

- For child and old age component, spline coefficients are given the usual 2nd order penalties + shrinkage towards 0 around the LQ derived priors
 - For the hump component, as discussed last week, want:
 - want smooth trends defined by 2nd order differences
 - does not want the linear trend to continue in periods without sufficient data
 - want extrapolation of the parameters into periods without data to converge approximately at the current levels
 - did not use an AR process in the end, but an ARIMA(1,1,0), below is my thought process
- ↪ the 2nd order smoothness penalty implies

$$\begin{aligned}
 \beta_{t+1} &= 2\beta_t - \beta_{t-1} + \varepsilon_{t+1} \\
 &= \beta_t + \underbrace{(\beta_t - \beta_{t-1})}_{\text{continuation of the trend}} + \varepsilon_{t+1}
 \end{aligned}$$

introduce $\rho \in (0, 1)$ such that $\beta_{t+1} = \beta_t + \rho(\beta_t - \beta_{t-1}) + \varepsilon_{t+1}$, i.e. the next beta does not continue the current trend entirely

- when $\rho \rightarrow 0$, a RW1 is obtained, so future coefficients maintain the current level (flat line)
 - when $\rho \rightarrow 1$, a RW2 is obtained, so future coefficients maintain the current trend (linear line)
 - varying $\rho \in (0, 1)$ maintains a trade of between smoothness in the linear trend sense and staying approximately at the current level
 - **I think** this is equivalent to having $\lambda_1(\mathbf{D}'_1 \mathbf{D}_1) + \lambda_2(\mathbf{D}'_2 \mathbf{D}_2)$ as penalty, where \mathbf{D}_i is the i -th order difference matrix, based on previous work on the ICAR representation of the spline coefficients
 - this suggests using an ARIMA(1,1,0) on the coefficients with ρ restricted to be in $(0,1)$, but in practice I used $\rho \in (-1, 1)$ to be consistent with time-series, might not be logical in the smoothing penalty sense? Should I restrict them to be in $(0, 1)$?
- will change smoothness priors on gx to be 2nd order diff
 - flatter priors on smoothness penalties?
 - male B under-smoothed
 - will set males and females lambda to be the same
 - investigating how to set informative priors on the smoothness penalties, as these are difficult to elicit due to the dependency on knot spacing, number of basis, design matrix etc.
 - converged for most countries, except for Gambia (outer mgc exploding), Lesotho (only converged when ρ restricted to $(0,1)$), etc.