

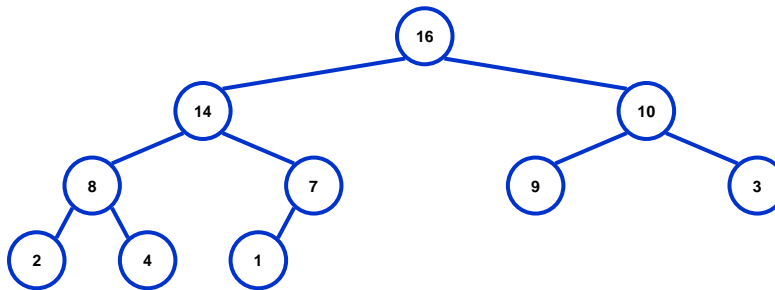
Heapsort

Sorting Revisited

- So far we've talked about two algorithms to sort an array of numbers
 - What is the advantage of merge sort?
 - ◆ Answer: $O(n \lg n)$ worst-case running time
 - What is the advantage of insertion sort?
 - ◆ Answer: sorts in place
 - ◆ Also: When array “nearly sorted”, runs fast in practice
- Next on the agenda: *Heapsort*
 - Combines advantages of both previous algorithms

Heaps

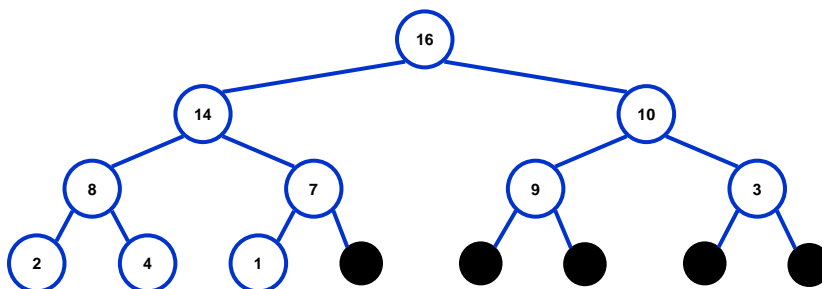
- A *heap* can be seen as a complete binary tree:



- *What makes a binary tree complete?*
- *Is the example above complete?*

Heaps

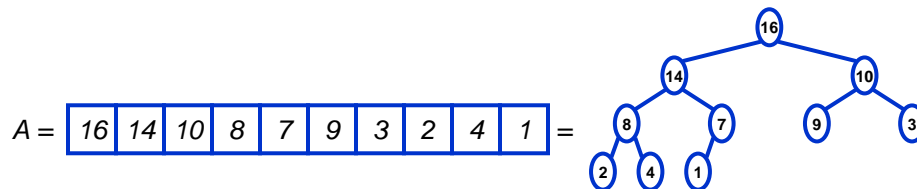
- A *heap* can be seen as a complete binary tree:



- The book calls them “nearly complete” binary trees; can think of unfilled slots as null pointers

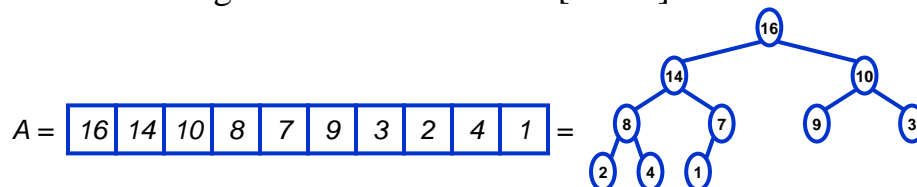
Heaps

- In practice, heaps are usually implemented as arrays:



Heaps

- To represent a complete binary tree as an array:
 - The root node is $A[1]$
 - Node i is $A[i]$
 - The parent of node i is $A[i/2]$ (note: integer divide)
 - The left child of node i is $A[2i]$
 - The right child of node i is $A[2i + 1]$



Referencing Heap Elements

- So...

```
Parent(i) { return  $\lfloor i/2 \rfloor$ ; }  
Left(i) { return 2*i; }  
right(i) { return 2*i + 1; }
```

The Heap Property

- Heaps also satisfy the *heap property*:

$A[\textit{Parent}(i)] \geq A[i]$ for all nodes $i > 1$

- In other words, the value of a node is at most the value of its parent
- *Where is the largest element in a heap stored?*

Heap Height

- Definitions:
 - The *height* of a node in the tree = the number of edges on the longest downward path to a leaf
 - The height of a tree = the height of its root
- *What is the height of an n -element heap? Why?*
- This is nice: basic heap operations take at most time proportional to the height of the heap

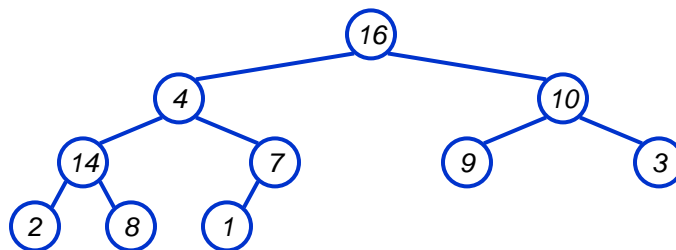
Heap Operations: Heapify()

- **Heapify()**: maintain the heap property
 - Given: a node i in the heap with children l and r
 - Given: two subtrees rooted at l and r , assumed to be heaps
 - Problem: The subtree rooted at i may violate the heap property in the **HeapSort()** algorithm.
 - Action: let the value of the parent node “float down” so subtree at i satisfies the heap property
 - ◆ *What do you suppose will be the basic operation between i , l , and r ?*

Heap Operations: Heapify()

```
Heapify(A, i)
{
    l = Left(i); r = Right(i);
    if (l <= heap_size(A) && A[l] > A[i])
        largest = l;
    else
        largest = i;
    if (r <= heap_size(A) && A[r] > A[largest])
        largest = r;
    if (largest != i)
        Swap(A, i, largest);
    Heapify(A, largest);
}
```

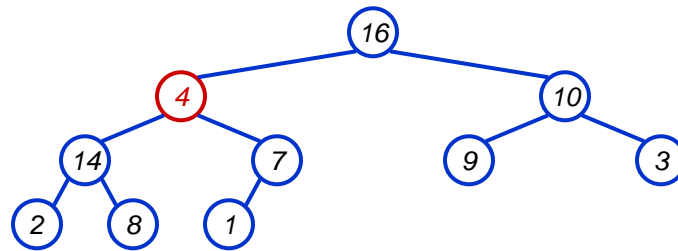
Heapify() Example



A =

16	4	10	14	7	9	3	2	8	1
----	---	----	----	---	---	---	---	---	---

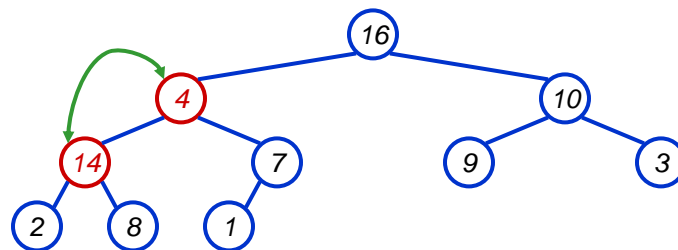
Heapify() Example



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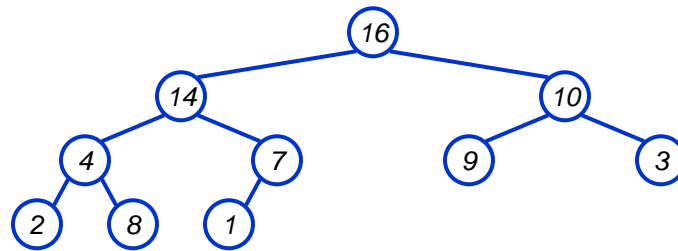
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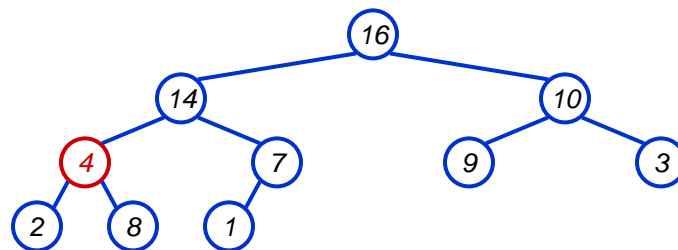
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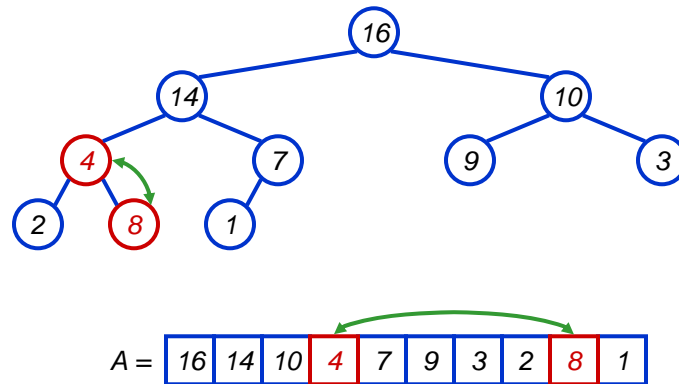
Heapify() Example



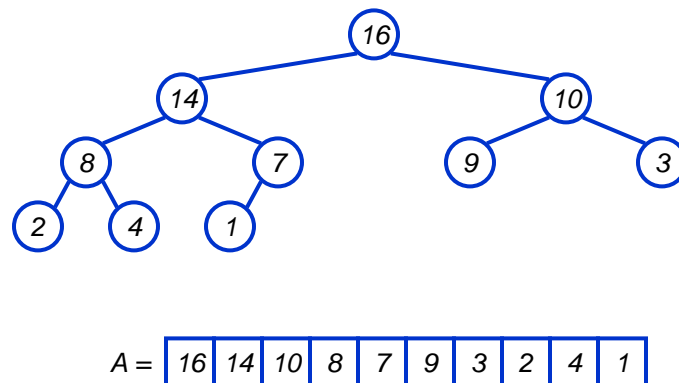
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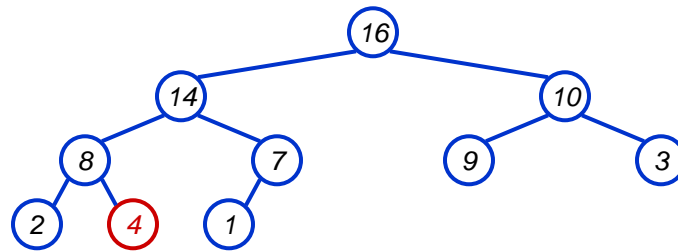
Heapify() Example



Heapify() Example



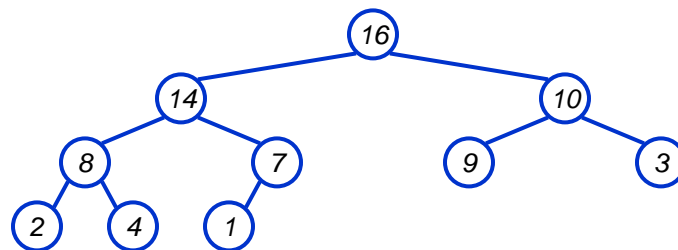
Heapify() Example



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Heapify() Example



A =

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Analyzing Heapify(): Informal

- *Aside from the recursive call, what is the running time of **Heapify()**?*
- *How many times can **Heapify()** recursively call itself?*
- *What is the worst-case running time of **Heapify()** on a heap of size n ?*

Analyzing Heapify(): Intuitive

- Heap is almost-complete binary tree, hence must process $T(n) = O(\lg n)$ levels.
- Thus, **Heapify()** takes logarithmic time

Heap Operations: BuildHeap()

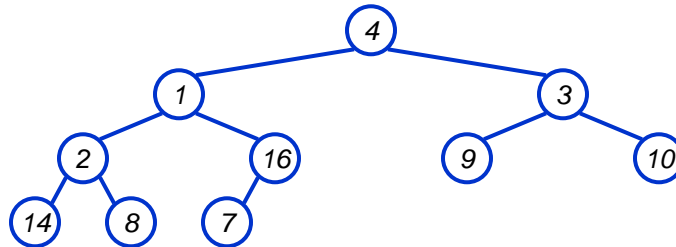
- We can build a heap in a bottom-up manner by running **Heapify()** on successive subarrays
 - Fact: for array of length n , all elements in range $A[\lfloor n/2 \rfloor + 1 .. n]$ are heaps (*Why?*)
 - So:
 - ◆ Walk backwards through the array from $n/2$ to 1, calling **Heapify()** on each node.
 - ◆ Order of processing guarantees that the children of node i are heaps when i is processed

BuildHeap()

```
// given an unsorted array A, make A a heap
BuildHeap(A)
{
    heap_size(A) = length(A);
    for (i =  $\lfloor \text{length}[A]/2 \rfloor$  downto 1)
        Heapify(A, i);
}
```

BuildHeap() Example

- Work through example
 $A = \{4, 1, 3, 2, 16, 9, 10, 14, 8, 7\}$



Analyzing BuildHeap()

- Each call to **Heapify()** takes $O(\lg n)$ time
- There are $O(n)$ such calls (specifically, $\lfloor n/2 \rfloor$)
- Thus the running time is $O(n \lg n)$
 - *Is this a correct asymptotic upper bound?*
 - *Is this an asymptotically tight bound?*
- A tighter bound is $O(n)$
 - *How can this be? Is there a flaw in the above reasoning?*

Analyzing BuildHeap(): Tight

- To **Heapify()** a subtree takes $O(h)$ time where h is the height of the subtree
 - $h = O(\lg m)$, $m = \#$ nodes in subtree
 - The height of most subtrees is small
- Fact: an n -element heap has at most $\lceil n/2^{h+1} \rceil$ nodes of height h
- CLR 7.3 uses this fact to prove that **BuildHeap()** takes $O(n)$ time

Heapsort

- Given **BuildHeap()**, an in-place sorting algorithm is easily constructed:
 - Maximum element is at $A[1]$
 - Discard by swapping with element at $A[n]$
 - ◆ Decrement $\text{heap_size}[A]$
 - ◆ $A[n]$ now contains correct value
 - Restore heap property at $A[1]$ by calling **Heapify()**
 - Repeat, always swapping $A[1]$ for $A[\text{heap_size}(A)]$

Heapsort

```
Heapsort(A)
{
    BuildHeap(A);
    for (i = length(A) downto 2)
    {
        Swap(A[1], A[i]);
        heap_size(A) -= 1;
        Heapify(A, 1);
    }
}
```

Analyzing Heapsort

- The call to **BuildHeap()** takes $O(n)$ time
- Each of the $n - 1$ calls to **Heapify()** takes $O(\lg n)$ time
- Thus the total time taken by **HeapSort()**
 $= O(n) + (n - 1) O(\lg n)$
 $= O(n) + O(n \lg n)$
 $= O(n \lg n)$

Priority Queues

- Heapsort is a nice algorithm, but in practice Quicksort (coming up) usually wins
- But the heap data structure is incredibly useful for implementing *priority queues*
 - A data structure for maintaining a set S of elements, each with an associated value or *key*
 - Supports the operations **Insert**(), **Maximum**(), and **ExtractMax**()
 - *What might a priority queue be useful for?*

Priority Queue Operations

- **Insert**(S, x) inserts the element x into set S
- **Maximum**(S) returns the element of S with the maximum key
- **ExtractMax**(S) removes and returns the element of S with the maximum key
- *How could we implement these operations using a heap?*