

# Hyung-gun Chi

PHD STUDENT · SOFTWARE ENGINEER

610 Purdue Mall, West Lafayette, IN, 47907

☎ (415)203-8543 | ✉ chi45@purdue.edu | 🌐 hyung-gun.me | 📧 stnoah1 | 📷 hyung-gun | 🎓 Hyung-gun Chi

## Research Interests

My research interests lie at the intersection of Computer Vision and Robotics, focusing on 3D Geometric Deep Learning for recognizing and synthesizing 3D objects. In this area, I applied Machine Learning (Deep Learning) algorithms for Augmented / Virtual Reality and Smart Factory.

## Education

### Purdue University

PHD IN ELECTRICAL AND COMPUTER ENGINEERING

- Advisor: Professor Karthik Ramani

West Lafayette, IN, USA

Aug. 2018 - PRESENT

### Yonsei University

BS IN MECHANICAL ENGINEERING

- Advisor: Professor Soo-Hong Lee
- 2011-2013, 2-year military service

Seoul, South Korea

Mar. 2010 - Feb. 2017

## Skills

**Programming** Python, Matlab, C/C++, SQL, JavaScript, HTML, CSS, PHP

**Frameworks** TensorFlow, PyTorch, Keras, ROS, OpenCV

**Software** Creo Parametric, SolidWorks, HyperWorks, GAZEBO

## Publications and Patents

### Journal Papers

- [J4][PDF] S. Kim, **H. G. Chi** and Karthik Ramani. Object synthesis by learning part geometry with surface and volumetric representations. In *Computer-Aided Design*, under review.
- [J3][PDF] S. Kim, N. Winovich, **H. G. Chi**, G. Lin, and K. Ramani. Latent transformations neural network for object view synthesis. In *The Visual Computer*, pp. 1-15, 2019
- [J2][PDF] H. T. Hwang, **H. G. Chi**, N. K. Kang, H. B. Kong and Soo-Hong Lee. An Evaluation Methodology for 3D Deep Neural Network using Visualization in 3D Data Classification. In *Journal of Mechanical Science and Technology (JMST)*, 33(3), pp. 1333-1339, 2019
- [J1][PDF] JIN YONGZHU, **H. G. Chi** and Soo-Hong Lee. A Study on the Optimal Design of Pedestrian Robots Using Jansen Mechanism. In *CDE review*, 22(2), pp. 18-22, 2016

### Conference Proceedings

- [C4][PDF] S. Kim, **H. G. Chi**, and Karthik Ramani. . In *The British Machine Vision Conference*, submitted.
- [C3][PDF] **H. G. Chi\***, S. Kim\*, X. Hu, Q. Huang, and Karthik Ramani. A Large-scale Mechanical Components Benchmark for Deep Neural Networks. In *European Conference on Computer Vision*, submitted.
- [C2][PDF] H. Hwang, **H. G. Chi**, S. H. Lee. A Research about 3D Design Data Classification with 3D Convolutional Neural Network. In *Proceedings of the Society for Computational Design and Engineering Conference*, pp. 441-442, 2017
- [C1][PDF] M. H. Woo, S. H. Kim, **H. G. Chi**, M. W. Park, J. K. Kim and S. H. Lee. Development of Web-based, Module Structure Platform for Surgical Workflow Management. In *Proceedings of the Society for Computational Design and Engineering Conference*, pp. 439-441, 2016

### Patents

- [P1][PDF] **H. G. Chi**. "Computer Input Automation System" KR Patent (2017): 10-1745330.

## Research Experience

### A Large-scale Mechanical Component Benchmark Dataset [C3]

C-Design LAB, Purdue Univ.

RESEARCH ASSISTANT

Feb. 2019 - Present

- Introduced large-scale mechanical components a benchmark for the classification and retrieval tasks named Mechanical Components Benchmark.
- Developed a data collecting pipeline including annotation interface and database.
- Benchmarked state-of-the-art 3D Deep Neural Networks for classification and retrieval tasks to explore the descriptor for mechanical components.

### Hand segmentation with RGBD-T data [C4]

C-Design LAB, Purdue Univ.

GRADUATE RESEARCH ASSISTANT

Jul. 2019 - Present

- Proposed a novel hand dataset by fusing RGB-D and thermal data for hand segmentation.
- Developed a method which segment hands and objects with a multi-modal Deep Neural network dealing with RGBD-T data.

### Part Geometry Net (PGNet) [J4]

C-Design LAB, Purdue Univ.

GRADUATE RESEARCH ASSISTANT

Oct. 2018 - Aug. 2019

- Built a Generative Adversarial Network which generates 3D objects given a discrete category condition and continuous instance-level attributes by fusing the various types of geometric information.
- Introduced a part identifier module which learns part geometry to preserve part properties of 3D objects.

### Latent Transformation Neural Network (LTNN) [J3]

C-Design LAB, Purdue Univ.

GRADUATE RESEARCH ASSISTANT

Aug. 2018 - April. 2019

- Developed a fully-convolutional conditional generative network which is capable of view synthesis using a light-weight neural network suited for real-time applications.
- Introduced the conditional transformation unit which is designed to learn the latent space transformations corresponding to specified target views.

### Visual Programming Language for Mobile Robots and IoT Nodes

C-Design LAB, Purdue Univ.

GRADUATE RESEARCH ASSISTANT

Aug. 2018 - Feb. 2019

- Proposed a web-based visual and spatial programming language that allows novice users and small industries to program mobile robots and IoT Nodes to execute planned tasks.
- Developed a virtual world using the Robotic Operating System (ROS) and GAZEBO which simulates the interaction between mobile robots and IoT devices.

### SleekPatch

C-Design LAB, Purdue Univ.

GRADUATE RESEARCH ASSISTANT

Aug. 2018 - Dec. 2018

- Proposed a parametrizing interface, accessible and straightforward fabrication workflow, and a pressure sensor using a soft piezoresistive elastomer material.
- Developed embedded system using Arduino and analyze signals from different sensors and materials.

### 3D Deep Neural Network evaluation method [J2][C2]

Knowledge-Based Design LAB, Yonsei Univ.

UNDERGRADUATE RESEARCH ASSISTANT

Feb. 2016 - Jul. 2017

- Proposed an evaluation method for 3D Deep Neural Networks by visualizing the impact of each voxel of each 3D object.
- Developed a web-based 3D CAD search engine using a 3D Deep Neural Network for demonstration.

### Web-based Surgical Workflow Management Platform [C1]

Knowledge-Based Design LAB, Yonsei Univ.

UNDERGRADUATE RESEARCH ASSISTANT

Feb. 2016 - Aug. 2016

- Developed a web-based interface and database for integrated surgical information, to optimize surgical procedures and reduce the medical loss caused by communication errors and lack of information.

## Working Experience

---

### Software Engineer and CEO

Seoul, South Korea

NEIL LAB CORPORATION

Sep. 2016 - Dec. 2017

- Developed an office automation system using Python specifically for automating tasks such as sending an e-mail or issuing receipts, and designed a back-end system and database for customer web-service which automatically scrap and integrate customer's financial and personal data. (Relevant patent: [PI])
- Founded and led a startup company as a CEO for a year and also worked as a Python developer. The company was funded \$ 30,000 by the SeongNam Industry Promotion Agency.

### Mechanic and Squad leader

Inje, South Korea

REPUBLIC OF KOREA ARMY

Apr. 2011 - Jan. 2013

- Maintained military weapons and equipment including firearms and vehicles.
- Led a squad as a squad leader; honored as a distinguished soldier.

## Professional Services

---

Conference    Reviewer: BMVC20