Homework 1

Shao-Ting Chiu (UIN:433002162)

9/20/22

Homework Description

Course: ECEN649, Fall2022

Problems (from Chapter 2 in the book): 2.1 , 2.3 (a,b), 2.4, 2.7, 2.9, 2.17 (a,b)

Note: the book is available electronically on the Evans library website.

- Deadline: `Sept. 26th, 11:59 pm`

Computational Enviromnent Setup

Third-party libraries

```
%matplotlib inline
import sys # system information
import matplotlib # plotting
import scipy # scientific computing
import pandas as pd # data managing
import numpy as np # numerical comuptation
import matplotlib.pyplot as plt
from numpy.linalg import inv, det
# Matplotlib setting
plt.rcParams['text.usetex'] = True
matplotlib.rcParams['figure.dpi']= 300
```

Version

```
print(sys.version)
print(matplotlib.__version__)
print(scipy.__version__)
print(np.__version__)
print(pd.__version__)
```

```
3.8.12 (default, Oct 22 2021, 18:39:35)
[Clang 13.0.0 (clang-1300.0.29.3)]
3.3.1
1.5.2
1.19.1
1.1.1
```

Problem 2.1

Suppose that X is a discrete feature vector, with distribution concentrated over a countable set $D = \{x^1, x^2, \dots\}$ in R^d. Derive the discrete versions of (2.3), (2.4), (2.8), (2.9), (2.11), (2.30), (2.34), and (2.36)

Hint: Note that if X has a discrete distribution, then integration becomes summation, $P(X = x_k)$, for $x_k \in D$, play the role of $p(x)$, and $P(X = x_k | Y = y)$, for $x_k \in D$, play the role of $p(x|Y = y)$, for $y = 0, 1$.

(2.3)

From Braga-Neto (2020, 16)

$$P(X \in E, Y = 0) = \int_E P(Y = 0)p(x|Y = 0)dx \tag{1}$$
$$P(X \in E, Y = 1) = \int_E P(Y = 1)p(x|Y = 1)dx \tag{2}$$
$$\tag{3}$$

Let $x_k = [x_1, \dots, x_d]$ be the feature vector of X in set $D \in R^d$,

$$
\begin{align}
P(X \in D, Y = 0) &= P(X = [x_1, \dots, x_d], Y = 0) \tag{4}\\
&= \sum_{X \in D} P(Y = 0) P(X = [x_1, \dots, x_d] | Y = 0) \tag{5}\\
P(X \in D, Y = 1) &= P(X = [x_1, \dots, x_d], Y = 1) \tag{6}\\
&= \sum_{X \in D} P(Y = 1) P(X = [x_1, \dots, x_d] | Y = 1) \tag{7}\\
& \tag{8}
\end{align}
$$

(2.4)

From Braga-Neto (2020, 17)

$$
\begin{align}
P(Y = 0 | X = x_k) &= \frac{P(Y = 0) p(X = x_k | Y = 0)}{p(X = x_k)} \tag{9}\\
&= \frac{P(Y = 0) p(X = x_k | Y = 0)}{P(Y = 0) p(X = x_k | Y = 0) + P(Y = 1) p(X = x_k | Y = 1)} \tag{10}\\
& \tag{11}
\end{align}
$$

$$
\begin{align}
P(Y = 1 | X = x_k) &= \frac{P(Y = 1) p(X = x_k | Y = 1)}{p(X = x_k)} \tag{12}\\
&= \frac{P(Y = 1) p(X = x_k | Y = 1)}{P(Y = 0) p(X = x_k | Y = 0) + P(Y = 1) p(X = x_k | Y = 1)} \tag{13}\\
& \tag{14}
\end{align}
$$

(2.8)

From Braga-Neto (2020, 18)

$$
\epsilon^0[\psi] = P(\psi(X) = 1 | Y = 0) = \sum_{\{x_k | \psi(x) = 1\}} p(x_k | Y = 0)
$$

$$
\epsilon^1[\psi] = P(\psi(X) = 0 | Y = 1) = \sum_{\{x_k | \psi(x) = 1\}} p(x_k | Y = 1)
$$

(2.9)

From Braga-Neto (2020, 18)

$$\epsilon[\psi] = \sum_{\{x|\psi(x)=1\}} P(Y=0)p(x_k|Y=0) + \sum_{\{x|\psi=0\}} P(Y=1)p(x_k|Y=1)$$

(2.11)

From Braga-Neto (2020, 19)

$$\epsilon[\psi] = E[\epsilon[\psi|X=x_k]] = \sum_{x_k \in D} \epsilon[\psi|X=x_k]p(x_k)$$

(2.30)

From Braga-Neto (2020, 24).

$$\epsilon^* = \sum_{x\in X} \left[I_{\eta(X=x)\leq 1-\eta(X=x)}\eta(X=x) + I_{\eta(X=x)>1-\eta(X=x)(1-\eta(X=x))} \right] p(X=x)$$

(2.34)

From Braga-Neto (2020, 25).

$$\begin{aligned} \epsilon^* &= P(Y=0)\epsilon^0[\psi^*] + P(Y=1)\epsilon^1[\psi^*] && (15) \\ &= \sum_{\{x|P(Y=1)p(x|Y=1)>P(Y=0)p(x|Y=0)\}} P(Y=0)p(x|Y=0) + \sum_{\{x|P(Y=1)p(x|Y=1)\leq P(Y=0)p(x|Y=0)\}} P(Y=1)p(x && (16) \end{aligned}$$

(2.36)

Problem 2.3

This problem seeks to characterize the case $\epsilon^* = 0$.

(a)

Prove the "Zero-One Law" for perfect discrimination:

$$\epsilon^* = 0 \Leftrightarrow \eta(X) = 0 \text{ or } 1 \quad \text{with probability 1.} \tag{17}$$

The optimal Bayes classifier is defined in Braga-Neto (2020, 20). That is

$$\psi^*(x) = \arg\max_i P(Y = i|X = x) = \begin{cases} 1, & \eta(x) > \frac{1}{2} \\ 0, & \text{otherwise} \end{cases} \tag{18}$$

Part 1: $\eta(X) = 1$

$$\eta(X) = E[Y|X = x] = P(Y = 1|X = x) = 1$$

$$\because \eta(X) = 1 > \frac{1}{2} \therefore \psi^*(x) = 1$$

$$\begin{aligned} \epsilon^* &= \epsilon[\psi^*(X)|X = x] && (19) \\ &= I_{\psi^*(x)=0} P(Y = 1|X = x) + I_{\psi^*(x)=1} P(Y = 0|X = x) && (20) \\ &= \underbrace{I_{\psi^*(x)=0}}_{=0} \underbrace{\eta(X)}_{=1} + \underbrace{I_{\psi^*(x)=1}}_{=1} \underbrace{(1 - \eta(X))}_{=0} && (21) \\ &= 0 && (22) \end{aligned}$$

Part 2: $\eta(X) = 0$

Similarly,

$$\because \eta(X) = 0 \leq \frac{1}{2} \therefore \psi^*(x) = 0$$

$$\begin{aligned} \epsilon^* &= \epsilon[\psi^*(X)|X = x] && (23) \\ &= I_{\psi^*(x)=0} P(Y = 1|X = x) + I_{\psi^*(x)=1} P(Y = 0|X = x) && (24) \\ &= \underbrace{I_{\psi^*(x)=0}}_{=1} \underbrace{\eta(X)}_{=0} + \underbrace{I_{\psi^*(x)=1}}_{=0} \underbrace{(1 - \eta(X))}_{=1} && (25) \\ &= 0 && (26) \end{aligned}$$

In conclusion, both cases shows that $\epsilon^* = 0$.

(b)

Show that

$$\epsilon^* = 0 \Leftrightarrow \text{ there is a function } f \text{ s.t. } Y = f(X) \text{ with probability 1}$$

$$\eta(X) = Pr(Y=1|X=x) = \begin{cases} 1, & f(X) = 1 \\ 0, & f(X) = 0 \end{cases} \tag{27}$$

The sceneraio is same as Problem 3.7 (a).

1. Given $\eta(X) = 1$
   - $\epsilon^* = 0$
2. Given $\eta(X) = 0$
   - $\epsilon^* = 0$

$\epsilon^* = 0$ for both cases.

Problem 2.4

This problem concerns the extension to the multiple-class case of some of the concepts derived in this chapter. Let $Y \in \{0, 1, \dots, c-1\}$, where c is the number of classes, and let

$$\eta_i(x) = P(Y = i|X = x), \quad i = 0, 1, \dots, c-1,$$

for each $x \in R^d$. We need to remember that these probabilities are not indpendent, but satisfy $\eta_0(x) + \eta_1(x) + \dots + \eta_{c-1}(x) = 1$, for each $x \in R^d$, so that one of the functions is redundant. In the two-class case, this is made explicit by using a single $\eta(x)$, but using the redundant set above proves advantageous in the multiple-class case, as seen below.

Hint: you should answer the following items in sequence, using the previous answers in the solution of the following ones

(a)

Given a classifier $\psi : R^d \to \{0, 1, \dots, c-1\}$, show that its conditional error $P(\psi(X) \neq Y|X = x)$ is given by

$$P(\psi(X) \neq Y|X = x) = 1 - \sum_{i=1}^{c-1} I_{\psi(x)=i}\eta_i(x) = 1 - \eta_{\psi(x)}(x) \tag{28}$$

Use the "Law of Total Probability" (Braga-Neto 2020, sec. A.53),

$$P(\psi(X) = Y|X = x) + P(\psi(X) \neq Y|X = x) = 1 \tag{29}$$

$\therefore$ We can derive the probability of error via

$$\begin{align}
P(\psi(X) \neq Y|X = x) &= 1 - P(\psi(X) = Y|X = x) \tag{30}\\
&= 1 - \sum_{i=0}^{c-1} P(\psi(x) = i, Y = i|X = x) \tag{31}\\
&= 1 - \sum_{i=0}^{c-1} I_{\psi(x)=i} P(Y = i|X = x) \tag{32}\\
&= 1 - \sum_{i=0}^{c-1} I_{\psi(x)=i}\eta_i(x) \tag{33}
\end{align}$$

Combining together, Equation 29 implies Equation 28.

(b)

Assuming that X has a density, show that the classification error of ψ is given by

$$\epsilon = 1 - \sum_{i=0}^{c-1} \int_{\{x|\psi(x)=i\}} \eta_i(x)p(x)dx.$$

Let $\{x|\psi(x) = i\}$ be the set of $\psi(x) = i$ in X.

Use the *multiplication rule* (Braga-Neto 2020, sec. A1.3)

$$
\begin{aligned}
\epsilon &= E[\epsilon[\psi(x)|X=x]] & (34)\\
&= 1 - \int_{R^d} P(\psi(X)=Y|X=x)p(x)dx & (35)\\
&= 1 - \sum_{i=0}^{c-1}\int_{R^d} p(\psi(X)=i, Y=i|X=x)p(x)dx & (36)\\
&= 1 - \sum_{i=0}^{c-1}\int_{R^d} \underbrace{p(\psi(X)=i|X=x)}_{=1 \text{ if } \{x|\psi(x)=i\}; 0, \text{ otherwise.}} p(Y=i|X=x)p(x)dx & (37)\\
&= 1 - \sum_{i=0}^{c-1}\int_{\{x|\psi(x)=i\}} 1\cdot p(Y=i|X=x)p(x)dx & (38)\\
&= 1 - \sum_{i=0}^{c-1}\int_{\{x|\psi(x)=i\}} p(Y=i|X=x)p(x)dx & (39)
\end{aligned}
$$

(c)

Prove that the Bayes classifier is given by

$$\psi^*(x) = \arg\max_{i=0,1,\dots,c-1} \eta_i(x), \quad x \in R^d \tag{40}$$

Hint: Start by considering the difference between conditional expected errors $P(\psi(X) \neq Y|X=x) - P(\psi^*(X) \neq Y|X=x)$.

According to Braga-Neto (2020, 20), a Bayes classifier (ψ^*) is defined as

$$\psi^* = \arg\min_{\psi\in\mathcal{C}} P(\psi(X) \neq Y)$$

over the set $\mathcal{C}$ of all classifiers. We need to show that the error of any $\psi \in \mathcal{C}$ has the conditional error rate:

$$\epsilon[\psi|X=x] \geq \epsilon[\psi^*|X=x], \quad \text{for all } x \in R^d \tag{41}$$

From Equation 28, classifiers have the error rates:

$$P(\psi^*(X) \neq |X = x) = 1 - \sum_{i=1}^{c-1} I_{\psi^*(x)=i}\eta_i(x) \tag{42}$$

$$P(\psi(X) \neq |X = x) = 1 - \sum_{i=1}^{c-1} I_{\psi(x)=i}\eta_i(x) \tag{43}$$

Therefore,

$$P(\psi(X) \neq Y|X = x) - P(\psi^*(X) \neq Y|X = x) = (1 - \sum_{i=1}^{c-1} I_{\psi(x)=i}\eta_i(x)) - (1 - \sum_{i=1}^{c-1} I_{\psi^*(x)=i}\eta_i(x)) \tag{44}$$

$$= \sum_{i=1}^{c-1}(I_{\psi^*(x)=i} - I_{\psi(x)=i})\eta_i(x) \tag{45}$$

$\because$

- $I_{\psi^*(x)=i^*} = 1$ when i^* satisfies $\eta_{i^*}(x) = \max_{i=0,1,\dots,c-1} \eta(x) = \eta_{\max}(x)$
- $I_{\psi(x)=i'} = 1$ when $\psi(x) = i'$ for $i' \in 0, 1, \dots, c-1$

$\therefore$

if $i^* \neq i'$

$$P(\psi(X) \neq Y|X = x) - P(\psi^*(X) \neq Y|X = x) = (1-0)\eta_{i^*}(x) + (0-1)\eta_{i'}(x) \tag{46}$$

$$= \eta_{i^*}(x) - \eta_{i'}(x) \tag{47}$$

$$= \eta_{\max}(x) - \eta_{i'}(x) \tag{48}$$

$$\geq 0 \tag{49}$$

if $i^* = i'$

$$P(\psi(X) \neq Y|X = x) - P(\psi^*(X) \neq Y|X = x) = \eta_{i^*}(x) - \eta_{i'}(x) = 0$$

Therefore, there is no classifier $\psi \in \mathcal{C}$ can have conditional error rate lower than Bayes classifier Equation 40.

(d)

Show that the Bayes error is given by

$$\epsilon^* = 1 - E[\max_{i=0,1,\ldots,c-1} \eta_i(X)]$$

From Problem 2.4.b,

- Noted that, $\{x|\psi^*(x) = i\} = \emptyset$ if $i \neq i^*$

$$\epsilon[\psi^*] = E[\epsilon[\psi^*(x)|X = x]] \tag{50}$$
$$= 1 - \sum_{i=0}^{c-1} \int_{\{x|\psi^*(x)=i\}} \eta_i(x)p(x)dx \tag{51}$$
$$= 1 - \int_{\{x|\psi^*(x)=i^*\}} \eta_{\max}(x)p(x)dx \tag{52}$$
$$= 1 - E[\eta_{\max}(x)] \tag{53}$$

(e)

Show that the maximum Bayes error possible is $1 - \frac{1}{c}$.

$$\max \epsilon[\psi^*] = 1 - \min E[\max_{i=0,1,\ldots,c-1} \eta_i(X)] \tag{54}$$

also,

given

$$\eta_1(x) = \eta_2(x) = \cdots = \eta_{c-1}(x)$$

$$\sum_{i=1}^{c-1} \eta_i(x) = 1$$

we can get that

$$\min \max \eta(X) = \frac{1}{c} \tag{55}$$

Combining Equation 54 and Equation 55 together, the maximum Bayes error is $1 - \frac{1}{c}$

Problem 2.7

Consider the following univariate Gaussian class-conditional densities:

$$p(x|Y=0) = \frac{1}{\sqrt{2\pi}}\exp(-\frac{(x-3)^2}{2})$$
$$p(x|Y=1) = \frac{1}{3\sqrt{2\pi}}\exp(-\frac{(x-4)^2}{18})$$

Assume that the classes are equally likely, i.e., $P(Y=0) = P(Y=1) = \frac{1}{2}$

(a)

Draw the densities and determine the Bayes classifier graphically.

(b)

Determine the Bayes classifier.

(c)

Determine the specificity and sensitivity of the Bayes classifier.

Hint: use the standard Gaussian CDF $\psi(x)$

Table 1: The definition of sensitivity and specificity from Braga-Neto (2020, 18)

Sensitivity	Specificity
$1-\epsilon^1[\psi]$	$1-\epsilon^0[\psi]$

(d)

Determine the overall Bayes error.

Problem 2.9

Obtain the optimal decision boundary in the Gaussian model with $P(Y=0) = P(Y=1)$ and

In each case draw the optimal decision boundary, along with the class means and class conditional density contours, indicating the 0- and 1-decision regions.

Since $\Sigma_0 \neq \Sigma_1$ happens in the following subproblems, these are *heteroskedastic cases*. As mentioned in Braga-Neto (2020, sec. 2.5.2). The Bayes classifier is

$$\psi^*_Q(x) = \begin{cases} 1, x^T A x + b^T x + c > 0 \\ 0, \text{ otherwise} \end{cases} \tag{56}$$

where

$$A = \frac{1}{2}(\Sigma_0^{-1} - \Sigma_1^{-1}) \tag{57}$$

$$b = \Sigma_1^{-1}\mu_1 - \Sigma_0^{-1}\mu_0 \tag{58}$$

$$c = \frac{1}{2}(\mu_0^T \Sigma_0^{-1}\mu_0 - \mu_1^T \Sigma_1^{-1}\mu_1) + \frac{1}{2}\ln\frac{\det(\Sigma_0)}{\det(\Sigma_1)} + \ln\frac{P(Y=1)}{P(Y=0)} \tag{59}$$

The following is the Python implementation with NumPy[1].

```
def compose(U,D):
    return U.transpose()@inv(D)@U

def mA(sigma0, sigma1):
    sigma0_inv = inv(sigma0)
    sigma1_inv = inv(sigma1)
    return 0.5*(sigma0_inv - sigma1_inv)

def mb(sigma0, sigma1, mu0, mu1):
    sigma0_inv = inv(sigma0)
    sigma1_inv = inv(sigma1)
    return sigma1_inv@mu1 - sigma0_inv@mu0

def mc(sigma0, sigma1, mu0, mu1, Py):
    return  0.5*(compose(mu0, sigma0) - compose(mu1, sigma1)) +\
        0.5*np.log(det(sigma0)/det(sigma1)) +\
            np.log(Py/(1-Py))

def BayesBound(x, sigma0, sigma1, mu0, mu1, Py):
    xax = x.transpose() @ mA(sigma0, sigma1)@x
```

[1] There is a well-written documentation for matrix operation: https://numpy.org/doc/stable/user/absolute_beginners.html#creatin matrices

```python
    bx = mb(sigma0, sigma1, mu0, mu1).transpose() @ x
    c = mc(sigma0, sigma1, mu0, mu1, Py)

    return float(xax + bx + c)

class GaussianBayesClassifier:
    def __init__(self, sigma0, sigma1, mu0, mu1, Py):
        self.sigma0 = sigma0
        self.sigma1 = sigma1
        self.mu0 = mu0
        self.mu1 = mu1
        self.Py = Py

        # Inferred Matrix
        self.mA = mA(sigma0, sigma1)
        self.mb = mb(sigma0, sigma1, mu0, mu1)
        self.mc = mc(sigma0, sigma1, mu0, mu1, Py)

    def BayesBound(self, x):
        return BayesBound(x, self.sigma0, self.sigma1, self.mu0, self.mu1, self.Py)

    def psi(self, x):
        """
        Bayes classification
        """
        pred = 0
        if self.BayesBound(x) > 0:
            pred = 1
        return pred

    def plot2D(self, psi_annotates=[[0.3,0.3], [0.7,0.7]]):
        fig, ax = plt.subplots()

        xlist = np.linspace(-3.5,3.5,30)
        ylist = np.linspace(-3.5,3.5,30)
        X, Y = np.meshgrid(xlist, ylist)
        Z = np.zeros(X.shape)
        for i in range(0, Z.shape[0]):
            for j in range(0, Z.shape[1]):
                x = np.matrix([X[i,j], Y[i,j]]).T
                Z[i,j] = self.psi(x)
```

```
        cmap = plt.get_cmap('Set1', 2)
        CS = ax.contour(X,Y,Z, cmap=cmap, levels=[0.9])
        ax.plot(self.mu0[0,0], self.mu0[1,0], marker="o", color="k",label="$\mu_0$")
        ax.plot(self.mu1[0,0], self.mu1[1,0], marker="o", color="gray",label="$\mu_1$")
        if psi_annotates==None:
            psi_annotates = [[self.mu0[0,0], self.mu0[1,0]],[self.mu1[0,0], self.mu1[1,0]]

        for ann in psi_annotates:
            i = X[int(X.shape[0]*ann[0]), int(X.shape[1]*ann[1])]
            j = Y[int(Y.shape[0]*ann[0]), int(Y.shape[1]*ann[1])]
            x = np.matrix([i, j]).T
            if self.psi(x) > 0:
                ax.annotate("$\psi^{*}(x) = 1$", (i, j))
            else:
                ax.annotate("$\psi^{*}(x) = 0$", (i, j))

        ax.set_xlabel("x")
        ax.set_ylabel("y")
        ax.legend()
```

(a)

$$\mu_0 = (0,0)^T, \mu_1 = (2,0)^T, \Sigma_0 = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}, \Sigma_1 = \begin{pmatrix} 2 & 0 \\ 0 & 4 \end{pmatrix}$$

```
bc = GaussianBayesClassifier(np.matrix([[2,0],[0,1]]),\
                             np.matrix([[2,0],[0,4]]),\
                             np.matrix([0,0]).T,\
                             np.matrix([2,0]).T, 0.5)
bc.plot2D()
```

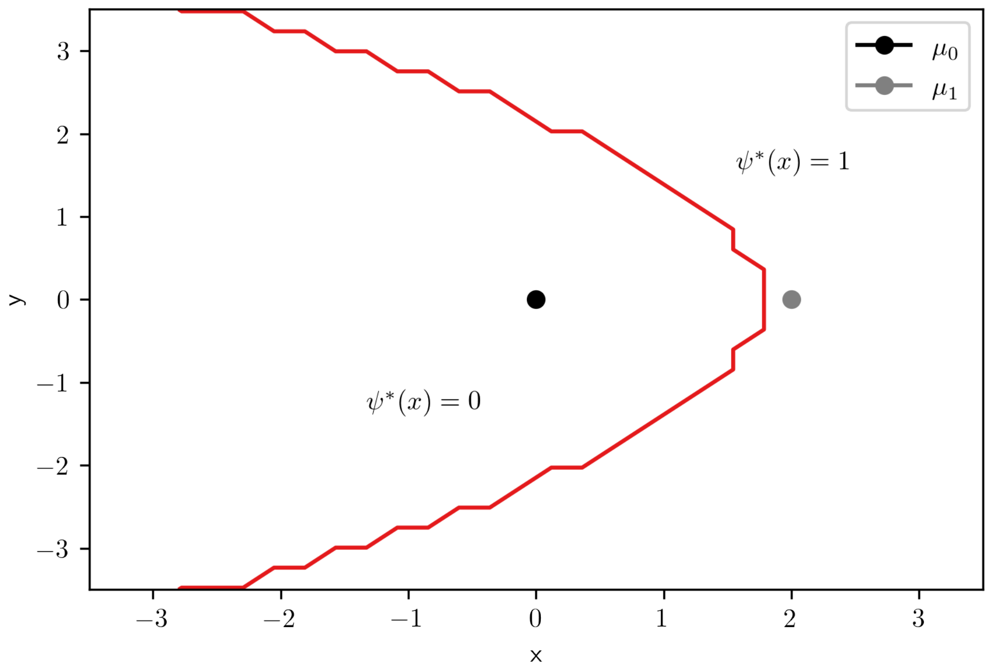

Figure 1: Bayes Classifier for 2D Gussian (a)

(b)

$$\mu_0 = (0,0)^T, \mu_1 = (2,0)^T, \Sigma_0 = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}, \Sigma_1 = \begin{pmatrix} 4 & 0 \\ 0 & 1 \end{pmatrix}$$

```
bc = GaussianBayesClassifier(np.matrix([[2,0],[0,1]]),\
                             np.matrix([[4,0],[0,1]]),\
                             np.matrix([0,0]).T,np.matrix([2,0]).T,\
                             0.5)
bc.plot2D()
```

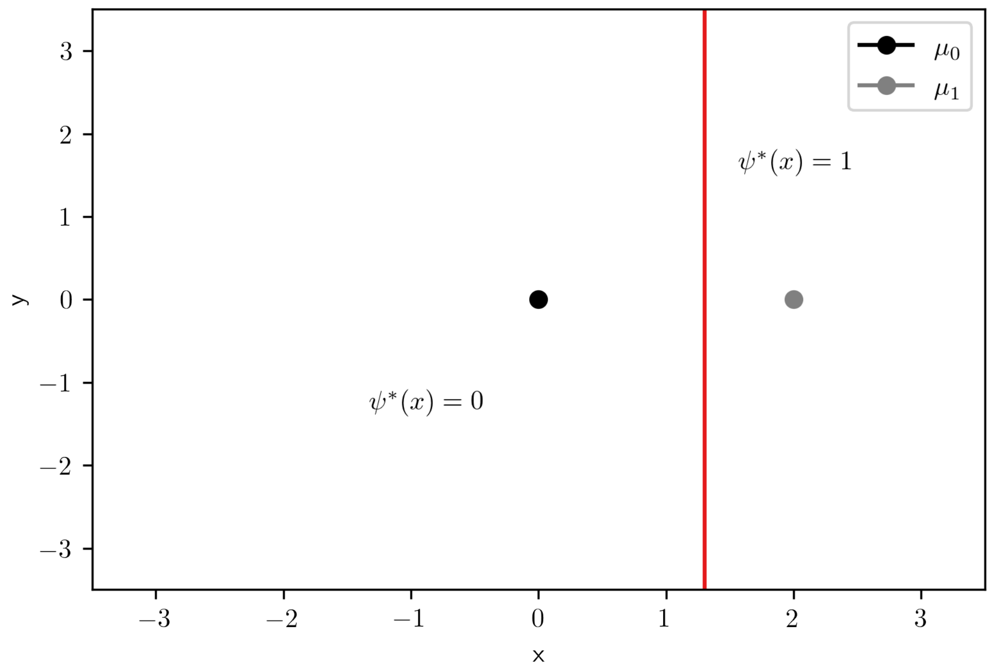

Figure 2: Bayes Classifier for 2D Gussian (b)

(c)

$$\mu_0 = (0,0)^T, \mu_1 = (0,0)^T, \Sigma_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \Sigma_1 = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$$

```
bc = GaussianBayesClassifier(np.matrix([[1,0],[0,1]]),\
                             np.matrix([[2,0],[0,2]]),\
                             np.matrix([0,0]).T,\
                             np.matrix([0,0]).T,\
                             0.5)
bc.plot2D(psi_annotates= [[0.4,0.3], [0.7,0.7]])
```

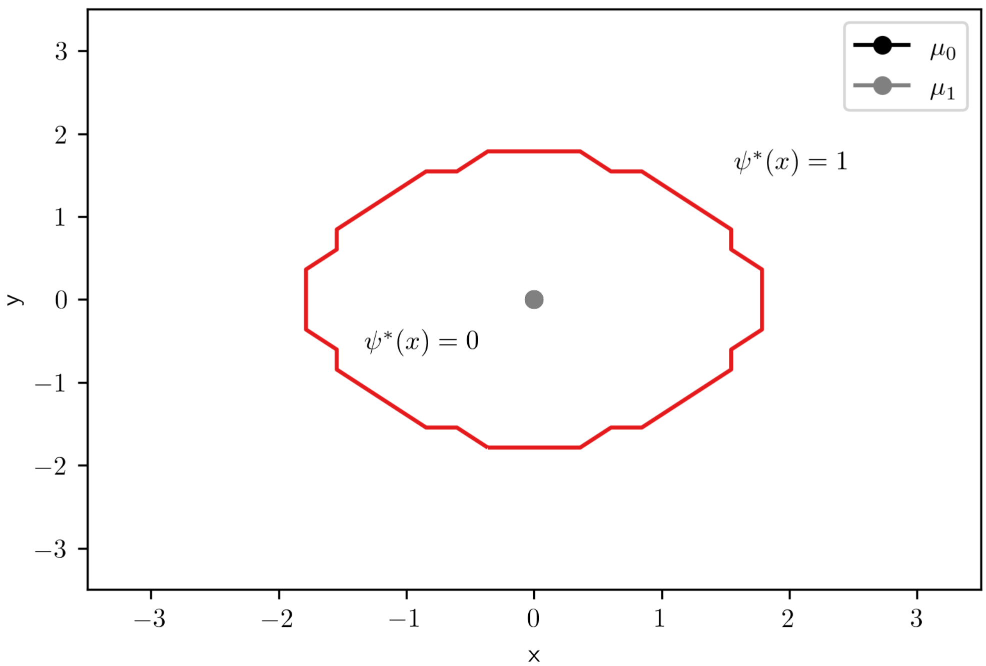

Figure 3: Bayes Classifier for 2D Gussian (c)

(d)

$$\mu_0 = (0,0)^T, \mu_1 = (0,0)^T, \Sigma_0 = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}, \Sigma_1 = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$$

```
bc = GaussianBayesClassifier(np.matrix([[2,0],[0,1]]),\
                             np.matrix([[1,0],[0,2]]),\
                             np.matrix([0,0]).T,\
                             np.matrix([0,0]).T,\
                             0.5)
bc.plot2D(psi_annotates= [[0.3,0.4], [0.6,0.7]])
```

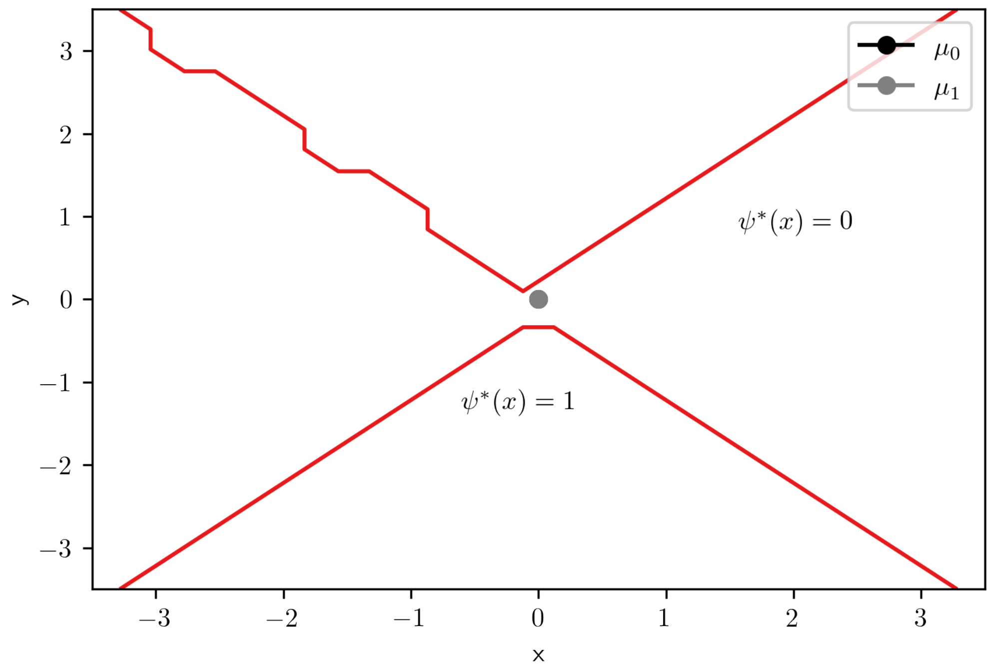

Figure 4: Bayes Classifier for 2D Gussian (d)

Python Assignment: Problem 2.17

This problem concerns the Gaussian model for synthetic data generation in Braga-Neto (2020, sec. A8.1).

(a)

Derive a general expression for the Bayes error for the homoskedastic case with $\mu_0 = (0, \dots, 0), \mu_1 = (1, \dots, 1)$, and $P(Y = 0) = P(Y = 1)$. Your answer should be in terms of $k, \sigma_1^2, \dots, \sigma_k^2, l_1, \dots, l_k$, and $\sigma_1, \dots, \sigma_k$.

Hint: Use the fact that

$$
\begin{bmatrix} 1 & \sigma & \cdots & \sigma \\ \sigma & 1 & \cdots & \sigma \\ \vdots & \vdots & \ddots & \vdots \\ \sigma & \sigma & \cdots & 1 \end{bmatrix}_{l\times l}^{-1} = \frac{1}{(1-\sigma)(1+(l-1)\sigma)} \begin{bmatrix} 1+(l-2)\sigma & -\sigma \cdots -\sigma & & \\ -\sigma & 1+(l-2)\sigma & \cdots -\sigma & \\ \vdots & \vdots & \ddots & \vdots \\ -\sigma & -\sigma & \cdots & 1+(l-2)\sigma \end{bmatrix} \tag{60}
$$

(b)

Specialize the previous formula for equal-sized blocks $l_1 = \cdots = l_k = l$ with equal correlations $\sigma_1 = \cdots = \sigma_k = \sigma$, and constant variance $\sigma_1^2 = \cdots, \sigma_k^2 = \sigma^2$. Write the resulting formula in terms of d, l, σ and σ.

i.

Using the python function `norm.cdf` in the `scipy.stats` module, plot the Bayes error as a function of $\sigma \in [0.01, 3]$ for $d = 20, l = 4$, and four different correlation values $\sigma = 0, 0.25, 0.5, 0.75$ (plot one curve for each value). Confirm that the Bayes error increasese monotonically with σ from 0 to 0.5 for each value of σ, and that Bayes error for large σ is uniformly larger than that for smaller σ. The latter fact shows that correlation between the features is detrimental to classfification.

ii.

Plot the Bayes error as a function of $d = 2, 4, 6, 8, \ldots, 40$, with fixed block size $l = 4$ and variance $\sigma^2 = 1$ and $\sigma = 0, 0.25, 0.5, 0.75$ (plot one curve for each value). Confirm that the Bayes error decreases monotonically to 0 with increasing dimensionality, with faster convergence for smaller correlation values.

iii.

Plot the Bayes error as a function of the correlation $\sigma \in [0, 1]$ for constant variance $\sigma^2 = 2$ and fixed $d = 20$ with varying block size $l = 1, 2, 4, 10$ (plot one curve for each value). Confirm that the Bayes error increases monotonically with increasing correlation. Notice that the rate of increase is particularly large near $\sigma = 0$, which shows that the Bayes error is very sensitive to correlation in the near-independent region.

References

Braga-Neto, Ulisses. 2020. *Fundamentals of Pattern Recognition and Machine Learning*. Springer.