

Shammah Thao
EEE 174 - CpE 185 Lab Section #2
Monday & Wednesday
Lab 5 – Area of Interests
Dahlquist

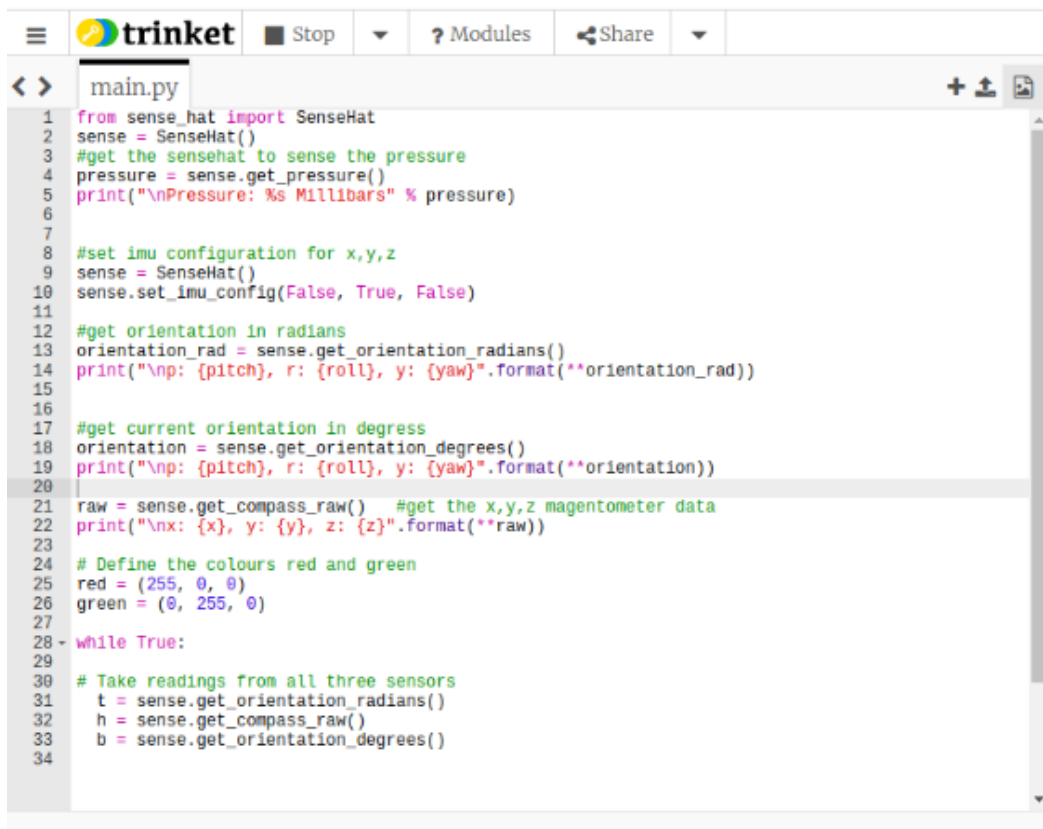
Introduction:

For this lab, I connected this part to what I needed to do for the final project. For the final project, we were planning on building a weather station logger. It basically used the hardware Sense hat to collect data surrounding it. It would display things that we want such as temperature, pressure, its orientation and so on. For me, I'm working on magnetometer and barometric pressure so what I did was put them all into one code and demo it for my lab 5.

Due to not having the physical device on hand, I used an online simulator from the website trinket.io. It has its own online sense hat that has the features that I needed for the code.

DEMO:

For my code I made it take in the pressure from the sense hat, along with its orientation. The code

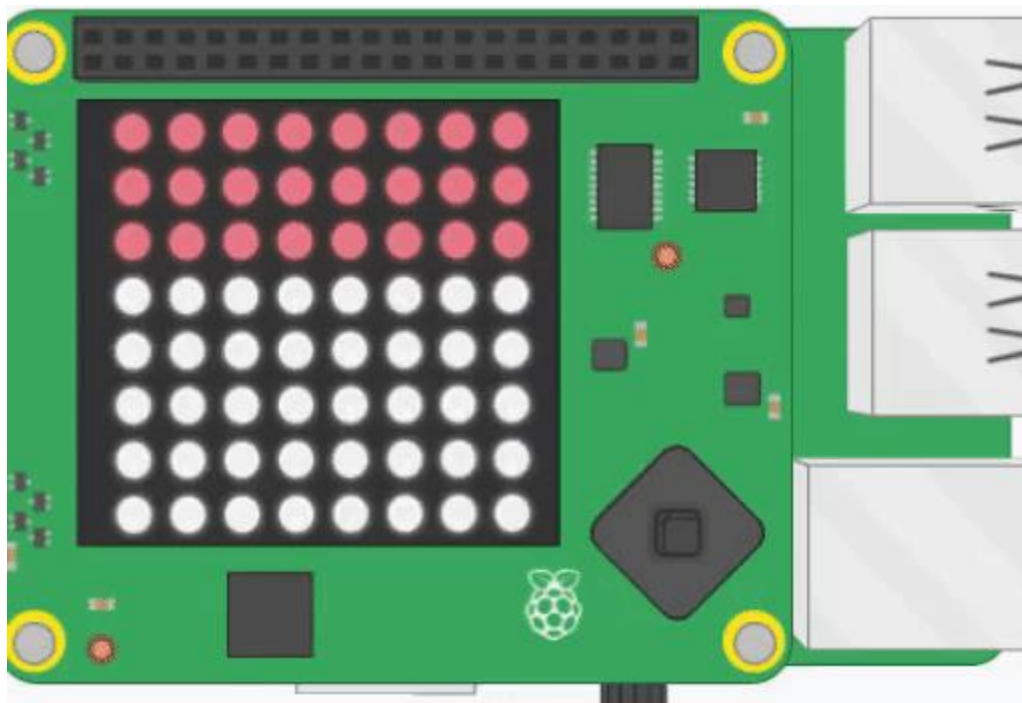
The image shows a screenshot of the Trinket.io web interface. At the top, there's a navigation bar with the Trinket logo, a 'Stop' button, a 'Modules' dropdown, and a 'Share' button. Below this, the code editor is open to a file named 'main.py'. The code is a Python script that interacts with the Sense Hat. It starts by importing SenseHat from the sense_hat module. Then, it initializes a SenseHat object. The script then prints the pressure from the Sense Hat. Next, it sets the IMU configuration for x, y, and z axes. It then prints the orientation in radians. After that, it prints the orientation in degrees. Finally, it prints the raw magnetometer data (x, y, z coordinates). The code is wrapped in a while True loop to keep running. The code is as follows:

```
1 from sense_hat import SenseHat
2 sense = SenseHat()
3 #get the sensehat to sense the pressure
4 pressure = sense.get_pressure()
5 print("\nPressure: %s Millibars" % pressure)
6
7
8 #set imu configuration for x,y,z
9 sense = SenseHat()
10 sense.set_imu_config(False, True, False)
11
12 #get orientation in radians
13 orientation_rad = sense.get_orientation_radians()
14 print("\np: {pitch}, r: {roll}, y: {yaw}".format(**orientation_rad))
15
16
17 #get current orientation in degrees
18 orientation = sense.get_orientation_degrees()
19 print("\np: {pitch}, r: {roll}, y: {yaw}".format(**orientation))
20
21 raw = sense.get_compass_raw() #get the x,y,z magnetometer data
22 print("\nx: {x}, y: {y}, z: {z}".format(**raw))
23
24 # Define the colours red and green
25 red = (255, 0, 0)
26 green = (0, 255, 0)
27
28 while True:
29
30 # Take readings from all three sensors
31 t = sense.get_orientation_radians()
32 h = sense.get_compass_raw()
33 b = sense.get_orientation_degrees()
34
```

The codes are then outputted on the display board. Showing the thing that I asked for which are the pressure, its orientation in radians, its orientation in degrees and along with the x,y and z coordinates.

```
Pressure: 1013.02128269 Millibars  
p: 0, r: 0, y: 1.5707963267948966  
p: 0, r: 0, y: 90  
x: 0.18653879990618716, y: -32.97854303836398, z:  
0.09758146346006699
```

Adding in a couple of line of code made me be able to print out the information onto the sense hat RGB.



Conclusion:

In conclusion, this is just the first part of what I need to do for the final project, just by doing this and showing what I have it complete so far. The final project is going to be a more complete version of code that would involve different code integrated together. Although this doesn't have the actual physical part yet, the final project would have an actual part included in there so it is more complete.