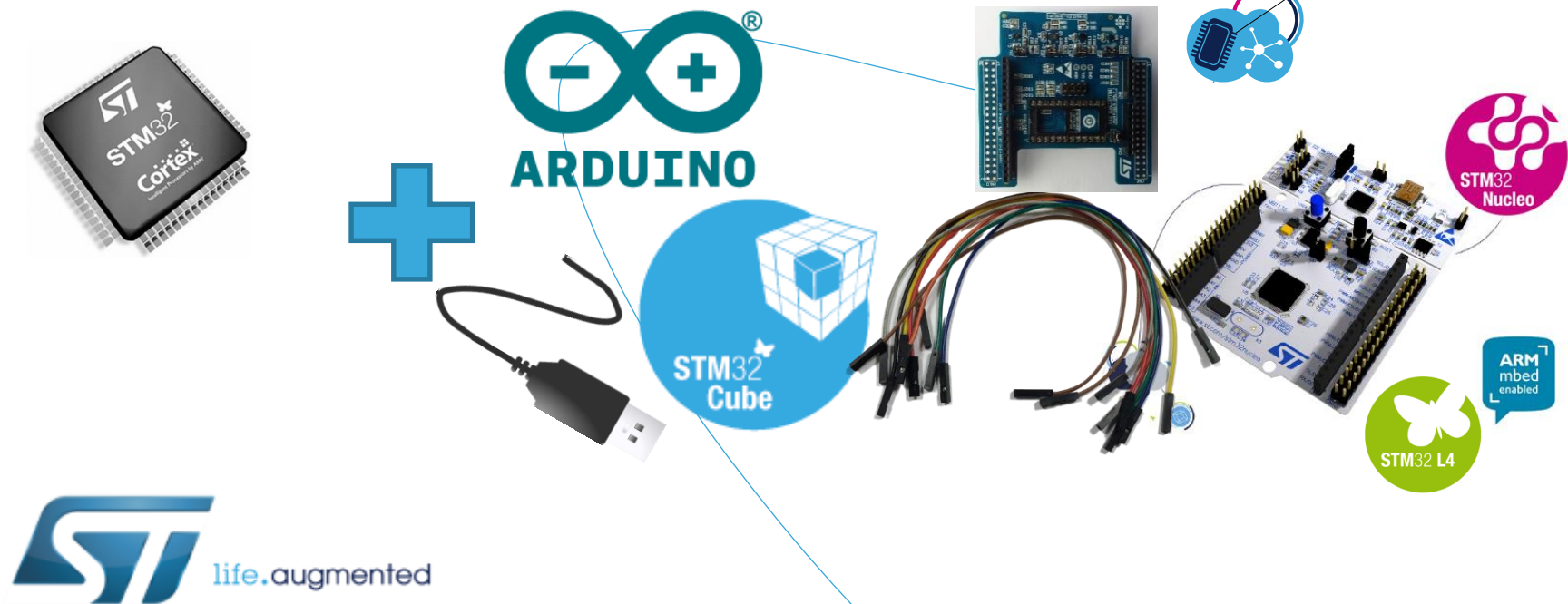


STM32 Arduino Ecosystem & sensor workshop



- Introduction
 - What is Arduino?
 - Arduino IDE downloading & installing
- Getting started with STM32 in Arduino IDE
 - Adding support for STM32 in Arduino IDE
 - List of STM32 hardware platforms supported by Arduino IDE
 - Selecting of STM32 platform in Arduino IDE sketch
- STM32 Arduino hands-ons
 - Guidelines how to develop applications
 - Hands-on 1: GPIOs
 - Hands-on 2: serial communication
 - Hands-on 3: ADC
 - Hands-in 4 : use of a X-nucleo board
- Summary
 - Benefits of Arduino
 - Drawbacks of Arduino

- Introduction
 - What is CubeMX ?
 - What is Atollic ?
- How to select the right product
 - MCU finder presentation
- STM32CubeMx hands-ons
 - Hands-on 1: Blinking a led
 - Hands-on 2: serial communication
 - Use of plotter through SWO
 - Hands-on 3: serial communication with DMA
- Summary
 - Arduino vs CubeMX
- Q&A

- Put your cell phone in silent mode
- Be respectful of the others
- Follow the signs
 - Your turn to work when the following sign appears



- When the following sign appears, you don't need to follow the instruction



- Don't hesitate to ask questions



What is Arduino?

5

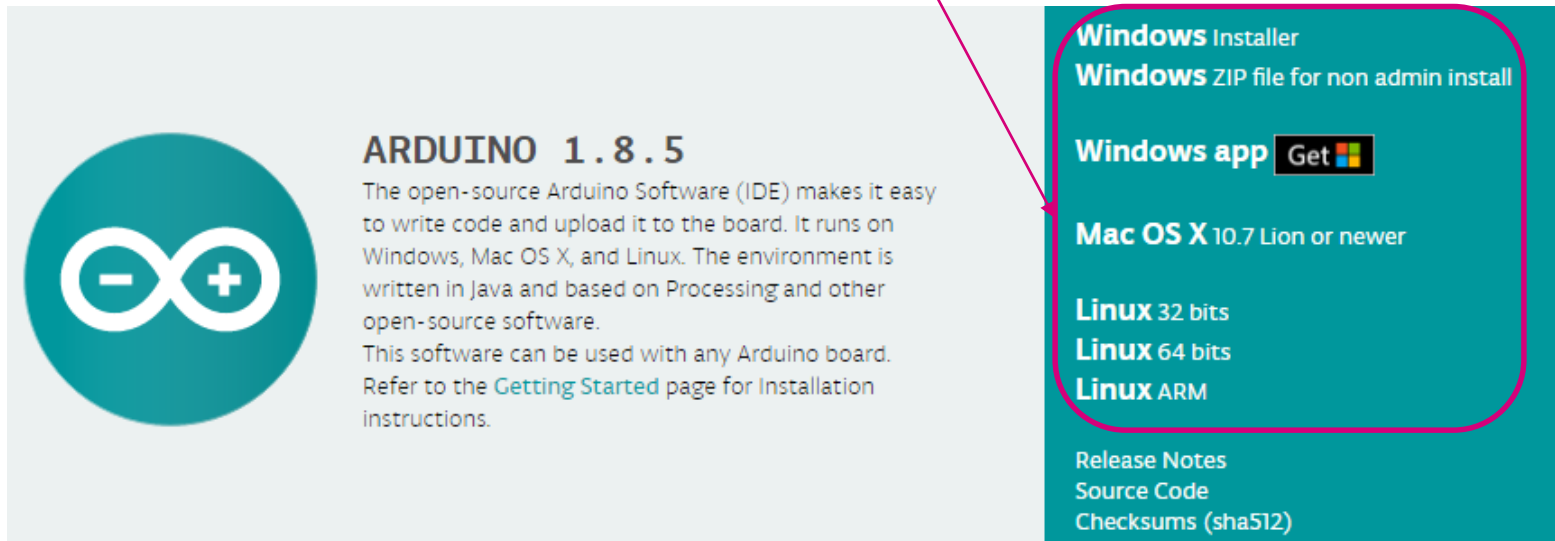
A development platform based on easy-to-use hardware and software.

- Hardware
 - **Evaluation kits with a MCUs** from different vendors
 - **Extension shields** with sensors, connectivity and more
- Software
 - **Arduino IDE** – software development platform, which allows to write, code, compile it and upload to the board. It runs on computer (Windows, Linux and Mac OS X are supported)
 - **Arduino Web Editor** – online editor, similar to Arduino IDE, giving the advantage of saving sketches in the cloud and having almost the most up-to-date version of IDE
 - **Arduino libraries** – libraries with API, used by both Arduino IDE and Arduino Web Editor for purpose of application development

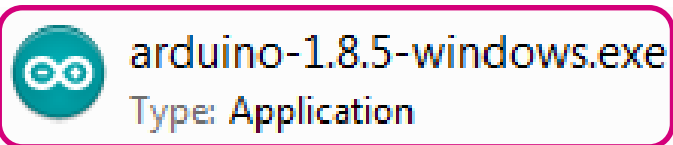
Arduino IDE – downloading & installing

6

- Downloading Arduino IDE from Arduino website
 - a) Go to <https://www.arduino.cc/>
 - b) Open tab **SOFTWARE**
 - c) Navigate to part of the website related to Arduino IDE
 - d) Click on download link for your operating system



- Installing Arduino IDE
 - Double click on downloaded file to start installation



Arduino IDE – user interface

7

- View of Arduino IDE with description of user interface

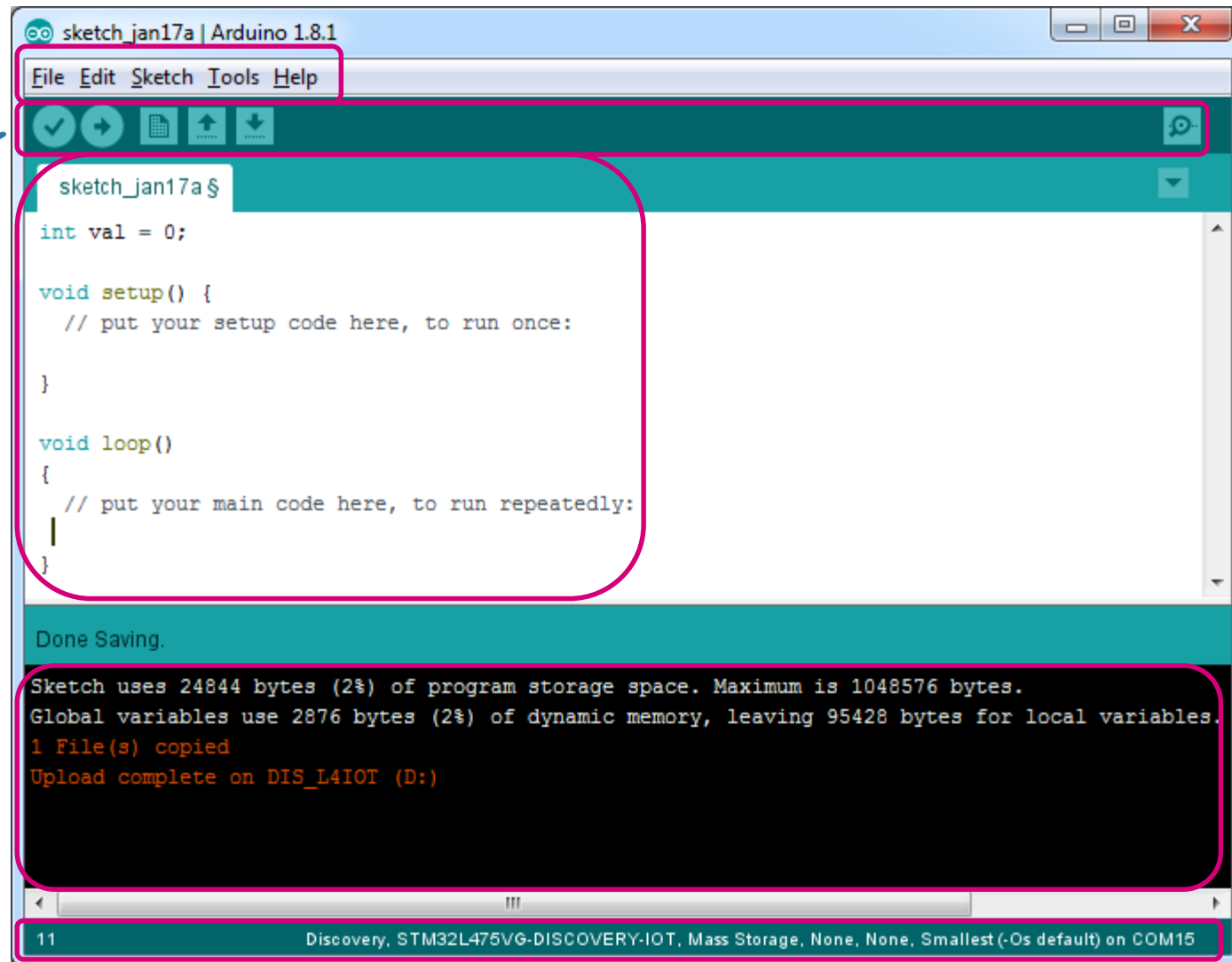
Main menu

Icons for frequently used operations

Editor

Console

Summary of HW/SW settings



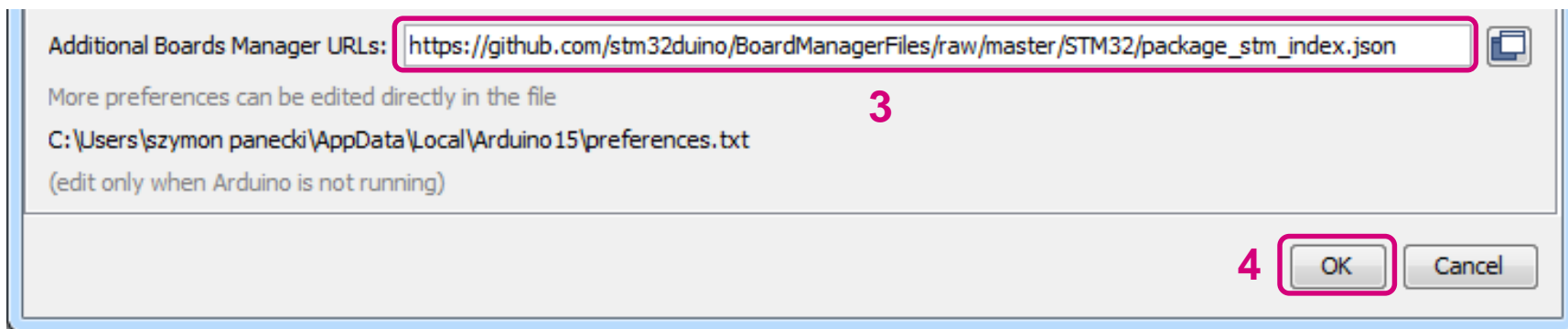
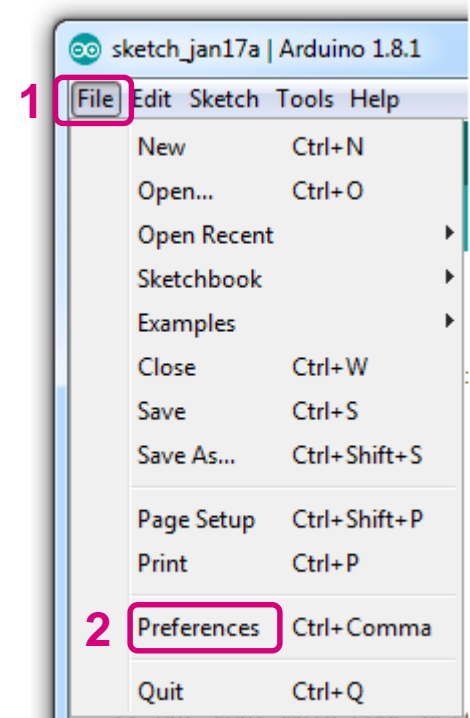
Arduino IDE – adding support for STM32

- From main menu select **File -> Preferences**



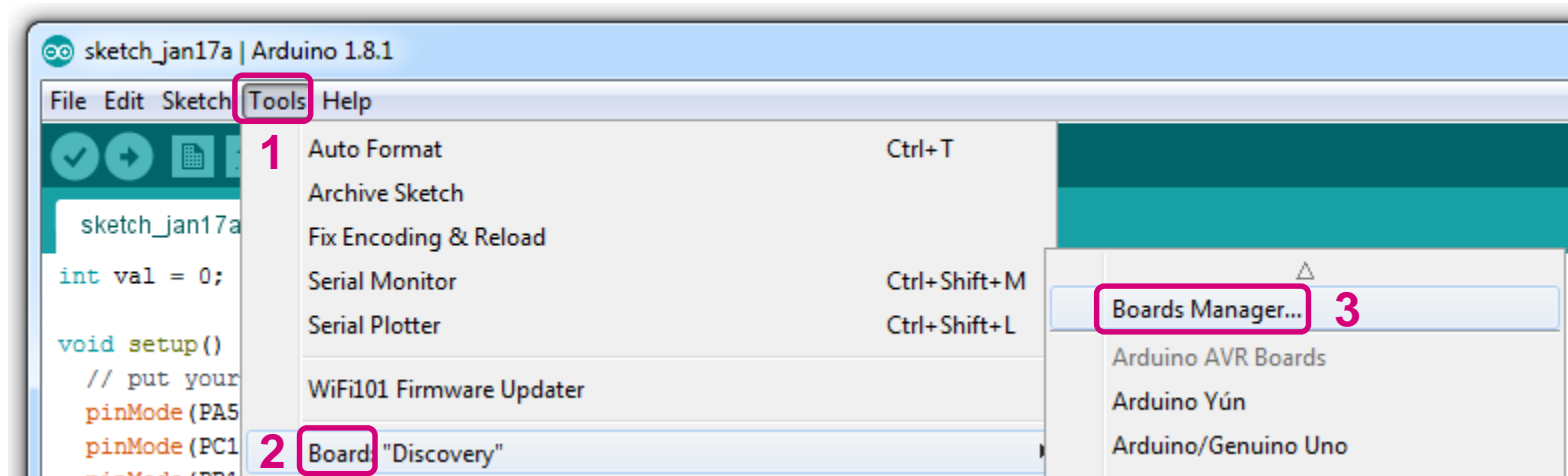
- In **Preferences** window fill in **Additional Boards Manager URL** with link:

https://github.com/stm32duino/BoardManagerFiles/raw/master/STM32/package_stm_index.json

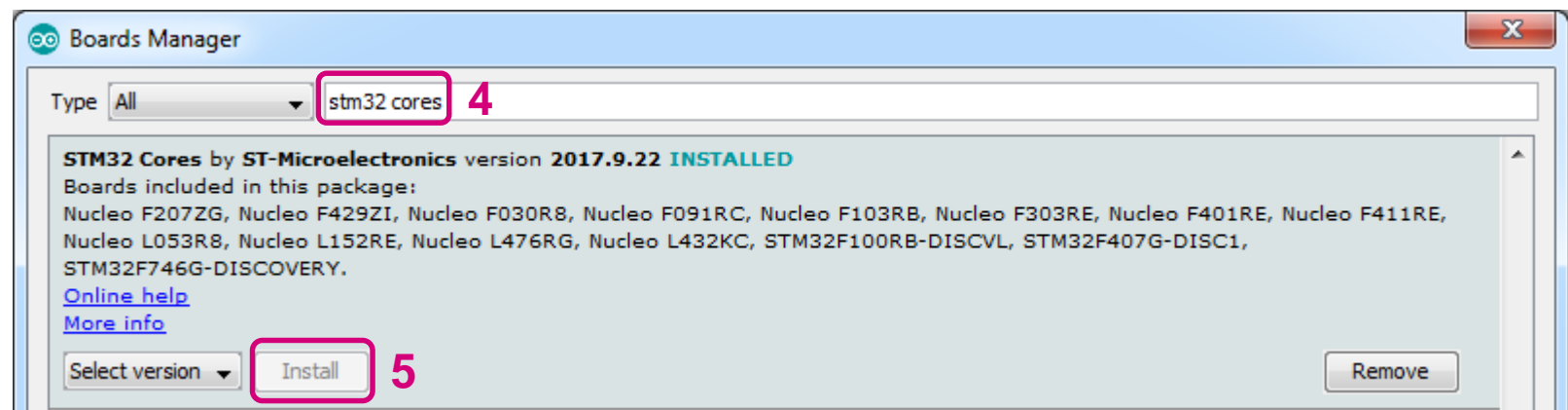


Arduino IDE – adding support for STM32

- From main menu select **Tools -> Board -> Boards Manager...**

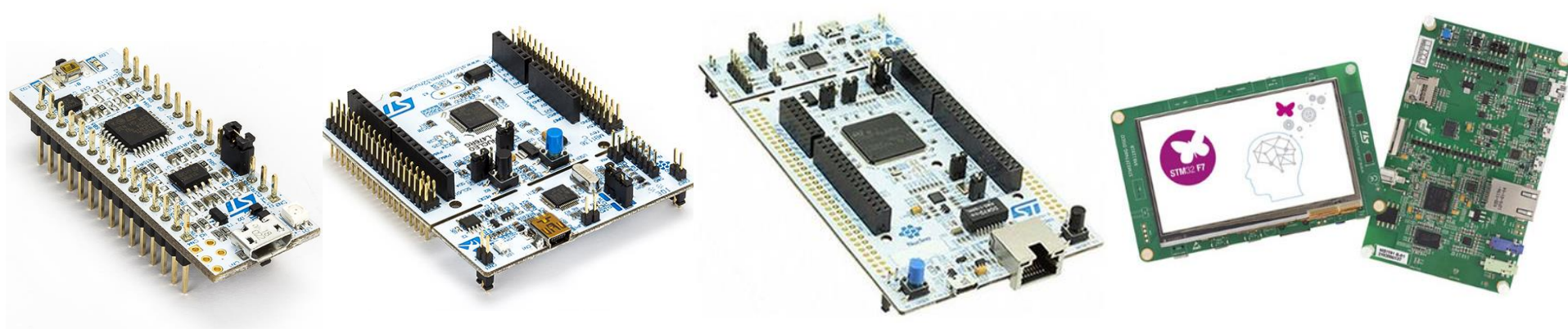


- In the filter item inside **Boards Manager** window type **STM32 cores**
- Select **STM32 cores** package and click on **Install** button

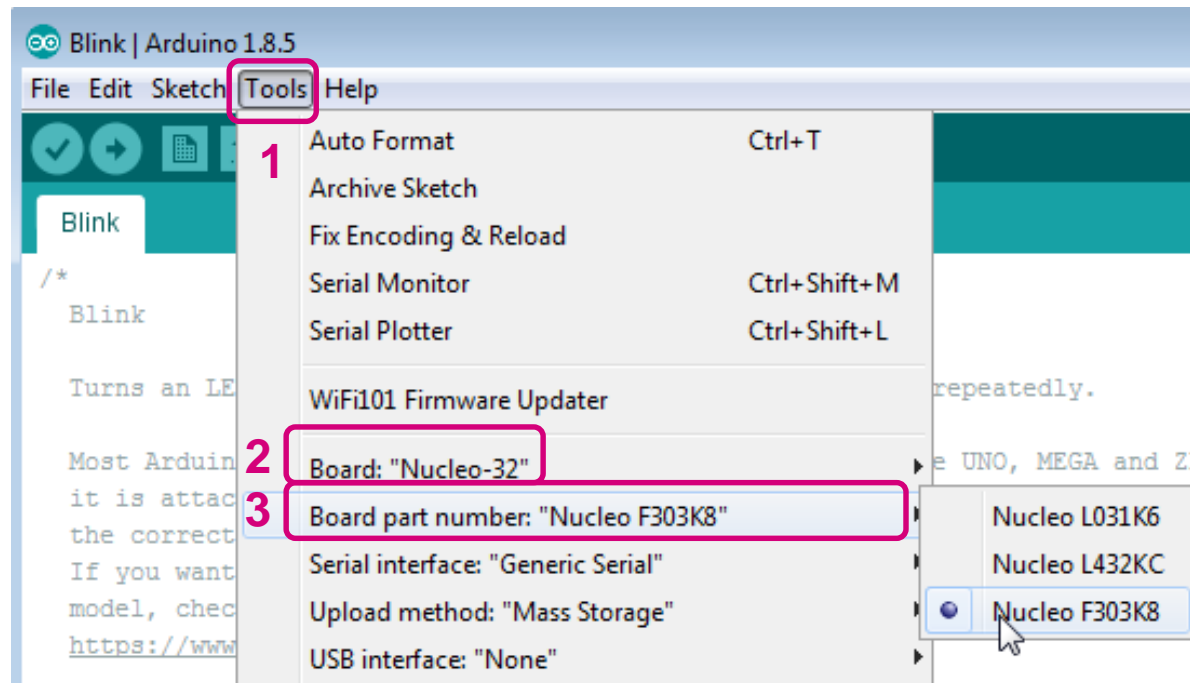


Arduino for STM32: hardware

- **STM32 cores** package provides Arduino support for these boards:
 - **STM32F0**: Nucleo F030R8, Nucleo F091RC
 - **STM32F1**: Nucleo F103RB, STM32VLDISCOVERY
 - **STM32F2**: Nucleo-F207ZG
 - **STM32F3**: Nucleo F303RE
 - **STM32F4**: Nucleo F401RE, Nucleo F411RE, Nucleo F429ZI, STM32F407G-DISC1
 - **STM32F7**: STM32F746G-DISCOVERY
 - **STM32L0**: Nucleo L053R8
 - **STM32L1**: Nucleo L152RE
 - **STM32L4**: Nucleo L432KC, Nucleo L476RG, STM32L4 Discovery kit IoT node



- From main menu select **Tools** -> **Board** and from the list click on one board type, for example **Nucleo-32**
- From main menu click on Tools -> Board part number and from the list click on one board, for example **Nucleo F303K8**



The board we will use

13

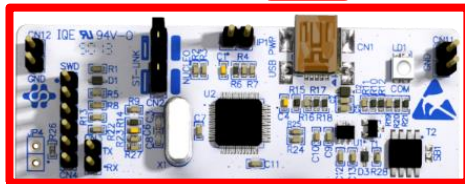
❑ NUCLEO-F303K8 board

❑ Mini-USB cable



STLink v2.1

USB

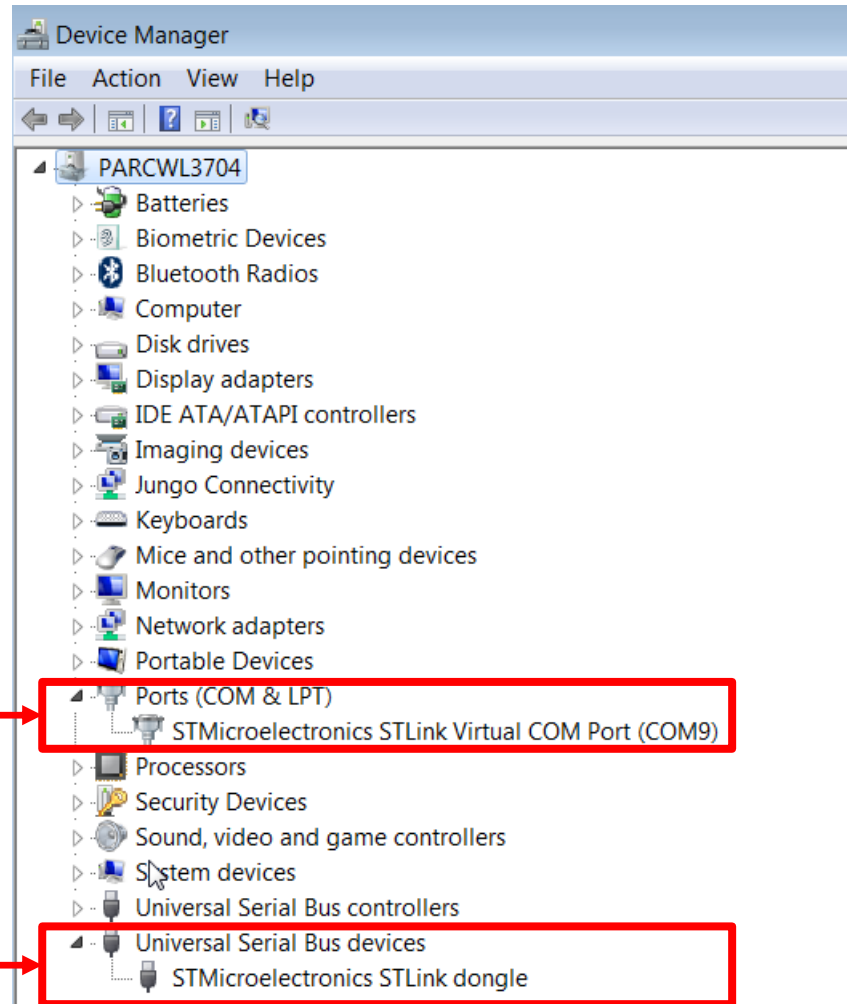


User Button
on PC13

Reset



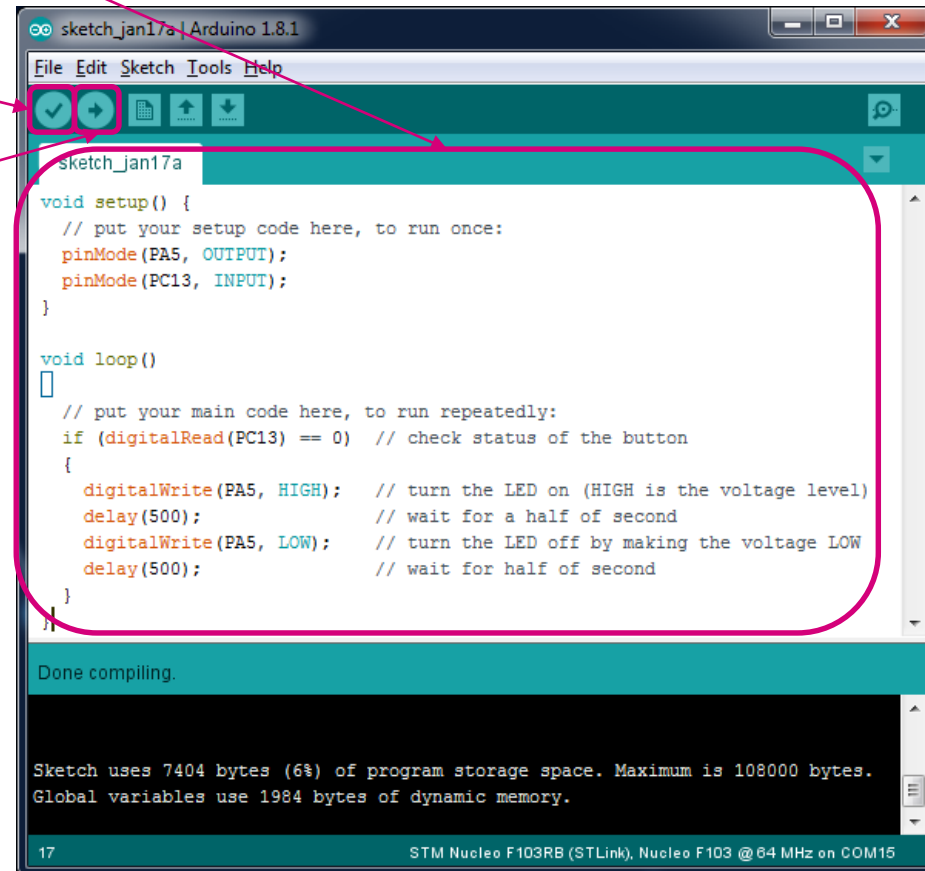
Picture to be changed



In Windows : 2 USB profile are created
STLINK & Serial comm (over USB)

Arduino IDE – guidelines how to develop applications

- Create a new sketch: from main menu click on **File -> New**
- Write user code in editor
- Compile an application by clicking on a **Verify/Compile** button
- Upload an application by clicking on an **Upload** button
- Watch the application running on hardware platform



STM32 Arduino application 1: GPIOs

Introduction to functions

- Function **pinMode**

- Purpose of usage: to configure selected GPIO
- Arguments: port name and pin number, configuration option
- Example of usage: `pinMode(PA5, OUTPUT);`

- Function **digitalWrite**

- Purpose of usage: to set logical state on output pin
- Arguments: port name and pin number, logical state
- Example of usage: `digitalWrite(PA5, HIGH);`

- Function **digitalRead**

- Purpose of usage: to read logical state on input pin
- Arguments: port name and pin number
- Example of usage: `digitalRead(PC13);`

STM32 Arduino application 1: GPIOs Implementation

- Application: reading of user button (pin PC13) and toggling of LED (pin PA5) when button is pressed
- Code:
 - Call of **pinMode** function to configure PC13 and PA5
 - Call of **digitalRead** function to read state of PC13
 - Call of **digitalWrite** function to toggle PA5
 - Call of **delay** function in milliseconds to make PA5 state visible



```
Blink | Arduino 1.8.5
File Edit Sketch Tools Help

void setup() {
  // initialize digital pin LED_BUILTIN as an output.
  pinMode(PA5, OUTPUT);
  pinMode(PC13, INPUT);
}

// the loop function runs over and over again forever
void loop() {
  if (digitalRead(PC13) == 0)
  {
    digitalWrite(PA5, HIGH); // turn the LED on (HIGH is the voltage level)
    delay(1000);              // wait for a second
    digitalWrite(PA5, LOW);  // turn the LED off by making the voltage LOW
    delay(1000);              // wait for a second
  }
}
```

STM32 Arduino application 2: serial comm.

Introduction to functions

- Function **Serial.begin**

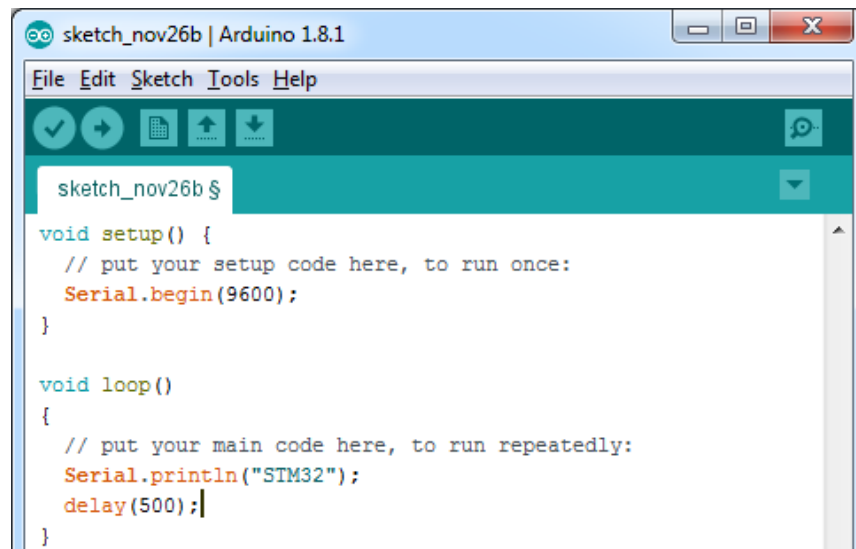
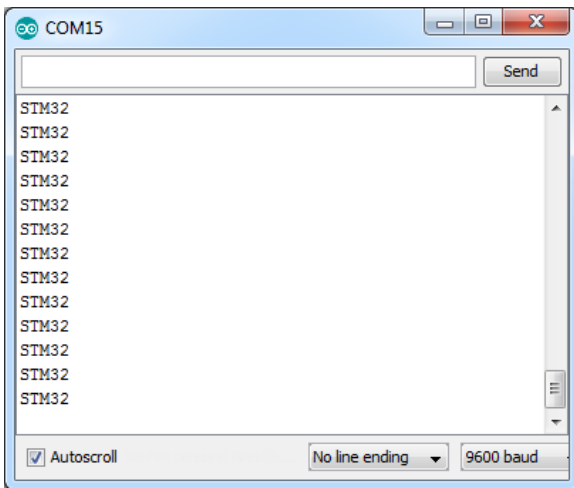
- Purpose of usage: to configure baudrate of serial interface
- Arguments: baudrate value
- Example of usage: `Serial.begin(9600);`

- Function **Serial.println**

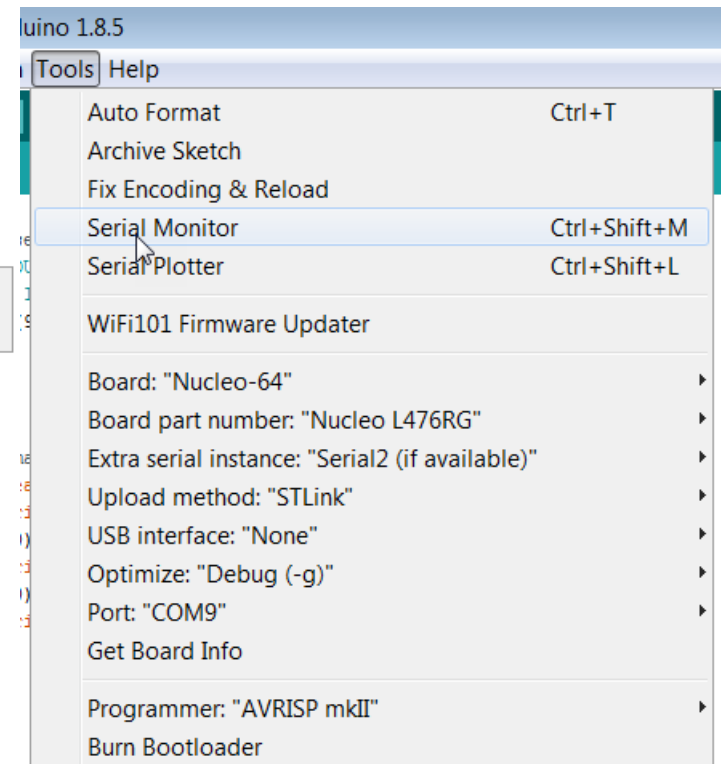
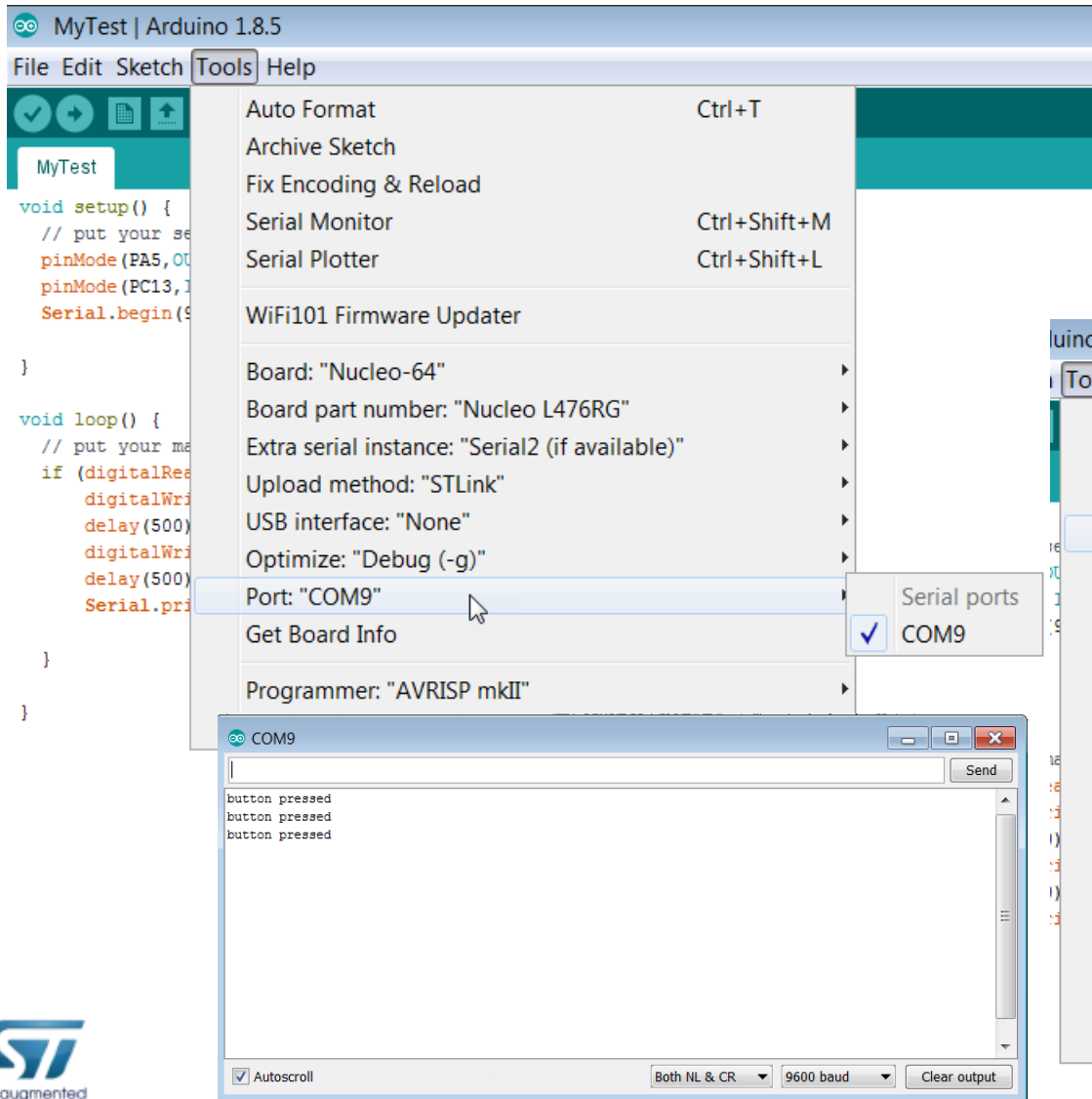
- Purpose of usage: to send data over serial interface
- Arguments: data to be sent
- Example of usage: `Serial.println(„Hello world“);`

STM32 Arduino application 2: serial comm. Implementation

- Application: sending data over serial interface
- Code:
 - Call of **Serial.begin** function to configure baudrate
 - Call of **Serial.println** function to send data
 - Call of **delay** function to make a short brake before sending again the data
- Additional steps
 - Open **Serial Monitor** (CTRL+Shift+M), which will present data received from the board



Using serial monitor of arduino (CTRL+SHIFT+M)



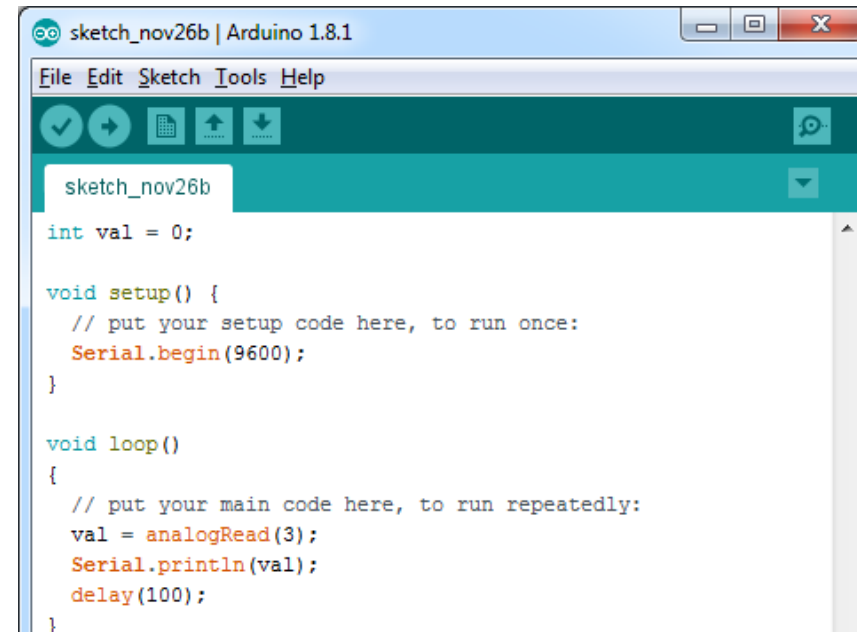
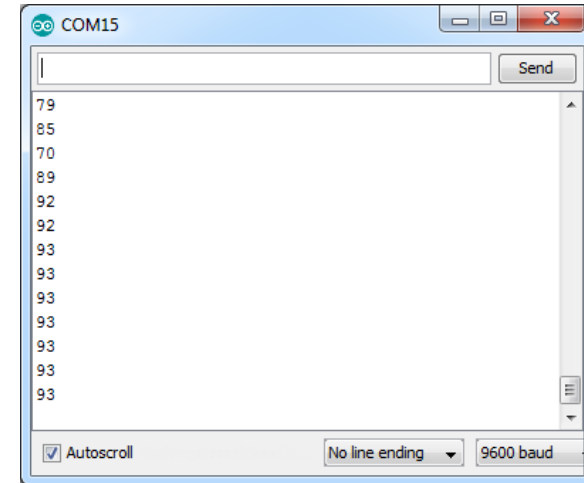
STM32 Arduino application 3: ADC

Introduction to functions

- Function **analogRead**
- Purpose of usage: Read voltage value
 - Arguments: analog pin number
 - Example of usage: `analogRead(3)`

STM32 Arduino application 3: ADC Implementation

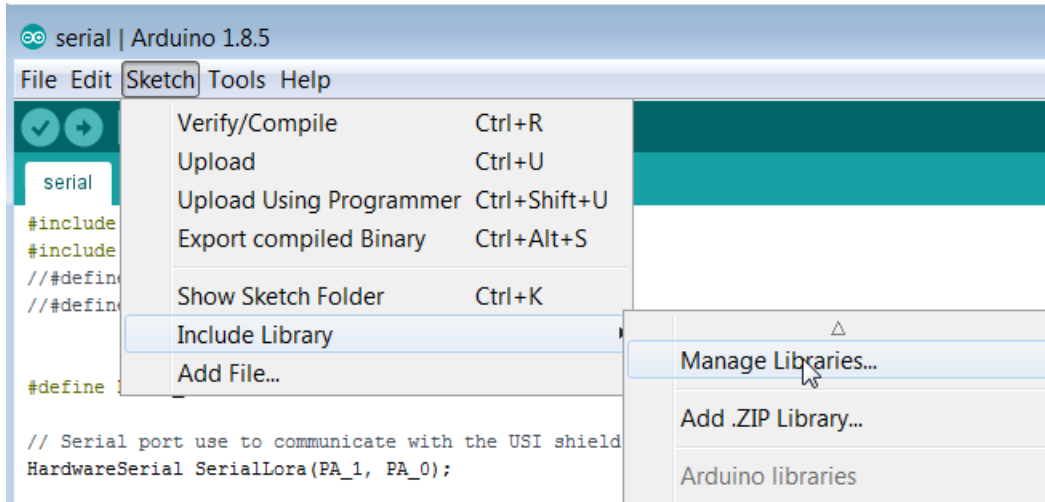
- Application: making A-D conversion from the analog pin 3 and sending conversion results over serial interface
- Code:
 - Define variable, which will store A-D result
 - Call of **Serial.begin** function to configure baudrate
 - Call of **analogRead** function to get value from analog pin 3
 - Call of **Serial.println** function to send data
 - Call of **delay** function to make a short brake before sending again the data
- Additional steps
 - Open **Serial Monitor** (CTRL+Shift+M), which will present data received from the board





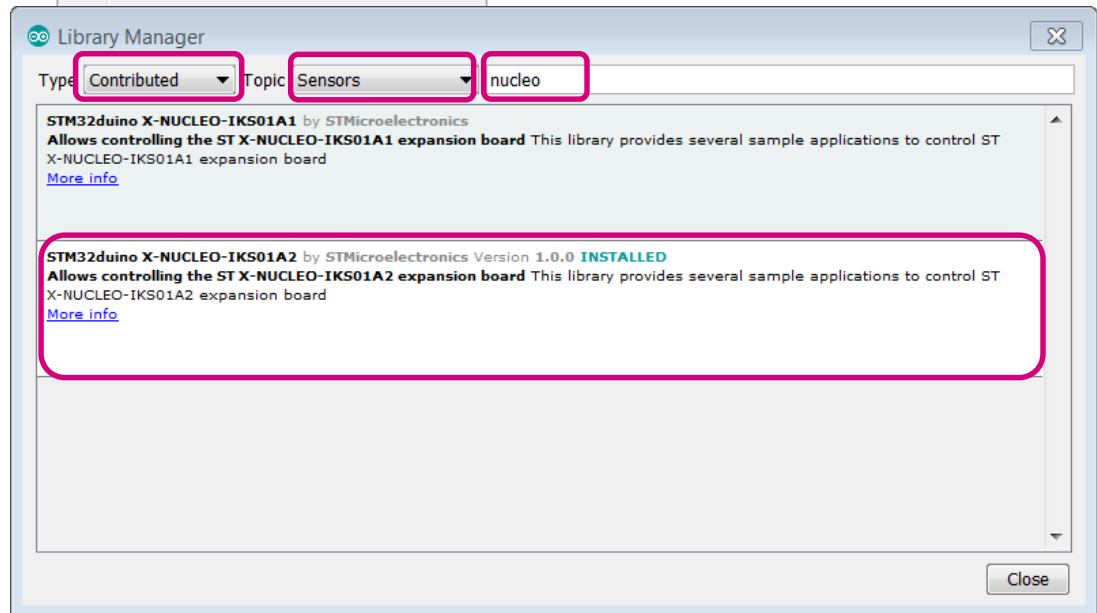
STM32 Arduino libraries for X-NUCLEO-IKS01A2

22



- The keyword can be:

- nucleo
- STM32duino
- The name of a sensor
 - HTS221
- etc...

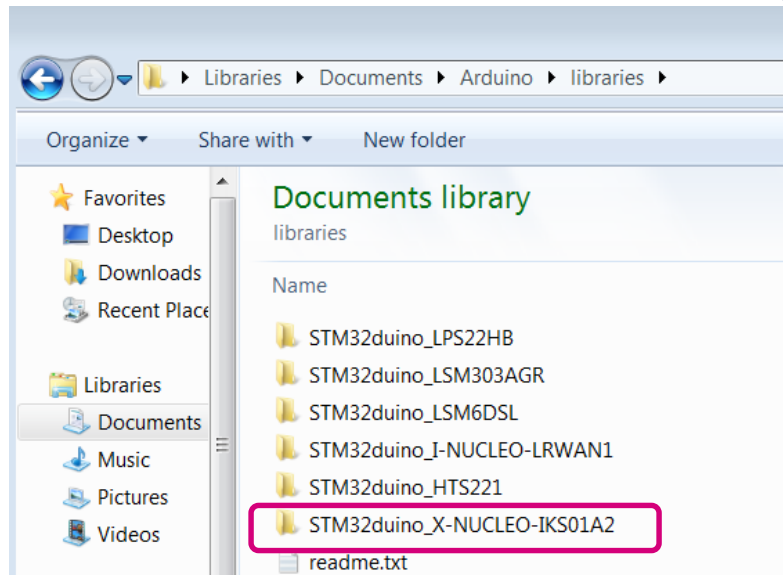




STM32 Arduino extensions for Sensors

23

1. Open a website with Arduino libraries for STM32:
<http://www.arduinolibraries.info/architectures/stm32>
2. Click on **STM32duino X-NUCLEO-IKS01A2** to download library for the **X-NUCLEO-IKS01A2** board
3. In Arduino IDE use main menu and click on **Sketch -> Include Library -> Add .ZIP library...**, then select downloaded library

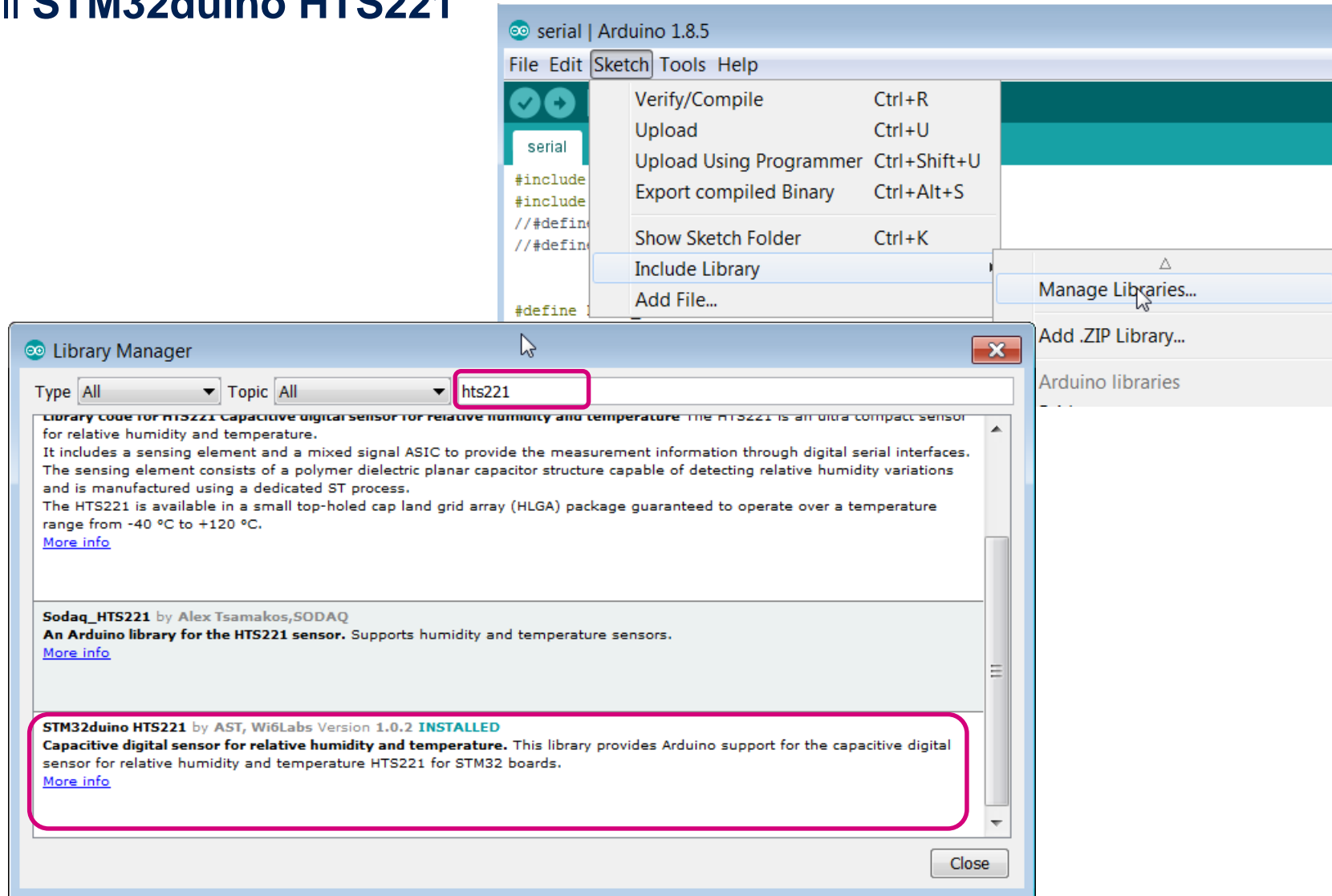




STM32 Arduino libraries for HTS221

24

- Install **STM32duino HTS221**





Send Humidity and Temperature by UART

25

- Select the example in STM32duino HTS221
 - You will have to adapt it as it is developed for a different board
- Where to find the definitions ?
 - Refer to <https://github.com/stm32duino/wiki/wiki/Where-are-sources>
 - Locate « variant.h » in variants folder
- What you need to look for ?
 - LED_BUILTIN
 - SDA/SCL : they are renamed on the board itself D14/D15
 - You can also look at or double-check with the schematics

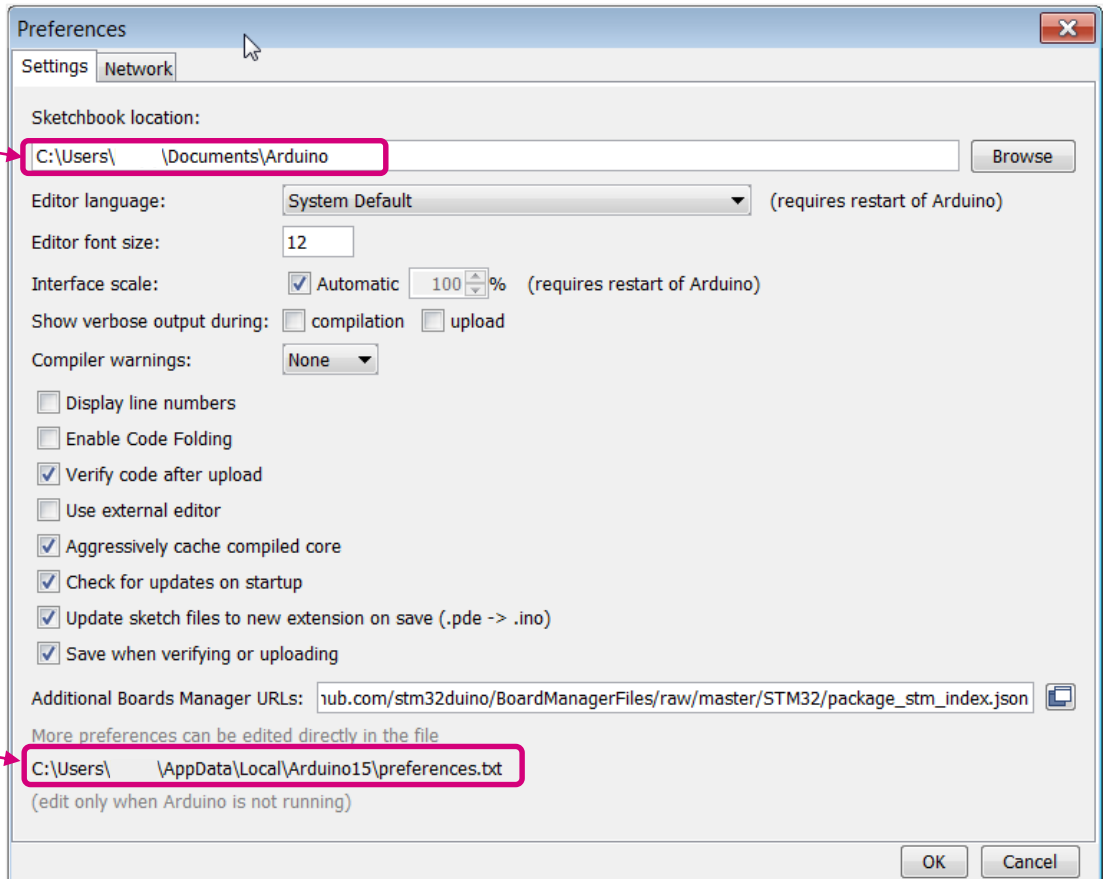
Quickly access to the package and libraries

26

- Open menu File/Preferences

Location of the
installed Libraries

Location of the core
packages, you can
click on the link



27





Customize the example

28

- Simply replace the initialization of the I2C bus with :

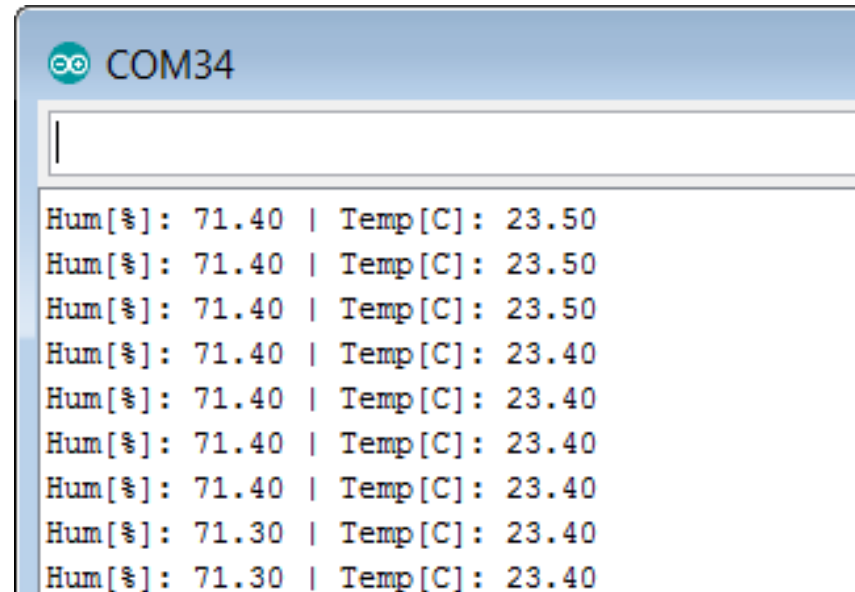
```
dev_i2c = new TwoWire(SDA, SCL);
```

- You can comment the definitions:

```
// #define I2C2_SCL PB10
```

```
// #define I2C2_SDA PB11
```

- Upload and check the monitor



```
COM34
Hum[%]: 71.40 | Temp[C]: 23.50
Hum[%]: 71.40 | Temp[C]: 23.50
Hum[%]: 71.40 | Temp[C]: 23.50
Hum[%]: 71.40 | Temp[C]: 23.40
Hum[%]: 71.40 | Temp[C]: 23.40
Hum[%]: 71.40 | Temp[C]: 23.40
Hum[%]: 71.40 | Temp[C]: 23.40
Hum[%]: 71.30 | Temp[C]: 23.40
Hum[%]: 71.30 | Temp[C]: 23.40
```

Benefits of using Arduino

- Rapid development of application

API is very easy to use:

- it contains mainly basic C forms (functions)
- one or few lines of code is/are enough to make peripherals work
- common API for all supported MCUs (easy porting/migrating)

API covers not only MCU's resources, but also external components (sensors, wireless communication, ...)

- Multiple MCUs platforms

Supports ARM and non-ARM MCU platforms from different vendors

- Supports many operating systems

Version for Windows, Linux and MacOS



- Free of charge

IDE is free of charge and doesn't have any time or code size limitations

- Open source

Libraries for MCUs and companion devices are developed by community

Drawbacks of using Arduino

- Limited selection of MCUs within family

Only part of MCUs from selected family are supported by Arduino

- Limited control of MCU

Detailed configuration of MCU is not possible like system clock configuration, low-power modes and more

- Limited debugging possibilities

There is no real debugger, which allows to run the code step by step, analyze MCU's registers, place breakpoints and more. Main debugging tool is serial monitor

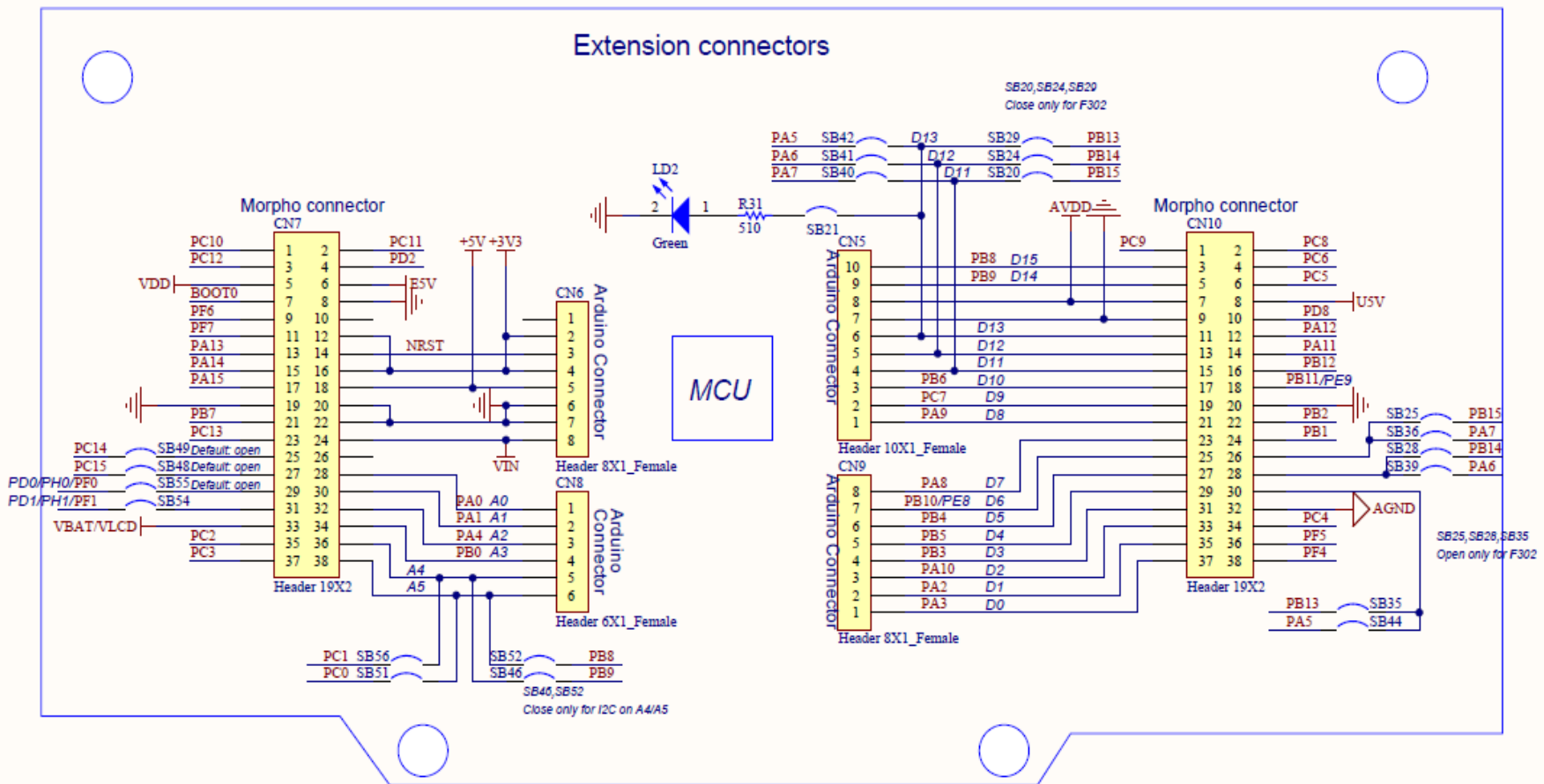
- Limited number of pins for interconnect

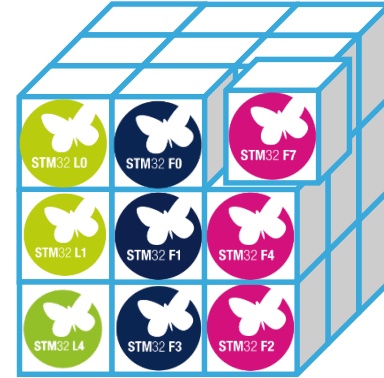
Arduino standard connect allows a few IO pins (PWM, UART, I2C, SPI...) Which had been extended with the MEGA



Arduino pin out & Morpho connectors

33

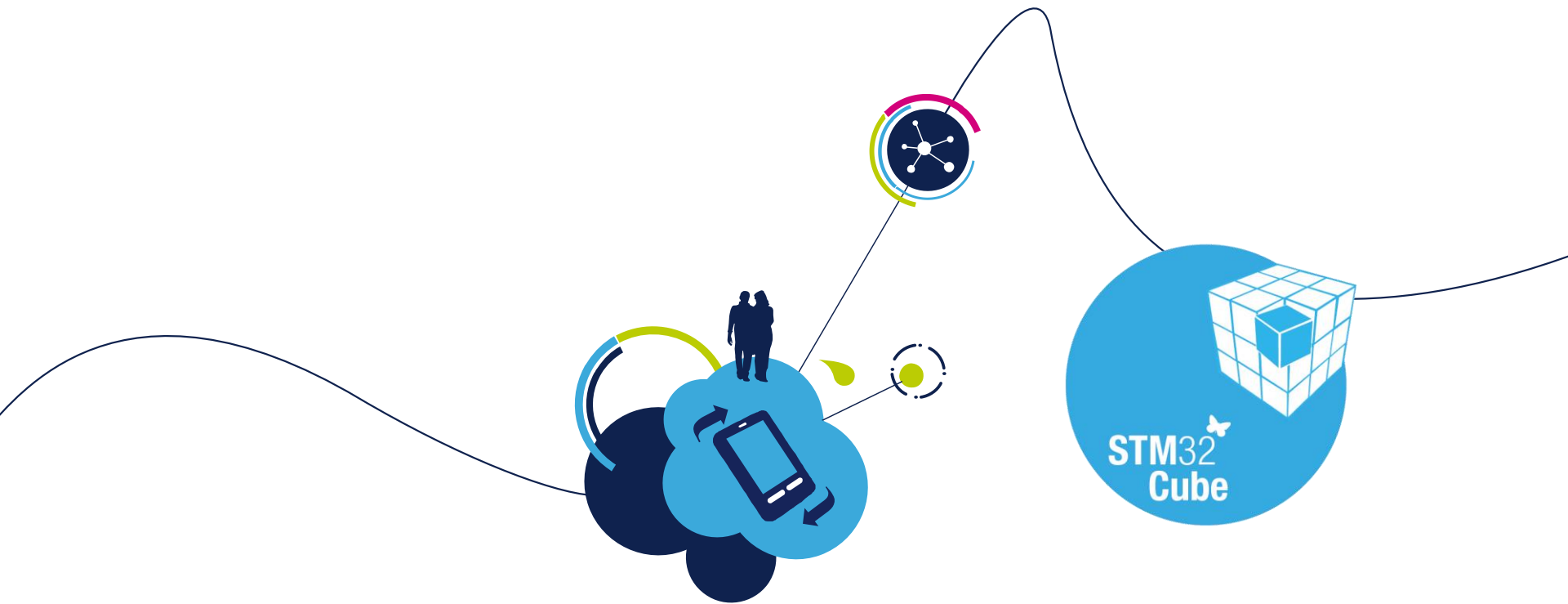




- Now it is a right time for some software activity with STM32 cube
- STM32 cube allows you fast prototyping like Arduino while offering full/precise configuration & access to power of STM32 devices

Let's discover with an example

- Our first task is to create LED blinking application – just to check whether all the software packs and drivers are installed correctly and whether the hardware is ready for more challenging job



Creating the 'L4_Blinky' example in STM32CubeMX

Goal of this part

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☐ To practice a little bit with STM32CubeMX by:

☐ MCU selection

☐ Play a bit with clock configuration for STM32L4 device

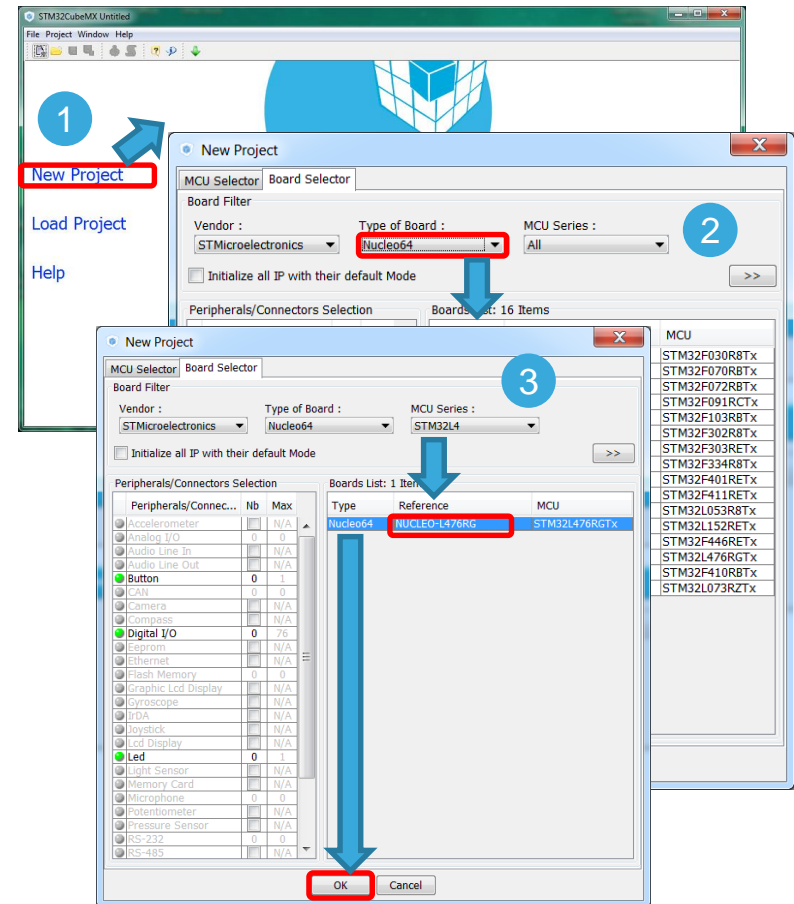
☐ Create a skeleton of simple LED blinking application

☐ Have some fun!



Creating a New Project

1. From the STM32Cube Home Page or **Menu** → **File** select **New Project**
2. There are 3 ways to create a New Project
 - By STM32 Series and Product Line
 - By Peripheral Mix
 - By Board
3. For this example we will use NUCLEO–L476RG
 - Select the **Board Selector** Tab from the top left
 - Select **Type of Board** to be **Nucleo64**
 - Select **STM32L4** in **MCU Series**
 - Select the **NUCLEO–L476RG** from the list on the right
 - Click 'OK' to continue

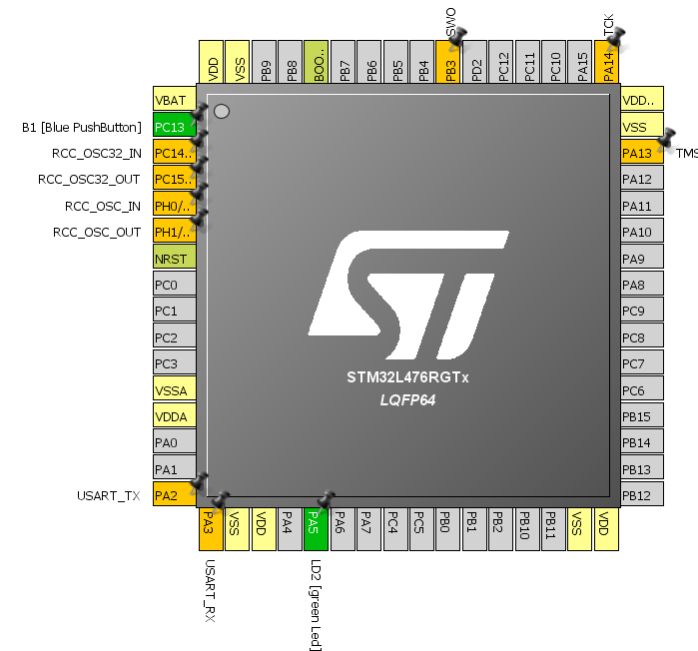


Peripheral and Pin Configuration

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- You will be presented with the pinout of the **NUCLEO-L476RG**
- The debug pins, Push Button and LED are already highlighted in **green**, to say they are connected to the hardware on the board.
- System Pins are highlighted in **yellow/yellow-green**
- Optional Hardware, like crystals and USART are highlighted in **orange**. This means there are PCB connections but not necessarily any hardware connected by default.
- For the “L4_Blinky” example all relevant peripherals are already connected, so no modifications are needed.



Clock Configuration

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Task: Configure clock system to use internal oscillator with PLL @80MHz

1. Select '**Clock Configuration**' tab

1

Clock Configuration

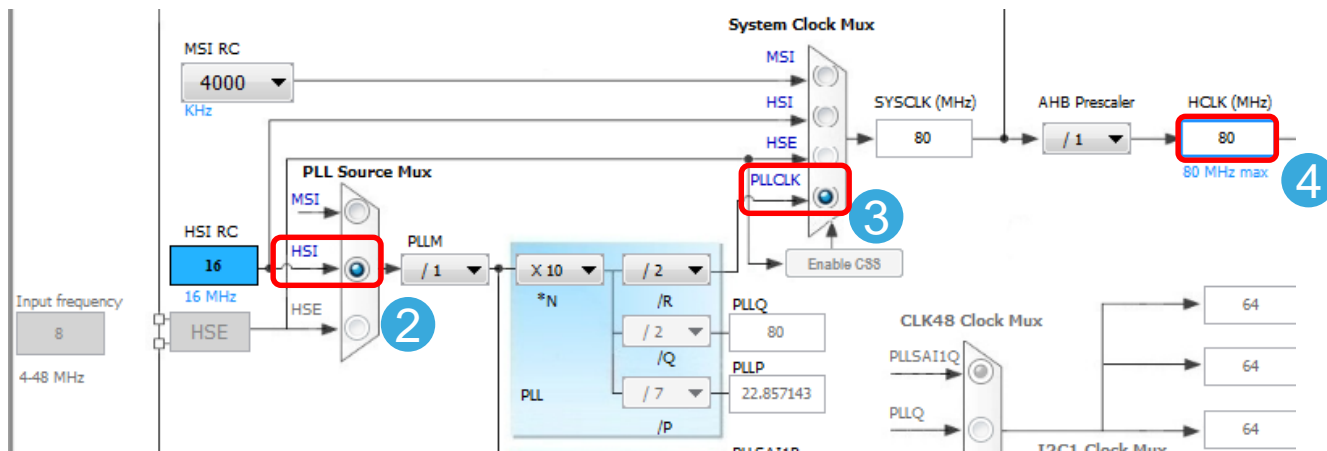
Configuration

Power Consumption Calculator

2. Select **HSI** in PLL Source Mux (HSI – High Speed Internal clock)

3. Select **PLLCLK** in the System Clock Mux

4. Set HCLK to **80** and press ENTER – application will propose PLL configuration to match this requirement



Peripheral Configuration

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- Select '**Configuration**' tab
- In this section peripherals with no physical pins or middleware can be added to the project
- For the 'L4_Blinky' example no additional configuration is required as LED is already configured in **GPIO** link as **Output Push-Pull**.



Pin Configuration

GPIO Single Mapped Signals

Search Signals
Search (Ctrl+F)

☐ Show only Modified

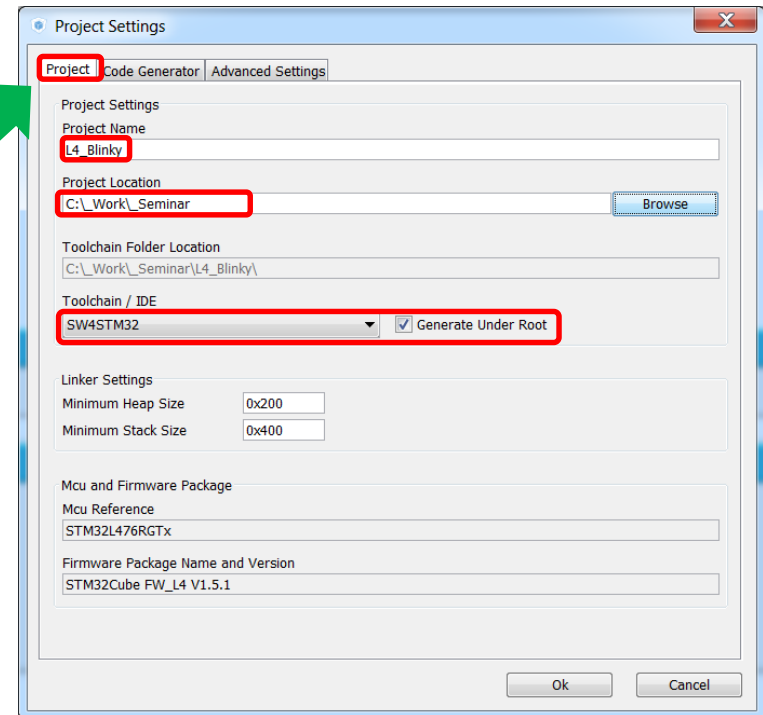
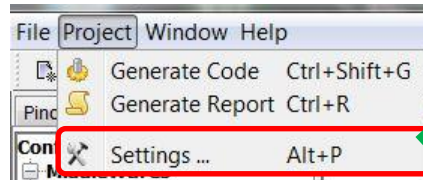
Pin N...	Sig...	GPIO output ...	GPIO mode	GPIO Pull-up/Pull-down	Maximum outpu...	Fast Mode	User Label	Modified
PA5	n/a	Low	Output Push Pull	No pull-up and no pull-down	Low	n/a	LD2 [green Led]	<input checked="" type="checkbox"/>
PC13	n/a	n/a	External Event Mode...	No pull-up and no pull-down	n/a	n/a	B1 [Blue PushButton]	<input checked="" type="checkbox"/>

Configure the code generator 1/2

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- Open project settings:
 - Menu → Project → Settings
- Under **Project** tab:
 - Give the project a name and location (i.e. **L4_Blinky**)
 - We strongly recommend to place this folder on the root of 'C:' as some C-compilers show issues when the build path contains too many characters
 - Select the toolchain to be SW4STM32
- For better understanding let's review code generation options (**Code Generation** tab) first



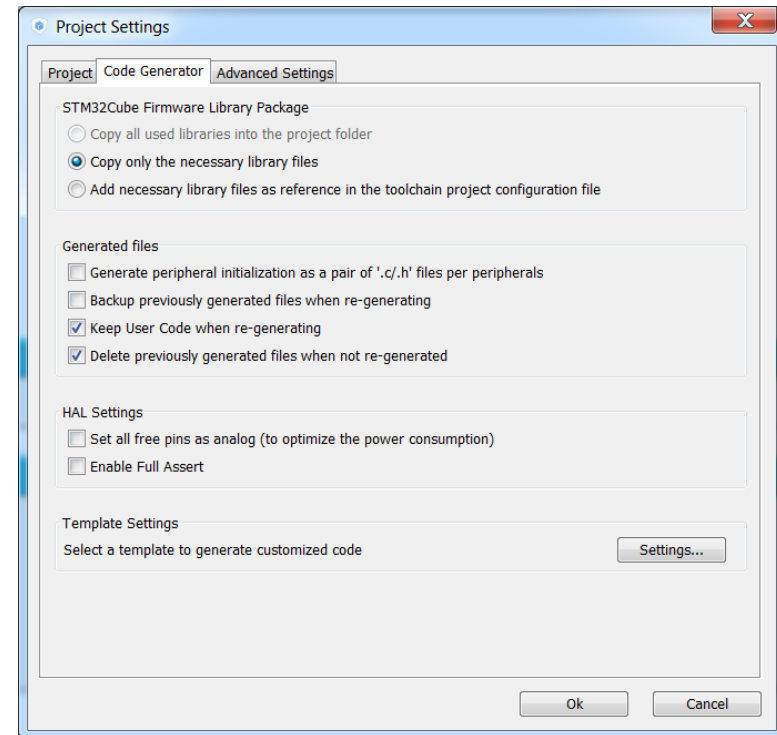
Configure the code generator 2/2

42




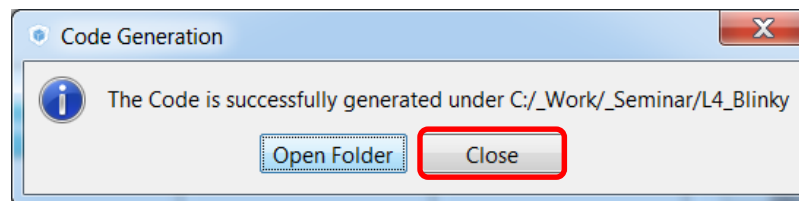
- Code generator options

- Copy either the full library or only the necessary files or just link the files from the common repository
- Place all peripherals initialization in the `stm321xx_hal_msp.c` file or one file per peripheral
- Keep user code or overwrite it (refers to code placed between user code comment sections)
- Delete or keep files that are not used anymore
- Set unused pins as analog to keep consumption low (**if SWD/JTAG is not selected in pinout, this option will disable it**)
- Enable full assert in project, this helps to discover incorrect HAL function parameter used in user code





- Once we have configured the code generator, we can generate code for selected toolchain.
- There are 3 ways to do it, namely:
 - Clicking  icon
 - Pressing **Ctrl+Shift+G** keys combination
 - Selecting **Project→Generate Code** option from menu
- When prompted, click 'Close' (we will import this project from SW4STM32 IDE).



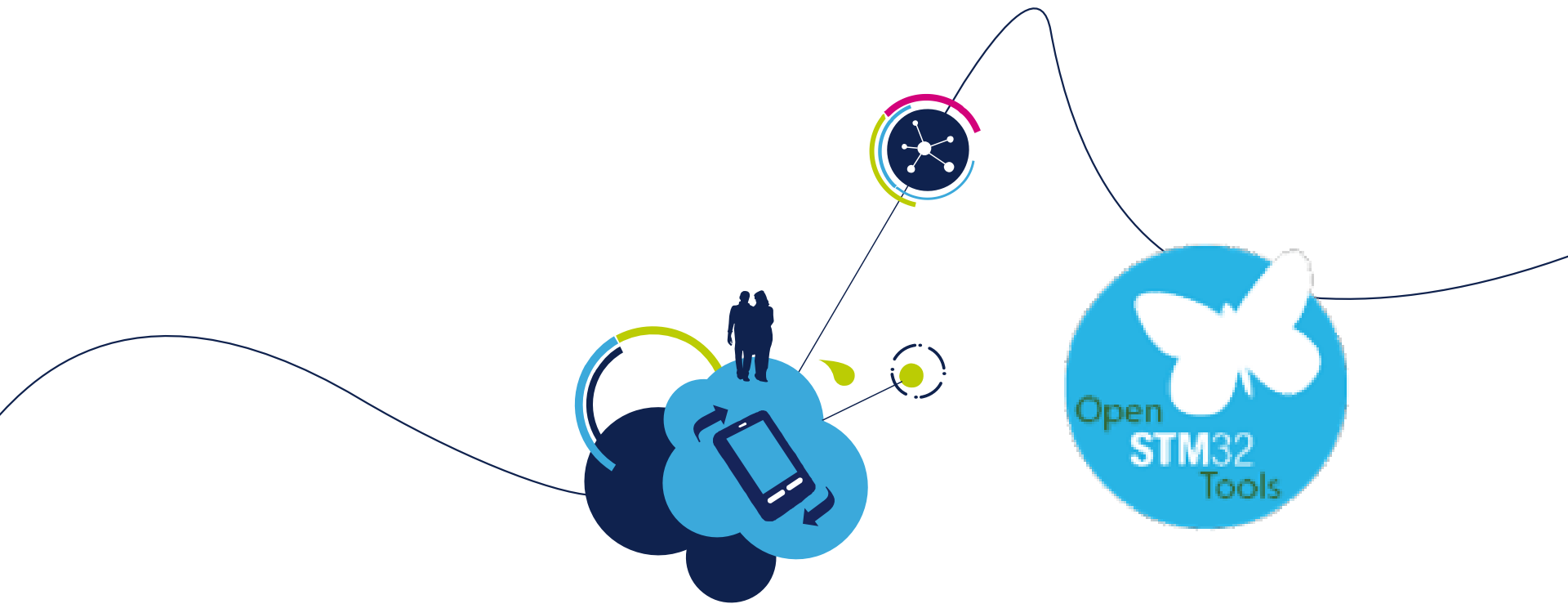


What have we gained during this part?

- ✓ Practice a little bit with STM32CubeMX by:
 - ✓ MCU selection
 - ✓ Play a bit with clock configuration for STM32L4 device
 - ✓ Create a skeleton of simple LED blinking application
- ✓ Have some fun!



- After successful code generation by STM32CubeMX this is the right time to import it into SW4STM32 toolchain for further processing



Handling the project in SW4STM32



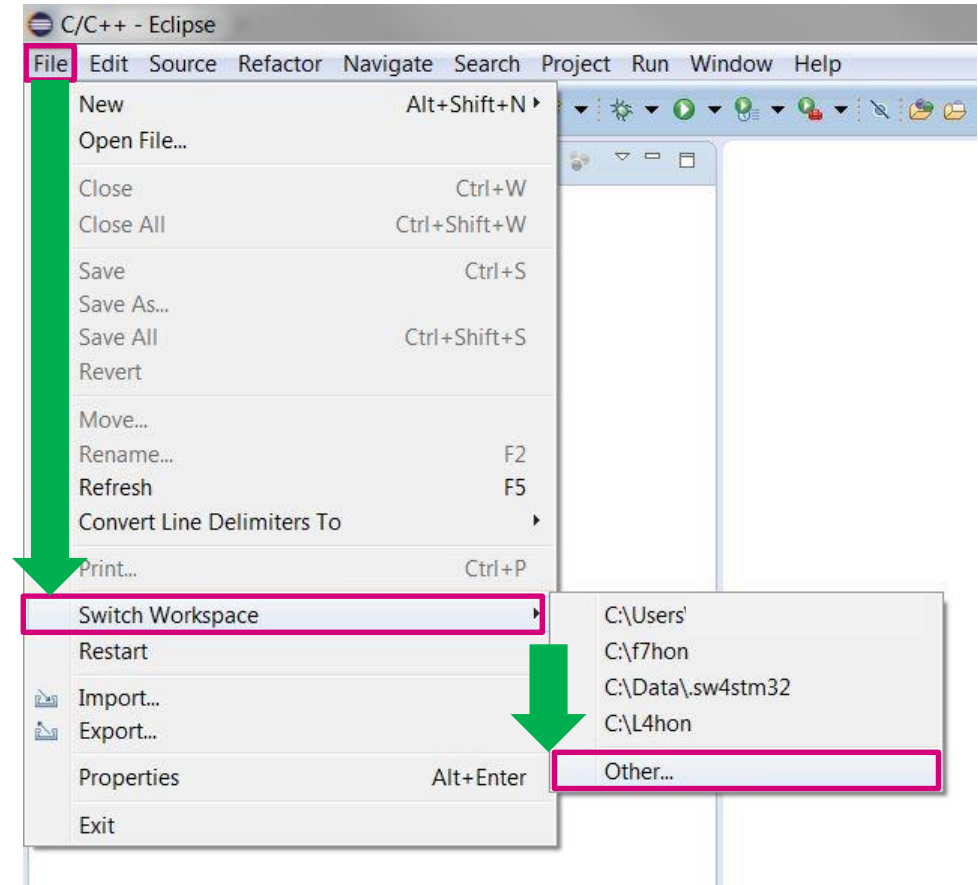
Our goals for this session

- ☐ Handling the projects generated by STM32CubeMX in SW4STM32
 - ☐ Import project generated by STM32CubeMX
 - ☐ Tune sources to run selected peripherals in desired algorithm
 - ☐ Build project
 - ☐ Configure debug session
 - ☐ Run debug session
 - ☐ Debug perspective
 - ☐ Watching the variables and registers content
 - ☐ Handling errors



- Start Workspace launcher if not done automatically by Eclipse.

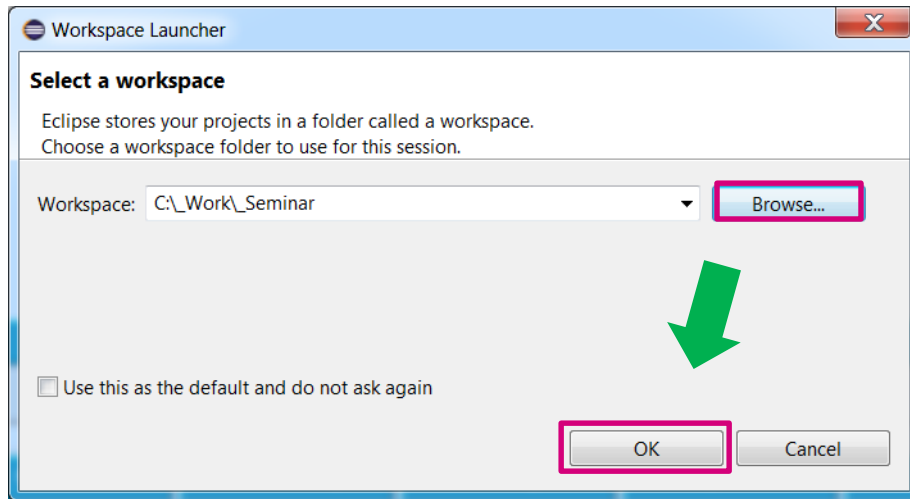
Create a new workspace SW4STM32



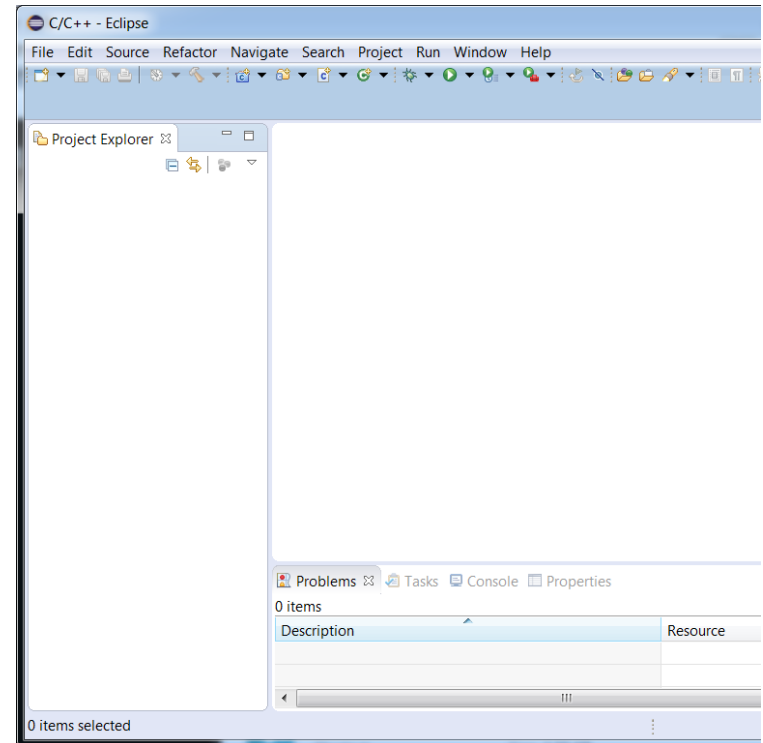


Create a new workspace SW4STM32

- Create new workspace in the desired location – but not in the same folder where the project which will be imported is located (it must be one level above the project)



- An empty workspace will be generated





Import the project into the workspace 1/3

SW4STM32

Import “L4_Blinky” project into empty workspace following below steps:

The image shows two screenshots from the Eclipse IDE. The left screenshot shows the 'File' menu with 'Import...' selected. A green arrow points from 'Import...' to the right screenshot. A pink callout bubble with the text 'IMPORT project into workspace' points to the 'Import...' option. The right screenshot shows the 'Import' dialog with 'Existing Projects into Workspace' selected. A green arrow points from this option to the 'Next >' button.

File Edit Source Refactor Navigate Search P
New Alt+Shift+N ▶
Open File...
Close Ctrl+W
Close All Ctrl+Shift+W
Save Ctrl+S
Save As...
Save All Ctrl+Shift+S
Revert
Move...
Rename... F2
Refresh
Convert Li
Print...
Switch Workspace ▶
Restart
Import...
Export...

Import
Select
Create new projects from an archive file or directory.
Select an import source:
type filter text
General
Archive File
Existing Projects into Workspace
File System
Preferences
C/C++
CVS
Git
Install
< Back Next > Finish Cancel

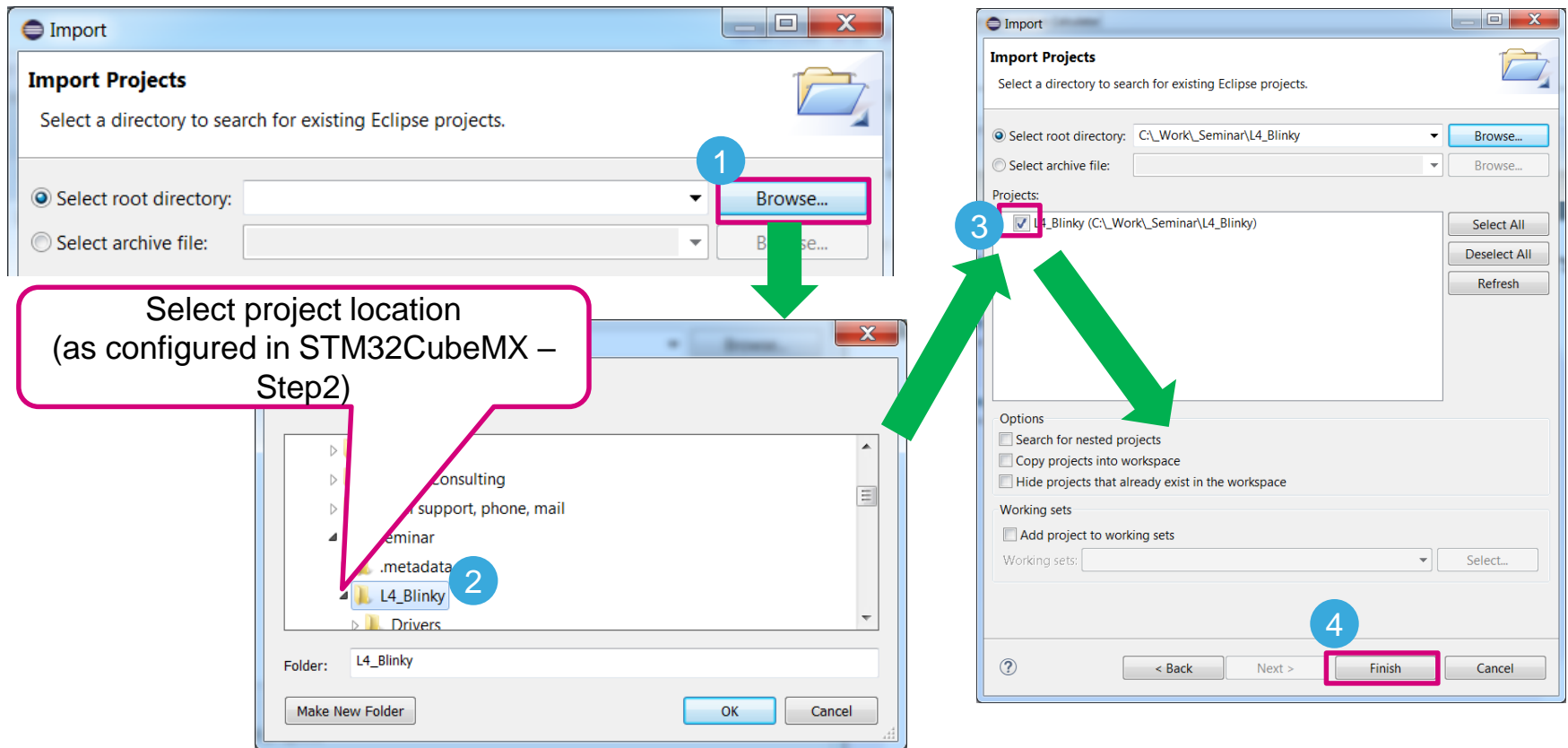
This is possible to import multiple projects into a single workspace



Import the project into the workspace 2/3

SW4STM32

In this example L4_Blinky project will be processed.





Import the project into the workspace 3/3

SW4STM32

Once project is included into the workspace, its folder structure becomes visible in Project Explorer

Places dedicated for user code are marked by
`/* USER CODE ... BEGIN*/`
 and
`/* USER CODE ... END*/`
 comment lines.

These places are protected from being removed during code re-generation by STM32CubeMX.
 This is **possible** to define another user code places in **.c** source files but **not possible** in **.h** header files.

Warnings and errors after build the project

The screenshot shows the Eclipse IDE with the project 'L4_Blinky' imported. The Project Explorer on the left shows the folder structure: L4_Blinky, Binaries, Includes, Drivers, Inc, Src, and Debug. The main editor shows the file 'main.c' with the following code:

```

33  /* Includes -----
34  #include "stm3214xx_hal.h"
35
36  /* USER CODE BEGIN Includes */
37
38  /* USER CODE END Includes */
39
40  /* Private variables -----
41
42  /* USER CODE BEGIN PV */
43  /* Private variables -----
44
45  /* USER CODE END PV */

```

The console at the bottom shows the build output for 'L4_Blinky':

```

CDT Build Console [L4_Blinky]
'Generating binary and Printing size information:'
arm-none-eabi-objcopy -O binary "L4_Blinky.elf" "L4_Blinky.b
arm-none-eabi-size "L4_Blinky.elf"
text    data    bss    dec    hex filename
4312    24    1568    5904    1710 L4_Blinky.elf
13:22:57 Build Finished (took 12s.239ms)

```



- STM32CubeMX generated project is only a skeleton which should be filled with some code from our side
- To make green LED (connected to properly configured PA5 pin) we should continuously invoke GPIO toggle function with the proper delay to make blink visible



Modifying the code

blinking green LED (PA5)

Tasks (within while(1) loop in main.c):

1. Add GPIO pin toggle function for PA5 pin. Which function we can use here?

?

2. Add 500ms delay between each change of the GPIO pin state. Which function we can use here?

?

Hints:

- All HAL function begins with **HAL_PPP_** prefix (PPP – short name of the peripheral, i.e. GPIO)
- Please try to use Content Assistant (**Ctrl+SPACE**) in Eclipse



Modifying the code

blinking green LED (PA5) - solution

Solutions (within while(1) loop in main.c):

1. Add GPIO pin toggle function for PA5 pin. Which function we can use here?

```
HAL_GPIO_TogglePin();
```

2. Add 500ms delay between each change of the GPIO pin state. Which function we can use here?

```
HAL_Delay();
```

```
/* Infinite loop */
/* USER CODE BEGIN WHILE */
while (1)
{
    /* USER CODE END WHILE */

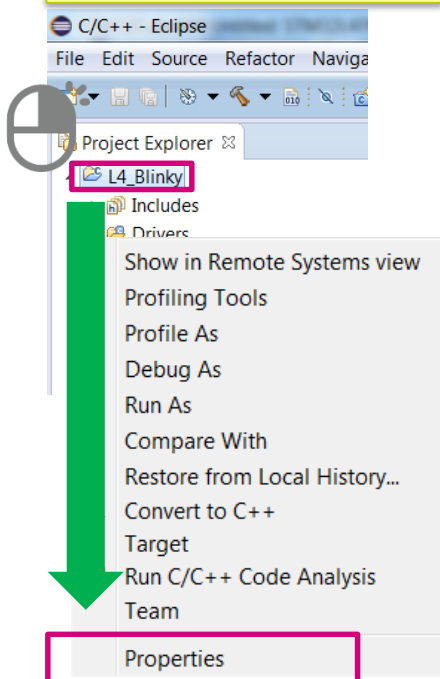
    /* USER CODE BEGIN 3 */
    HAL_GPIO_TogglePin(GPIOA, GPIO_PIN_5);
    HAL_Delay(500);
}
/* USER CODE END 3 */
```



Useful project settings in SW4STM32 configuring C dialect and parallel build

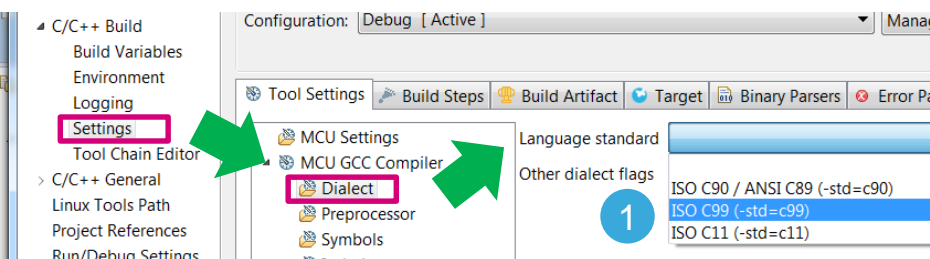
56

Project->Properties



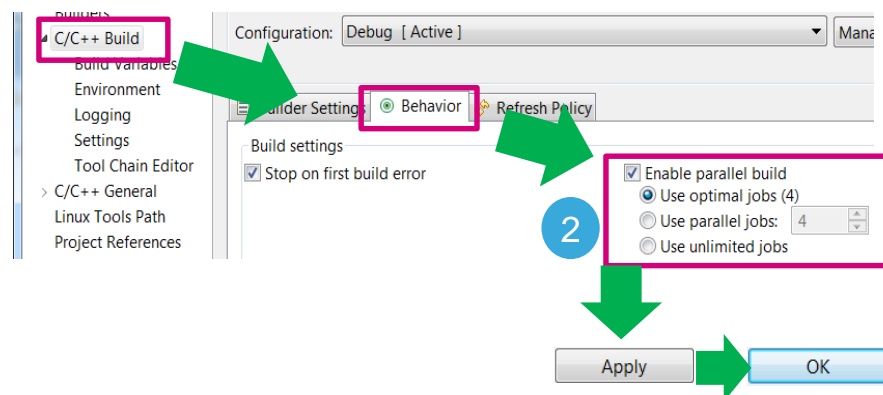
C/C++ Build->Settings->Tools Settings tab->MCU GCC Compiler->Dialect

1. Configure C standard to **C99** to avoid possible compilation errors




C/C++ Build->Behavior tab

2. Check **Enable parallel build** to make use of your machine potential and to shorten compilation time





Building the project in SW4STM32

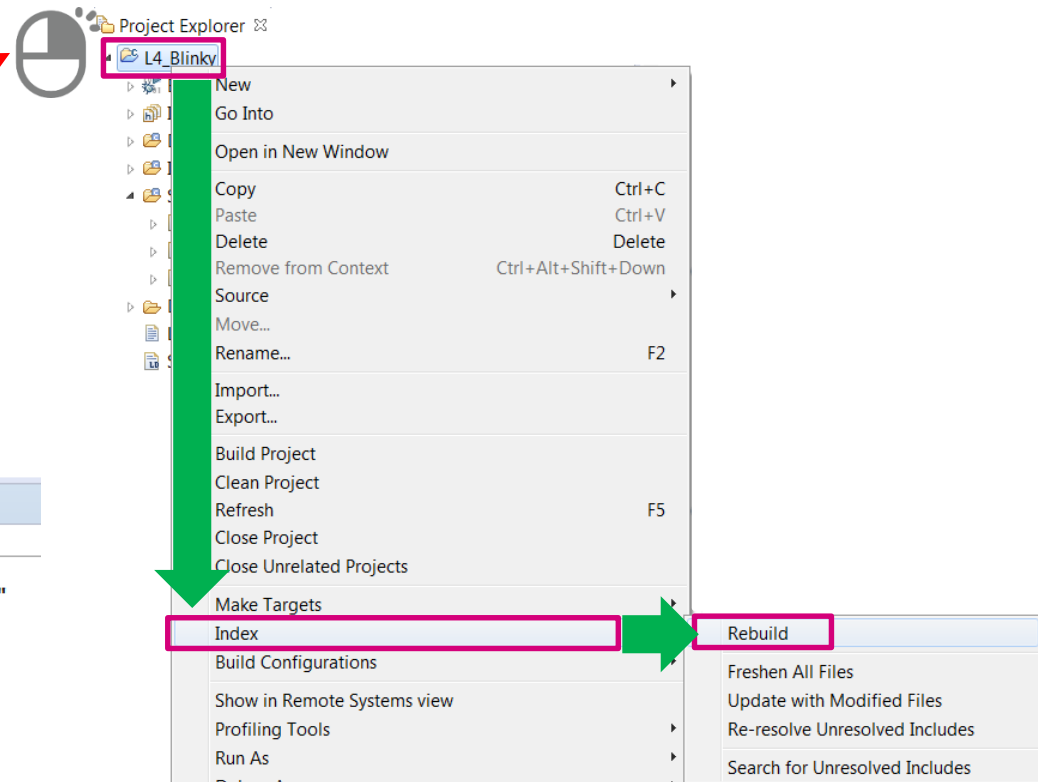
- To build the project press **Ctrl+B** or click Make All  icon
- In case of multiple compilation errors, re-run Indexing of the project
- After proper build there are information about code/data space usage in Console window displayed

Problems Tasks Console Properties

CDT Build Console [L4_Blinky]

```
'Generating binary and Printing size information:'
arm-none-eabi-objcopy -O binary "L4_Blinky.elf" "L4_Blinky.bin"
arm-none-eabi-size "L4_Blinky.elf"
  text    data    bss     dec     hex filename
  4256    24     1568    5848    16d8 L4_Blinky.elf
```

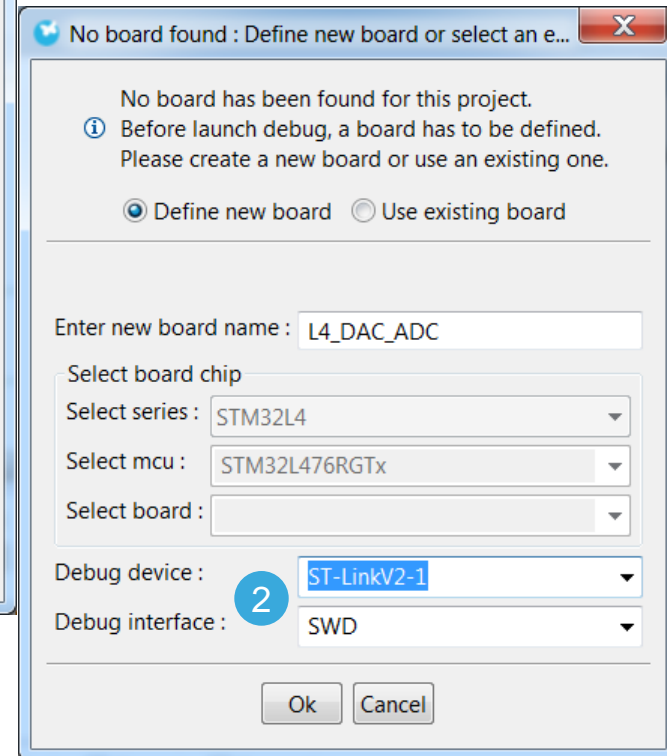
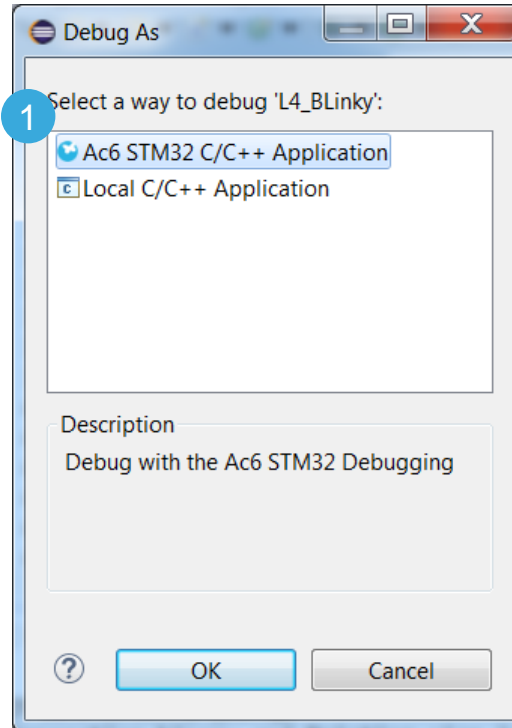
13:37:56 Build Finished (took 25s.41ms)





Configure the debug session in SW4STM32 for single project in the workspace

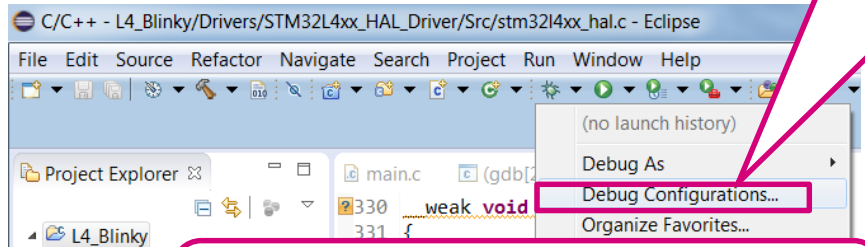
- Before running debug session this is necessary to configure it for current project
- In case there is a single project in the workspace this is enough to click the “bug” icon and:
 1. Select “Ac6 STM32 C/C++ Application” line and click ‘OK’
In case the project was generated on existing/defined board (like NUCLEO-L476RG in our example) debug will run automatically
 2. Otherwise (we will practice it in L4_DAC_ADC example later) it is necessary to configure debug device (STLinkV2-1 in our case) and debug interface (SWD in our case) and click ‘OK’
- Next step would be to run the debug session (see the next slide)





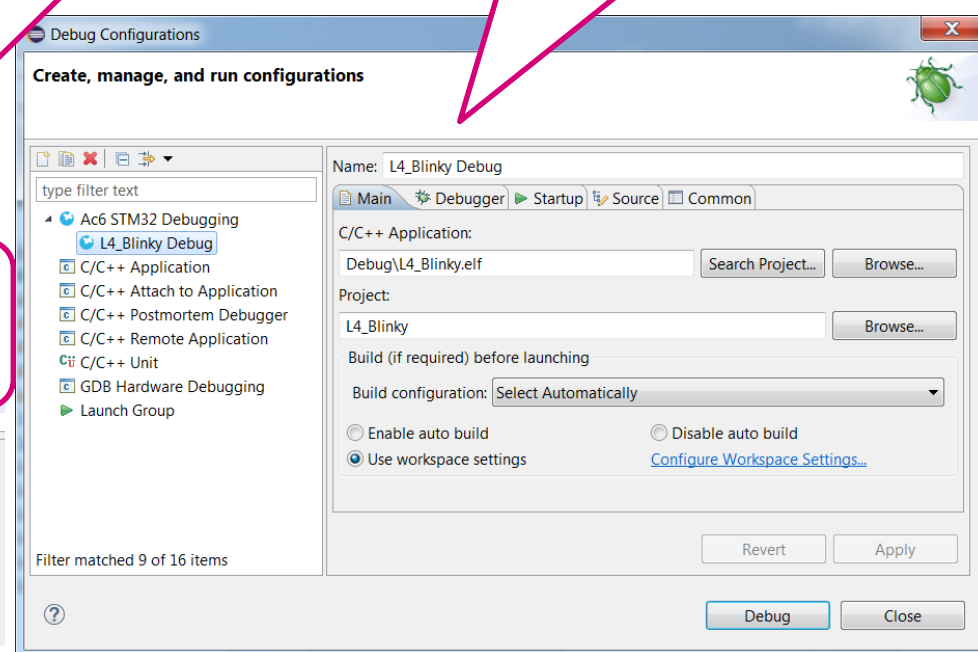
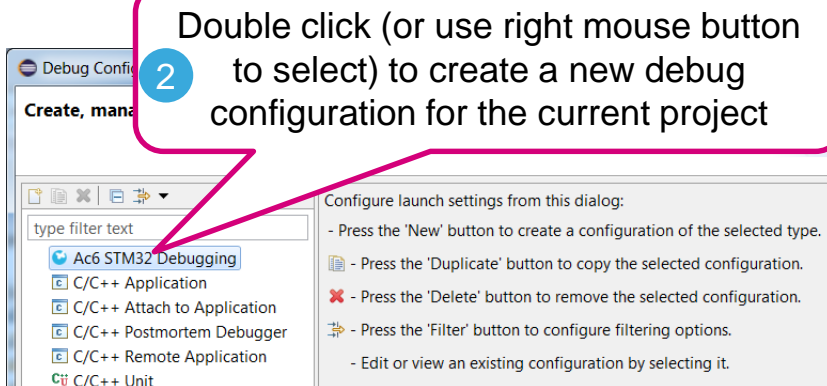
Configure the debug session in SW4STM32 for multiple projects in the workspace 1/2

Before debugging current project for the first time, this is necessary to configure its debug session



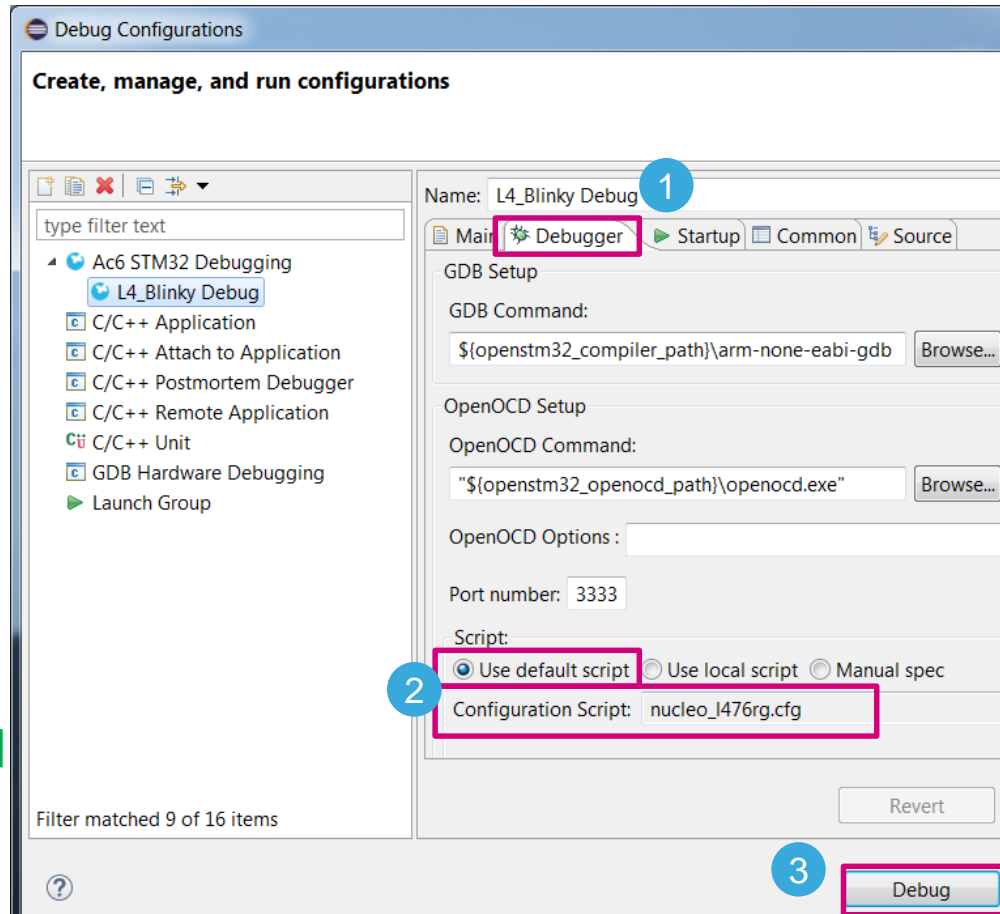
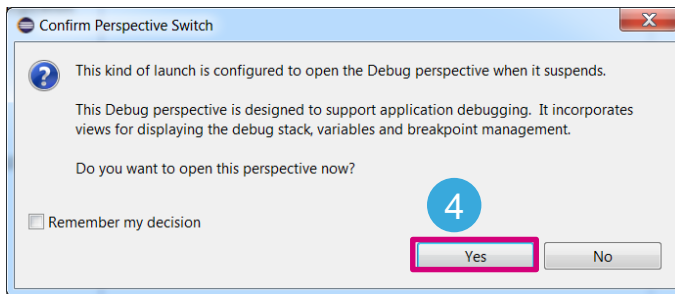
1 Select Debug Configuration option

3 All project parameters should be filled-in automatically



Run the debug session in SW4STM32 for multiple projects in the workspace 2/2

- Connect Nucleo board with miniUSB cable (ST-Link)
- In case of the projects generated for ST board, there should be selected board configuration script which specifies debug device and its interface (you can check it in Debugger tab)
- Debug perspective will be run (please select Yes in the information window)
- This is enough just to click a “bug” icon to enter debug session next time.

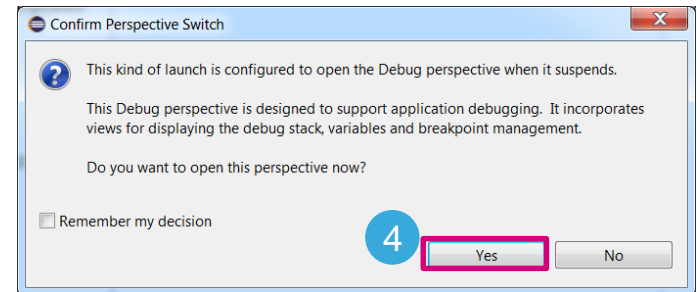
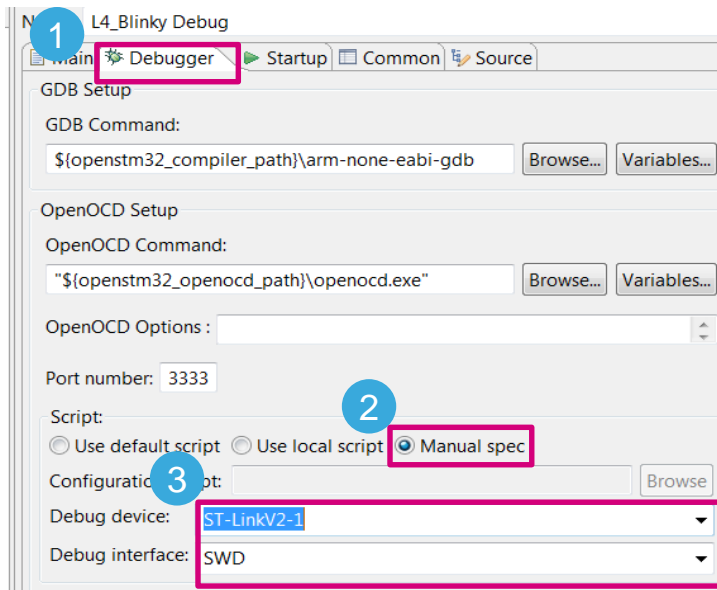




Run the debug session in SW4STM32

for multiple projects in the workspace, but no board specification

- Connect Nucleo board with miniUSB cable (ST-Link)
- Under **Debugger** tab select debug device (ST LinkV2-1 for Nucleo ones) and debug interface (SWD)
- Click **Apply** and then **Debug**
- Debug perspective will be run (please select Yes in the information window)
- This is enough just to click a “bug” icon to enter debug session next time.





Debug session perspective

watching the variables

- This is possible to monitor CPU registers, peripherals registers and variables during debug session, but we need to pause the code execution (no live view is possible for the time being).
- To add variable to be monitored - highlight it, press right mouse button and select “**Add Watch Expression**”. It will appear in Expressions tab then.
- Values which has changed from previous project pause will be presented on yellow background

Watched variables

Expression	Type	Value
uwTick	volatile uint32_t	3234
Add new expression		

Values changed from previous application pause



Debug session perspective

watching the registers content

- This is possible to monitor CPU registers, peripherals registers and variables during debug session, but we need to pause the code execution (no live view is possible for the time being).
- To add peripheral register to watch - click right mouse button and select “**Activate**”. Peripheral icon and its registers names will be highlighted in green and will contain “caught” values on next debug pause.
- Values which has changed from previous project pause will be **highlighted in red**.

Core registers

Peripherals registers

Non-watched peripheral

Watched peripheral

Value changed from previous application pause

Register	Hex value	Binary value
ADC2		
ADC3		
ADC123_Common		
GPIO		
GPIOA		
MODER	0xABFFF7AF	10_10_10_11_11_11_11_11_01_11...
OTYPER	0x00000000	0000000000000000_0_0_0_0_0_0...
OSPEEDR	0x0C0000F0	00_00_11_00_00_00_00_00_00_00...
PUPDR	0x64000000	01_10_01_00_00_00_00_00_00_00...
IDR	0x0000C028	0000000000000001_1_0_0_0_0_0_0...



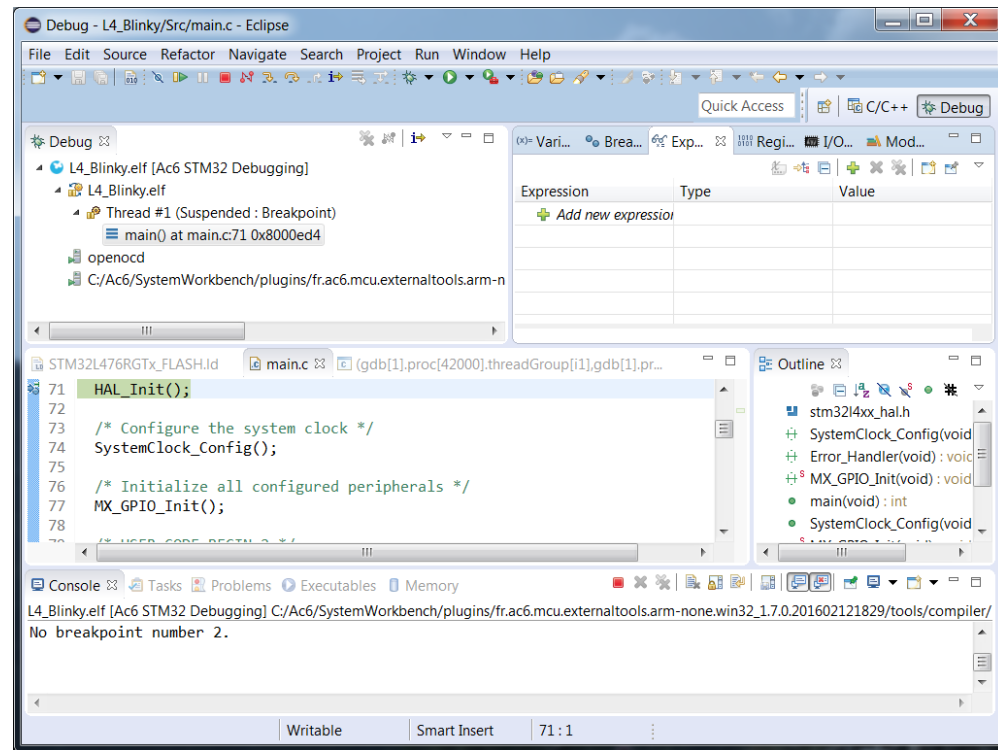
Handling the debug session

SW4STM32

1 2 3 4 5 6 7 8



1. Skip all breakpoints
2. Run/resume
3. Suspend
4. Terminate debug session
5. Disconnect from the target
6. Step into
7. Step Over
8. Step Return



windows configuration in debug perspective

What have we learnt?



- ✓ Handling the projects generated by STM32CubeMX in SW4STM32
 - ✓ Import project generated by STM32CubeMX
 - ✓ Tune sources to run selected peripherals in desired algorithm
 - ✓ Build project
 - ✓ Configure debug session
 - ✓ Run debug session
 - ✓ Debug perspective
 - ✓ Watching the variables and registers content
 - ✓ Handling errors

Benefits of using Arduino

- Rapid development of application

API is very easy to use:

- it contains mainly basic C forms (functions)
- one or few lines of code is/are enough to make peripherals work
- common API for all supported MCUs (easy porting/migrating)

API covers not only MCU's resources, but also external components (sensors, wireless communication, ...)

- Multiple MCUs platforms

Supports ARM and non-ARM MCU platforms from different vendors

- Supports many operating systems

Version for Windows, Linux and MacOS



- Free of charge

IDE is free of charge and doesn't have any time or code size limitations

- Open source

Libraries for MCUs and companion devices are developed by community



Benefits of using STM32 cube

- Rapid development of application

API is very

- it

- or

- co

API cover

wireless co

Default working (fast) config
Allocate time necessary to fine
tune device.
LL api and HAL api

ipherals work

migrating)

ponents (sensors,

- Multiple MCUs platforms

Supports

STM8 & STM32

ndors

- Supports many operating systems

Version fo

OSX , Linux & Windows



- Free of charge

IDE is fre

0000000.00\$

limitations

- Open source



Libraries

Loads of githubs, open source project avail. STM32

community

Drawbacks of using Arduino

- Limited selection of MCUs within family

Only part of MCUs from selected family are supported by Arduino

- Limited control of MCU

Detailed configuration of MCU is not possible like system clock configuration, low-power modes and more

- Limited debugging possibilities

There is no real debugger, which allows to run the code step by step, analyze MCU's registers, place breakpoints and more. Main debugging tool is serial monitor

- Limited number of pins for InterConnect

Arduino standard connect allows a few IO pins (PWM, UART, I2C, SPI...)
Which had been extended with the MEGA



Benefits

Summary

Drawbacks of using Arduino

69

STM32 cube

- Limited selection of MCUs within family

Only part of

Full list of STM32 family members available

Arduino

- Limited control of MCU

Detailed configuration,
power mode

Fine & details configuration possible

by step, analyze

- Limited debugging possibilities

There is no
MCU's register
monitor

All debugging facilities (BRK, STEP, WATCH....)

g tool is serial



- Limited number of pins for InterConnect

Arduino standard connect allows a few IO pins (PWM, UART, I2C, SPI...)
Which had

All STM32's pin from package configurable

- STM32L4 Discovery kit IoT node
 - <http://www.st.com/en/evaluation-tools/b-l475e-iot01a.html>
- STM32duino
 - <https://github.com/stm32duino/wiki/wiki/Boards-Manager>
- ST Community thread about Arduino
 - <https://community.st.com/community/stm32-community/blog/2017/07/13/stm32-cores-enabled-in-arduino-ide>
- STM32 libraries for Arduino
 - <http://www.arduinolibraries.info/architectures/stm32>

More information can be found in the following document:

- **UM1718** - STM32CubeMX for STM32 configuration, available on the web:
http://www.st.com/resource/en/user_manual/dm00104712.pdf

Thank you