Binary Search Trees

Review: Dynamic Sets

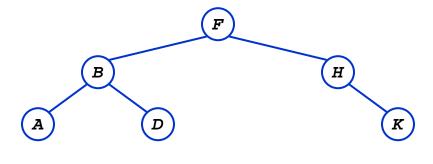
- Next few lectures will focus on data structures rather than straight algorithms
- In particular, structures for *dynamic sets*
 - Elements have a key and satellite data
 - Dynamic sets support *queries* such as:
 - Search(S, k), Minimum(S), Maximum(S),
 Successor(S, x), Predecessor(S, x)
 - They may also support *modifying operations* like:
 - \circ *Insert*(S, x), *Delete*(S, x)

Review: Binary Search Trees

- Binary Search Trees (BSTs) are an important data structure for dynamic sets
- In addition to satellite data, elements have:
 - key: an identifying field inducing a total ordering
 - *left*: pointer to a left child (may be NULL)
 - right: pointer to a right child (may be NULL)
 - *p*: pointer to a parent node (NULL for root)

Review: Binary Search Trees

- BST property: key[leftSubtree(x)] ≤ key[x] ≤ key[rightSubtree(x)]
- Example:



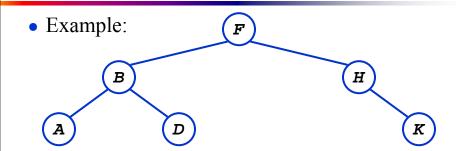
Inorder Tree Walk

• What does the following code do?

```
TreeWalk(x)
    TreeWalk(left[x]);
    print(x);
    TreeWalk(right[x]);
```

- A: prints elements in sorted (increasing) order
- This is called an *inorder tree walk*
 - *Preorder tree walk*: print root, then left, then right
 - Postorder tree walk: print left, then right, then root

Inorder Tree Walk



- How long will a tree walk take?
- Prove that inorder walk prints in monotonically increasing order

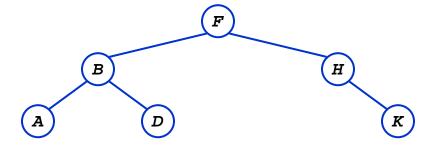
Operations on BSTs: Search

• Given a key and a pointer to the root node, returns an element with that key or NULL:

```
TreeSearch(x, k)
   if (x = NULL or k = key[x])
      return x;
   if (k < key[x])
      return TreeSearch(left[x], k);
   else
      return TreeSearch(right[x], k);</pre>
```

BST Search: Example

• Search for *D* and *C*:



Operations on BSTs: Search

• Here's another function that does the same:

```
TreeSearch(x, k)
    while (x != NULL and k != key[x])
        if (k < key[x])
            x = left[x];
    else
            x = right[x];
    return x;</pre>
```

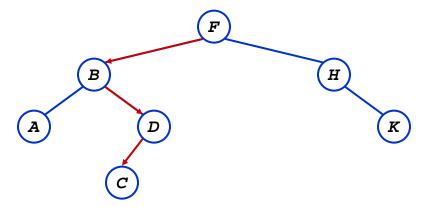
• Which of these two functions is more efficient?

Operations with BST: Insert

- Adds an element x to the tree so that the binary search tree property continues to hold
- The basic algorithm
 - Like the search procedure above
 - Insert x in place of NULL
 - Use a "trailing pointer" to keep track of where you came from (like inserting into singly linked list)
- Like search, takes time O(h), h =tree height

BST Insert: Example

• Example: Insert *C*



BST Search/Insert: Running Time

- What is the running time of TreeSearch() or TreeInsert()?
- A: O(h), where h = height of tree
- What is the height of a binary search tree?
- A: worst case: h = O(n) when tree is just a linear string of left or right children
 - We'll keep all analysis in terms of h for now
 - Later we'll see how to maintain $h = O(\lg n)$

Sorting With Binary Search Trees

• Informal code for sorting array A of length n: BSTSort(A)

```
for i=1 to n
    TreeInsert(A[i]);
InorderTreeWalk(root);
```

- What will be the running time in the
 - Worst case?
 - Average case? (hint: remind you of anything?)

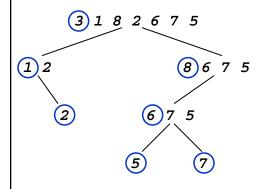
Sorting With Binary Search Trees – contd.

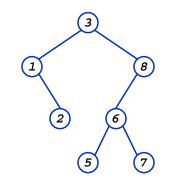
- Worst case: $\Theta(n^2)$ occurs when a linear chain of nodes results from the repeated **TreeInsert** operations.
- Best case: $\Theta(n \mid g \mid n)$ occurs when a binary tree of height $\Theta(\lg n)$ results from the repeated **TreeInsert** operations.

Sorting With BSTs

- Average case analysis
 - It's a form of quicksort!

for i=1 to n
 TreeInsert(A[i]);
InorderTreeWalk(root);





Sorting with BSTs

- Same partitions are done as with quicksort, but in a different order
 - In previous example
 - Everything was compared to 3 once
 - Then those items < 3 were compared to 1 once
 - o Etc.
 - Same comparisons as quicksort, different order!
 - Example: consider inserting 5

Sorting with BSTs

- Since run time is proportional to the number of comparisons, same time as quicksort: O(n lg n)
- Which do you think is better, quicksort or BSTsort? Why?

Sorting with BSTs

- Since run time is proportional to the number of comparisons, same time as quicksort: O(n lg n)
- Which do you think is better, quicksort or BSTSort? Why?
- A: quicksort
 - Better constants
 - Sorts in place
 - Doesn't need to build data structure

Review: Sorting With BSTs

- Basic algorithm:
 - Insert elements of unsorted array from 1..n
 - Do an inorder tree walk to print in sorted order
- Running time:
 - Best case: $\Omega(n \lg n)$ (it's a comparison sort)
 - Worst case: O(n²)
 - Average case: $O(n \lg n)$ (it's a quicksort!)

More BST Operations

- BSTs are good for more than sorting. For example, can implement a priority queue
- What operations must a priority queue have?
 - Insert
 - Minimum
 - Extract-Min

More BST Operations

- Minimum:
 - Find leftmost node in tree
- Successor:
 - x has a right subtree: successor is minimum node in right subtree
 - x has no right subtree: successor is first ancestor of x whose left child is also ancestor of x
 - Intuition: As long as you move to the left up the tree, you're visiting smaller nodes.
- Predecessor: similar to successor

BST Operations: Minimum

- How can we implement a Minimum() query?
- What is the running time?

BST Operations: Successor

- For deletion, we will need a Successor() operation
- Draw Fig 12.2
- What is the successor of node 3? Node 15? Node 13?
- What are the general rules for finding the successor of node x? (hint: two cases)

Deletion is a bit tricky 3 cases: x has no children: Remove x x has one child: Splice out x x has two children: Swap x with successor

o Perform case 1 or 2 to delete it

BST Operations: Delete

- Why will case 2 always go to case 0 or case 1?
- A: because when x has 2 children, its successor is the minimum in its right subtree
- Could we swap x with predecessor instead of successor?
- A: yes. Would it be a good idea?
- A: might be good to alternate

The End

• Up next: guaranteeing a O(lg n) height tree