# Lab Assignment 4

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#### Task 1

Assume that at a given step n, we have  $\mu^n$  and  $r^n$ .

In the first phase of minimizing  $E(\mu^n, r^n)$ , for each  $x_i$  in our data set, we assign

$$r_{ik}^{n+1} = \begin{cases} 1 & \text{if } k = \arg\min_{1 \le j \le k} ||x_i - \mu_j|| \\ 0 & \text{otherwise.} \end{cases}$$

This clearly causes E to decrease (or stay the same) because we replace the previous  $\|x_i - \mu_j\|$  term with the one that gives the minimum norm.

In the second phase, we have  $E(\mu^n, r^{n+1})$ , and minimize with respect to  $\mu^n$ . Since E is convex as a function of  $\mu^n$ , then  $\mu^{n+1}$ , which gives a 0 gradient, must be the global minimizer with our given  $r^{n+1}$ . Hence, in this phase, E must decrease (or stay the same) also.

Thus, the k-cluster means algorithm guarantees descent at each step.

#### Task 2

In one step of the algorithm, we have to calculate all the norms between  $x_n$  and  $\mu_i$  in order to update r.

We first have to calculate the centroids, which are given by

$$oldsymbol{\mu}_j = rac{\displaystyle\sum_{n=1}^N r_{nj} oldsymbol{x}_n}{\displaystyle\sum_{n=1}^N r_{nj}}.$$

So, for the k classes, we have to do N products, 2N sums, and a division, which gives us an upper bound of k(3N+1) steps for the calculation of the means.

We then have to calculate all the norms  $\|\mathbf{x}_n - \boldsymbol{\mu}_j\|$ , which involves d subtractions, multiplications, and sums for Nk pairs of  $\mathbf{x}_n$  and  $\boldsymbol{\mu}_j$ , which gives us 3Ndk calculations to figure out how to update  $r_{nj}$ .

So, each update has k(3N+1) + 3Ndk calculations total.

#### Task 3

Because of symmetry, if we had  $\mu$  which gave us a minimum, we can switch around the order of the  $\mu_j$  and have the same minimum, but with class labels changed. Convex functions must only have one minimum, so if k is at least 2, then  $J(\mu)$  is not convex.

#### Task 4

```
load iris_data.mat
   [N, d] = size(data);
global k;
   k = 3; % Number of classes
 7 % Helper Functions
9 % Given r and j, this computes |Cj|
function y = clusterSize(r, j)

y = sum(r(:, j) == 1);
12 end
13
14 % E step (calculating means)
15 function newMu = updateMu(data, r)
16 global k;
      [N, d] = size(data);
17
18
     \begin{array}{ll} newMu = & \mathbf{zeros} (1, d); \\ & \mathbf{for} & i = 1:k \end{array}
19
20
        currentSum = zeros(1, d);
21
        for j = 1:N
if (r(j, i) == 1)
22
23
            currentSum = currentSum + data(j, :);
24
25
          end
        end
26
         \begin{array}{lll} cSize = clusterSize(r,\ i); \\ newMu(i,\ :) = currentSum\ /\ (cSize\ +\ (cSize\ ==\ 0)\ *\ eps);\ \%\ Avoid\ division\ by\ 0 \end{array} 
27
28
29
30 end
31
32 % M step (updating r)
33 function newR = updateR(data, mu, r)
34 global k;
35
      [N, d] = size(data);
36
37
     \% min always takes the first occurance of the minimum,
38
     % so we don't have to worry about infinite loops
39
40
      for i = 1:N
41
        norms = zeros(k, 1);
42
        for j = 1:k
43
          norms(j) = norm(data(i, :) - mu(j, :));
        end
[M, I] = min(norms);
45
        newR(i, I) = mm(norms);

newR(i, I) = zeros(1, k);

newR(i, I) = 1;
46
47
51 % Assign via random partition method (RPM)
52 function [mu, r] = rpm(data)
53 global k;
      [N, d] = size(data);
54
55
      r = zeros(N, k); % The row is the data point, and the columns give its current classification
56
      for i = 1:N
57
      col = ceil(rand * k);
58
59
       r(i, col) = 1;
60
     mu = updateMu(data, r); % updateMu just calculates the means, essentially
61
62 end
63
64 % Assign via the Forgy method
65 function [mu, r] = forgy (data)
66 global k;
      [N, d] = size(data);
67
68
     r = zeros(N, k); % The row is the data point, and the columns give its current classification
69
     p = \frac{\text{randperm}(N, k)}{\text{for } i = 1:k}
70
71
      mu(i, :) = data(p(i), :);
72
     end
73
74 end
75
76 %%% Main Script
78 % Initialization
79 [mu, r] = forgy(data);
```

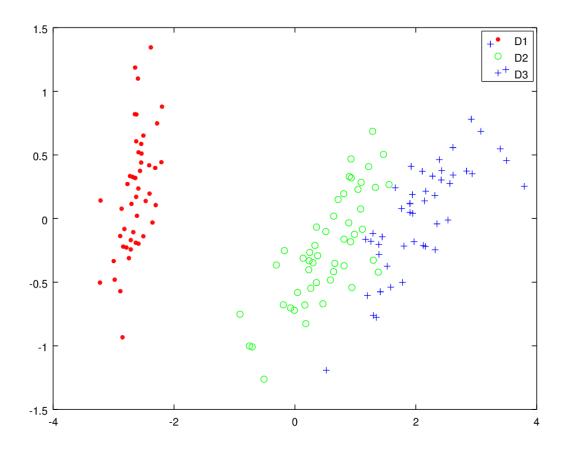
```
80 while true
        newR = updateR(data, mu, r); % E step
mu = updateMu(data, newR); % M step
if (r == newR) % Check if points were moved to a new cluster
break;
81
82
83
84
85
         else
       r = newR;
86
87
88 end
89
89
90 classifications = zeros(N, 1);
91 for i = 1:N
92 for j = 1:k
93 if (r(i, j) == 1)
94 classifications(i) = j;
95
96 end
97 end
98
99 mu
100 classifications
```

### Task 5

On average, the Forgy method performed slightly better. Each cluster's purity for the Forgy method was larger every purity for the random partition method.

Forgy Method	Purity $(C_1)$	Purity $(C_2)$	Purity $(C_1)$
	0.88	0.88	0.87
Random Parition Method	Purity $(C_1)$ $0.85$	Purity $(C_2)$ $0.82$	Purity $(C_1)$ $0.80$

## Task 6



The performance of k-means clustering was fairly good because the classes roughly made up different clusters. However, class 2 and class 3 mixed quite a bit, so it was more difficult to separate those two classes when clustering the data points. So, 80–90% accuracy between the two methods on average is not surprising.