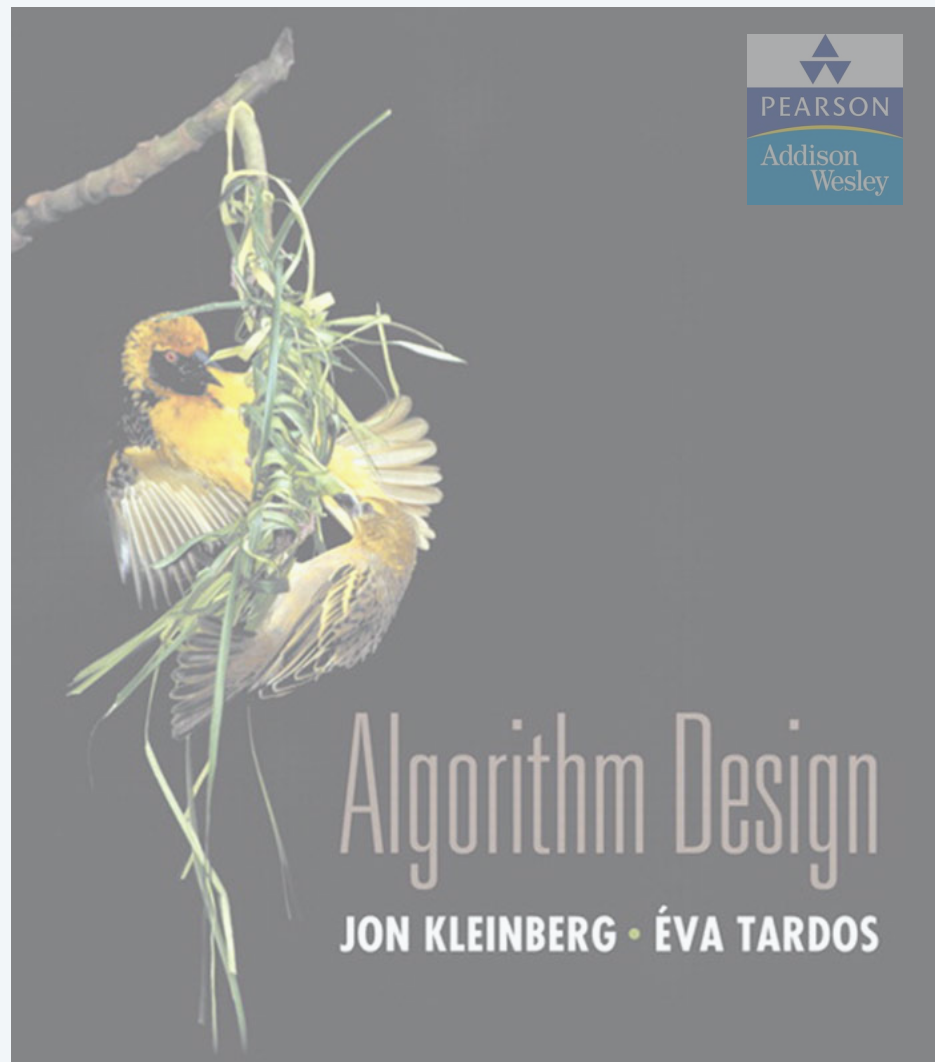


# ALGORITHM ANALYSIS

---

- ▶ *computational tractability*
- ▶ *asymptotic order of growth*
- ▶ *survey of common running times*



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# Brute force

---

**Brute force.** For many nontrivial problems, there is a natural brute-force search algorithm that checks every possible solution.

- Typically takes  $2^n$  steps (or worse) for inputs of size  $n$ .
- Unacceptable in practice.



# Polynomial running time

---

**Desirable scaling property.** When the input size doubles, the algorithm should slow down by at most some constant factor  $C$ .

**Def.** An algorithm is **poly-time** if the above scaling property holds.

There exist constants  $c > 0$  and  $d > 0$  such that,  
for every input of size  $n$ , the running time of the algorithm  
is bounded above by  $c n^d$  primitive computational steps.

← choose  $C = 2^d$

# Polynomial running time

---

We say that an algorithm is **efficient** if it has a polynomial running time.

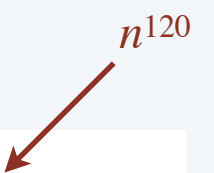
**Theory.** Definition is (relatively) insensitive to model of computation.

**Practice.** It really works!

- The poly-time algorithms that people develop have both small constants and small exponents.
- Breaking through the exponential barrier of brute force typically exposes some crucial structure of the problem.

**Exceptions.** Some poly-time algorithms in the wild have galactic constants and/or huge exponents.

**Q.** Which would you prefer:  $20 n^{120}$  or  $n^{1 + 0.02 \ln n}$  ?



**Map graphs in polynomial time**

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**Abstract**

*Chen, Grigni, and Papadimitriou (WADS'97 and STOC'98) have introduced a modified notion of planarity, where two faces are considered adjacent if they share at least one point. The corresponding abstract graphs are called map graphs. Chen et.al. raised the question of whether map graphs can be recognized in polynomial time. They showed that the decision problem is in NP and presented a polynomial time algorithm for the special case where we allow at most 4 faces to intersect in any point — if only 3 are allowed to intersect in a point, we get the usual planar graphs.*

*Chen et.al. conjectured that map graphs can be recognized in polynomial time, and in this paper, their conjecture is settled affirmatively.*

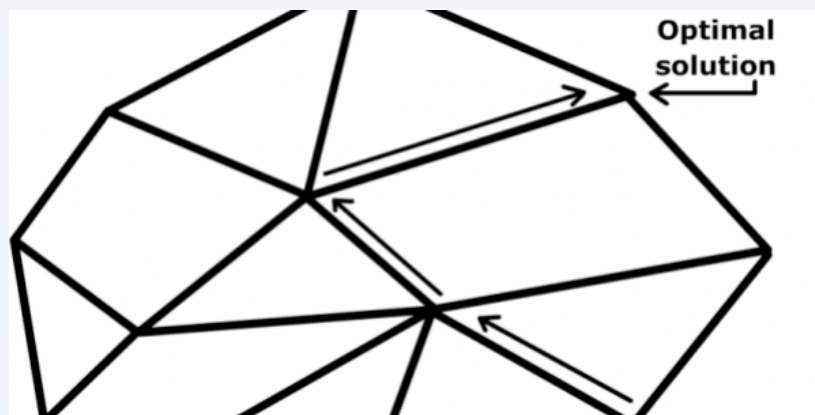
# Worst-case analysis

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**Worst case.** Running time guarantee for **any input** of size  $n$ .

- Generally captures efficiency in practice.
- Draconian view, but hard to find effective alternative.

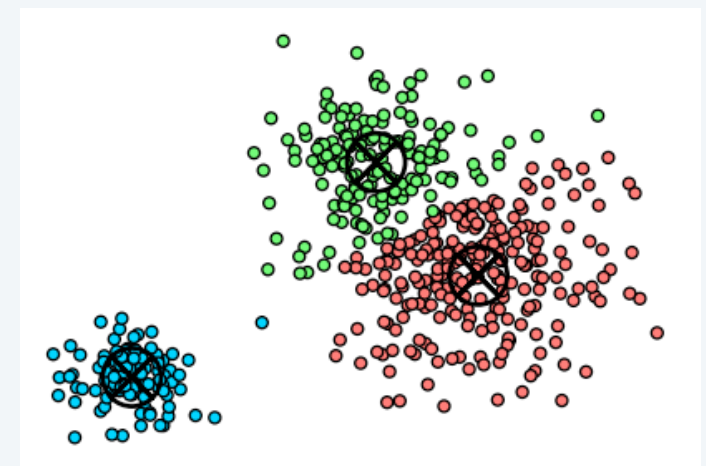
**Exceptions.** Some exponential-time algorithms are used widely in practice because the worst-case instances don't arise.



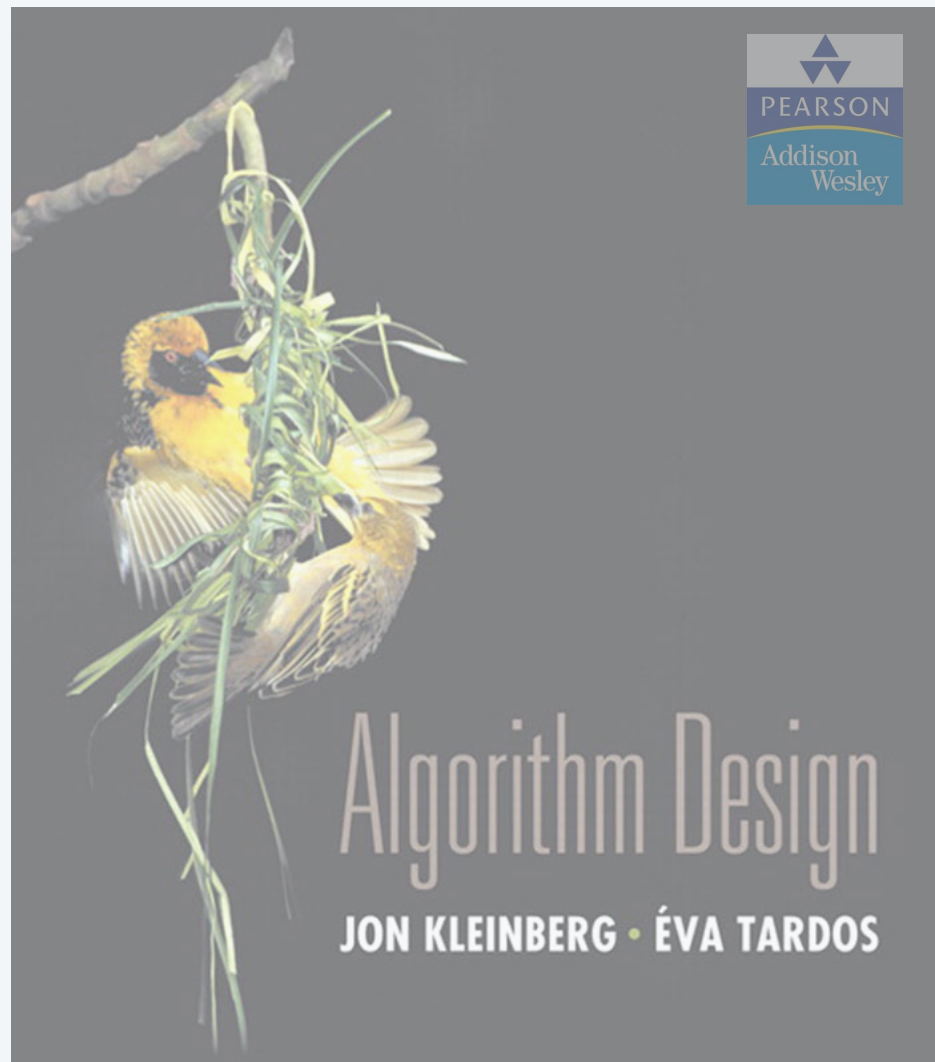
simplex algorithm



Linux grep



k-means algorithm



# ALGORITHM ANALYSIS

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- ▶ *computational tractability*
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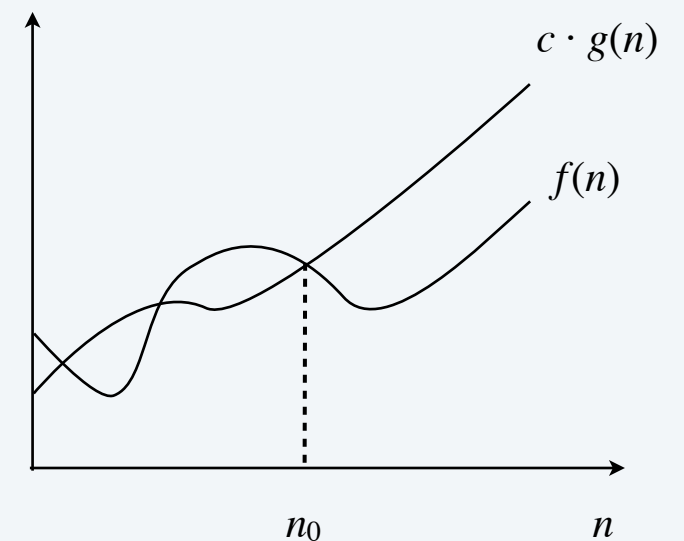
# Big O notation

---

**Upper bounds.**  $f(n)$  is  $O(g(n))$  if there exist constants  $c > 0$  and  $n_0 \geq 0$  such that  $0 \leq f(n) \leq c \cdot g(n)$  for all  $n \geq n_0$ .

**Ex.**  $f(n) = 32n^2 + 17n + 1$ .

- $f(n)$  is  $O(n^2)$ . ← choose  $c = 50, n_0 = 1$
- $f(n)$  is neither  $O(n)$  nor  $O(n \log n)$ .







Let  $f(n) = 3n^2 + 17n \log_2 n + 1000$ . Which of the following are true?

- A.  $f(n)$  is  $O(n^2)$ .
- B.  $f(n)$  is  $O(n^3)$ .
- C. Both A and B.
- D. Neither A nor B.

# Big O notational abuses

---

**One-way “equality.”**  $O(g(n))$  is a set of functions, but computer scientists often write  $f(n) = O(g(n))$  instead of  $f(n) \in O(g(n))$ .

**Ex.** Consider  $g_1(n) = 5n^3$  and  $g_2(n) = 3n^2$ .

- We have  $g_1(n) = O(n^3)$  and  $g_2(n) = O(n^3)$ .
- But, do not conclude  $g_1(n) = g_2(n)$ .

**Domain and codomain.**  $f$  and  $g$  are real-valued functions.

- The domain is typically the natural numbers:  $\mathbb{N} \rightarrow \mathbb{R}$ .
- Sometimes we extend to the reals:  $\mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$ .
  - input size, recurrence relations
- Or restrict to a subset.
  - plotting, limits, calculus

**Bottom line.** OK to abuse notation in this way; not OK to misuse it.

# Big O notation: properties

---

**Reflexivity.**  $f$  is  $O(f)$ .

**Constants.** If  $f$  is  $O(g)$  and  $c > 0$ , then  $cf$  is  $O(g)$ .

**Products.** If  $f_1$  is  $O(g_1)$  and  $f_2$  is  $O(g_2)$ , then  $f_1 f_2$  is  $O(g_1 g_2)$ .

**Pf.**

- $\exists c_1 > 0$  and  $n_1 \geq 0$  such that  $0 \leq f_1(n) \leq c_1 \cdot g_1(n)$  for all  $n \geq n_1$ .
- $\exists c_2 > 0$  and  $n_2 \geq 0$  such that  $0 \leq f_2(n) \leq c_2 \cdot g_2(n)$  for all  $n \geq n_2$ .
- Then,  $0 \leq f_1(n) \cdot f_2(n) \leq \underbrace{c_1 \cdot c_2}_c \cdot g_1(n) \cdot g_2(n)$  for all  $n \geq \underbrace{\max \{n_1, n_2\}}_{n_0}$ . ■

**Sums.** If  $f_1$  is  $O(g_1)$  and  $f_2$  is  $O(g_2)$ , then  $f_1 + f_2$  is  $O(\max \{g_1, g_2\})$ .

ignore lower-order terms

**Transitivity.** If  $f$  is  $O(g)$  and  $g$  is  $O(h)$ , then  $f$  is  $O(h)$ .

**Ex.**  $f(n) = 5n^3 + 3n^2 + n + 1234$  is  $O(n^3)$ .

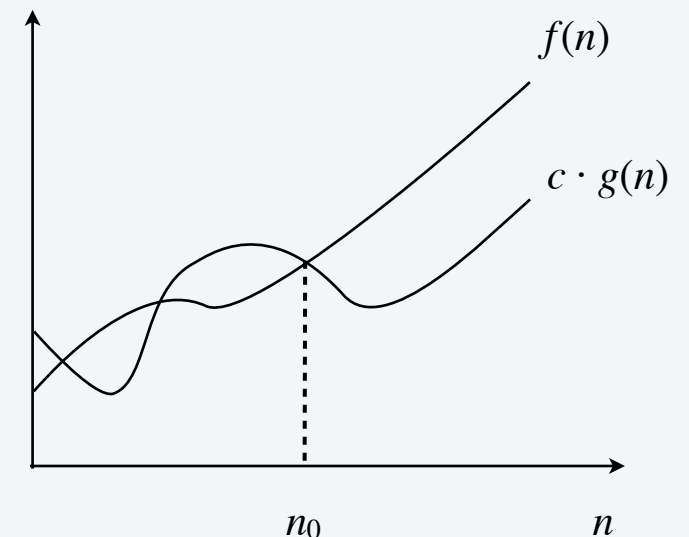
# Big Omega notation

---

**Lower bounds.**  $f(n)$  is  $\Omega(g(n))$  if there exist constants  $c > 0$  and  $n_0 \geq 0$  such that  $f(n) \geq c \cdot g(n) \geq 0$  for all  $n \geq n_0$ .

**Ex.**  $f(n) = 32n^2 + 17n + 1$ .

- $f(n)$  is both  $\Omega(n^2)$  and  $\Omega(n)$ . ← choose  $c = 32, n_0 = 1$
- $f(n)$  is not  $\Omega(n^3)$ .



**Typical usage.** Any compare-based sorting algorithm requires  $\Omega(n \log n)$  compares in the worst case.

**Vacuous statement.** Any compare-based sorting algorithm requires at least  $O(n \log n)$  compares in the worst case.



Which is an equivalent definition of big Omega notation?

- A.  $f(n)$  is  $\Omega(g(n))$  iff  $g(n)$  is  $O(f(n))$ .
- B.  $f(n)$  is  $\Omega(g(n))$  iff there exist constants  $c > 0$  such that  $f(n) \geq c \cdot g(n) \geq 0$  for infinitely many  $n$ .
- C. Both A and B.
- D. Neither A nor B.

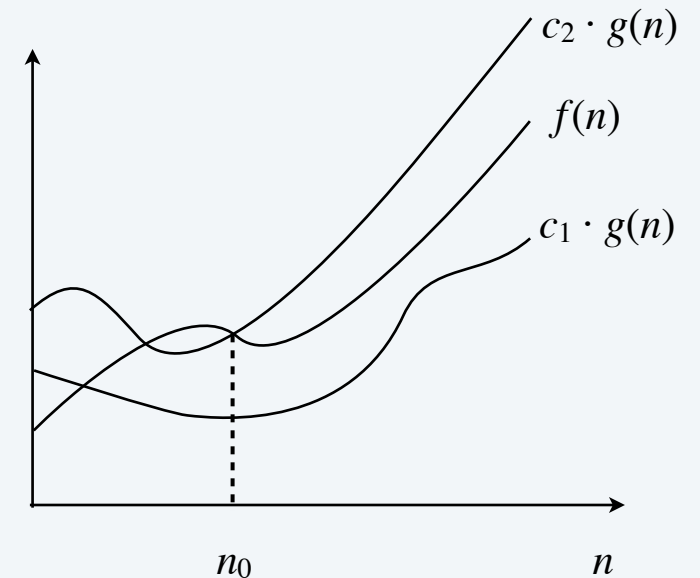
# Big Theta notation

---

**Tight bounds.**  $f(n)$  is  $\Theta(g(n))$  if there exist constants  $c_1 > 0$ ,  $c_2 > 0$ , and  $n_0 \geq 0$  such that  $0 \leq c_1 \cdot g(n) \leq f(n) \leq c_2 \cdot g(n)$  for all  $n \geq n_0$ .

**Ex.**  $f(n) = 32n^2 + 17n + 1$ .

- $f(n)$  is  $\Theta(n^2)$ . ← choose  $c_1 = 32, c_2 = 50, n_0 = 1$
- $f(n)$  is neither  $\Theta(n)$  nor  $\Theta(n^3)$ .



**Typical usage.** Mergesort makes  $\Theta(n \log n)$  compares to sort  $n$  elements.

between  $\frac{1}{2} n \log_2 n$   
and  $n \log_2 n$

↑



Which is an equivalent definition of big Theta notation?

- A.  $f(n)$  is  $\Theta(g(n))$  iff  $f(n)$  is both  $O(g(n))$  and  $\Omega(g(n))$ .
- B.  $f(n)$  is  $\Theta(g(n))$  iff  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = c$  for some constant  $0 < c < \infty$ .
- C. Both A and B.
- D. Neither A nor B.

# Asymptotic bounds and limits

---

**Proposition.** If  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = c$  for some constant  $0 < c < \infty$  then  $f(n)$  is  $\Theta(g(n))$ .

**Pf.**

- By definition of the limit, for any  $\varepsilon > 0$ , there exists  $n_0$  such that

$$c - \epsilon \leq \frac{f(n)}{g(n)} \leq c + \epsilon$$

for all  $n \geq n_0$ .

- Choose  $\varepsilon = \frac{1}{2} c > 0$ .
- Multiplying by  $g(n)$  yields  $\frac{1}{2} c \cdot g(n) \leq f(n) \leq \frac{3}{2} c \cdot g(n)$  for all  $n \geq n_0$ .
- Thus,  $f(n)$  is  $\Theta(g(n))$  by definition, with  $c_1 = \frac{1}{2} c$  and  $c_2 = \frac{3}{2} c$ . ■

**Proposition.** If  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$ , then  $f(n)$  is  $O(g(n))$  but not  $\Omega(g(n))$ .

**Proposition.** If  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = \infty$ , then  $f(n)$  is  $\Omega(g(n))$  but not  $O(g(n))$ .



# Big O notation with multiple variables

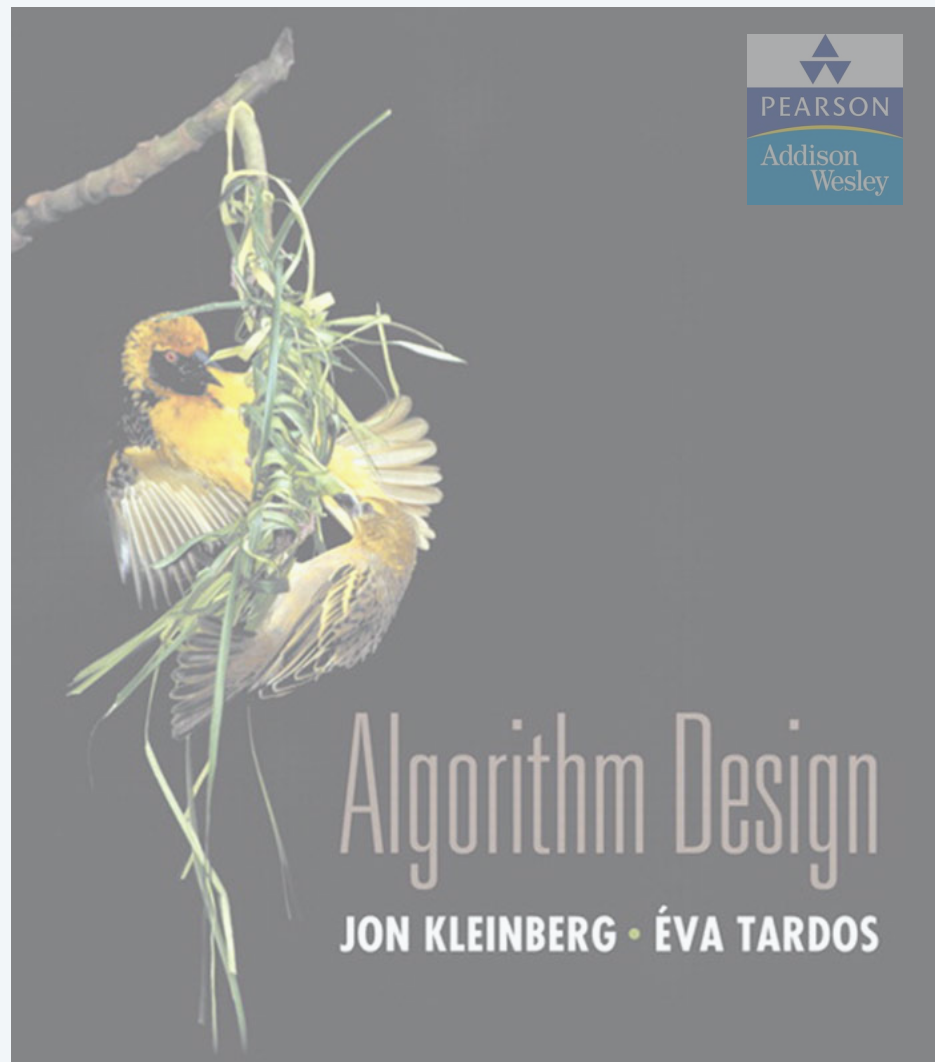
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**Upper bounds.**  $f(m, n)$  is  $O(g(m, n))$  if there exist constants  $c > 0$ ,  $m_0 \geq 0$ , and  $n_0 \geq 0$  such that  $f(m, n) \leq c \cdot g(m, n)$  for all  $n \geq n_0$  and  $m \geq m_0$ .

**Ex.**  $f(m, n) = 32mn^2 + 17mn + 32n^3$ .

- $f(m, n)$  is both  $O(mn^2 + n^3)$  and  $O(mn^3)$ .
- $f(m, n)$  is neither  $O(n^3)$  nor  $O(mn^2)$ .

**Typical usage.** Breadth-first search takes  $O(m + n)$  time to find a shortest path from  $s$  to  $t$  in a digraph with  $n$  nodes and  $m$  edges.



# ALGORITHM ANALYSIS

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# Constant time

---

Constant time. Running time is  $O(1)$ .

## Examples.

 bounded by a constant,  
which does not depend on input size  $n$

- Conditional branch.
- Arithmetic/logic operation.
- Declare/initialize a variable.
- Follow a link in a linked list.
- Access element  $i$  in an array.
- Compare/exchange two elements in an array.
- ...

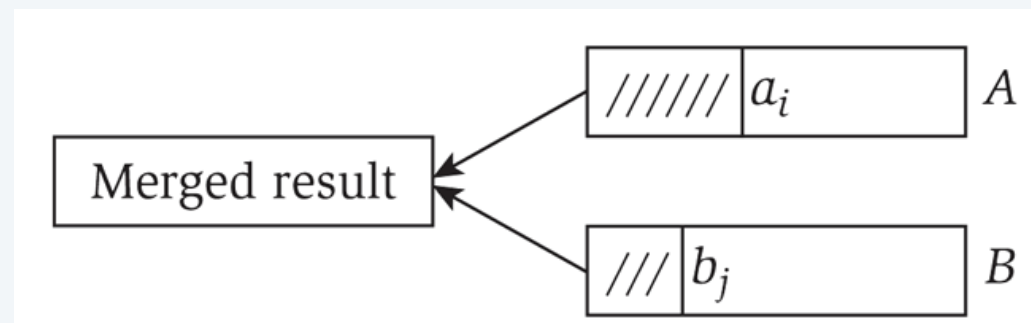
# Linear time

---

**Linear time.** Running time is  $O(n)$ .

**Merge two sorted lists.** Combine two sorted linked lists  $A = a_1, a_2, \dots, a_n$  and  $B = b_1, b_2, \dots, b_n$  into a sorted whole.

**$O(n)$  algorithm.** Merge in mergesort.



$i \leftarrow 1; j \leftarrow 1.$

**WHILE** (both lists are nonempty)

**IF** ( $a_i \leq b_j$ ) append  $a_i$  to output list and increment  $i$ .

**ELSE**           append  $b_j$  to output list and increment  $j$ .

Append remaining elements from nonempty list to output list.

# Logarithmic time

---

**Logarithmic time.** Running time is  $O(\log n)$ .

**Search in a sorted array.** Given a sorted array  $A$  of  $n$  distinct integers and an integer  $x$ , find index of  $x$  in array.

**$O(\log n)$  algorithm.** Binary search.

- Invariant: If  $x$  is in the array, then  $x$  is in  $A[lo .. hi]$ .
- After  $k$  iterations of WHILE loop,  $(hi - lo + 1) \leq n / 2^k \Rightarrow k \leq 1 + \log_2 n$ .

remaining elements



```
lo ← 1; hi ← n.
```

```
WHILE (lo ≤ hi)
```

```
    mid ← ⌊(lo + hi) / 2⌋.
```

```
    IF      (x < A[mid]) hi ← mid - 1.
```

```
    ELSE IF (x > A[mid]) lo ← mid + 1.
```

```
    ELSE RETURN mid.
```

```
RETURN -1.
```



# Linearithmic time

---

Linearithmic time. Running time is  $O(n \log n)$ .

Sorting. Given an array of  $n$  elements, rearrange them in ascending order.

$O(n \log n)$  algorithm. Mergesort.

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
E	M	R	G	E	S	O	R	T	E	X	A	M	P	L	E
E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
E	G	M	R	E	O	R	S	T	E	X	A	M	P	L	E
E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E
E	E	G	M	O	R	R	S	E	T	X	A	M	P	L	E
E	E	G	M	O	R	R	S	E	T	A	X	M	P	L	E
E	E	G	M	O	R	R	S	A	E	T	X	M	P	L	E
E	E	G	M	O	R	R	S	A	E	T	X	M	P	E	L
E	E	G	M	O	R	R	S	A	E	T	X	E	L	M	P
E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

# Quadratic time

---

**Quadratic time.** Running time is  $O(n^2)$ .

**Closest pair of points.** Given a list of  $n$  points in the plane  $(x_1, y_1), \dots, (x_n, y_n)$ , find the pair that is closest to each other.

**$O(n^2)$  algorithm.** Enumerate all pairs of points (with  $i < j$ ).

```
min  $\leftarrow \infty$ .  
FOR  $i = 1$  TO  $n$   
  FOR  $j = i + 1$  TO  $n$   
     $d \leftarrow (x_i - x_j)^2 + (y_i - y_j)^2$ .  
    IF ( $d < min$ )  
       $min \leftarrow d$ .
```

**Remark.**  $\Omega(n^2)$  seems inevitable, but this is just an illusion. [see §5.4]

# Cubic time

---

**Cubic time.** Running time is  $O(n^3)$ .

**3-SUM.** Given an array of  $n$  distinct integers, find three that sum to 0.

**$O(n^3)$  algorithm.** Enumerate all triples (with  $i < j < k$ ).

```
FOR  $i = 1$  TO  $n$ 
  FOR  $j = i + 1$  TO  $n$ 
    FOR  $k = j + 1$  TO  $n$ 
      IF  $(a_i + a_j + a_k = 0)$ 
        RETURN  $(a_i, a_j, a_k)$ .
```




# Polynomial time

---

**Polynomial time.** Running time is  $O(n^k)$  for some constant  $k > 0$ .

**Independent set of size  $k$ .** Given a graph, find  $k$  nodes such that no two are joined by an edge.

  $k$  is a constant

**$O(n^k)$  algorithm.** Enumerate all subsets of  $k$  nodes.

**FOREACH** subset  $S$  of  $k$  nodes:

Check whether  $S$  is an independent set.


**IF** ( $S$  is an independent set)

**RETURN**  $S$ .

- Check whether  $S$  is an independent set of size  $k$  takes  $O(k^2)$  time.

- Number of  $k$ -element subsets =  $\binom{n}{k} = \frac{n(n-1)(n-2) \times \cdots \times (n-k+1)}{k(k-1)(k-2) \times \cdots \times 1} \leq \frac{n^k}{k!}$

- $O(k^2 n^k / k!) = O(n^k)$ .

 poly-time for  $k = 17$ ,  
but not practical

# Exponential time

---

**Exponential time.** Running time is  $O(2^{n^k})$  for some constant  $k > 0$ .

**Independent set.** Given a graph, find independent set of max cardinality.

**$O(n^2 2^n)$  algorithm.** Enumerate all subsets.

$S^* \leftarrow \emptyset.$

**FOREACH** subset  $S$  of nodes:

    Check whether  $S$  is an independent set.

**IF** ( $S$  is an independent set and  $|S| > |S^*|$ )

$S^* \leftarrow S.$

**RETURN**  $S^*.$