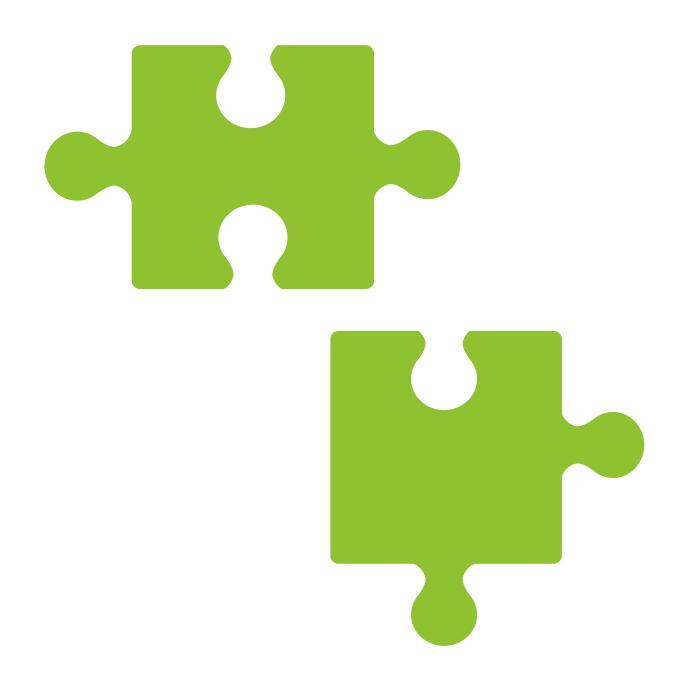
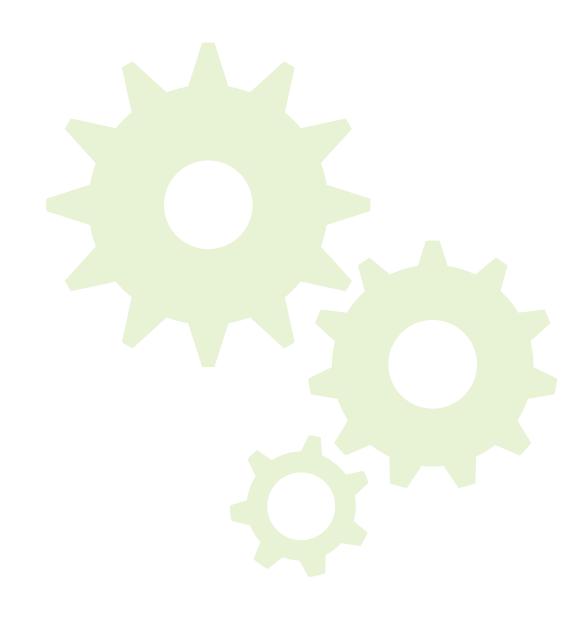


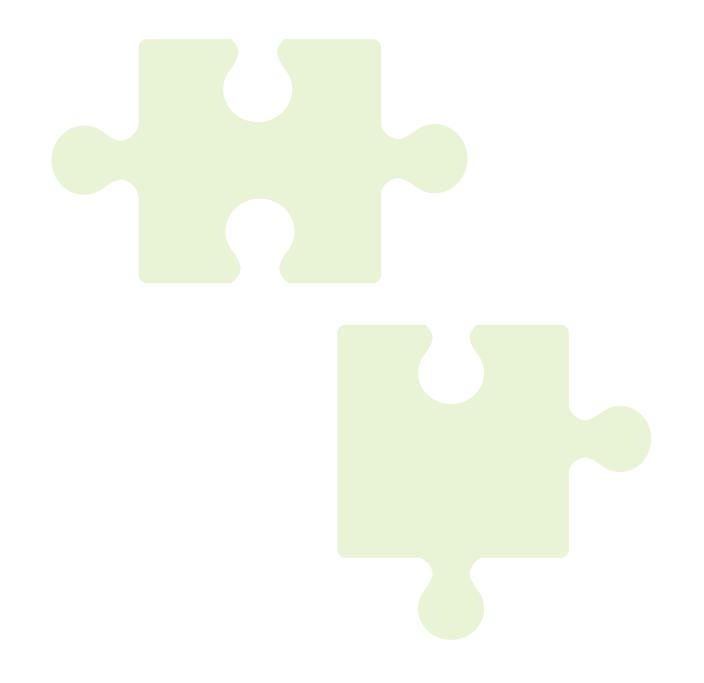
William Benton willb@redhat.com • @willb



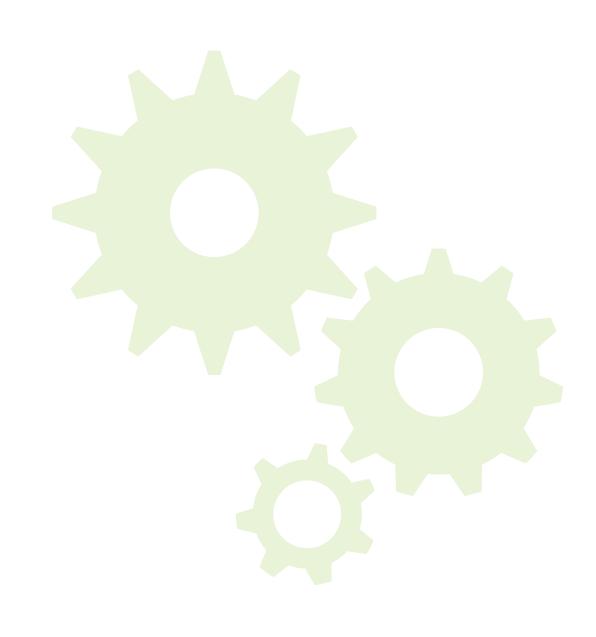




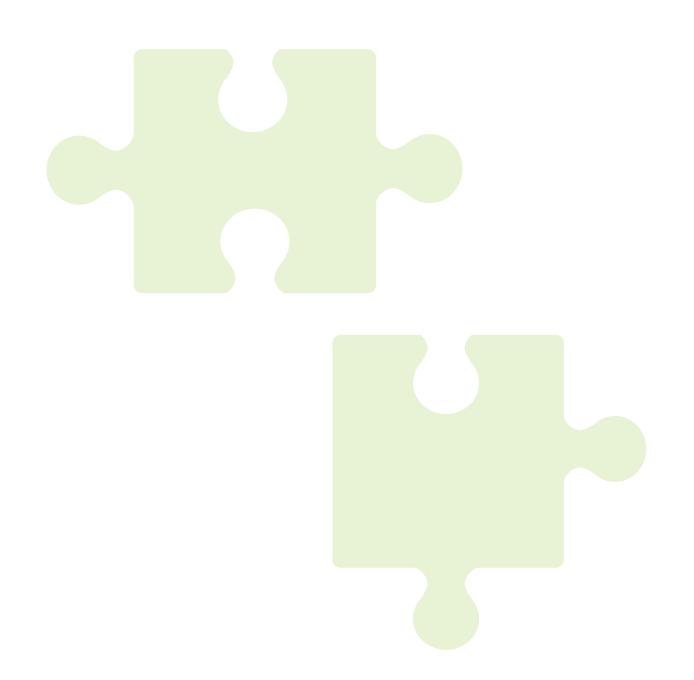








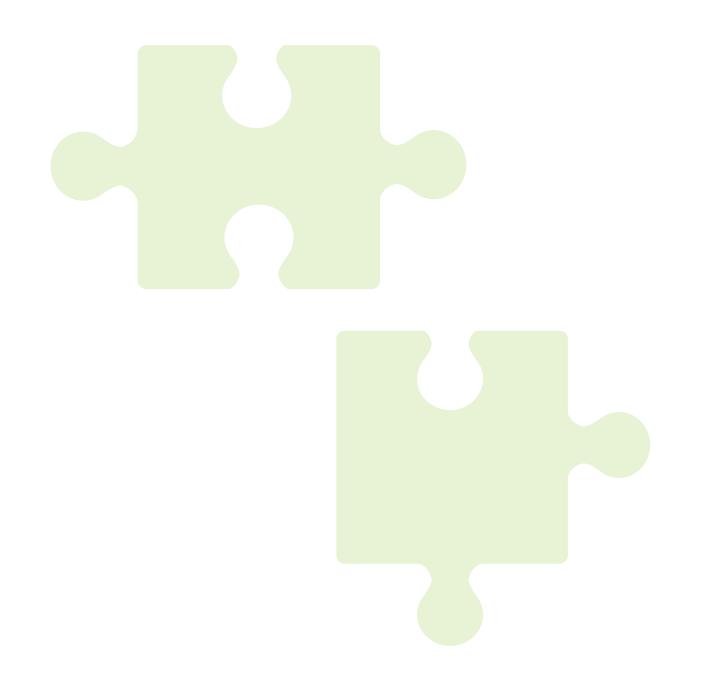




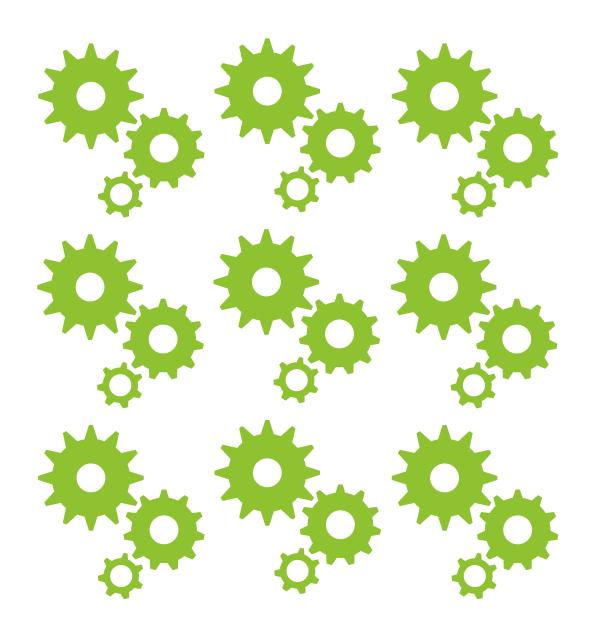














Forecast

Introducing our case study: self-organizing maps

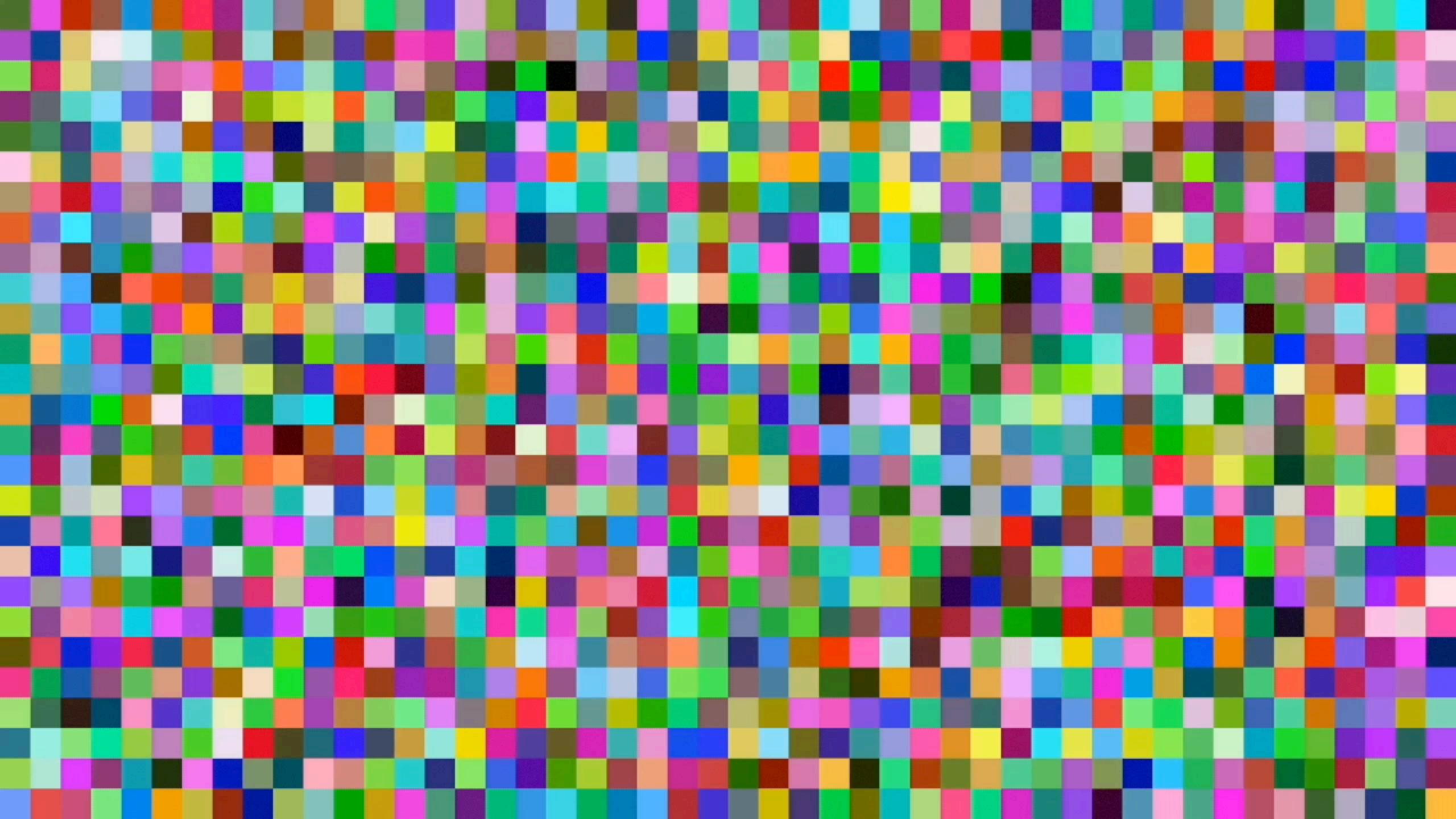
Parallel implementations for partitioned collections (in particular, RDDs)

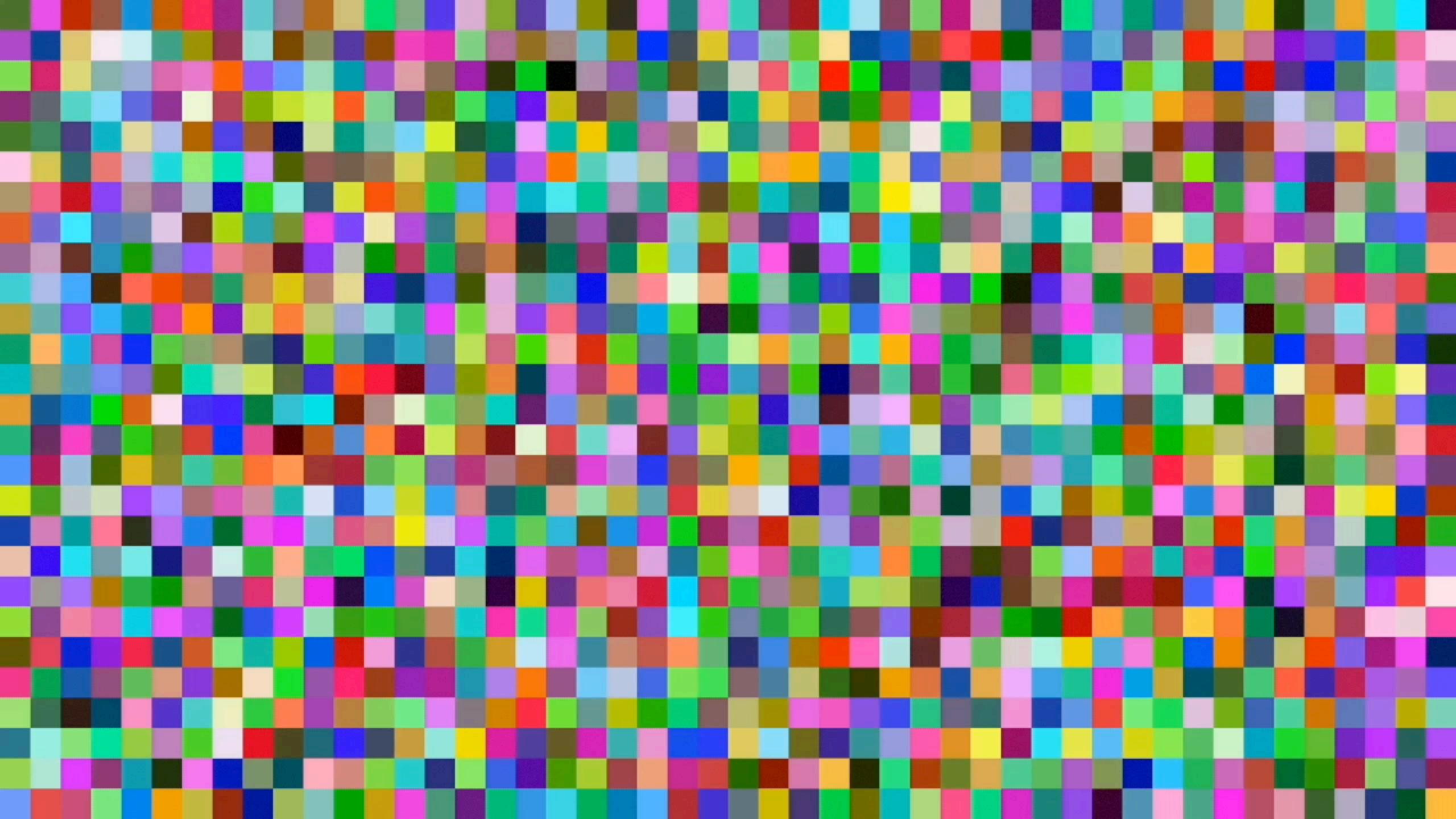
Beyond the RDD: data frames and ML pipelines

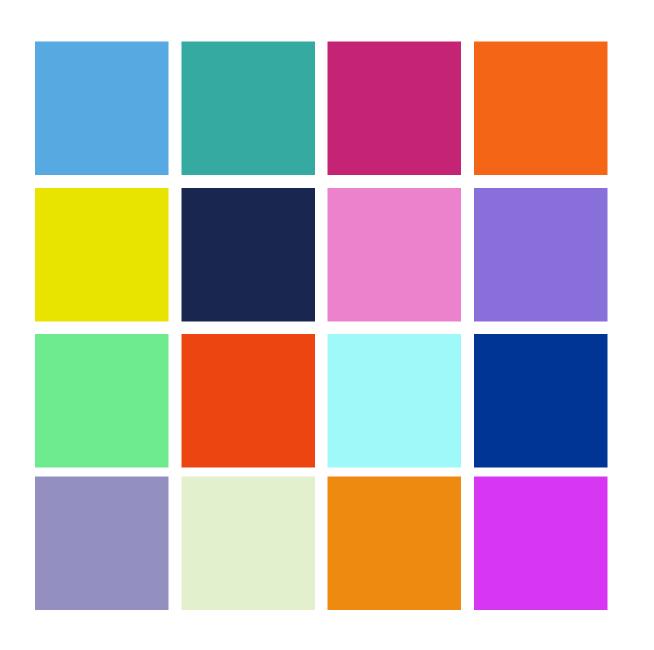
Practical considerations and key takeaways



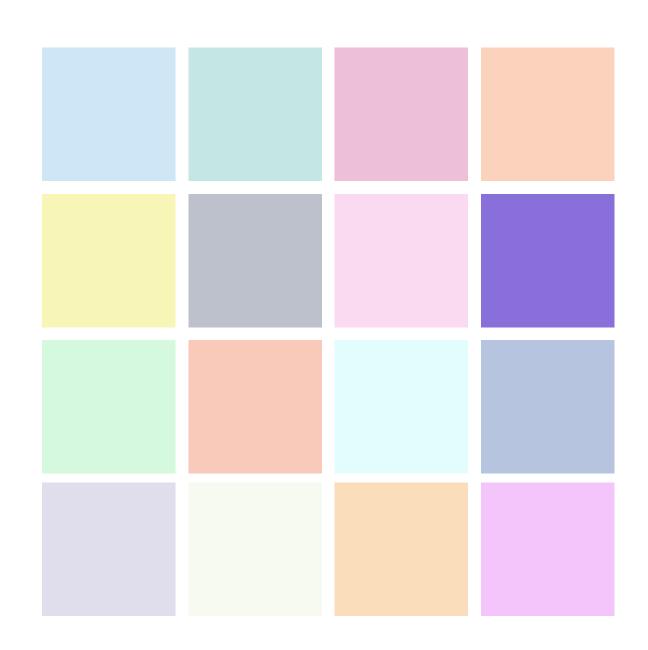
Introducing our case study



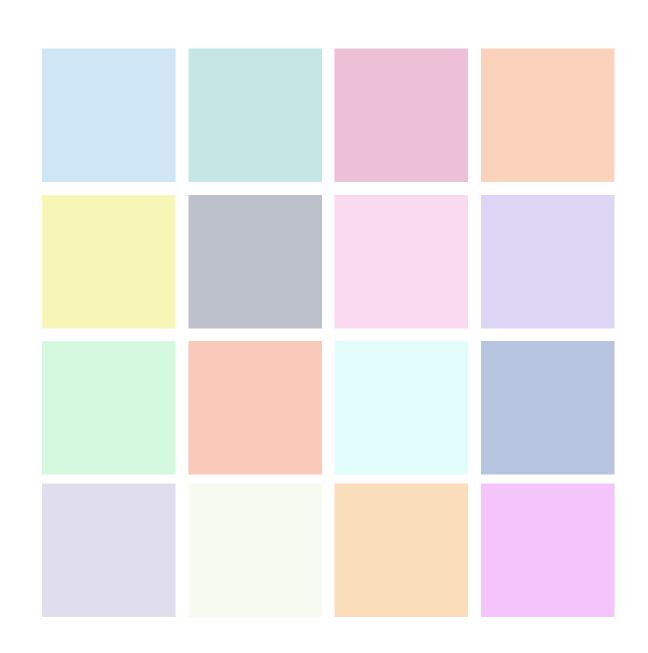




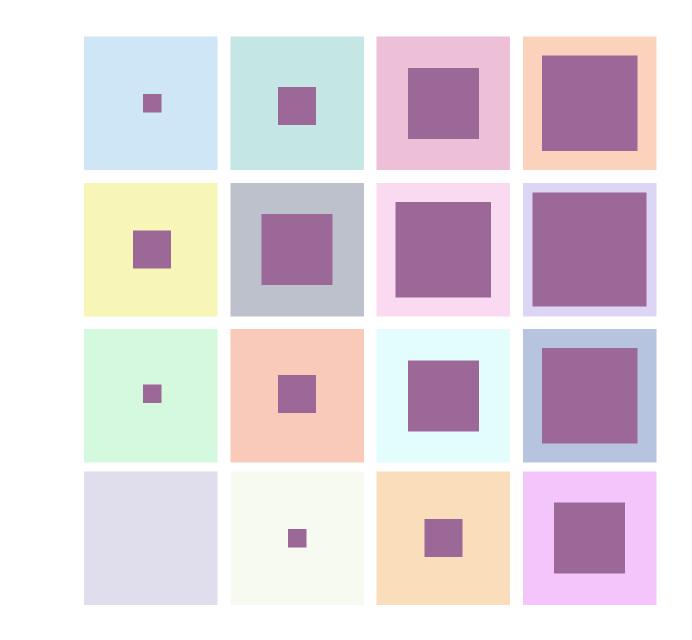














```
while t < maxupdates:
    random.shuffle(examples)
    for ex in examples:
        t = t + 1
        if t == maxupdates:
            break
        bestMatch = closest(somt, ex)
        for (unit, wt) in neighborhood(bestMatch, sigma(t)):
        somt+1[unit] = somt[unit] + (ex - somt[unit]) * alpha(t) * wt</pre>
```



```
process the training
while t < maxupdates:</pre>
                                     set in random order
 random.shuffle(examples)
 for ex in examples:
    t = t + 1
    if t == maxupdates:
      break
    bestMatch = closest(som_t, ex)
    for (unit, wt) in neighborhood(bestMatch, sigma(t)):
      som_{t+1}[unit] = som_t[unit] + (ex - som_t[unit]) * alpha(t) * wt
```



```
process the training
while t < maxupdates:</pre>
                                      set in random order
 random.shuffle(examples)
 for ex in examples:
                                 the neighborhood size controls
    t = t + 1
                                  how much of the map around
    if t == maxupdates:
                                     the BMU is affected
       break
    bestMatch = closest(som_t, ex)
    for (unit, wt) in neighborhood(bestMatch, sigma(t)):
       som_{t+1}[unit] = som_t[unit] + (ex - som_t[unit]) * alpha(t) * wt
```



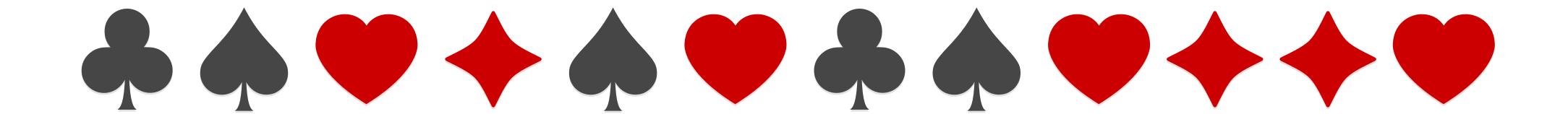
```
process the training
while t < maxupdates:</pre>
                                        set in random order
                                                              the learning rate controls
 random.shuffle(examples)
                                                               how much closer to the
 for ex in examples:
                                                               example each unit gets
                                  the neighborhood size controls
     t = t + 1
                                   how much of the map around
     if t == maxupdates:
                                      the BMU is affected
       break
     bestMatch = closest(som_t, ex)
     for (unit, wt) in neighborhood(bestMatch, sigma(t)):
       som_{t+1}[unit] = som_t[unit] + (ex - som_t[unit]) * alpha(t)
```

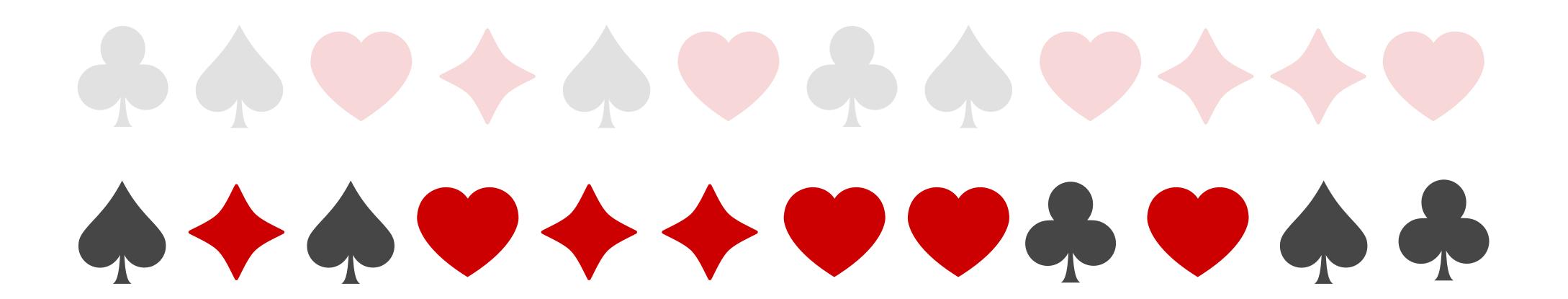


Parallel implementations for partitioned collections

Historical aside: Amdahl's Law

$$\lim_{s_p \to \infty} S_0 = \frac{1}{1 - p}$$





```
state[t+1] =
  combine(state[t], x)
```



```
state[t+1] =
  combine(state[t], x)
```





f1: (T, T) => T

f2: (T, U) => T



```
f1: (T, T) => T
f2: (T, U) => T
```



```
f1: (T, T) => T
f2: (T, U) => T
```



$$(a \oplus b) \oplus c = a \oplus (b \oplus c)$$

$$a \oplus b = b \oplus a$$

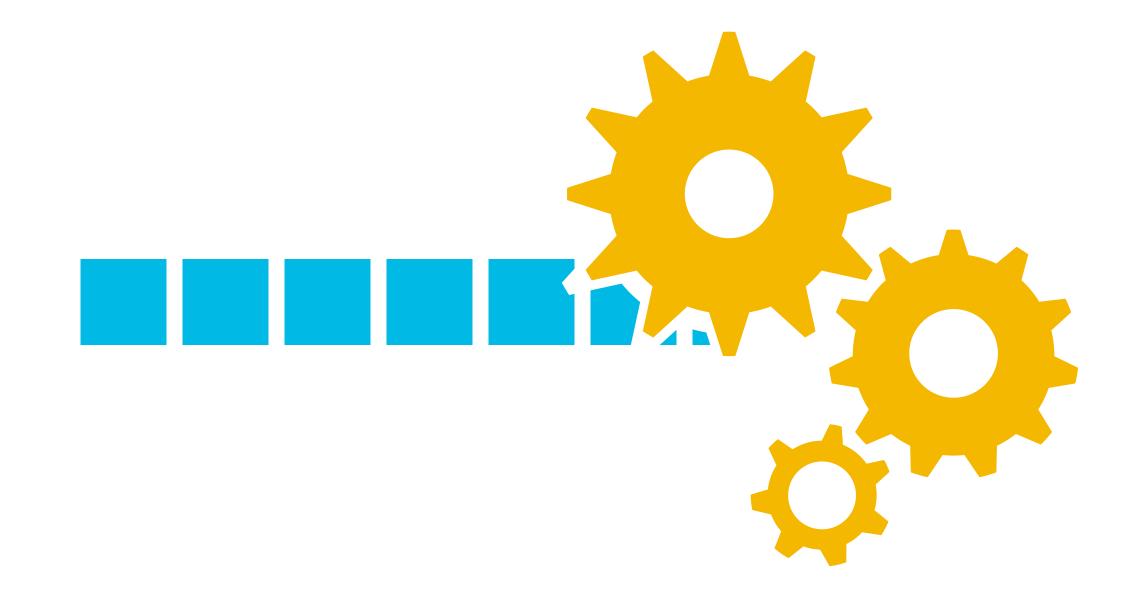
 $(a \oplus b) \oplus c = a \oplus (b \oplus c)$





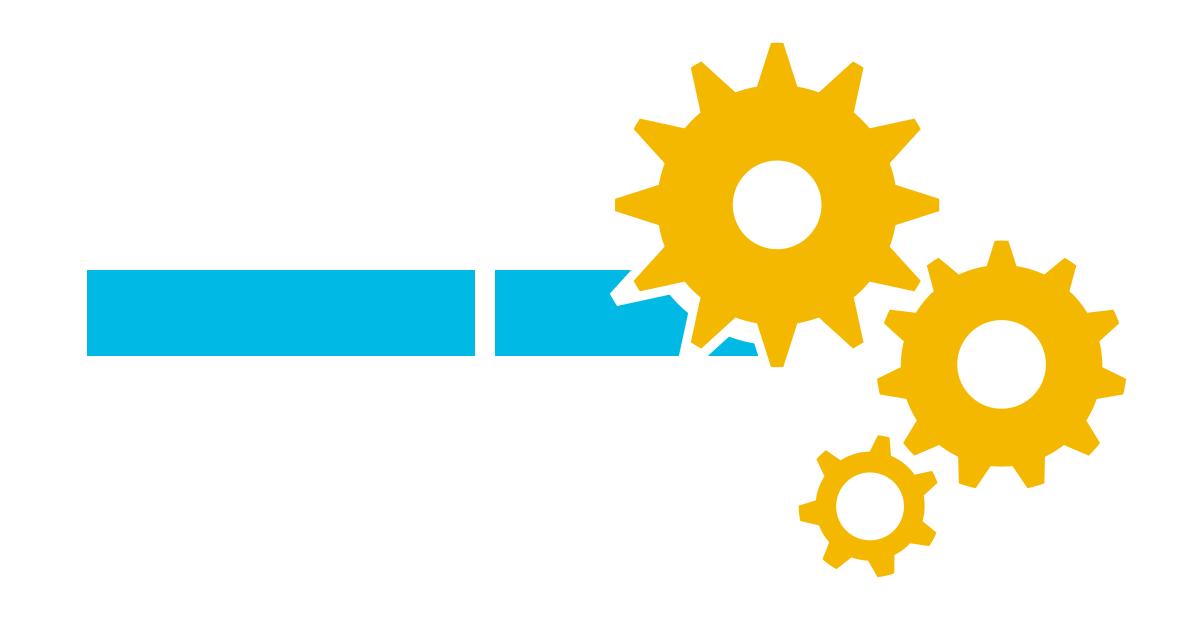
$$a \oplus b = b \oplus a$$

$$(a \oplus b) \oplus c = a \oplus (b \oplus c)$$



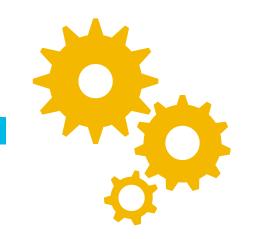
$$a \oplus b = b \oplus a$$

 $(a \oplus b) \oplus c = a \oplus (b \oplus c)$

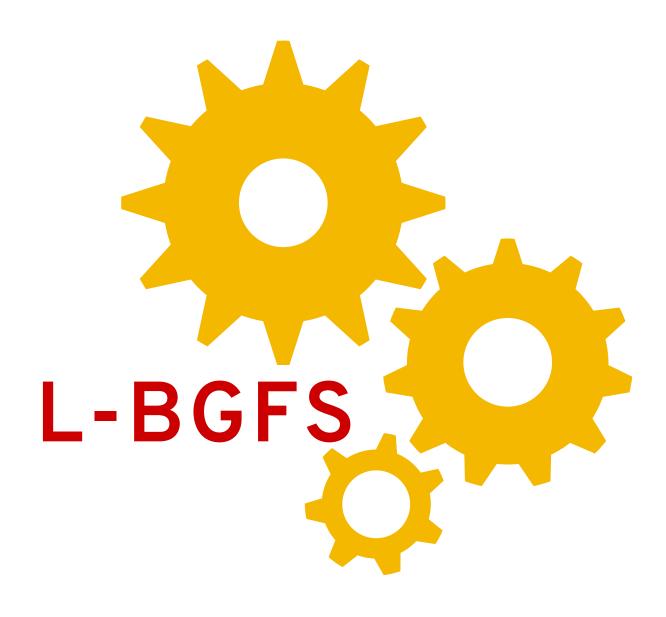


$$a \oplus b = b \oplus a$$

$$(a \oplus b) \oplus c = a \oplus (b \oplus c)$$

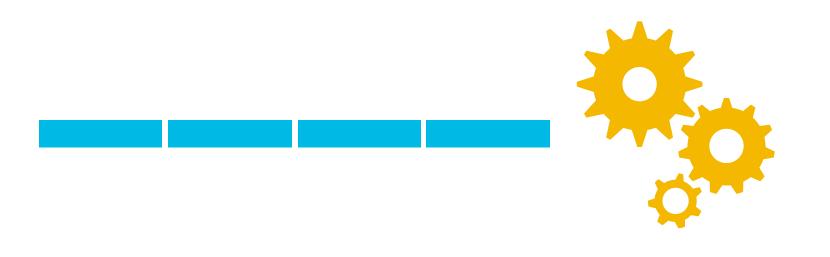






$$a \oplus b = b \oplus a$$

$$(a \oplus b) \oplus c = a \oplus (b \oplus c)$$







There will be examples of each of these approaches for many problems in the literature and in open-source code!



We'll start with a batch implementation of our technique:

```
for t in (1 to iterations):
    state = newState()
    for ex in examples:
        bestMatch = closest(som<sub>t-1</sub>, ex)
        hood = neighborhood(bestMatch, sigma(t))
        state.matches += ex * hood
        state.hoods += hood
        som<sub>t</sub> = newSOM(state.matches / state.hoods)
```



```
for t in (1 to iterations):
    state = newState()
    for ex in examples:
        bestMatch = closest(som<sub>t-1</sub>, ex)
        hood = neighborhood(bestMatch, sigma(t))
        state.matches += ex * hood
        state.hoods += hood
        som<sub>t</sub> = newSOM(state.matches / state.hoods)
```

Each batch produces a model that can be averaged with other models

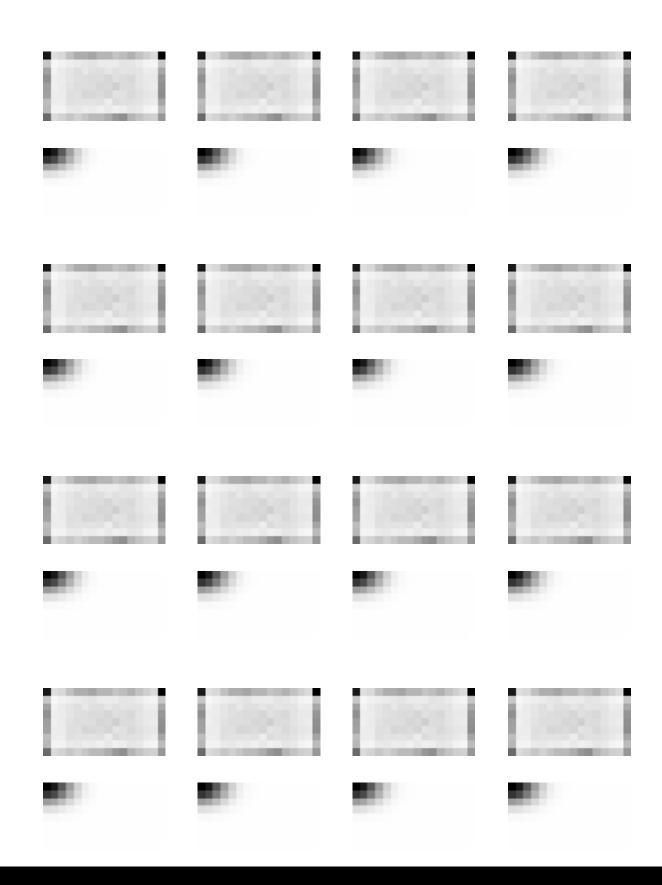


```
for t in (1 to iterations):
 state = newState()
 for ex in examples:
   bestMatch = closest(som_{t-1}, ex)
   hood = neighborhood(bestMatch, sigma(t))
   state.matches += ex * hood
   state.hoods += hood
 somt = newSOM(state.matches / state.hoods)
 partition
Each batch produces a model that
 can be averaged with other models
```



```
for t in (1 to iterations):
    state = newState()
    for ex in examples:
        bestMatch = closest(som<sub>t-1</sub>, ex)
        hood = neighborhood(bestMatch, sigma(t))
        state.matches += ex * hood
        state.hoods += hood
        som<sub>t</sub> = newSOM(state.matches / state.hoods)
```

This won't always work!









```
var nextModel = initialModel
for (int i = 0; i < iterations; <math>i++) {
  val current = sc.broadcast(nextModel)
  val newState = examples.aggregate(ModelState.empty()) {
    { case (state: ModelState, example: Example) =>
      state.update(current.value.lookup(example, i), example) }
    { case (s1: ModelState, s2: ModelState) => s1.combine(s2) }
  nextModel = modelFromState(newState)
  current.unpersist
                                                            "reduce": combine the
                                                          states from two partitions
```



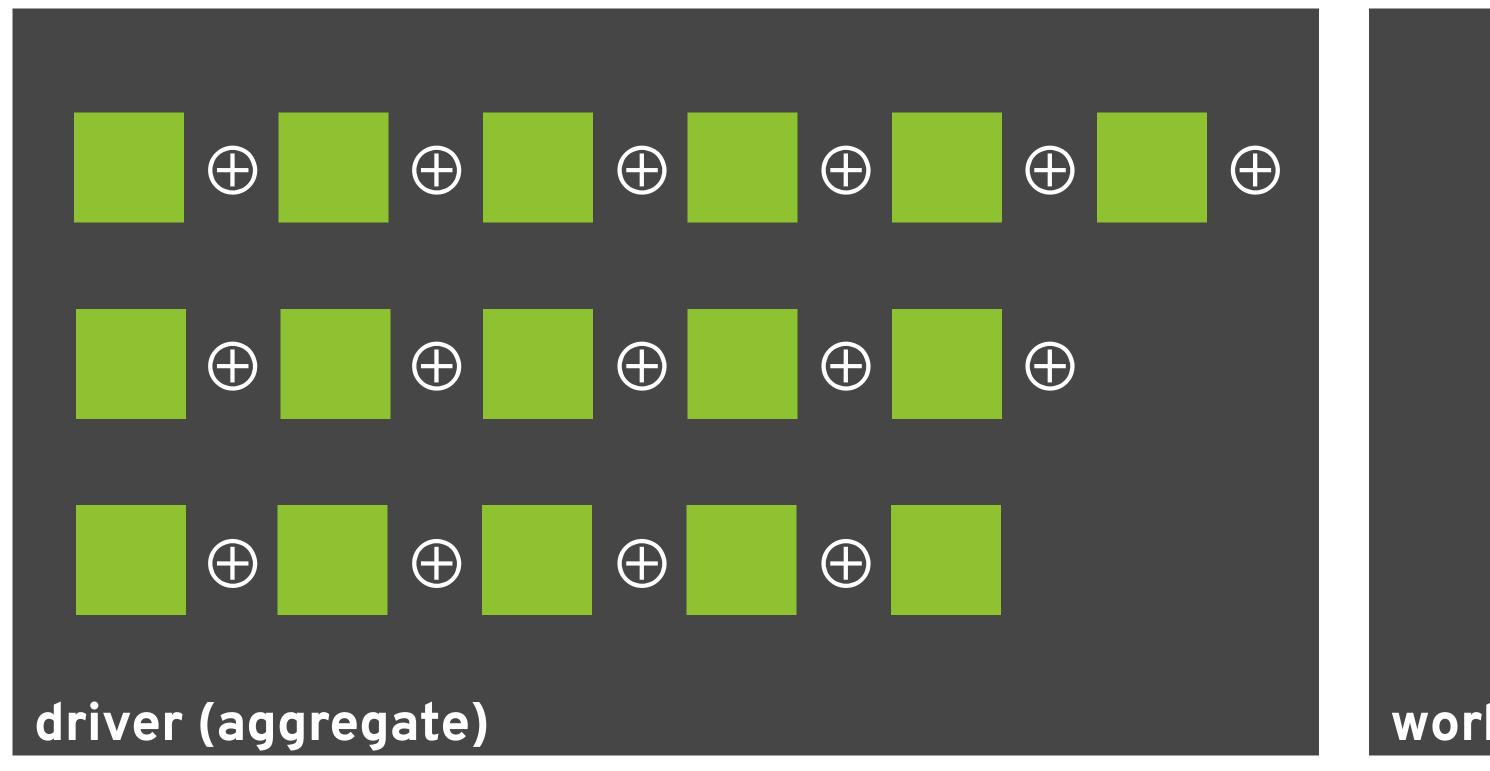
```
broadcast the current working
var nextModel = initialModel
                                                     model for this iteration
for (int i = 0; i < iterations; i++) {</pre>
  val current = sc.broadcast(nextModel) 
  val newState = examples.aggregate(ModelState.empty()) {
    { case (state: ModelState, example: Example) =>
      state.update(current.value.lookup(example, i), example) }
    { case (s1: ModelState, s2: ModelState) => s1.combine(s2) }
  nextModel = modelFromState(newState)
  current.unpersist
                             remove the stale
                            broadcasted model
```

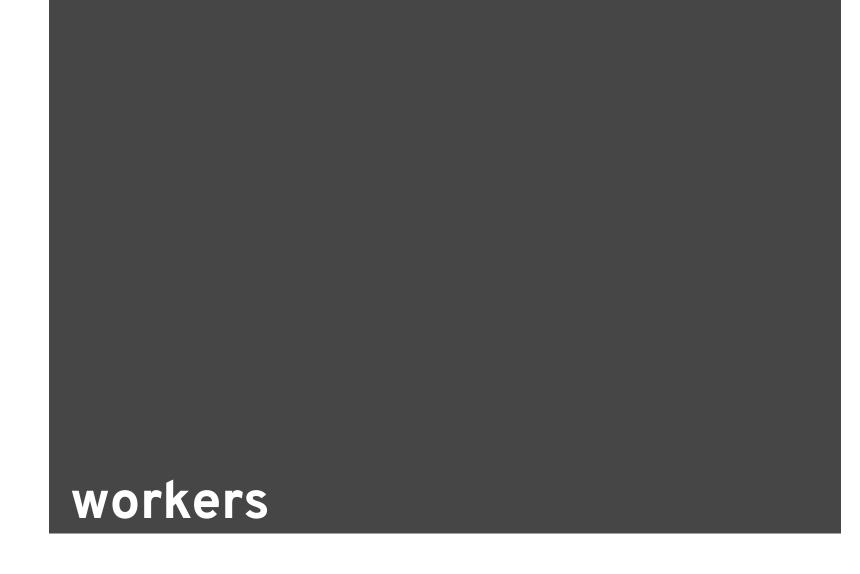














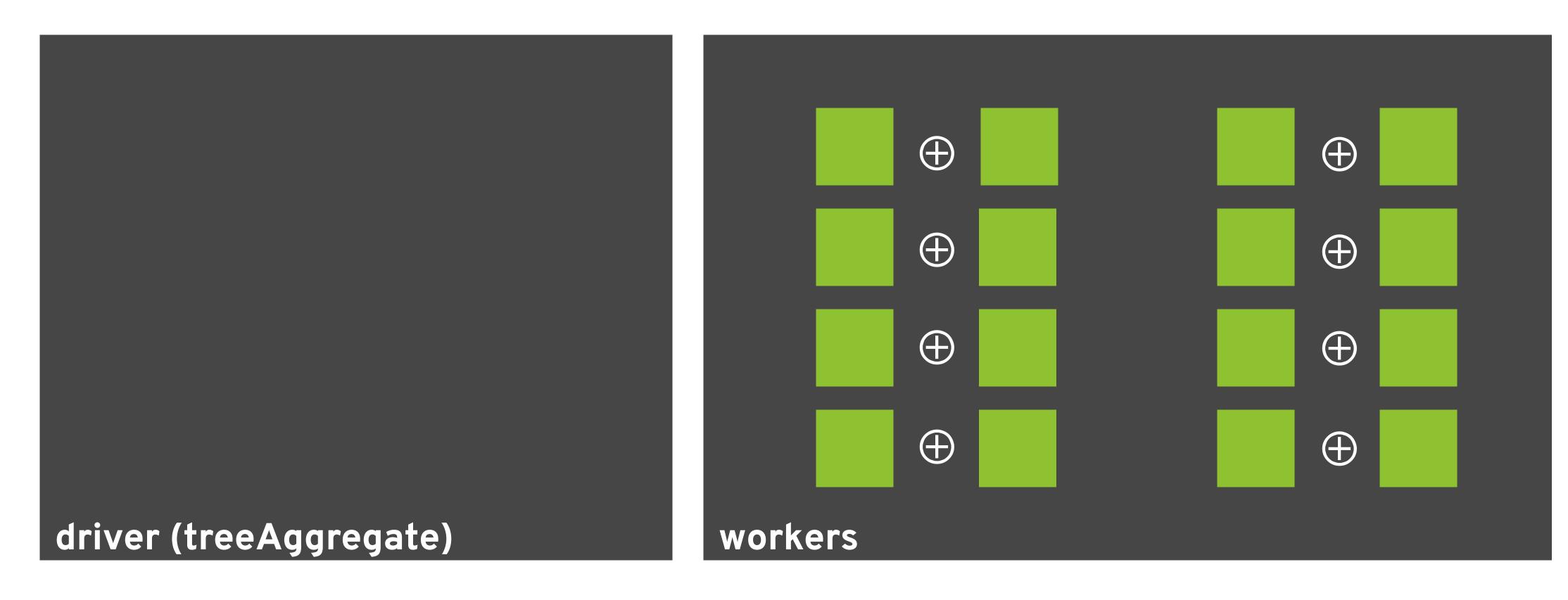




















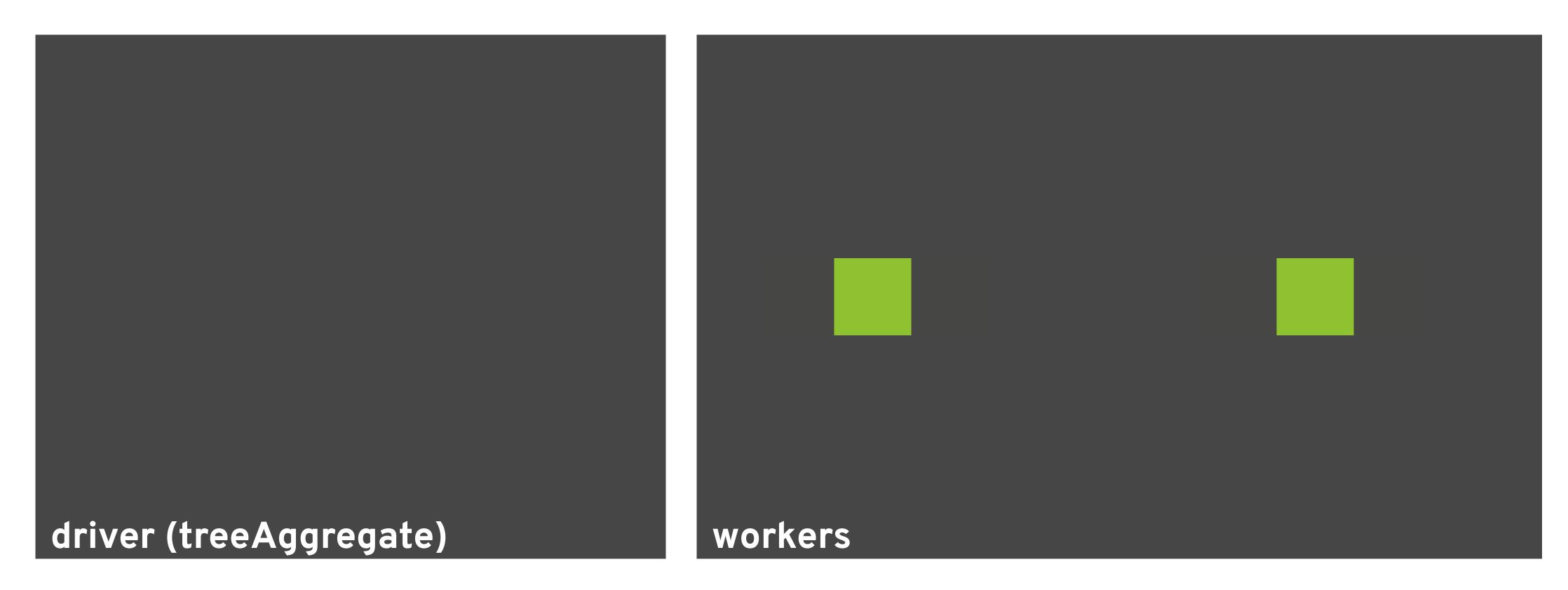


















Beyond the RDD: Data frames and ML Pipelines

```
val rdd: RDD[String] = /* ... */
rdd.map(_ * 3.0).collect()
```



```
val rdd: RDD[String] = /* ... */
rdd.map(_ * 3.0).collect()
```



```
val rdd: RDD[String] = /* ... */
rdd.map(_ * 3.0).collect()

val df: DataFrame = /* data frame with one String-valued column */
df.select($"_1" * 3.0).show()
```



```
val rdd: RDD[String] = /* ... */
rdd.map(_ * 3.0).collect()

val df: DataFrame = /* data frame with one String-valued column */
df.select($"_1" * 3.0).show()
```



```
rdd.map {
  vec => (vec, model.value.closestWithSimilarity(vec))
}
```



```
rdd.map {
 vec => (vec, model.value.closestWithSimilarity(vec))
val predict = udf ((vec: SV) =>
  model.value.closestWithSimilarity(vec))
df.withColumn($"predictions", predict($"features"))
```



RDDs versus query planning

```
val numbers1 = sc.parallelize(1 to 100000000)
val numbers2 = sc.parallelize(1 to 1000000000)
numbers1.cartesian(numbers2)
   .map((x, y) => (x, y, expensive(x, y)))
   .filter((x, y, _) => isPrime(x), isPrime(y))
```



RDDs versus query planning

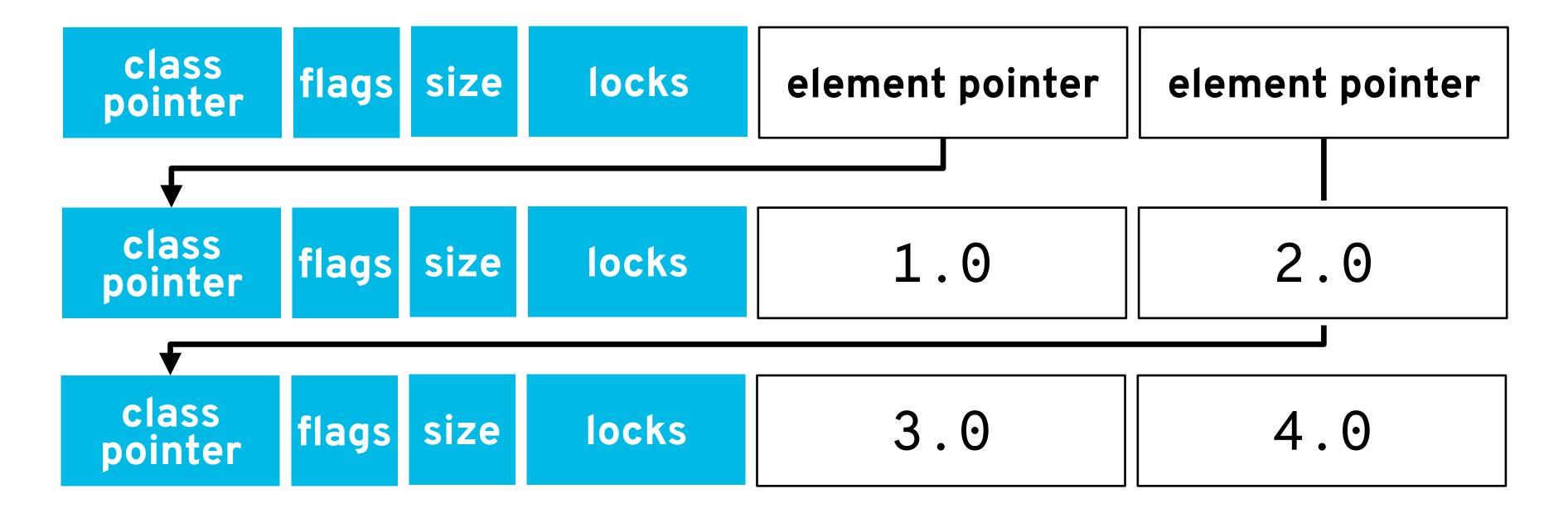
```
val numbers1 = sc.parallelize(1 to 100000000)
val numbers2 = sc.parallelize(1 to 1000000000)
numbers1.filter(isPrime(_))
    .cartesian(numbers2.filter(isPrime(_)))
    .map((x, y) => (x, y, expensive(x, y)))
```



```
val mat = Array(Array(1.0, 2.0), Array(3.0, 4.0))
```

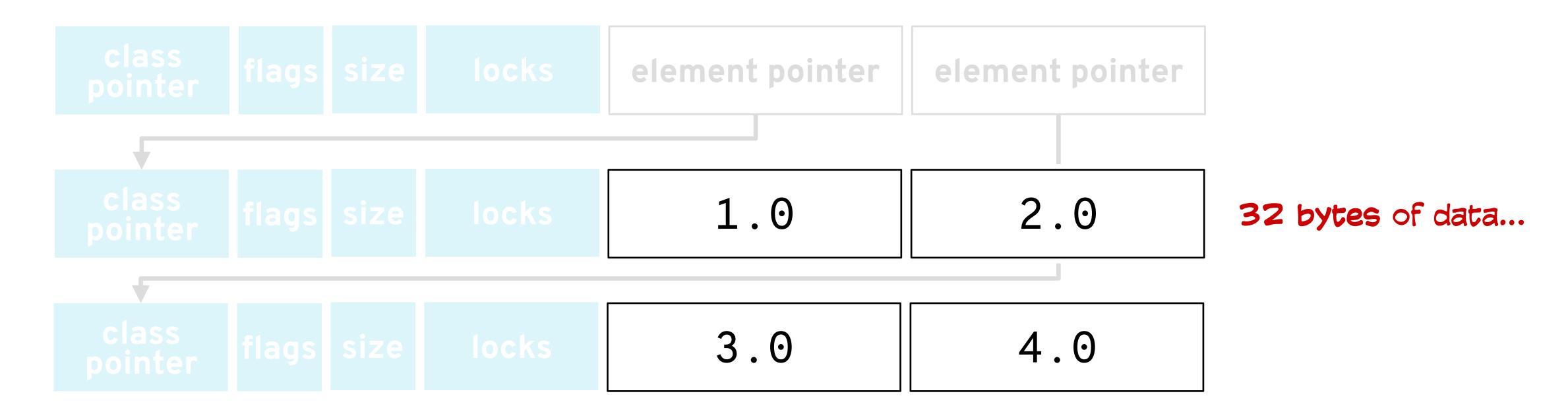


val mat = Array(Array(1.0, 2.0), Array(3.0, 4.0))



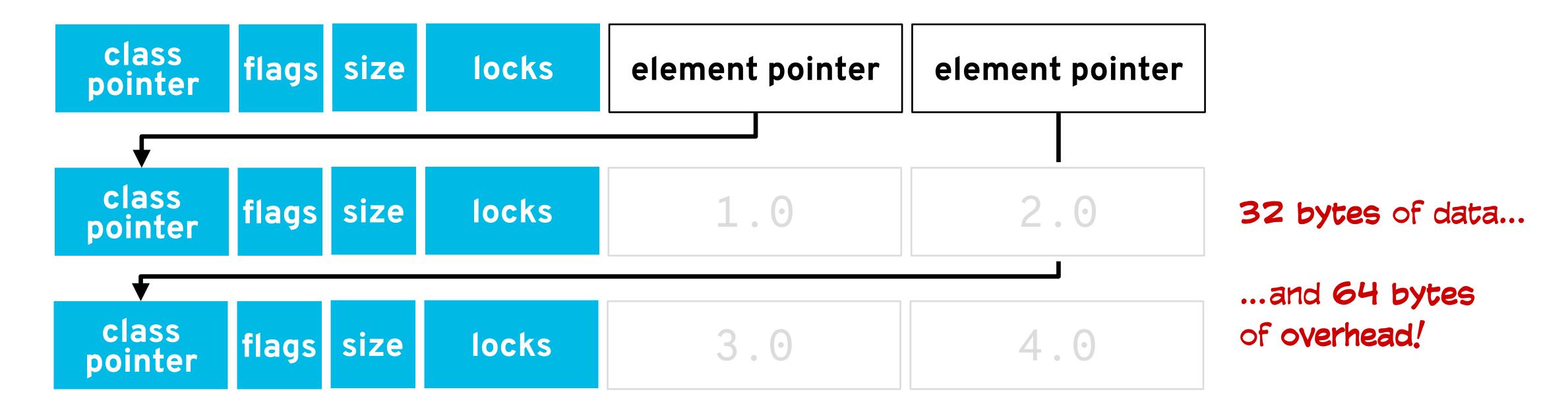


val mat = Array(Array(1.0, 2.0), Array(3.0, 4.0))





val mat = Array(Array(1.0, 2.0), Array(3.0, 4.0))





ML pipelines: a quick example

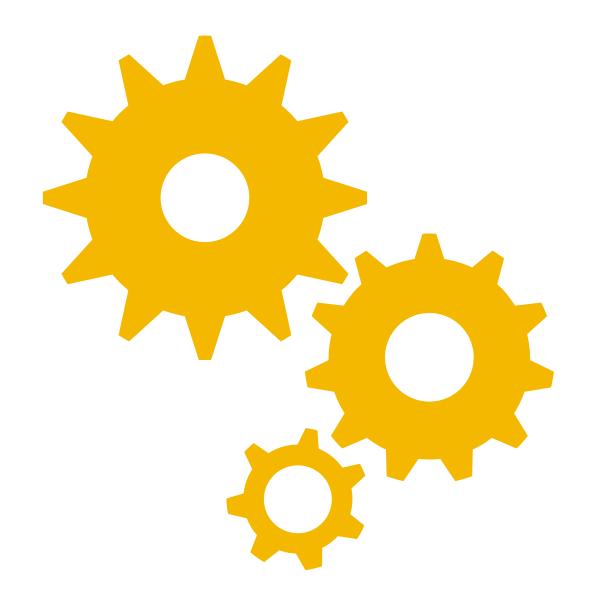
```
from pyspark.ml.clustering import KMeans

K, SEED = 100, 0xdea110c8

randomDF = make_random_df()

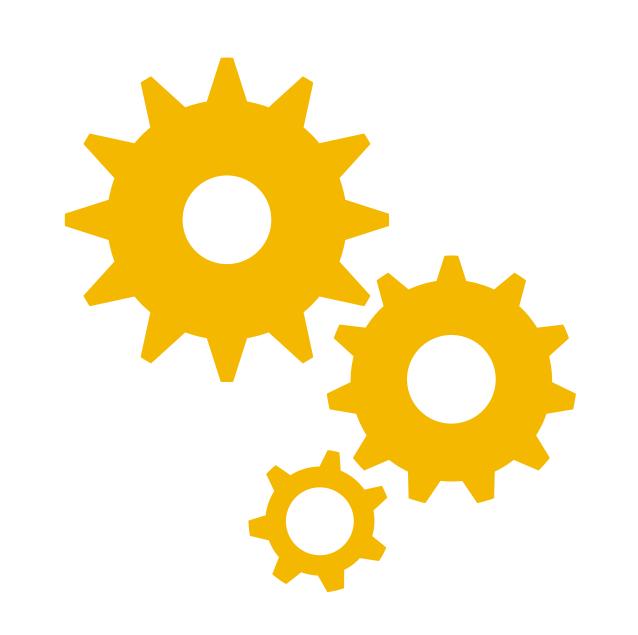
kmeans = KMeans().setK(K).setSeed(SEED).setFeaturesCol("features")
model = kmeans.fit(randomDF)
withPredictions = model.transform(randomDF).select("x", "y", "prediction")
```

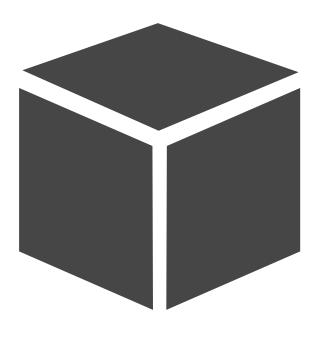




estimator.fit(df)





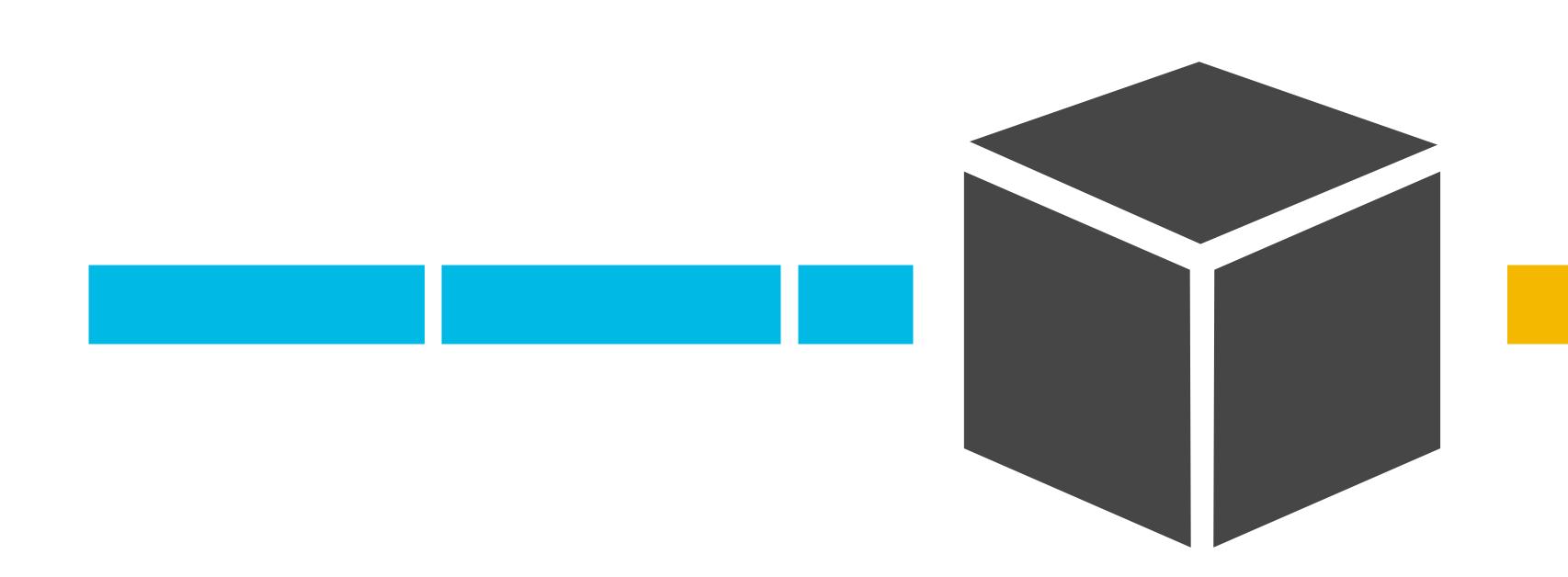


estimator.fit(df)

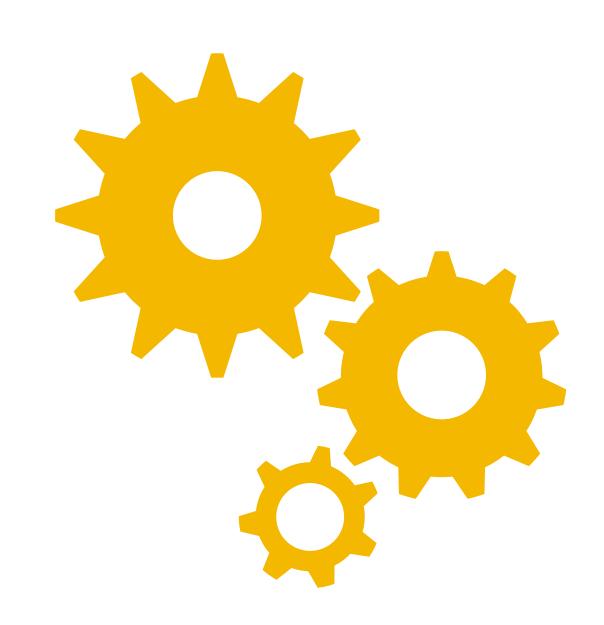




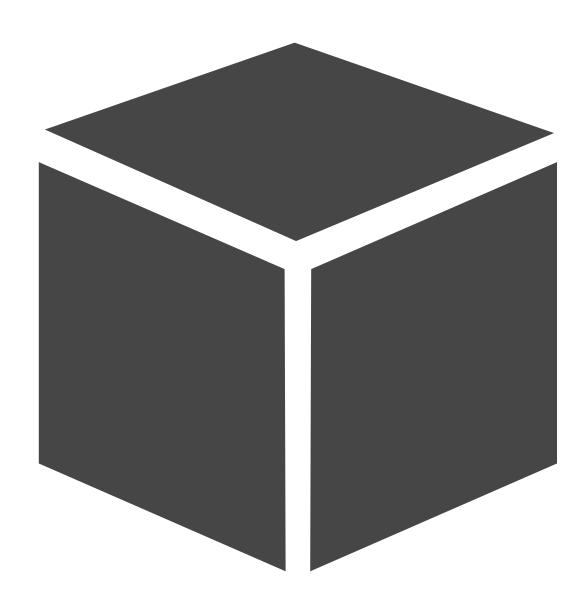




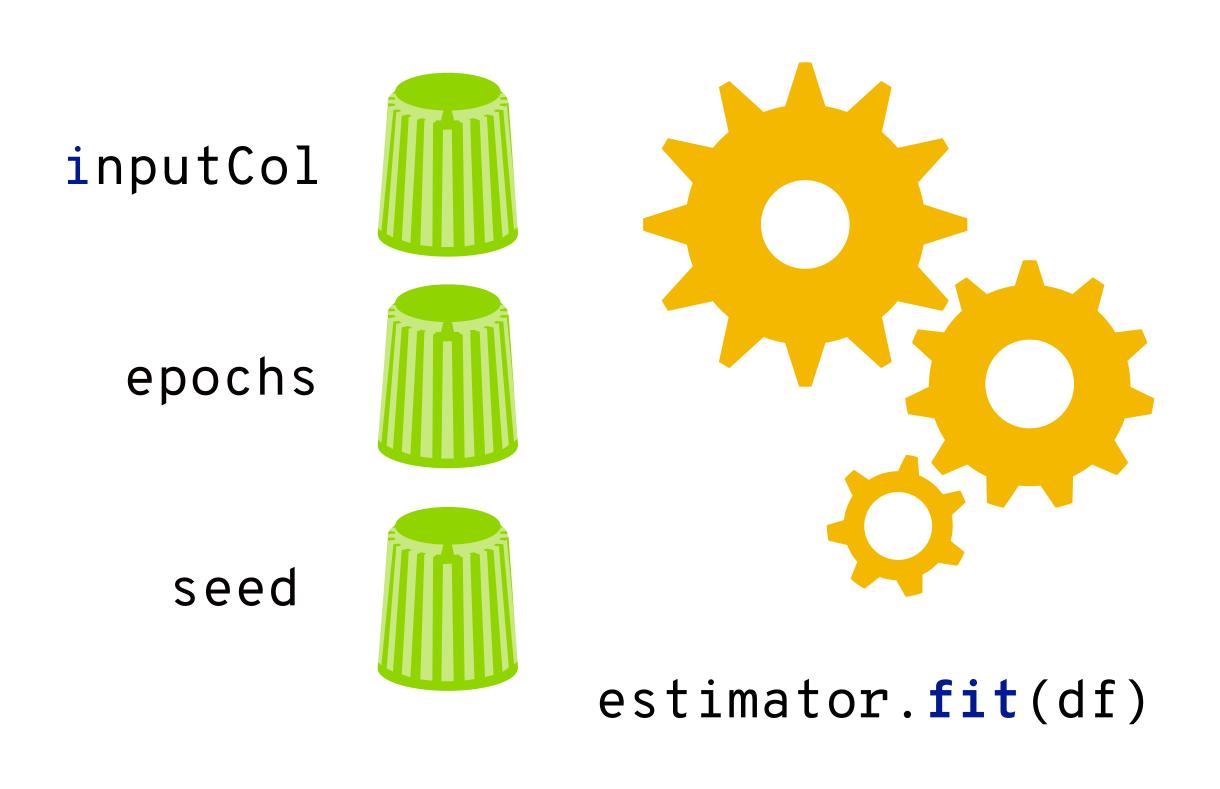


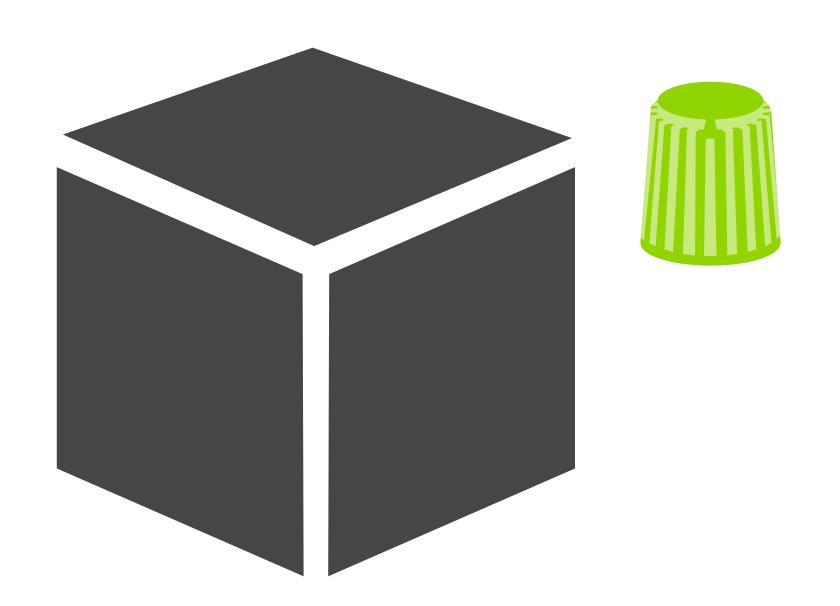












outputCol



Defining parameters

```
private[som] trait SOMParams extends Params
    with DefaultParamsWritable {
  final val x: IntParam =
    new IntParam(this, "x", "width of self-organizing map (>= 1)",
                       ParamValidators.gtEq(1))
  final def getX: Int = \$(x)
  final def setX(value: Int): this.type = set(x, value)
  // . . .
```



```
private[som] trait SOMParams extends Params
    with DefaultParamsWritable {
  final val x: IntParam =
   new IntParam(this, "x", "width of self-organizing map (>= 1)",
                       ParamValidators.gtEq(1))
  final def getX: Int = \$(x)
  final def setX(value: Int): this.type = set(x, value)
  // . . .
```



```
private[som] trait SOMParams extends Params
    with DefaultParamsWritable {
  final val x: IntParam =
   new IntParam(this, "x", "width of self-organizing map (>= 1)",
                       ParamValidators.gtEq(1))
  final def getX: Int = \$(x)
  final def setX(value: Int): this.type = set(x, value)
  // . . .
```



```
private[som] trait SOMParams extends Params
    with DefaultParamsWritable {
  final val x: IntParam =
   new IntParam(this, "x", "width of self-organizing map (>= 1)",
                       ParamValidators.gtEq(1))
  final def getX: Int = \$(x)
  final def setX(value: Int): this.type = set(x, value)
  // . . .
```



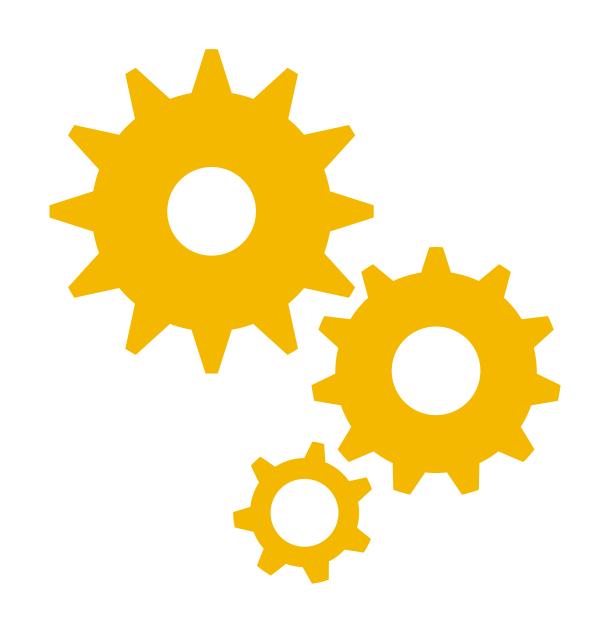
```
private[som] trait SOMParams extends Params
    with DefaultParamsWritable {
  final val x: IntParam =
    new IntParam(this, "x", "width of self-organizing map (>= 1)",
                       ParamValidators.gtEq(1))
  final def getX: Int = \$(x)
  final def setX(value: Int): this.type = set(x, value)
  // . . .
```



Don't repeat yourself

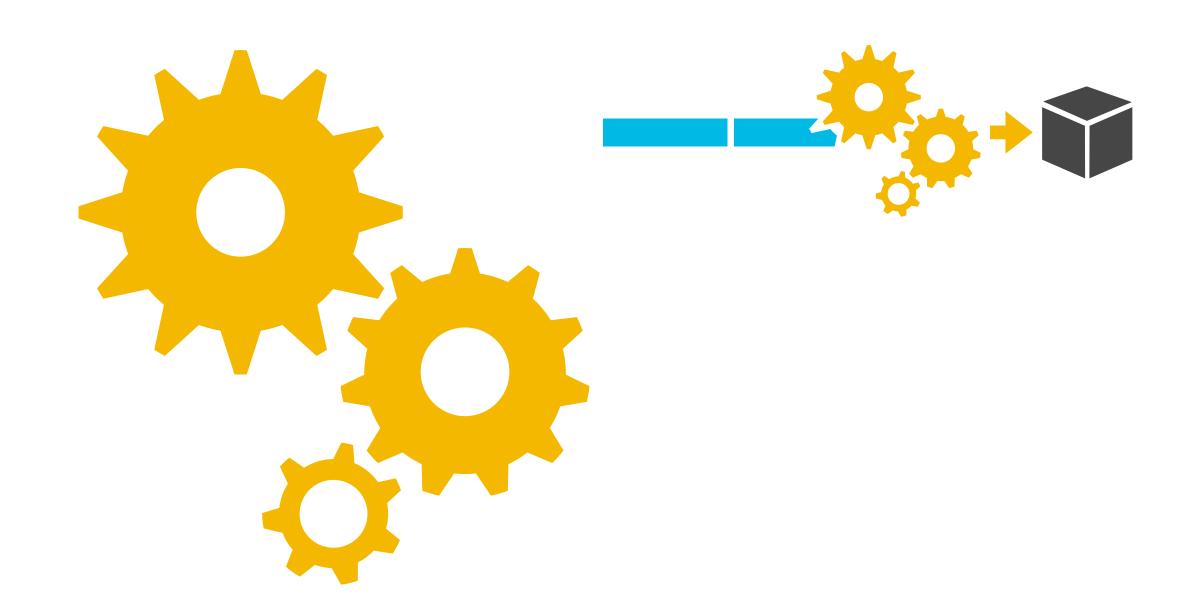
```
/**
  * Common params for KMeans and KMeansModel
  */
private[clustering] trait KMeansParams extends Params
  with HasMaxIter with HasFeaturesCol
  with HasSeed with HasPredictionCol with HasTol { /* ... */ }
```





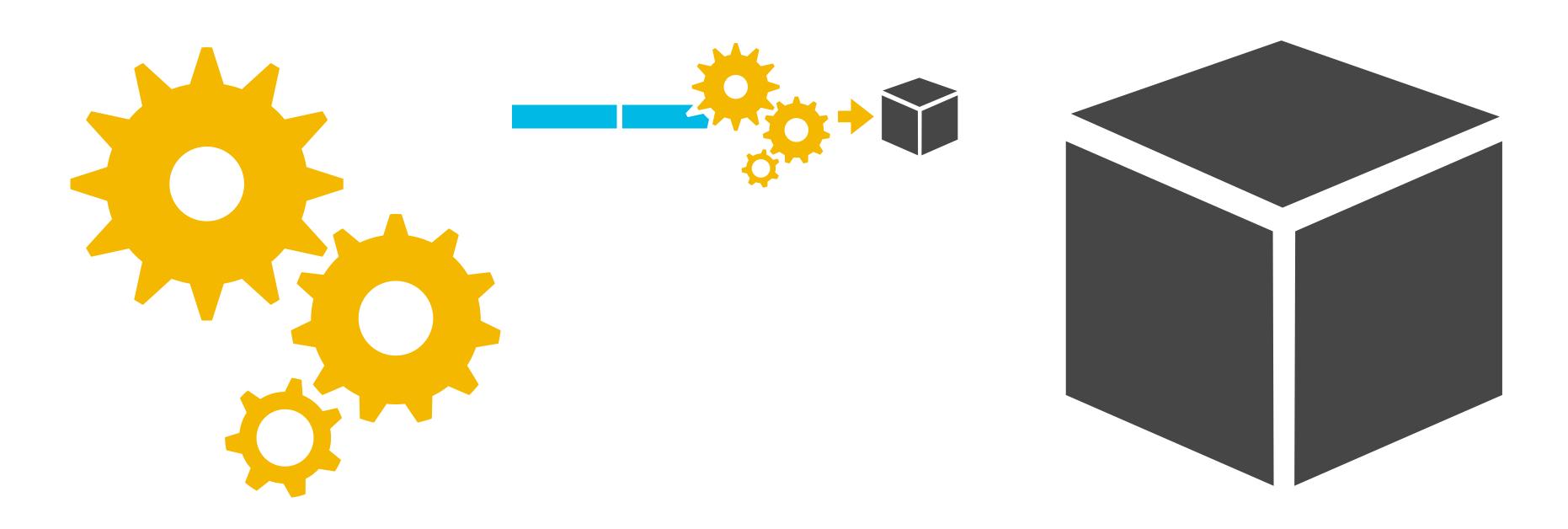
estimator.fit(df)





estimator.fit(df)

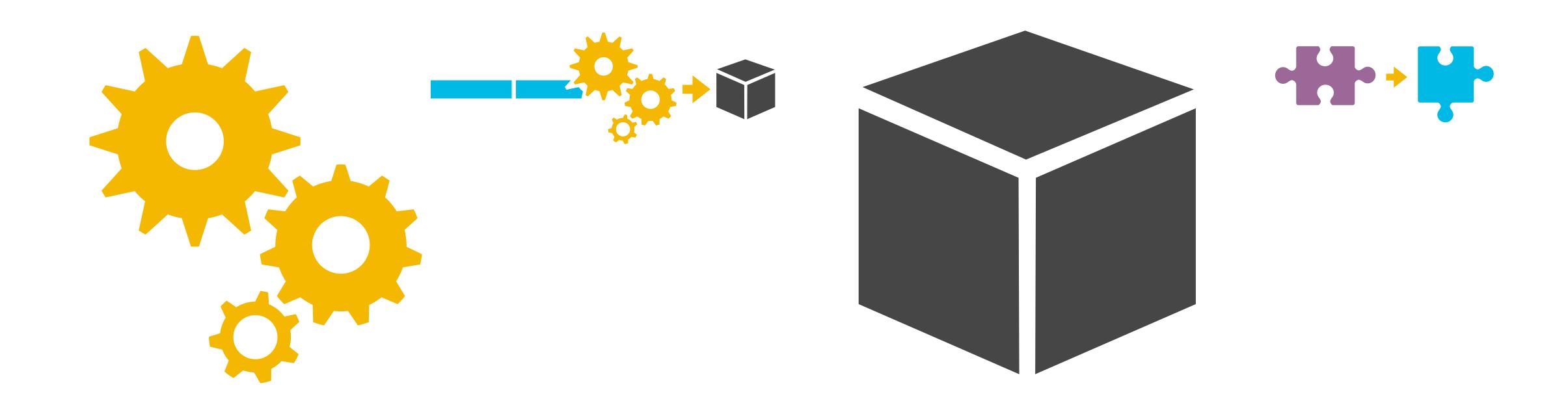




estimator.fit(df)

model.transform(df)

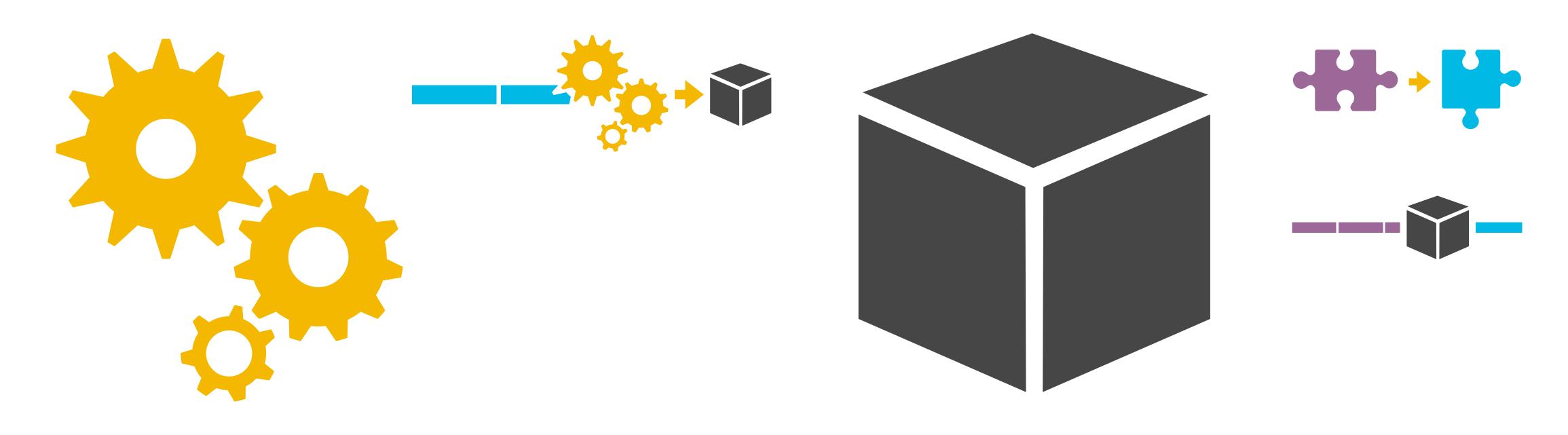




model.transform(df)



estimator.fit(df)



estimator.fit(df)

model.transform(df)



```
def transformSchema(schema: StructType):
    StructType = {
    // check that the input columns exist...
    // ...and are the proper type
    // ...and that the output columns don't exist
    // ...and then make a new schema
}
```



```
def transformSchema(schema: StructType):
    StructType = {
    // check that the input columns exist...
    require(schema.fieldNames.contains($(featuresCol)))
    // ...and are the proper type
    // ...and that the output columns don't exist
    // ...and then make a new schema
}
```



```
def transformSchema(schema: StructType):
    StructType = {
  // check that the input columns exist...
  // ...and are the proper type
  schema($(featuresCol)) match {
    case sf: StructField => require(sf.dataType.equals(VectorType))
  // ...and that the output columns don't exist
  // ...and then make a new schema
```



```
def transformSchema(schema: StructType):
    StructType = {
    // check that the input columns exist...
    // ...and are the proper type
    // ...and that the output columns don't exist
    require(!schema.fieldNames.contains($(predictionCol)))
    require(!schema.fieldNames.contains($(similarityCol)))
    // ...and then make a new schema
}
```



```
def transformSchema(schema: StructType):
    StructType = {
    // check that the input columns exist...
    // ...and are the proper type
    // ...and that the output columns don't exist
    // ...and then make a new schema
    schema.add($(predictionCol), "int")
        .add($(similarityCol), "double")
}
```



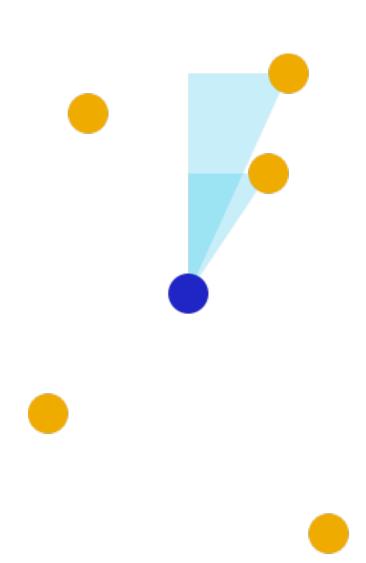
Training on data frames

```
def fit(examples: DataFrame) = {
  import examples.sparkSession.implicits._
  import org.apache.spark.ml.linalg.{Vector=>SV}
  val dfexamples = examples.select($(exampleCol)).rdd.map {
    case Row(sv: SV) => sv
  /* construct a model object with the result of training */
  new SOMModel(train(dfexamples, $(x), $(y)))
```

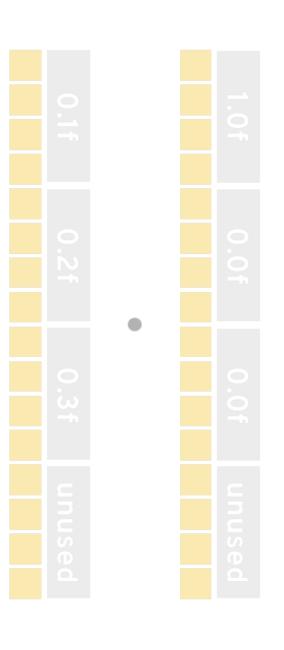


Practical considerations

Improve serial execution times

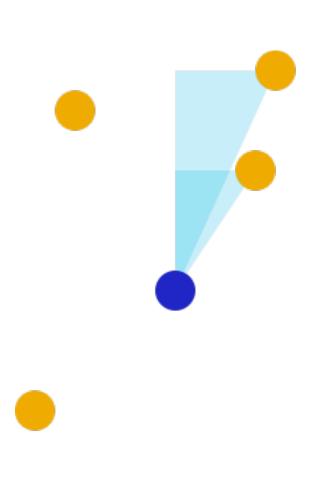


		1	ΓΩ 1
0	1		0.1
0		1	0.7
1			LO.2

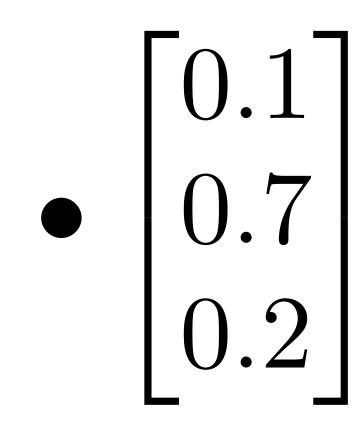


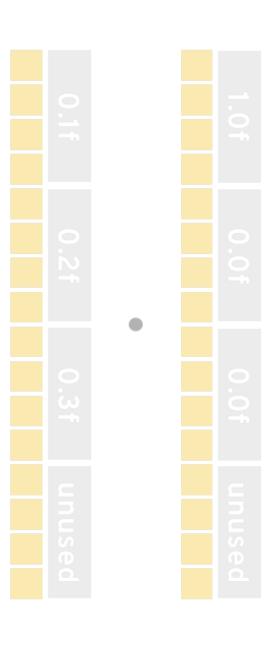


Improve serial execution times



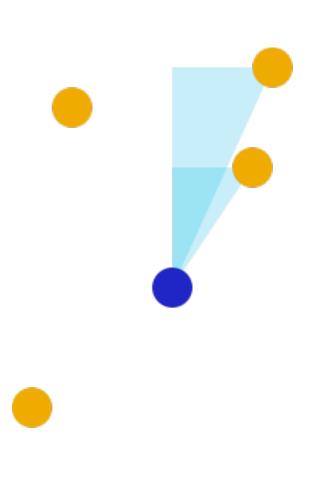
$\overline{0}$	0	1	
0	1	0	
0	0	1	
1	0	0	



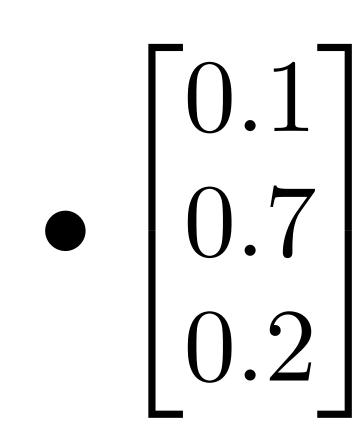


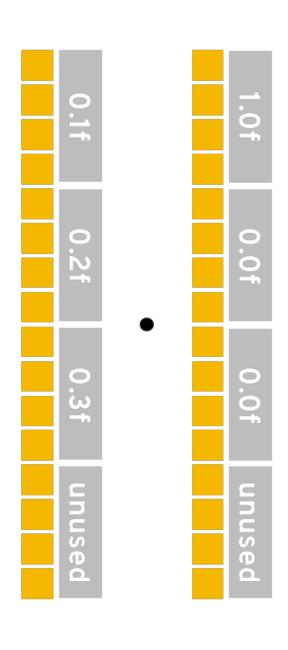


Improve serial execution times

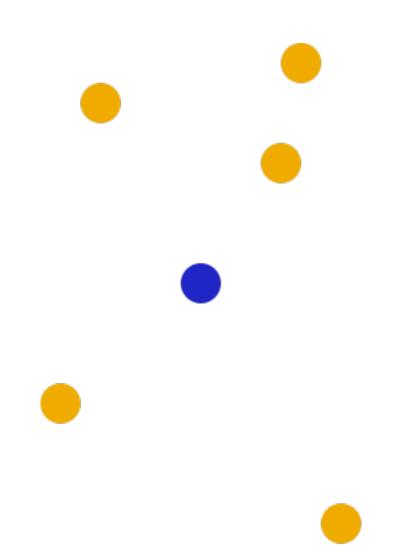


\int_{0}^{∞}	0	17
0	1	0
0	0	1
1	0	0

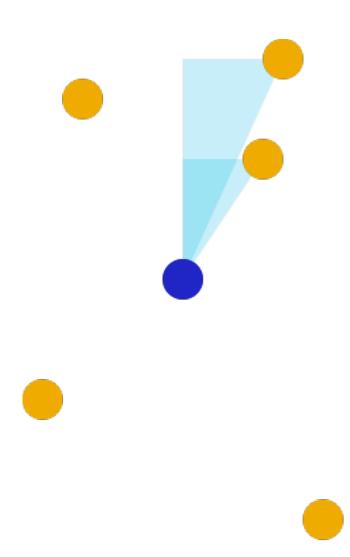




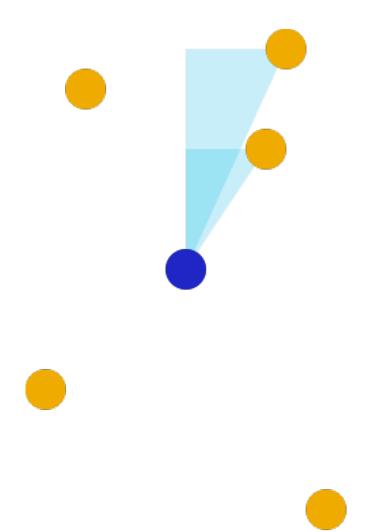


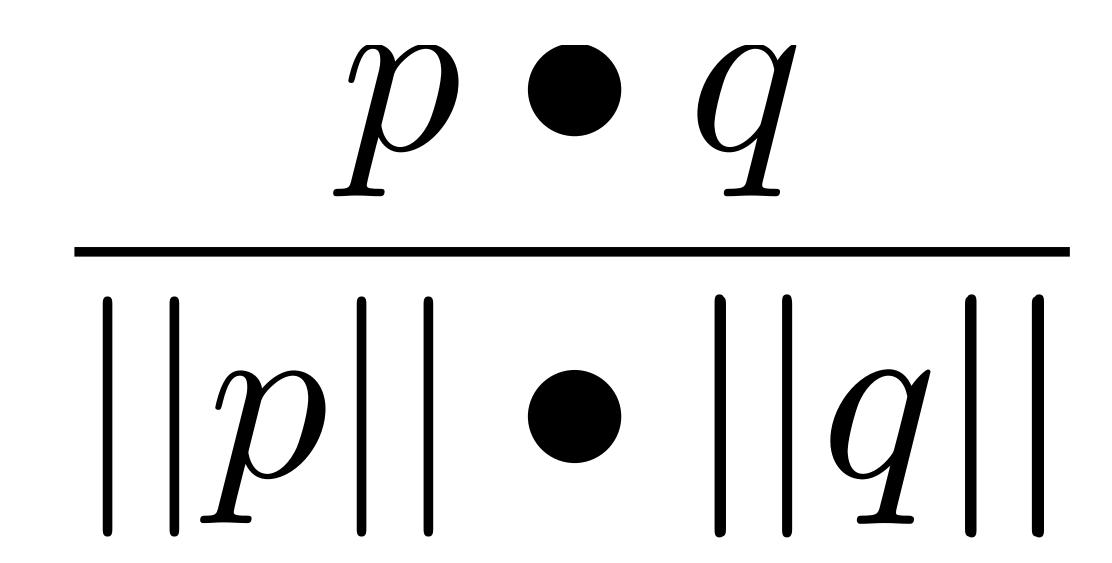




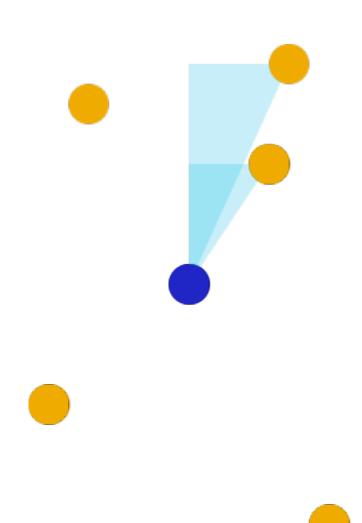


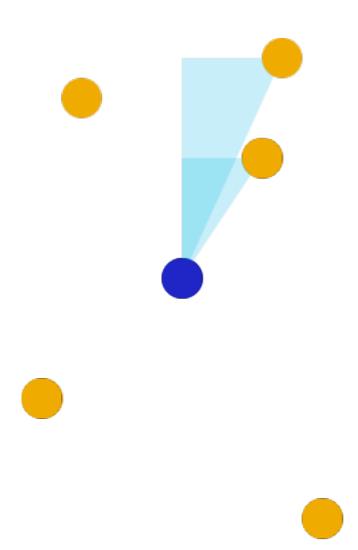


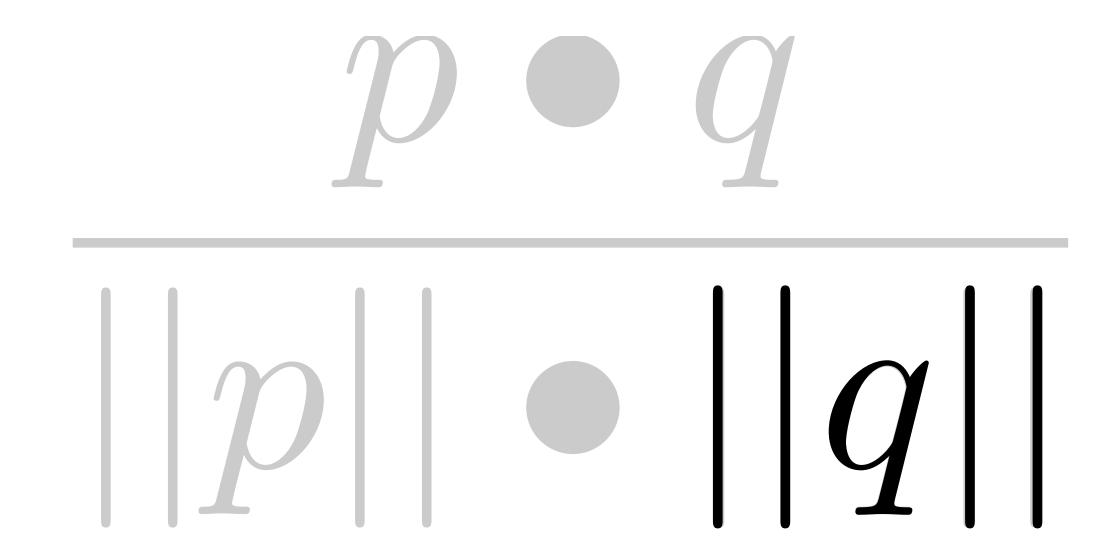












 $\begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \bullet \begin{bmatrix} 4 & 5 & 6 \end{bmatrix}$

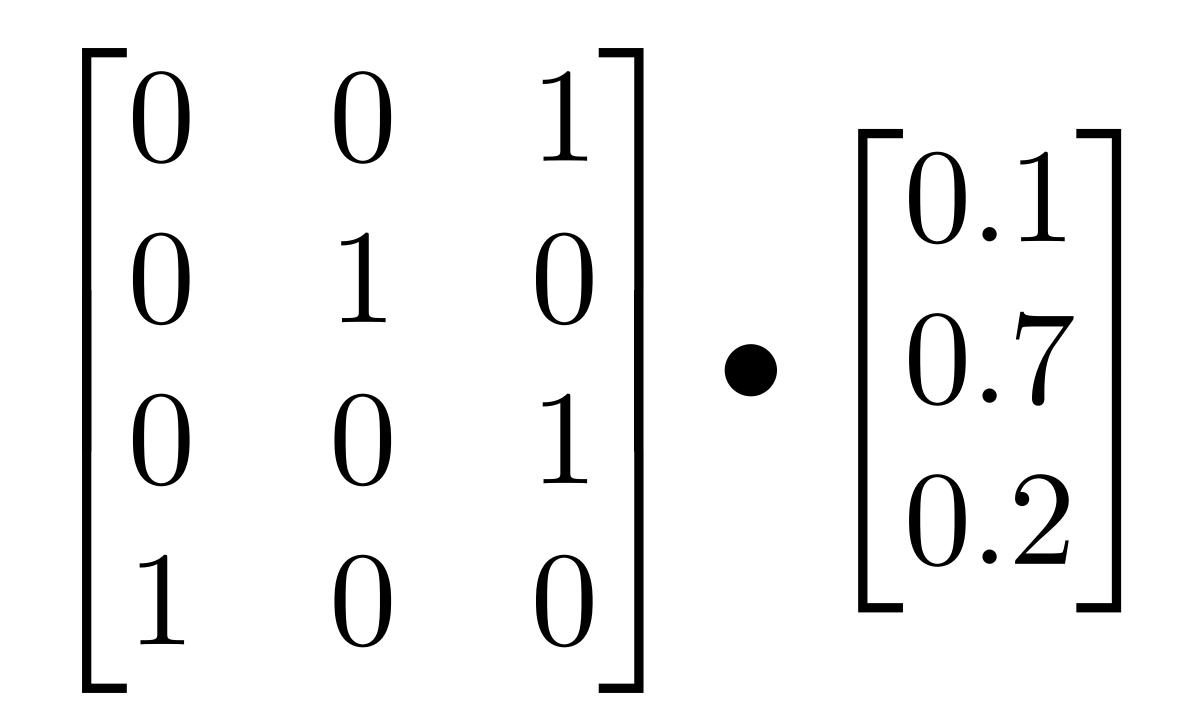
 $\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$ $\begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$ $\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$

$$\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$



$$\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix} \\ \begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix} \\ \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix} \\ \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix} \\ \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \bullet \begin{bmatrix} 0.1 & 0.7 & 0.2 \end{bmatrix} \\ \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \end{bmatrix} \bullet \begin{bmatrix} 0.1 \\ 0.7 \\ 0.2 \end{bmatrix}$$

libraryDependencies +=

"org.scalanlp" %% "breeze-natives" % "0.13.1"



val vec = Array[Double](/* ... */)



val vec = Array[Double](/* ... */)



```
val vec = Array[Double](/* ... */)
def dot[S](a: Array[S], b: Array[S])
  (implicit num: Numeric[S]): S = {
  import num._
  (0 until a.length).foldLeft(num.zero)({
    (acc, i) => acc + a(i) * b(i)
  })
```



```
val vec = Array[Double](/* ... */)
def dot[S](a: Array[S], b: Array[S])
  (implicit num: Numeric[S]): S = {
  import num.
  (O until a.length).foldLeft(num.zero)({
    (acc, i) => acc + a(i) * b(i)
  })
dot(Array(0.1d, 0.2d, 0.3d), Array(1.0d, 0.0d, 0.0d))
dot(Array(0.1f, 0.2f, 0.3f), Array(1.0f, 0.0f, 0.0f))
```



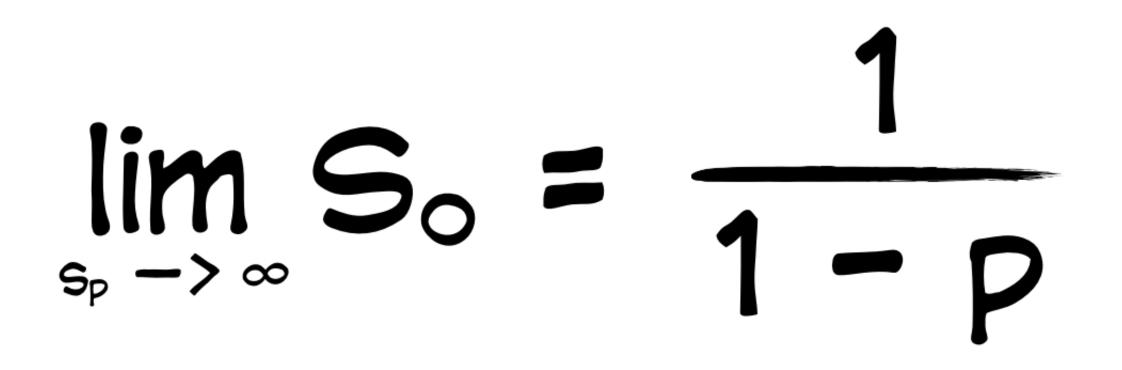
```
val vec = Array[Double](/* ... */)
 def dot[S](a: Array[S], b: Array[S])
   (implicit num: Numeric[S]): S = {
  import num._
   (0 until a.length).foldLeft(num.zero)({
     (acc, i) => acc + a(i) * b(i)
                   0.1d
                                   0.2d
                                                        1.0d
                                                                         0.0d
vdppd
                  0.3d
                                                        0.0d
                                  (unused)
                                                                       (unused)
vdppd
```

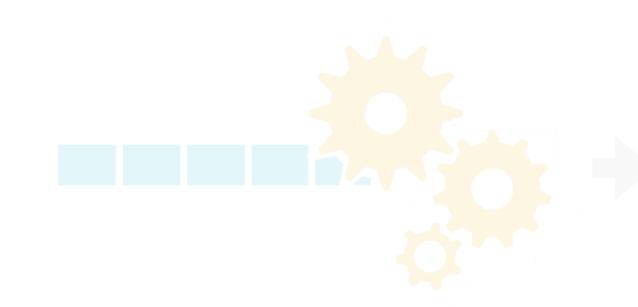


```
val vec = Array[Double](/* ... */)
 def dot[S](a: Array[S], b: Array[S])
   (implicit num: Numeric[S]): S = {
  import num._
   (0 until a.length).foldLeft(num.zero)({
     (acc, i) => acc + a(i) * b(i)
                                    0.2d
                                                         1.0d
                                                                          0.0d
                   0.1d
vdppd
                   0.3d
                                                         0.0d
                                  (unused)
                                                                        (unused)
vdppd
                       0.2f
                                0.3f
               0.1f
                                                    1.0f
                                                             0.0f
                                                                      0.0f
                                       unused
                                                                             unused
vdpps
```



KEY TAKEAWAYS





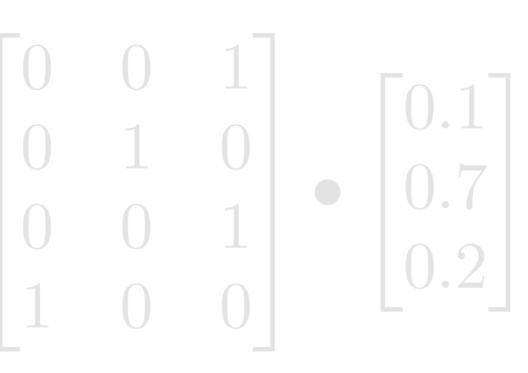


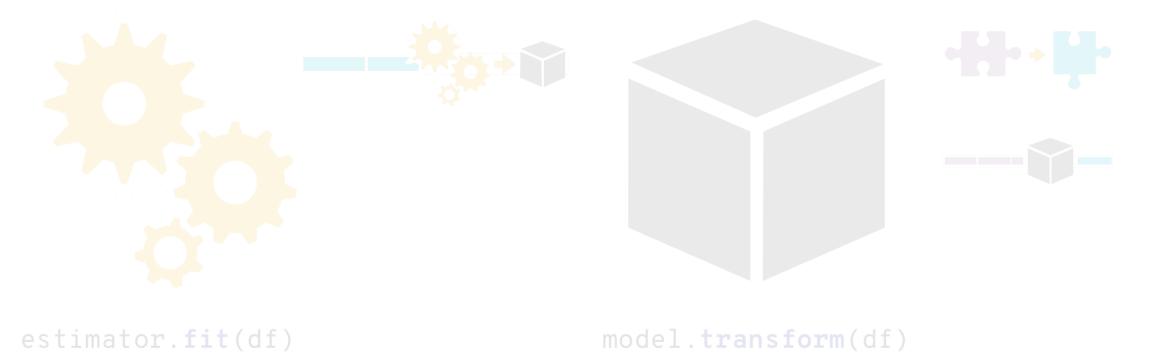








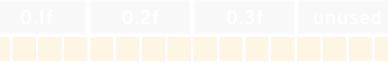


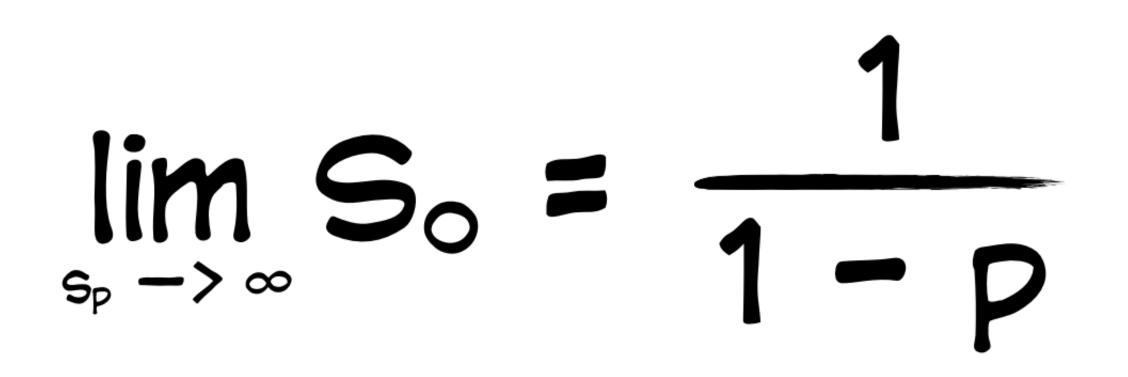


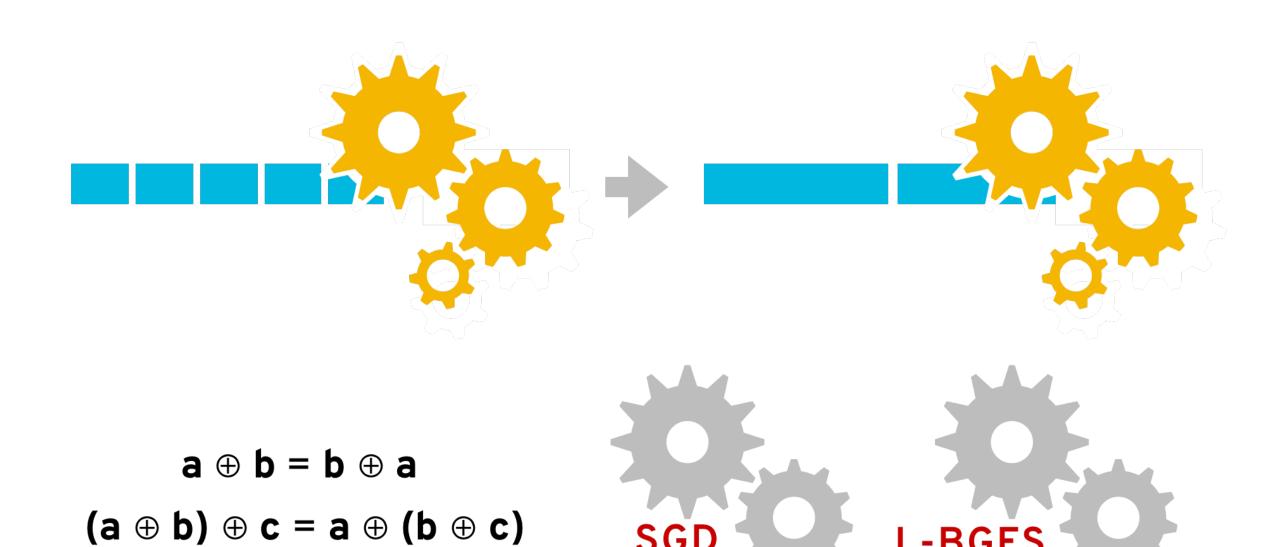
dot(Array(0.1d, 0.2d, 0.3d), Array(1.0d, 0.0d, 0.0d)) dot(Array(0.1f, 0.2f, 0.3f), Array(1.0f, 0.0f, 0.0f))

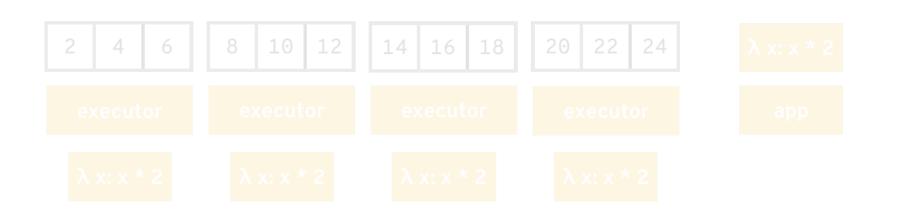
vdpps					

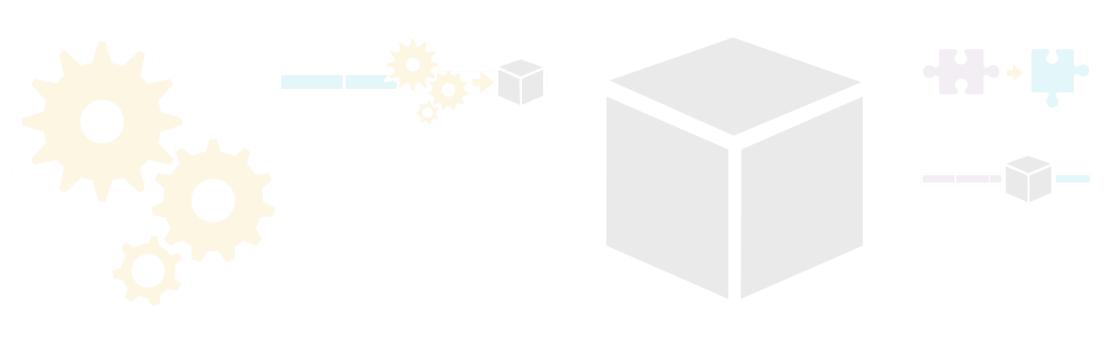






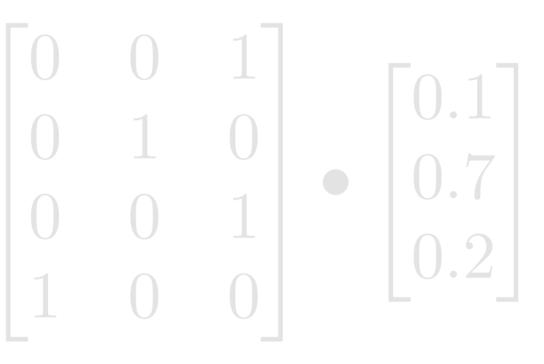






model.transform(df)





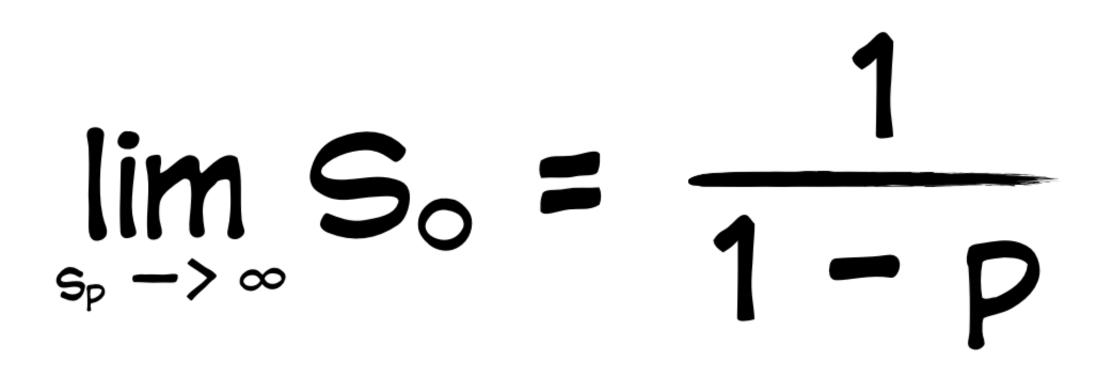
L-BGFS

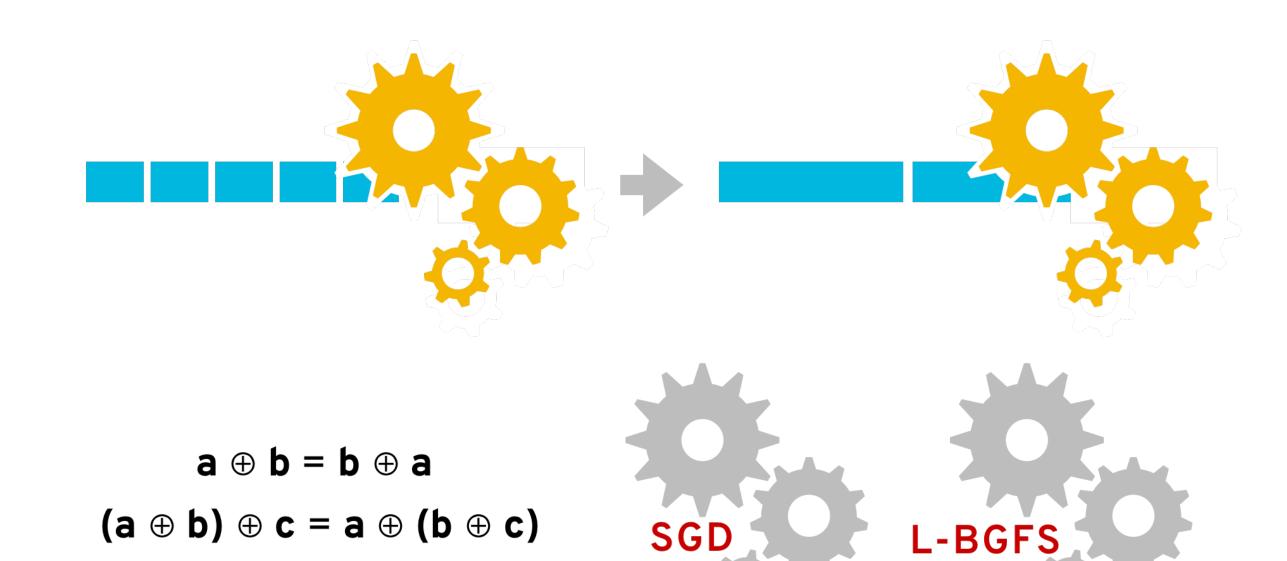
dot(Array(0.1d, 0.2d, 0.3d), Array(1.0d, 0.0d, 0.0d)) dot(Array(0.1f, 0.2f, 0.3f), Array(1.0f, 0.0f, 0.0f))

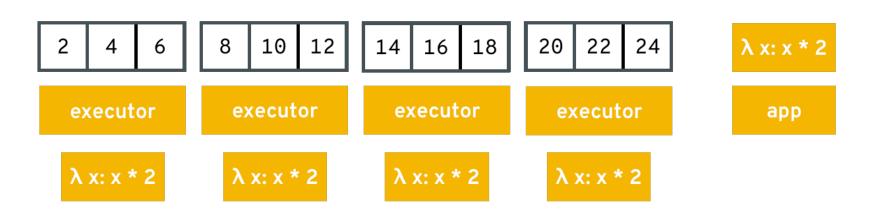
vdpps				

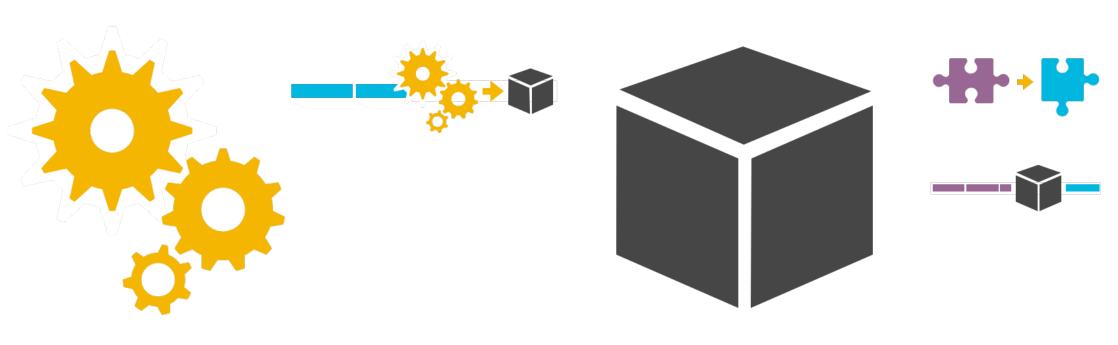


estimator.fit(df)



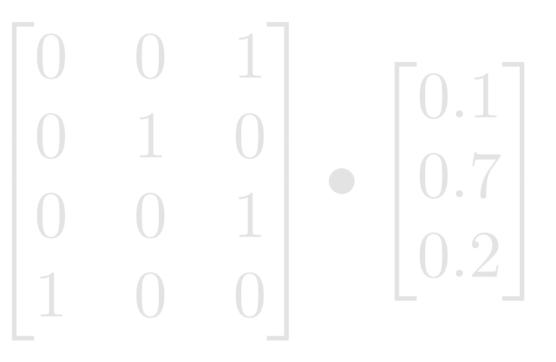






model.transform(df)

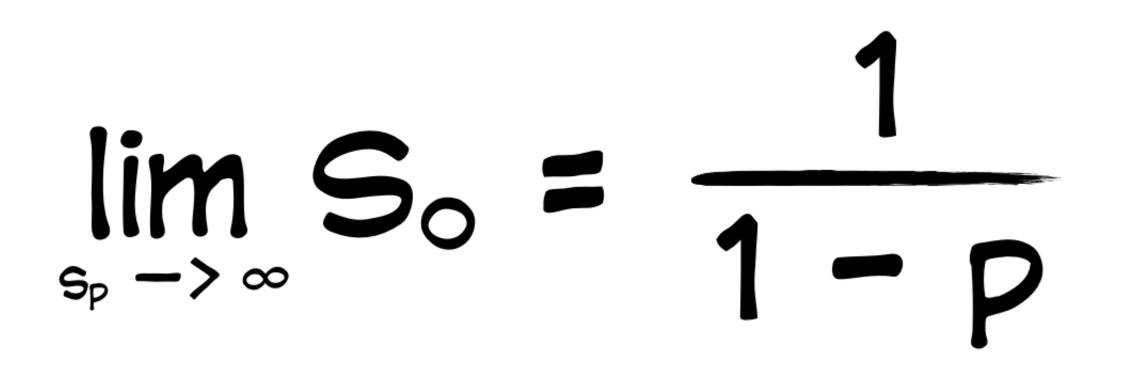


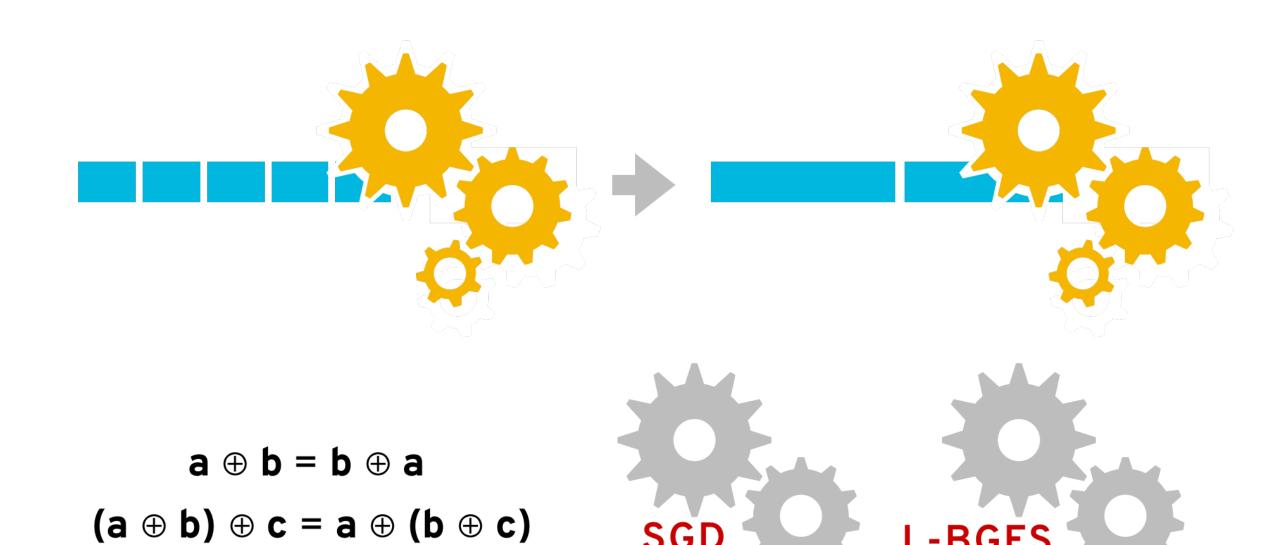


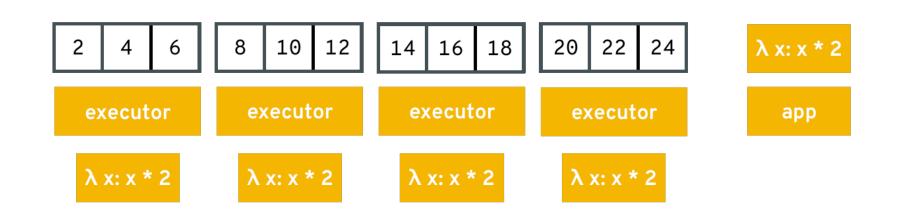
dot(Array(0.1d, 0.2d, 0.3d), Array(1.0d, 0.0d, 0.0d))
dot(Array(0.1f, 0.2f, 0.3f), Array(1.0f, 0.0f, 0.0f))

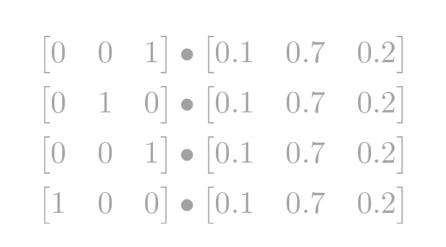
vdpps				

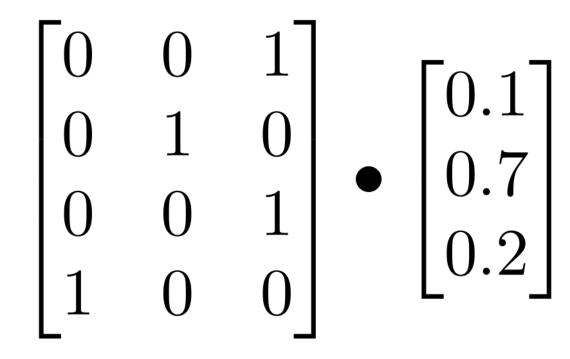
estimator.fit(df)



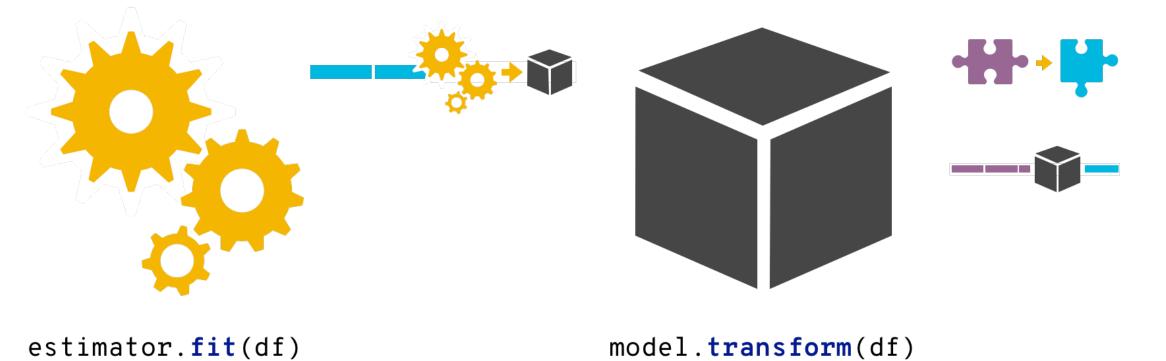


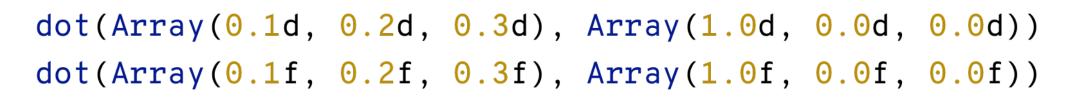






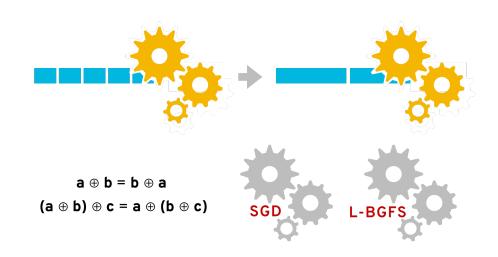
L-BGFS

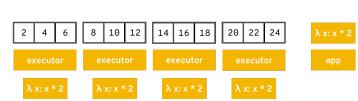


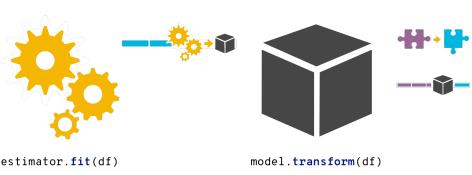


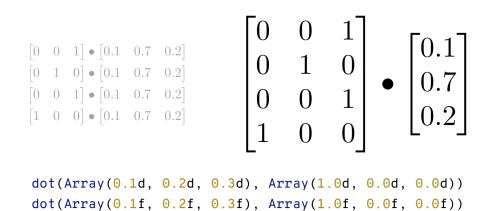
	0.1f	0.2f	0.3f	unused	1.0f	0.0f	0.0f	unused
vdpps								

$$\lim_{s_p \to \infty} S_o = \frac{1}{1 - p}$$









 0.1f
 0.2f
 0.3f
 unused
 1.0f
 0.0f
 0.0f
 unused

 vdpps
 1.0f
 0.0f
 <

THANKSI

willb@redhat.com • @willb https://chapeau.freevariable.com https://radanalytics.io

also: "Spark for Library Developers" Room 2014 at 5:40 PM today

