

# CSci 127: Introduction to Computer Science



[hunter.cuny.edu/csci](http://hunter.cuny.edu/csci)

# Announcements



- Each lecture includes a survey of computing research and tech in NYC.

*Today: Prof. Susan Epstein  
Machine Learning*

# Today's Topics



- Recap: Functions & Top Down Design
- Mapping GIS Data
- Loops
- CS Survey

## In Pairs or Triples:

```
def prob4(amy, beth):  
    if amy > 4:  
        print("Easy case")  
        kate = -1  
    else:  
        print("Complex case")  
        kate = helper(amy,beth)  
    return(kate)
```

```
def helper(meg,jo):  
    s = ""  
    for j in range(meg):  
        print(j, ": ", jo[j])  
        if j % 2 == 0:  
            s = s + jo[j]  
    print("Building s:", s)  
    return(s)
```

- What are the formal parameters for the functions?
- What is the output of:

```
r = prob4(4,"city")  
print("Return:  ", r)
```

- What is the output of:

```
r = prob4(2,"university")  
print("Return:  ", r)
```

# Python Tutor

```
def prob4(any, beth):
    if any > 4:
        print("Easy case")
        kate = -1
    else:
        print("Complex case")
        kate = helper(any,beth)
    return(kate)

def helper(meg,jo):
    s = ""
    for j in range(meg):
        print(j, "; ", jo[j])
        if j % 2 == 0:
            s = s + jo[j]
        print("Building s:", s)
    return(s)
```

(Demo with pythonTutor)

# In Pairs or Triples:

- Write the missing functions for the program:

```
def main():
    tess = setUp()      #Returns a purple turtle with pen up.
    for i in range(5):
        x,y = getInput()      #Asks user for two numbers.
        markLocation(tess,x,y) #Move tess to (x,y) and stamp.
```

# Group Work: Fill in Missing Pieces

```
def main():
    tess = setUp()      #Returns a purple turtle with pen up.
    for i in range(5):
        x,y = getInput()          #Asks user for two numbers.
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```

# Group Work: Fill in Missing Pieces

- ① Write import statements.

```
import turtle
```

```
def main():
    tess = setUp()      #Returns a purple turtle with pen up.
    for i in range(5):
        x,y = getInput()          #Asks user for two numbers.
        markLocation(tess,x,y) #Move tess to (x,y) and stamp.
```

## Third Part: Fill in Missing Pieces

- ① Write import statements.
- ② Write down new function names and inputs.

```
import turtle
def setUp():
    #FILL IN
def getInput():
    #FILL IN
def markLocation(t,x,y):
    #FILL IN

def main():
    tess = setUp()      #Returns a purple turtle with pen up.
    for i in range(5):
        x,y = getInput()          #Asks user for two numbers.
        markLocation(tess,x,y)  #Move tess to (x,y) and stamp.
```

## Third Part: Fill in Missing Pieces

- ① Write import statements.
- ② Write down new function names and inputs.
- ③ Fill in return values.

```
import turtle
def setUp():
    #FILL IN
    return(newTurtle)
def getInput():
    #FILL IN
    return(x,y)
def markLocation(t,x,y):
    #FILL IN

def main():
    tess = setUp()      #Returns a purple turtle with pen up.
    for i in range(5):
        x,y = getInput()          #Asks user for two numbers.
        markLocation(tess,x,y) #Move tess to (x,y) and stamp.
```

## Third Part: Fill in Missing Pieces

- ① Write import statements.
- ② Write down new function names and inputs.
- ③ Fill in return values.
- ④ Fill in body of functions.

```
import turtle
def setUp():
    newTurtle = turtle.Turtle()
    newTurtle.penup()
    return(newTurtle)
def getInput():
    x = int(input('Enter x: '))
    y = int(input('Enter y: '))
    return(x,y)
def markLocation(t,x,y):
    t.goto(x,y)
    t.stamp()
def main():
    tess = setUp()      #Returns a purple turtle with pen up.
    for i in range(5):
        x,y = getInput()          #Asks user for two numbers.
        markLocation(tess,x,y)
```

# Top-Down Design

- The last example demonstrates **top-down design**: breaking into subproblems, and implementing each part separately.



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  - ▶ Translate list into function names & inputs/returns.

# Top-Down Design



- The last example demonstrates **top-down design**: breaking into subproblems, and implementing each part separately.
  - ▶ Break the problem into tasks for a “To Do” list.
  - ▶ Translate list into function names & inputs/returns.
  - ▶ Implement the functions, one-by-one.

# Top-Down Design



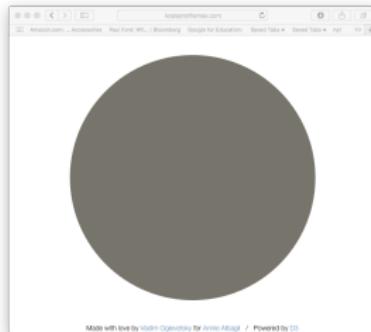
- The last example demonstrates **top-down design**: breaking into subproblems, and implementing each part separately.
  - ▶ Break the problem into tasks for a “To Do” list.
  - ▶ Translate list into function names & inputs/returns.
  - ▶ Implement the functions, one-by-one.
- Excellent approach since you can then test each part separately before adding it to a large program.

# Top-Down Design

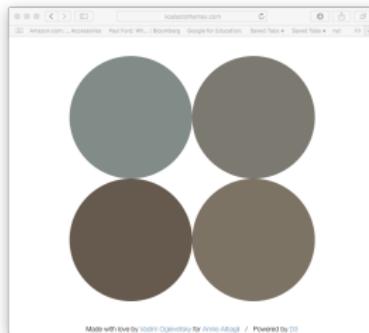
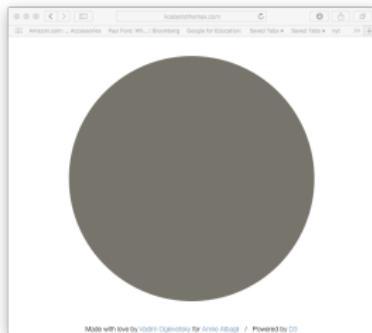


- The last example demonstrates **top-down design**: breaking into subproblems, and implementing each part separately.
  - ▶ Break the problem into tasks for a “To Do” list.
  - ▶ Translate list into function names & inputs/returns.
  - ▶ Implement the functions, one-by-one.
- Excellent approach since you can then test each part separately before adding it to a large program.
- Very common when working with a team: each has their own functions to implement and maintain.

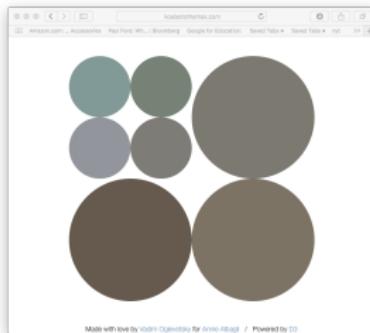
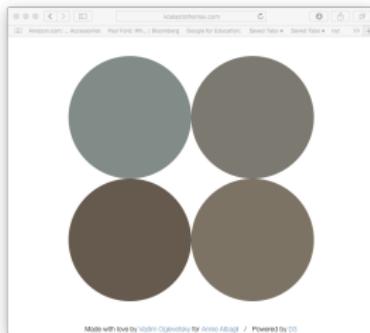
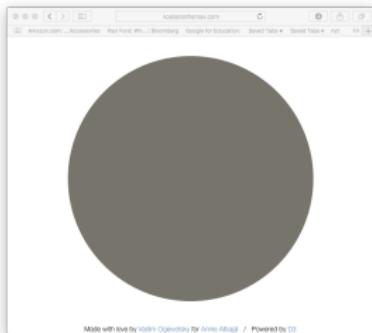
# From Last Time: koalas



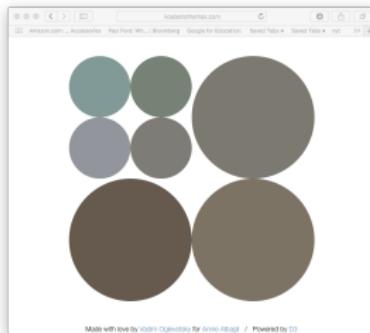
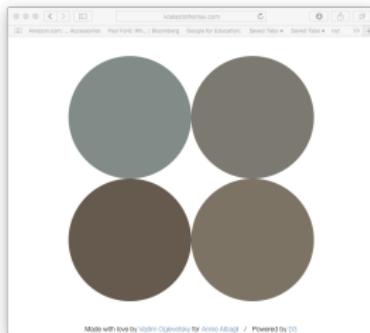
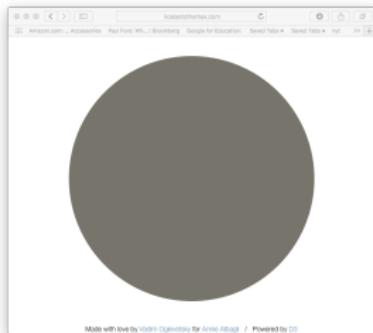
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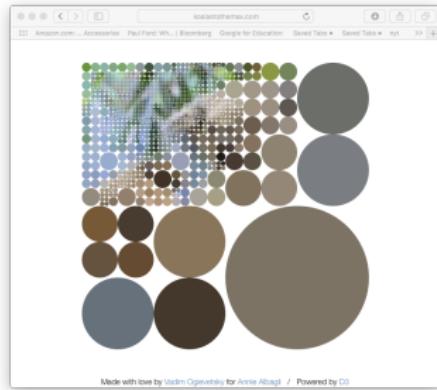


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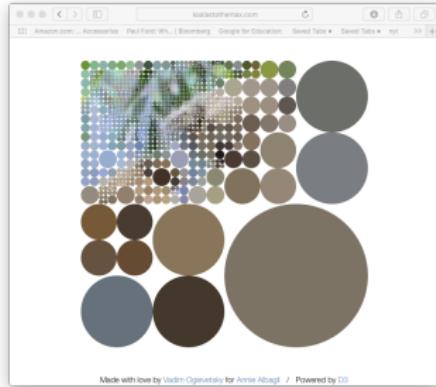


<http://koalastothemax.com>

# From Last Time: koalas



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- Top-down design puzzle:
  - ▶ What does koalastomax do?
  - ▶ What does each circle represent?
- Write a high-level design for it.
- Translate into a `main()` with function calls.

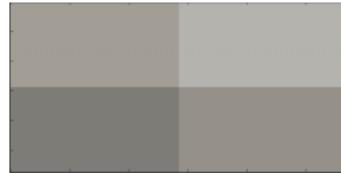
## From Last Time: koalas



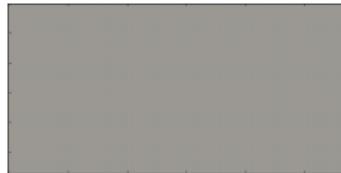
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  - ▶ What does each circle represent?
- Write a high-level design for it.
- Translate into a `main()` with function calls.

# From Last Time: koalas



```
69  def main():
70      inFile = input('Enter image file name: ')
71      img = plt.imread(inFile)
72
73      #Divides the image in 1/2, 1/4, 1/8, ... 1/2^8, and displays each:
74      for i in range(8):
75          img2 = img.copy()    #Make a copy to average
76          quarter(img2,i)    #Split in half i times, and average regions
77
78          plt.imshow(img2)    #Load our new image into pyplot
79          plt.show()           #Show the image (waits until closed to continue)
80
81      #Shows the original image:
82      plt.imshow(img)        #Load image into pyplot
83      plt.show()             #Show the image (waits until closed to continue)
84
85
```

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```

- The `main()` is written for you.

# From Last Time: koalas



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71      img = plt.imread(inFile)
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85
```

- The `main()` is written for you.
- Only fill in two functions: `average()` and `setRegion()`.

# From Last Time: koalas

*Process:*

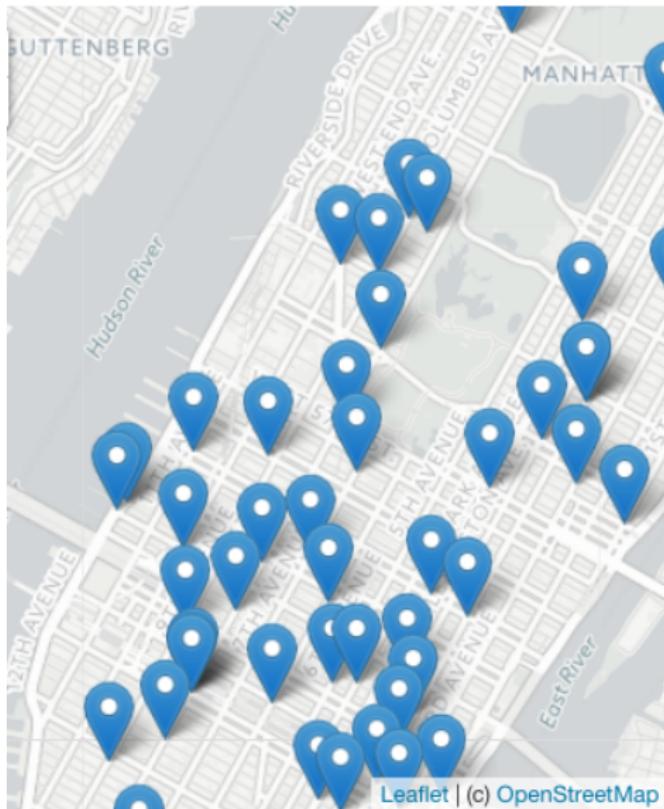


# Today's Topics



- Recap: Functions & Top Down Design
- **Mapping GIS Data**
- Loops
- CS Survey

# Folium



# Folium

- A module for making HTML maps.

# Folium



# Folium

## Folium



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- It's a Python interface to the popular `leaflet.js`.

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- Outputs `.html` files which you can open in a browser.

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- It's a Python interface to the popular `leaflet.js`.
- Outputs `.html` files which you can open in a browser.
- An extra step:

# Folium

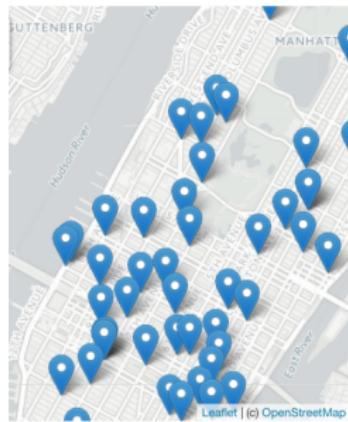
## Folium



- A module for making HTML maps.
- It's a Python interface to the popular `leaflet.js`.
- Outputs `.html` files which you can open in a browser.
- An extra step:

*Write code.* → *Run program.* → *Open .html in browser.*

# Demo



(Map created by Folium.)

# Folium

- To use:

```
import folium
```

# Folium



# Folium

## Folium



- To use:

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- Create a map:

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myMap = folium.Map()
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# Folium

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newMark = folium.Marker([lat,lon],popup=name)
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- Add to the map:

```
newMark.add_to(myMap)
```

# Folium

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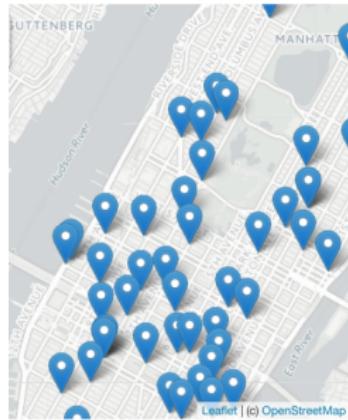
```
newMark = folium.Marker([lat,lon],popup=name)
```

- Add to the map:

```
newMark.add_to(myMap)
```

- Many options to customize background map ("tiles") and markers.

# Demo



(Python program using Folium.)

# In Pairs of Triples

- Predict which each line of code does:

```
m = folium.Map(  
    location=[45.372, -121.6972],  
    zoom_start=12,  
    tiles='Stamen Terrain'  
)  
  
folium.Marker(  
    location=[45.3288, -121.6625],  
    popup='Mt. Hood Meadows',  
    icon=folium.Icon(icon='cloud')  
) .add_to(m)  
  
folium.Marker(  
    location=[45.3311, -121.7113],  
    popup='Timberline Lodge',  
    icon=folium.Icon(color='green')  
) .add_to(m)  
  
folium.Marker(  
    location=[45.3300, -121.6823],  
    popup='Some Other Location',  
    icon=folium.Icon(color='red', icon='info-sign')  
) .add_to(m)
```



(example from Folium documentation)

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- **Loops**
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## In Pairs or Triples:

Predict what the code will do:

```
dist = int(input('Enter distance: '))
while dist < 0:
    print('Distances cannot be negative.')
    dist = int(input('Enter distance: '))
    ...
print('The distance entered is', dist)
```

#Spring 2012 Final Exam, #8

```
nums = [1,4,0,6,5,2,9,8,12]
print(nums)
i=0
while i < len(nums)-1:
    if nums[i] < nums[i+1]:
        nums[i], nums[i+1] = nums[i+1], nums[i]
    i=i+1
    ...
print(nums)
```

# Python Tutor

```
dist = int(input('Enter distance: '))
while dist < 0:
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    i+=1
print(nums)
```

(Demo with pythonTutor)

# Indefinite Loops

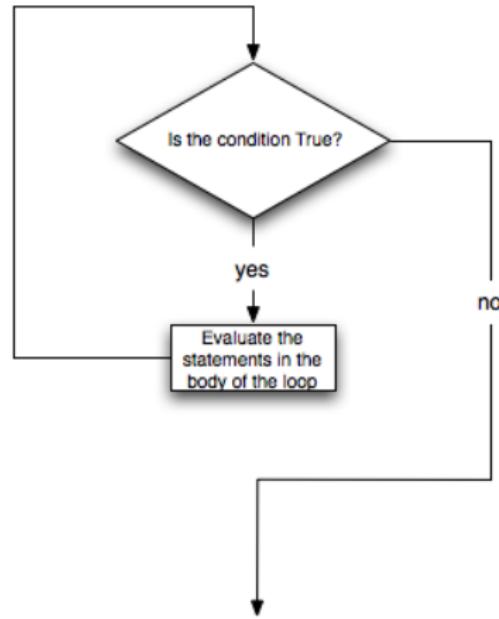
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# Indefinite Loops

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dist = int(input('Enter distance: '))
while dist < 0:
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# Indefinite Loops

- Indefinite loops repeat as long as the condition is true.

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dist = int(input('Enter distance: '))
while dist < 0:
    print('Distances cannot be negative.')
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    i=i+1
print(nums)
```

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```

- Indefinite loops repeat as long as the condition is true.
- Could execute the body of the loop zero times, 10 times, infinite number of times.

# Indefinite Loops

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```

- Indefinite loops repeat as long as the condition is true.
- Could execute the body of the loop zero times, 10 times, infinite number of times.
- The condition determines how many times.
- Very useful for checking input, simulations, and games.

# Python's random package

- Python has a built-in package for generating pseudo-random numbers.

```
import turtle
import random

trey = turtle.Turtle()
trey.speed(10)

for i in range(100):
    trey.forward(10)
    a = random.randrange(0, 360, 90)
    trey.right(a)
```

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- Useful command to generate whole numbers:

```
random.randrange(start,stop,step)
```

which gives a number chosen randomly from the specified range.

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- Useful command to generate real numbers:

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random.randrange(start,stop,step)
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which gives a number chosen randomly from the specified range.

- Useful command to generate real numbers:

```
random.random()
```

which gives a number chosen (uniformly) at random from [0.0,1.0].

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import turtle
import random

trey = turtle.Turtle()
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for i in range(100):
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- Useful command to generate real numbers:

```
random.random()
```

which gives a number chosen (uniformly) at random from [0.0,1.0].

- Very useful for simulations, games, and testing.

# Trinket

```
import turtle  
import random  
  
trey = turtle.Turtle()  
trey.speed(10)  
  
for i in range(100):  
    trey.forward(10)  
    a = random.randrange(0,360,90)  
    trey.right(a)
```

(Demo turtle  
random walk)

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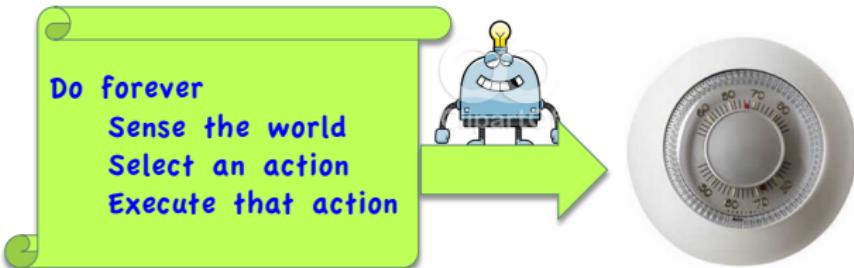
# CS Survey Talk



Prof. Susan Epstein  
(Machine Learning)

# Computational agents

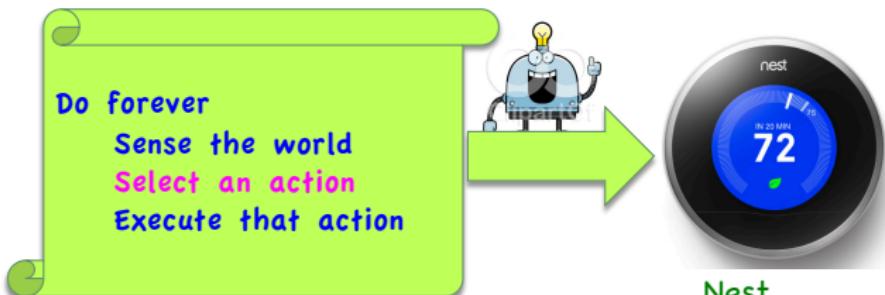
- Computational system implements decisions and actions on a physical device
- A computational agent executes a perpetual sense-decide-act loop



- How to sense the world: infrared sonar radar Kinect microphone camera
- Given a set of possible actions, an agent decides by selecting one

# Artificial intelligence (AI)

- An AI agent doesn't have to be a **robot** (embodied in the world)
- An AI agent doesn't have to be **autonomous** (make decisions entirely on its own)
- But it does have to be smart...
- That means it has to make smart decisions
- **Artificial intelligence** = **simulation** of intelligent (**human**) **behavior** by a computational agent



# What AI does

- Tackles hard, interesting problems
  - Does this image show cancer?
  - Should I move this car through the intersection?
  - How do I get to that concert?
- Builds models of perception, thinking, and action
- Uses these models to build smarter programs



Apollo and ROSie

Our autonomous robot navigators

- Despite uncertainty, noise, and constant changes in the world
- Learn models of their environment
- Make smart decisions with those models

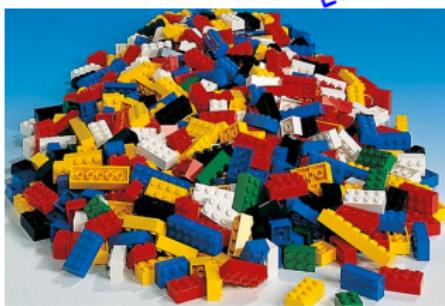
## How our robots navigate

- We built SemaFORR, a robot controller that makes decisions autonomously
- First the robots learn to travel by building a model of the world we put them in
- Then they prove they can find both hard and easy targets there
- Apollo has already done this on a small part of the 10<sup>th</sup> floor here
- And in simulation ROSie has traveled
  - Through much of Hunter, The Graduate Center, and MOMA
  - Through moving crowds of people
  - Without collision and without coming too close to people
  - And explained her behavior in natural language

# How to build an intelligent agent

- Find good problems
- Start simple
- Run lots of experiments
- Analyze the results carefully
- ...and repeat

Fun problems  
Good reasons  
Learning algorithms



## Want to know more?

- Fall 2018: SCI 111 Brains, Minds, and Machines = cognitive neuroscience + cognitive psychology + AI
- Fall 2019: CSCI 350 Artificial Intelligence
- Fall 2018: CSCI 353 Machine Learning
- ...and then there's my lab, where workstations run 24/7, learning to be intelligent agents

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- On lecture slip, write down a topic you wish we had spent more time (and why).



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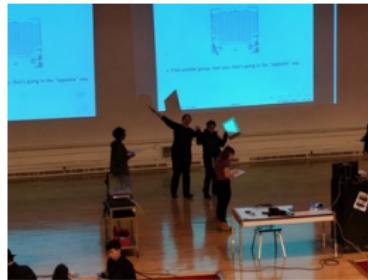
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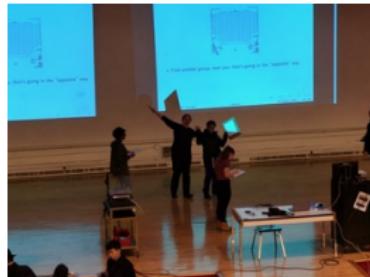
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# Practice Quiz & Final Questions



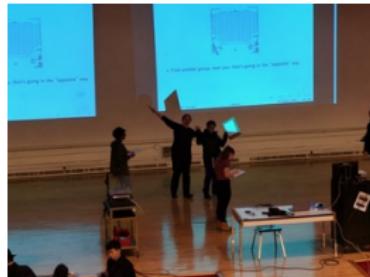
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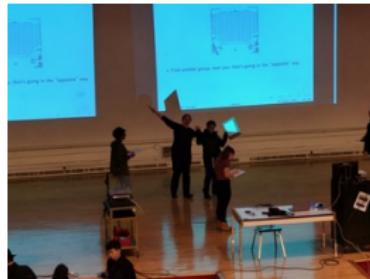
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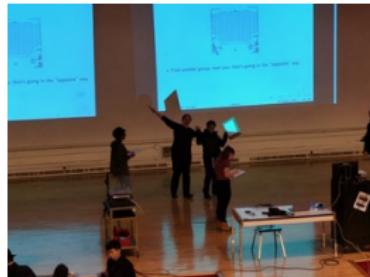
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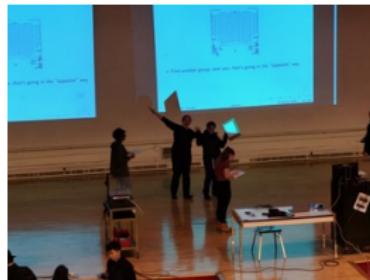
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- Theme: Functions & Top-Down Design (Summer 18, #7 & #5).