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Education

Yonsei University

Purdue University West Lafayette, IN, USA

MASTER OF SCIENCE IN MECHANICAL ENGINEERING

Aug. 2018 - PRESENT Seoul, South Korea

Aug. 2018 - Present

BACHELOR OF SCIENCE IN MECHANICAL ENGINEERING Mar. 2010 - Feb. 2017

Skills

Programming Python, C/C++, Matlab, SQL, JavaScript, HTML, CSS, PHP

Frameworks TensorFlow, Keras, PyTorch, ROS, OpenCV

Software Creo Parametric, SolidWorks, AutoCAD, HyperWorks, GAZEBO

Work Experience _

Graduate Assistant West Lafayette, IN, USA

C-DESIGN LAB, PURDUE UNIVERSITY

· Participated in many projects which developing 3D Deep Neural Networks and processing the 3D data

CEO and Python Developer Seoul, South Korea

NEIL LAB CORPORATION Sep. 2016 - Dec. 2017

• Developed an office automation system using Python specifically for automating tasks such as sending an e-mail or issuing receipts, and designed a back-end system and database for customer web-service which automatically scrap and integrate customer's financial and personal data.

Featured Projects

Hand motion prediction with RGBD-T data

· Proposed a novel dataset by fusing RGB-D and thermal data for action recognition. Developed a method which predicts hand motion by segmenting hands and objects with a 3D Deep Neural network dealing with RGBD-T data.

Mechanical Net

 Collected massive 3D mechanical component CAD data with a web-scrapper and expanded the data for dense data distribution using Creo Parametric and SolidWorks API. Also, developed a web-based 3D CAD search engine using a 3D Deep Neural Network and PostgreSQL database.

• Developed a Generative Adversarial Network which generates 3D objects given a discrete category condition and continuous instance-level attributes. Developed a 3D data pre-processing program which converts 3D data to various types of geometric tensors.

Latent Transformation Neural Network (LTNN)

Developed a fully-convolutional conditional generative network which is capable of view synthesis using a light-weight neural network suited for real-time applications. (Relevant publication: [J3])

Visual Programming Language for Mobile Robots and IoT

· Proposed a web-based visual and spatial programming language that allows novice users and small industries to program mobile robots and IoT Nodes to execute planned tasks. Developed a virtual world using ROS with Python and GAZEBO for simulating the spatial programming language.

3D Objects Classification Model Evaluation

· Proposed an evaluation method for 3D Deep Neural Networks by visualizing the impact of each voxel of each 3D objects. Developed a web-based CAD data retrieval engine for demonstration. (Relevant publication: [J2])

Publications

Journal Papers

- [J4][PDF] S. Kim, H. G. Chi and Karthik Ramani. "Object synthesis by learning part geometry with surface and volumetric representations" (2019) Computer-Aided Design, submitted.
- [J3][PDF] S. Kim, N. Winovich, H. G. Chi, G. Lin, and K. Ramani (2019). Latent transformations neural network for object view synthesis. The Visual Computer, 1-15.
- [J2][PDF] H. T. Hwang, H. G. Chi, N. K. Kang, H. B. Kong and Soo-Hong Lee. "An Evaluation Methodology for 3D Deep Neural Network using Visualization in 3D Data Classification" (2019) Journal of Mechanical Science and Technology (JMST), 33(3), pp. 1333-1339.
- [J1][PDF] JIN YONGZHU, H. G. Chi and Soo-Hong Lee. "A Study on the Optimal Design of Pedestrian Robots Using Jansen Mechanism". (2016) Korean Journal of Computational Design and Engineering, 22(2), pp. 18-22.

Conference Papers

- [C2][PDF] H. Hwang, H. G. Chi, S. H. Lee. "A Research about 3D Design Data Classification with 3D Convolutional Neural Network" (2017) Proceedings of the Society for Computational Design and Engineering Conference, pp. 441-442.
- [C1][PDF] M. H. Woo, S. H. Kim, H. G. Chi, M. W. Park, J. K. Kim and S. H. Lee. "Development of Web-based, Module Structure Platform for Surgical Workflow Management". (2016) Proceedings of the Society for Computational Design and Engineering Conference, pp. 439-441.

Patents

• [P1][PDF] H. G. Chi. "Computer Input Automation System" KR Patent (2017): 10-1745330.