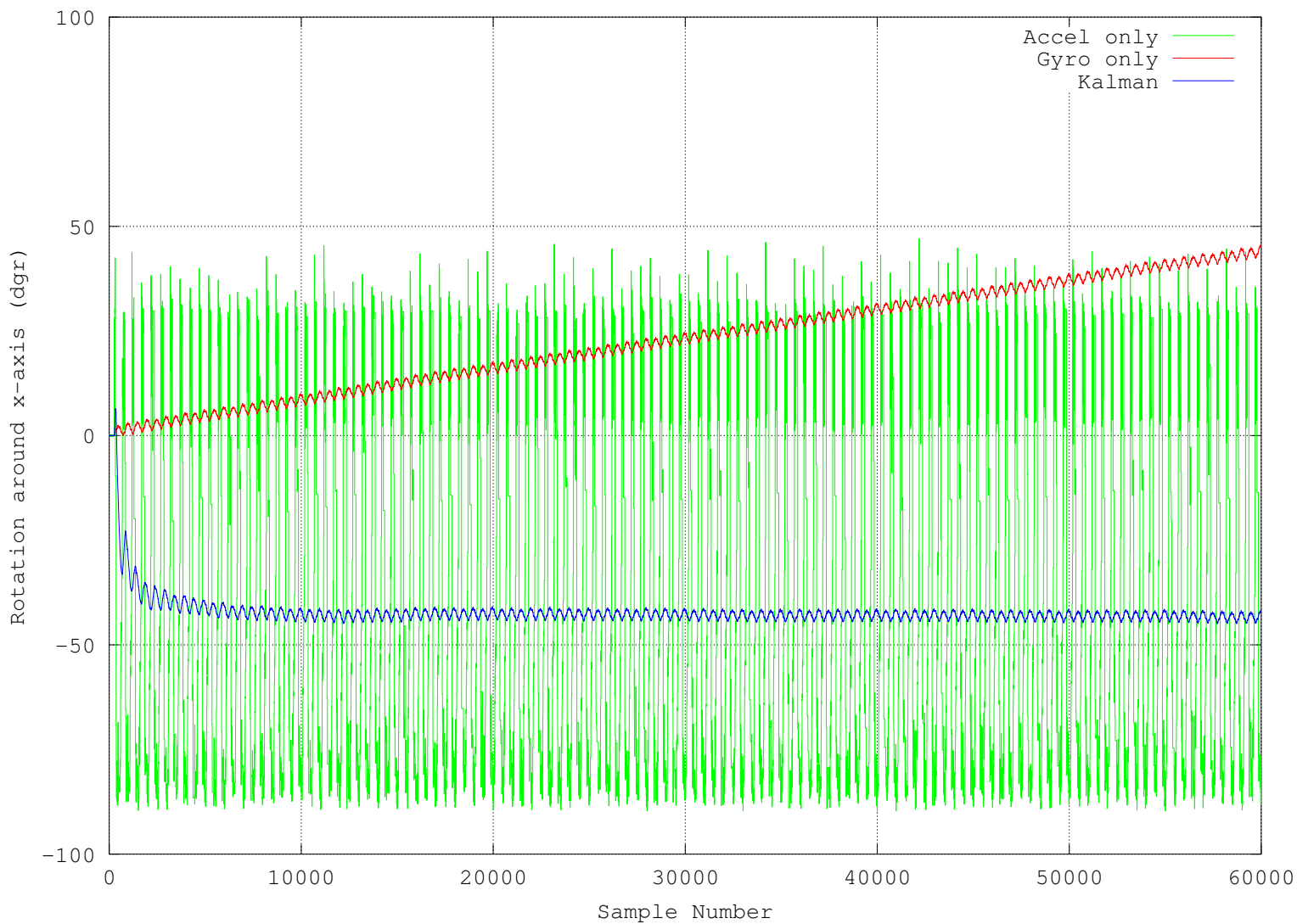


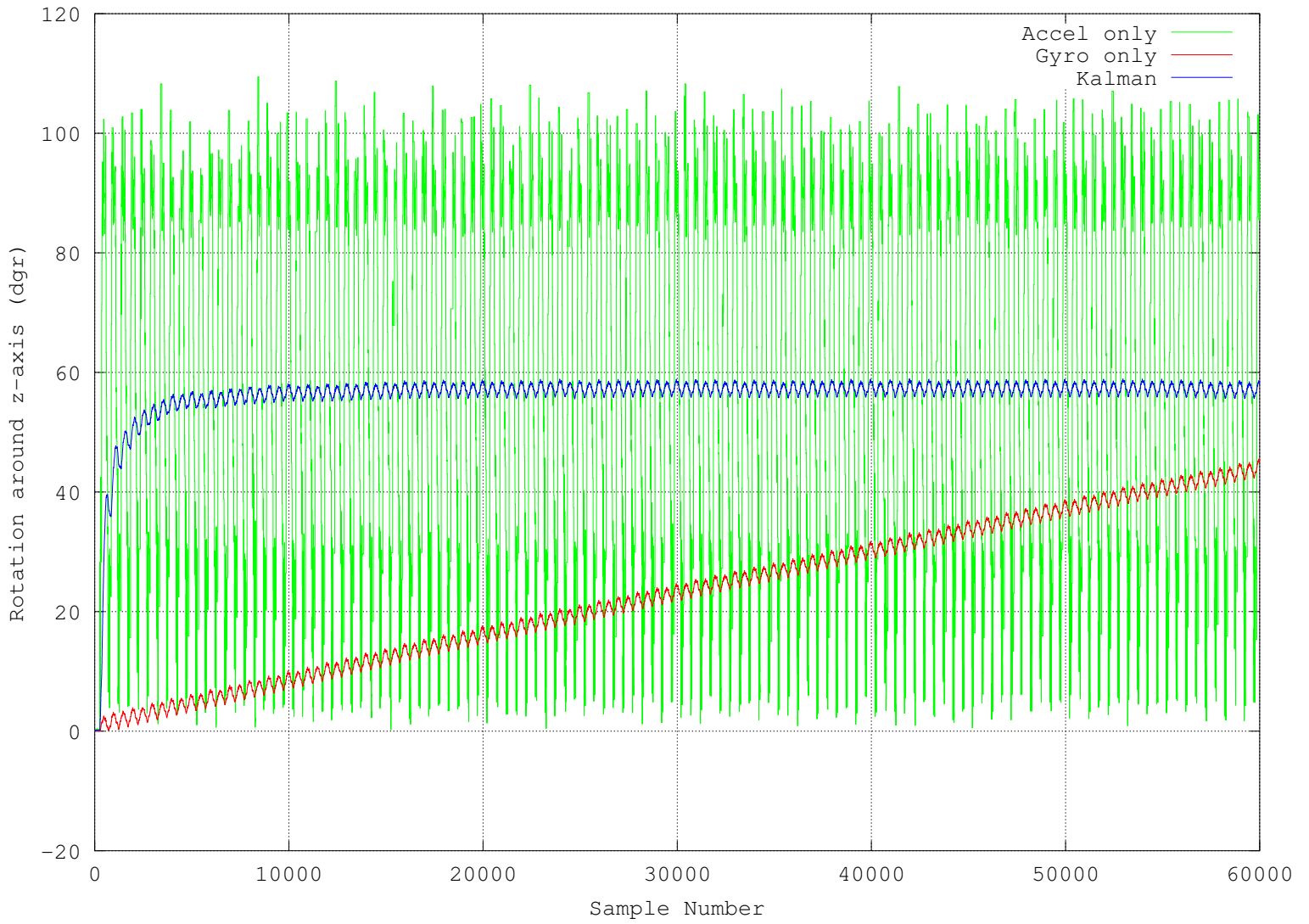
Sensor Fusion using Kalman Filter



Sensor Fusion using Kalman Filter



Sensor Fusion using Kalman Filter



Quaternions (after calibration and filtering)

