

💌 stnoah1@gmail.com | 🗥 hyung-gun.me | 😱 stnoah1 | 🛅 hyung-gun | 🎓 Hyung-gun Chi

Research Interests

AI/ML researcher specializing in vision-language models, multimodal learning, and large-scale AI systems. Extensive experience in foundation models, representation learning, and generative AI applied to computer vision and robotics. Proven track record in top-tier AI research (CVPR, ECCV, ICRA), with multiple patents in multimodal AI, human motion forecasting, and trajectory prediction. Passionate about pushing boundaries in AI and translating research into scalable real-world applications.

Education

Purdue University West Lafayette, IN, USA

PHD IN ELECTRICAL AND COMPUTER ENGINEERING

Aug. 2018 - Dec. 2023

• Thesis: Towards Improved Representations on Human Activity Understanding

Advisor: Dr. Karthik Ramani

Purdue University West Lafayette, IN, USA

MS IN ELECTRICAL AND COMPUTER ENGINEERING

Aug. 2018 - Dec. 2022

Yonsei University

Seoul, South Korea

BS IN MECHANICAL ENGINEERING

Mar. 2010 - Feb. 2017

Professional Experience

Apple Inc. Cupertino, CA, USA

AIML RESIDENT Jul 2024 -

· Conducted knowledge distillation research on speech foundation models to enhance Siri's performance and efficiency.

Hanwha Vision America Santa Clara, CA, USA

AI RESEARCHER

CV RESEARCH INTERN

Jan - June 2024

• Researched human pose estimation and activity recognition to enhance surveillance AI.

• Developed and deployed AI models, significantly increasing detection accuracy while reducing false positives.

Toyota Research Institute Los Altos, CA, USA

ML RESEARCH INTERN May - Aug 2023

· Led a project on multi-modal representation learning for robotics, integrating vision, language, and tactile sensors.

• Published a large-scale vision-language-tactile dataset, facilitating enhanced robotic perception.

Honda Research Institute San Jose, CA, USA

• Developed a VQ-Diffusion model for text-to-human-motion generation, setting a new benchmark in the field.

- · Created LLM-based human motion prediction models, deployed in autonomous vehicle safety systems.
- · Proposed a NeuralODE based Transformer model for trajectory prediction, significantly improving action forecasting accuracy.

Convergence Design Lab, Purdue University

West Lafayette, IN, USA

Jan - May 2023 & May - Aug 2022

GRADUATE RESEARCH ASSISTANT Aug 2018 - Dec 2023

- Pioneered vision-language representation learning for 3D human action recognition.
- Developed a self-attention-based skeleton recognition model integrating graph convolutional networks.
- · Published extensively in CVPR, ECCV, ICRA, with multiple patents in motion prediction and multimodal AI.

HeumLabs Corporation Seoul, South Korea

SOFTWARE ENGINEER & CEO Sep 2016 - Dec 2017

- Founded and led a startup developing an office automation system, securing initial funding and overseeing the product development lifecycle.
- Achieved a successful market entry, with the system adopted by over 150 businesses within the first year.

Skills

Research and Development Stacks

Other Tools and Skills

Major Languages Python, C/C++ **Text Editors** Neovim & Vim

Machine Learning PyTorch, TensorFlow **Computer Vision** OpenCV, OpenGL

Other Langauges Shell Scripts(bszh, zsh), MATLAB, R

> VCS Git

Publications and Patents

Conference Proceedings

- [C17] Chi et al, "DiceHuBERT: Distilling HuBERT with a Self-Supervised Learning Objective", Interspeech, 2025, submitted.
- [C16] Chi et al, "Adaptive Knowledge Distillation for Device-Directed Speech Detection", Interspeech, 2025, submitted.
- [C15] Kim et al, "Context-Enriched Voxel Queries for Camera-based 3D Occupancy Prediction", CVPR, 2025.
- [C14] Shi et al, "CARING-AI: Context-aware Augmented Reality Instruction through Generative Artificial Intelligence", CHI, 2025.
- [C13] Seo et al, "Egocentric View Hand Action Recognition by Leveraging Hand Surface and Hand Grasp Type", ICPRAI, 2024.
- [C12] Chi et al, "M2D2M: Discrete Diffusion Model for the Multi-Motion Generation from the Text", ECCV, 2024.
- [C11] Kim et al, "Enhanced Motion Forecasting with Visual Relation Reasoning", ECCV, 2024.
- [C10] Moon et al, "Vision-Trap: Vision-Augmented Trajectory Prediction Guided by Textual Descriptions", ECCV, 2024.
- [C9] Chi et al, "Multi-Modal Representation Learning with Tactile Modality", IROS, 2024.
- [C8] Kim et al, "Higher-order Relation Reasoning for Trajectory Prediction", CVPR, 2024.
- [C7] Roh et al, "Functional Hand Type Prior for 3D Hand Pose Estimation & Action Recognition from Egocentric View Monocular Videos, BMVC (Oral), 2023
- [C6] Chi et al, "AdamsFormer for Spatial Action Localization in the Future", CVPR, 2023.
- [C5] Xu et al, "Uncovering the Missing Pattern: Unified Framework Towards Trajectory Imputation and Prediction", CVPR, 2023.
- [C4] Chi et al, "Pose Relation Transformer: Refine Occlusions for Human Pose Estimation", ICRA, 2023.
- [C3] Chi et al, "InfoGCN: Representation Learning for Human Skeleton-based Action Recognition", CVPR, 2022.
- [C2] Chi et al, "A Large-scale Annotated Mechanical Components Benchmark for Classification and Retrieval Tasks with Deep Neural Networks", ECCV, 2020.
- [C1] Kim et al, "First-Person View Hand Segmentation of Multi-Modal Hand Activity Video Dataset", BMVC, 2020.

Journal Papers

- [J9] Kim et al, "Enhanced fringe-to-phase framework using deep learning", Image and Vision Computing, 2024.
- [J8] Chi et al, "InfoGCN++: Learning Representation by Predicting the Future for Online Skeleton-based Action Recognition", TPAMI 2024.
- [J7] Lee et al, "Deep Learning-Assisted Design of Bilayer Nanowire Gratings for High-Performance MWIR Polarizers, **Advanced Materials Technologies**, 2024.
- [J6] Lee et al, "Robust Sound-Guided Image Manipulation", Neural Networks, 2024.
- [J5] Unmesh et al, "Interacting Objects: A dataset of object-object interactions for richer dynamic scene representations", RA-L, 2024.
- [J4] Kim et al, "3D CAD Model Simplification for Mechanical Parts Using Generative Adversarial Networks", Computer-Aided Design, 2023.
- [J3] Kim et al, "Object synthesis by learning part geometry with surface and volumetric representations", Computer-Aided Design, 2021.
- [J2] Kim et al, "Latent transformations neural network for object view synthesis", The Visual Computer, 2019.
- [J1] Hwang et al, "An Evaluation Methodology for 4D Deep Neural Network using Visualization in 3D Data Classification", JMST, 2019.

Patents

- [P7] "Multi-Motion Generation", US Patent App.
- [P6] "System and Method for Authoring Context-augmented Reality Instruction through Generative Artificial Intelligence", US Patent App.
- [P5] "Pose Relation Transformer Refine Occlusions for Human Pose Estimation", US Patent App. 18/584,191.
- [P4] "Spatio Action Localization in the Future", US Patent App. 18/300,844.
- [P3] "Trajectory Imputation and Prediction", US Patent App. 18/182,195.
- [P2] "Pixel-wise Hand Segmentation of Multi-modal Hand Activity Video Dataset", US Patent 11,562,489.
- [P1] "Computer Input System for Office/Factory Automation", WO Patent 2018/074729 A1.

Academic Services

Reviewer

- Conferences: CVPR(2023-2025), ECCV(2024), ICCV(2023, 2025), ICML(2024-2025), ICLR(2024-2025), NeurIPS(2023), AAAI(2025), BMVC(2021-2023), ACCV(2024), ICRA(2025), ICRA(2025), ICRA(2025), ICASSP(2025).
- Journals: TPAMI, PR, TIP, IJCV, TNNLS, JVCI, CVIU, TOMM, R-AL, TETCI, JCISE.

Awards and Honors.

2024	Doctoral Consortium , IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)	Seattle, WA, USA
2023	Conference Travel Funds, Purdue Engineering Graduate Program	West Lafayette, IN, USA
2023	Travel Grants, Purdue Graduate Student Government	West Lafayette, IN, USA

References_

Available upon request.