Resource-Guided Program Synthesis

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Program Synthesis

Declarative specification

Synthesizer

Executable program

State of the art

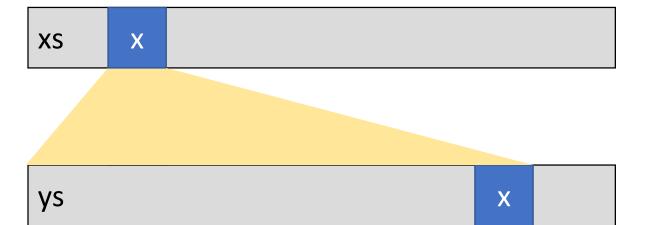
"Find the intersection of two sorted lists" Synthesizer

Type-directed synthesis

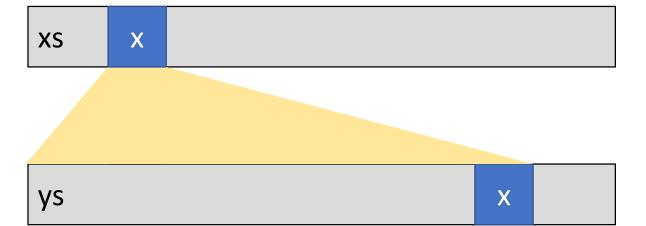
```
common :: xs: SList a → ys: SList a
           → v: {List a | elems v = elems xs ∩ elems ys}
                                Synthesizer
                        common = \lambda xs. \lambda ys.
                         match xs with
                           Nil → Nil
                           Cons x xt →
                            if !(member x ys)
                              then common xt ys
```

else Cons x (common xt ys)

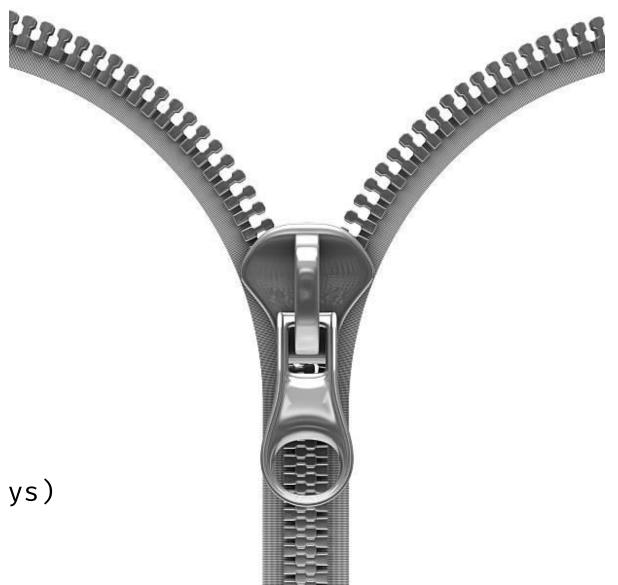
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common = λ xs. λ ys.
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```



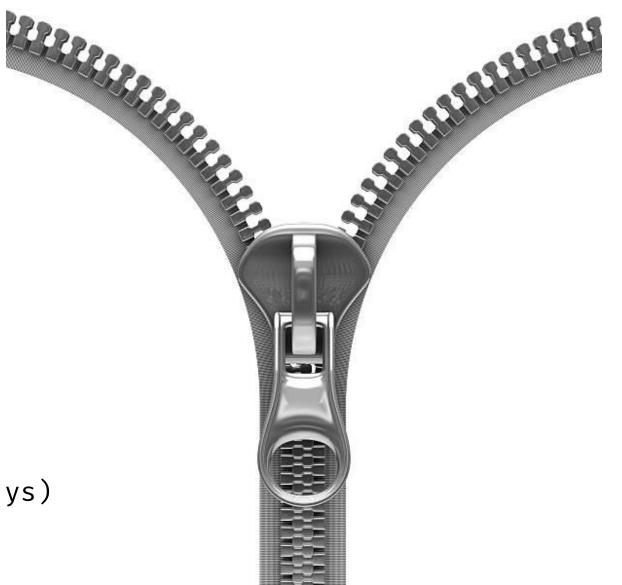
```
common = λ xs. λ ys.
match xs with
Nil → Nil
Cons x xt →
if !(member x ys)
then common xt ys
else Cons x (common xt ys)
```



```
common = \lambda xs. \lambda ys.
  match xs with
    Nil → Nil
    Cons x xt →
      match ys with
        Nil → Nil
        Cons y yt →
           if x < y
             then common xt ys
             else if y < x</pre>
               then common xs yt
               else Cons x (common xs ys)
```



```
common = \lambda xs. \lambda ys.
  match xs with
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      match ys with
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```



$O(m \cdot n)$

```
common = λ xs. λ ys.
  match xs with
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  if !(member x ys)
    then common xt ys
  else Cons x (common xt ys)
```

O(m + n)

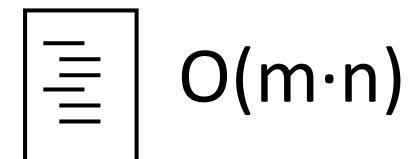
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  match xs with
  Nil → Nil
  Cons x xt →
    match ys with
    Nil → Nil
    Cons y yt →
    if x < y
        then common xt ys
    else if y < x
        then common xs yt
    else Cons x (common xs ys)</pre>
```

What we have

"Find the intersection of two sorted lists"

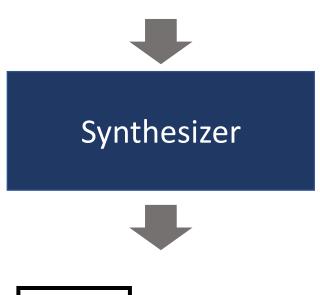


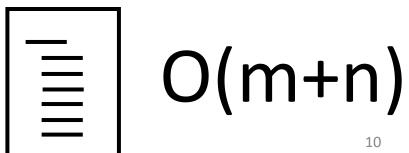




What we want

"Find the intersection of two sorted lists in linear time"





ReSyn

The first resource-aware synthesizer for recursive programs

1. Specification

"Find the intersection of two sorted lists in linear time"



Synthesizer



"Find the intersection of two sorted lists in linear time"



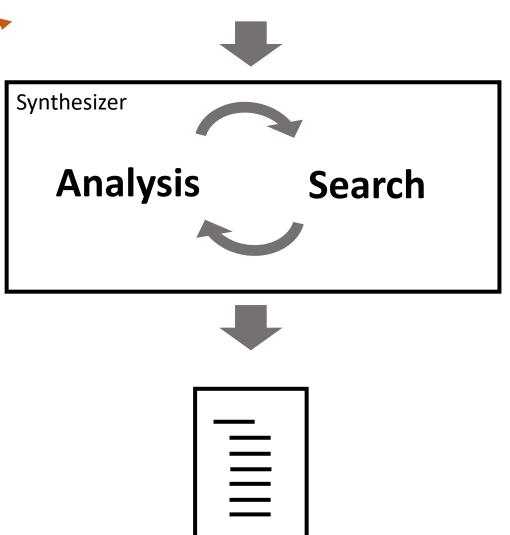
1. Specification

Synthesizer



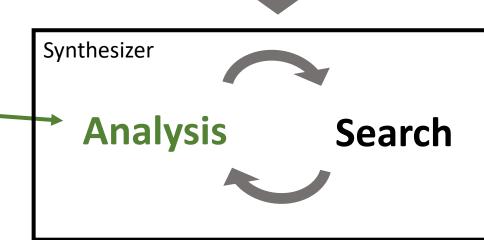
"Find the intersection of two sorted lists in linear time"

1. Specification



"Find the intersection of two sorted lists in linear time"

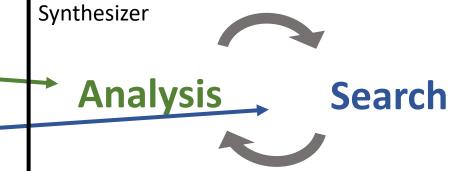
- 1. Specification
- 2. Analysis





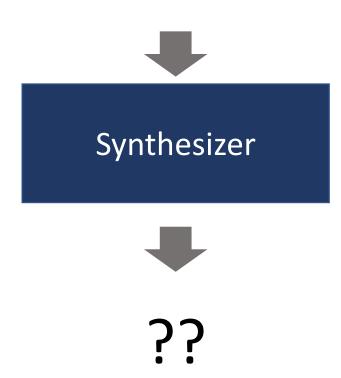
"Find the intersection of two sorted lists in linear time"

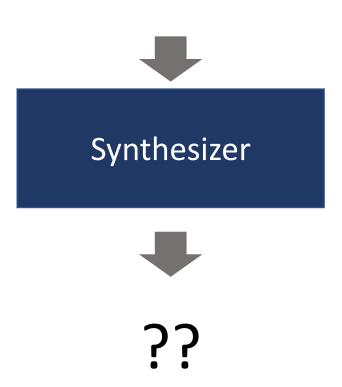
- 1. Specification
- 2. Analysis
- 3. Search

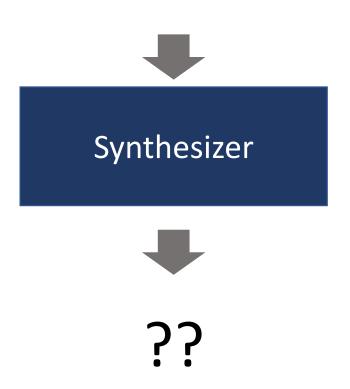




- 1. Specification
- 2. Analysis
- 3. Search

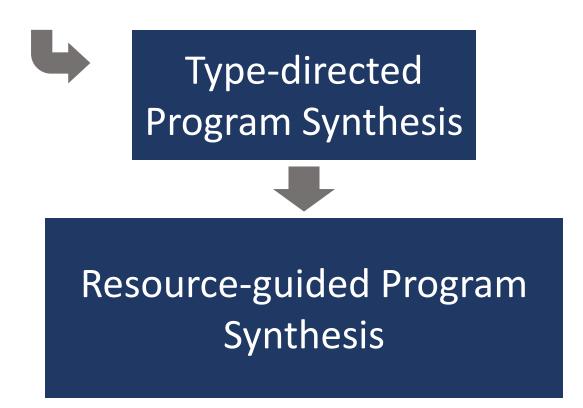




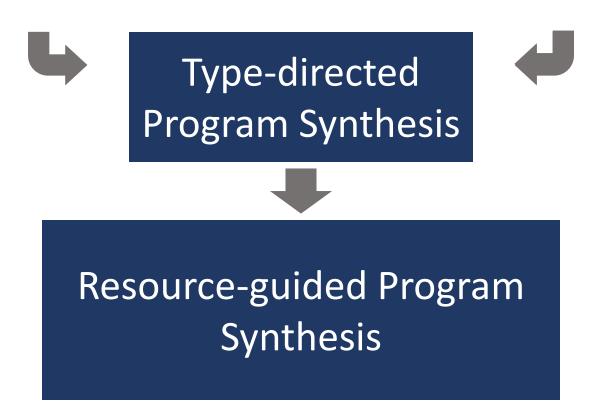


Refinement types with Resource annotations

Refinements: Synquid



Refinements: Synquid Resource annotations: AARA



[Polikarpova et. al 2016]

[Hoffmann et al. 2010]

B

v:{Int|v≥0}

common = ??

```
common :: xs: SList a → ys: SList a
   → v: {List a | elems v = elems xs ∩ elems ys}
common = ??
```

```
common :: xs: SList a → ys: SList a
  → v: {List a | elems v = elems xs ∩ elems ys}
common = ??
```

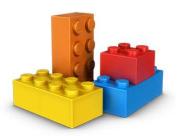
Functional specification



Synquid







Functional specification







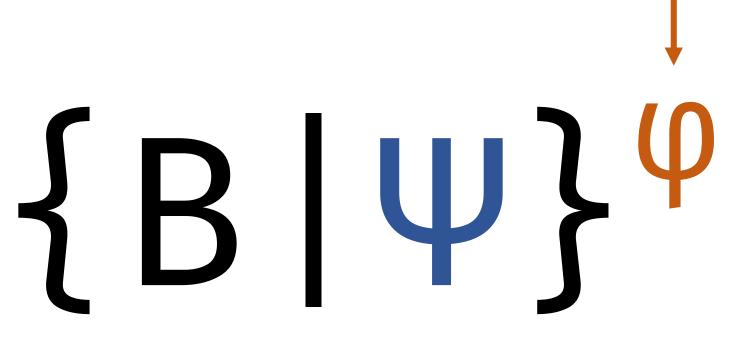
```
common = \lambda xs. \lambda ys.
  match xs with
    Nil → Nil
    Cons x xt →
      if !(member x ys)
        then common xt ys
        else Cons x (common xt ys)
```



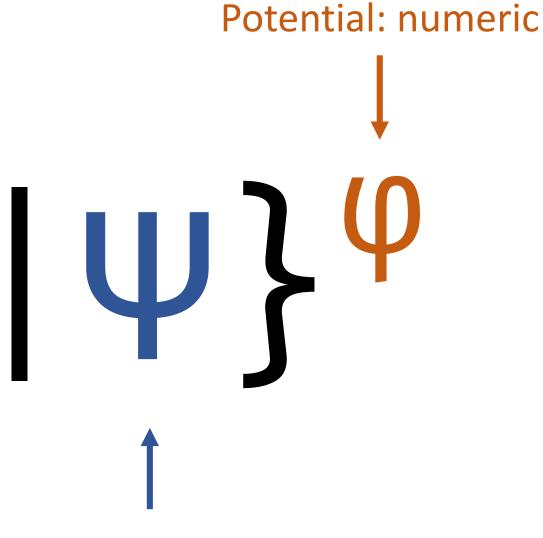








Potential



Refinement: boolean

Resource annotations

```
common :: xs: SList a → ys: SList a
  → v: {List a | elems v = elems xs ∩ elems ys}
common = ??
```

Resource budget

```
common :: xs: SList a¹ → ys: SList a¹
   → v: {List a | elems v = elems xs ∩ elems ys}
common = ??
```

Synthesize with ReSyn

```
common :: xs: SList a¹ → ys: SList a¹
  → v: {List a | elems v = elems xs ∩ elems ys}
common = ??
```

```
member
Cons, Nil, ...
≤, =, !, ...
```

Components: member

```
member :: z:a → zs:List a

→ v:{Bool|v = (x ∈ elems xs)}
```

Components: member

```
member :: z:a \rightarrow zs:List a^1
 \rightarrow v:\{Bool|v = (x \in elems xs)\}
```

Components: member

```
member :: z:a → zs:List a¹
→ v:{Bool|v = (x ∈ elems xs)}
```

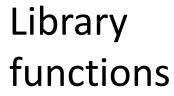
Functional specification



Resource bound



ReSyn





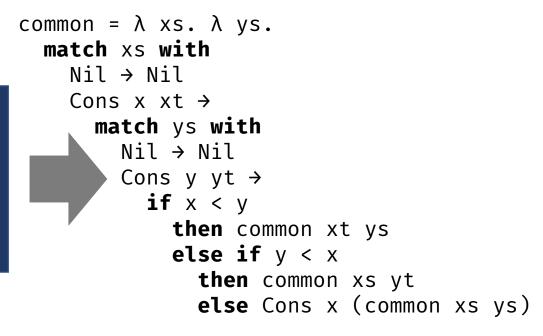
Functional specification



Resource bound



ReSyn







This talk

- 1. Specification
- 2. Analysis
- 3. Search

How do we know **common** does not run in linear time?

```
common = λ xs. λ ys.
  match xs with
  Nil → Nil
  Cons x xt →
  if !(member x ys)
    then common xt ys
  else Cons x (common xt ys)
```

```
common = λ xs. λ ys.
match xs with
Nil → Nil
Cons x xt →
if !(member x ys)
then common xt ys
else Cons x (common x ys)

xs x
```

```
member :: z:a \rightarrow zs: List a<sup>1</sup> \rightarrow v:{Bool|v = (x \in elems xs)}
```

How do we automate this reasoning?

```
common = λ xs. λ ys.
  match xs with
  Nil → Nil
  Cons x xt →
  if !(member x ys)
    then common xt ys
  else Cons x (common xt ys)
```

```
common :: xs: SList a^1 \rightarrow ys: SList a^1 \rightarrow v: {List a \mid ...}
common = \lambda xs. \lambda ys.
  match xs with
    Nil → Nil
     Cons x xt →
       if !(member x ys)
          then common xt ys
          else Cons x (common xt ys)
```

Can we partition the allotted resources between all function calls?

```
common = λ xs. λ ys.
  match xs with
  Nil → Nil
  Cons x xt →
  if !(member x ys)
    then common xt ys
  else Cons x (common xt ys)
```

```
common = λ xs. λ ys.
  match xs with
  Nil → Nil
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  if !(member x ys)
    then common xt ys
  else Cons x (common xt ys)
```

```
common = λ xs. λ ys.
match xs with
Nil → Nil
Cons x xt →
if !(member x (ys :: List a<sup>p</sup>))
then common xt (ys :: List a<sup>q</sup>)
else Cons x (common xt ys)
```

```
common = λ xs. λ ys.
match xs with
Nil → Nil
Cons x xt →
if !(member x (ys :: List a<sup>p</sup>))
then common xt ys
else Cons x (common xt ys)
```

```
member :: z:a \rightarrow zs: List a^1 \rightarrow v:\{Bool|...\}
common = \lambda xs. \lambda ys.
  match xs with
     Nil → Nil
     Cons x xt →
        if !(member x (ys :: List a<sup>p</sup>))
          then common xt ys
          else Cons x (common xt ys)
```

```
member :: z:a \rightarrow zs: List a^1 \rightarrow v:\{Bool|...\}
                                           List a<sup>p</sup> <: List a<sup>1</sup>
common = \lambda xs. \lambda ys.
  match xs with
     Nil → Nil
      Cons x xt \rightarrow
        if !(member x (ys :: List a<sup>p</sup>))
           then common xt ys
           else Cons x (common xt ys)
```

```
member :: z:a \rightarrow zs: List a^1 \rightarrow v:\{Bool|...\}
                                           List a<sup>p</sup> <: List a<sup>1</sup>
common = \lambda xs. \lambda ys.
                                                      p \geq 1
  match xs with
     Nil → Nil
      Cons x xt \rightarrow
        if !(member x (ys :: List a<sup>p</sup>))
           then common xt ys
           else Cons x (common xt ys)
```

a <: b p ≥ q

List a^p <: List b^q

```
common :: xs: SList a^1 \rightarrow ys: SList a^1 \rightarrow v: {List a \mid ...}
common = \lambda xs. \lambda ys.
  match xs with
     Nil → Nil
     Cons x xt \rightarrow
        if !(member x ys)
          then common xt (ys :: List aq)
          else Cons x (common xt ys)
```

```
common :: xs: SList a^1 \rightarrow ys: SList a^1 \rightarrow v: {List a \mid ...}
                                             List a<sup>q</sup> <: List a<sup>1</sup>
common = \lambda xs. \lambda ys.
                                                        q \geq 1
  match xs with
     Nil → Nil
      Cons x xt \rightarrow
        if !(member x ys)
            then common xt (ys :: List a<sup>q</sup>)
           else Cons x (common xt ys)
```

Sharing \rightarrow SList a^1 \bigvee SList a^p , SList a^q

```
common = λ xs. λ ys.
match xs with
Nil → Nil
Cons x xt →
if !(member x ys)
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else Cons x (common xt ys)
```

```
Sharing \rightarrow SList a^1 \bigvee SList a^p, SList a^q
common = \lambda xs. \lambda ys.
  match xs with
    Nil → Nil
     Cons x xt \rightarrow
       if !(member x ys)
          then common xt ys
```

else Cons x (common xt ys)

```
Sharing \rightarrow SList a^1
                                           SList a<sup>p</sup>, SList a<sup>q</sup>
common = \lambda xs. \lambda ys.
  match xs with
     Nil → Nil
     Cons x xt \rightarrow
       if !(member x ys)
                                                         Subtyping
          then common xt ys
          else Cons x (common xt ys)
```

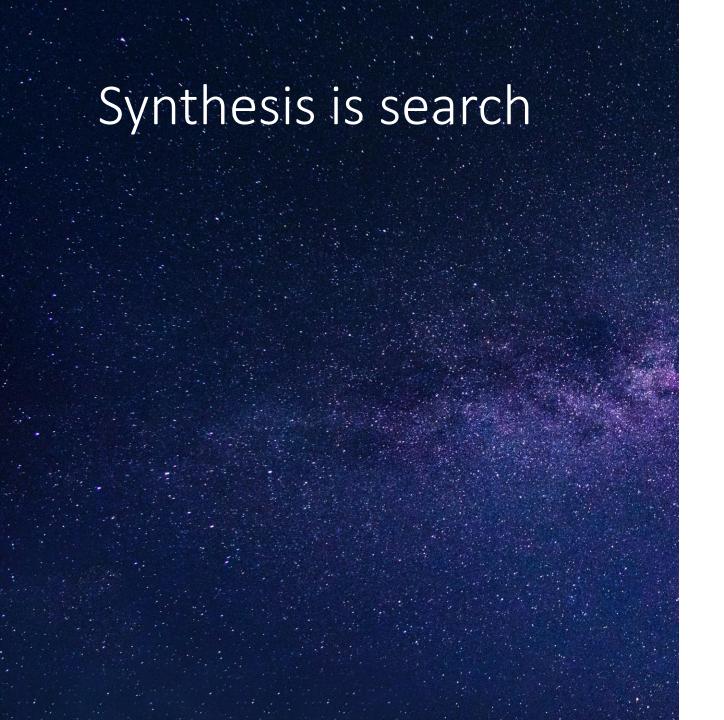
SMT

SMT

This talk

- 1. Specification
- 2. Analysis
- 3. Search

Synthesis is search



Synthesis is search

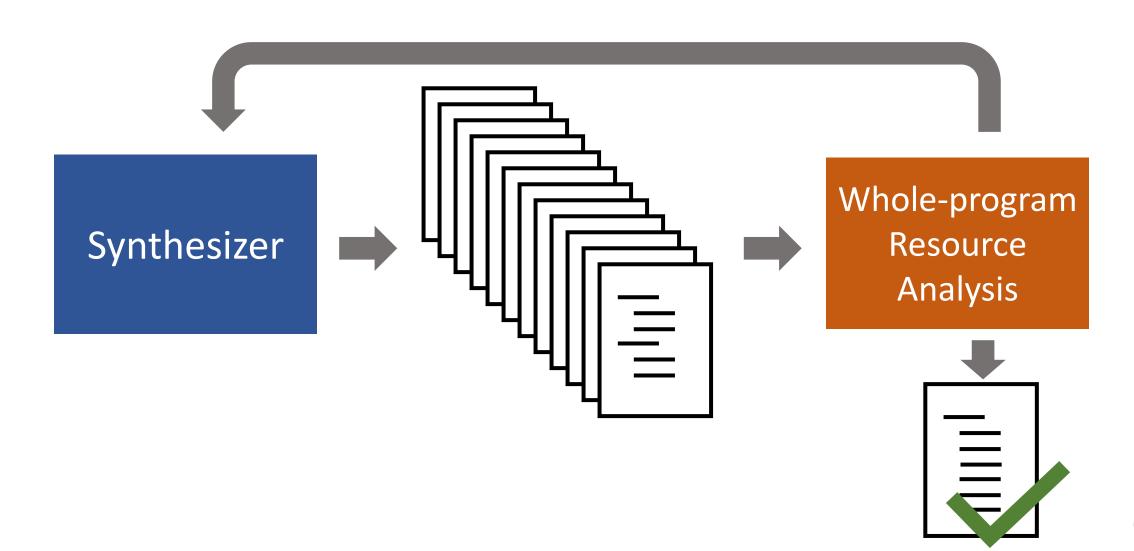
Synthesis is search



Reject impossible programs early

```
common = λ xs. λ ys.
  match xs with
  Nil → Nil
  Cons x xt →
  if !(member x ys)
    then common xt ys
  else ??
```

A different approach

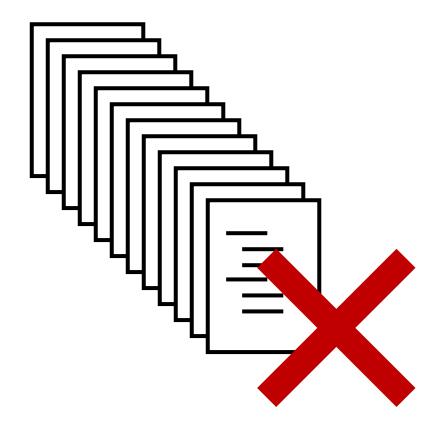


Reject impossible programs early with local analysis

```
common = λ xs. λ ys.
  match xs with
  Nil → Nil
  Cons x xt →
   if !(member x ys)
      then common xt ys
      else ??
```

Reject impossible programs early with local analysis

```
common = \lambda xs. \lambda ys.
  match xs with
    Nil → Ni
    Cons x
       if !(men
                        xt ys
         then co
         else
```



Reject impossible programs early with local analysis

```
common = λ xs. λ ys.
  match xs with
  Nil → Nil
  Cons x xt →
  if !(member x ys)
    then common ys ??
  else ??
```

Results

Results

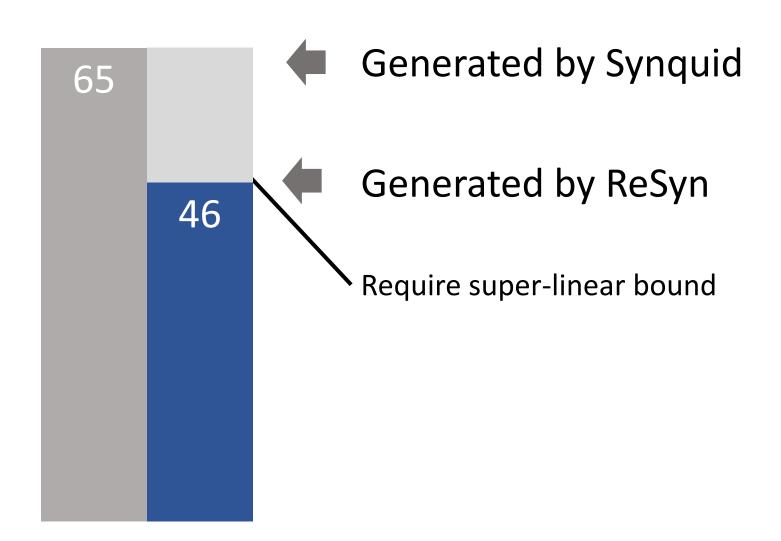
1. Can ReSyn generate faster programs than Synquid?

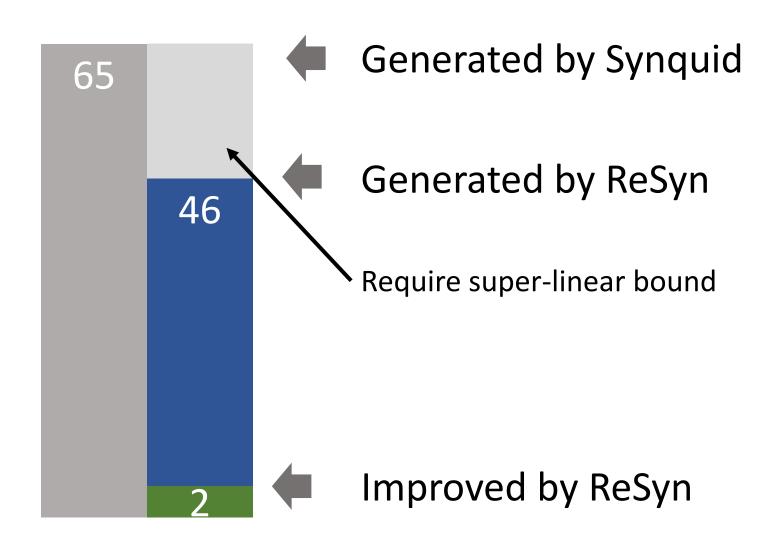
Results

- 1. Can ReSyn generate faster programs than Synquid?
- 2. How much longer does ReSyn take to generate code?

Results

- 1. Can ReSyn generate faster programs than Synquid?
- 2. How much longer does ReSyn take to generate code?
- 3. Is local resource analysis effective at guiding the search?





Generated by ReSyn 59 Improved by ReSyn 9

compress: Remove adjacent duplicates

```
compress xs =
                                             compress xs =
 match xs with
                                               match xs with
   Nil -> Nil
                                                 Nil -> Nil
   Cons x3 x4 ->
                                                 Cons x3 x4 ->
     match compress x4 with
                                                   match compress x4 with
                                                     Nil -> Cons x3 Nil
       Nil -> Cons x3 Nil
       Cons x10 x11 ->
                                                     Cons x10 x11 ->
         if x3 == x10
                                                       if x3 == x10
                                                         then Cons x10 x11
           then compress x4
           else Cons x3 (Cons x10 x11)
                                                         else Cons x3 (Cons x10 x11)
           O(2^n)
                                                              O(n)
```

Synquid

ReSyn

insert: Insert into a sorted list

O(n)



O(n)

Synquid

ReSyn

```
insert :: x:a → xs: SList a<sup>if x > v then 1 else 0</sup>
         → v:{SList a | elems v = elems xs ∪{x}}
```

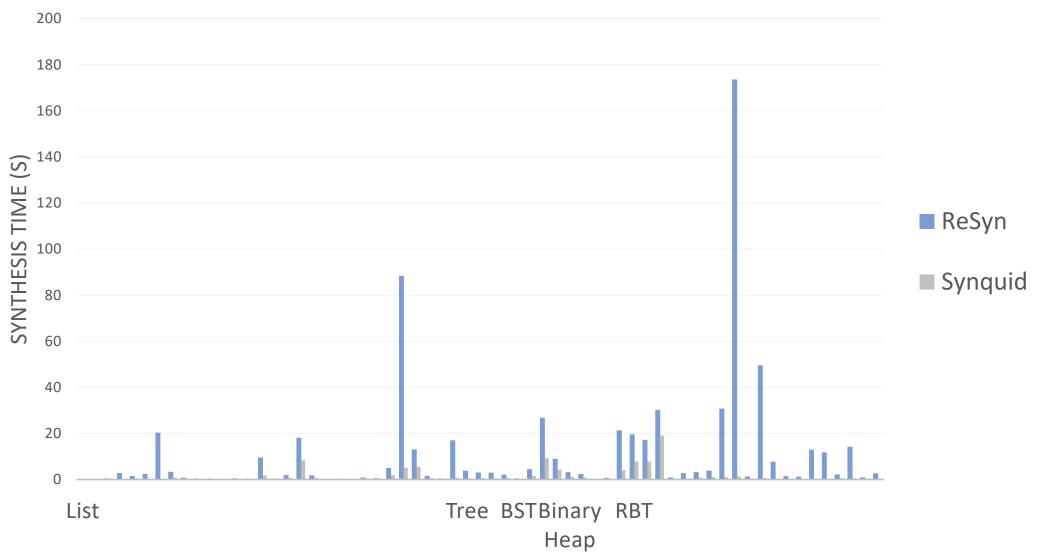
```
insert x xs =
                                                insert x xs =
 match xs with
                                                  match xs with
                                                    Nil -> Cons x Nil
   Nil -> Cons x Nil
                                                    Cons y ys ->
   Cons y ys ->
      if x < y
                                                      if x < y
        then Cons x (insert y ys)
                                                         then Cons x (Cons y ys)
                                                        else Cons y (insert x ys)
        else Cons y (insert x ys)
```

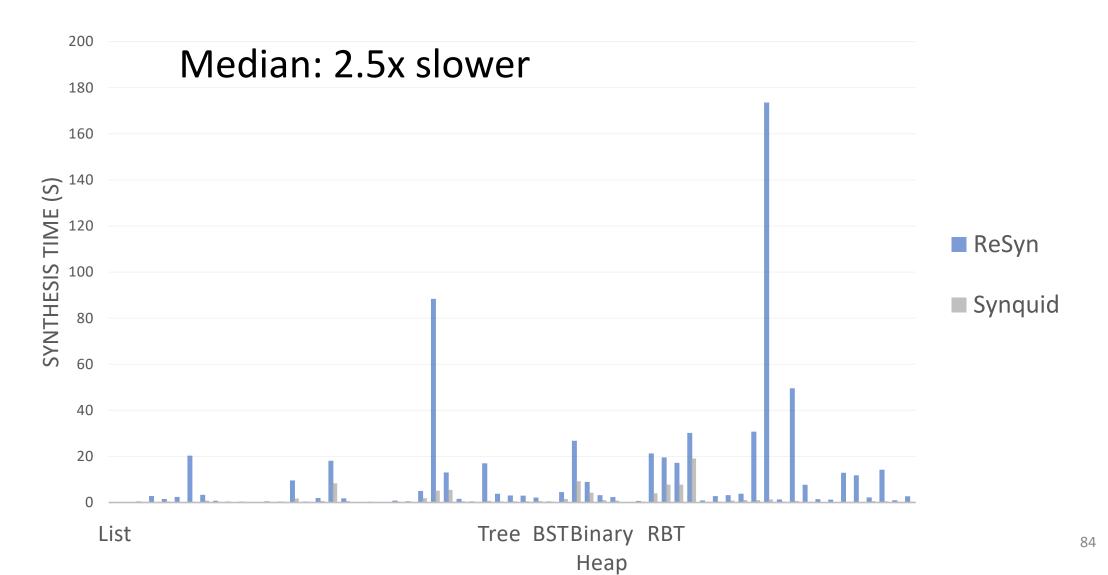
O(n)

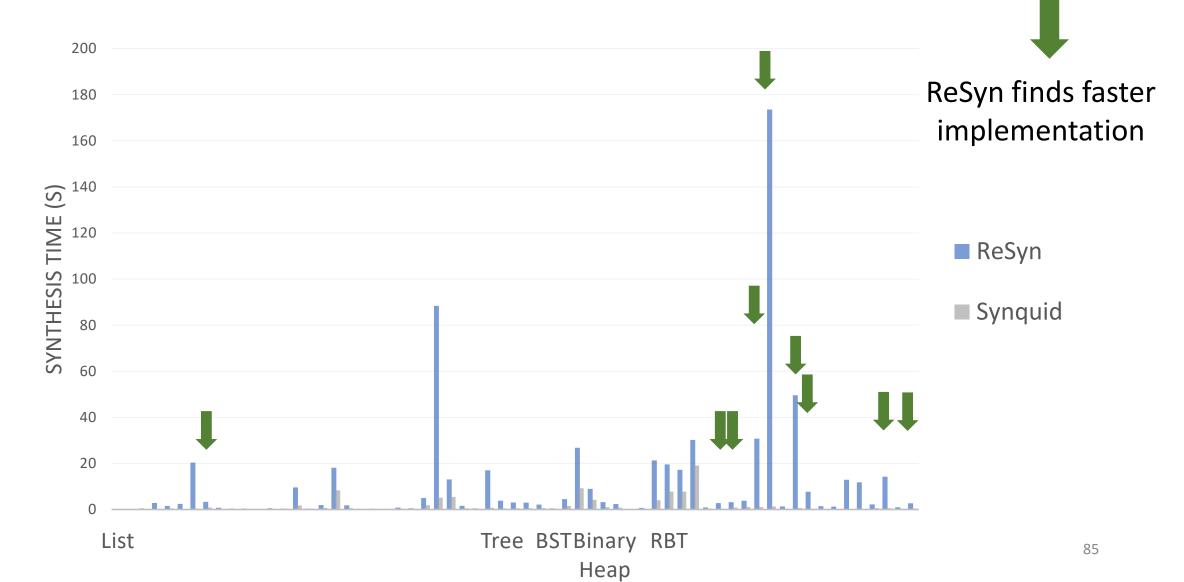


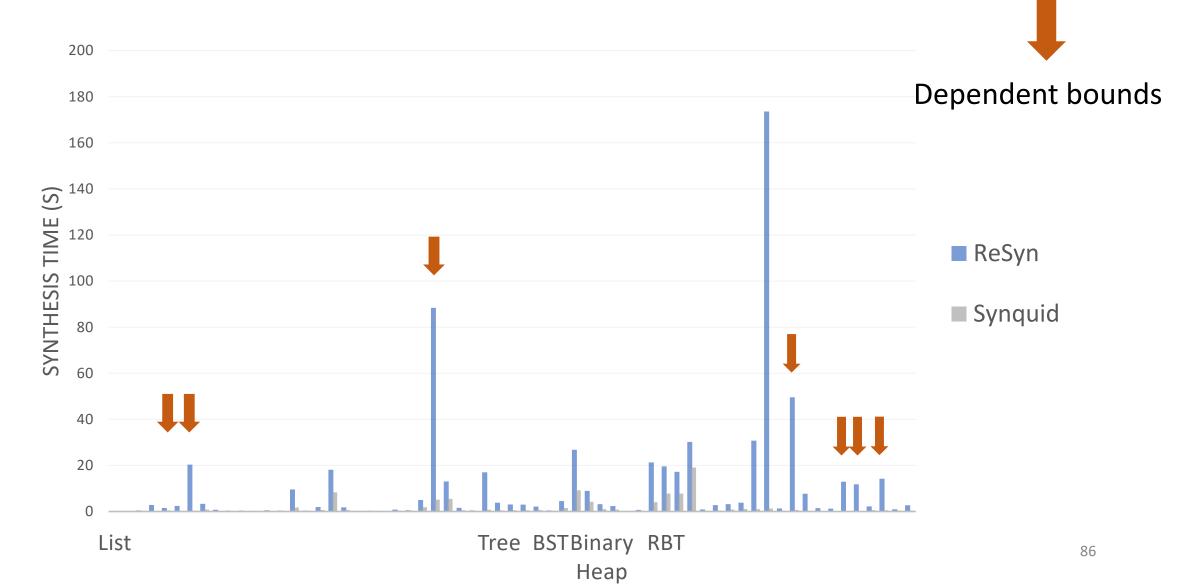
O(n)

"One recursive call per element in xs that is smaller than x''

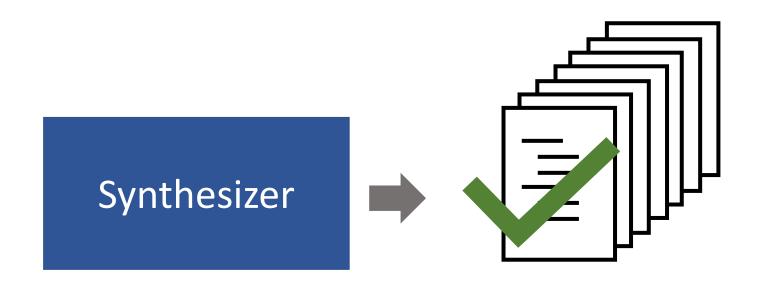


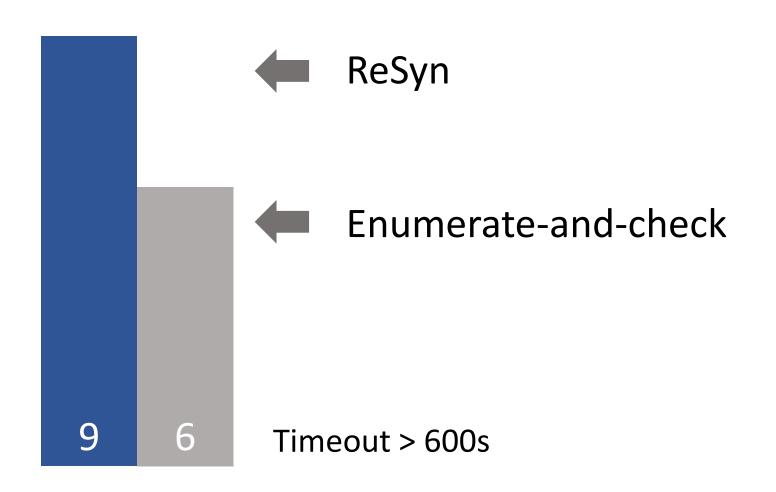


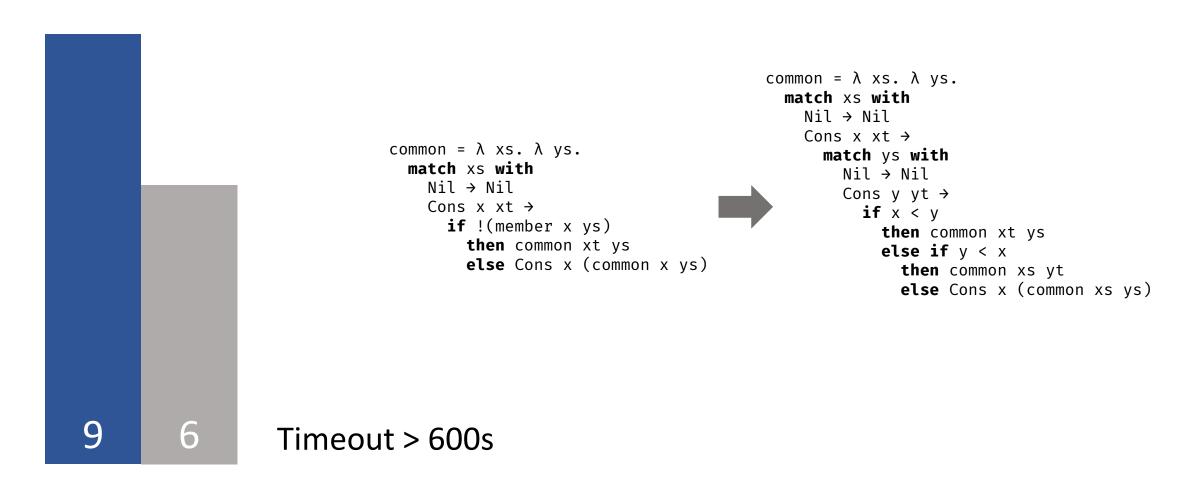




3. Does local resource analysis guide synthesis?







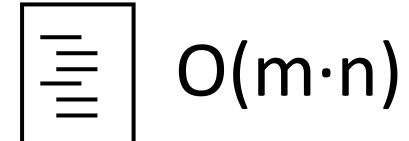
What we had

"Find the intersection of two sorted lists"



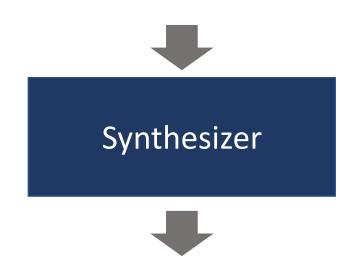
Synthesizer

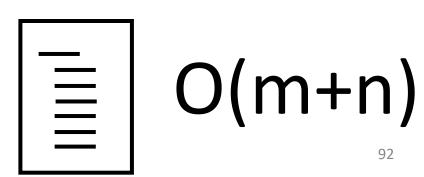




What we have now

"Find the intersection of two sorted lists in linear time"





https://bitbucket.org/tjknoth/resyn