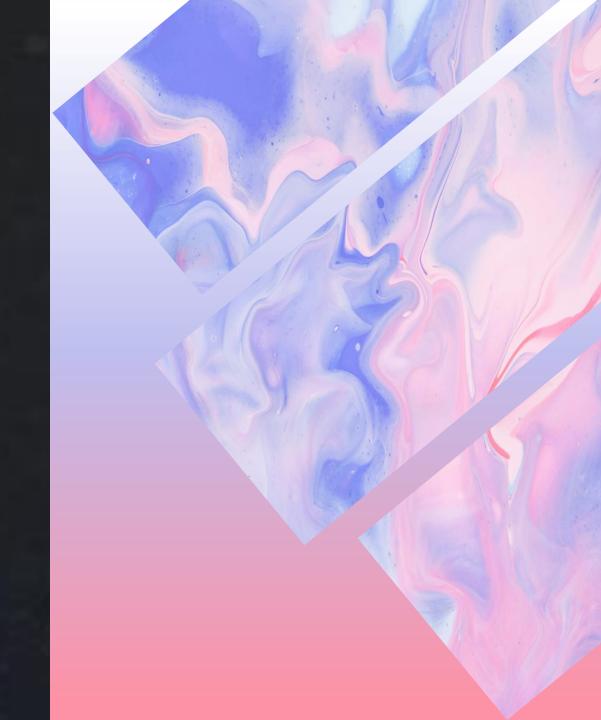
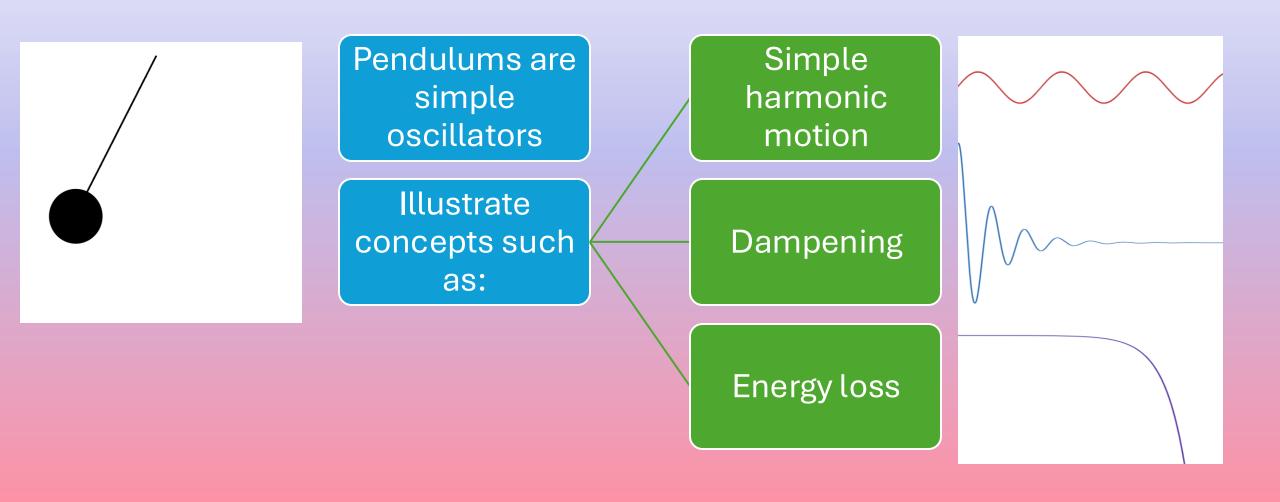
Pendulum Motion Through Fluids: Experimental and Predictive Analysis

Sammy Stollman



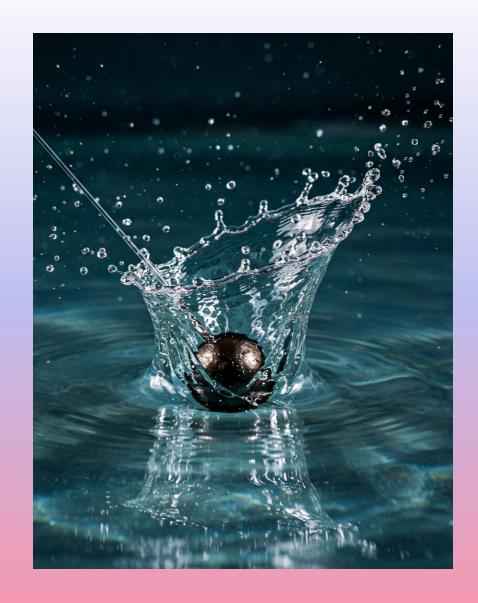
## INTRODUCTION

#### Pendulums



#### What makes pendulum swing differently in different mediums?

- Viscosity
- Density
- Resistance/Dampening



#### Why This Interests Me

- Computer Science
  - Computational Physics
  - Data Collection
  - Machine Learning
  - Mathematical Techniques
- Dynamics and Study of Motion

#### **Learning Outcomes**

#### **Physics**

- Mechanics
- Dampening
- FluidDynamics

#### Data Science

- DataCollection
- Modeling
- Machine Learning

#### Programming

- Python
- JupyterNotebook

#### Importance in Lab Setting

Prediction Methods

Computational Physics

#### **End Goals of Experiment**

Videos

Use The Model

**Predictions** 

Benefits/Drawbacks

Question How we can Improve Model

## Materialsand Methodology

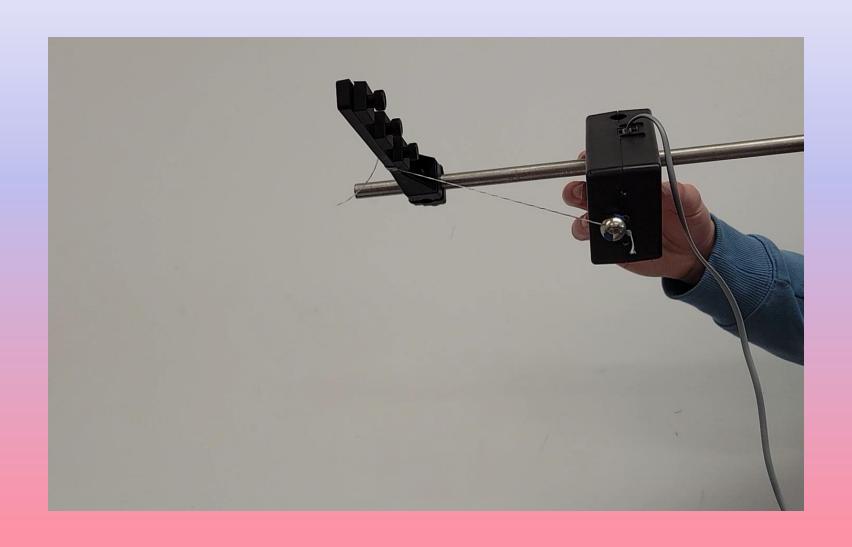
#### Fluids

- Air
- Water
- OilSyrup

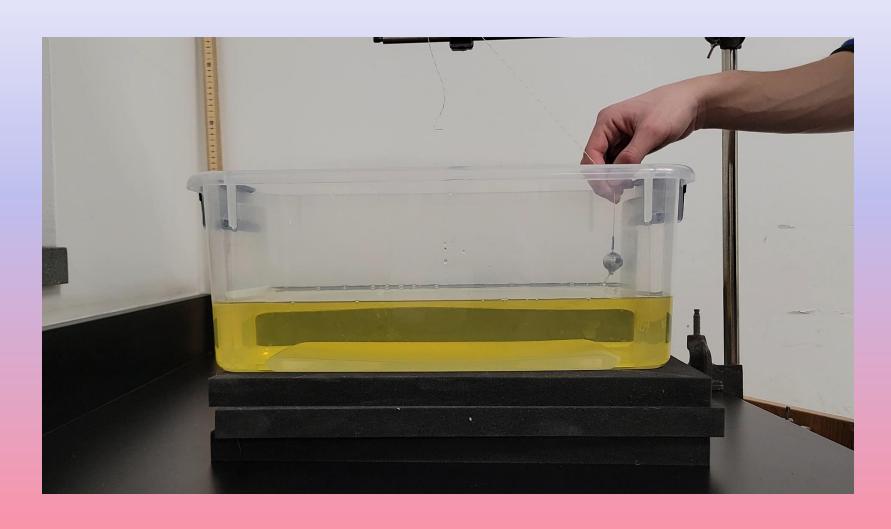














#### Materials

Pendulum Clamp

Steel Ball

String

Plastic Bin

Phone Holder

Meter Stick



**Drop Box With Magnet** 

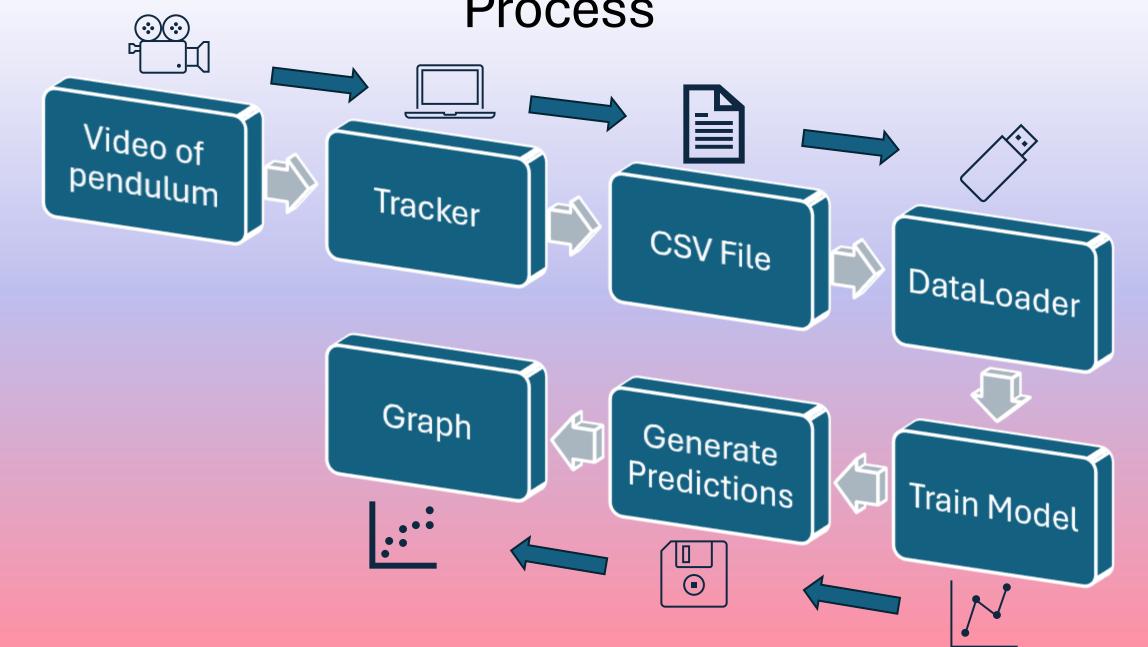
Control Box

Button

Large Table Clamp and Rod

Small Table Clamp and Rod

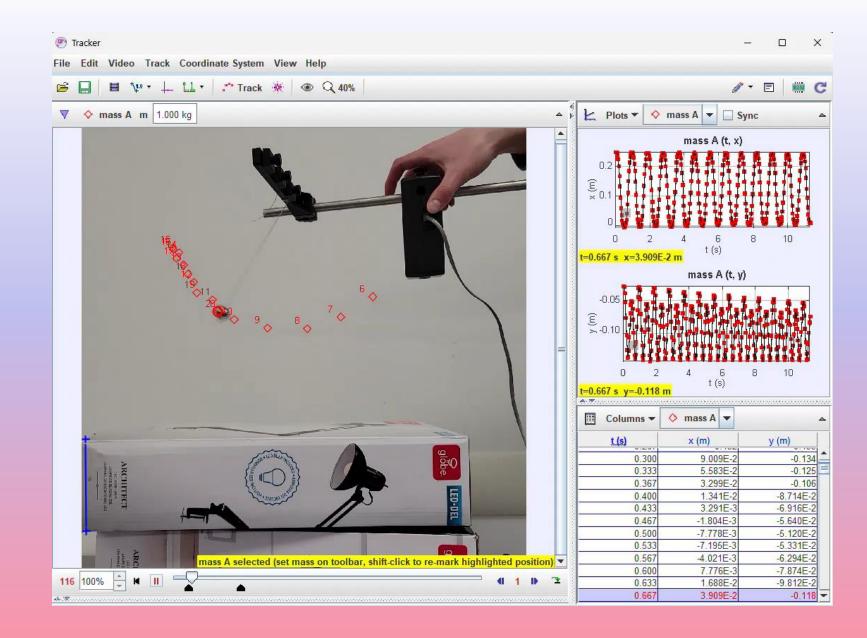
#### **Process**



### Data Collection

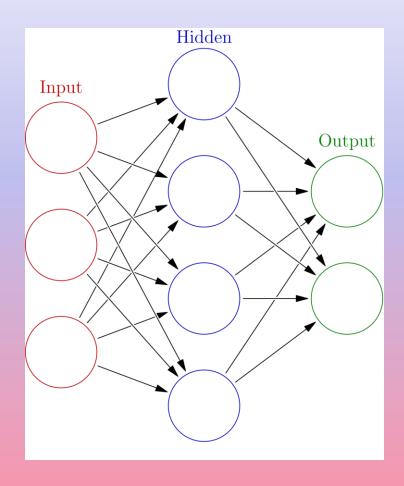
#### Software

- Tracker
  - 30 fps vs 60 fps
- Python Notebook
  - Pytorch library
- CSV files



#### Why Use Machine Learning for This?

- Simple pendulums can be easily modeled with traditional analytical equations
- Damped pendulums in fluids are complex
- ML can help by
  - Predicting motion without solving complex differential equations
  - Model behavior using experimental data



#### Deciding How Many Data Points Are Important

- Considerations:
  - Training time
  - Computational power
- I ended up using about 5 files for each fluid
  - Each containing between 300 and 500 data points
- Very easy to modify

```
CONFIG = {
    "sequence_length": 200,
    "prediction_length": 300,
    "hidden_size": 256,
    "num_layers": 4,
    "learning_rate": 0.001,
    "batch_size": 32,
    "dropout": 0.2,
    "epochs": 150
}
```

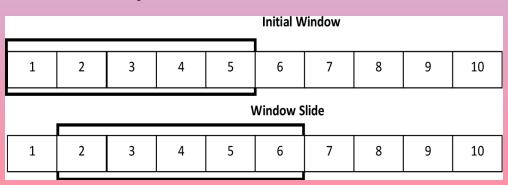
#### Training one model vs training multiple

One Model	Multiple Models
Learns patterns for all fluids (more adaptable)	Less data efficient
Only train once	Must train separately for each fluid
Easier to add more fluids later	No risk of fluid type confusion
Smaller storage space	More storage space

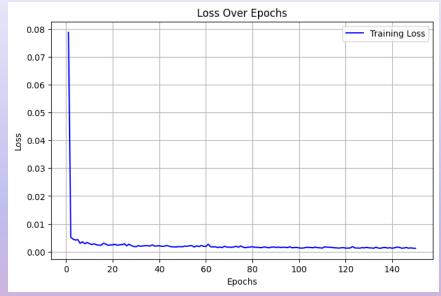
## Data Processing

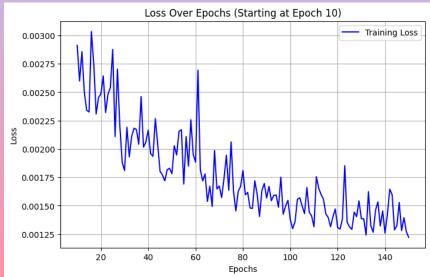
#### **LSTM**

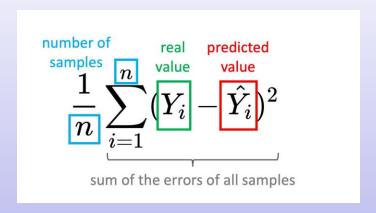
- LSTM stands for Long Short-Term Memory
- Models like this can store data from multiple different time periods in a dataset
- Data is classified in terms of importance for future predictions and re-evaluated at each full training run-through (Epoch)
- The primary goal of any machine learning model is to minimize loss between actual and predicted values



#### **Training**









#### Challenges

- Shaky Video
- Inconsistent Starting Point
- String Friction
- Tracking Shiny Ball
- Training Time
- Number of Data Points ———— The more data the better
- Cleaning up CSV Files
   Deleting extra lines

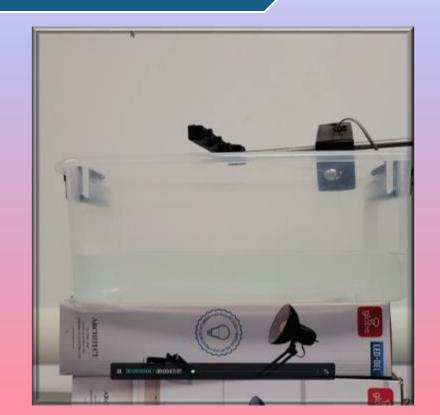




Shaky Video

CapCut Video editor stabilize feature





Inconsistent Start Point Drop Box and Push Button







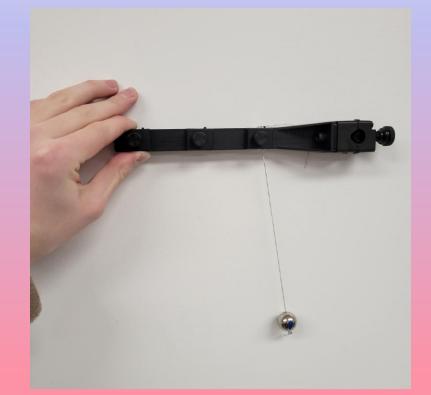
**Control Box** 

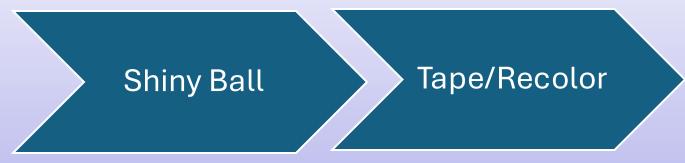


**Button** 



Pendulum Clamp





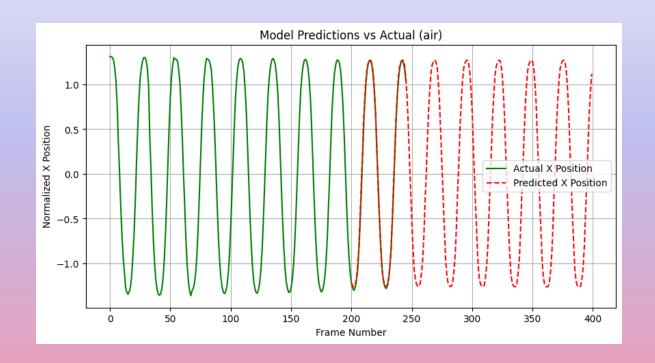


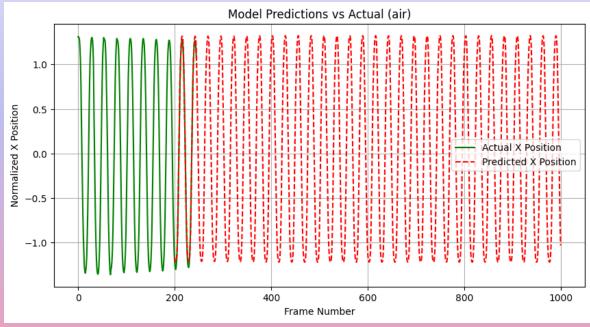
Training
Time

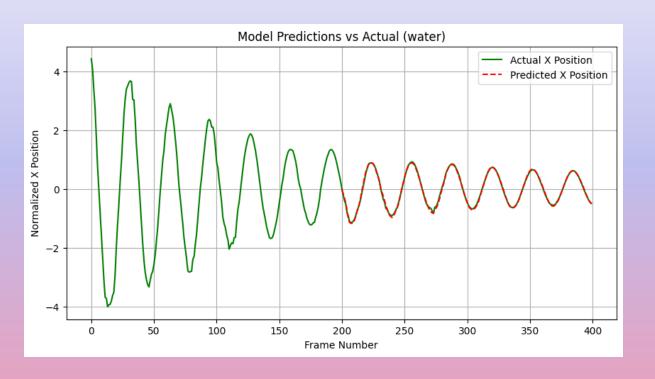
Reduce Features

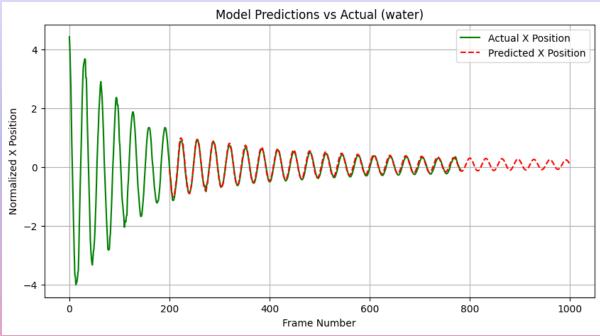
Features: x,y,vx,vy	Features: x
Epochs: 125	Epochs: 125
Training took 2230.79 seconds	Training took: 259.19 seconds
$\frac{2230s}{60s/min} \approx 37min$	$\frac{259s}{60s/min} \approx 4.3min$

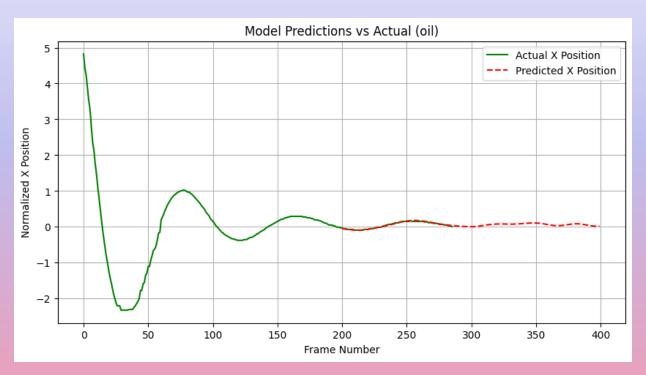


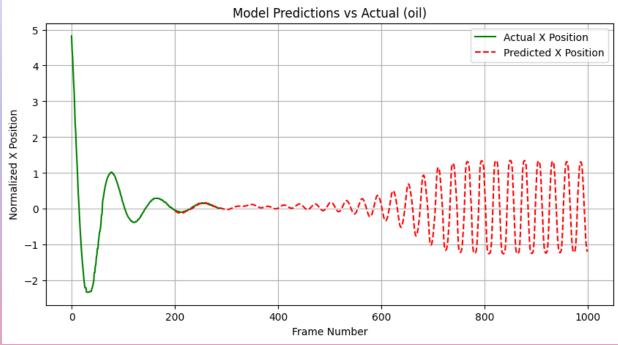


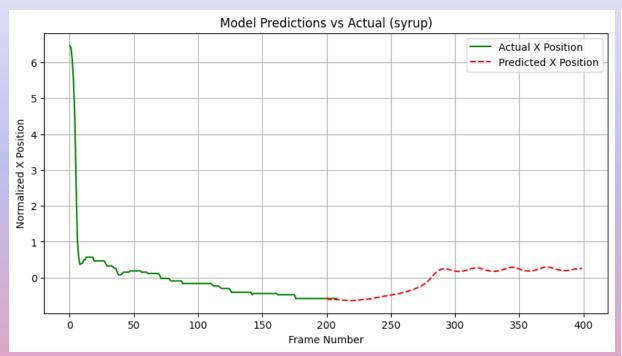


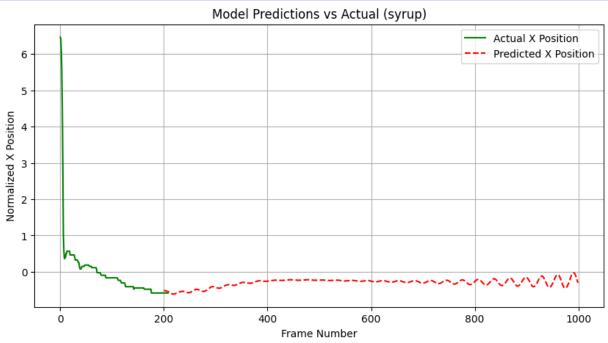






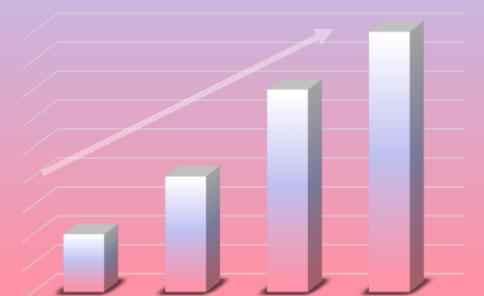






#### **Future Improvements**

- Using water and water thickener to show how different amounts of thickener change viscosity and period
  - Easier cleanup
- Different Tracker Application using Al
- Increase feature size for more predictions (y, vx, vy...)



# Questions