

Ivan's stochastic interventions

9/29/2011

for $O = (w, A, Y)$

$$\left. \begin{array}{l} w = f_w(u_w) \\ A = f_A(w, u_A) \\ Y = f_Y(w, A, u_Y) \end{array} \right\} \text{to intervene, set } A \text{ rather than } w \text{ in the equation} \Rightarrow Y_i = f_Y(w_i, 1, u_Y)$$

Can be rewritten

$$\left. \begin{array}{l} w = f_w(u_w) \\ A = \begin{cases} 1 & \text{prob } 1 \\ 0 & \text{prob } 0 \end{cases} \\ Y = f_Y(w, 1, u_Y) \end{array} \right\}$$

Question: Why not set $A = \begin{cases} 1 & \text{w/ prob } P(w) \\ 0 & \text{w/ prob } 1 - P(w) \end{cases}$?

↑ probabilities of getting intervention

So, new notation: $w = f_w(u_w)$

$$A_{PS} = a \text{ w/ prob } P_S(g_0)(A=a, w)$$

$$Y_{PS} = f_Y(A_{PS}, w, u_Y)$$

$$P(O) = P(Y|A, w) P(A|w) P(w)$$

$$P(A|w) = g(A|w)$$

$$P(w) = Q_w(w)$$

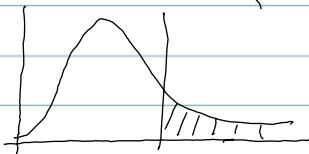
$$E(Y|A, w) = \bar{Q}(A, w)$$

$$\text{Example: } 1) P_S(g_0)(A, w) = g_0(A - \delta(w)/w)$$

↑
will only focus on this today

$$2) P_S(g_0)(A=a, w) = \begin{cases} g_0(a/w) & \text{if } a < \delta \\ \sum_{a \geq \delta} g_0(a/w) & \text{if } a = \delta \\ 0 & \text{if } a > \delta \end{cases}$$

shifts +x as function of covariates



⇒



↑ all obs on right set to this value
(in this ex., = 0)

Dealing w/ parameter, can est.

$$E(Y_{PS}) \text{ or } E(Y_{PS} - Y) = E(Y_{PS}) - E(Y)$$

already well known, so can throw out.

So, $E(Y_{ps}) = \sum_y y P(Y_{ps} = y)$, by def of expectation

Assumptions

- 1) $A \perp Y_a | w \wedge a \in A$ (RA assumption)
- 2) $Y = Y_a \Rightarrow$ if $A = a$, then $Y_a = y$ (def of counterfactuals)

$$\begin{aligned} P(Y_{ps} = y) &= \sum_a \sum_w P(Y_{ps}, A_{ps}, w) \\ &= \sum_a \sum_w \underbrace{P(Y_{ps} = y | A_{ps} = a, w = w)}_{\text{need to identify}} \underbrace{P(A_{ps} = a | w = w)}_{P_g(g)(A=a|w)} \underbrace{P(w = w)}_{Q_u(w)} \end{aligned}$$

Note, 1) $A_{ps} = a \Rightarrow Y_{ps} = Y_a$

\hookrightarrow comes from consistency def. (assumption #2)

2) $A \perp Y_a | w \Rightarrow A_{ps} \perp Y_a | w$

* think of $A_{ps} = A - S(w)$

\hookrightarrow comes from assumption #1

$\Rightarrow P(Y_a = y | A_{ps} = a, w = w)$, from note #1

$$= P(Y_a = y | w = w) = P(Y = y | A = a, w = w)$$

\Rightarrow Identifiability satisfied

$$(*) \text{ So, } E(Y_{ps}) = \psi(p) = \sum_y \sum_a \sum_w y P(Y = y | A = a, w = w) g(a - S(w) | w) Q_u(w)$$

$$= E_p \left[\frac{g_0(A - S(w))}{g(A/w)} y \right] \text{ depends on } g(A/w)$$

$$= E_p \left[\bar{Q}(A + \delta, w) \right] \text{ depends on } \bar{Q}(A, w)$$

* Recall: EC of $\psi(p)$ is the gradient

\hookrightarrow Another way of getting IC: $\frac{\partial \psi(p(\epsilon))}{\partial \epsilon} \Big|_{\epsilon=0} = E[\bar{Q}(0)S(0)]$

1st, define class of parametric submodels

$$\hookrightarrow p(\epsilon)(y | A, w) = [1 + c s_y(w, A, \epsilon)] P(Y = y | A, w) \quad \left\{ E[s_y | A, w] = 0 \right.$$

$$g(\epsilon)(A | w) = [1 + c s_A(w, A, \epsilon)] P(A | w) \quad \left\{ E[s_A | w] = 0 \right.$$

$$q_w(\epsilon)(w) = [1 + \epsilon s_w(w)] Q_w(w) \quad \left\{ E[s_w] = 0 \right.$$

$$\text{Note: } P_\epsilon(\epsilon) = P_y(\epsilon) g(\epsilon) Q_w(\epsilon)$$

$$= s_y + s_A + s_w \\ \underbrace{s_y + s_A + s_w}_{= S(0)}, \text{ the score}$$

$$T(p) = L^2(p)$$

Going back to $\frac{\partial}{\partial \epsilon} \Psi(P(\epsilon))|_{\epsilon=0}$

$$\hookrightarrow \Psi(P(\epsilon)) = \sum_y \sum_a \sum_w Y(1 + \epsilon s_y(w, a, y)) P(Y|a, w) \\ (1 + \epsilon s_A(a - \delta, w)) g(a - \delta|w) \\ (1 + \epsilon s_w(w)) Q_w(w)$$

Note: all we've done is replace functions in (*) w/ our score fns.

$$\hookrightarrow \frac{\partial}{\partial \epsilon} \Psi(P(\epsilon))|_{\epsilon=0} = \sum_y \sum_a \sum_w Y(s_y(w, a, y) + s_A(a - \delta, w) + s_w(w)) P(Y|a, w) g(a - \delta|w) Q_w(w) \\ = \sum_y \sum_a \sum_w Y \frac{g(a - \delta|w)}{g(a|w)} (s_y + s_w) P(Y|a, w) g(a|w) Q_w(w) \xrightarrow{P} \\ + \sum_y \sum_a \sum_w Y s_A(a - \delta, w) P(Y|a, w) g(a - \delta|w) Q_w(w) \\ \xrightarrow{(**) \text{ need to figure this out} \Rightarrow \text{let } a' = a - \delta} \\ \Rightarrow (*) = \sum_{a' w y} Y P(Y|a' + \delta, w) s_A(a'|w) g(a'|w) Q_w(w) \\ = \sum_a \sum_w \bar{Q}(a + \delta, w) s_A g(a|w) Q_w(w) \\ = E_p [\bar{Q}(A + \delta, w) s_A]$$

$$\text{So, } \frac{\partial}{\partial \epsilon} \Psi(P(\epsilon))|_{\epsilon=0} = E_p \left[\frac{g(A - \delta|w)}{g(A|w)} Y(s_y + s_w) \right] + E_p [\bar{Q}(A + \delta, w) s_A] \\ = E_p \left[\left(\frac{g(A - \delta|w)}{g(A|w)} Y + \bar{Q}(A + \delta, w) \right) (s_y + s_w + s_A) \right] \\ - E_p \left[\frac{g(A - \delta|w)}{g(A|w)} Y s_A \right] - E_p [\bar{Q}(A + \delta, w) s_w]$$

10/11/2011 Oracle selector = defined by looking at true risk of candidate applied to training sample \Rightarrow and min true risk.

For loss: $L(\hat{Q}_k, Q_0) = P_0 L(\hat{Q}_k) - \underbrace{P_0 L(Q_0)}_{\min \text{ at } Q_0}$
 dissimilarities

tells us we will do as well as oracle,
 * loss function has to be uniformly bounded.

CV-Risk: $E_{P_n} [P_n B_n L(\hat{Q}_k, P_n B_n)]$

Auger learner

$$\hat{Q}_K : M_{np} \rightarrow \mathbb{R} \\ \Rightarrow \left\{ \sum_{k=1}^K \alpha_k \hat{Q}_k, \hat{\alpha} \right\} \Rightarrow$$

we want estimator

$$\alpha_n = \operatorname{argmin}_{\alpha} E_{B_n} [P_n B_n L(\hat{Q}_k(P_n B_n))]$$