IEEE RAS Winter School on SLAM in Deformable environments

SLAM on Victoria Park Dataset

Group 7a : SLAM_!!

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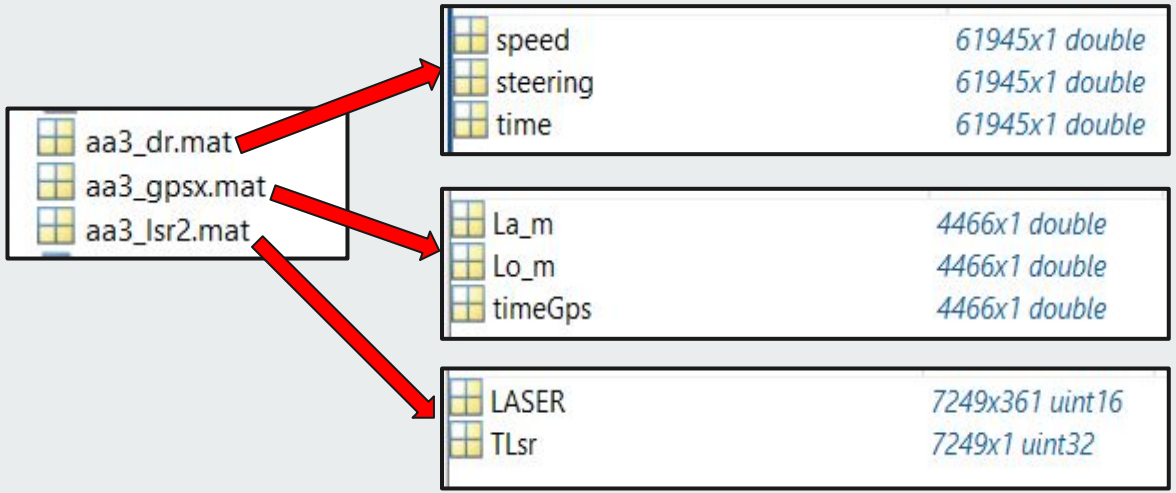
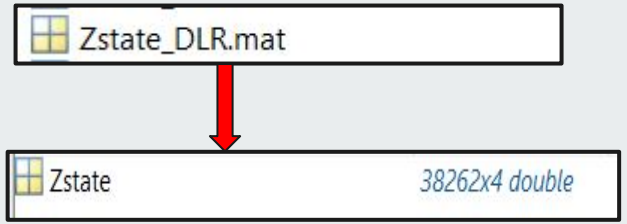
Executing SLAM

Inputs for EKF based SLAM



Input for Optimization based SLAM



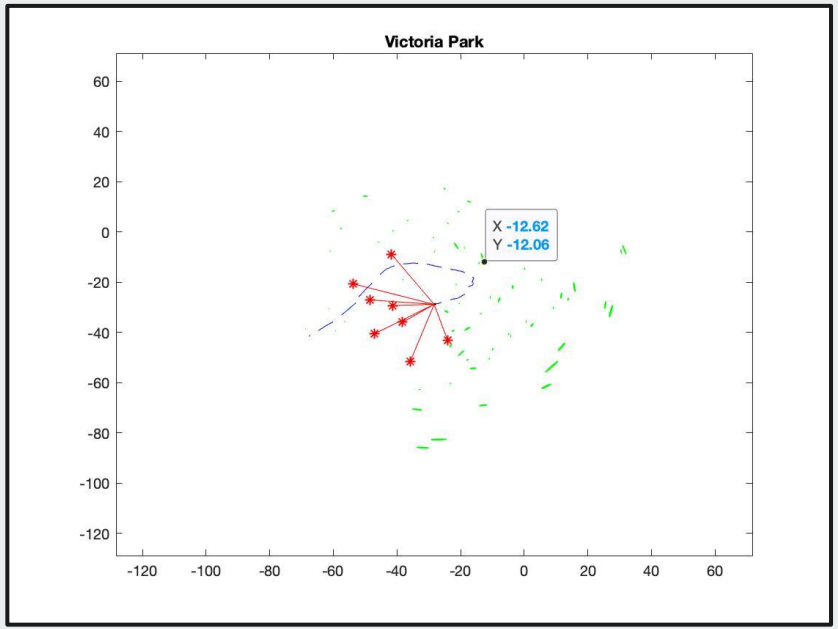


Fig. 1. Running EKF SLAM on the Victoria Park Dataset

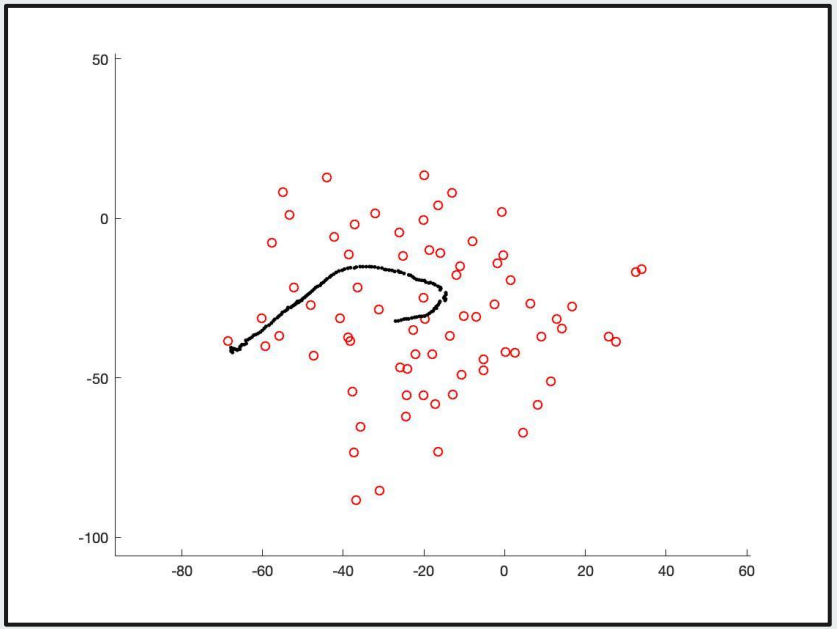


Fig. 2. Running Least squares optimization based SLAM

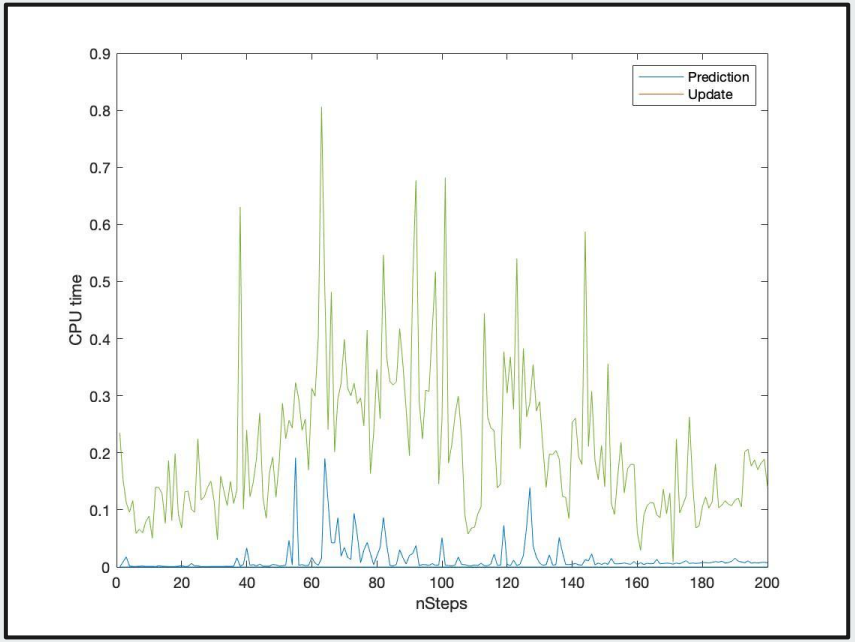


Fig. 3. CPU Runtime graph

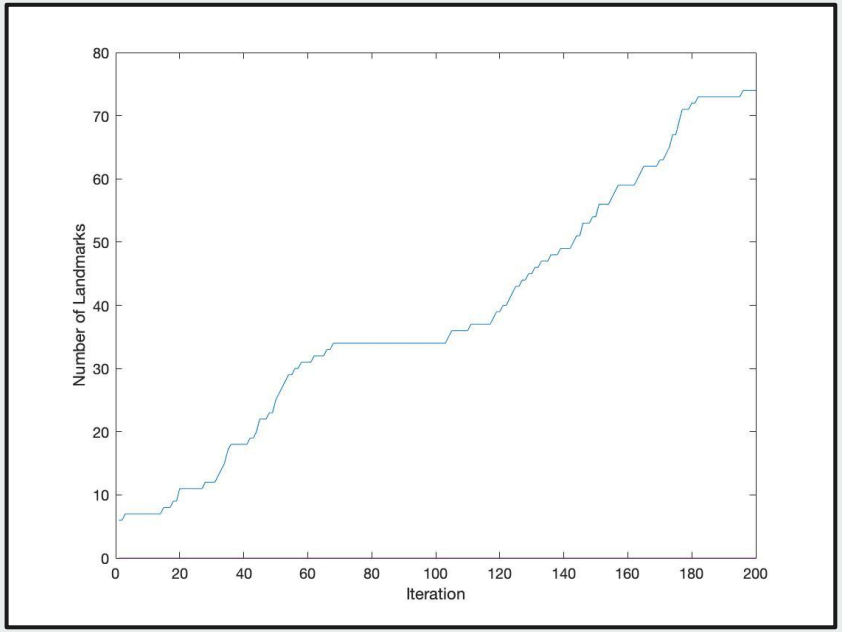


Fig. 1. # Landmark Observations encountered

Evaluating the Landmark Diameter

File := detectTrees16.m

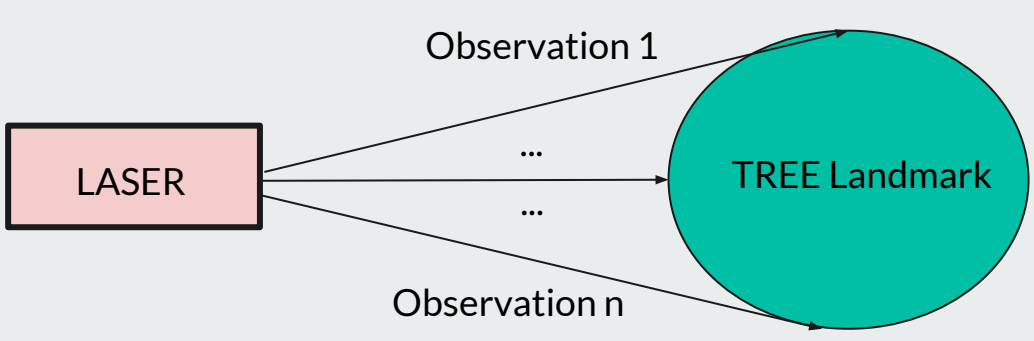


Fig. 5. Uniform weighted average distance over observations

Thank you.