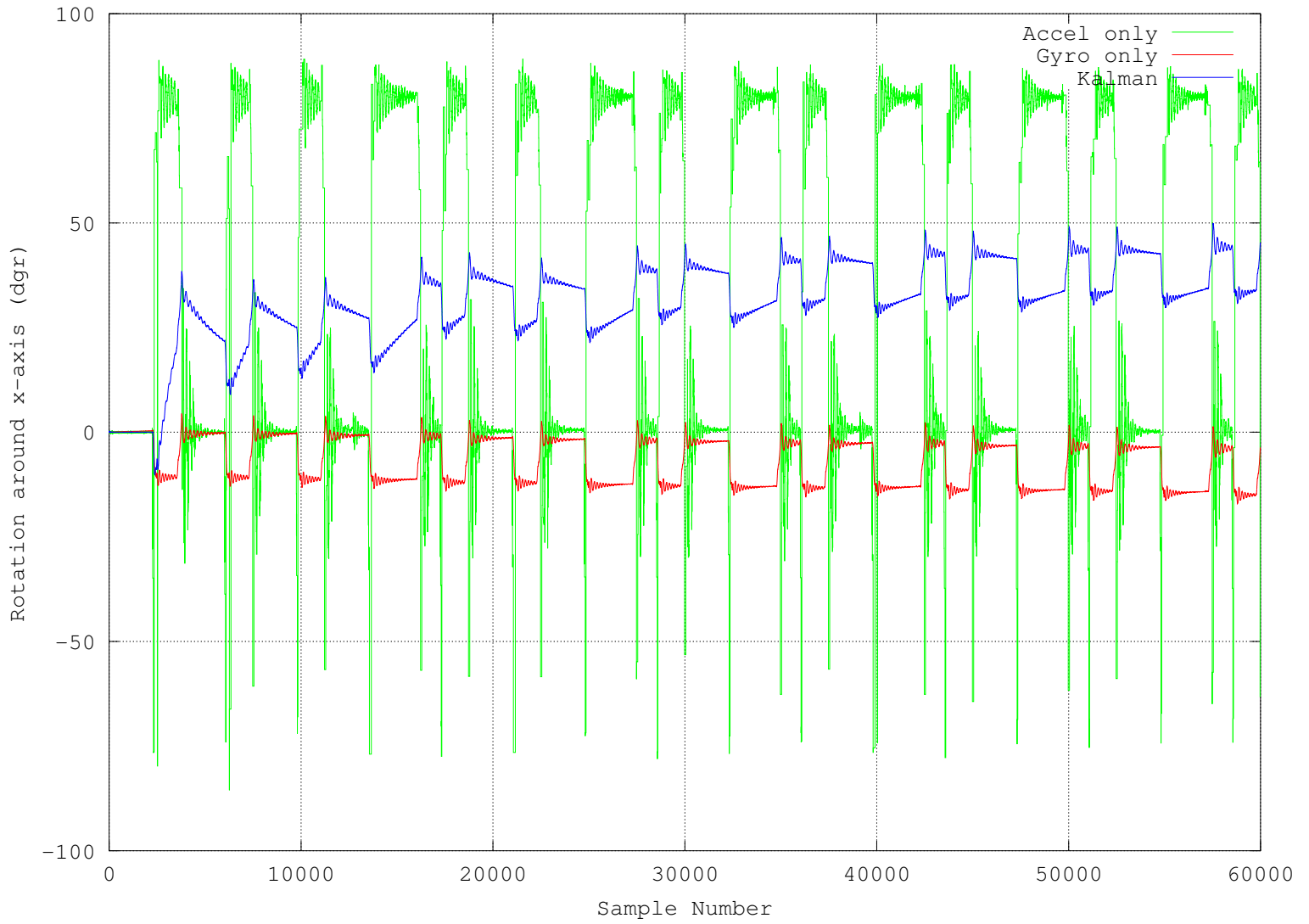
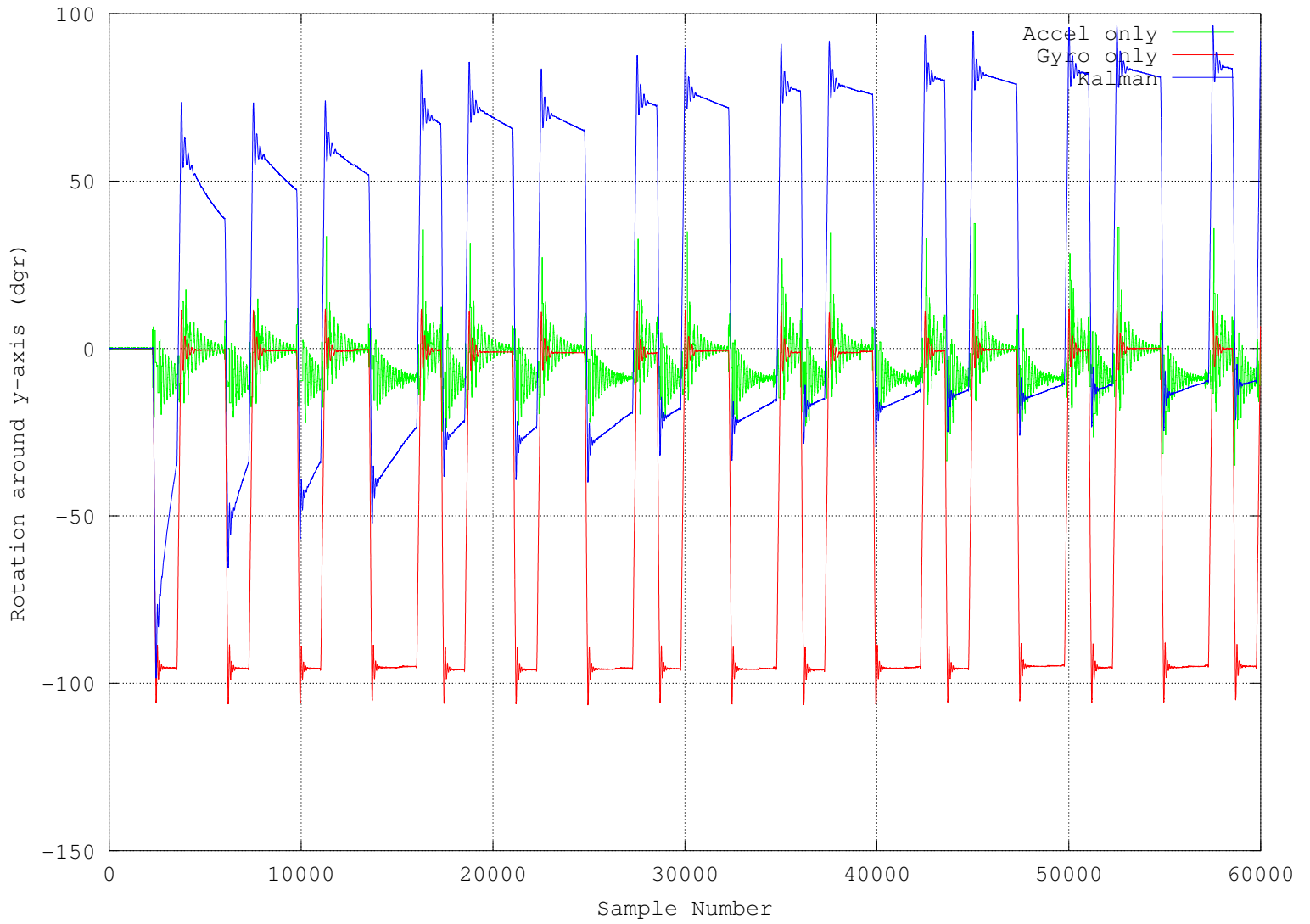


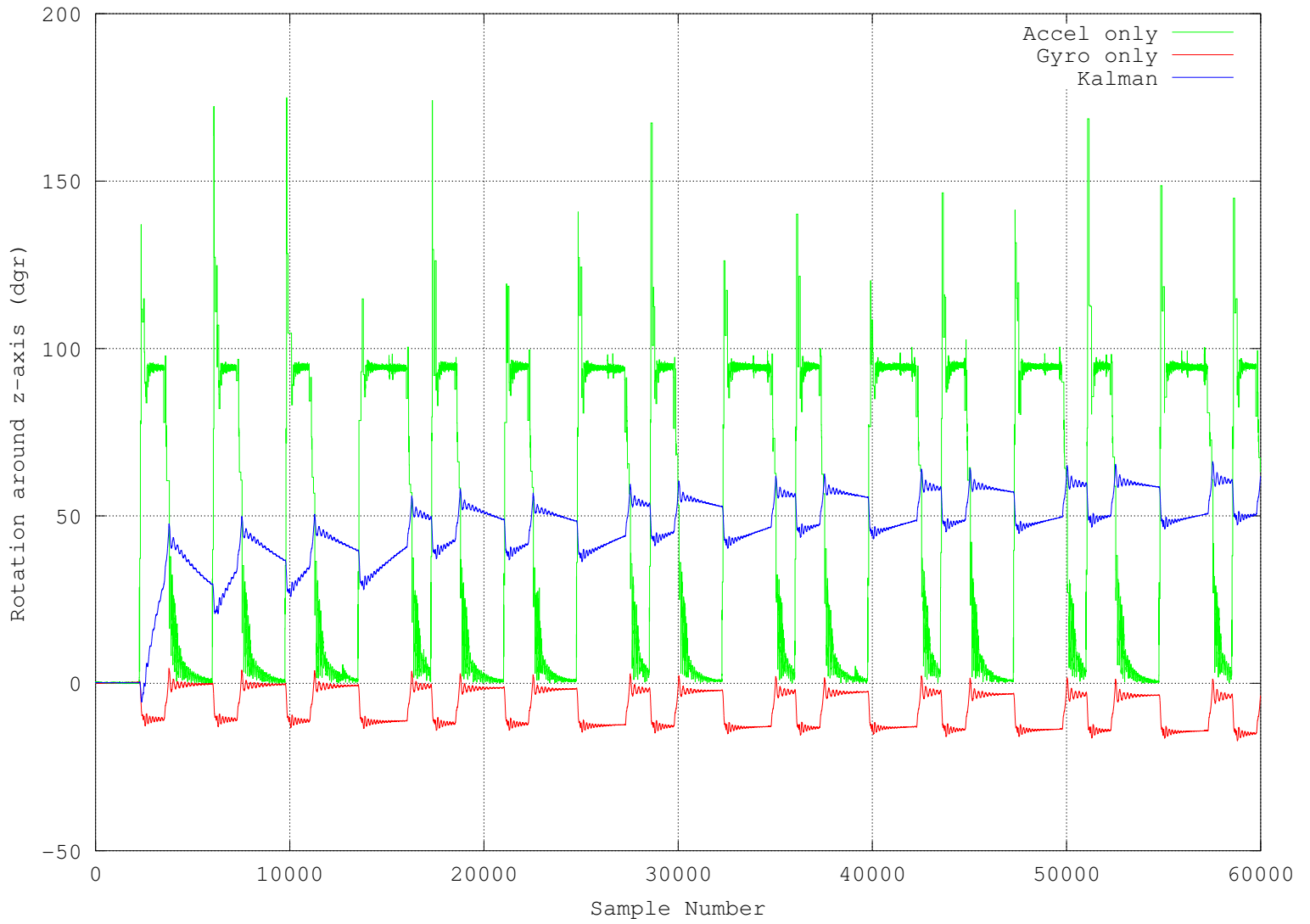
Sensor Fusion using Kalman Filter



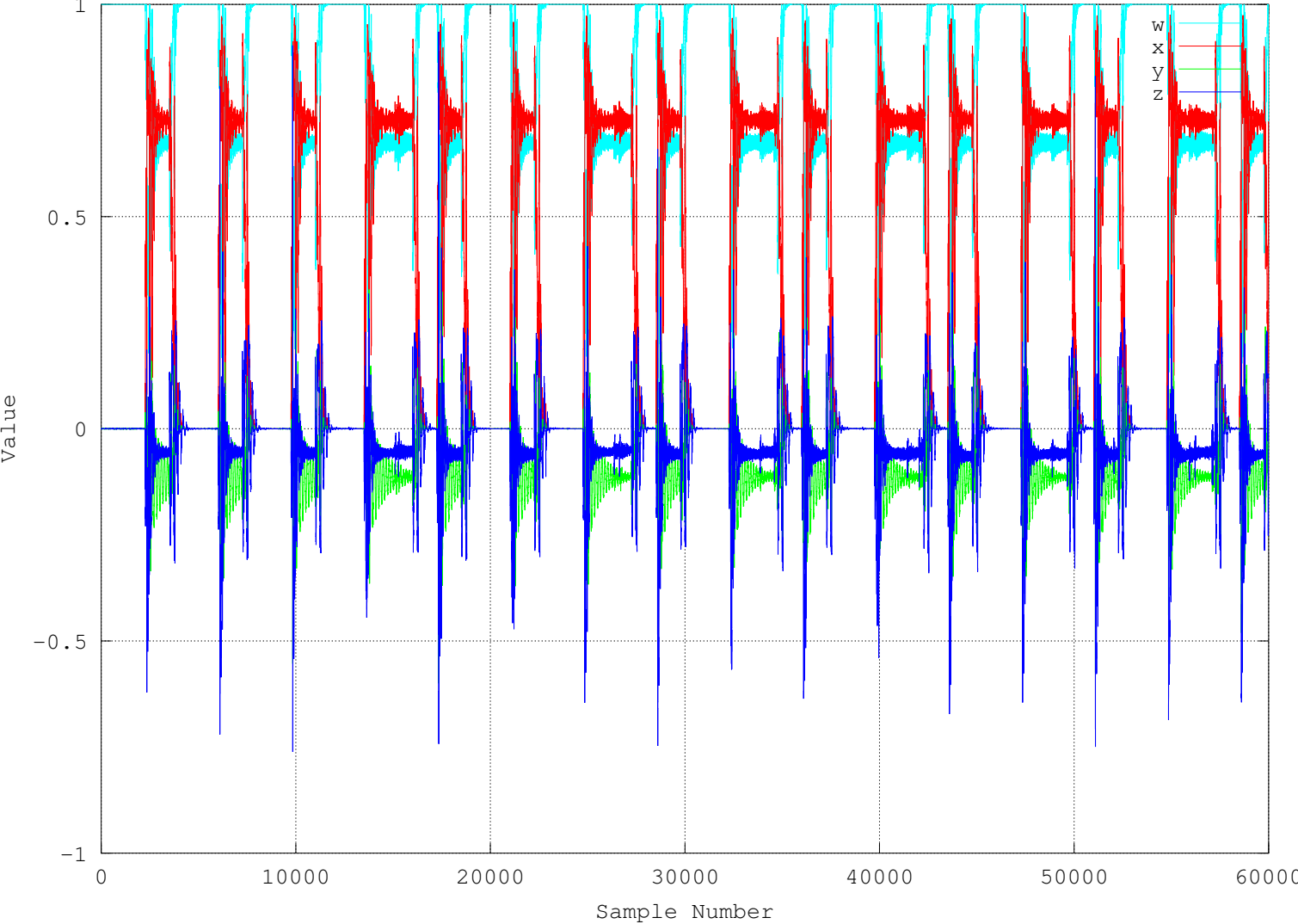
Sensor Fusion using Kalman Filter

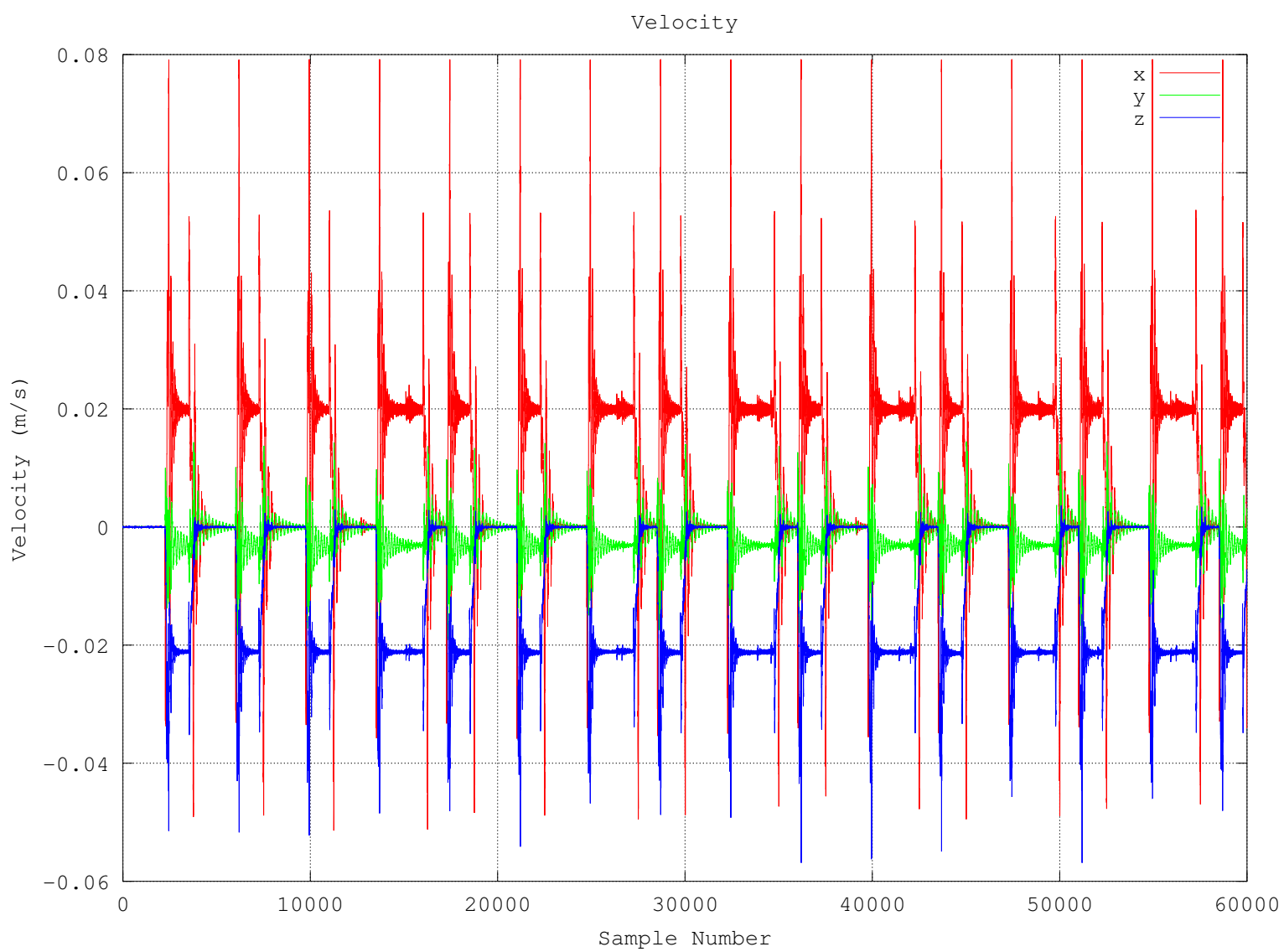


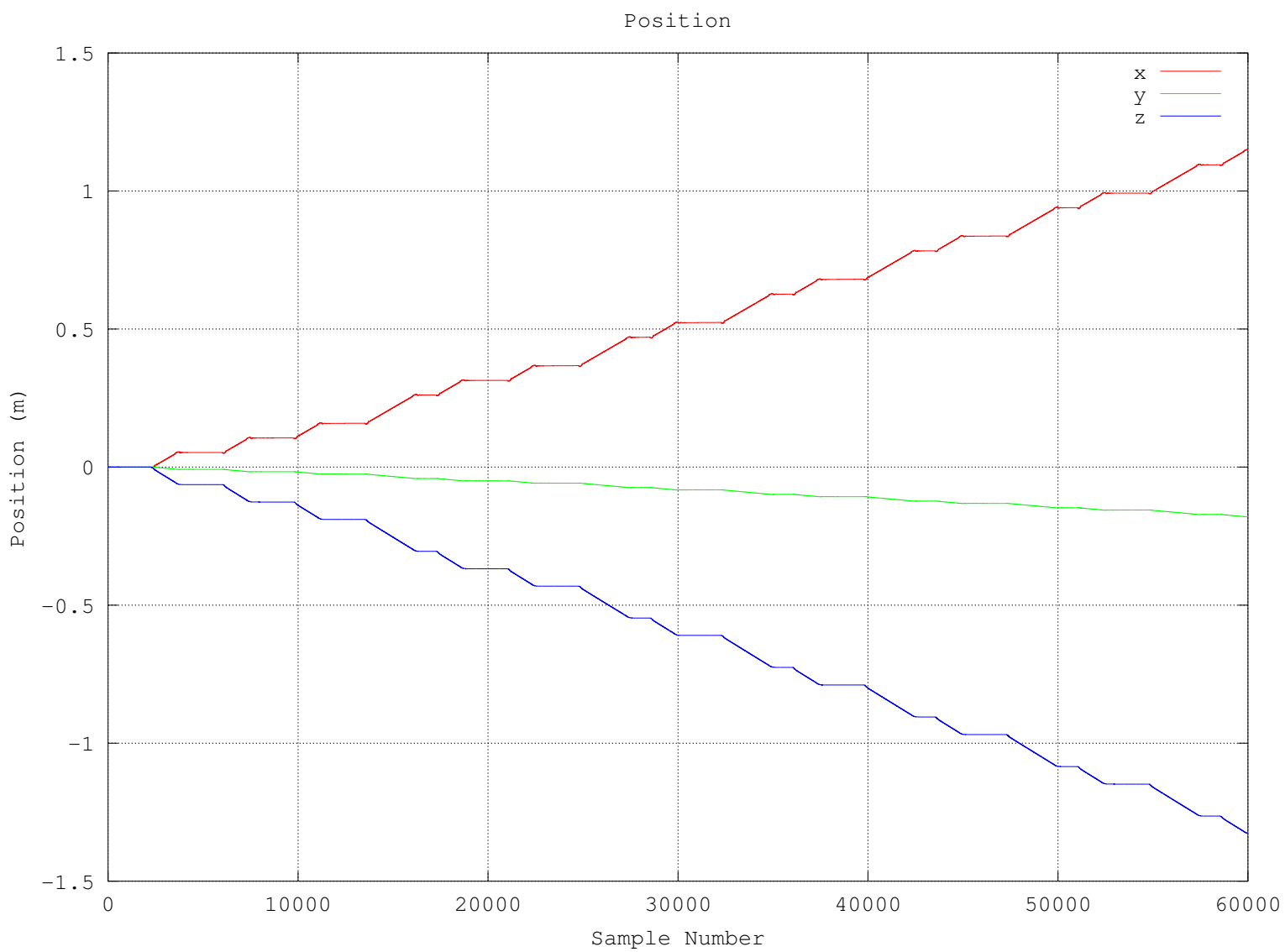
Sensor Fusion using Kalman Filter



Quaternions (after calibration and filtering)







Quaternions (after calibration and filtering)

