

## Math 673/4

## Multigrid Methods: A Mostly Matrix-Based Approach

Chapter 03: Fourier Analysis of the Two-Grid Algorithm

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# Chapter 03, Part 3 of 3 Fourier Analysis of the Two-Grid Algorithm



## Other Restriction Matrices

#### Other Restriction Matrices



The prolongation matrix makes good geometric sense. If  $u_0 \in \mathbb{R}^{n_0}$  is the unique coordinate vector of the function  $u_0 \in V_0$  with respect to the basis  $B_0$ , then  $P_0u_0$  is its unique coordinate vector in the basis  $B_1$ . But what is the interpretation of the restriction matrix?

Consider the fine grid function,  $u_1 \in V_1$ , pictured in the next figure, where  $n_1 = 7$ . Suppose its coordinate vector in the basis  $B_1$  is represented as  $\boldsymbol{u}_1 \in \mathbb{R}^7$ . Let  $R_0u_1 \in V_0$  ( $\frac{1}{2}R_0u_1 \in V_0$ ) be the function whose coordinate representation in the basis  $B_0$  is  $R_0\boldsymbol{u}_1$  ( $\frac{1}{2}R_0\boldsymbol{u}_1$ ). See the figure on the next slide.



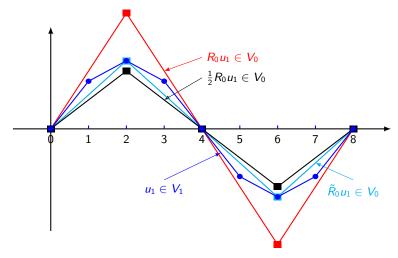


Figure: A Fine grid function,  $u_1 \in V_1$ , for  $n_1 = 7$ , and three possible restrictions  $R_0u_1 \in V_0$ ,  $\frac{1}{2}R_0u_1 \in V_0$ , and  $R_0u_1 \in V_0$ . The restriction  $\frac{1}{2}R_0u_1$  is called the full weighting restriction.

#### Other Restriction Matrices



To understand what is pictured in the figure on the last slide, we need to understand what is the action of  $R_0$  on  $u_1$ . If  $u_1 \in \mathbb{R}^{n_1}$  is the coordinate vector of  $u_1 \in V_1$  with respect to the hat function basis  $B_1$ , then, clearly,

$$\mathsf{R}_{0}\boldsymbol{u}_{1} = \begin{bmatrix} \frac{1}{2} & 1 & \frac{1}{2} \\ & & \frac{1}{2} & 1 & \frac{1}{2} \\ & & & \frac{1}{2} & 1 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} u_{1,1} \\ u_{1,2} \\ u_{1,3} \\ u_{1,4} \\ u_{1,5} \\ u_{1,6} \\ u_{1,7} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}u_{1,1} + u_{1,2} + \frac{1}{2}u_{1,3} \\ \frac{1}{2}u_{1,3} + u_{1,4} + \frac{1}{2}u_{1,5} \\ \frac{1}{2}u_{1,5} + u_{1,6} + \frac{1}{2}u_{1,7} \end{bmatrix}.$$

The results of this calculation give coordinates that are twice the size that they should be in order to be geometrically and analytically sensible. Thus, dividing by 2, we get a more satisfying result.

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#### Other Restriction Matrices



There is another possibility that might seem obvious. If  $u_1 \in \mathbb{R}^{n_1}$  is the coordinate vector of  $u_1 \in V_1$  with respect to the hat function basis  $B_1$ , then, we could define

$$\tilde{\mathsf{R}}_{0}\boldsymbol{u}_{1} = \begin{bmatrix} 0 & 1 & 0 & & & \\ & & 0 & 1 & 0 & \\ & & & & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} u_{1,1} \\ u_{1,2} \\ u_{1,3} \\ u_{1,4} \\ u_{1,5} \\ u_{1,6} \\ u_{1,7} \end{bmatrix} = \begin{bmatrix} u_{1,2} \\ u_{1,4} \\ u_{1,6} \end{bmatrix}.$$

In the figure two slides ago,  $\ddot{R}_0u_1\in V_0$  is the function whose coordinate representation in the basis  $B_0$  is  $\tilde{R}_0 u_1$ . This too gives a more satisfying result than the standard restriction.



#### Definition (Full Weighting Restriction)

The matrix  $\frac{1}{2}R_0$ , where  $R_0$  is defined as above, is called the **full weighting** restriction matrix.



#### Remark

Clearly,  $\frac{1}{2}R_0$  and  $\tilde{R}_0$  seem to give more geometrically meaningful results than  $R_0$ . So, why do we not use them? The answer is simple, the Galerkin condition. If we use either  $\frac{1}{2}R_0$  or  $\tilde{R}_0$ , the Galerkin condition will be broken, and it is too useful to dismiss, as we shall see.



# Fourier Error Analysis

#### Fourier Error Analysis



Recall the following result from the last chapter concerning the two-grid algorithm:

$$\boldsymbol{e}_1^{k+1} = \mathsf{E}_1 \boldsymbol{e}_1^k,$$

where

$$\mathsf{E}_1 = (\mathsf{K}_1^*)^{m_2} \left( \mathsf{I}_1 - \tilde{\mathsf{\Pi}}_1 \right) (\mathsf{K}_1)^{m_1}.$$

Also, for the present case,

$$K_1 = I_1 - \omega_0 \frac{h_1}{2} A_1 = K_1^*.$$

 $\tilde{\Pi}_1$  is the coarse grid Ritz projection matrix

$$\tilde{\Pi}_1 = R_0^\top A_0^{-1} R_0 A_1.$$

Assuming that the level-0 stiffness matrix  $A_0$  satisfies the Galerkin condition, we have

$$\tilde{\Pi}_1^2 = \tilde{\Pi}_1$$
.

#### Notation



We will use the following simplifying notation throughout this section:

$$C_m: = \cos^2\left(\frac{m\pi h_1}{2}\right) = \frac{1}{2}(1 + \cos(m\pi h_1)),$$
 (1)

$$S_m: = \sin^2\left(\frac{m\pi h_1}{2}\right) = \frac{1}{2}(1-\cos(m\pi h_1)).$$
 (2)

## Notation



#### Definition

For all  $1 \le k \le n_1$ , define

$$k' := n_1 + 1 - k. \tag{3}$$

k' is called the **reciprocal wave number** of k.

Clearly, (k')' = k. See table below for the relationship between k and its reciprocal wave number, k'.

<i>k</i> frequency characterization	k	$k' = n_1 + 1 - k$	<ul><li>k' frequency</li><li>characterization</li></ul>
low	1	$7 = n_1$	high
low	2	6	high
low	3	5	high
high	$n_0 + 1 = 4$	$4 = n_0 + 1$	high
high	5	3	low
high	6	2	low
high	$n_1 = 7$	1	low

Table: The values of k' as a function of k for the case  $n_1 = 7$ ,  $n_0 = 3$ .

#### Analysis of Fourier Modes



To analyze the error quantitatively, we need know what are the actions of our various matrices on the eigenvectors from the coarse and fine grids, which are denoted in the usual way,

$$\left[\mathbf{v}_{\ell}^{(k)}\right]_{i} = \sin(k\pi x_{\ell,i}), \quad 1 \leq i, k \leq n_{\ell}, \quad \ell = 0, 1,$$

where the grid points for the coarse and fine grids are determined via

$$x_{\ell,i}=i\cdot h_{\ell},\quad \ell=0,1,\quad 0\leq i\leq n_{\ell}+1.$$

We begin by listing some aliasing-type results that will be needed in our Fourier analysis.



## Lemma (Aliasing)

Suppose the two-level grid is uniform and nested. Then, for  $1 \le k \le n_1$  and  $1 \le i \le n_0$ ,

$$\sin(k'\pi x_{0,i}) = \left[\mathbf{v}_0^{(k')}\right]_i = -\left[\mathbf{v}_0^{(k)}\right]_i = -\sin(k\pi x_{0,i}. \tag{4}$$

Furthermore, for  $1 \le k \le n_1$ ,

$$\cos\left(k'\pi h_1\right) = -\cos(k\pi h_1). \tag{5}$$

Finally, for  $1 \le k \le n_1$  and  $1 \le i \le n_1$ ,

$$\sin(k'\pi x_{1,i}) = \left[\mathbf{v}_1^{(k')}\right]_i = (-1)^{i+1} \left[\mathbf{v}_1^{(k)}\right]_i = (-1)^{i+1} \sin(k\pi x_{1,i}). \tag{6}$$



#### Proof.

First, observe that, for any  $1 \le k \le n_1$ ,

$$\begin{split} \left[ \mathbf{v}_{0}^{(k')} \right]_{i} &= \left[ \mathbf{v}_{0}^{(n_{1}+1-k)} \right]_{i} \\ &= \sin \left( (n_{1}+1-k)\pi i h_{0} \right) \\ &= \sin \left( (n_{1}+1-k)\pi \frac{2i}{n_{1}+1} \right) \\ &= \sin \left( 2\pi i - k\pi x_{0,i} \right) \\ &= \sin \left( -k\pi x_{0,i} \right) \\ &= -\sin \left( k\pi x_{0,i} \right) \\ &= -\left[ \mathbf{v}_{0}^{(k)} \right]_{i}, \end{split}$$

which quantifies the phenomenon known as *aliasing*, that is, high frequency modes (sine waves) are distorted on a coarse grid.



Similarly,

$$\cos(k'\pi h_1) = \cos((n_1 + 1 - k)\pi h_1)$$

$$= \cos(\pi - k\pi h_1)$$

$$= -\cos(k\pi h_1).$$

To see the last result, consider

$$\begin{aligned} \left[ \mathbf{v}_{1}^{(k')} \right]_{i} &= & \sin \left( (n_{1} + 1 - k) \pi x_{1,i} \right) \\ &= & \sin \left( (n_{1} + 1 - k) \pi \frac{i}{n_{1} + 1} \right) \\ &= & \sin \left( i \pi - k \pi x_{1,i} \right). \end{aligned}$$



## Proposition (Restriction Modal Analysis)

Suppose that the two-level grid is uniform and nested. Then

$$\mathsf{R}_0 \mathbf{v}_1^{(k)} = \begin{cases} 2\mathsf{C}_k \mathbf{v}_0^{(k)}, & 1 \le k \le n_0, \\ -2\mathsf{S}_{k'} \mathbf{v}_0^{(k')}, & n_0 + 1 \le k \le n_1. \end{cases}$$
 (7)

#### Proof.

(Low frequency components): Consider for  $1 \le i \le n_0$ ,  $1 \le k \le n_0$ ,

$$\begin{split} \left[\mathsf{R}_{0} \boldsymbol{v}_{1}^{(k)}\right]_{i} &= \frac{1}{2} \left\{ \sin(k\pi x_{1,2i-1}) + 2\sin(k\pi x_{1,2i}) + \sin(k\pi x_{1,2i+1}) \right\} \\ &= \frac{1}{2} \left[ \sin(k\pi x_{1,2i} - k\pi h_{1}) + 2\sin(k\pi x_{1,2i}) + \sin(k\pi x_{1,2i}) + \sin(k\pi x_{1,2i} + k\pi h_{1}) \right] \\ &= \frac{1}{2} \left[ \sin(k\pi x_{1,2i}) \cos(k\pi h_{1}) - \cos(k\pi x_{1,2i}) \sin(k\pi h_{1}) + \sin(k\pi x_{1,2i}) \cos(k\pi h_{1}) + \cos(k\pi x_{1,2i}) \sin(k\pi h_{1}) + 2\sin(k\pi x_{1,2i}) \right] \\ &= \sin(k\pi x_{1,2i}) \cos(k\pi h_{1}) + \sin(k\pi x_{1,2i}) \\ &= \sin(k\pi x_{1,2i}) (\cos(k\pi h_{1}) + 1) \\ &= 2\cos^{2} \left( \frac{k\pi h_{1}}{2} \right) \sin(k\pi x_{1,2i}) \\ &= 2\mathsf{C}_{k} \left[ \boldsymbol{v}_{0}^{(k)} \right]_{i}. \end{split}$$

The first part is complete.



(High frequency components): The first part of the calculation above is still valid for  $n_0+1\leq k\leq n_1$ . We now use the aliasing results (4) and (5) from the technical lemma to obtain

$$\begin{split} \left[\mathsf{R}_{0} \mathbf{v}_{1}^{(k)}\right]_{i} &= \frac{1}{2} \left\{ \sin(k\pi x_{1,2i-1}) + 2\sin(k\pi x_{1,2i}) + \sin(k\pi x_{1,2i+1}) \right\} \\ &= \sin(k\pi x_{1,2i}) (\cos(k\pi h_{1}) + 1) \\ &= \left(\cos(k\pi h_{1}) + 1\right) \left[\mathbf{v}_{0}^{(k)}\right]_{i} \\ &= -(1 - \cos(k'\pi h_{1})) \left[\mathbf{v}_{0}^{(k')}\right]_{i} \\ &= -2\sin^{2} \left(\frac{k'\pi h_{1}}{2}\right) \left[\mathbf{v}_{0}^{(k')}\right]_{i} \\ &= -2\mathsf{S}_{k'} \left[\mathbf{v}_{0}^{(k')}\right]_{i}, \end{split}$$

where we have used the aliasing calculations above. The result is proved.



## Proposition (Prolongation Modal Analysis)

Suppose that the two-level grid is uniform and nested. For  $1 \le k \le n_0$ ,

$$P_0 \mathbf{v}_0^{(k)} = C_k \mathbf{v}_1^{(k)} - S_k \mathbf{v}_1^{(k')}. \tag{8}$$



#### Proof.

Now, for  $1 \le i \le n_1$ , define

$$j := \begin{cases} \frac{i+1}{2}, & \text{if } i \text{ is odd,} \\ \frac{i}{2}, & \text{if } i \text{ is even.} \end{cases}$$



Working with the right hand side of the desired result, for  $1 \le i \le n_1$ , and  $1 \le k \le n_0$ , it follows that

$$\begin{split} I_i^{(k)} &:= \mathtt{C}_k \left[ \mathbf{v}_1^{(k)} \right]_i - \mathtt{S}_k \left[ \mathbf{v}_1^{(k')} \right]_i \\ &= \begin{cases} \cos(k\pi h_1) \sin(k\pi x_{1,i}), & i \text{ is odd,} \\ \sin(k\pi x_{1,i}), & i \text{ is even,} \end{cases} \end{aligned}$$
 ((6) and basic trigonometry) 
$$= \begin{cases} \cos(k\pi h_1) \sin(k\pi x_{1,2j-1}), & i \text{ is odd,} \\ \sin(k\pi x_{1,2j}), & i \text{ is even,} \end{cases}$$
 
$$= \begin{cases} \frac{1}{2} \sin(k\pi x_{1,2j-1} + k\pi h_1) + \frac{1}{2} \sin(k\pi x_{1,2j-1} - k\pi h_1), & i \text{ is odd,} \\ \sin(k\pi x_{1,2j}), & i \text{ is even,} \end{cases}$$
 
$$= \begin{cases} \frac{1}{2} \sin(k\pi x_{1,2j}) + \frac{1}{2} \sin(k\pi x_{1,2j-2}), & i \text{ is odd,} \\ \sin(k\pi x_{1,2j}), & i \text{ is even,} \end{cases}$$
 
$$= \begin{cases} \left[ P_0 \mathbf{v}_0^{(k)} \right]_{2j-1}, & i \text{ is odd,} \\ \left[ P_0 \mathbf{v}_0^{(k)} \right]_{2j-1}, & i \text{ is even.} \end{cases}$$



Thus

$$I_i^{(k)} = \mathtt{C}_k \left[ \mathbf{v}_1^{(k)} \right]_i - \mathtt{S}_k \left[ \mathbf{v}_1^{(k')} \right]_i = \left[ \mathsf{P}_0 \mathbf{v}_0^{(k)} \right]_i.$$



We list now a couple more aliasing-type results that will be needed in the analysis. The proofs are straightforward and omitted.

#### Lemma (Aliasing)

Suppose that the two-level grid is uniform and nested. Then,

$$\sin(k'\pi h_1) = \sin(k\pi h_1) \tag{9}$$

and

$$\sin\left(\frac{k'\pi h_1}{2}\right) = \cos\left(\frac{k\pi h_1}{2}\right),\tag{10}$$

for all  $1 \le k \le n_1$ .



## Proposition (Ritz Projection Modal Analysis)

Suppose that the two-level grid is uniform and nested and  $A_0$  satisfies the Galerkin condition. Then

$$(I_1 - \tilde{\Pi}_1) \mathbf{v}_1^{(k)} = S_k \mathbf{v}_1^{(k)} + S_k \mathbf{v}_1^{(k')}, \tag{11}$$

for  $1 \le k \le n_0$ . Similarly,

$$(\mathsf{I}_1 - \tilde{\mathsf{\Pi}}_1) \mathbf{v}_1^{(k')} = \mathsf{C}_k \mathbf{v}_1^{(k)} + \mathsf{C}_k \mathbf{v}_1^{(k')}, \tag{12}$$

for  $1 \le k \le n_0 + 1$ .

#### Proof.

Recall that

$$\tilde{\mathsf{\Pi}}_1 = \mathsf{P}_0 \mathsf{A}_0^{-1} \mathsf{R}_0 \mathsf{A}_1 \in \mathbb{R}^{n_1 \times n_1},$$

where, since A<sub>0</sub> satisfies the Galerkin condition,

$$\mathsf{A}_0 = \mathsf{R}_0 \mathsf{A}_1 \mathsf{P}_0 \in \mathbb{R}^{n_0 \times n_0}.$$

Then, for  $1 \le k \le n_0$ ,

$$\begin{split} \tilde{\Pi}_{1} \boldsymbol{v}_{1}^{(k)} &= P_{0} A_{0}^{-1} R_{0} A_{1} \boldsymbol{v}_{1}^{(k)} \\ &= \lambda_{1}^{(k)} P_{0} A_{0}^{-1} R_{0} \boldsymbol{v}_{1}^{(k)} \\ &\stackrel{(7)}{=} 2 C_{k} \lambda_{1}^{(k)} P_{0} A_{0}^{-1} \boldsymbol{v}_{0}^{(k)} \\ &= \frac{2 C_{k} \lambda_{1}^{(k)}}{\lambda_{0}^{(k)}} P_{0} \boldsymbol{v}_{0}^{(k)} \\ &\stackrel{(8)}{=} \frac{2 C_{k} \lambda_{1}^{(k)}}{\lambda_{0}^{(k)}} \left\{ C_{k} \boldsymbol{v}_{1}^{(k)} - S_{k} \boldsymbol{v}_{1}^{(k')} \right\}. \end{split}$$

Observe,

$$\begin{split} \frac{\lambda_1^{(k)}}{\lambda_0^{(k)}} &= \frac{\frac{2}{h_1} \left( 1 - \cos(k\pi h_1) \right)}{\frac{2}{h_0} \left( 1 - \cos(k\pi h_0) \right)} \\ &= \frac{h_0}{h_1} \frac{\sin^2\left(\frac{k\pi h_1}{2}\right)}{\sin^2(k\pi h_1)} \\ &= \frac{2S_k}{\sin^2(k\pi h_1)}. \end{split}$$

Thus

$$\tilde{\Pi}_1 \mathbf{v}_1^{(k)} = \frac{4C_k S_k}{\sin^2(k\pi h_1)} \left\{ C_k \mathbf{v}_1^{(k)} - S_k \mathbf{v}_1^{(k')} \right\}.$$

But

$$C_kS_k=\frac{1}{4}\sin^2(k\pi h_1),$$

as the reader can easily check. We have

$$\tilde{\Pi}_1 \mathbf{v}_1^{(k)} = C_k \mathbf{v}_1^{(k)} - S_k \mathbf{v}_1^{(k')}, \quad 1 \leq k \leq n_0.$$





Therefore, for  $1 \le k \le n_0$ ,

$$\begin{aligned} (I_1 - \tilde{\Pi}_1) \mathbf{v}_1^{(k)} &= (1 - C_k) \mathbf{v}_1^{(k)} + S_k \mathbf{v}_1^{(k')} \\ &= S_k \left( \mathbf{v}_1^{(k)} + \mathbf{v}_1^{(k')} \right), \end{aligned}$$

which is (11).

Equation (12) is established in an analogous way. One must make use of the aliasing results (9) and (10). The proof is an exercise.

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Using the aliasing results again, we can establish the following equivalent identity.

#### Corollary

Suppose that the two-level grid is uniform and nested and  $A_0$  is constructed via the Galerkin condition. Then,

$$(I_1 - \tilde{\Pi}_1) \mathbf{v}_1^{(k)} = S_k \mathbf{v}_1^{(k)} + S_k \mathbf{v}_1^{(k')}, \tag{13}$$

for  $1 \le k \le n_1$ , that is, for all frequencies, high and low.



For our convergence result, we will consider the one-sided two-grid algorithm, that is, the usual two-grid algorithm with no post-smoothing,  $m_2=0$ . This non-symmetric version of the algorithm works perfectly well, as we shall see, for the quantitative Fourier analysis that we are using. Other forms of analysis will require the symmetry.

#### Theorem (Convergence of the One-Sided Two-Grid Algorithm)

Suppose that the two-level grid is uniform and nested and  $A_0$  satisfies the Galerkin condition. Assume that  $m_2=0$ ,  $\omega_0=\frac{2}{3}$ , and  $m_1\geq 1$ . Then

$$\left\| oldsymbol{e}_1^{\ell+1} 
ight\|_1 \leq \left\{ rac{1}{2} + rac{1}{3^{m_1}} 
ight\}^{1/2} \left\| oldsymbol{e}_1^{\ell} 
ight\|_1.$$



#### Proof.

We begin with the basis expansion

$$oldsymbol{e}_1^\ell = \sum_{k=1}^{n_1} \epsilon_k oldsymbol{v}_1^{(k)}.$$

The error transfer matrix,  $E_1$ , for the two-grid scheme, in this case, satisfies

$$oldsymbol{e}_1^{\ell+1} = \mathsf{E}_1 oldsymbol{e}_1^\ell,$$

where

$$E_1 = (I_1 - \tilde{\Pi}_1)K_1^{m_1}.$$

Hence,

$$\mathbf{e}_1^{\ell+1} = \sum_{k=1}^{n_1} \epsilon_k (\mathsf{I}_1 - \tilde{\mathsf{\Pi}}_1) \mathsf{K}_1^{m_1} \mathbf{v}_1^{(k)}.$$



By the Galerkin Projection Modal Analysis, for  $1 \le k \le n_0 + 1$ ,

$$(I_1 - \tilde{\Pi}_1) K_1^{m_1} \mathbf{v}_1^{(k)} = \alpha_k \left\{ \mathbf{v}_1^{(k)} + \mathbf{v}_1^{(k')} \right\}, \tag{14}$$

and, for  $1 \le k \le n_0 + 1$ ,

$$(I_1 - \tilde{\Pi}_1) K_1^{m_1} \mathbf{v}_1^{(k')} = \beta_k \left\{ \mathbf{v}_1^{(k)} + \mathbf{v}_1^{(k')} \right\}, \tag{15}$$

where

$$\alpha_k := \left(\mu_1^{(k)}(\omega_0)\right)^{m_1} S_k, \quad 1 \le k \le n_0 + 1,$$

and

$$eta_k := \left(\mu_1^{(k')}(\omega_0)\right)^{m_1} C_k, \quad 1 \le k \le n_0 + 1.$$



Observe that we have extended the upper limit of the index k in (14) by 1, up to  $k = n_0 + 1$ . The result is still valid in this case. Further, observe that

$$\alpha_{n_0+1}=\beta_{n_0+1},$$

as the reader can easily verify.

With the optimal choice of  $\omega_0$  of the damped Jacobi method derived in the last chapter, we have

$$\left|\mu_1^{(k)}(\omega_0)\right| \leq rac{1}{3}, \quad n_0+1 \leq k \leq n_1 \quad ext{(high frequencies)},$$

and

$$\left|\mu_1^{(k)}(\omega_0)
ight| < 1, \quad 1 \leq k \leq n_1 \quad ext{(all frequencies)}.$$

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We can estimate  $\alpha_k$  and  $\beta_k$  as follows:

$$|\alpha_k| \le 1^{m_1} S_k \le 1 \cdot \frac{1}{2}, \quad 1 \le k \le n_0 + 1,$$

and

$$|eta_k| \leq \left(rac{1}{3}
ight)^{m_1} \mathtt{C}_k \leq \left(rac{1}{3}
ight)^{m_1} \cdot 1, \quad 1 \leq k \leq n_0 + 1.$$

We can represent the error as at iteration  $\ell$  as

$$oldsymbol{e}_1^\ell = \sum_{k=1}^{n_0+1} \delta_k \left( \epsilon_k oldsymbol{v}_1^{(k)} + \epsilon_{k'} oldsymbol{v}_1^{(k')} 
ight),$$

where

$$\delta_k = \begin{cases} \frac{1}{2}, & k = n_0 + 1, \\ 1, & 1 \le k \le n_0, \end{cases}$$

which reconciles the double counting of the term indexed  $k = n_0 + 1 = k'$ .



Then,

$$\begin{array}{lcl} \boldsymbol{e}_{1}^{\ell+1} & = & \mathsf{E}_{1}\boldsymbol{e}_{1}^{\ell} \\ & = & \sum_{k=1}^{n_{0}+1} \delta_{k} \left( \epsilon_{k} \alpha_{k} + \epsilon_{k'} \beta_{k} \right) \left( \boldsymbol{v}_{1}^{(k)} + \boldsymbol{v}_{1}^{(k')} \right). \end{array}$$

## Proof (Cont.)



Now, notice that the eigenvectors satisfy the orthogonality condition

$$\left(\mathbf{v}_{1}^{(i)},\mathbf{v}_{1}^{(j)}\right)_{1} = \sum_{m=1}^{n_{1}} \sin(i\pi x_{1,m})\sin(j\pi x_{1,m}) = \delta_{ij}\frac{n_{1}+1}{2}.$$

Using this orthogonality, one can prove, with a bit of care, that

$$\left\|\boldsymbol{e}_{1}^{\ell}\right\|_{1}^{2} = \left(\boldsymbol{e}_{1}^{\ell}, \boldsymbol{e}_{1}^{\ell}\right)_{1} = \frac{n_{1}+1}{2} \sum_{k=1}^{n_{0}+1} \delta_{k} \left(\epsilon_{k}^{2} + \epsilon_{k'}^{2}\right)$$
(16)

and

$$\begin{aligned} \left\| \mathbf{e}_{1}^{\ell+1} \right\|_{1}^{2} &= \left( \mathbf{e}_{1}^{\ell+1}, \mathbf{e}_{1}^{\ell+1} \right)_{1} \\ &= \left( \mathsf{E}_{1} \mathbf{e}_{1}^{\ell}, \mathsf{E}_{1} \mathbf{e}_{1}^{\ell} \right)_{1} \\ &= \left( n_{1} + 1 \right) \sum_{k=1}^{n_{0}+1} \delta_{k} \left( \epsilon_{k}^{2} \alpha_{k}^{2} + \epsilon_{k'}^{2} \beta_{k}^{2} + 2 \epsilon_{k} \epsilon_{k'} \alpha_{k} \beta_{k} \right). \end{aligned}$$
 (17)



## Proof (Cont.)

Once this last result is obtained, we can estimate:

$$\begin{aligned} \left\| \boldsymbol{e}_{1}^{\ell+1} \right\|_{1}^{2} &\stackrel{\mathrm{AGMI}}{\leq} & (n_{1}+1) \sum_{k=1}^{n_{0}+1} \delta_{k} \left\{ \epsilon_{k}^{2} \alpha_{k}^{2} + \epsilon_{k'}^{2} \beta_{k}^{2} + \left( \epsilon_{k}^{2} + \epsilon_{k'}^{2} \right) |\alpha_{k}| |\beta_{k}| \right\} \\ &\leq & (n_{1}+1) \sum_{k=1}^{n_{0}+1} \delta_{k} \left\{ \epsilon_{k}^{2} \left( \frac{1}{2} \right)^{2} + \epsilon_{k'}^{2} \left( \frac{1}{3} \right)^{2m_{1}} \right. \\ & \left. + \left( \epsilon_{k}^{2} + \epsilon_{k'}^{2} \right) \frac{1}{2} \left( \frac{1}{3} \right)^{m_{1}} \right\} \\ &= & (n_{1}+1) \sum_{k=1}^{n_{0}+1} \delta_{k} \left\{ \epsilon_{k}^{2} \left( \left( \frac{1}{2} \right)^{2} + \frac{1}{2} \left( \frac{1}{3} \right)^{m_{1}} \right) \right. \\ & \left. + \epsilon_{k'}^{2} \left( \left( \frac{1}{3} \right)^{2m_{1}} + \frac{1}{2} \left( \frac{1}{3} \right)^{m_{1}} \right) \right\}. \end{aligned}$$

Since.

$$\left(\frac{1}{3}\right)^{m_1} \leq \frac{1}{2},$$

we have

$$egin{array}{cccc} \left\|m{e}_{1}^{\ell+1}
ight\|_{1}^{2} & \leq & rac{n_{1}+1}{2}\left\{rac{1}{2}+\left(rac{1}{3}
ight)^{m_{1}}
ight\}\sum_{k=1}^{n_{0}+1}\delta_{k}\left(\epsilon_{k}^{2}+\epsilon_{k'}^{2}
ight) \ & = & \left\{rac{1}{2}+\left(rac{1}{3}
ight)^{m_{1}}
ight\}\left\|m{e}_{1}^{\ell}
ight\|_{1}^{2}. \end{array}$$

Finally,

$$\left\|oldsymbol{e}_1^{\ell+1}
ight\|_1 \leq \gamma(m_1)\left\|oldsymbol{e}_1^{\ell}
ight\|_1,$$

where

$$\gamma(m_1) := \left\{ \frac{1}{2} + \left(\frac{1}{3}\right)^{m_1} \right\}^{1/2}. \tag{18}$$



$m_1$	1	2	3	 $\infty$
$\gamma(m_1)$	0.91287	0.78176	0.73283	 0.70710

Table: Numerical values of  $\gamma(m_1)$ , defined in Equation (18), for certain values of the pre-smoothing number,  $m_1$ . It does not make much sense to use  $m_1 > 3$ , since the geometric convergence rate does not significantly improve, at least theoretically.

#### Remark

The key observation is that  $\gamma(m_1)$  is  $h_1$  independent. See the table above for guidance on choosing  $m_1$ .



## Some Computational Experiments

#### Experimental Setup



To conclude this chapter, let us perform some computational experiments to confirm the predicted convergence results. In particular, let us use the one-sided two-grid algorithm to approximate the solution of

$$\mathsf{A}_1 \textbf{\textit{u}}_1^\mathrm{E} = \textbf{\textit{f}}_1,$$

where  $A_1$  is the standard finite element stiffness matrix, defined in

$$a_{1,i,j} = (\psi'_{1,j}, \psi'_{1,i})_{L^2(0,1)} = (\psi'_{1,i}, \psi'_{1,j})_{L^2(0,1)}$$
(19)

for the model problem

$$\begin{cases}
-u'' = f, & \text{in } \Omega = (0,1), \\
u = 0, & \text{on } \partial\Omega = \{0,1\}.
\end{cases}$$
(20)

#### Experimental Setup



In our experiments, we specify the exact solution:

$$\left[\mathbf{u}_{1}^{\mathrm{E}}\right]_{i} = u_{1,i}^{\mathrm{E}} = \exp(\sin(3.0\pi * x_{1,i})) - 1.0.$$

In other words, we manufacture the force vector by setting  $\boldsymbol{f}_1 \coloneqq \mathsf{A}_1 \boldsymbol{u}_1^\mathrm{E}$ . We report on four particular computational experiments in the figures on the next two slides and a number of other experiments in the coming table. The initial approximation,  $\boldsymbol{u}_1^0$ , is chosen via pseudorandom number selection.

The Matlab code is listed in the book and can be downloaded from GitHub.



In experiment 1, we use the parameters  $\omega=2/3$  and  $m_1=3$ . The results are posted in the figures on the next three slides. The error reduction is plotted as a function of iteration, k, in the next figure. The computed error reduction factor,  $\gamma_{\rm comp}$ , is much better than the theoretically predicted value, almost 10 times smaller. This contraction factor is computed using a log-linear fit of the last four error values,

$$\left\| \boldsymbol{u}_{1}^{\mathrm{E}} - \boldsymbol{u}_{1}^{\ell} \right\|_{1}, \quad \ell = k_{\star} - 3, k_{\star} - 2, k_{\star} - 1, k_{\star},$$

where  $k_{\star}$  is that value of k at which the stopping tolerance is reached. For our experiments, the stopping tolerance is achieved when

$$\left\| \boldsymbol{u}_{1}^{\mathrm{E}} - \boldsymbol{u}_{1}^{k_{\star}} \right\|_{1} \leq 1.0 \times 10^{-09}.$$

Stopping using the exact error is not practical. But our, computations show that the norm of the coarse grid correction is a good indicator of the error.



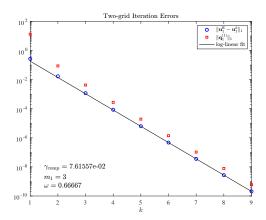


Figure: The error reduction for the one-sided two-grid algorithm, using the parameters  $\omega=2/3,\ m_1=3,$  and  $n_1=255.$  The computed error reduction factor,  $\gamma_{\rm comp}$ , is much better than the theoretically predicted value, almost 10 times smaller. The factor  $\gamma_{\rm comp}$  is computed using a log-linear fit of the last four error values. Note that the norm of the coarse grid correction is a good indicator of the error.



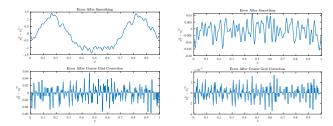


Figure: The errors after pre-smoothing and after coarse grid correction for the one-sided two-grid algorithm at iterations k=1 (left two plots) and k=2 (right two plots), using the parameters  $\omega=2/3$ ,  $m_1=3$ , and  $n_1=255$ . See the figure one slide ago.

The error function after pre-smoothing,  $u_1^{\rm E}(x_{1,i})-u_1^{(1)}(x_{1,i})$ , and after coarse grid correction,  $u_1^{\rm E}(x_{1,i})-u_1^{(2)}(x_{1,i})$ , for iterations k=1 through k=4. Notice that the smoothing operation really does "smooth" the error. Applying the coarse grid correction then drastically reduces the error, but it reintroduces some high frequency error. These are later squashed by smoothing, et cetera.



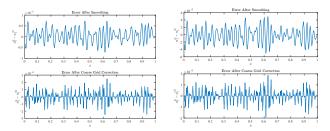


Figure: The errors after pre-smoothing and after coarse grid correction for the one-sided two-grid algorithm at iterations k=3 (left two plots) and k=4 (right two plots), using the parameters  $\omega=2/3$ ,  $m_1=3$ , and  $n_1=255$ . See the figure two slides ago.

The error function after pre-smoothing,  $u_1^{\rm E}(x_{1,i})-u_1^{(1)}(x_{1,i})$ , and after coarse grid correction,  $u_1^{\rm E}(x_{1,i})-u_1^{(2)}(x_{1,i})$ , for iterations k=1 through k=4. Notice that the smoothing operation really does "smooth" the error. Applying the coarse grid correction then drastically reduces the error, but it reintroduces some high frequency error. These are later squashed by smoothing, et cetera.



In experiment 2, we use the parameters  $\omega=2/3$  and  $m_1=10$ . The error reduction is plotted as a function of the two-grid iteration number, k, in the figure on the next page. The computed error contraction factor  $\gamma_{\rm comp}$  is calculated as in experiment 1, and is smaller than the factor from experiment 1. Doing more smoothing iterations reduces the error contraction factor  $\gamma_{\rm comp}$ , but there is a diminishing return with this effort.



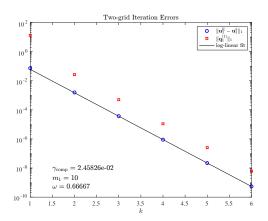


Figure: The error reduction for the one-sided two-grid algorithm, using the parameters  $\omega=2/3$ ,  $m_1=10$ , and  $n_1=255$ . The factor  $\gamma_{\rm comp}$  is computed using a log-linear fit of the last four error values. Compare this rate with that from the previous fugure.



In experiment 3, we use the parameters  $\omega=1/2$  and  $m_1=3$ . The computed error contraction factor  $\gamma_{\rm comp}$  is larger than that of experiment 1. In the next chapter, we will discuss the use of the parameter  $\omega=1/2$  in the damped Jacobi smoother. See the table at the end of the slides for the computed error contraction factors,  $\gamma_{\rm comp}$ , for several different values of  $\omega$ .



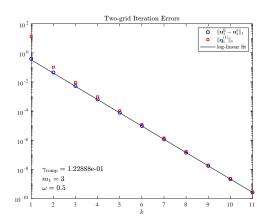


Figure: The error reduction for the one-sided two-grid algorithm, using the parameters  $\omega=1/2,\ m_1=3,$  and  $n_1=255.$  The factor  $\gamma_{\rm comp}$  is computed using a log-linear fit of the last four error values. Compare to experiment 1, and it appears that  $\omega=0.5$  is not optimal.



In experiment 4, we use the parameters  $\omega=2/3$  and  $m_1=20$ . The error reduction is plotted as a function of the two-grid iteration number, k, in the figure on the next page. The computed error contraction factor  $\gamma_{\rm comp}$  is calculated as in experiment 1, and is smaller than that computed in experiments 1 ( $m_1=3$ ) and 2 ( $m_1=10$ ).



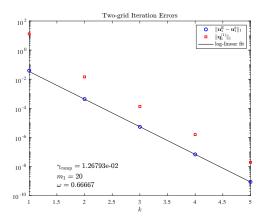


Figure: The error reduction for the one-sided two-grid algorithm, using the parameters  $\omega=2/3$ ,  $m_1=20$ , and  $n_1=255$ . The factor  $\gamma_{\rm comp}$  is computed using a log-linear fit of the last four error values. Compare this rate with those from previous figures. There is a diminishing return for doing more pre-smoothing steps. The convergence factor  $\gamma_{\rm comp}$  is reduced, but not by much. See the table on the last page.



Doing 20 pre-smoothing steps is not practical. But this experiment shows the (exaggerated) smoothing effect of the damped Jacobi method with a large number of pre-smoothing steps. See the figures on the next two pages.



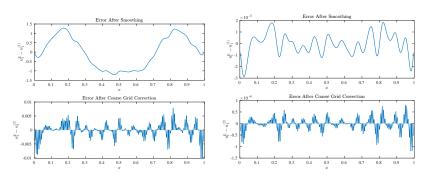


Figure: The errors after pre-smoothing and after coarse grid correction for the one-sided two-grid algorithm at iterations k=1 (left two plots) and k=2 (right two plots), using the parameters  $\omega=2/3$ ,  $m_1=20$ , and  $n_1=255$ . This is an exaggerated number of pre-smoothing steps. Compare with experiment 1.



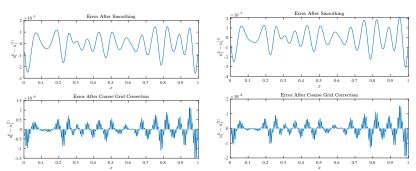


Figure: The errors after pre-smoothing and after coarse grid correction for the one-sided two-grid algorithm at iterations k=3 (left two plots) and k=4 (right two plots), using the parameters  $\omega=2/3$ ,  $m_1=20$ , and  $n_1=255$ . This is an exaggerated number of pre-smoothing steps. We use this this exaggeration to show the error "smoothing" effect of the pre-smoothing operation.

## Summary of the experiments



Finally, a number of further computational experiments are summarized in the table at the end of the slides. We report only the computed contraction factor  $\gamma_{\rm comp}.$  Doing experiments like this for known solutions can help users tune the parameters in their codes for close-to-optimal performance.

## Summary of the experiments



$n_1$	ω	m <sub>1</sub>	$\gamma_{\rm comp}$
63	2/3	3	$7.48 \times 10^{-02}$
127	2/3	3	$7.50 \times 10^{-02}$
255	2/3	3	$7.62 \times 10^{-02}$
511	2/3	3	$7.55 \times 10^{-02}$
1023	2/3	3	$7.50 \times 10^{-02}$
127	2/3	5	$4.84 \times 10^{-02}$
127	2/3	7	$3.54 \times 10^{-02}$
127	2/3	9	$2.70 \times 10^{-02}$
127	2/3	11	$2.22 \times 10^{-02}$
127	2/3	13	$1.88 \times 10^{-02}$
127	2/3	15	$1.62 \times 10^{-02}$
127	0.40	3	$2.12 \times 10^{-01}$
127	0.45	3	$1.62 \times 10^{-01}$
127	0.50	3	$1.23 \times 10^{-01}$
127	0.55	3	$9.75 \times 10^{-02}$
127	0.60	3	$8.47 \times 10^{-02}$
127	0.65	3	$7.73 \times 10^{-02}$
127	0.70	3	$6.91 \times 10^{-02}$
127	0.75	3	$1.22 \times 10^{-01}$
127	0.80	3	$2.13 \times 10^{-01}$

Table: Computed two-grid convergence factors,  $\gamma_{\rm comp}$ , for various parameter choices. The factor  $\gamma_{\rm comp}$  is computed using a log-linear fit of the last four error values  $\| {m u}_{\rm L}^{\rm E} - {m u}_{\rm L}^k \|_1$ .