

# Accelerating Inference in the Data Center

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**Intel**

**#HWCSAIS11**

# Autonomous Vehicles – R & D

## Data Pressure

### How a Car Drives Itself

#### LIDAR UNIT

Constantly spinning, it uses laser beams to generate a 360-degree image of the car's surroundings.

#### RADAR SENSORS

Measure the distance from the car to obstacles.

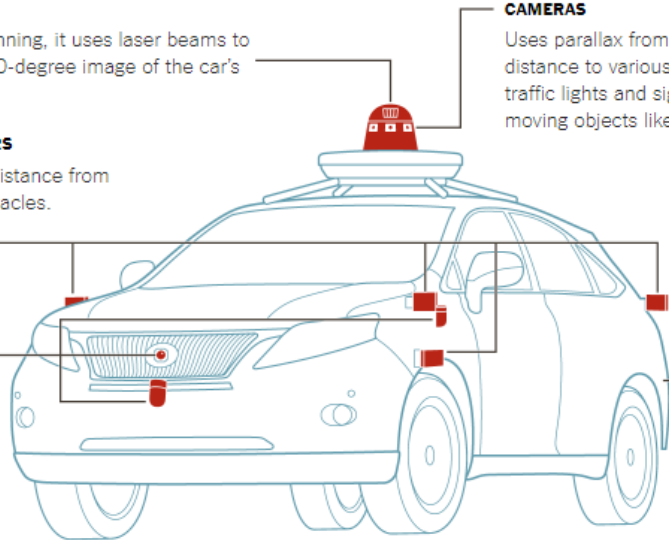
#### ADDITIONAL LIDAR UNITS

#### CAMERAS

Uses parallax from multiple images to find the distance to various objects. Cameras also detect traffic lights and signs, and help recognize moving objects like pedestrians and bicyclists.

#### MAIN COMPUTER (LOCATED IN TRUNK)

Analyzes data from the sensors, and compares its stored maps to assess current conditions.



By Guilbert Gates | Source: Google | Note: Car is a Lexus model modified by Google.

Image Credit: <https://clepa.eu/mediaroom/autonomous-vehicles-will-drive-change-auto-manufacturing-insurance/>  
<https://ia.acs.org.au/article/2017/who-should-the-driverless-car-kill-.html>

1-20 TB/car/hour  
# cameras, resolution,  
other sensor arrays



# Inference Everywhere Faster Please!

- Speed ground truth generation
  - Human improves upon automated
- Speed Privacy transformations
  - Face/license plate obscuring
- Speed simulation
  - Detect (edge-ish), Plan, Act



<https://medium.com/@xslittlegrass/self-driving-car-in-a-simulator-with-a-tiny-neural-network-13d33b871234>

# Compute Continuum



CPU  
Flexible, Slower

GPUs  
FPGAs,  
Movidius

ASICs  
Fixed, Faster



## Can Spark Leverage? Easily?



## FPGA

- Logic blocks, memory, security, variable sizes
- Programmable, OpenCL
- Fast but Expensive
- Applications: Networking, Telecommunication, Research, Machine Learning



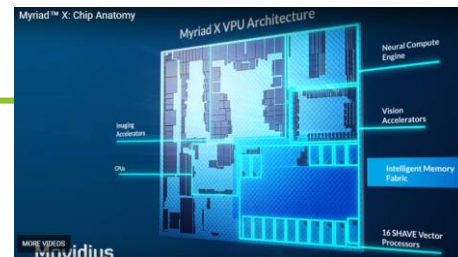
A Stratix IV FPGA from Altera



A Spartan FPGA from Xilinx

## Movidius Chip

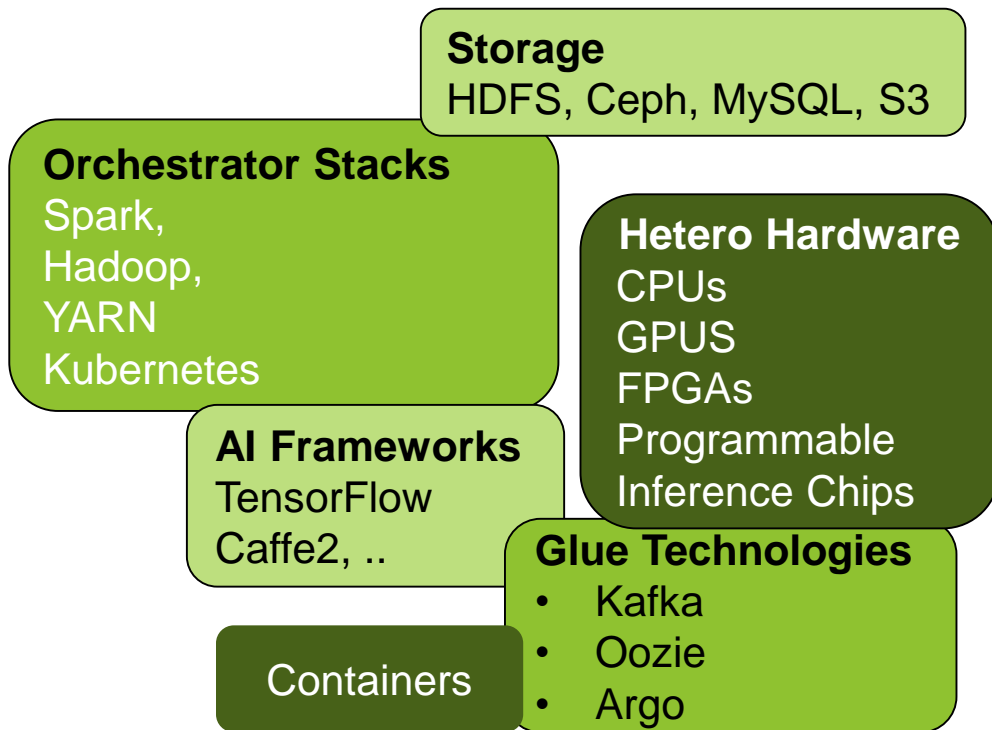
- Programmable, SDK
- Low Power
- Tuned for image processing
- Fast, Inexpensive
- Applications: Drones, Cameras, Augmented Reality



# Data Center Platform

## Drivers

- Fungible
- Dynamic
- Resilient
- Easy to Use
- Fast



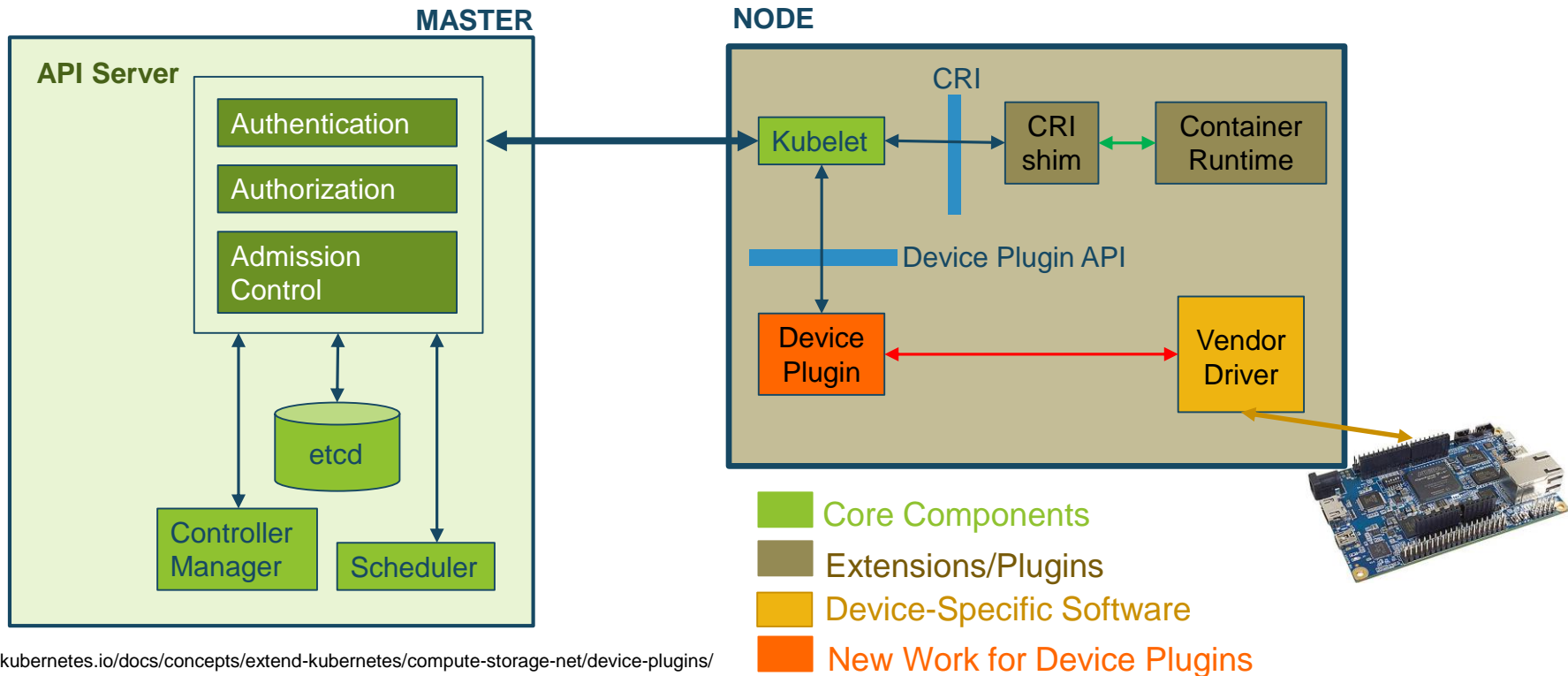
# Environment

- **Kubernetes** – resilient, auto scaling, easy to use
- Spark – big data in memory processing, possible data locality



# Kubernetes Device Plugin

## Enables use of new Resources



<https://kubernetes.io/docs/concepts/extend-kubernetes/compute-storage-net/device-plugins/>



# Experiment

- SqueezeNet 1.1
- gRPC calls  
3-4 ms
- Data pre-Processing  
16-30 ms



# FPGA Inference

- Model Size
- FPGA Size
- Trade-off
  - Model accuracy, speed
  - Compile to target hardware

## Supported Deep Learning Topologies

- AlexNet
- GoogleNet v1
- VGG-16 & VCG-19
- SqueezeNet 1.0 & 1.1
- ResNet-18
- SqueezeNet-based variant of SSD
- GoogleNet-based variant of SSD
- VGG-based variant of SSD

# Movidius USB Learnings & Workarounds

## USB

- Access to host network (isolation loss)  
`--net=host`
- Visibility into Device Manager events in Docker environment  
`libusb`
- Privilege Escalation (insecure)  
`--privileged`
- Access to Virtual File System to access USB device from within container  
`-v /dev:/dev`

- No Python support  
- loss of data locality
- Model – as-a-service

Common  
Paradigm:  
TensorFlow  
Serving

- Movidius NCSDK2 – resolves some issues
- Feedback to Movidius team
- Service running on bare metal
- Movidius PCIe device coming soon!  
USB related issues moot

# Movidius Next

- SDK2 just released
  - Up to 10 models may co-exist on one device,
  - FIFO queue,
  - 32 bit floating point
- Chip-2 Coming soon – at least an order of magnitude faster

<https://developer.movidius.com/start>

<https://github.com/movidius/ncsdk>

[https://github.com/kzzalews/sparkaisummit\\_movidius](https://github.com/kzzalews/sparkaisummit_movidius)

# Results

	CPU	FPGA	Movidius
Software Tools		CentOS 7.4 Intel Acceleration StackStack 1.0 Intel OpenVINO Toolkit with FPGA Support	SDK 1
Hardware	CPU: Intel Xeon CPU E5-1650 v2 @ 3.50GHz	FPGA: Arria 10 GX (1150K Logic elements, 8GB DDR4, PCIe Gen3)	Movidius
Inference Time/image	7.5 ms	3.2 ms	34 ms

# Demo

[https://videoportal.intel.com/media/0\\_selfn06l](https://videoportal.intel.com/media/0_selfn06l)

# Future Work

- Kubernetes Device Manager support for Movidius
- Explore native Spark support for Movidius
- Kubernetes/Spark Scheduler Enhancements
  - Wait for HW or launch anywhere?
  - Speed, power, and latency implications
  - Targeted models



# Conclusion

- FPGA support more mature
- Give Movidius a try, delightful at its price point!!

<https://developer.movidius.com/start>

<https://github.com/movidius/ncsdk>

[https://github.com/kzzalews/sparkaisummit\\_movidius](https://github.com/kzzalews/sparkaisummit_movidius)

# References

## Kubernetes Device Plugin:

- <https://kubernetes.io/docs/tasks/manage-gpus/scheduling-gpus/>
- <https://kubernetes.io/docs/concepts/cluster-administration/device-plugins/>
- <https://github.com/kubernetes/community/blob/master/contributors/design-proposals/resource-management/device-plugin.md>

## FPGAs and the Movidius Chip

- <https://venturebeat.com/2018/02/27/intel-makes-it-easier-to-bring-movidius-ai-accelerator-chip-into-production/>
- <https://newsroom.intel.com/editorials/introducing-myriad-x-unleashing-ai-at-the-edge/>
- <https://www.altera.com/products/fpga/stratix-series/stratix-10/overview.html>
- <https://medium.com/@xslittlegrass/self-driving-car-in-a-simulator-with-a-tiny-neural-network-13d33b871234>

## SparkCL: A Unified Programming Framework for Accelerators on Heterogeneous Clusters:

- <https://arxiv.org/ftp/arxiv/papers/1505/1505.01120.pdf>

# Thank You!

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