of the layer is a binary vector.

Let  $\bar{O}$  be the k output of first hidden layer, and there are  $2^k$  types of binary vectors  $[O_1,\dots,O_k].$ 

For each data point  $x \in \mathbb{R}^d$  where d is the feature space. the output of first layer is

$$O(x)_i = I_{q_i(x)}(x), \quad i = 1, \dots, k$$
 (1)

where  $g_i(\cdot)$  is the perceptron function of neuron i. Thus, any point x belong to one type of  $[I_{g_1(x)}(x),\ldots,I_{g_k(x)}(x)]$ . For each  $O_i$ , the space forms a half-space with  $\{x:g_i(x)>0\}$ , and there are k half space in total.

#### Problem 6.5

For the VGG16 CNN architecture:

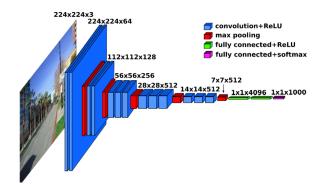


Figure 1: VGG16

(a)

Determine the number of filters used in each convolution layer.

```
Conv-1: 64 filters (pre-depth: 3)
Conv-2: 128 filters (pre-depth: 64)
Conv-3: 256 filters (pre-depth: 128)
Conv-4: 512 filters (pre-depth: 256)
Conv-5: 512 filters (pre-depth: 512)
```

#### There are total

```
rs = np.array([3, 64, 128, 256, 512])
t_filters = np.array([64, 128, 256, 512, 512])
np.sum(t_filters)
```

1472

filters.

### (b)

CONV3

Based on the fact that all filters are of size  $3 \times 3 \times r$ , where r is the depth of the previous layer, determine the total number of convolution weights in the entire network.

```
CONV1 = (3*3*3)*64 + (3*3*64)*64

CONV1

38592

CONV2 = (3*3*64)*128 + (3*3*128)*128

CONV2

221184

CONV3 = (3*3*128)*256 + (3*3*256)*256 + (3*3*256)*256
```

```
1474560
```

```
1 CONV4 = (3*3*256)*512 + (3*3*512)*512 + (3*3*512)*512
2 CONV4
5898240
 CONV5 = (3*3*512)*512 *3
2 CONV5
7077888
_{1} fc1 = 512 * 7 * 7 * 4096
_2 fc1
102760448
_{1} fc2 = 4096 * 4096
_2 fc2
16777216
_{1} fc3 = 4096 * 1000
_2 fc3
```

(c)

4096000

Add the weights used in the fully-connected layers to obtain the total number of weights used by VGG16.

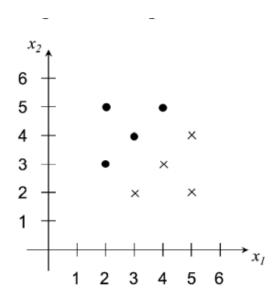
Total of weights

```
total = np.sum([CONV1, CONV2, CONV3, CONV4, CONV5, fc1, fc2, fc3])
total
```

138344128

## Problem 6.7

Consider the training data set given in the figure below.



(a)

By inspection, find the coefficients of the linear SVM hyperplane  $a_1x_1+a_2x_2+a_0=0$  and plot it. What is the value of the margin? Say as much as you can about the values of the Lagrange multipliers associated with each of the points.

The boundary passes by  $\frac{1}{2}((3,3)+(3,2))=(3,2.5)$  and  $\frac{1}{2}((3,4)+(4,3))=(3.5,3.5)$ 

- $a_1 = 2.5 3.5 = -1$
- $a_2 = 3.5 3 = 0.5$
- $a_0 = 3 \cdot 3.5 3.5 \cdot 2.5 = 1.75$
- The boundary is

$$-x_1 + 0.5x_2 + 1.75 = 0$$

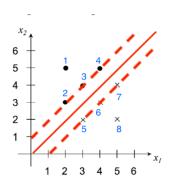


Figure 2: SVM boundry

In Figure 2, there are 6 support vectors that are  $\lambda_2$  to  $\lambda_7$ . The KKT conditions<sup>1</sup> state that

$$\lambda_i = 0 \Rightarrow y_i E_i \le 0 \tag{2}$$

$$0 < \lambda_i < C \Rightarrow y_i E_i = 0 \tag{3}$$

$$\lambda_i = C \Rightarrow y_i E_i \ge 0 \tag{4}$$

• Lagrange multipliers

$$-\lambda_1=0$$

$$-\ \lambda_2 \in (0,C)$$

$$-\lambda_3 \in (0,C)$$

$$-\ \lambda_4 \in (0,C)$$

$$-\ \lambda_5\in(0,C)$$

$$\frac{1}{2}$$
  $= \frac{1}{2}$ 

$$\begin{array}{l} -\ \lambda_6 \in (0,C) \\ -\ \lambda_7 \in (0,C) \end{array}$$

$$-\lambda_8 = 0$$

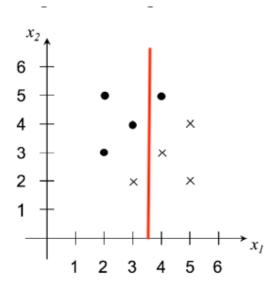
where C is the pentalty term.

(b)

Apply the CART rule, using the misclassification impurity, and stop after finding one splitting node (this is the "1R" or "stump" rule). If ther eis a tie between best splits, pick one that makes at most one error in each class. Plot this classifier as a decision boundary superimposed on the training data and also as a binary decision tree showing the splitting and leaf nodes.

where  $\bullet$  labelled as 1;  $\circ$  labelled as 0.

 $<sup>^1</sup> Intro.\ to\ SVM:\ https://article.sciencepublishinggroup.com/html/10.11648.j.acm.s.2017060401.11.html$ 



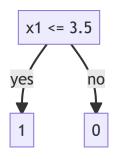


Figure 3: Decision boundary

Figure 4: Apply CART rule

(c)

How do you compare the classifiers in (a) and (b)? Which one is more likely to have a smaller classification error in this problem?

• SVM of (a) yields smaller classification error than (b) because it allow any slope of decision boundary.

## Problem 7.1

Suppose that the classification error  $\epsilon_n$  and an error estimator  $\hat{\epsilon}_n$  are jointly Gaussian, such

$$\epsilon_n \sim N(\epsilon^* + \frac{1}{n}, \frac{1}{n^2}), \hat{\epsilon}_n \sim N(\epsilon^* - \frac{1}{n}, \frac{1}{n^2}), Cov(\epsilon_n, \hat{\epsilon}_n) = \frac{1}{2n^2}$$

where  $\epsilon^*$  is the Bayes error. Find the bias, deviation variance, RMS, correlation coefficient and tail probabilities  $P(\hat{\epsilon}_n - \epsilon_n < -\tau)$  and  $P(\hat{\epsilon}_n - \epsilon_n > \tau)$  of  $\hat{\epsilon}_n$ . Is this estimator optimistically or pessimistically biased? Does performance improve as sample size increases? Is the estimator consistent?

### **Bias**

Use Eq. 7.3 (Braga-Neto 2020, 154),

$$Bias(\hat{\epsilon}_n) = E[\hat{\epsilon}_n] - E[\epsilon_n]$$

•  $E[\hat{\epsilon}_n] = \epsilon^* - \frac{1}{n}$ •  $E[\epsilon_n] = \epsilon^* + \frac{1}{n}$ 

Thus,

$$Bias(\hat{\epsilon}_n) = \frac{-2}{n} < 0$$

This estimator is optimisitcally biased.

#### **Deviation variance**

Use Eq. 7.4 (Braga-Neto 2020, 154),

$$Var_{dev}(\hat{\epsilon}_n) = Var(\hat{\epsilon}_n, \epsilon_n) = Var(\hat{\epsilon}_n) + Var(\epsilon_n) - 2Cov(\epsilon_n, \hat{\epsilon}_n)$$

- $\begin{array}{l} \bullet \ \ Var(\hat{\epsilon}_n) = \frac{1}{n^2} \\ \bullet \ \ Var(\epsilon_n) = \frac{1}{n^2} \\ \bullet \ \ Cov(\epsilon_n, \hat{\epsilon}_n) = \frac{1}{2n^2} \end{array}$

Thus,

$$Var_{dev}(\hat{\epsilon}_n) = \frac{1}{n^2} + \frac{1}{n^2} - 2\frac{1}{2n^2} = \frac{1}{n^2}$$

The deviation variance reduces as sample size increases.

#### Root mean-square error

Use Eq. 7.5 (Braga-Neto 2020, 154),

$$RMS(\hat{\epsilon}_n) = \sqrt{E[(\hat{\epsilon}_n - \epsilon_n)^2]} = \sqrt{Bias(\hat{\epsilon}_n)^2 + Var_{dev}(\hat{\epsilon}_n)}$$

Apply previous results,

$$RMS(\hat{\epsilon}_n) = \sqrt{\frac{-2}{n} + \frac{1}{n^2}}$$

#### Correlation coefficient

Use the pearson correlation coefficient<sup>2</sup>

$$\rho_{X,Y} = \frac{Cov(X,Y)}{\sigma_X \sigma_Y}$$

- $\begin{array}{ll} \bullet & Cov(\epsilon_n, \hat{\epsilon}_n) = \frac{1}{2n^2} \\ \bullet & \sigma_{\epsilon_n} = \frac{1}{n} \\ \bullet & \sigma_{\hat{\epsilon}_n} = \frac{1}{n} \end{array}$

$$\rho_{\epsilon_n,\hat{\epsilon}_n} = \frac{1}{2}$$

Correlation coefficient is a constant and independent from sample size.

### Tail probabilities

Use Eq. 7.6 (Braga-Neto 2020, 154),

$$P(|\hat{\epsilon}_n - \epsilon_n| \geq \tau) = P(\hat{\epsilon}_n - \epsilon_n \geq \tau) + P(\hat{\epsilon}_n - \epsilon_n \leq -\tau), \quad \text{for } \tau > 0$$

The normal difference distribution<sup>3</sup> of  $\hat{\epsilon}_n - \epsilon_n$ 

$$\hat{\epsilon}_n - \epsilon_n \sim N(\frac{-2}{n}, \frac{2}{n^2}) = N(\mu, \sigma^2)$$

 $<sup>{}^2</sup> Correlation\ coefficient:\ https://en.wikipedia.org/wiki/Pearson\_correlation\_coefficient$ 

 $<sup>^3</sup>$ Normal difference distribution: https://mathworld.wolfram.com/NormalDifferenceDistribution.html

That  $\Delta \epsilon_n = \hat{\epsilon}_n - \epsilon_n$ 

$$P(\Delta \epsilon_n \leq -\tau) = P(\frac{\Delta \epsilon_n - \mu}{\sigma} \leq \frac{\tau - \mu}{\sigma}) \tag{5}$$

$$=\Phi(\frac{-\tau-\mu}{\sigma})\tag{6}$$

$$=\Phi(\frac{-\tau+2/n}{2/n^2})\tag{7}$$

$$=\Phi(\frac{-n^2\tau + 2n}{2})\tag{8}$$

$$P(\Delta \epsilon_n \ge \tau) = P(\frac{\Delta \epsilon_n - \mu}{\sigma} \ge \frac{\tau - \mu}{\sigma}) \tag{9}$$

$$=1-P(\frac{\Delta\epsilon_n-\mu}{\sigma}<\frac{\tau-\mu}{\sigma})\tag{10}$$

$$= 1 - P(\frac{\Delta \epsilon_n - \mu}{\sigma} < \frac{\tau - \mu}{\sigma})$$

$$= 1 - \Phi(\frac{\tau - \mu}{\sigma})$$
(10)

$$=1-\Phi(\frac{n^2\tau+2n}{2})$$
 (12)

Thus, when  $n \to \infty$ 

$$\lim_{n\to\infty}P(\Delta\epsilon_n\leq -\tau)=1 \tag{13}$$

$$\lim_{n \to \infty} P(\Delta \epsilon_n \ge \tau) = 1 \tag{14}$$

The estimator is *consistent*.

#### Problem 7.10

This problem illustrates the very poor (even paradoxical) performance of crossvalidation with very small sample sizes. Consider the resubstitution and leave-oneout estimators  $\hat{\epsilon}_n^r$  and  $\hat{\epsilon}_n^l$  for the 3NN classification rule, with a sample of size n=4 from a mixture of two equally-likely Gaussian populations  $\Pi_0 \sim N_d(\mu_0, \Sigma)$ and  $\Pi_1 \sim N_d(\mu_1, \Sigma)$ . Assume that  $\mu_0$  and  $\mu_1$  are far enough apart to make  $\delta = \sqrt{(\mu_1 - \mu_0)^T \Sigma^{-1} (\mu_1 = \mu_0)} \gg 0$  (in which case the Bayes error is  $\epsilon_{\rm bay} = 0$ )  $\Phi(-\frac{\delta}{2}) \approx 0$ ).

(a)

For a sample  $S_n$  with  $N_0=N_1=2$ , which occurs  $P(N_0=2)={4\choose 2}2^{-4}=37.5\%$  of the time, show that  $\epsilon_n\approx 0$  but  $\hat{\epsilon}_n^l=1$ 

(b)

Show that  $E[\epsilon_n] \approx \frac{5}{16} = 0.3125$ , but  $E[\hat{\epsilon}_n^l] = 0.5$ , so that  $\text{Bias}(\hat{\epsilon}_n^l) \approx \frac{3}{16} = 0.1875$ , and the leave-one-out estimator is far from unbiased.

(c)

Show that  $Var_d(\hat{\epsilon}_n^l) \approx \frac{103}{256} \approx 0.402$ , which corresponds to a standard deviation of  $\sqrt{0.402} = 0.634$ . The leave-one-out estimator is therefore highly-biased and highly-variable in this case.

(d)

Consider the correlation coefficient of an error estimator  $\hat{\epsilon}_n$  with the true error  $\epsilon_n$ :

$$\rho(\epsilon_n, \hat{\epsilon}_n) = \frac{Cov(\epsilon_n, \hat{\epsilon}_n)}{Std(\epsilon_n)Std(\hat{\epsilon}_n)}$$

Show that  $\rho(\epsilon_n, \hat{\epsilon}_n^l \approx 0.98)$ , i.e., the leave-one-out estimator is almost perfectly negatively correlated with the true error.

(e)

For comparison, show that, although  $E[\hat{\epsilon}_n^r] = \frac{1}{8} = 0.125$ , so that  $\mathrm{Bias}(\hat{\epsilon}_n^r) \approx \frac{-3}{16} = -0.1875$ , which is exactly the negative of the bias of leave-one-out, we have  $Var_d(\hat{\epsilon}_n^r) \approx \frac{7}{256} \approx 0.027$ , for a standard deviation of  $\frac{\sqrt{7}}{16} \approx 0.165$ , which is several times smaller than the leave-one-out variance, and  $\rho(\epsilon_n, \hat{\epsilon}_n^r) \approx \sqrt{\frac{3}{5}} \approx 0.775$ , showing that the resubstitution estimator is highly positively correlated with the true error.

#### References

Braga-Neto, Ulisses. 2020. Fundamentals of Pattern Recognition and Machine Learning. Springer.