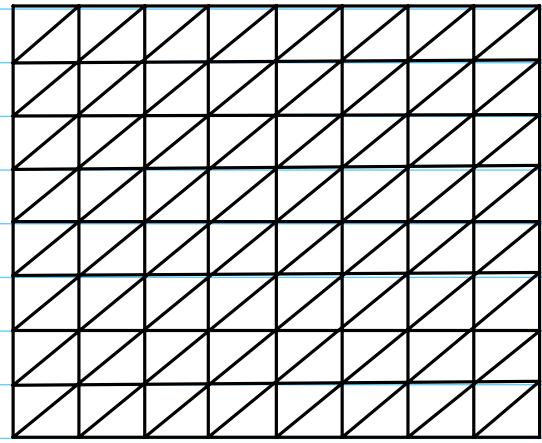
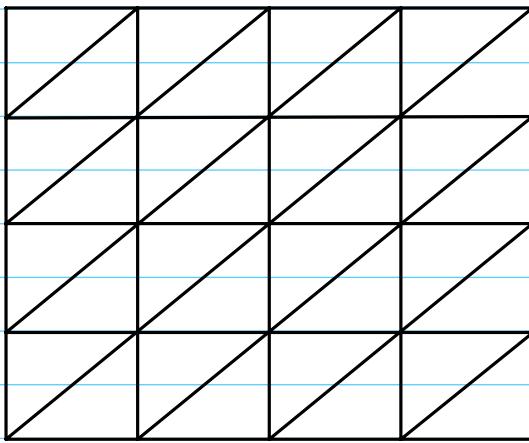


Math 579  
 class # 14  
 10/09/2025

This family of triangulations is shape regular.



Recall that, if the mesh is shape regular, we have

Corollary (13.6): If  $\{\mathcal{T}_n\}_n$  is a shape regular family,  $\exists C > 0$ , independent of the shape and size of  $K$ , such that

$$\|v - \Pi_K v\|_{H^m(K)} \leq C h_K^{r+1-m} |v|_{H^{r+1}(K)}$$

for all  $v \in H^{r+1}(K)$ ,  $\forall K \in \mathcal{T}_n$ .

Proof:

$$\begin{aligned} \|v - \Pi_K v\|_{H^m(K)} &\stackrel{\text{Thm 13.4}}{\leq} C \frac{h_K^{r+1}}{\int_K^m} |v|_{H^{r+1}(K)} \\ &= C \left( \frac{h_K}{\int_K} \right)^m h_K^{r+1-m} |v|_{H^{r+1}(K)} \end{aligned}$$

$$\leq C \sigma^m h_K^{r+1-m} |v|_{H^{r+1}(K)}.$$

To finish the proof, write

$$\|v - \Pi_K v\|_{H^m(K)}^2 = \sum_{t=0}^m \|v - \Pi_K v\|_{H^t(K)}^2. //$$


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### Global Interpolation Error

Theorem (14.1): Assume the conditions of Cor (12.6) hold.  
Then  $\exists C > 0$ , independent of

$$h = \max_{K \in \mathcal{T}_h} h_K,$$

such that

$$(14.1) \quad \|v - \Pi_h v\|_{H^m(\Omega)} \leq C h^{r+1-m} |v|_{H^{r+1}(\Omega)},$$

for all  $v \in H^{r+1}(\Omega)$ .

Proof: Recall that

$$\Pi_h v|_K = \Pi_K v|_K$$

$$\|u - \Pi_h u\|_{H^m(\Omega)}^2 = \sum_{K \in \mathcal{T}_h} \|u - \Pi_K u\|_{H^m(K)}^2$$

$$\leq \sum_{K \in \mathcal{T}_h} C h_K^{2(r+1-m)} \|u\|_{H^{r+1}(K)}^2$$

$$\leq C h^{2(r+1-m)} \sum_{K \in \mathcal{T}_h} \|u\|_{H^{r+1}(K)}^2$$

$$= Ch^{2(r+1-m)} \|u\|_{H^{r+1}(\Omega)}^2$$

Now, take square roots. //

Remark: Here we have used the useful property that

$$\int_{\Omega} f(\vec{x}) d\vec{x} = \sum_{K \in \mathcal{T}_h} \int_K f(x) dx$$

### Error Estimates for the Model Problem

Find  $u \in C^2(\Omega) \cap C^0(\bar{\Omega})$  such that

$$(14.2) \quad \begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

The weak formulation is given by the following: given  $f \in L^2(\Omega)$ , find  $u \in H_0^1(\Omega)$  such that

$$(14.3) \quad a(u, v) = (f, v)_{L^2}, \quad \forall v \in H_0^1(\Omega),$$

where

$$a(u, v) = (\nabla u, \nabla v)_{L^2}$$

The Galerkin approx is given as follows: find  $u_h \in V_h = M_{0,r}$  such that

$$(14.4) \quad a(u_n, v) = (f, v)_L^2 \quad \forall v \in V_h.$$

Recall Cea's lemma for the model problem:

$$(14.5) \quad |u - u_n|_{H^1} = \min_{v \in V_h} |u - v|_{H^1}$$

Corollary (14.2) Suppose that  $V_h = M_{0,r}$ , for  $r \in \mathbb{N}$ . Assume that  $u \in H_0^1(\Omega) \cap H^{r+1}(\Omega)$  is the solution of the model problem in the weak formulation (14.3). Suppose that  $u_n \in V_h$  is the Galerkin (Finite Element) approximation. Assume that  $\mathcal{T}_h$  is a shape regular family of triangulations. Then

$$|u - u_n|_{H^1} \leq C h^r |u|_{H^{r+1}},$$

for some constant that is independent of  $h$ .

Proof:

$$\begin{aligned} |u - u_n|_{H^1} &= \min_{v \in V_h} |u - v|_{H^1} && (14.5) \\ &\leq |u - \Pi_h u|_{H^1} \quad (\Pi_h u \in V_h) \\ &\stackrel{(14.1)}{\leq} C h^{r+1-m} |u|_{H^{r+1}} \quad (m=1) \\ &= C h^r |u|_{H^{r+1}} // \end{aligned}$$

Example:

$r=1$  (piecewise linear FEM):

$$|u - u_n|_{H^1} \leq C h |u|_{H^2}$$

$r=2$  (piecewise quadratic FEM):

$$\|u - u_n\|_{H^1} \leq C h^2 \|u\|_{H^3}$$

$r=3$  (piecewise cubic FEM):

$$\|u - u_n\|_{H^1} \leq C h^3 \|u\|_{H^4}$$

"The currency of approximation is derivatives."

- Ohannes Karakashian

Question: Can we improve our approximations by measuring error in the  $L^2$  norm?

Theorem (14.3): Suppose that  $\Omega \subset \mathbb{R}^2$  is a convex polygonal domain and  $f \in L^2(\Omega)$ . Let  $u \in H_0^1(\Omega)$  be the solution to (14.3) and suppose that  $u_n \in V_h = M_{0,1}$  is the solution to (14.4). Assume that  $T_h$  is a shape regular family of triangulations. Then

$$\|u - u_n\|_{L^2} \leq C_1 h \|u - u_n\|_{H^1},$$

for some constant  $C_1 > 0$  that is independent of  $h$ .  
Consequently,

$$\|u - u_n\|_{L^2} \leq C_1 C h^2 \|u\|_{H^2},$$

for some  $C > 0$  that is independent of  $h$ .

Proof: By elliptic regularity theory, since  $\Omega$  is convex polygonal and  $f \in L^2(\Omega)$ , it follows that

$$u \in H_0^1(\Omega) \cap H^2(\Omega)$$

and there is a constant  $C_R > 0$  such that

$$(14.6) \quad \|u\|_{H^2} \leq C_R \|f\|_{L^2} = C_R \|\Delta u\|_{L^2}.$$

We are going to use a "duality argument," in this context known as Nitsche's Trick.

First, recall the fundamental Galerkin orthogonality (FGO):

$$(14.7) \quad 0 = a(u - u_h, v) = a(e, v), \quad \forall v \in V_h,$$

where

$$e := u - u_h \in H_0^1(\Omega)$$

Consider the following problem: Find  $\phi \in H_0^1(\Omega)$  such that

$$(14.8) \quad \begin{aligned} -\Delta \phi &= e && \text{in } \Omega \\ \phi &= 0 && \text{on } \partial\Omega \end{aligned}$$

which, in weak form, is expressed as

$$(14.9) \quad a(\phi, v) = (e, v) \quad \forall v \in H_0^1(\Omega)$$

By elliptic regularity theory, we know that

$$\phi \in H_0^1(\Omega) \cap H^2(\Omega)$$

and

$$(14.10) \quad \|\phi\|_{H^2} \leq C_R \|e\|_{L^2}$$

Now,

$$\begin{aligned} \|e\|_{L^2}^2 &= (e, e)_{L^2} \\ &\stackrel{(14.9)}{=} a(\phi, e) \\ &\stackrel{\text{sym}}{=} a(e, \phi) \\ &\stackrel{\text{FGD}}{=} a(e, \phi - v) \end{aligned}$$

for any  $v \in V_h$ . Thus, for arbitrary  $v \in V_h$ ,

$$\begin{aligned} \|e\|_{L^2}^2 &= a(e, \phi - v) \\ &\stackrel{\text{C.S.}}{\leq} \|e\|_{H^1} \|\phi - v\|_{H^1}. \end{aligned}$$

Now, since  $H^2(\Omega) \hookrightarrow C^0(\bar{\Omega})$ ,  $\Pi_h \phi \in V_h$  is well-defined and

$$\begin{aligned} \|e\|_{L^2}^2 &\leq \|e\|_{H^1} \|\phi - \Pi_h \phi\|_{H^1} \\ &\stackrel{(14.1)}{\leq} \|e\|_{H^1} C_h \|\phi\|_{H^2} \quad (m=1, r=1) \\ &\stackrel{(14.10)}{\leq} \underbrace{C_R C_h}_{C_1} \|e\|_{L^2} \|e\|_{H^1} \end{aligned}$$

Hence

$$\|e\|_{L^2} \leq C_1 h \|e\|_{H^1}. //$$

Now, we know that  $u \in H^1(\Omega) \cap H^2(\Omega)$  and

$$|e|_{H^1} \leq C h \|u\|_{H^2}$$

by Corollary 14.2. Combining the last two estimates gives

$$\|u - u_h\|_{L^2} \leq CC_1 h^2 \|u\|_{H^2}. \quad \text{III}$$

We'll prove a more general result shortly ...

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### A Non-Symmetric Problem

Given  $f \in C^0(\bar{\Omega})$ ,  $\vec{b} \in \mathbb{R}^d$  and  $c > 0$ . Find  $u \in C^2(\Omega) \cap C^1(\bar{\Omega})$  such that

$$\left\{ \begin{array}{l} -\Delta u + \vec{b} \cdot \nabla u + cu = f \quad \text{in } \Omega \subset \mathbb{R}^d \\ u = 0 \quad \text{on } \Gamma_D \\ \frac{\partial u}{\partial n} = g \quad \text{on } \Gamma_N \end{array} \right.$$

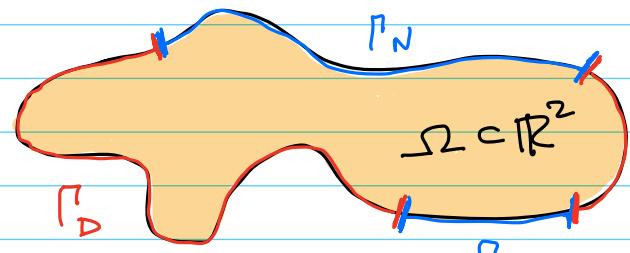
(4.11)

Here

$$\Gamma_D \cup \Gamma_N = \partial\Omega,$$

$$\Gamma_D \cap \Gamma_N = \emptyset,$$

$$\mu_1(\Gamma_D), \mu_1(\Gamma_N) > 0$$



Let us formulate a weak version of the problem.  
Let

$$V \in V := \{v \in H^1(\Omega) \mid v = 0 \text{ on } \Gamma_D\}$$

be arbitrary. Then, using integration-by-parts,

$$\begin{aligned}
 (\mathbf{f}, v)_{L^2} - c(u, v)_{L^2} - (\vec{b} \nabla u, v)_{L^2} \\
 &= -(\Delta u, v)_{L^2} + \underbrace{\frac{\partial u}{\partial n}}_{\Gamma_D} v \, ds \\
 &= (\nabla u, \nabla v)_{L^2} - \int_{\partial\Omega} \hat{n} \cdot \nabla u \, v \, ds \\
 &= (\nabla u, \nabla v)_{L^2} - \int_{\Gamma_D} \frac{\partial u}{\partial n} v \, ds \\
 &\quad - \int_{\Gamma_N} \frac{\partial u}{\partial n} v \, ds \\
 &= (\nabla u, \nabla v)_{L^2} - \int_{\Gamma_N} g v \, ds
 \end{aligned}$$

Thus,

$$(14.12) \quad a(u, v) = L(v), \quad \forall v \in V$$

where

$$\begin{cases} a(u, v) := (\nabla u, \nabla v)_{L^2} + (\vec{b} \cdot \nabla u, v)_{L^2} + c(u, v)_{L^2}, \\ L(v) := (\mathbf{f}, v)_{L^2} + (g, v)_{L^2(\Gamma_N)}. \end{cases}$$

Definition (14.4): The following is a weak formulation of the non-symmetric problem (14.11). Given  $\mathbf{f} \in L^2(\Omega)$ ,  $g \in L^2(\Gamma_N)$ ,  $c > 0$ , and  $\vec{b} \in \mathbb{R}^d$ , find  $u \in V$ , where

$$(14.14) \quad V := \{v \in H^1(\Omega) \mid v = 0 \text{ on } \Gamma_N\}$$

such that (14.12) holds. We call such a  $u \in V$ , if it exists, a weak solution to (14.11).

Proposition (14.5): The space defined in (14.4) is a Hilbert space. The functional  $L: V \rightarrow \mathbb{R}$  is linear and bounded. The bilinear form

$$a: V \times V \rightarrow \mathbb{R}$$

is, in general, non-symmetric, but is unconditionally continuous. In particular,

$$|a(u, v)| \leq \gamma \|u\|_H \|v\|_H$$

where

$$\gamma = 1 + \|\vec{b}\|_2 + c.$$

$a$  is coercive, provided that

$$(14.15) \quad \beta := \min\{1, c\} > \frac{\|\vec{b}\|_2}{2}.$$

In particular, in this case,

$$\alpha \|u\|_H \leq a(u, u),$$

where

$$\alpha = \beta - \frac{\|\vec{b}\|_2}{2} > 0.$$

Under condition (14.15) there exists a unique weak solution  $u \in V$  to (14.11).

Proof: The conclusion follows from the Lax-Milgram lemma, provided we can prove the other points.

1)  $L$  is a bounded linear operator on  $V$ .

$L$  is clearly linear. To show that it is bounded, let  $v \in V$  be arbitrary. Then

$$\begin{aligned} |L(v)| &\leq \left| \int_{\Omega} f v \, dx \right| + \left| \int_{\Gamma_N} g v \, d\tilde{x} \right| \\ &\stackrel{\text{C.S}}{\leq} \|f\|_{L^2} \|v\|_{L^2} + \|g\|_{L^2(\Gamma_N)} \|v\|_{L^2(\Gamma_N)} \end{aligned}$$

Using the Trace Theorem (lecture 06)

$$\|v\|_{L^2(\Gamma_N)} \leq C_T \|v\|_{H^1(\Omega)}$$

we have

$$\begin{aligned} |L(v)| &\leq (\|f\|_{L^2} + C_T \|g\|_{L^2(\Gamma_N)}) \|v\|_{H^1} \\ &= C \|v\|_{H^1}. \end{aligned}$$

(To use the Trace Theorem we need to assume that the boundary  $\Gamma_N$  is sufficiently regular. Let us assume that  $\partial\Omega$  is Lipschitz cont. This should be enough.)

2)  $a$  is continuous: Let  $u, v \in V$  be arbitrary.  
Then

$$\begin{aligned} |a(u, v)| &\leq |(\nabla u, \nabla v)|_2 + |(\vec{b} \cdot \nabla u, c)v|_2 \\ &\quad + c |(u, v)|_2 \\ &\leq \|u\|_{H^1} \|v\|_{H^1} + \|\vec{b}\|_2 \|u\|_{H^1} \|v\|_{L^2} \end{aligned}$$

$$\begin{aligned}
& + c \|u\|_2 \|\langle v \rangle\|_{L^2} \\
& \leq (1 + \|\vec{b}\|_2 + c) \|u\|_H \|\langle v \rangle\|_H \\
& = \gamma \|u\|_H \|\langle v \rangle\|_H
\end{aligned}$$

3) a is coercive:

$$a(u, u) = \|u\|_H^2 + (\vec{b} \cdot \nabla u, u) + c \|u\|_2^2$$

For non-symmetric terms,

$$\begin{aligned}
-(\vec{b} \cdot \nabla u, u) & \leq |(\vec{b} \cdot \nabla u, u)| \\
& \leq \|\vec{b}\|_2 \|u\|_H \|u\|_2 \\
& \leq \|\vec{b}\|_2 \|u\|_H
\end{aligned}$$

This estimate is not optimal. We can do just a bit better by using the AGMI:

$$ab \leq \frac{a^2}{2} + \frac{b^2}{2}$$

$$\begin{aligned}
-(\vec{b} \cdot \nabla u, u) & \leq |(\vec{b} \cdot \nabla u, u)| \\
& \leq \|\vec{b}\|_2 \|u\|_H \|u\|_2 \\
& = \left( \|\vec{b}\|_2^2 \|u\|_H^2 \right) \cdot \left( \frac{\|\vec{b}\|_2^2}{2} \|u\|_2^2 \right) \\
& \stackrel{\text{AGMI}}{\leq} \frac{\|\vec{b}\|_2^2}{2} \|u\|_H^2 + \frac{\|\vec{b}\|_2^2}{2} \|u\|_2^2 \\
& = \frac{\|\vec{b}\|_2^2}{2} \left( \|u\|_2^2 + \|u\|_H^2 \right)
\end{aligned}$$

$$= \frac{\|\vec{b}\|_2}{2} \|u\|_{H^1}^2.$$

Thus,

$$(\vec{b} \cdot \nabla u, u) \geq - \frac{\|\vec{b}\|_2}{2} \|u\|_{H^1}^2$$

so that

$$\begin{aligned} a(u, u) &\geq \|u\|_{H^1}^2 - \frac{\|\vec{b}\|_2}{2} \|u\|_{H^1}^2 + c \|u\|_2^2 \\ &\geq \beta (\|u\|_2^2 + \|u\|_{H^1}^2) - \frac{\|\vec{b}\|_2}{2} \|u\|_{H^1}^2 \\ &= \alpha \|u\|_{H^1}^2 \end{aligned}$$

where

$$\alpha = \beta - \frac{\|\vec{b}\|_2}{2} > 0. //$$

Using the Lax-Milgram lemma, a unique solution  $u \in V$  to (14.12) exists. //