

# Hyung-gun Chi

MASTERS STUDENT

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## Education

### Purdue University

MASTER OF SCIENCE IN MECHANICAL ENGINEERING

West Lafayette, IN, USA

Aug. 2018 - PRESENT

### Yonsei University

BACHELOR OF SCIENCE IN MECHANICAL ENGINEERING

Seoul, South Korea

Mar. 2010 - Feb. 2017

## Skills

**Programming** Python, C/C++, Matlab, SQL, JavaScript, HTML, CSS, PHP

**Frameworks** TensorFlow, Keras, PyTorch, ROS, OpenCV

**Software** Creo Parametric, SolidWorks, AutoCAD, HyperWorks, GAZEBO

## Work Experience

### Graduate Assistant

C-DESIGN LAB, PURDUE UNIVERSITY

West Lafayette, IN, USA

Aug. 2018 - Present

- Participated in many projects which developing 3D Deep Neural Networks and processing the 3D data

### CEO and Python Developer

NEIL LAB CORPORATION

Seoul, South Korea

Sep. 2016 - Dec. 2017

- Developed an office automation system using Python specifically for automating tasks such as sending an e-mail or issuing receipts, and designed a back-end system and database for customer web-service which automatically scrap and integrate customer's financial and personal data.

## Featured Projects

### Hand motion prediction with RGBD-T data

- Proposed a novel dataset by fusing RGB-D and thermal data for action recognition. Developed a method which predicts hand motion by segmenting hands and objects with a 3D Deep Neural network dealing with RGBD-T data.

### Mechanical Net

- Collected massive 3D mechanical component CAD data with a web-scraper and expanded the data for dense data distribution using Creo Parametric and SolidWorks API. Also, developed a web-based 3D CAD search engine using a 3D Deep Neural Network and PostgreSQL database.

### Part Geometry Net

- Developed a Generative Adversarial Network which generates 3D objects given a discrete category condition and continuous instance-level attributes. Developed a 3D data pre-processing program which converts 3D data to various types of geometric tensors.

### Latent Transformation Neural Network (LTNN)

- Developed a fully-convolutional conditional generative network which is capable of view synthesis using a light-weight neural network suited for real-time applications. (Relevant publication: [J3])

### Visual Programming Language for Mobile Robots and IoT

- Proposed a web-based visual and spatial programming language that allows novice users and small industries to program mobile robots and IoT Nodes to execute planned tasks. Developed a virtual world using ROS with Python and GAZEBO for simulating the spatial programming language.

### 3D Objects Classification Model Evaluation

- Proposed an evaluation method for 3D Deep Neural Networks by visualizing the impact of each voxel of each 3D objects. Developed a web-based CAD data retrieval engine for demonstration. (Relevant publication: [J2])

## Publications

### Journal Papers

- [J3][PDF] S. Kim, N. Winovich, **H. G. Chi**, G. Lin and Karthik Ramani. "Latent Transformations Neural Network for Object View Synthesis" (2019) *The Visual Computer*, accepted
- [J2][PDF] H. T. Hwang, **H. G. Chi**, N. K. Kang, H. B. Kong and Soo-Hong Lee. "An Evaluation Methodology for 3D Deep Neural Network using Visualization in 3D Data Classification" (2019) *Journal of Mechanical Science and Technology (JMST)*, 33(3), pp. 1333-1339.
- [J1][PDF] JIN YONGZHU, **H. G. Chi** and Soo-Hong Lee. "A Study on the Optimal Design of Pedestrian Robots Using Jansen Mechanism". (2016) *Korean Journal of Computational Design and Engineering*, 22(2), pp. 18-22.

### Conference Papers

- [C2][PDF] H. Hwang, **H. G. Chi**, S. H. Lee. "A Research about 3D Design Data Classification with 3D Convolutional Neural Network" (2017) *Proceedings of the Society for Computational Design and Engineering Conference*, pp. 441-442.
- [C1][PDF] M. H. Woo, S. H. Kim, **H. G. Chi**, M. W. Park, J. K. Kim and S. H. Lee. "Development of Web-based, Module Structure Platform for Surgical Workflow Management". (2016) *Proceedings of the Society for Computational Design and Engineering Conference*, pp. 439-441.

### Patents

- [P1][PDF] **H. G. Chi**. "Computer Input Automation System" KR Patent (2017): 10-1745330.