Elementary Graph Algorithms - contd.

Graphs

- Motivation and Terminology
- Representations
- Traversals

Traversing a Graph

One of the most fundamental graph problems is to traverse every edge and vertex in a graph. Applications include:

- Printing out the contents of each edge and vertex.
- Counting the number of edges.
- Identifying connected components of a graph.

For *correctness*, we must do the traversal in a systematic way so that we don't miss anything.

For *efficiency*, we must make sure we visit each edge at most twice.

Marking Vertices

The idea in graph traversal is that we mark each vertex when we first visit it, and keep track of what is not yet completely explored.

For each vertex, we maintain two flags:

- ***discovered*** - have we encountered this vertex before?
- ***explored*** - have we finished exploring this vertex?

We must maintain a structure containing all the vertices we have discovered but not yet completely explored.

Initially, only a single start vertex is set to be discovered.

Correctness of Graph Traversal

Every edge and vertex in the connected component is eventually visited.

Suppose not, i.e. there exists a vertex which was unvisited whose neighbor *was* visited. This neighbor will eventually be explored so we *would* visit it….

Traversal Orders

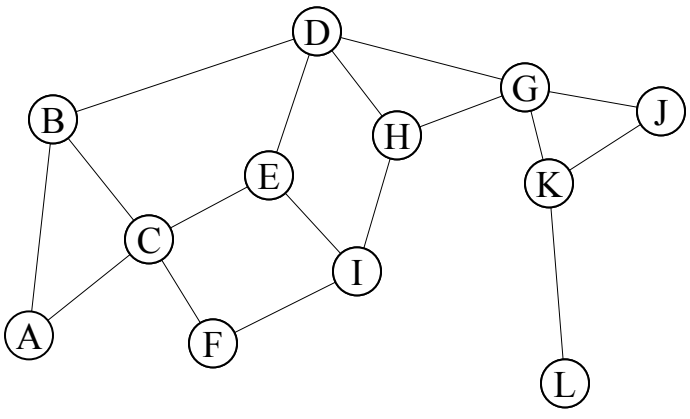
The order we explore the vertices depends upon the data structure used to hold the discovered vertices yet to be fully explored:

- ***Queue*** - by storing the vertices in a first-in, first out (FIFO) queue, we explore the oldest unexplored vertices first. Thus we radiate out slowly from the starting vertex, defining a so-called *breadth-first search*.
- ***Stack*** - by storing the vertices in a last-in, first-out (LIFO) stack, we explore the vertices by constantly visiting a new neighbor if one is available; we back up only when surrounded by previously discovered vertices. This defines a so-called *depth-first search*.

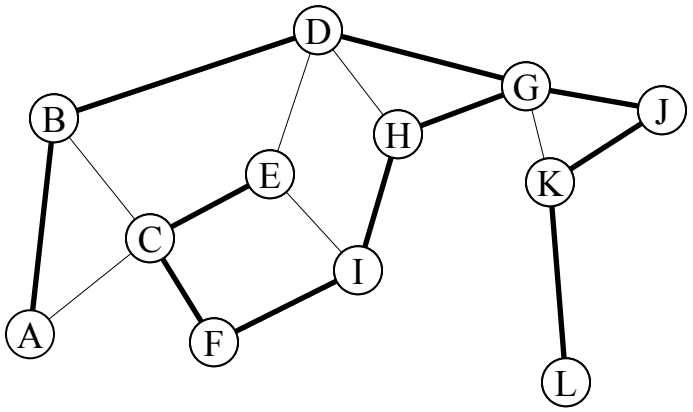
Depth-First Search

- *Depth-first search* is another strategy for exploring a graph
  - Explore "deeper" in the graph whenever possible
  - Edges are explored out of the most recently discovered vertex *v* that still has unexplored edges
  - When all of *v*'s edges have been explored, backtrack to the vertex from which *v* was discovered

Graph Traversal - Example



Depth-First Search Tree



Key Property: each edge is either in DFS tree (tree edge) or leads back to an ancestor in the tree (back edge) .

Directed Graph DFS trees

- Things are a bit more complicated
  - Forward edges (ancestor to descendant)
  - Cross Edges
    - Not from an ancestor to a descendant
- Parenthesis structure still holds
  - The discovery and finishing times of nodes in a DFS tree have a parenthesis structure
- Can create a forest of DFS trees

Depth-First Search

- Vertices initially colored white
- Then colored gray when discovered
- Then black when finished

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

What does `u->d` *represent?*

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

What does `u->f` *represent?*

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

Will all vertices eventually be colored black?

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

What will be the running time?

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

Running time: $O(n^2)$ because call DFS_Visit on each vertex, and the loop over Adj[] can run as many as |V| times

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

BUT, there is actually a tighter bound.
How many times will DFS_Visit() actually be called?

Depth-First Search: The Code

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

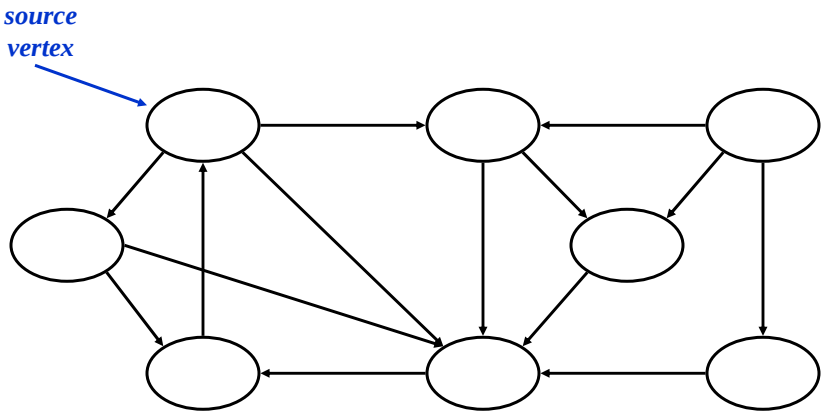
```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

So, running time of DFS = O(V+E)

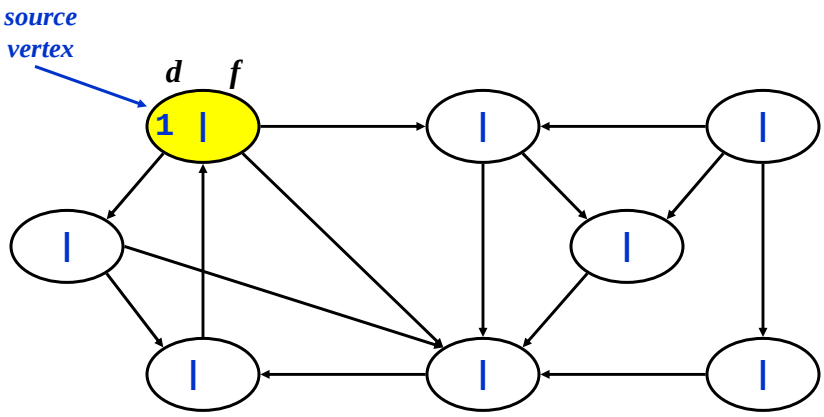
Depth-First Sort Analysis

- This running time argument is an informal example of *amortized analysis*
  - "Charge" the exploration of edge to the edge:
    - Each loop in DFS_Visit can be attributed to an edge in the graph
    - Runs once/edge if directed graph, twice if undirected
    - Thus loop will run in O(E) time, algorithm O(V+E)
      - Considered linear for graph, b/c adj list requires O(V+E) storage
  - Important to be comfortable with this kind of reasoning and analysis

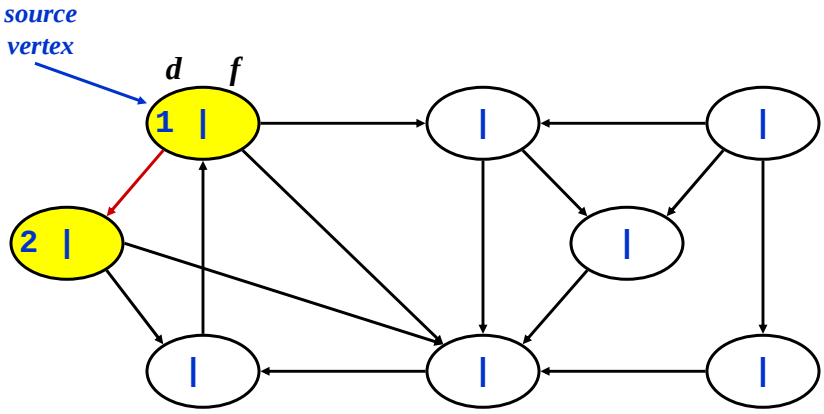
DFS Example



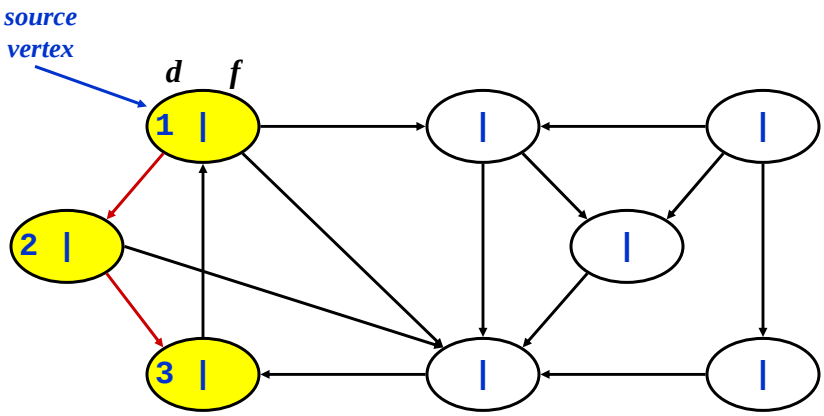
DFS Example



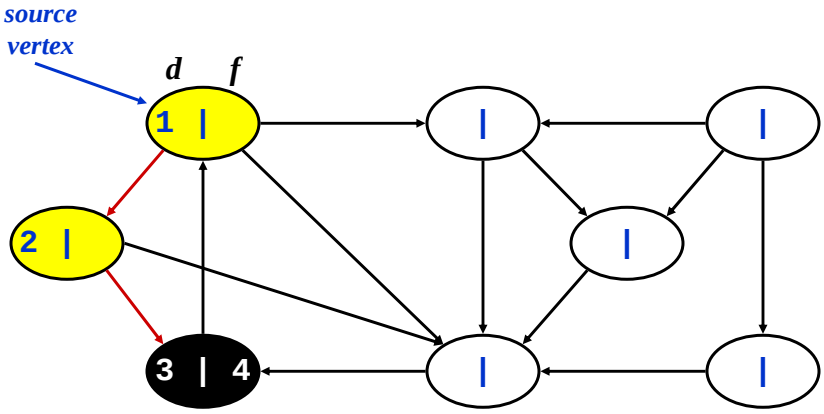
DFS Example



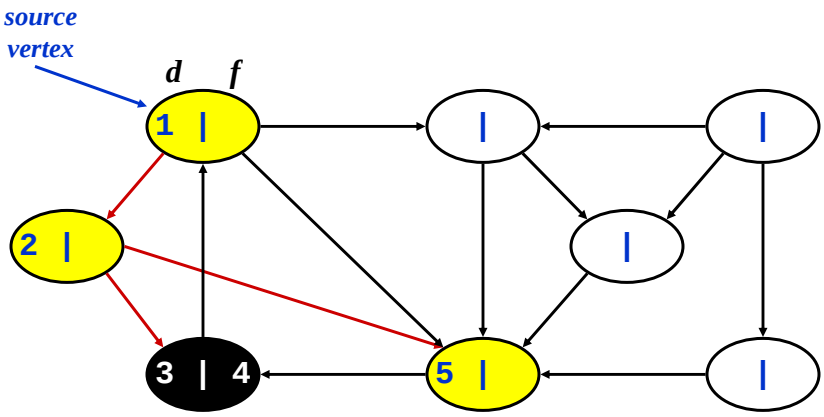
DFS Example



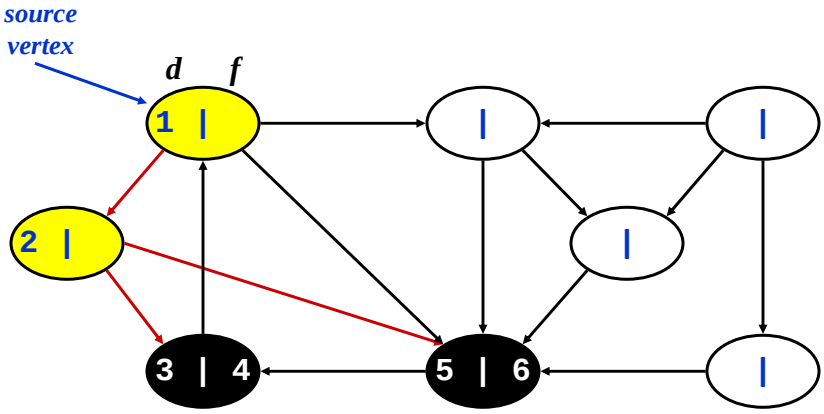
DFS Example



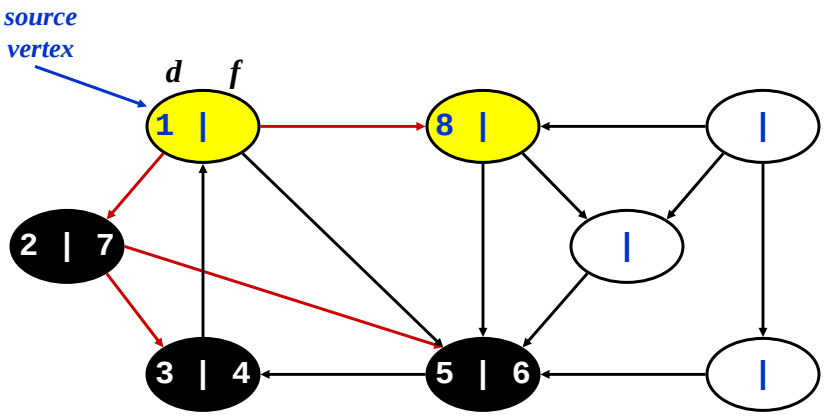
DFS Example



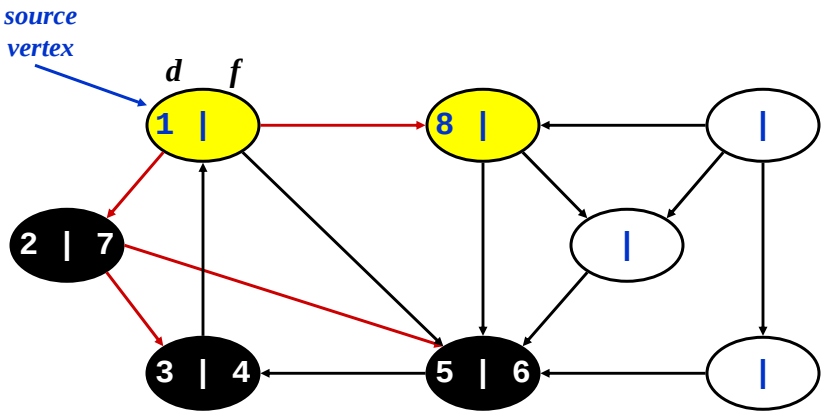
DFS Example



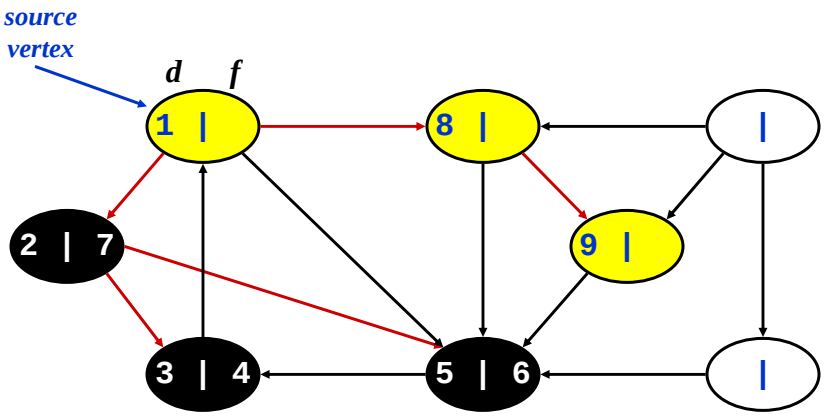
DFS Example



DFS Example

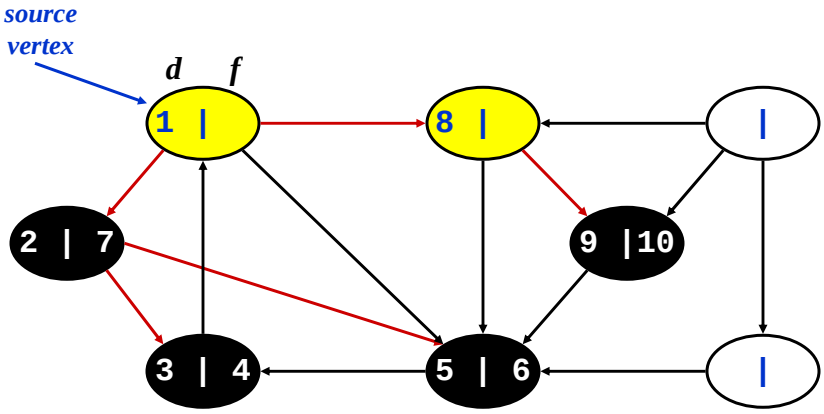


DFS Example

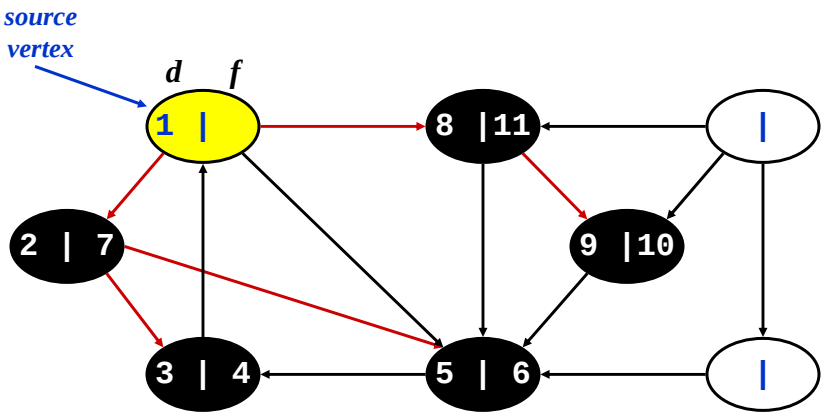


What is the structure of the yellow vertices?
What do they represent?

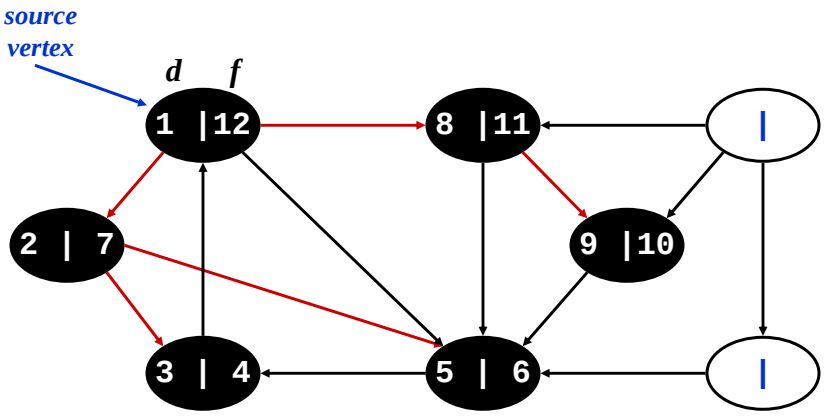
DFS Example



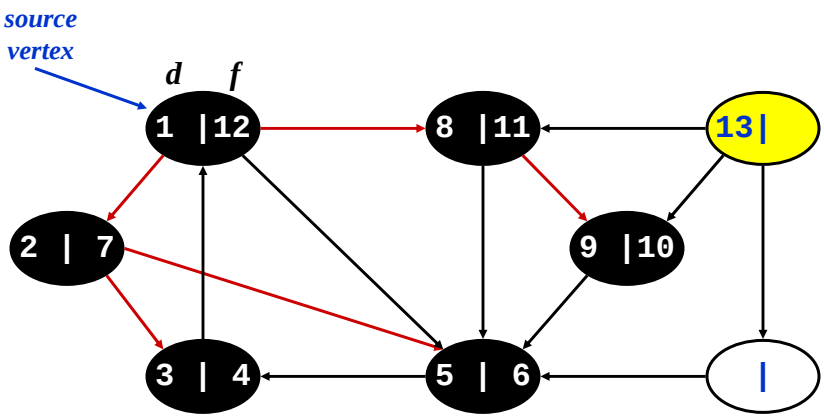
DFS Example



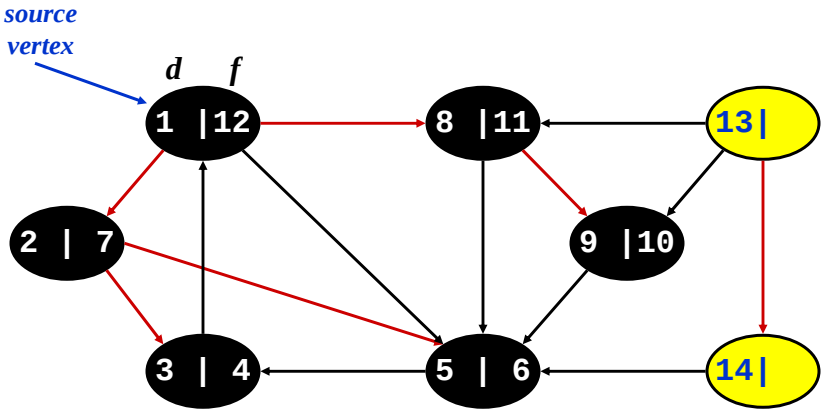
DFS Example



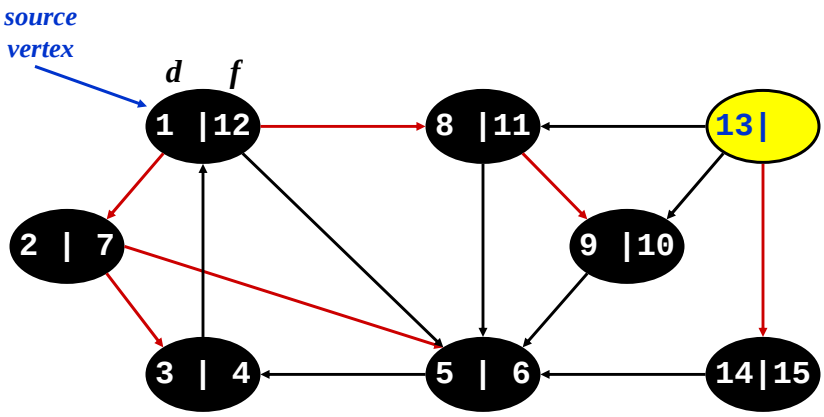
DFS Example



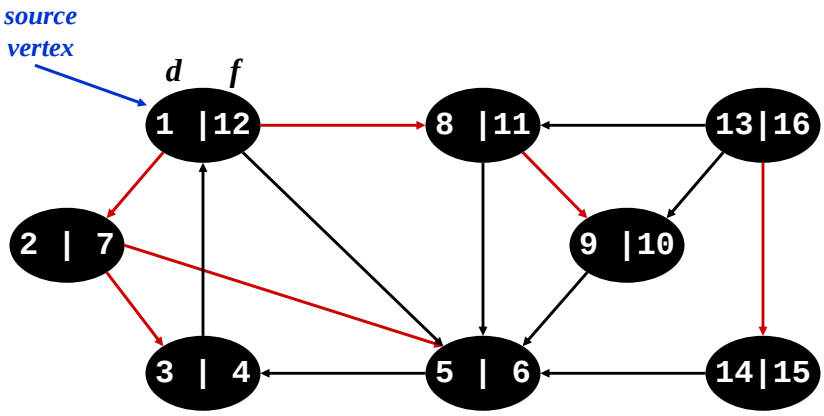
DFS Example



DFS Example



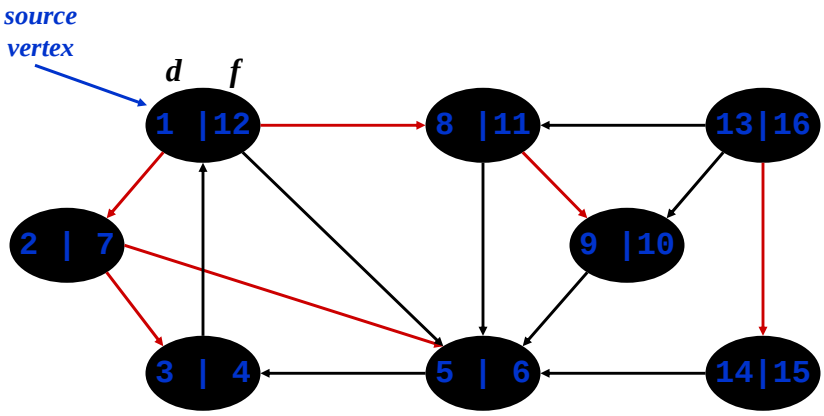
DFS Example



DFS: Kinds of edges

- DFS introduces an important distinction among edges in the original graph:
  - *Tree edge*: encounter new (white) vertex
    - The tree edges form a spanning forest
    - *Can tree edges form cycles? Why or why not?*

DFS Example

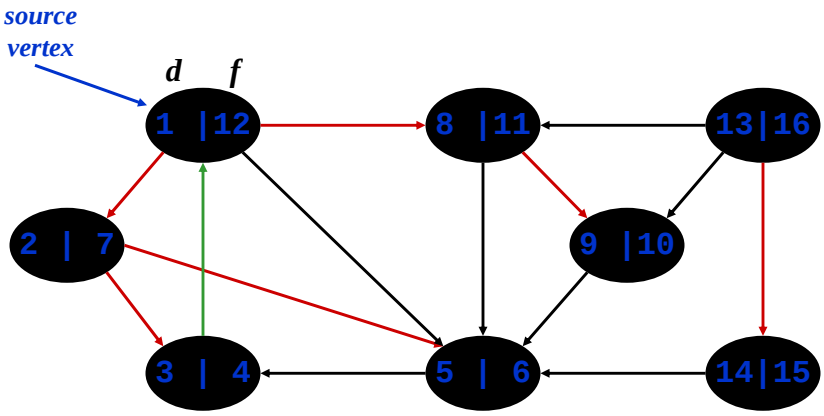


Tree edges

DFS: Kinds of edges

- DFS introduces an important distinction among edges in the original graph:
  - *Tree edge*: encounter new (white) vertex
  - *Back edge*: from descendent to ancestor
    - Encounter a yellow vertex (yellow to yellow)

DFS Example

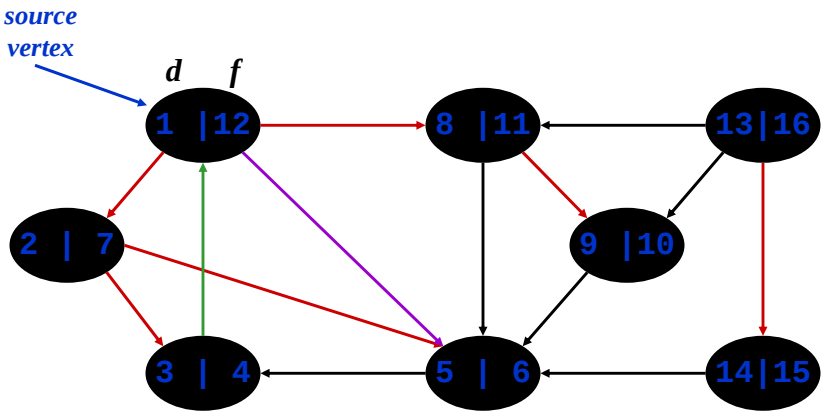


Tree edges *Back edges*

DFS: Kinds of edges

- DFS introduces an important distinction among edges in the original graph:
  - *Tree edge*: encounter new (white) vertex
  - *Back edge*: from descendent to ancestor
  - *Forward edge*: from ancestor to descendent
    - Not a tree edge, though
    - From yellow node to black node

DFS Example

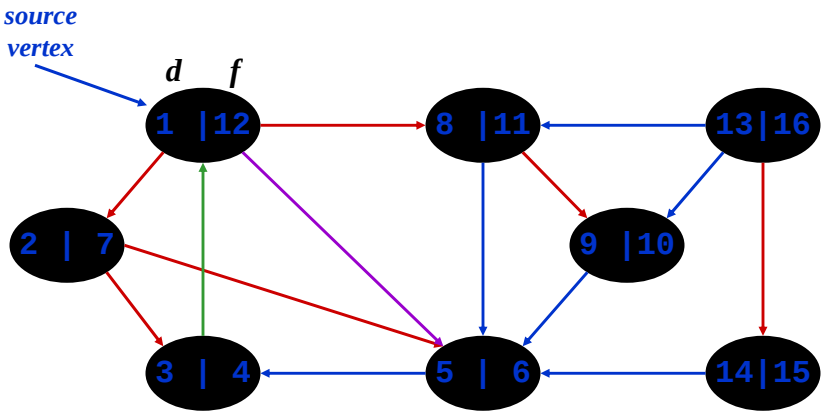


Tree edges *Back edges* *Forward edges*

DFS: Kinds of edges

- DFS introduces an important distinction among edges in the original graph:
  - *Tree edge*: encounter new (white) vertex
  - *Back edge*: from descendent to ancestor
  - *Forward edge*: from ancestor to descendent
  - *Cross edge*: between a tree or subtrees
    - From a yellow node to a black node

DFS Example



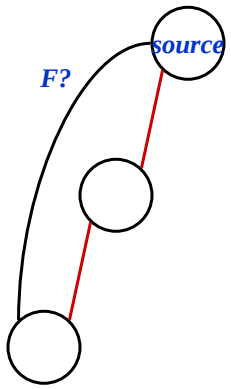
Tree edges *Back edges* *Forward edges* *Cross edges*

DFS: Kinds of edges

- DFS introduces an important distinction among edges in the original graph:
  - *Tree edge*: encounter new (white) vertex
  - *Back edge*: from descendent to ancestor
  - *Forward edge*: from ancestor to descendent
  - *Cross edge*: between a tree or subtrees
- Note: tree & back edges are important; most algorithms don't distinguish forward & cross

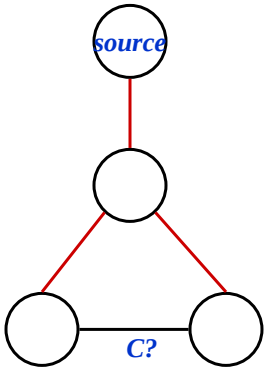
DFS: Kinds Of Edges

- Thm 22.10: If G is undirected, a DFS produces only tree and back edges
- Proof by contradiction:
  - Assume there's a forward edge
    - But F? edge must actually be a back edge (*why?*)



DFS: Kinds Of Edges

- Thm 22.10 : If G is undirected, a DFS produces only tree and back edges
- Proof by contradiction:
  - Assume there's a cross edge
    - But C? edge cannot be cross:
    - must be explored from one of the vertices it connects, becoming a tree vertex, before other vertex is explored
    - So in fact the picture is wrong…both lower tree edges cannot in fact be tree edges



DFS And Graph Cycles

- Thm: An undirected graph is *acyclic* iff a DFS yields no back edges
  - If acyclic, no back edges (because a back edge implies a cycle
  - If no back edges, acyclic
    - No back edges implies only tree edges (*Why?*)
    - Only tree edges implies we have a tree or a forest
    - Which by definition is acyclic
- Thus, can run DFS to find whether a graph has a cycle

DFS And Cycles

- *How would you modify the code to detect cycles?*

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

DFS And Cycles

- *What will be the running time?*

```
DFS(G)
{
   for each vertex u ∈ G->V
   {
      u->color = WHITE;
   }
   time = 0;
   for each vertex u ∈ G->V
   {
      if (u->color == WHITE)
         DFS_Visit(u);
   }
}
```

```
DFS_Visit(u)
{
   u->color = GREY;
   time = time+1;
   u->d = time;
   for each v ∈ u->Adj[]
   {
      if (v->color == WHITE)
         DFS_Visit(v);
   }
   u->color = BLACK;
   time = time+1;
   u->f = time;
}
```

DFS And Cycles

- *What will be the running time?*
- A: O(V+E)
- We can actually determine if cycles exist in O(V) time:
  - In an undirected acyclic forest, $|E| \leq |V| - 1$
  - So count the edges: if ever see |V| distinct edges, must have seen a back edge along the way