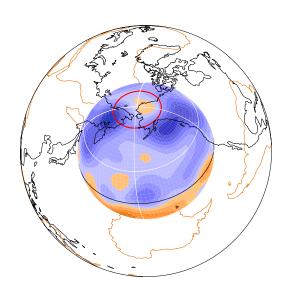
LEOPACK



kriepgrf

 $\begin{array}{c} \mathbf{K} umar \ \mathbf{R} oberts \ velocity \ \mathbf{I} nstability \ \mathbf{E} igenvalue \ \mathbf{P} roblem \\ \mathbf{G} rowth \ \mathbf{R} ate \ \mathbf{F} ind \end{array}$

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1 kriepgrf

Kumar Roberts velocity Instability Eigenvalue Problem Growth Rate Find

The majority of these notes are directly plagerised from [Sar94].

The equation describing the evolution of a magnetic field, \boldsymbol{B} , in a conducting fluid with velocity \boldsymbol{u} is derived from the pre-Maxwell equations

$$\nabla \times \boldsymbol{E} = -\frac{\partial \boldsymbol{B}}{\partial t} , \quad \nabla \times \boldsymbol{B} = \mu \boldsymbol{J} \quad \text{and} \quad \nabla \cdot \boldsymbol{B} = 0 ,$$
 (1)

and Ohm's law

$$J = \sigma(E + u \times B), \tag{2}$$

where \mathbf{E} is the electric field and σ the electrical conductivity. The pre-Maxwell forms are used since the displacement current, $\partial \mathbf{E}/\partial t$, will be negligible for the relatively slow variations appropriate for the Earth. Assuming the electrical conductivity to be a constant, taking the curl of Equation (2) and applying the relations of (1) together with the vector identity

$$\nabla \times (\nabla \times \boldsymbol{V}) = \nabla(\nabla \cdot \boldsymbol{V}) - \nabla^2 \boldsymbol{V},$$

gives the induction equation

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \frac{1}{\mu_0 \sigma} \nabla^2 \mathbf{B}.$$
 (3)

The generalised form of the induction equation, as used by the programs, is

$$c_k \frac{\partial \mathbf{B}}{\partial t} = c_m \nabla \times (\mathbf{u} \times \mathbf{B}) + c_l \nabla^2 \mathbf{B}. \tag{4}$$

We can write Equation (3) in the form

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B},\tag{5}$$

where $\eta = 1/(\mu_0 \sigma)$ is the magnetic diffusivity. If L, U, L^2/η and η^2/L^3 are respectively scales for length, velocity, time and the magnetic field strength (we are employing the diffusive time-scale) then we can write Equation (5) in the non-dimensional form

$$\frac{\partial \mathbf{B}}{\partial t} = R_m \nabla \times (\mathbf{u} \times \mathbf{B}) + \nabla^2 \mathbf{B}. \tag{6}$$

The magnetic Reynolds number, $R_m = (UL/\eta) = \mu_0 UL\sigma$, gives the ratio of the magnitude of the advective term, $\nabla \times (\boldsymbol{u} \times \boldsymbol{B})$, to the diffusive term, $\nabla^2 \boldsymbol{B}$.

The program is specific to the Kumar Roberts flow ([KR75]). $\boldsymbol{u}_{\text{\tiny KR}}$ is defined as

$$\boldsymbol{u}_{\text{KR}} = \nabla \times \nabla \times \left[P_{\text{KR}} v(r, t, \theta, \phi) \boldsymbol{r} \right] + \nabla \times \left[P_{\text{KR}} v(r, t, \theta, \phi) \boldsymbol{r} \right], \tag{7}$$

where the only non-zero radial functions for the velocity are

$${}_{\mathrm{KR}}^T v_1^{0c}(r) = \varepsilon_0 \left[r(1-r^2) + \Lambda r \right], \tag{8}$$

$${}_{KR}^{P}v_{2}^{0c}(r) = \varepsilon_{1}r^{5}(1-r^{2})^{3}, \tag{9}$$

$${}_{KR}^{P}v_2^{2s}(r) = \varepsilon_2 r^3 (1 - r^2)^2 \cos(pr)$$
(10)

and

$${}_{KR}^{P}v_2^{2c}(r) = \varepsilon_3 r^3 (1 - r^2)^2 \sin(pr). \tag{11}$$

The geometry is a sphere with outer boundary at r = 1: this means $r_i = 0$ and $r_0 = 1$.

The relative strengths of different components of the velocity are given by the parameters ε_0 , ε_1 , ε_2 and ε_3 .

The stand-alone source code version of the program is is compiled by typing

make kriepgrf

within this directory. Once the executable is created, begin execution by typing

kriepgrf < inputfile</pre>

The inputs file must have the following format.

* input file for kriepgrf *													
ez	camp	ole_	aOUTI	PUT				: ROOT					
0.0		1.0		10.0		4	20	20 : RI, RO, DRSV, NEV, NCV				CV	
*	NR	LH	ITRI	ISF	IOF	ISP	NBNO	E0	E1	E2	E3	PPAR	RM
	50	8	0	1	0	1	4	1.00	0.03	0.04	0.04	3	3860.0
	50	8	0	1	0	1	4	1.00	0.03	0.04	0.04	3	3890.0
	50	10	0	1	0	1	4	1.00	0.03	0.04	0.04	3	3860.0
	50	10	0	1	0	1	4	1.00	0.03	0.04	0.04	3	3890.0
	50	12	0	1	0	1	4	1.00	0.03	0.04	0.04	3	3860.0
	50	12	0	1	0	1	4	1.00	0.03	0.04	0.04	3	3890.0

Any line in the input file beginning with an asterisk, *, is ignored by the program and can thus be used to enter comments and notes.

The following arguments are common to all of the runs carried out by the execution:

- ROOT: First characters in output files to be generated by current run.
- RI. Inner boundary radius: essentially always set to zero.
- RO. Outer boundary radius: essentially always set to 1.0.
- DRSV. The real shift this is λ_r^s .
- NEV. The number of eigenvalues requested.
- NCV. The length of the Arnoldi factorisation. See [LSY98]) for details.

All of the (uncommented) lines which follow describe a single run and contain the following variables:

- NR. Number of radial grid nodes.
- LH. Highest spherical harmonic degree, l requested.
- ITRI. Determines whether or not triangular truncation is used. The normal truncation of spherical harmonics is to include only terms with l up to including LH. This option is selected by ITRI = 0. If ITRI = 1 then only radial functions with (l+m) up to including LH are selected.
- ISF. Symmetry selection flag. This essential selects the seed field. Due to the symmetry of the flow (equations 8 to 11) there are four distinct symmetries of magnetic field which decouple. Each is determined by a poloidal magnetic seed field with a single spherical harmonic with degree $l_{\rm Seed}$ and order $m_{\rm Seed}$. The options are:

```
ISF = 1: \rightarrow axial dipole. l_{\text{Seed}} = 1, m_{\text{Seed}} = 0.
```

ISF = 2: \rightarrow equatorial quadrupole. $l_{\text{Seed}} = 2$, $m_{\text{Seed}} = 0$.

ISF = 3: \rightarrow axial dipole. $l_{\text{Seed}} = 1$, $m_{\text{Seed}} = 1$.

ISF = 4: \rightarrow equatorial quadrupole. $l_{\text{Seed}} = 2$, $m_{\text{Seed}} = 1$.

See ([Sar94]) and ([GZ93]) for details on symmetry.

• IOF. Output file flag. Options are:

IOF = $0: \rightarrow$ no output of eigenvectors.

IOF = 1: \rightarrow only output eigenfunctions corresponding to the eigenvalue with the largest real part.

IOF = 2: \rightarrow output all eigenfunctions.

Note that for kriepgrf, options IOF = 1 and IOF = 2 only ever produce a single eigenvector.

- ISP. Radial grid node spacings flag.

 isp = 1 forces evenly spaced grid nodes from ESNAAS and isp = 2 forces

 Chebyshev zero spaced nodes from ZCPAAS.
- NBNO. Number of bounding nodes for derivatives of velocity radial functions. Limited by the integer parameter NBNOMX in the source code. Whereas, for example, David Gubbins' code uses analytic expressions for the velocity radial functions and their derivatives, this code differentiates the functions numerically. The main reason for this approach was so that the subroutines used could handle general flows, e.g. steady flows locked by thermal boundary heating. However, it also has the advantage that (once thoroughly tested) any velocity may be applied without fear of making algebraic errors in the differentiation. The clear disadvantage is that it is not exact, although NBNO may be increased arbitrarily with little detriment to the program, other than the time required to compute these derivatives. Experiment to see what effect this has. NBNO must be atleast 3.
- E0. Parameter ε_0 in Equation (8).
- E1. Parameter ε_1 in Equation (9).
- E2. Parameter ε_2 in Equation (10).
- E3. Parameter ε_3 in Equation (11).
- PPAR. p/π where p is defined in Equations (10) and (11). PPAR = 3.0 \rightarrow $p=3\pi$.
- RM1. A value for the magnetic Reynolds number which is known to be below critical.
- RM2. A value for the magnetic Reynolds number which is known to be below critical.

1.1 Subprograms required for kriepgrf

SUBS subroutines

```
fopen.f krvhmf.f esnaas.f zcpaas.f svkrvf.f kdthsr.f
svfdcf.f ontppf.f gauwts.f schnla.f matop.f vcpcc.f
rv0mfa.f amlp.f mfseps.f hmfwt.f xarrwt.f evecex.f
svfwt.f fclose.f fnamer.f radvlf.f cntric.f ldgnmf.f
```

```
gfdcfd.f shvect.f vfcp.f vf2qst.f invmft.f vicexr.f
innlca.f amdlt.f amlica.f amta.f amsdea.f vecop.f
asvta.f asvcpl.f cubeop.f dvecz.f fftrlv.f asvdr.f
matind.f bmrcop.f powtwo.f
```

SUBS double precision function

```
emmult.f pmm.f pmm1.f plm.f dpmm.f dpmm1.f
dplm.f sqrll1.f
```

SUBS integer function

indfun.f indshc.f

BLAS double precision function

dnrm2.f ddot.f dasum.f

BLAS integer function

idamax.f

BLAS subroutines

```
daxpy.f dcopy.f dgemm.f dger.f dscal.f dswap.f
dtrsm.f dgemv.f dtbsv.f dtrmm.f drot.f dtrmv.f
```

ARPACK subroutines

```
dnaupd.f dneupd.f dnaup2.f dvout.f ivout.f second.f
dstatn.f dmout.f dgetv0.f dnaitr.f dnconv.f dneigh.f
dngets.f dnapps.f dlaqrb.f dsortc.f
```

LAPACK subroutines

```
dgbtrf.f dgbtrs.f dgetrf.f dgetri.f dgbtf2.f dlaswp.f xerbla.f dlahqr.f dgeqr2.f dlacpy.f dlaset.f dorm2r.f dtrevc.f dtrsen.f dgetf2.f dtrtri.f dlabad.f dlanv2.f dlarfg.f dlarf.f dlaln2.f dlacon.f dtrexc.f dtrsyl.f dtrti2.f dlarnv.f dlascl.f dlartg.f dlassq.f dladiv.f dlaexc.f dlasy2.f dlaruv.f dlarfx.f
```

LAPACK double precision function

dlapy2.f dlamch.f dlanhs.f dlange.f

LAPACK integer function

ilaenv.f

LAPACK logical function

lsame.f

1.2 Run-time limitations

Several parameters are set at the outset which limit the physical size of the problem.

```
INTEGER NRMAX, LHMAX, NHMAX, NPHMAX, NTHMAX, KLMAX,
1
         NBNDMX, NDCS, NDRVM, ISVMAX, NPMAX, LHLH2M, NCFM,
2
         NBN, NBNOMX, NRUNM, NCFMOM, NVMAX, IVELMX, NDCSO,
3
         MAXNVI, NCVM
PARAMETER ( NRMAX = 100, LHMAX = 20, MAXNVI = 30000, NRUNM = 50,
1
             LHLH2M = LHMAX*(LHMAX+2), NBN = 2, NCVM = 25,
             NHMAX = LHLH2M/2, NPHMAX = 64, NTHMAX = LHMAX + 2,
2
3
             KLMAX = (NBN+1)*NHMAX-1, NBNDMX = 3*KLMAX+1)
PARAMETER ( NBNOMX = 5, NDCS = LHMAX + 1, NDRVM = 2,
             NCFM = 2*NBN + 1, NCFMOM = 2*NBNOMX + 1,
1
2
             ISVMAX = NRMAX*NHMAX, NVMAX = 4,
3
             IVELMX = NVMAX*NRMAX, NDCSO = 1,
4
             NPMAX = (LHMAX+1)*(LHMAX+2)/2
```

If the values are insufficient, then change them and recompile. (Note that NDRVM and NDCSO are not size dependent and should not be changed.)

- NRMAX is the maximum permitted number of radial grid nodes.
- LHMAX is the highest permitted spherical harmonic degree, l.
- MAXNVI is the maximum number of spherical harmonic interactions. These are pre-calculated and stored in an array. There is no real way of knowing how many of these will be required without simply working them out. This number is therefore rather trial and error based: it clearly increases with LH. (This is probably quite an inefficient way of calculating non-linear interactions. Anybody is welcome to think up new ways. However, since the majority of time in this program is at the linear algebra stage, this aspect of the code never seemed worth examining.)
- NRUNM is the maximum number of independent runs permitted.
- NBN is the number of bounding nodes on either side of the finite difference stencil. NBN = 2 is recommended value. Since the matrix describing the advective term couples distinct spherical harmonic radial functions (i.e. we are using the IFORMF = 3 option, the bandwidth of the matrix soon becomes very large as the number of radial functions increases. NBN = 3 therefore is a far higher computational cost than NBN = 2. (NBN = 3 is necessary for the vorticity equation, for example in linons1, because of the fourth derivatives for the poloidal velocity. However, for the induction equation, NBN = 2 gives fourth order accuracy.)

- NPHMAX is the maximum permitted number of grid nodes in ϕ for the Fast Fourier Transforms.
- NBNOMX is the upper limit for NBNO.
- NVMAX is the maximum number of velocity spherical harmonic radial functions. NVMAX = 4 is quite adequate for the Kumar and Roberts flow (which has exactly 4 spherical harmonics). This will need to be changed if this program is to be modified to deal with other flows.

1.3 Outputs from KRIEPGRF

If the filename stem "root" was specified in the input file, the file root.log will be generated, along with any output solution vectors.

For each run demanded from the input file, the following information is given in the file root.log:

```
ri:
       0.000000D+00 ro:
                            1.000000D+00 nr:
                                                  50 isp:
                                                           1 nbn0:
1h:
      8 itri: 0 Field sym: Axial_dipole
       1.000000D+00 e1:
                            3.000000D-02 e2:
                                                  4.000000D-02
e0:
       4.000000D-02 pp:
e3:
                            3.000000D+00 rm:
                                                  3.860000D+03
   4 eigenvalues converged.
eval:
        1 (
             -3.5027366D-02,
                               0.000000D+00) res:
                                                       6.3415803D-14
eval:
        2 (
             -3.5978165D+01,
                               0.000000D+00) res:
                                                       5.7301550D-11
eval:
        3 (
             -3.7009492D+01,
                              -4.2301365D+01) res:
                                                       1.6574127D-09
eval:
             -3.7009492D+01,
                               4.2301365D+01) res:
                                                       1.6574127D-09
```

This simply echos the specified parameters together with the growth rate eigenvalues and their direct residuals.

1.4 Sample runs of kriepgrf

The directory

\$LEOPACK DIR/SAMPLERUNS/KRIEPGRF

contains example input files and model output. Do not under any circumstances edit these files, as these examples should serve as a control for the correct working of the code. After compiling the program, copy the .input files to another directory, run the code and confirm that the output agrees with that in the directory.

1.4.1 Example a

With the file example_a.input, we simply calculate the same growth rate eigenvalues as we do in the input file of the same name for the program krcmrnif. Compare the output between the two files

\$LEOPACK_DIR/SAMPLERUNS/KRIEPGRF/example_aOUTPUT.log

and

\$LEOPACK_DIR/SAMPLERUNS/KRCMRNIF/example_aOUTPUT.log

References

- [GZ93] D. Gubbins and K. Zhang. Symmetry properties of the dynamo equations for paleomagnetism and geomagnetism. *Phys. Earth Planet. Inter.*, 75:225–241, 1993.
- [KR75] S. Kumar and P. H. Roberts. A three-dimensional kinematic dynamo. *Proc. Roy. Soc. Lond. A*, 344:235–258, 1975.
- [LSY98] R. B. Lehoucq, D. C. Sorensen, and C. Yang. Arpack users guide: Solution of large scale eigenvalue problems by implicitly restarted Arnoldi methods. SIAM, 1998.
- [Sar94] G. R. Sarson. *Kinematic Dynamo Calculations for Geomagnetism*. PhD thesis, University of Leeds, 1994.