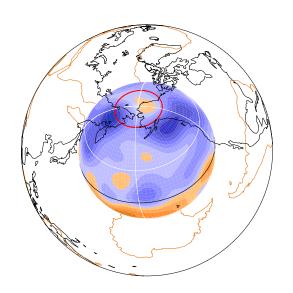
# **LEOPACK**



# krddmcmrnif

 $\begin{array}{c} \mathbf{K} \mathrm{umar} \ \mathbf{R} \mathrm{oberts} \ \mathbf{D} \mathrm{ynamo} \ (\mathbf{D}, \mathbf{M}) \ \mathbf{C} \mathrm{ritical} \ \mathbf{M} \mathrm{agnetic} \\ \mathbf{R} \mathrm{eynolds} \ \mathbf{N} \mathrm{umber} \ \mathbf{I} \mathrm{terative} \ \mathbf{F} \mathrm{ind} \end{array}$ 

Steven J. Gibbons, Oslo Original document: November  $21^{\rm st}$ , 2001. Updated: October  $30^{\rm th}$ , 2022.

## 1 krddmcmrnif

Kumar Roberts Dynamo (D,M) Critical Magnetic Reynolds Number Iterative Find

This performs essentially the same task as krcmrnif: finds a critical magnetic Reynolds number for the Kumar Roberts velocity based flow.

We concentrate on a class of flows developed from the velocity of Kumar Roberts, [KR75]. The flow is defined,

$$\boldsymbol{u} = \epsilon_0 \boldsymbol{t}_1^0 + \epsilon_1 \boldsymbol{s}_2^0 + \epsilon_2 \boldsymbol{s}_2^{2c} + \epsilon_3 \boldsymbol{s}_2^{2s},\tag{1}$$

where  $t_l^m$ ,  $s_l^m$  are toroidal and poloidal vector spherical harmonics:

$$\mathbf{t}_{l}^{m\{_{s}^{c}\}} = \nabla \times [t_{l}^{m}(r)P_{l}^{m}(\cos\theta) \begin{Bmatrix} \cos \\ \sin \end{Bmatrix} (m\phi)\mathbf{e}_{r}], \tag{2}$$

$$\mathbf{s}_{l}^{m\{c\}} = \nabla \times \nabla \times [\mathbf{s}_{l}^{m}(r)P_{l}^{m}(\cos\theta) \begin{Bmatrix} \cos \theta \\ \sin \end{Bmatrix} (m\phi)\mathbf{e}_{r}],$$
 (3)

 $(r, \theta, \phi)$  are spherical coordinates,  $P_l^m$  are Schmidt-normalised associated Legendre functions, and  $e_r$  is the unit radial vector. The scalar functions were chosen to give a u that is differentiable at the origin, and to be zero with zero stress on the outer boundary:

$$t_1^0(r) = r^2(1-r^2),$$

$$s_2^0(r) = r^6(1-r^2)^3,$$

$$s_2^{2s}(r) = r^4(1-r^2)^2\cos(p\pi r),$$

$$s_2^{2c}(r) = r^4(1-r^2)^2\sin(p\pi r).$$
(4)

Instead of using the coefficients  $\epsilon_0$ ,  $\epsilon_1$ ,  $\epsilon_2$  and  $\epsilon_3$ , as defined by [KR75], [GBGL00] set  $\epsilon_2 = \epsilon_3$  and p = 3 and defined the flow in terms of two parameters, D and M. These parameters are such that the fraction of kinetic energy in the meridian circulation ( $\mathbf{s}_2^0$ ) is given by |M|, where

$$M = \operatorname{sgn}(\epsilon_1)\beta \epsilon_1^2, \tag{5}$$

and the fraction of energy in the differential rotation  $(t_1^0)$  is given by |D|, where

$$D = \operatorname{sgn}(\epsilon_0)\alpha\epsilon_0^2. \tag{6}$$

Here, the scalars  $\alpha$ ,  $\beta$ ,  $\gamma$  and  $\delta$  are integrals of the radial functions in (4) such that

$$\int \mathbf{u}^2 dV = \alpha \epsilon_0^2 + \beta \epsilon_1^2 + \gamma \epsilon_2^2 + \delta \epsilon_3^2 = 1$$
 (7)

The fraction of kinetic energy which is in the non-axisymmetric convective rolls is given by

$$C = 1 - |M| - |D|. (8)$$

The only difference is that whereas krcmrnif uses the standard  $\epsilon$  scalings of [KR75], krddmcmrnif uses the (D, M) parametrisation of the flow as used by [GBGL00].

The stand-alone source code version of the program is compiled by typing

#### make krddmcmrnif

within this directory. Once the executable is created, begin execution by typing

#### krddmcmrnif < inputfile</pre>

The inputs file must have the following format.

* input file for krddmcmrnif *																			
example_aOUTPUT											: ROOT								
0.0					4	20	7	0.001	:	RI,	RO,	DF	RSV,	NEV,	NCV	/, NOITM,	DTOL		
* NR	LH	ITRI	ISF	IOF	ISP	NBNO		DD		D			RM1		RM2				
50	10	0	1	0	1	4	Ο.	98349148		0.00	0163	27	51	.4666	67	51.866667			
50	10	0	1	0	1	4	0.	98349148		0.00	0163	27	51	.45		51.86			
50	12	0	1	0	1	4	0.	98349148		0.00	0163	27	51	.45		51.86			
*																			

Any line in the input file beginning with an asterisk, \*, is ignored by the program and can thus be used to enter comments and notes.

The following arguments are common to all of the runs

- ROOT: First characters in output files to be generated by current run.
- RI. Inner boundary radius: essentially always set to zero.
- RO. Outer boundary radius: essentially always set to 1.0.
- DRSV. The real shift this is  $\lambda_{\rm r}^{\rm s}$
- NEV. The number of eigenvalues requested.
- NCV. The length of the Arnoldi factorisation. See [LSY98]) for details.

- NOITM: The maximum number of iterations (values for  $R_m$  tried) permitted in order to find  $R_m^c$ .
- DTOL: Stopping criterion.  $|\sigma_r|$  must be less than DTOL for convergence to have occured.

All of the (uncommented) lines which follow describe a single run and contain the following variables:

- NR. Number of radial grid nodes.
- LH. Highest spherical harmonic degree, l requested.
- ITRI. Determines whether or not triangular truncation is used. The normal truncation of spherical harmonics is to include only terms with l up to including LH. This option is selected by ITRI = 0. If ITRI = 1 then only radial functions with (l+m) up to including LH are selected.
- ISF. Symmetry selection flag. This essential selects the seed field. Due to the symmetry of the flow there are four distinct symmetries of magnetic field which decouple. Each is determined by a poloidal magnetic seed field with a single spherical harmonic with degree  $l_{\rm Seed}$  and order  $m_{\rm Seed}$ . The options are:

```
ISF = 1: \rightarrow axial dipole. l_{\text{Seed}} = 1, m_{\text{Seed}} = 0.
```

ISF = 2:  $\rightarrow$  equatorial quadrupole.  $l_{\text{Seed}} = 2$ ,  $m_{\text{Seed}} = 0$ .

ISF = 3:  $\rightarrow$  axial dipole.  $l_{\text{Seed}} = 1$ ,  $m_{\text{Seed}} = 1$ .

ISF = 4:  $\rightarrow$  equatorial quadrupole.  $l_{\text{Seed}} = 2$ ,  $m_{\text{Seed}} = 1$ .

See ([Sar94]) and ([GZ93]) for details on symmetry.

• IOF. Output file flag. Options are:

IOF = 0:  $\rightarrow$  no output of eigenvectors.

IOF = 1:  $\rightarrow$  only output eigenfunctions corresponding to the eigenvalue with the largest real part.

IOF = 2:  $\rightarrow$  output all eigenfunctions.

Note that for krcmrnif, options IOF = 1 and IOF = 2 only ever produce a single eigenvector.

- ISP. Radial grid node spacings flag.
  - isp = 1 forces evenly spaced grid nodes from ESNAAS and isp = 2 forces
    Chebyshev zero spaced nodes from ZCPAAS.
- NBNO. Number of bounding nodes for derivatives of velocity radial functions.
   Limited by the integer parameter NBNOMX in the source code. Whereas, for example, David Gubbins' code uses analytic expressions for the velocity radial functions and their derivatives, this code differentiates the functions

numerically. The main reason for this approach was so that the subroutines used could handle general flows, e.g. steady flows locked by thermal boundary heating. However, it also has the advantage that (once thoroughly tested) any velocity may be applied without fear of making algebraic errors in the differentiation. The clear disadvantage is that it is not exact, although NBNO may be increased arbitrarily with little detriment to the program, other than the time required to compute these derivatives. Experiment to see what effect this has. NBNO must be atleast 3.

- DD: Parameter D.
- DM: Parameter M.
- RM1: Sub-critical value of  $R_m$ .
- RM2: Super-critical value of  $R_m$ .

### 1.1 Subprograms required for krddmcmrnif

#### SUBS subroutines

```
fopen.f krvhmf.f esnaas.f zcpaas.f svkrvf.f kdthsr.f svfdcf.f ontppf.f gauwts.f schnla.f dm2e.f kdcmrn.f hmfwt.f xarrwt.f svfwt.f fclose.f fnamer.f radvlf.f cntric.f ldgnmf.f gfdcfd.f vcpcc.f matop.f rv0mfa.f amlp.f mfseps.f evecex.f shvect.f vfcp.f vf2qst.f invmft.f vicexr.f innlca.f amdlt.f amlica.f amta.f amsdea.f vecop.f asvta.f asvcpl.f cubeop.f dvecz.f fftrlv.f asvdr.f matind.f bmrcop.f powtwo.f
```

#### SUBS double precision function

```
emmult.f pmm.f  pmm1.f  plm.f  dpmm.f  dpmm1.f
dplm.f  sqrll1.f
```

#### SUBS integer function

indfun.f indshc.f

#### BLAS double precision function

dnrm2.f ddot.f dasum.f

#### **BLAS** integer function

idamax.f

#### **BLAS** subroutines

```
daxpy.f dgemm.f dtrsm.f dgemv.f dswap.f dcopy.f dger.f dscal.f dtbsv.f dtrmm.f drot.f dtrmv.f
```

#### ARPACK subroutines

```
dnaupd.f dneupd.f dnaup2.f dvout.f ivout.f second.f
dstatn.f dmout.f dgetv0.f dnaitr.f dnconv.f dneigh.f
dngets.f dnapps.f dlaqrb.f dsortc.f
```

#### LAPACK subroutines

```
dgetrf.f dgetri.f dgbtrf.f dgbtrs.f dgetf2.f dlaswp.f xerbla.f dtrtri.f dgbtf2.f dlahqr.f dgeqr2.f dlacpy.f dlaset.f dorm2r.f dtrevc.f dtrsen.f dtrti2.f dlabad.f dlanv2.f dlarfg.f dlarf.f dlaln2.f dlacon.f dtrexc.f dtrsyl.f dlarnv.f dlascl.f dlartg.f dlassq.f dladiv.f dlaexc.f dlasy2.f dlaruv.f dlarfx.f
```

#### LAPACK double precision function

dlapy2.f dlamch.f dlanhs.f dlange.f

#### LAPACK integer function

ilaenv.f

#### LAPACK logical function

lsame.f

#### 1.2 Run-time limitations

Several parameters are set at the outset which limit the physical size of the problem.

```
INTEGER NRMAX, LHMAX, NHMAX, NPHMAX, NTHMAX, KLMAX,

NBNDMX, NDCS, NDRVM, ISVMAX, NPMAX, LHLH2M, NCFM,

NBN, NBNOMX, NRUNM, NCFMOM, NVMAX, IVELMX, NDCSO,

MAXNVI, NCVM

PARAMETER ( NRMAX = 100, LHMAX = 20, MAXNVI = 30000, NRUNM = 50,

LHLH2M = LHMAX*(LHMAX+2), NBN = 2, NCVM = 25,

NHMAX = LHLH2M/2, NPHMAX = 64, NTHMAX = LHMAX + 2,

KLMAX = (NBN+1)*NHMAX-1, NBNDMX = 3*KLMAX+1 )

PARAMETER ( NBNOMX = 5, NDCS = LHMAX + 1, NDRVM = 2,
```

```
1 NCFM = 2*NBN + 1, NCFMOM = 2*NBNOMX + 1,
2 ISVMAX = NRMAX*NHMAX, NVMAX = 4,
3 IVELMX = NVMAX*NRMAX, NDCSO = 1,
4 NPMAX = (LHMAX+1)*(LHMAX+2)/2 )
```

If the values are insufficient, then change them and recompile. (Note that NDRVM and NDCSO are not size dependent and should not be changed.)

- NRMAX is the maximum permitted number of radial grid nodes.
- LHMAX is the highest permitted spherical harmonic degree, l.
- MAXNVI is the maximum number of spherical harmonic interactions. These are pre-calculated and stored in an array. There is no real way of knowing how many of these will be required without simply working them out. This number is therefore rather trial and error based: it clearly increases with LH. (This is probably quite an inefficient way of calculating non-linear interactions. Anybody is welcome to think up new ways. However, since the majority of time in this program is at the linear algebra stage, this aspect of the code never seemed worth examining.)
- NRUNM is the maximum number of independent runs permitted.
- NBN is the number of bounding nodes on either side of the finite difference stencil. NBN = 2 is recommended value. Since the matrix describing the advective term couples distinct spherical harmonic radial functions (i.e. we are using the IFORMF = 3 option, the bandwidth of the matrix soon becomes very large as the number of radial functions increases. NBN = 3 therefore is a far higher computational cost than NBN = 2. (NBN = 3 is necessary for the vorticity equation, for example in linons1, because of the fourth derivatives for the poloidal velocity. However, for the induction equation, NBN = 2 gives fourth order accuracy.)
- NPHMAX is the maximum permitted number of grid nodes in  $\phi$  for the Fast Fourier Transforms.
- NBNOMX is the upper limit for NBNO.
- NVMAX is the maximum number of velocity spherical harmonic radial functions. NVMAX = 4 is quite adequate for the Kumar and Roberts flow (which has exactly 4 spherical harmonics). This will need to be changed if this program is to be modified to deal with other flows.

### 1.3 Outputs from KRDDMCMRNIF

If the filename stem "root" was specified in the input file, the files root.log and root.res will be generated, along with any output solution vectors.

For each iteration of each run demanded from the input file, the following information is given in the file root.log:

```
Number of vector interactions =
Iteration 1: 4 eigenvalues converged.
Rm value =
                 51.4666670
_____
Eval 1 ( -0.0355436, 0.0000000) Res = Eval 2 ( -35.6623743, 0.0000000) Res =
                                                           0.0000000
           -35.6623743,
                                                           0.0000000
Eval 3 ( -37.6145508, -42.3467569) Res = Eval 4 ( -37.6145508, 42.3467569) Res =
                                                           0.0000000
                                                           0.0000000
Iteration 2: 4 eigenvalues converged.
Rm value = 51.8666670
Eval 1 (
           0.0230214, 0.0000000) Res = -35.6658094, 0.0000000) Res =
                                                           0.0000000
Eval 2 (
                                                          0.0000000
Eval 2 ( -35.6656094, 0.0000000) Res = Eval 3 ( -37.6436482, -42.6605030) Res = Eval 4 ( -37.6436482, 42.6605030) Res =
                                                          0.0000000
                                                           0.0000000
Iteration 3: 4 eigenvalues converged.
Rm value =
                  51.7094304
             0.0000016, 0.0000000) Res =
                                                        0.0000000
Eval 1 (
           -35.6644089, 0.0000000) Res = 
-37.6321748, -42.5371073) Res = 
-37.6321748, 42.5371073) Res =
Eval 2 (
                                                          0.0000000
Eval 3 (
                                                          0.0000000
                                                        0.0000000
Eval 4 (
RM= 5.1709430D+01 Real= 1.5642527D-06 Imag= 0.0000000D+00
     0.0000000D+00 ro: 1.0000000D+00 nr: 50 isp: 1 nbn0: 4
ri:
lh: 10 itri: 0 Field sym: Axial_dipole
e0:
     7.4999974D+01 e1: 2.2500067D+00 e2:
                                                  3.000000D+00
      3.0000000D+00 pp: 3.000000D+00 rmc: 5.1709430D+01
e3:
       0.000000D+00
```

This simply returns a summary of eigenvalues, their direct residuals and parameter specifications (in terms of the  $\epsilon$  parameters, rather than D and M).

The file root.res produces one line of summary for each line of the input file:

```
D= 9.8349148D-01 M= 1.6327000D-04 R= 5.1706213D+01 O= 0.000000D+00
```

## 1.4 Sample runs of krddmcmrnif

The directory

#### \$LEOPACK\_DIR/SAMPLERUNS/KRDDMCMRNIF

contains example input files and model output. Do not under any circumstances edit these files, as these examples should serve as a control for the correct working of the code. After compiling the program, copy the .input files to another directory, run the code and confirm that the output agrees with that in the directory.

### 1.4.1 Example a

example\_a.input basically reproduces the Kumar Roberts flow results obtained by the programs krssgeps and krcmrnif with notes explaining the different scaling.

## References

- [GBGL00] D. Gubbins, C. N. Barber, S. Gibbons, and J. J. Love. Kinematic dynamo action in a sphere: I effects of differential rotation and meridional circulation on solutions with axial dipole symmetry. *Proc. R. Soc. Lond. A*, 456:1333–1353, 2000.
- [GZ93] D. Gubbins and K. Zhang. Symmetry properties of the dynamo equations for paleomagnetism and geomagnetism. *Phys. Earth Planet. Inter.*, 75:225–241, 1993.
- [KR75] S. Kumar and P. H. Roberts. A three-dimensional kinematic dynamo. Proc. Roy. Soc. Lond. A, 344:235–258, 1975.
- [LSY98] R. B. Lehoucq, D. C. Sorensen, and C. Yang. Arpack users guide: Solution of large scale eigenvalue problems by implicitly restarted Arnoldi methods. SIAM, 1998.
- [Sar94] G. R. Sarson. Kinematic Dynamo Calculations for Geomagnetism. PhD thesis, University of Leeds, 1994.