

$$+ \frac{I(\bar{A} = \bar{a})}{g(0)} \left[Y - \underbrace{E[Y^a | \bar{L}(1), \bar{A}(1) = \bar{a}]}_{\bar{Q}_1^a(\bar{L}(1))} \right]$$

As, summary result,

$$\begin{aligned} D^*(0) &= [E[Y^a | L(0)] - \psi] + \frac{\pm(A=a)}{g_0(0)} [\bar{Q}_1^a(\bar{L}(0))] - \mathbb{E}[\bar{Q}_1^a(\bar{L}(1)) | L(0), A(0) = a(0)] \\ &\quad + \frac{\pm(A=\bar{a})}{g(0)} [Y - E[Y^a | \bar{L}(1), \bar{A}(1) = \bar{a}]] \end{aligned}$$

$$\text{Our form is } \psi(Q) = \mathbb{E}_{P^a}[Y^a] = E[E[E(Y^a | \bar{L}(1)) | L(0)]]$$

$$\begin{aligned} \text{Note: } P^a &= Q_0^a Q_1^a Q_2^a \\ &= \cancel{P(0)} P(\bar{Q}(0)) \cdot P(\bar{L}(1) | L(0), A(0)) \cdot P(\bar{L}(2) | \bar{L}(1), \bar{A}(1) = \bar{a}(1)) \end{aligned}$$

$$= E \left[E \left[E[Y | \bar{L}(1), \bar{A}(1) = \bar{a}(1)] | L(0), A(0) = a(0) \right] \right]$$

Algorithm

- ① $\bar{Q}_1^a = E[Y | \bar{L}(1), \bar{A}(1) = \bar{a}(1)]$
- ② $\bar{Q}_2^a = E[\bar{Q}_1^a | L(0), A(0) = a(0)]$
- ③ $\bar{Q}_0^a = E[\bar{Q}_1^a] \rightarrow \psi(Q) = \bar{Q}_0^a$

Read his paper!

11/15/2011 Note: Skipped last few classes to prepare for GRE
 * Taught mainly out of slides today

$$\begin{aligned} L_1(t+1) &= L_1(t) \exp(m_1(t)\Delta t) \Rightarrow S_1(t) = \exp(m_1(t)\Delta t) \\ L_2(t+1) &= L_2(t) \exp(m_2(t)\Delta t) \quad S_2(t) = \exp(m_2(t)\Delta t) \end{aligned}$$

↓

$$\frac{\log[S_1(t)]}{\log[S_2(t)]} = \beta$$

Read H Bang, J Robins paper

↳ Doubly robust estimation in missing data & causal inference models

Back to basics: Consider simple WY data

$$\frac{\text{IPTW}}{P_{\text{IPW}}} = \frac{E\left[\left(\frac{I(A=1)}{g(1|w)} - \frac{I(A=0)}{g(0|w)}\right) Y\right]}{E\left[\left(\frac{I(A=1)}{g(1|w)} - \frac{I(A=0)}{g(0|w)}\right)\right]}$$

$$\frac{\text{TMLE}}{\bar{\psi}_{\text{TMLE}}} = \Psi(\bar{Q}_n^*, Q_{w,n}) = \frac{1}{n} \sum_{i=1}^n [\bar{Q}_n^*(1, w_i) - \bar{Q}_n^*(0, w_i)]$$

To beat an estimator:

consider $\hat{\psi}^* - \psi^* = \frac{1}{n} \sum_{i=1}^n D^*(P_i)(O_i)$

↑
estimator we want to beat

IC of $\hat{\psi}^*$

We construct $Q_n^*, g_n \ni P_n D^*(Q_n^*, g_n) = 0$

$P_n D^*(Q_n^*, g_n) = 0 \Leftarrow$ solving this egn verifies that it at least match the estimator we want to beat.

In previous paper, updated est. by

$$\hat{P}_n(A=1|w) = \frac{1}{1 + \exp\{\text{logit } \hat{g}^*(1|w) + c_2 \left[\frac{\bar{Q}(1|w)}{g(1|w)} + \frac{\bar{Q}(0|w)}{g(0|w)} \right]\}}$$

We solve score egn: $P_n \underbrace{\left(\frac{Q_n^*(1,w)}{g_n^*(1,w)} + \frac{Q_n^*(0,w)}{g_n^*(0,w)} \right) (A_i - g_n^*(1|w))}_{D_{\text{CAR}}^*(\bar{Q}_n^*, g_n^*)} = 0$

Note: Every IC can be written as $D^* = D_{\text{IPW}}^* + D_{\text{CAR}}^*$

$$P_n D^*(Q_n^*, g_n^*) = 0 \Rightarrow P_n D_{\text{IPW}}^*(Q_n^*, g_n^*) = 0 \Rightarrow \psi(Q_n^*) = P_n \left(\frac{I(A=1)}{g_n^*(1|w)} - \frac{I(A=0)}{g_n^*(0|w)} \right) Y$$

So! The TMLE is also an IPTW estimator!
 (paper from 2006)

∴ For any estimator, can find IC and apply TMLE to guarantee that we beat original estimator