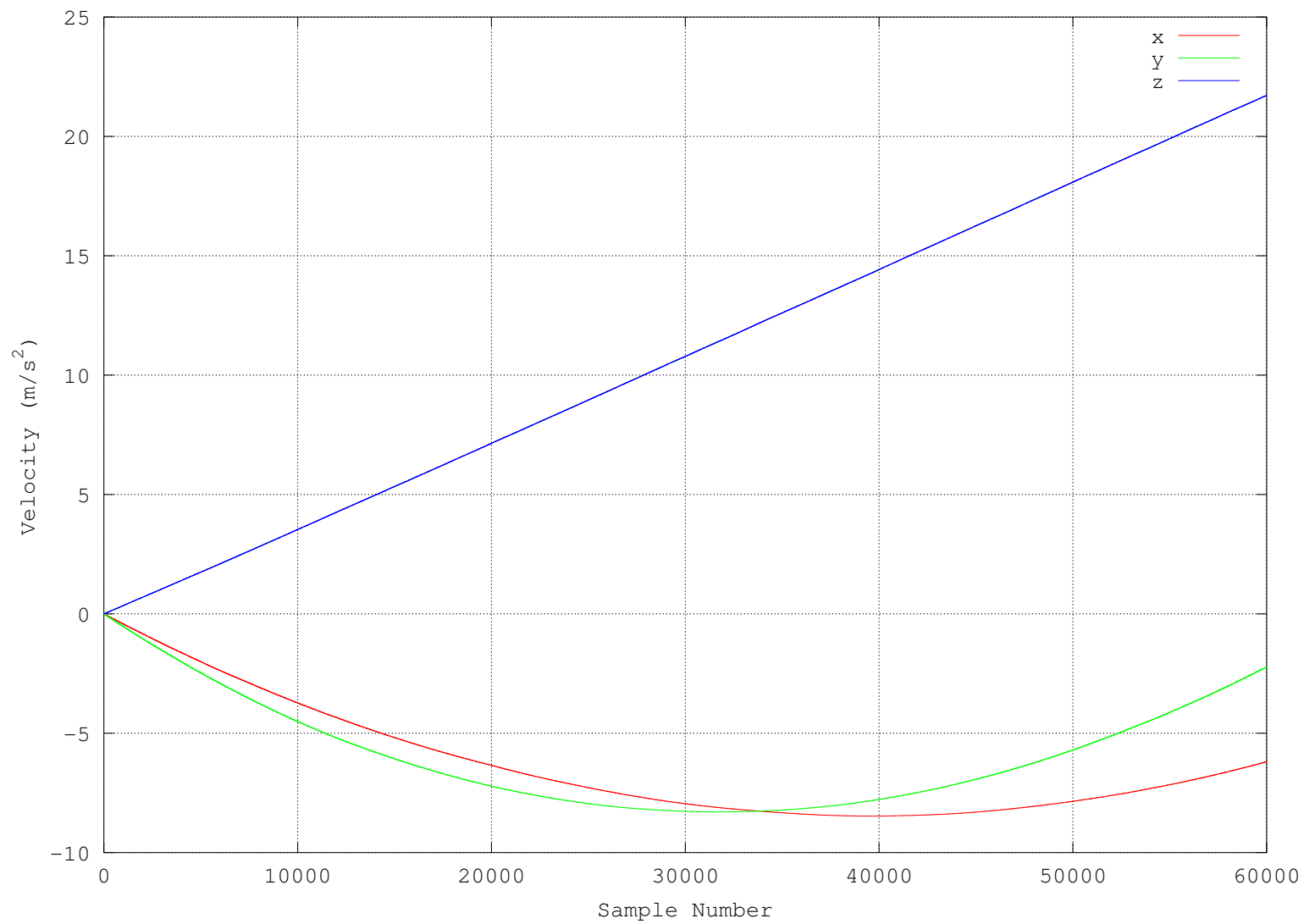


Velocity (after calibration and filtering)



Position (after calibration and filtering)

