

Storage Systems (StoSys)

XM_0092

Lecture 11: CXL and io_uring

Animesh Trivedi

<https://stonet-research.github.io/>

Autumn 2023, Period 1



Syllabus outline

1. Welcome and introduction to NVM
2. Host interfacing and software implications
3. Flash Translation Layer (FTL) and Garbage Collection (GC)
4. NVM Block Storage File systems
5. NVM Block Storage Key-Value Stores
6. Emerging Byte-addressable Storage
7. Networked NVM Storage
8. Trends: Specialization and Programmability
9. Distributed Storage / Systems - I
10. Distributed Storage / Systems - II
11. Emerging Topics



Today is the last course lecture

We survived, it has been quite fun to teach this course

Hope you also had fun and learn a lot of advancements happening in the area of storage research

In coming days and weeks

- **Next Tuesday:** Milestone 5 interview - **sign up!**
- **Next Wednesday:** Guest Lecture from Nikolas
- **Afterwards:** Prepare for the exam - Good luck !
- **In the End:** We will ask for some feedback on the course
 - Me as a teacher
 - Broadly about the course - *you can be frank!*
 - **Want to be the TA next year?**



If you are interested in such research ...

Individual research projects (XM_405088)

- 6 or 12 ECTS credits

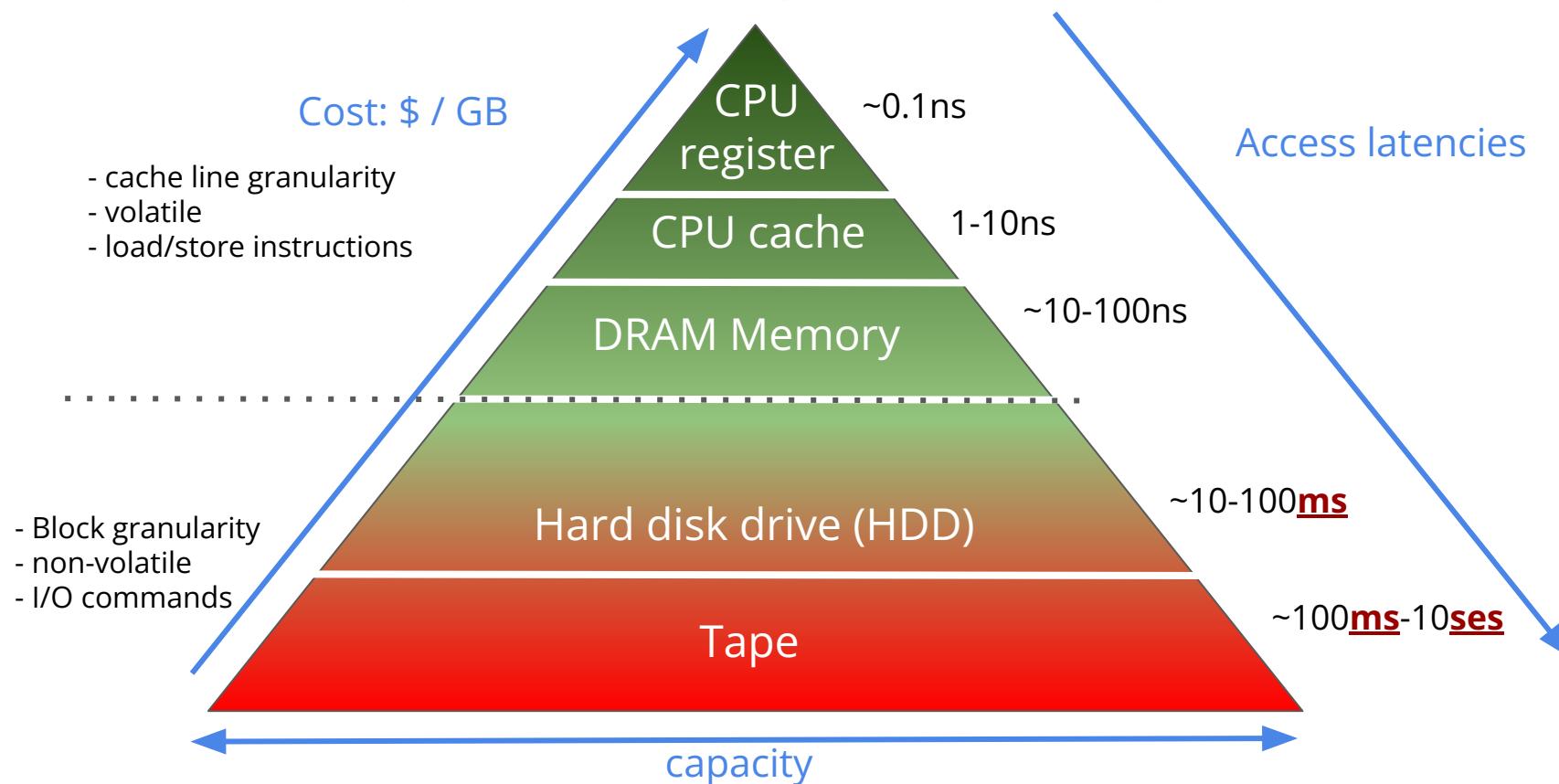
Master projects / literature study

- Benchmarking the storage benchmarks
- io_uring/CXL research (*today's lecture*)
- Integrating NVM(e)/NVMe storage in ML runtime to train large models
(Swapping Tensors)
- Building computation storage device prototype in QEMU
- Virtualizing ZNS/NVMe devices
- Scheduling I/O operations for workload-specific optimizations
- ***Your favorite idea ... I am broadly open to ideas from your side, pick a paper and lets discuss***

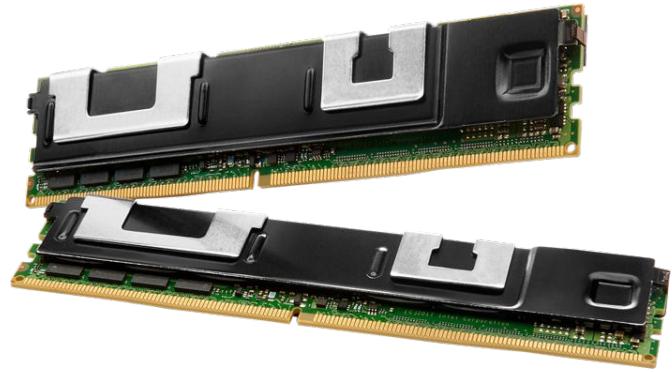
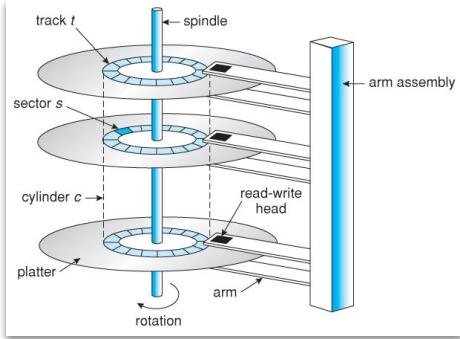


**footnote: Thanks to Gary from Carleton U. for this comic idea!

The triangle of storage hierarchy



Recap: From HDDs to Persistent Memories (PMem)



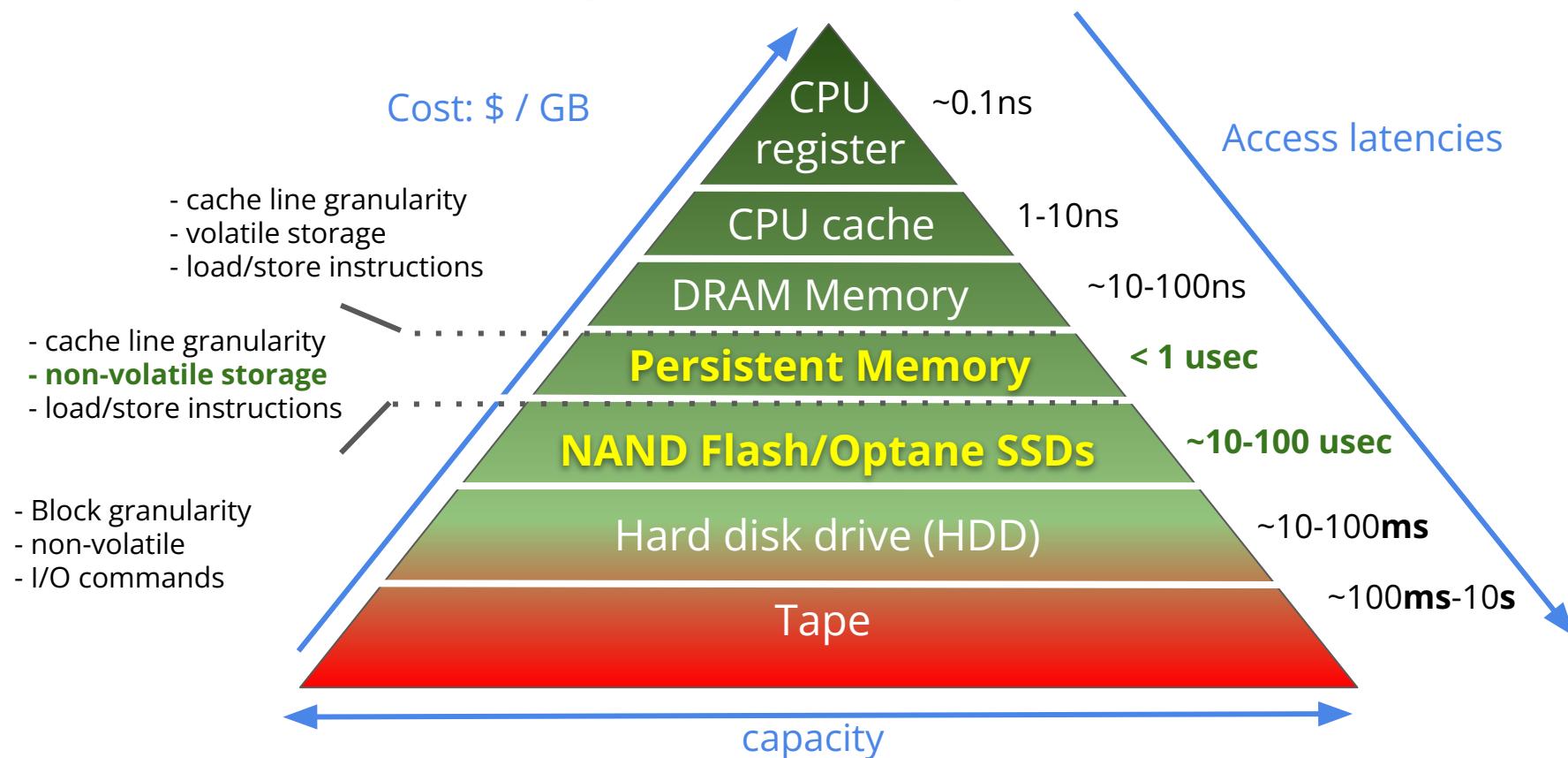
10s ms
HDD

100s us
Flash

100s ns
Optane

10s ns
DRAM

The (new) triangle of storage hierarchy



Multiple Emerging Topics (non-exhaustive)

Domain-specific/specialized storage solutions

Storage virtualization, Disaggregation (end-to-end software-defined-*)

Quality-of-service in Storage Ecosystems (scheduling, multi-tenancy)

Energy Considerations

CPU-free Computing (re-thinking the computing architecture)

- [CPU-free Computing: A Vision with a Blueprint | Proceedings of the 19th Workshop on Hot Topics in Operating Systems](#)

Hardware changes: Computer Express Link (CXL)

- *Brief motivation and capabilities (without getting into too much hw/PCIe details)*

New software APIs: io_uring (Linux, also being ported to other OSes)

- *How is it different than other APIs and what options does it provide, performance implications*

The Key Problems 1 / 2

The CPU is the center of computing

- direct memory access
- center of coherency
- controller of the devices

and the final coordinator and arbiter

The CPU performance was fast!

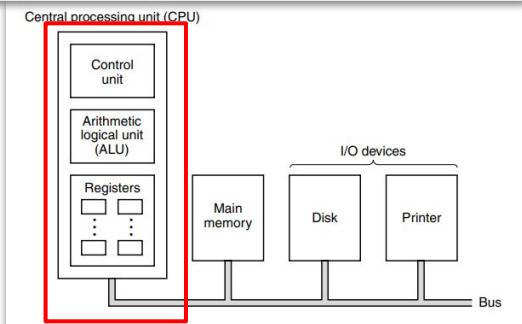
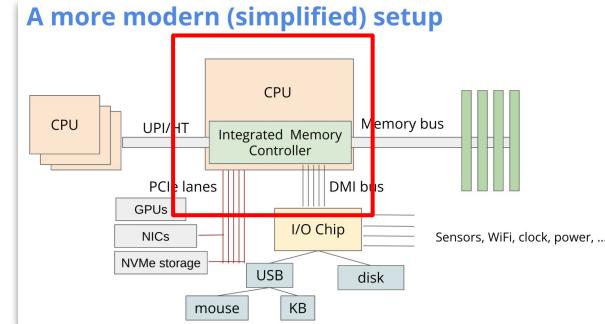


Figure 2-1. The organization of a simple computer with one CPU and two I/O devices.

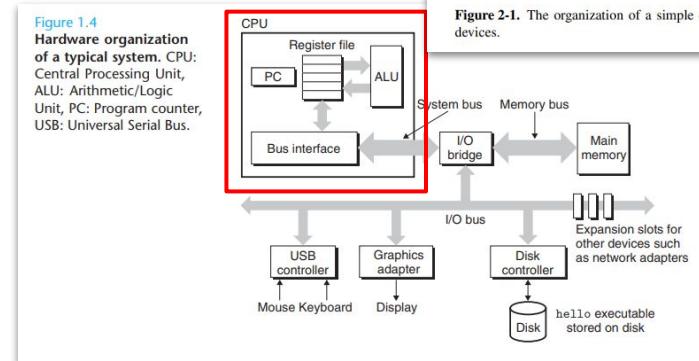
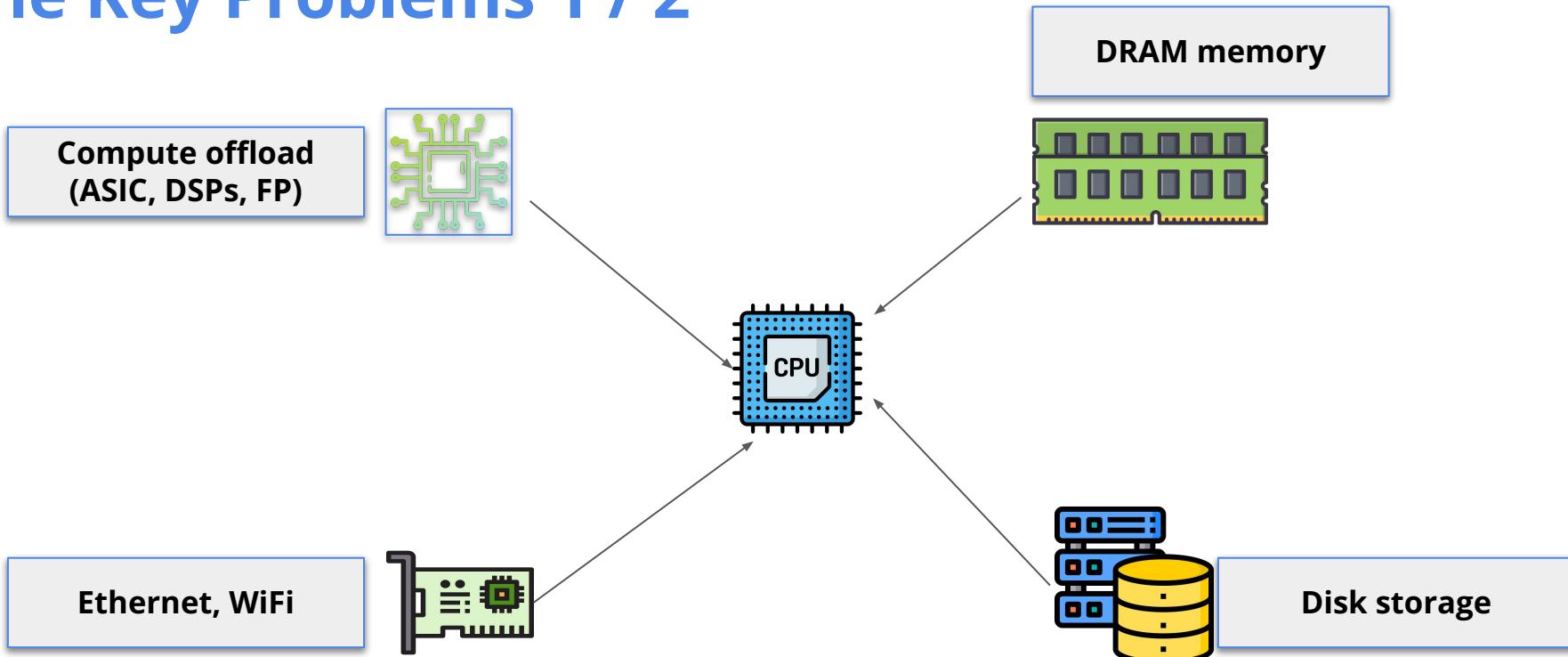
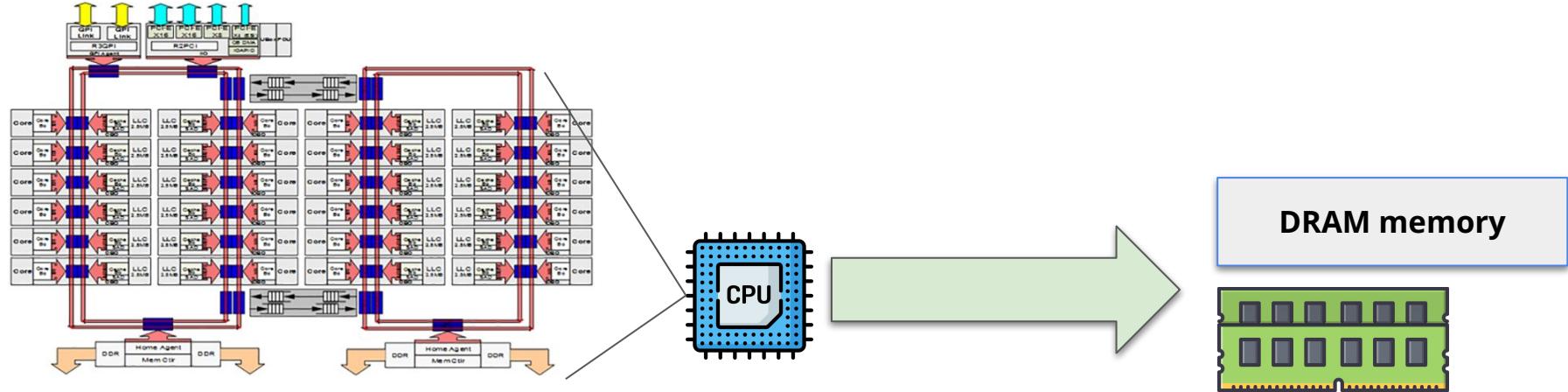


Figure 1.4
Hardware organization
of a typical system.
CPU: Central Processing Unit,
ALU: Arithmetic/Logic
Unit, PC: Program counter,
USB: Universal Serial Bus.

The Key Problems 1 / 2

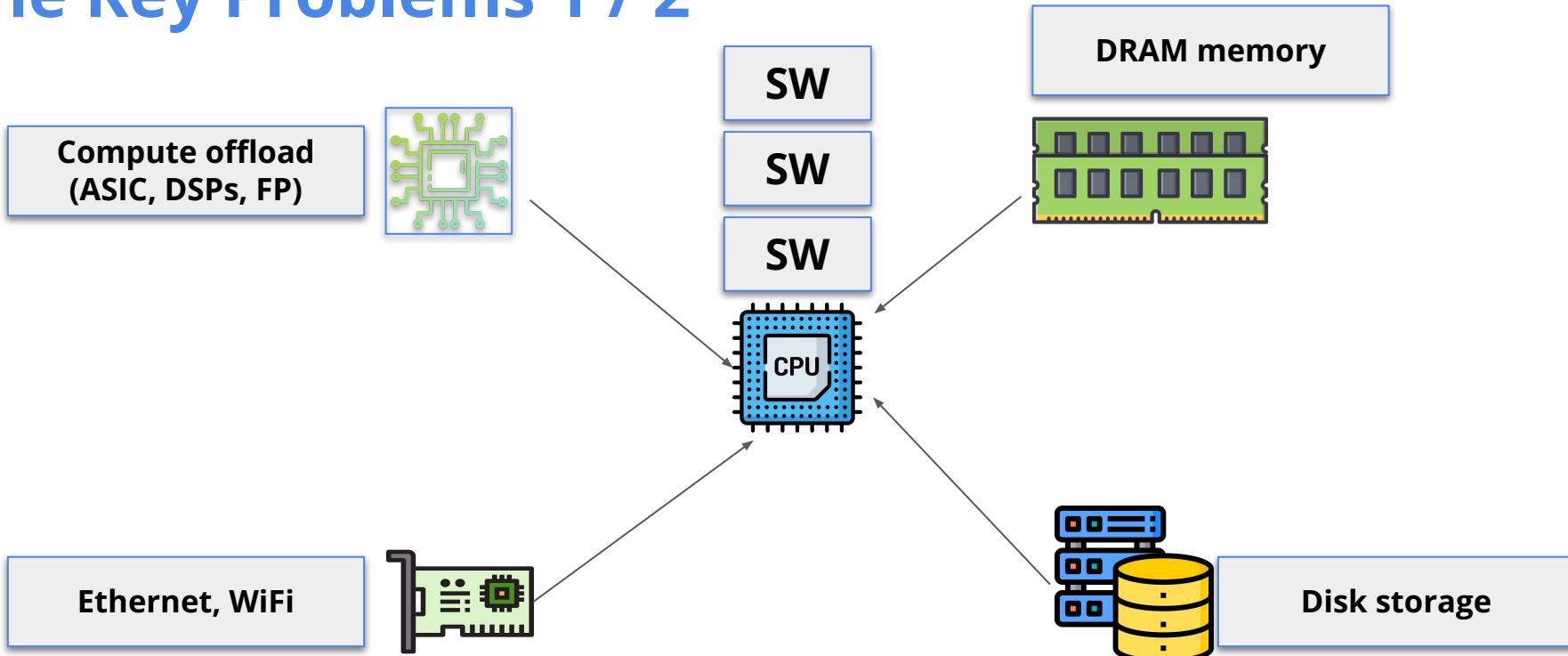


The Key Problems 1 / 2



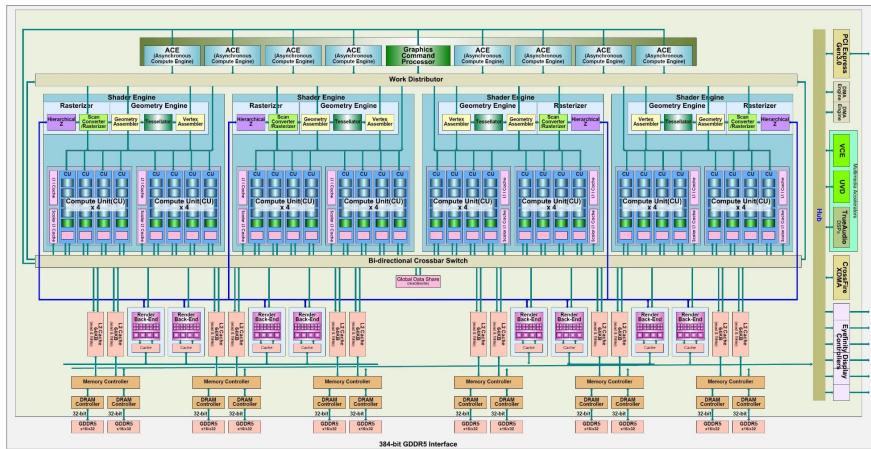
**CPU cache management is non-trivial and complex
(even with same/similar homogeneous CPU architectures)**

The Key Problems 1 / 2

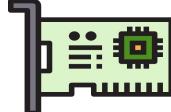


The Key Problems 1 / 2

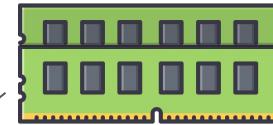
AMD Tonga Full Configuration Overview



Ethernet, WiFi



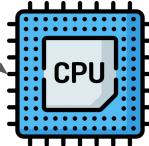
DRAM memory



SW

SW

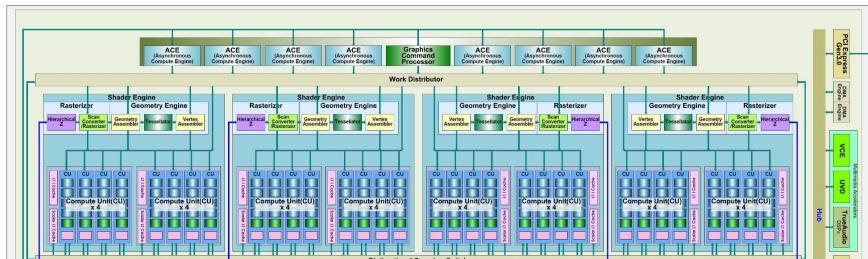
SW



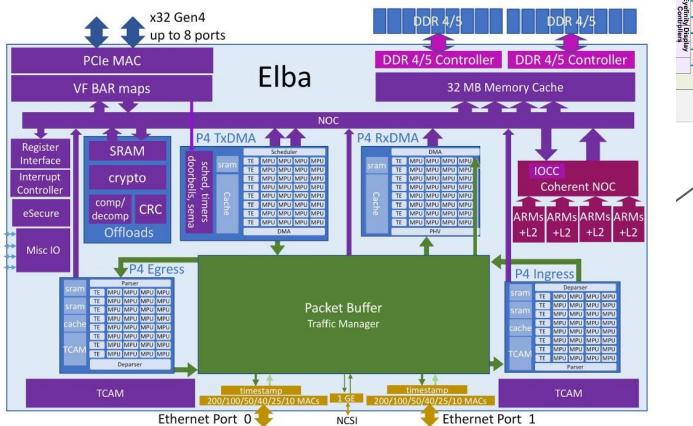
Disk storage

The Key Problems 1 / 2

AMD Tonga Full Configuration Overview

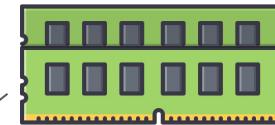


Elba (7 nm) Block Diagram



<https://www.servethehome.com/what-is-a-dpu-a-data-processing-unit-quick-primer/>

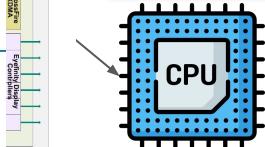
DRAM memory



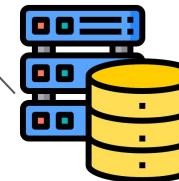
SW

SW

SW

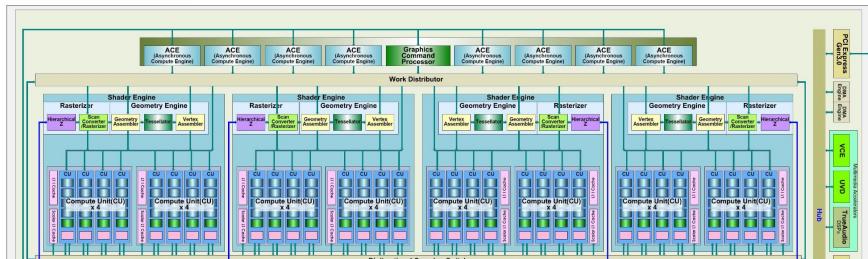


Disk storage

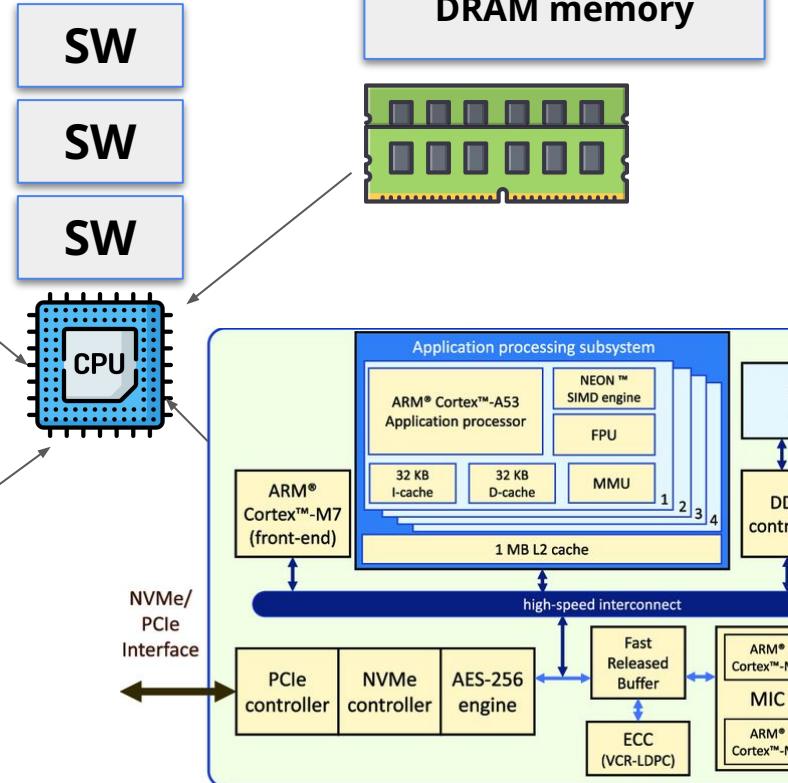
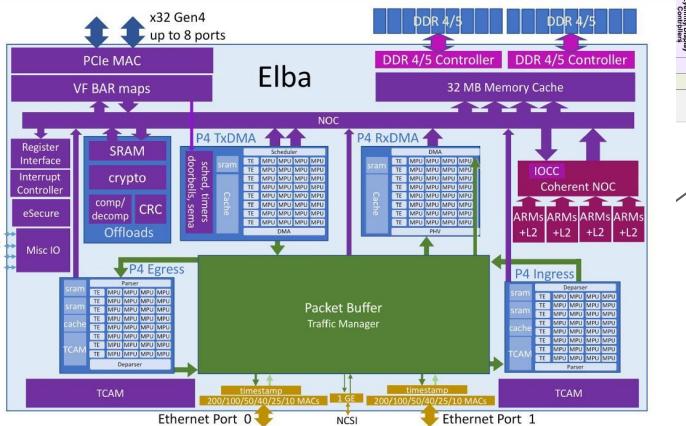


The Key Problems 1 / 2

NVIDIA Tonga Full Configuration Overview

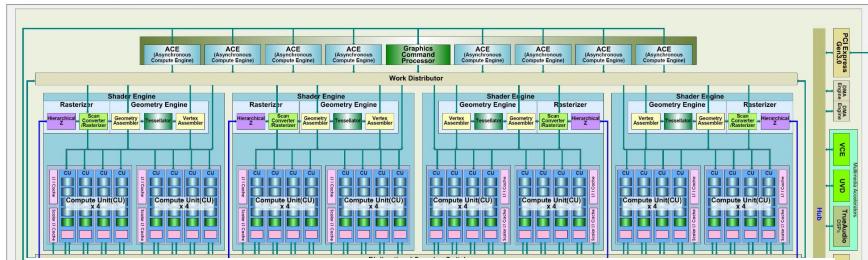


Elba (7 nm) Block Diagram

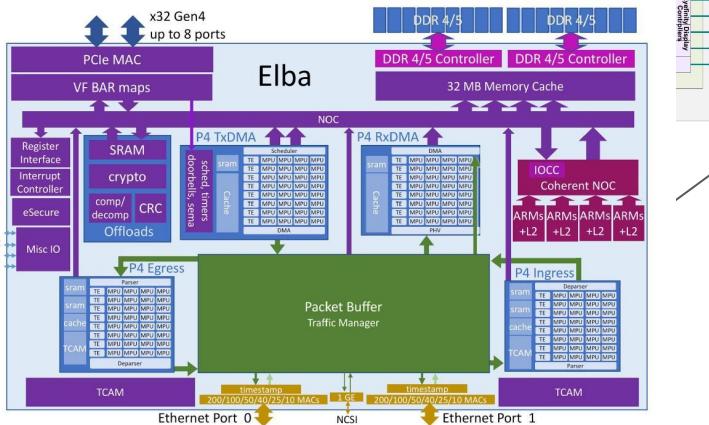


The Key Problems 1 / 2

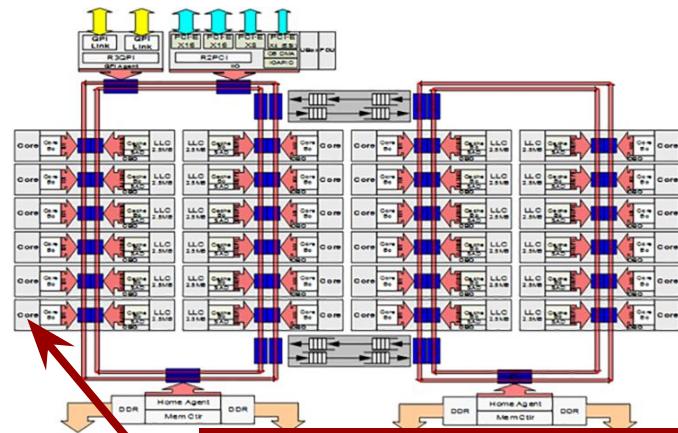
NVIDIA Tonga Full Configuration Overview



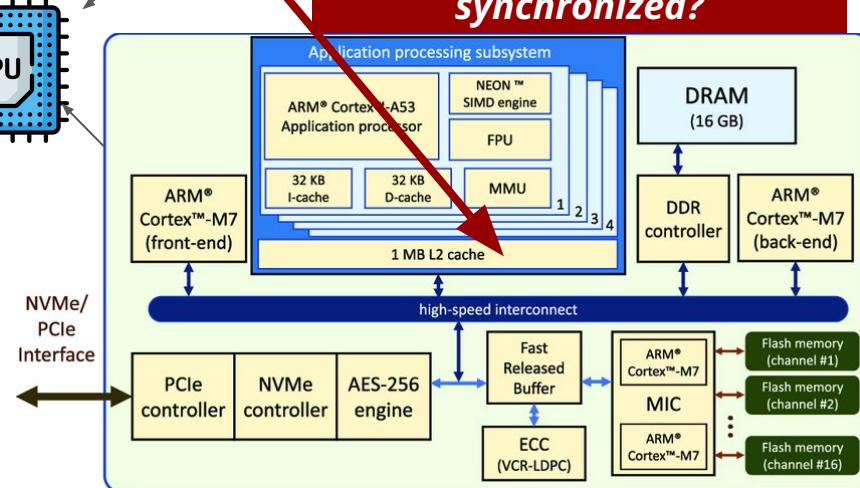
Elba (7 nm) Block Diagram



SW
SW
SW



How are these two caches synchronized?



The Key Problems 1 / 2

Elba

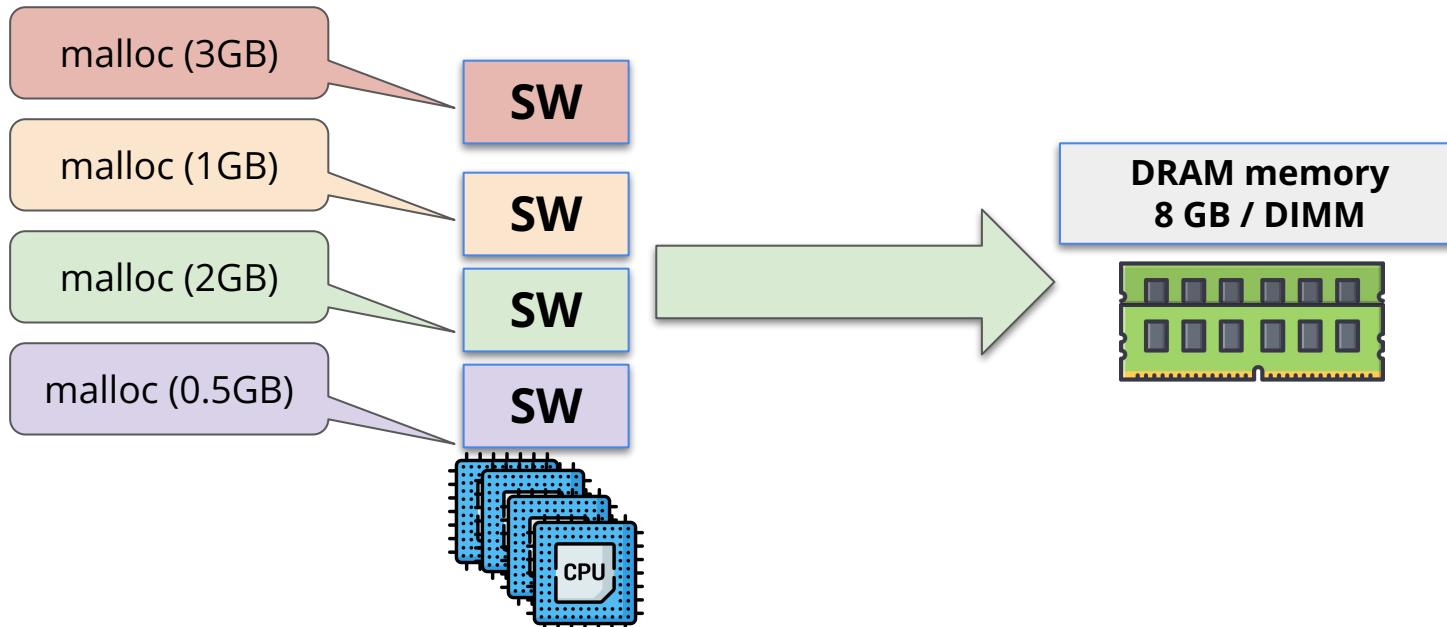
These accelerators can have :

- Compute elements (specialized - FPGA, or general - ARM)
- Memory elements
- Storage chips
- Multi-level caches
- Outside connectivity

Who manages “coherency”, “data flow”, “configuration”, “management” of memories/caches/devices here? Software, hardware? Performance?

Cost of development of new APIs, protocols?

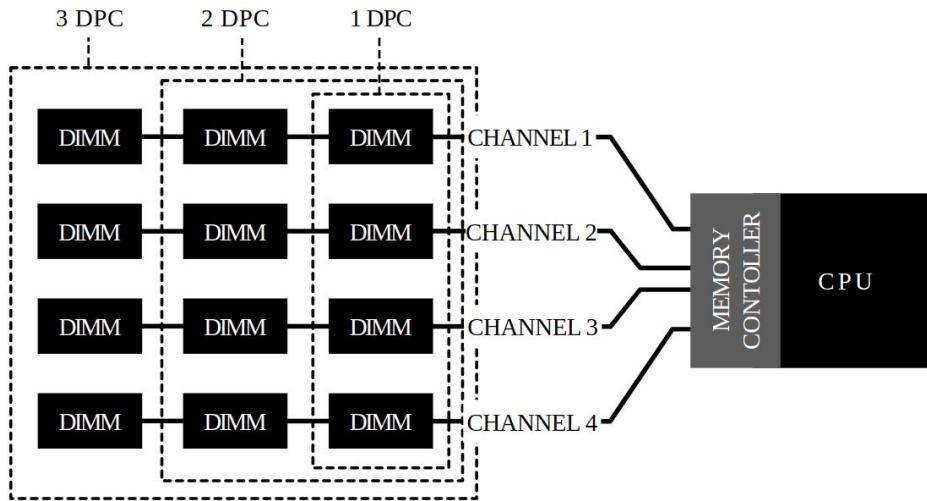
The Key Problems 2 / 2 : CPU - DRAM Coupling



- What happens to the remaining 1.5 GB DRAM?
- Do applications use all the DRAM what they ask for?

The Key Problems 2 / 2 : CPU - DRAM Coupling

1. Can not mix and match different DRAM technologies and generations
2. More performance means more capacity (need to buy more DIMMs)
3. Limit to how much DRAM can be packed in a single machine



Very close coupling of CPU-DRAM (1) DRAM technology; (2) Density, capacity; and (3) Performance

The Key Problems 2 / 2 : CPU - DRAM Coupling

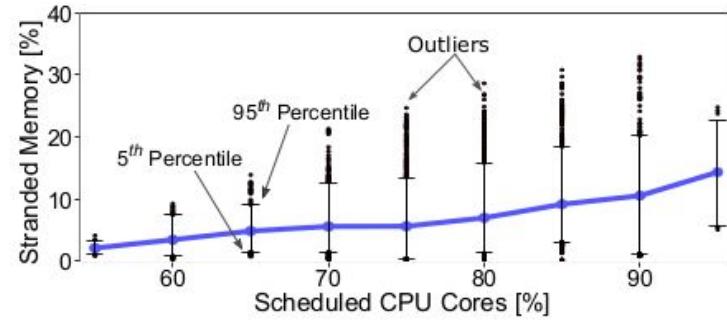
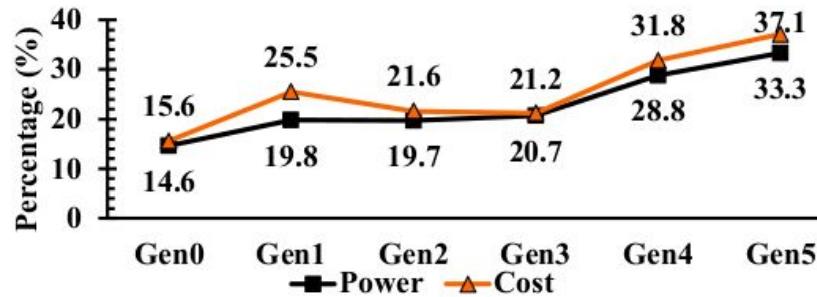


Figure 2: Memory stranding (§3.1). Stranding increases significantly as more CPU cores are scheduled. Error bars indicate the 5th and 95th percentiles (outliers in dots).

DRAM is a big power and cost factor in data center (up to ~40%)
A big part can remain underutilized
Azure with VMs : on average ~10% (but as high as ~30%)

The Key Problems 2 / 2 : CPU - DRAM Coupling

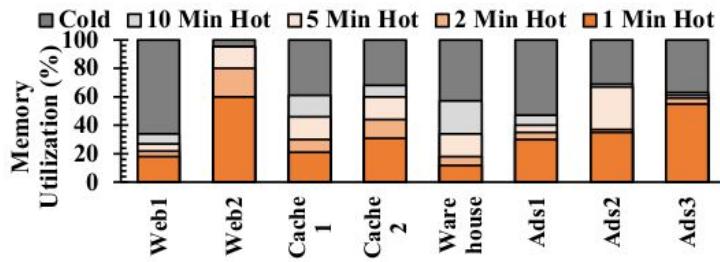


Figure 7: Application memory usage over last N mins.

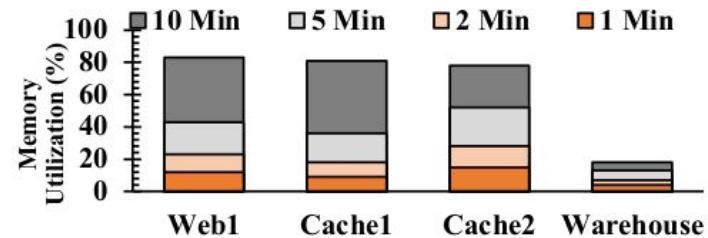


Figure 11: Fraction of pages re-accessed at different intervals.

Not all pages allocation are used uniformly:

- (1) Only a small fraction of memory is accessed in 1-2 minutes window
- (2) For Web, almost 80% of the pages are re-accessed within a ten-minute interval but for warehouse it is 20%.

(do they all have to be in DRAM?)

Summary Problem

There has to be a better way to

- Manage non-CPU memories and caches (accelerators)
 - Manage CPU-attached memories (allocation, disaggregate from the CPU)
 - Expand beyond the CPU-attached memories
-
- + **Think of non-volatile memories ...**
- Persistent memories
 - Fast storage

Solution : **Compute Express Link (CXL)** (*the last protocol we will ever need*)

Computer Express Link (CXL)

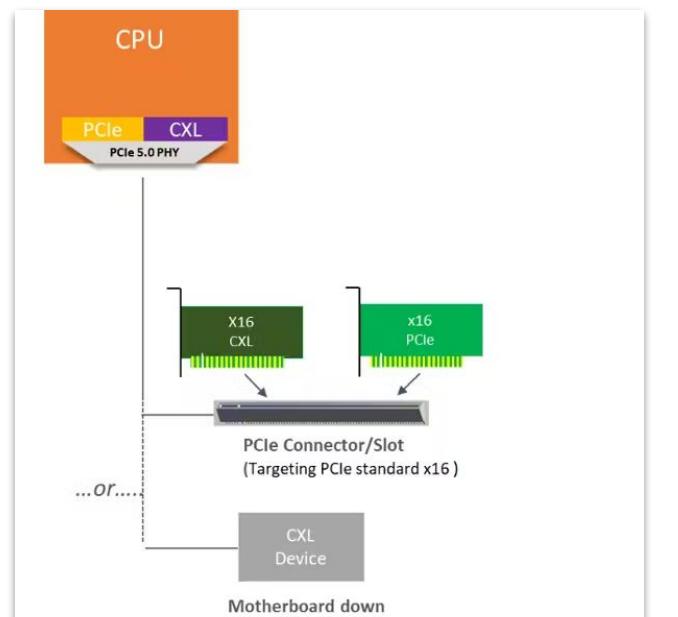
A cache coherent Interconnect between

- The CPU
- Accelerators
- Memory expansion cards

Asymmetric protocol

A set of standardized protocols defined on the top of PCIe 5.0 (PHY)

- Runs in the standard PCIe slots
- 32 GT/s, or 4 GB/lane \Rightarrow x32 card = **128 GB/sec**
- *Latencies approaching the NUMA CPU (with v6.0)*



PCIe Specification	Data Rate per Lane (GT/s)	Encoding	x16 Unidirectional Bandwidth (GB/s)	Specification Ratification Year
1.x	2.5	8b/10b	4	2003
2.x	5	8b/10b	8	2007
3.x	8	128b/130b	15.75	2010
4.0	16	128b/130b	31.5	2017
5.0	32	128b/130b	63	2019
6.0	64	PAM4/FLIT	128	2022

<https://www.electronicdesign.com/technologies/embedded/article/21162617/cxl-coherency-memory-and-io-semantics-on-pcie-infrastructure>

<https://www.xda-developers.com/pcie-5/>

<https://www.rambus.com/blogs/pcie-6/>

Three CXL Protocols

CXL.io

- Mandatory for all hosts, and CXL supported devices
- Discovery, enumerations, capabilities (DMA, interrupts, IOV), and host physical address configuration
- Same in spirit to what any basic PCIe device would support

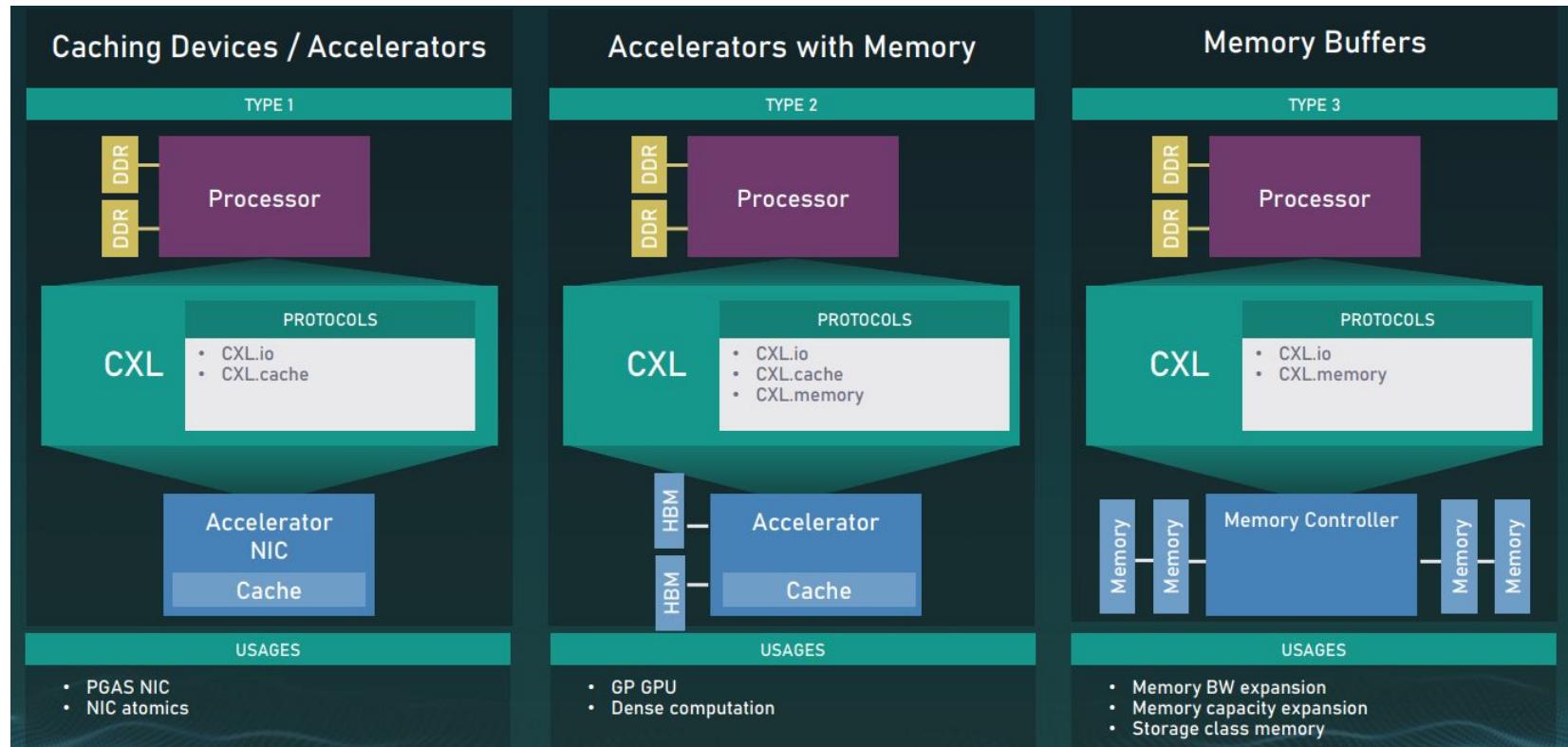
CXL.mem

- Enables (only) CPU to access device/accelerator memory in a cacheable manner
- Useful in DRAM expansion
- Device is not initiating any communication

CXL.cache

- The same as CXL.mem, but now devices can also access the CPU memory/caches
- Additional commands/requests for maintaining coherence among all copies

Three Classes of Devices



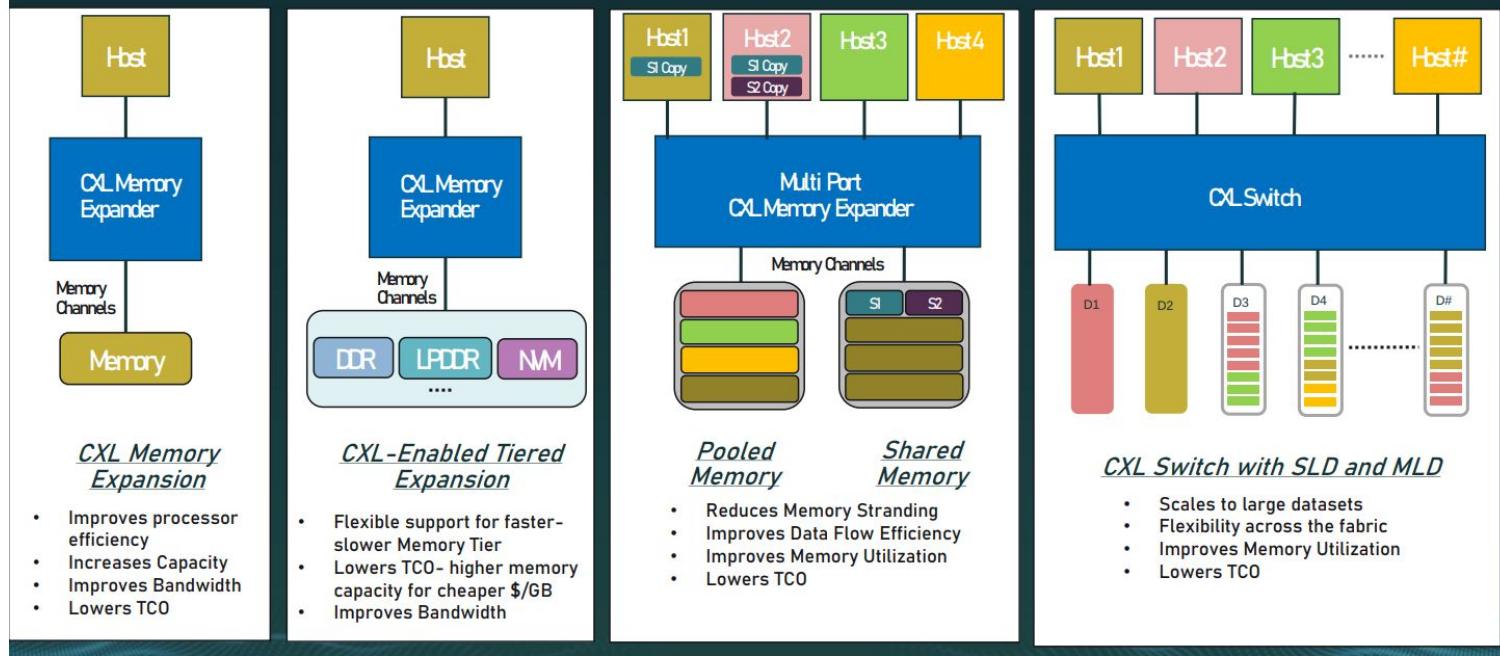
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Three Generations of CXL Protocols

Features	CXL 1.0 / 1.1	CXL 2.0	CXL 3.0
Release date	2019	2020	1H 2022
Max link rate	32GTs	32GTs	64GTs
Flit 68 byte (up to 32 GTs)	✓	✓	✓
Flit 256 byte (up to 64 GTs)			✓
Type 1, Type 2 and Type 3 Devices	✓	✓	✓
Memory Pooling w/ MLDs		✓	✓
Global Persistent Flush		✓	✓
CXL IDE		✓	✓
Switching (Single-level)		✓	✓
Switching (Multi-level)			✓
Direct memory access for peer-to-peer			✓
Enhanced coherency (256 byte flit)			✓
Memory sharing (256 byte flit)			✓
Multiple Type 1/Type 2 devices per root port			✓
Fabric capabilities (256 byte flit)			✓

- CXL 3.0: Enabling composable systems with expanded fabric capabilities, October 6, 2022,
https://www.computeexpresslink.org/_files/ugd/0c1418_998df4f459734f319e7a12cc2163b943.pdf
- Good overview, https://community.cadence.com/cadence_blogs/8/b/breakfast-bytes/posts/hot-chips-cxl-tutorial

Evolving Use Cases

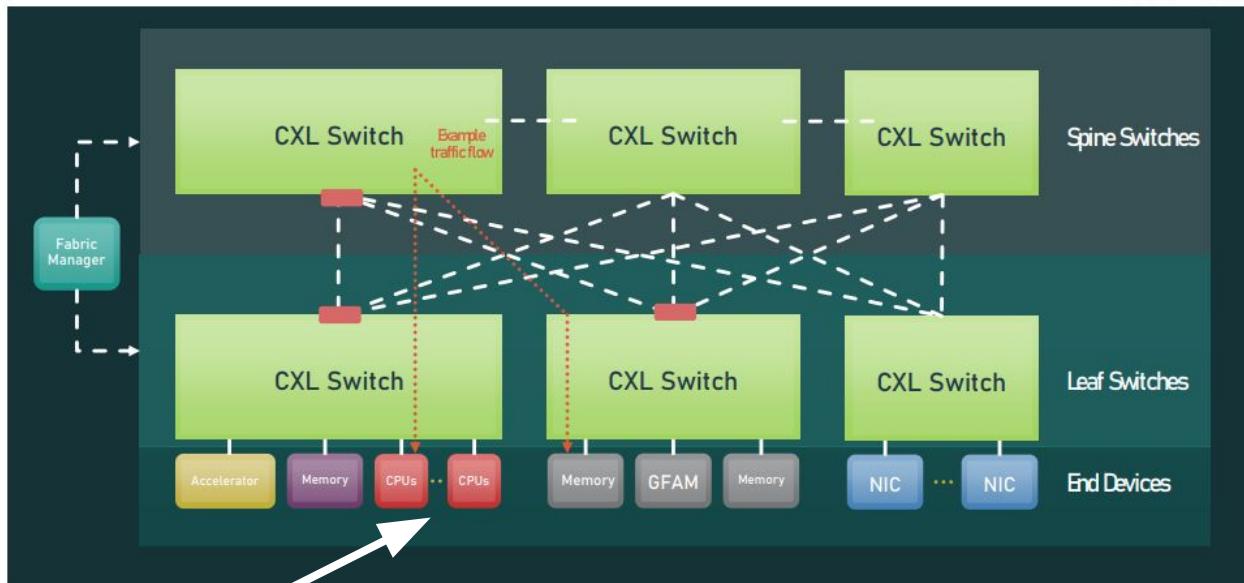


What can we do? Expansion of DRAM, CPU-Memory Decoupling (multiple generation of devices), Memory Pooling and sharing, Single Logical Device (SLD → Exclusive to one CXL root) to Multiple Logical Device (MLD, connected to multiple CXL roots), Memory hot swapping ...

A look into the CXL device ecosystem and the evolution of CXL use cases,

https://0c141887-fbe4-4ec3-be17-adc8d70d3922.usrfiles.com/ugd/0c1418_037d4ba31f4b44cf9fc37f5b36ae4d6.pdf

Design a Distributed Cluster Running CXL



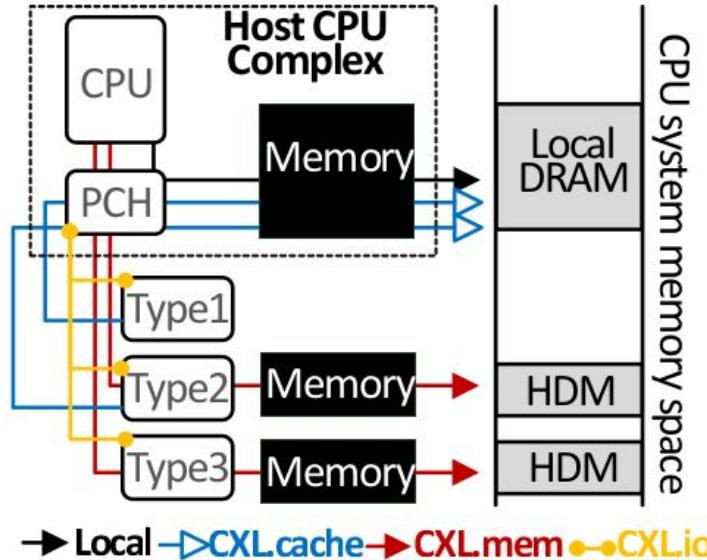
CXL 3.0 Fabric Architecture

- Interconnected Spine Switch System
- Leaf Switch NIC Enclosure
- Leaf Switch CPU Enclosure
- Leaf Switch Accelerator Enclosure
- Leaf Switch Memory Enclosure

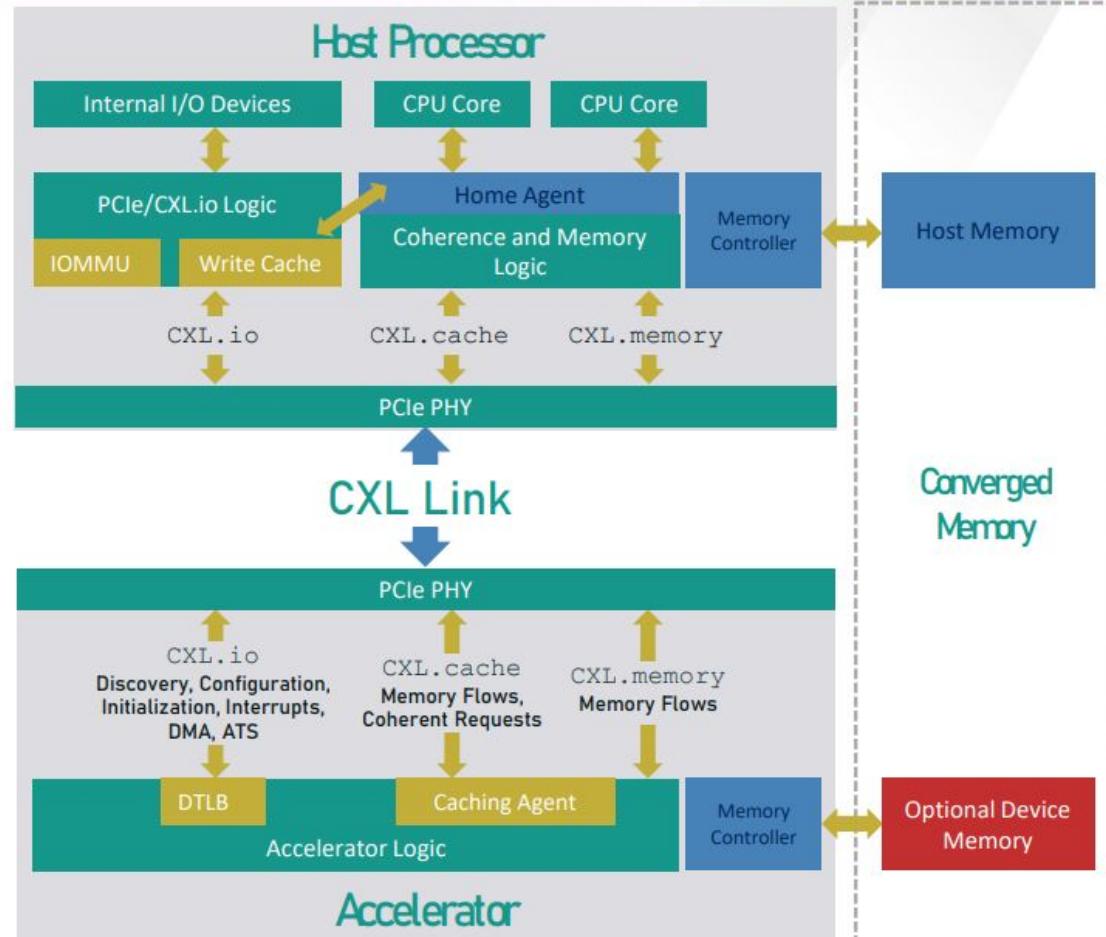


Multiple type of devices, Global Fabric Attached Memory (GFAM)

CXL.mem



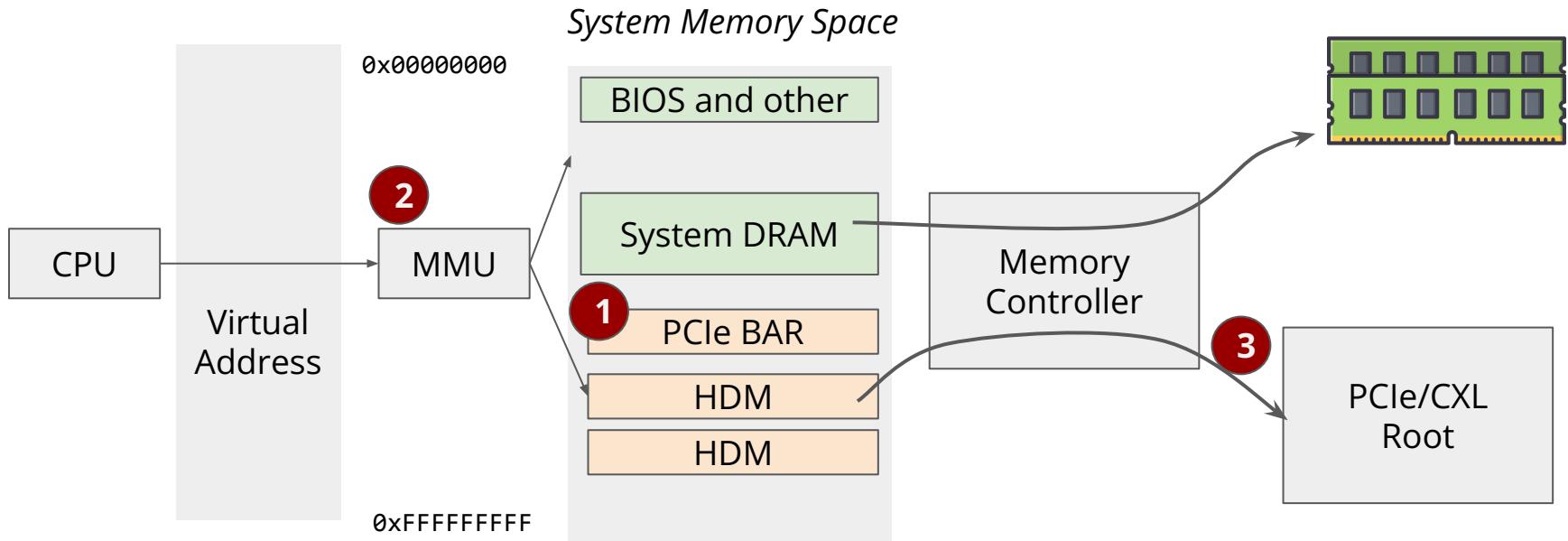
→ Local → CXLcache → CXLmem → CXLio



https://www.computeexpresslink.org/_files/ugd/0c1418_998df4f459734f319e7a12cc2163b943.pdf

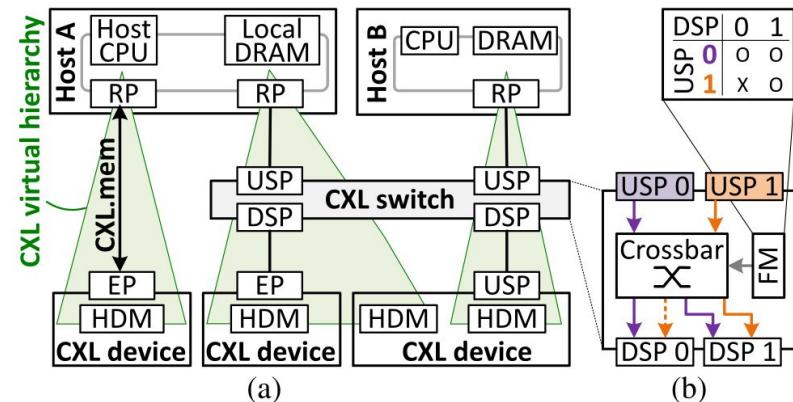
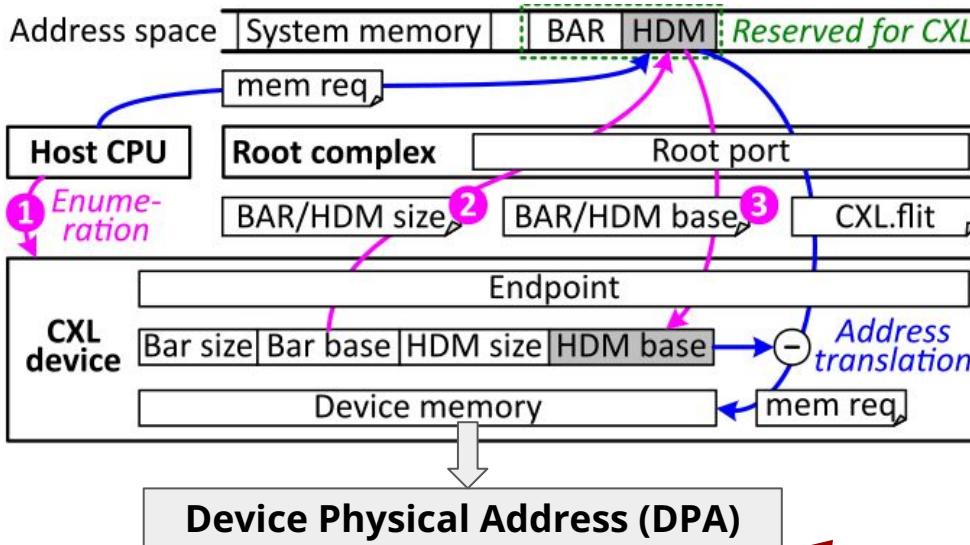
Hello bytes, bye blocks: PCIe storage meets compute express link for memory expansion (CXL-SSD). <https://doi.org/10.1145/3538643.3539745>

CXL.mem Expansion Device Example



1. PCIe enumeration and BAR mapping with, Host-Managed Device Memory (HDM) areas
2. Setup MMU and allocate the DRAM physical address from this area (software support)
3. Access happens, and the request is routed to the PCIe/CXL root

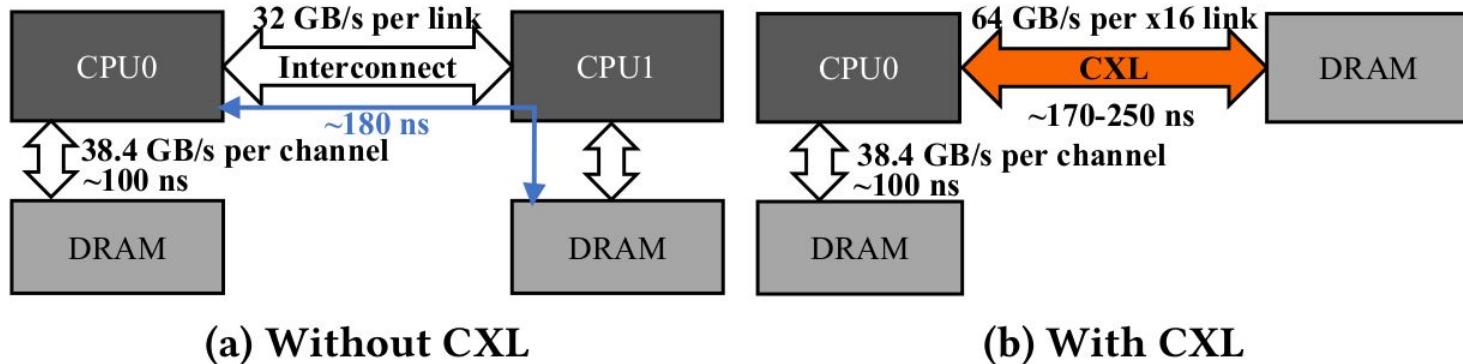
CXL.mem Expansion Device Example



DRAM Translation Layer DTL ;)
See the ISCA'23 reference at the end of the slides

Multiple configurations (1) striping across multiple devices, ports, roots; (2) allocation units...

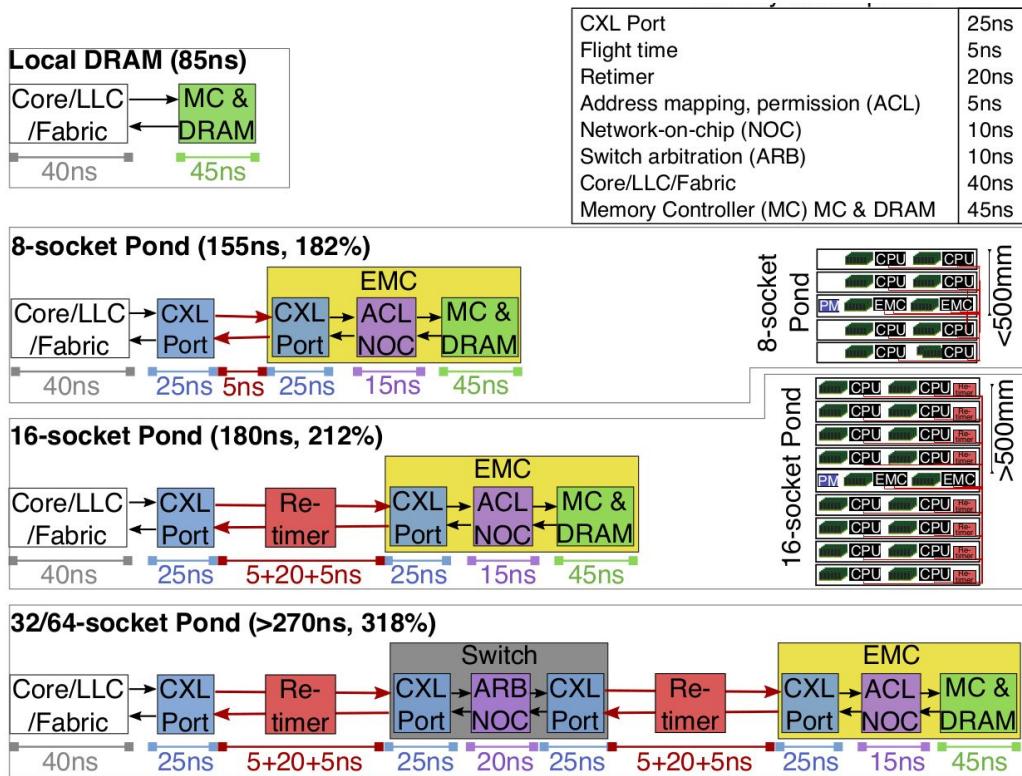
Transparent Page Placement (TPP)



PCIe 6.0 latencies and bandwidth are approaching access to a remote NUMA CPU socket

Challenge: How to profile pages (at low-overheads) and put them in the right storage level in the CXL-enabled memory hierarchy

POND (ASPLOS'23): How to Disaggregate VM Memory

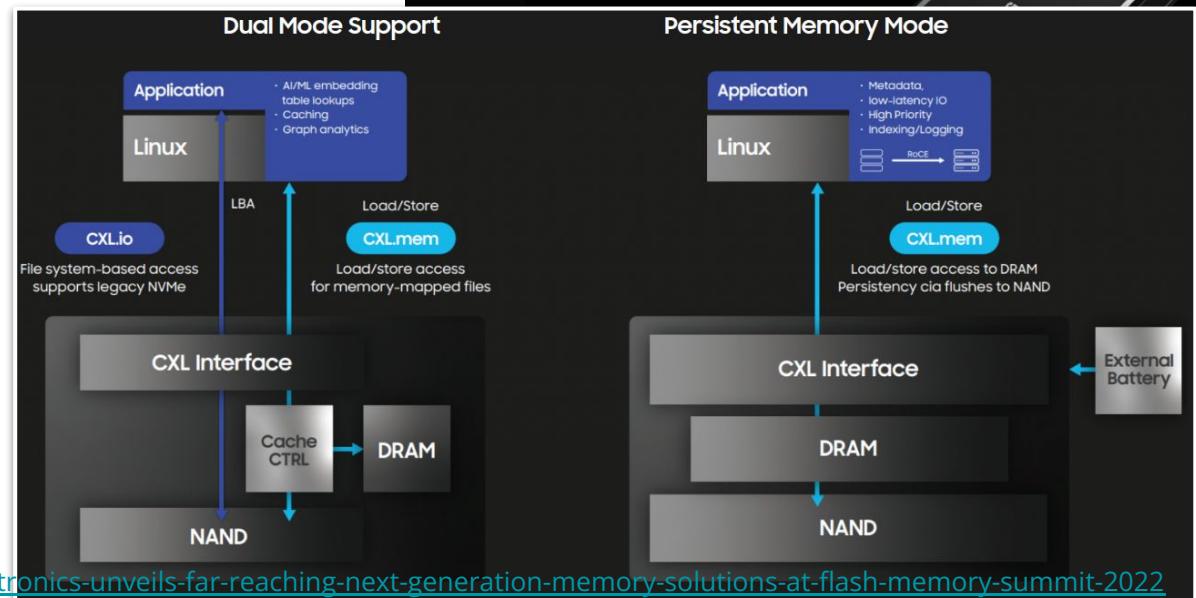
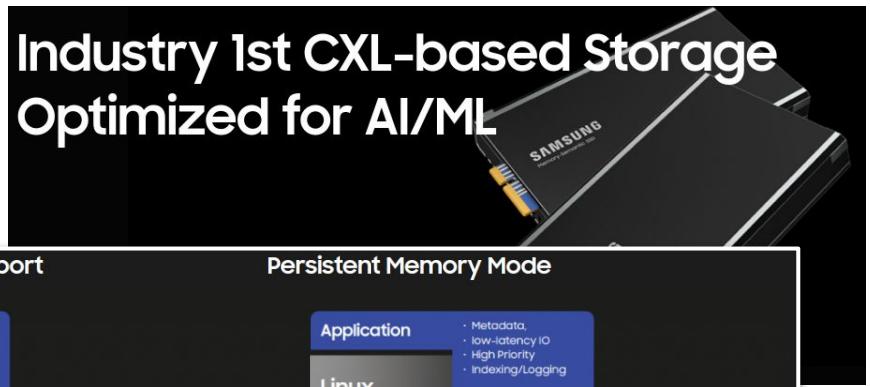


Where does Storage Come into the Play?

Any device can implement the CXL protocol

- Use SSD as large capacity RAM
- Byte*-addressable
- Persistent

*64B addressable



Emerging work: Quantifying and Hiding Flash Latencies

Hello Bytes, Bye Blocks: PCIe Storage Meets Compute Express Link for Memory Expansion (CXL-SSD)

Myoungsoo Jung
Computer Architecture and Memory Systems Laboratory,
Korea Advanced Institute of Science and Technology (KAIST)
<http://camelab.org>

ABSTRACT

Compute express link (CXL) is the first open multi-protocol method to support cache coherent interconnect for different processors, accelerators, and memory device types. Even though CXL leverages data coherency mainly between CPU memory devices and memory on accelerated devices, we argue that it can also be useful to refine existing block storage as cost-efficient, large-scale working memory. Specifically, this paper examines three different sub-protocols of CXL from a memory expander viewpoint. It then suggests which device type can be the best option for PCIe storage to bridge its block semantics to memory-compatible, byte semantics. We then discuss how to integrate a storage-integrated memory expander into an existing system and speculate how much effect it does have on the system performance. Lastly, we visit various CXL network topologies and explore a new opportunity to efficiently manage the storage-integrated, CXL-based memory expansion.

1 INTRODUCTION

Cache coherence interconnects are recently emerged to integrate different CPUs, accelerators, and memory components into a heterogeneous, single computing domain. Specifically, the interconnect technologies maintain data coherency between CPU memory and private memory attached to devices, defining a new type of globally shared memory and network space. While there have been several efforts to coherently connect different hardware components, such as Gen-Z [1] and CIXX [2], *Compute Express Link* (CXL) is the first open interconnect protocol supporting various types of processors and device endpoints [3]. CXL has absorbed Gen-Z [4] and has become one of the most promising interconnect interfaces thanks to its high-speed coherence control and full compatibility with the existing bus standard. A broad spectrum

Even though CXL can be the most promising interface for the block storage in getting closer to CPU, it is non-trivial to speculate how much effect a storage-integrated memory expander does have on system performance. As there is no CPU and fabric for CXL yet, it is also unclear for the storage designers and system architects to see how CXL-enabled storage can be implemented and interact with CPU. To answer this, we discuss what a PCIe storage device needs to change, how it can be connected to the host over CXL, and how users can access the device through load/store instructions (§4). We then project the performance of the storage-integrated memory expander by prototyping CXL agents and controllers in different FPGA nodes, all connected by a PCIe network.

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ACM ISBN 978-1-4503-9999-7/23/07...\$15.00
<https://doi.org/10.1145/359864.359745>

Cache in Hand: Expander-Driven CXL Prefetcher for Next Generation CXL-SSDs

Miryeong Kwon^{*†}, Sangwon Lee^{*†}, Myoungsoo Jung^{*†}
*Computer Architecture and Memory Systems Laboratory, KAIST
†Pannnesia, inc.

ABSTRACT

Integrating compute express link (CXL) with SSDs allows scalable access to large memory but has speeds than DRAMs. While EXPAND, an expander-driven CXL prefetcher that offloads last-level cache (LLC) prefetching from host CPU to CXL-SSDs. EXPAND uses a heterogeneous prediction algorithm for prefetching and ensures data consistency with CXL.mem's back-invalidation. We examine prefetch timeliness for accurate latency estimation. EXPAND, being aware of CXL multi-tiered switching, provides end-to-end latency for each CXL-SSD and precise prefetch timeliness estimations. Our method reduces CXL-SSD reliance and enables direct host cache access for most data. EXPAND enhances graph application performance by 3.5x, surpassing CXL-SSD pools with diverse prefetching strategies.

1 INTRODUCTION

Compute Express Link (CXL) is receiving considerable attention as an emerging interface that separates memory resources from computing servers, allowing users to access large-capacity memory scalably. In terms of capacity, storage class memory (SCM) technologies such as PRAM [1], Z-NAND [2], and XL-Flash [3] offer greater advantages over DRAMs. As a result, both industry and academia strive to produce byte-addressable solid-state drives (SSDs) using the CXL protocol and SCM's memory instruction semantics. For instance, our method integrates CXL into Optane SSDs for hierarchical memory expansion, while several proof-of-concepts (PoCs) employ new flash like Z-NAND and XL-Flash to develop CXL-SSDs [4–6].

Even though CXL can be the most promising interface for the block storage in getting closer to CPU, it is non-trivial to speculate how much effect a storage-integrated memory expander does have on system performance. As there is no CPU and fabric for CXL yet, it is also unclear for the storage designers and system architects to see how CXL-enabled storage can be implemented and interact with CPU. To answer this, we discuss what a PCIe storage device needs to change, how it can be connected to the host over CXL, and how users can access the device through load/store instructions (§4). We then project the performance of the storage-integrated memory expander by prototyping CXL agents and controllers in different FPGA nodes, all connected by a PCIe network.

Overcoming the Memory Wall with CXL-Enabled SSDs

Shao-Peng Yang
Syracuse University
Minjae Kim
DGIST
Sanghyun Nam
Soongsil University
Juhyung Park
DGIST
Jin-yong Choi
FADU Inc.

Eeye Hyun Nam
FADU Inc.
Eunji Lee
Soongsil University
Sungjin Lee
DGIST
Bryan S. Kim
Syracuse University

Abstract

This paper investigates the feasibility of using inexpensive flash memory on new interconnect technologies such as CXL (Compute Express Link) to overcome the memory wall. We explore the design space of a CXL-enabled flash device and show that techniques such as caching and prefetching can help mitigate the concerns regarding flash memory's performance and lifetime. We demonstrate using real-world application traces that these techniques enable the CXL device to have an estimated lifetime of at least 3.1 years and serve 68–91% of the memory requests under a microsecond. We analyze the limitations of existing techniques and suggest system-level changes to achieve a DRAM-level performance using flash.

1 Introduction

The growing imbalance between computing power and memory capacity requirement in computing systems has developed into a challenge known as the memory wall [23, 34, 52]. Figure 1, based on the data from Ghoshali et al. [34] and expanded with more recent data [11, 30, 43], illustrates the rapid growth in NLP (natural language processing) models (14.3x per year), which far outpaces that of memory capacity (1.3x per year). The memory wall forces modern data-intensive applications such as databases [8, 10, 14, 20], data analytics [1, 35], and machine learning (ML) [45, 48, 66] to either be aware of their memory usage [61] or implement user-level memory management [66] to avoid expensive page swaps [37, 53]. As a result, overcoming the memory wall in an application-transparent manner is an active research avenue; approaches such as creating an ML-centric system [45, 48, 61], building a memory disaggregation framework [36, 37, 52, 69], and designing new memory architecture [23, 42] are actively pursued.

We question whether it is possible to overcome the memory wall using flash memory — a memory technology that is typically used in storage due to its high density and capacity scaling [59]. While DRAM can only scale to gigabytes in capacity, a flash memory-based solid-state drive (SSD) is

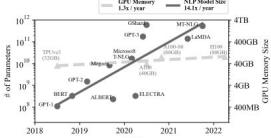


Figure 1: The trend in memory requirements for NLP applications [11, 30, 34, 43]. The number of parameters increases by a factor of 14.1x per year, while the memory capacity in GPUs only grows by a factor of 1.3x every year.

in the terabyte scale [23], a sufficiently large capacity to address the memory wall challenge. The use of flash memory as main memory is enabled by the recent emergence of interconnect technologies such as CXL [1], Gen-Z [7], CECX [2], and OpenCAPI [12], which allow PCIe (Peripheral Component Interconnect Express) devices to be accessed directly by the CPU through load/store instructions. Furthermore, these technologies promise excellent scalability as more PCIe devices can be attached across switches [13] unlike DIMM (Dual Inline Memory Module) used for DRAM.

However, there are three main challenges to using flash memory as CPU-accessible main memory. First, there is a granularity mismatch between memory requests and flash memory. This results in a significant traffic amplification on top of the existing need for indirection in flash [23, 33]; for example, a 64B cache line flush to the CXL-enabled flash would result in 16KB flash memory page read, 64B update, and 16KB flash program to a different location (assuming a 16KB page-level mapping). Second, flash memory is still orders of magnitude slower than DRAM (tens of microseconds vs. tens of nanoseconds) [5, 24]. As a consequence, while the peak data transfer rate between the two technologies is similar [4, 15], the long flash memory latency hinders sustained performance as data-intensive applications can only endure

Putting SSDs with CXL Memory Expander

Which type of device to use? Type-1, Type-2, or Type-3 when using SSD as memory expander?

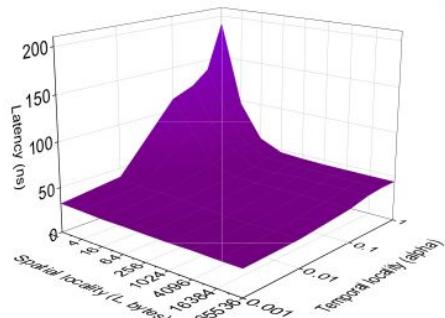
Type-3:

- (*in CXL 1.0, 2.0*): Only one Type-1 or Type-2 device allowed per CXL root, hence Type-3 are more scalable.
- Type-1/2 can be more complex, caches, all load/store requests require checking the cache states of PCIe storage computing complex

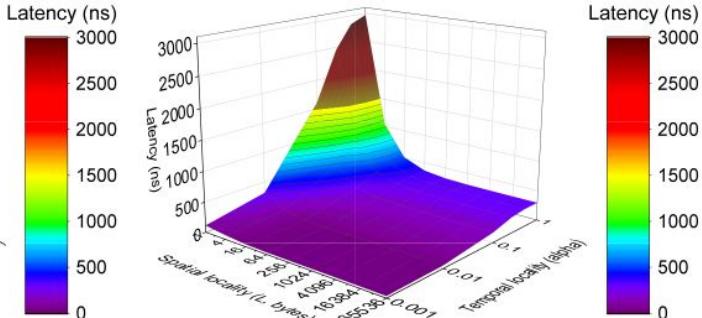


Hence, a Type-3 device type is the ideal CXL device for a “memory expander”

CXL + Flash SSDs: Can Flash do it?



(a) LocalDRAM.



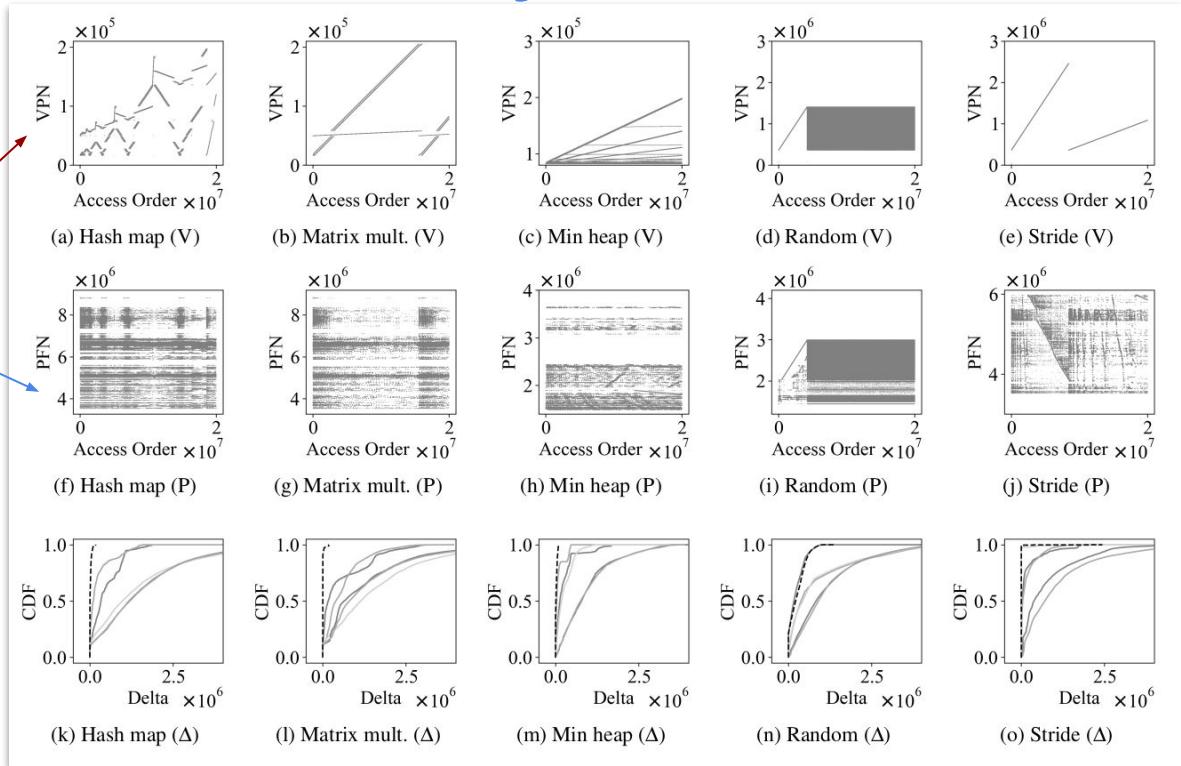
(b) CXL-SSD.

Can we use NAND flash SSDs as memory expander?

- What latencies one get with the granularity mismatch?
 - Cache line : 64B, flash pages : 8-16 KiB
 - DRAM: 100s of nanoseconds, vs. flash in 10-100 microseconds
- What is the access pattern for common workloads?
- Can we optimize latencies in any manner? Prefetching, buffering, caching?
- How about flash P/E limitations? Can it endure small 64B writes?

CXL-Enabled SSDs - Virtual vs. Physical Addresses

⇒ Shows that the access pattern at the **virtual address level** do not correspond to the **physical address level**



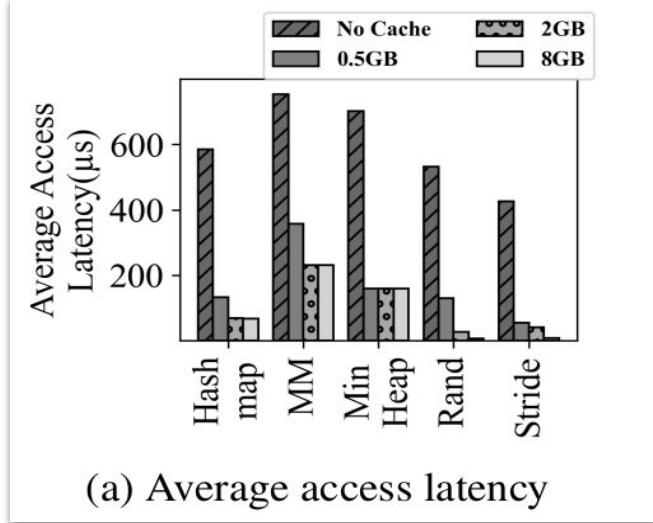
Why?

Just basic prefetching is not effective to hide latencies

Impact of Caching

Inter-arrival time of 64B requests
has a huge impact

- Queuing delays w/o cache
- Small amount of cache helps (0.5GB)



(a) Average access latency

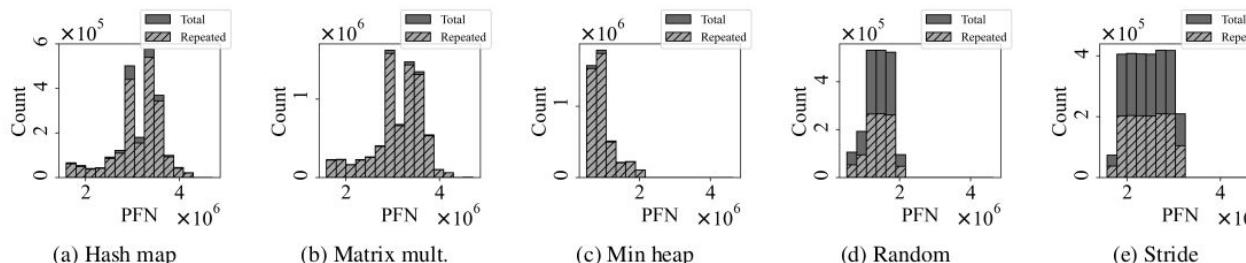
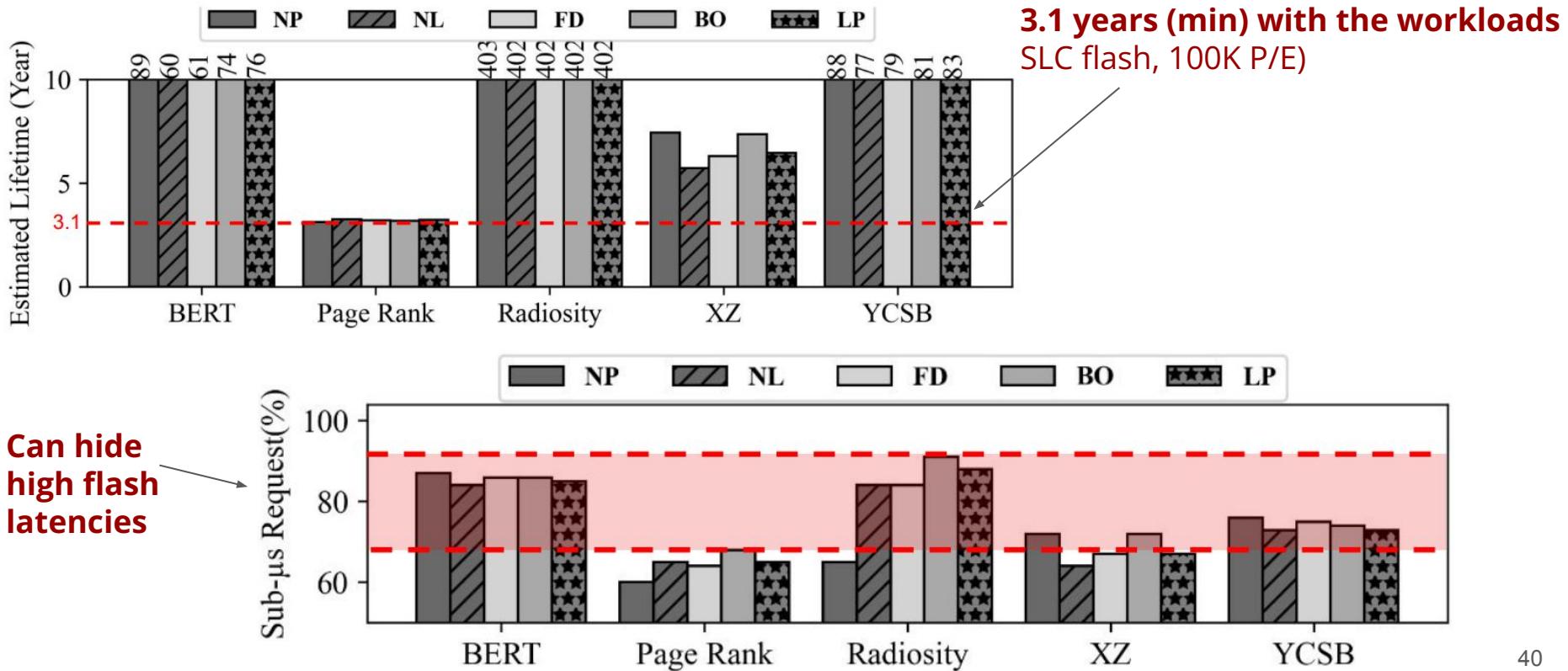


Figure 6: Flash memory read count for physical memory frames. The solid bar represents the total number of reads, while the shaded bar, the number of repeated reads. A repeated read is a read request to an outstanding read request.

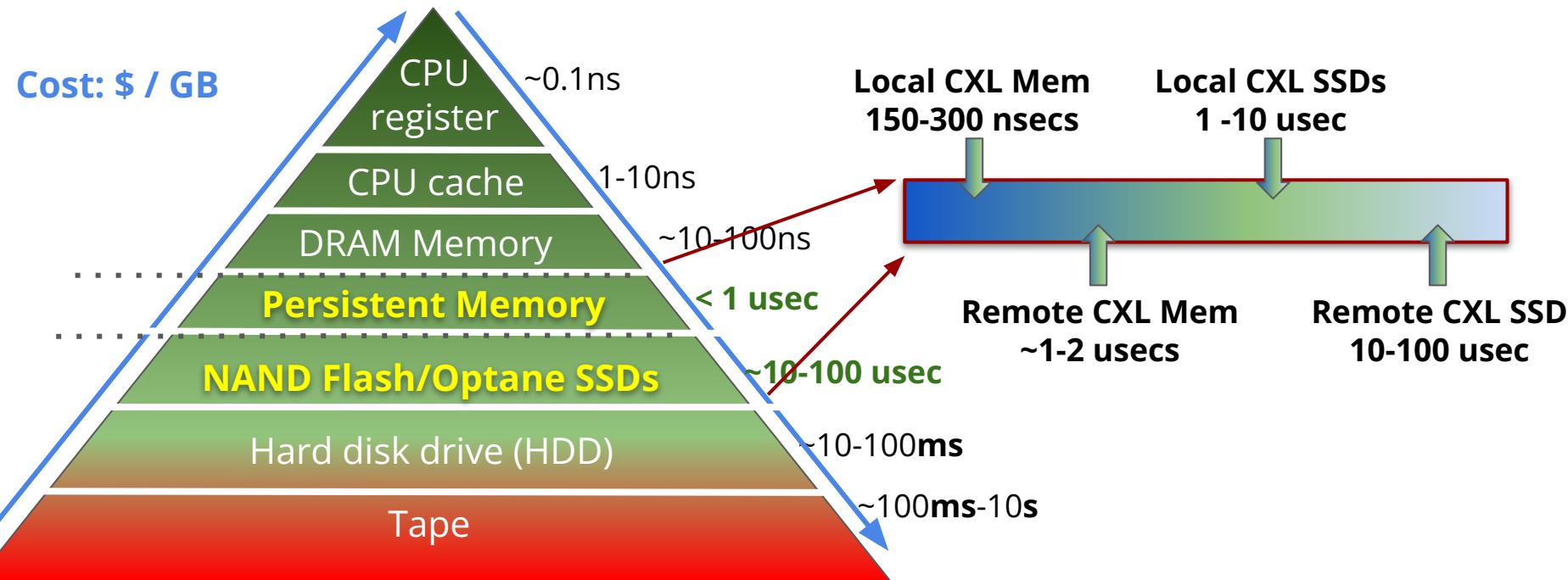
Lots of repeated
accesses for the same
page!

Multiple 64B requests go
into the same flash page
(Keep track of it)

Workload-level Performance

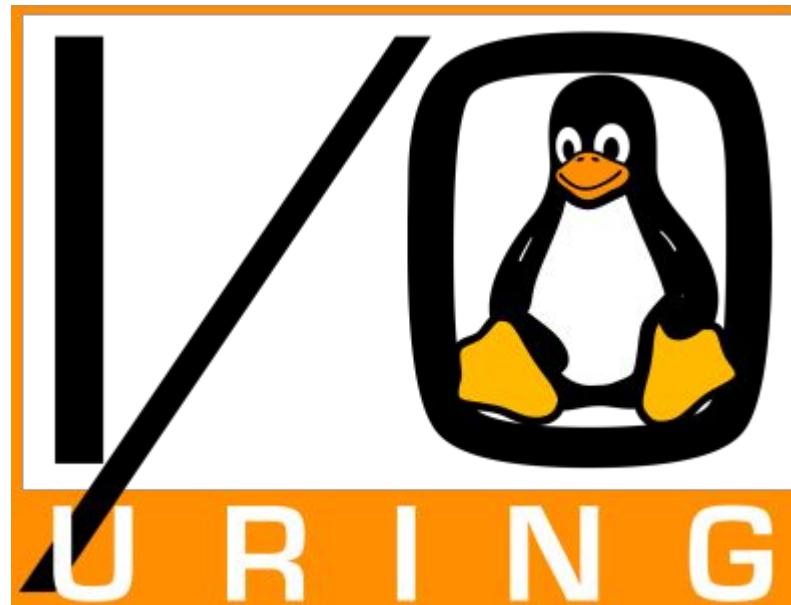


The New(er) Triangle of Storage-Memory Continuum



Instead of discrete steps, it is a continuous spectrum now: Continuum

io_uring : What is it and why you should care?

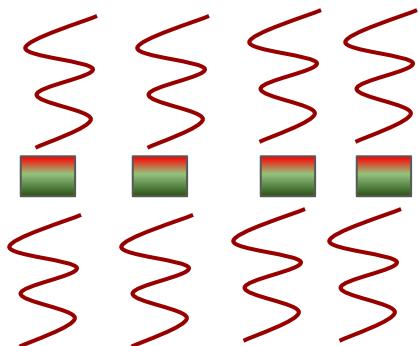


What is io_uring?, https://unixism.net/loti/what_is_io_uring.html

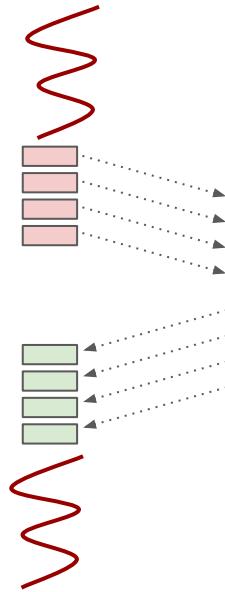
The Long Debate: How to get Concurrency?

Threads versus Events (Asynchronous)

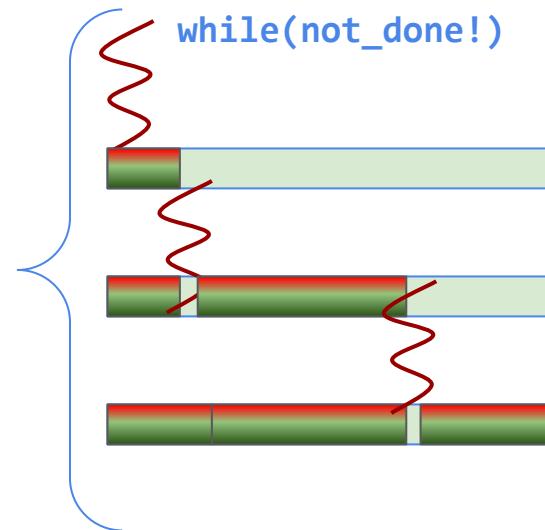
Blocking I/O



Asynchronous I/O



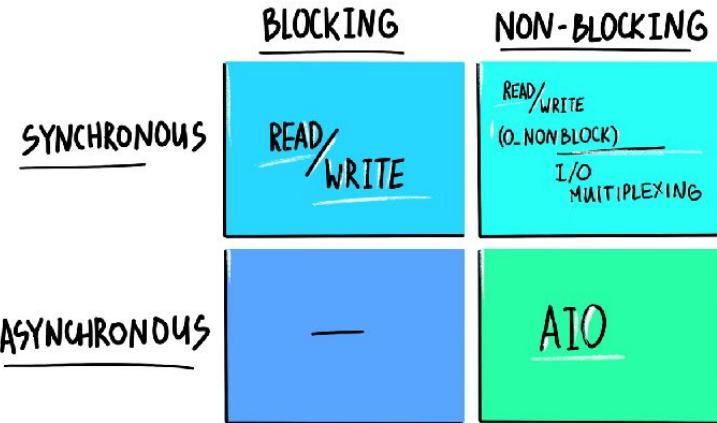
Non-Blocking I/O and **Asynchronous I/O**
are two different things!



Linux I/O Options

Standard POSIX I/O **blocking** read/write calls:

- <https://man7.org/linux/man-pages/man2/read.2.html>
- <https://man7.org/linux/man-pages/man2/write.2.html>



Make I/O calls **non-blocking** : set O_NONBLOCK flag on the file descriptor

- <https://man7.org/linux/man-pages/man2/fcntl.2.html> (o_NONBLOCK)

Asynchronous I/O on Linux : libaio and POSIX AIO

- <https://github.com/littledan/linux-aio>
- Example of how to use libaio: <https://github.com/axboe/fio/blob/master/engines/libaio.c>

AIO Issues

SIGNAL based delivery of completion

- Preemption and context switch
- Needs care for signal-safe function execution

Linux' AIO works truly “asynchronously” under very restricted conditions:

- works only with O_DIRECT modes (alignment, and size restrictions)
- works only when the file's metadata is available
(otherwise blocks until the metadata is fetched)
- can block based on device's queue capacity
- needs to memcpy of I/O metadata (~100 bytes)

Good introduction: https://unixism.net/loti/async_intro.html and https://kernel.dk/io_uring.pdf

On Mon, Jan 11, 2016 at 2:07 PM, Benjamin LaHaise <bcrl@kvack.org> wrote:
> Another blocking operation used by applications that want aio
> functionality is that of opening files that are not resident in memory.
> Using the thread based aio helper, add support for IOCB_CMD_OPENAT.

So I think this is ridiculously ugly.

AIO is a horrible ad-hoc design, with the main excuse being "other, less gifted people, made that design, and we are implementing it for compatibility because database people - who seldom have any shred of taste - actually use it".

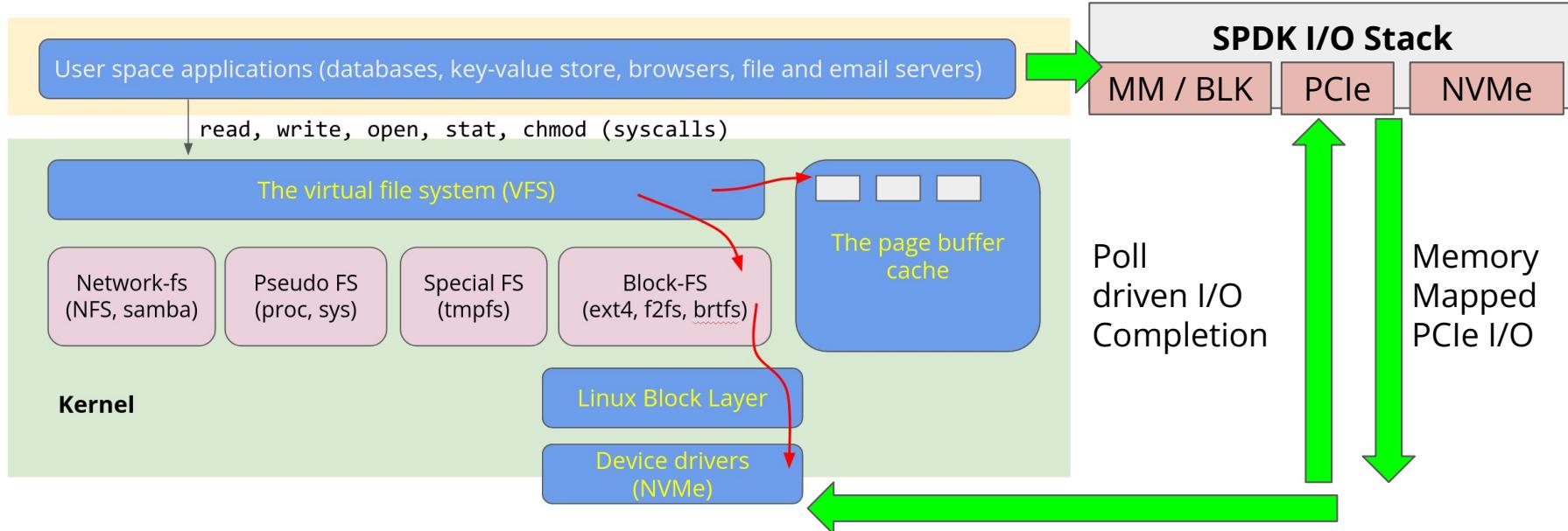
But AIO was always really really ugly.

Cost of these Interfaces

TABLE I: Categories of system-call techniques

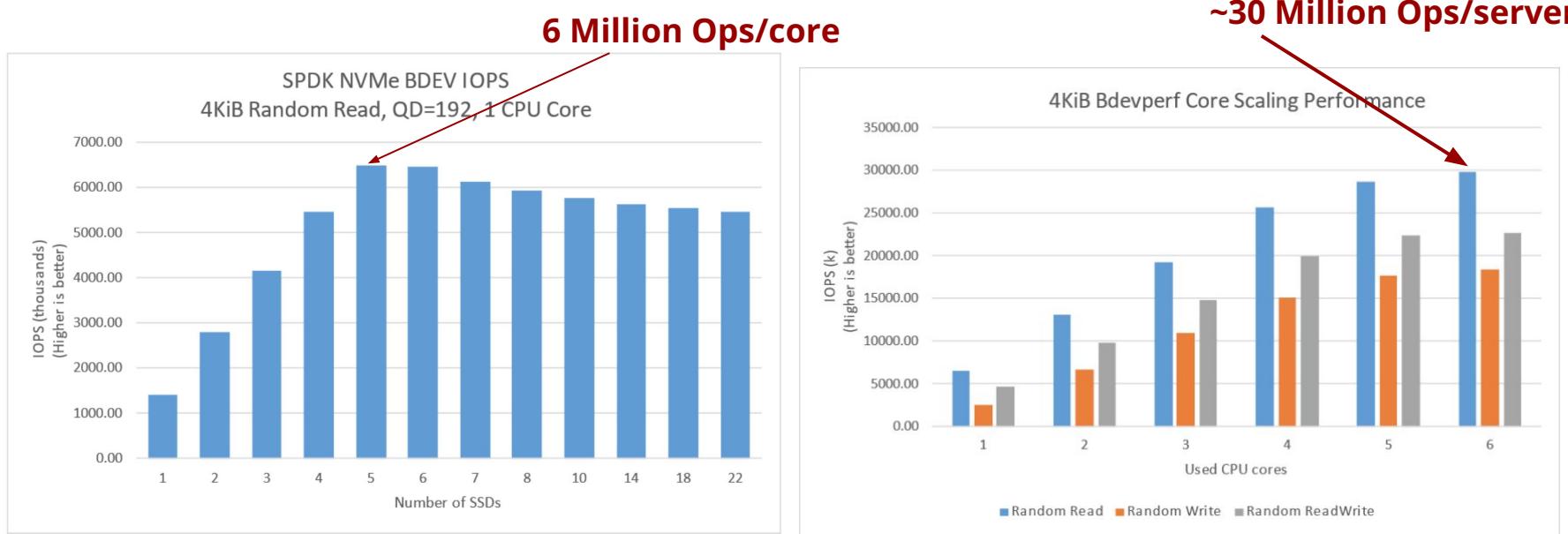
Kind	Mechanism	Examples	per sys request		
			traps	csw	cost[ns]
Sync	Blocking	read(), write()	1	2	955 ± 1069
Sync	Non-Blocking	SOCK_NONBLOCK & epoll()	[1, 3]	[2, 6]	1656 ± 1318
Async	Callback	POSIX AIO [13]	1	2, 3	$6224 \pm 12\,232$
Async	Queue-based	Linux AIO	[0, 2]	[1, 4]	1922 ± 1467

Skip the OS Complexity: The SPDK Stack



- A user-space I/O framework for NVMe devices (only)
- Block-level abstraction (no file system, but there are research prototypes)
- Has user-space mapped drivers (<https://spdk.io/doc/userspace.html>)
- Designed for light-weight I/O, best performance (eschews many core OS features)

SPDK can have the Highest Performance



2 CPU sockets, Intel(R) Xeon(R) Gold 6348 CPU @ 2.60GHz

22x Kioxia® KCM61VUL3T20 3.2TBs (FW: 0105) (10 on CPU NUMA Node 0, 12 on CPU NUMA Node 1)

SPDK NVMe BDEV Performance Report Release 23.05, June 2023,

https://ci.spdk.io/download/performance-reports/SPDK_nvme_bdev_perf_report_2305.pdf

Intricately Linked Issues

What is the system call interface

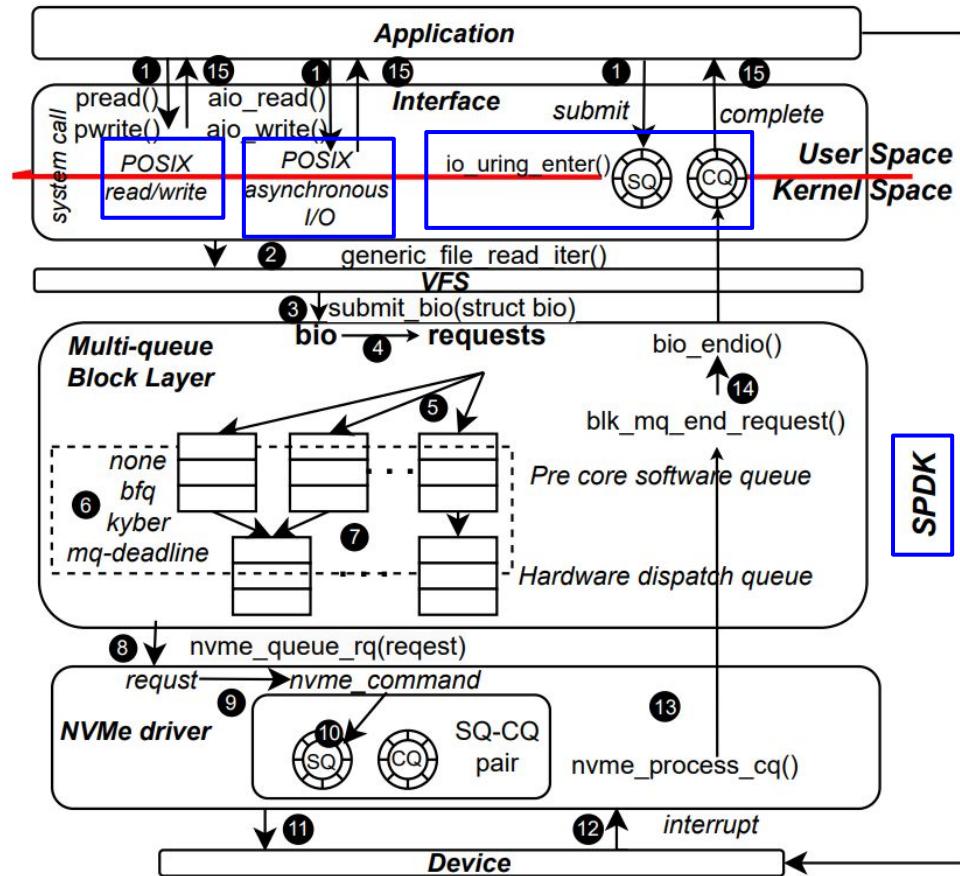
What is the kernel threading model

Signal vs queuing

What is the cost of scheduling, context switching

Management of concurrency

Programming languages (error handling)



Background Reading on this Topic

Because the original of the following paper by Lauer and Needham is not widely available, we are reprinting it here. If the paper is referenced in published work, the citation should read: "Lauer, H.C., Needham, R.M., "On the Duality of Operating Systems Structures," in Proc. Second International Symposium on Operating Systems, IRIA, Oct. 1978, reprinted in Operating Systems Review, 13,2 April 1979, pp. 3-19.

On the Duality of Operating System Structures

Hugh C. Lauer
Xerox Corporation
Palo Alto, California

Roger M. Needham*
Cambridge University
Cambridge, England

Abstract

Many operating system designs can be placed into one of two very rough categories, depending upon how they implement and use the notions of process and synchronization. One category, the "Message-oriented System," is characterized by a relatively small, static number of processes with an explicit message system for communicating among them. The other category, the "Procedure-oriented System," is characterized by a large, rapidly changing number of small processes and a process synchronization mechanism based on shared data.

In this paper, it is demonstrated that these two categories are duals of each other and that a system which is constructed according to one model has a direct counterpart in the other. The principal conclusion is that neither model is inherently preferable, and the main consideration for choosing between them is the nature of the machine architecture upon which the system is being built, not the application which the system will ultimately support.

This is an empirical paper, in the sense of empirical studies in the natural sciences. We have observed a number of samples from a class of objects and identified a classification of some of their properties. We have then generalized our classification and constructed abstract models to describe these properties. With the aid of these models, we were able to make some observations about the nature of the objects themselves, observations which are supported by other experimental evidence. Finally, we have drawn some conclusions about the class of objects which better aid our understanding of that class and the decisions which affect the design of members of that class.

The universe in this investigation is the class of operating systems, and the properties in which we are interested are the ways in which the concepts of process, synchronization, and interprocess communication occur within these systems and among their clients. There appear to be two general categories in this respect, which we designate the *Message-oriented Systems* and the *Procedure-oriented Systems*. Most systems which we have observed tend to be biased fairly strongly in favour of one or the other, rather than being neutral or indeterminate. Moreover,

* This work was done while the author was on sabbatical leave at the Xerox Palo Alto Research Center during the summer of 1977.

Why Threads Are A Bad Idea (for most purposes)

John Ousterhout
Sun Microsystems Laboratories

john.ousterhout@eng.sun.com
http://www.sunlabs.com/~ouster

Introduction

- **Threads:**
 - Grew up in OS world (processes).
 - Evolved into user-level tool.
 - Proposed as solution for a variety of problems.
 - Every programmer should be a threads programmer?

■ Problem: threads are very hard to program.

- **Alternative: events.**
- **Claims:**
 - For most purposes proposed for threads, events are better.
 - Threads should be used only when true CPU concurrency is needed.

Why Threads Are A Bad Idea

September 28, 1995, slide 2

Rob von Behren, Jeremy Condit and Eric Brewer
Computer Science Division, University of California at Berkeley
[jrvb, jcondit, brewer]@cs.berkeley.edu
http://capriccio.cs.berkeley.edu/

ing has been highly touted in recent literature highly concurrent applications. In these systems, we believe that threads of events, including support overhead, and a simple concurrency model that threads allow a simpler and easier way to handle the inherent difficulties of over-use of threads. We believe that extensive use of threads in high-concurrency environments, including N-SEDA [17], and Iktomi's Traffic Server. In these systems, we realized that the problems are not restricted to event systems; many have been implemented with threads, and the rest are in progress. Our experiments show that event-based programming is the wrong choice for concurrent systems. We believe that (1) threads are a more natural abstraction for high-concurrency and that (2) small improvements to compilers runtime systems can eliminate the historical use of threads, thus making them more to compiler-based enhancements; we believe paradigm for highly concurrent applications package with better compiler support.

Section 2 compares events with threads the common arguments against threads. Next, we argue that threads do not fit well into high-concurrency servers. Section 4 explores of compiler support for threads. In Section 5, our approach with a simple web server. Finally covers (some) related work, and Section 7 concludes.

2 Threads vs. Events
The debate between threads and events is a very old one [1, 2, 3]. Needham attempted to end the discussion in 1978 [4], showing that message-passing systems and process-based systems are duals, both in terms of program structure and performance characteristics [10]. Nonetheless, in recent years, many authors have declared the need for event-driven programming for highly concurrent systems [11, 12, 17].

HotOS IX: The 9th Workshop on Hot Topics in Operating Systems

Theoretical Computer Science 410 (2009) 202–220
Contents lists available at ScienceDirect
Theoretical Computer Science
journal homepage: www.elsevier.com/locate/tcs



Scala Actors: Unifying thread-based and event-based programming*

Philipp Haller*, Martin Odersky
EPFL, Switzerland

ARTICLE INFO

Keywords:
Concurrent programming
Actors
Threads
Events

ABSTRACT

There is an impedance mismatch between message-passing concurrency and virtual machines such as the JVM which map their threads to heavyweight OS threads. Without a lighter-weight abstraction, users are often forced to write parts of concurrent applications in an event-driven style which obscures control flow, and increases the burden on the programmer. In this paper, we show how thread-based and event-based programming can be unified under a single actor abstraction. Using advanced abstraction mechanisms of the Scala programming language, we implement our approach on unmodified JVMs. Our programming model integrates well with the threading model of the underlying VM.
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1. Introduction

Concurrency issues have lately received enormous interest because of two converging trends: first, multi-core processors make parallel programs practical to execute. Second, message-passing and event-based systems are inherently concurrent. Message-based concurrency is attractive because it might provide a way to address the two challenges at the same time. It can be seen as a higher-level model for threads with the potential to generalize to distributed computation. Many message-passing systems used in practice are instantiations of the actor model [28,2]. A popular implementation of this form of concurrency is the Erlang programming language [4]. Erlang supports massively concurrent systems such as telephones, and is gaining a very strong foothold in domains of concurrent processes [3,28].

On the other hand, platforms such as the JVM [34] are usually not native implementations, as yet, of the standard concurrency constructs, shared-memory threads, which locks suffer from high memory consumption and context-switching overhead. Therefore, the interleaving of independent computations is often modeled in an event-driven style on these platforms. However, programming in an explicitly event-driven style is complicated and error-prone, because it involves an inversion of control [41,13].

In previous work [24], we developed event-based actors which let one program event-driven systems without inversion of control. Event-based actors support the same operations as thread-based actors, except that the receive operation cannot return normally to the thread that invoked it. Instead, the entire continuation of such an actor has to be a part of the receive operation. This makes it possible to model a suspended actor by a continuation closure, which is usually much cheaper than suspending a thread.

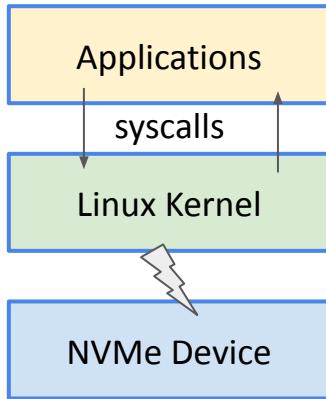
In this paper, we present a unification of thread-based and event-based actors. An actor can suspend with a full thread stack (*suspend*) or it can suspend with just a continuation closure (*reset*). The first form of suspension corresponds to thread-based, the second form to event-based programming. The new system combines the benefits of both models.

* A preliminary version of the paper appears in the proceedings of COORDINATION 2007, LNCS 4467, June 2007.

* Corresponding address: EPFL Station 14, 1015 Lausanne, Switzerland, Tel.: +41 21 693 6483; fax: +41 21 693 6660.
E-mail address: philipp.haller@epfl.ch (P. Haller).

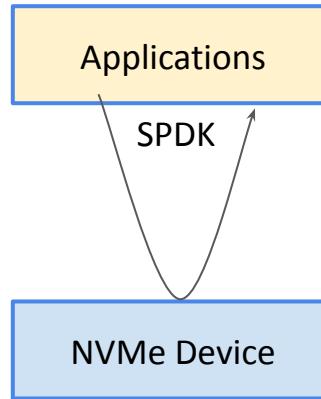
0304-3975/\$ - see front matter © 2008 Elsevier B.V. All rights reserved.
doi:10.1016/j.tcs.2008.09.019

Storage APIs: Recap



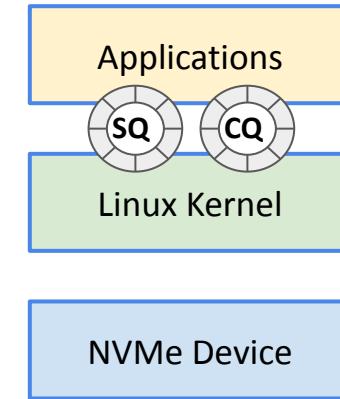
Libaio:

- + Async I/O
- + Any files/FSes
- + Any device: HDD, NVMe
- Async only with direct I/O
- Performance
- Metadata management



SPDK:

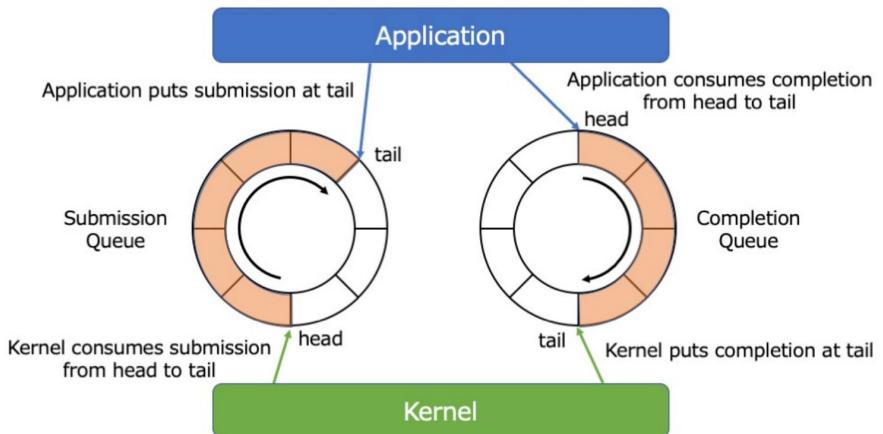
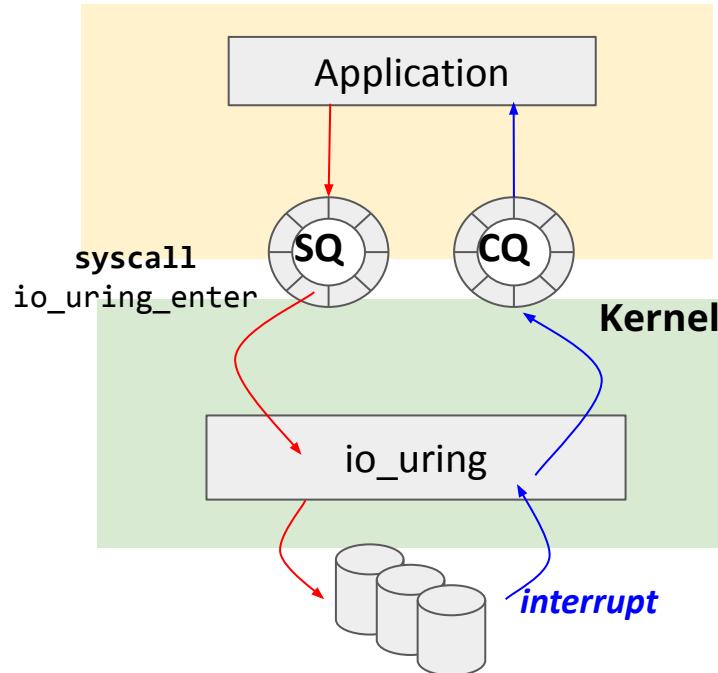
- + Performance
- + Close application integration
- + No syscall or interrupts
- Only NVMe
- No kernel assistance
- Scalability and brittle



io_uring

Best of both worlds?

io_uring: A Structured Approach to Asynchronous I/O

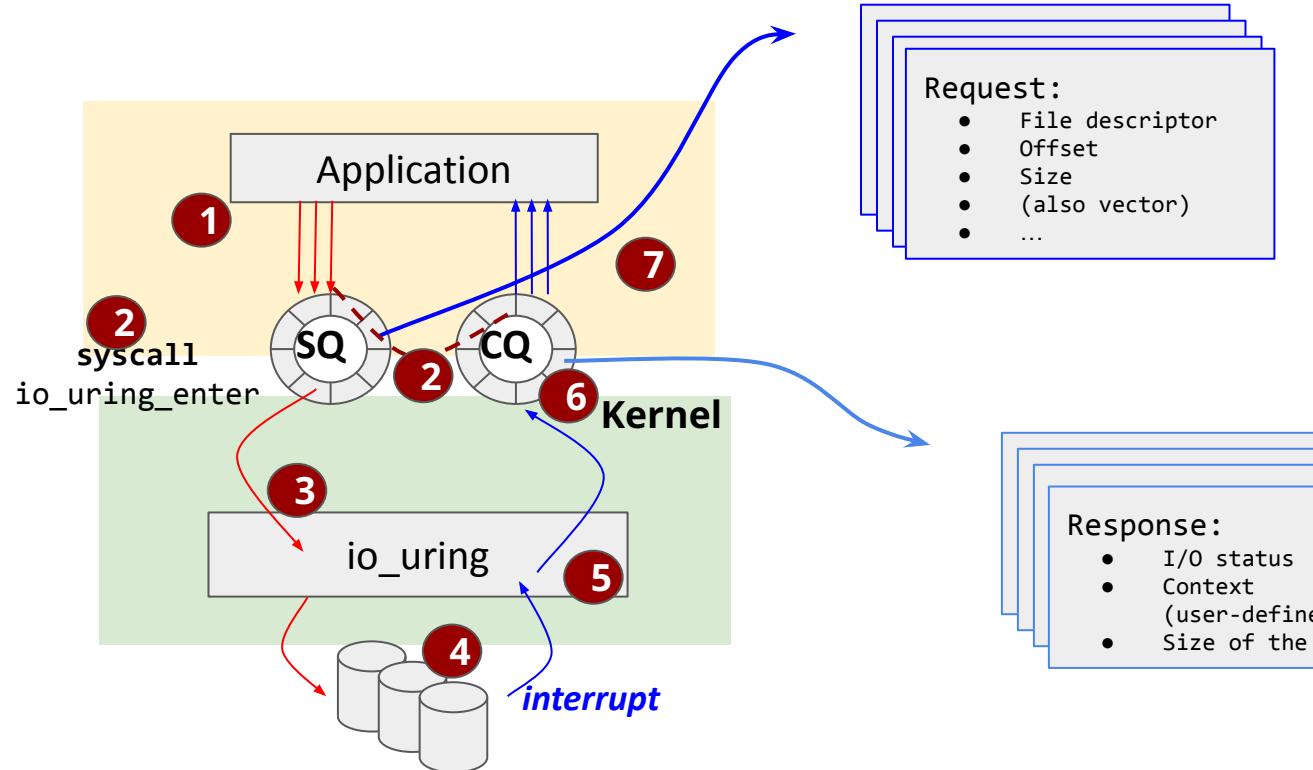


Producer-consumer pattern

- SQ: producer = application (tail), consumer = kernel (head)
- CQ: producer = kernel (tail), consumer = application (head)

Head and tail pointers manipulation with exclusive write ownership

io_uring: A Structured Approach to Asynchronous I/O



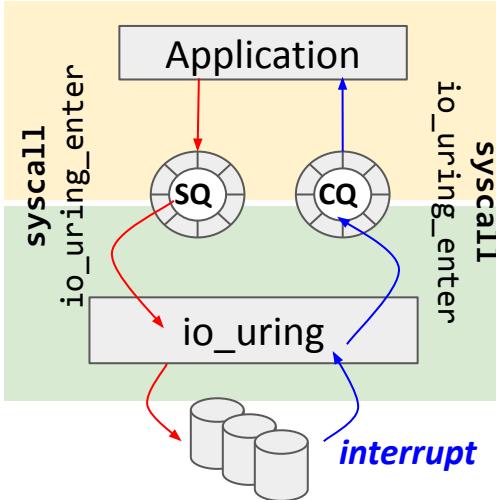
Applications can

- **Async I/O**
- I/O on any fd type (+net)
- Queue requests (batch)
- Vector I/O
- Optimize (fixed FD, pin)

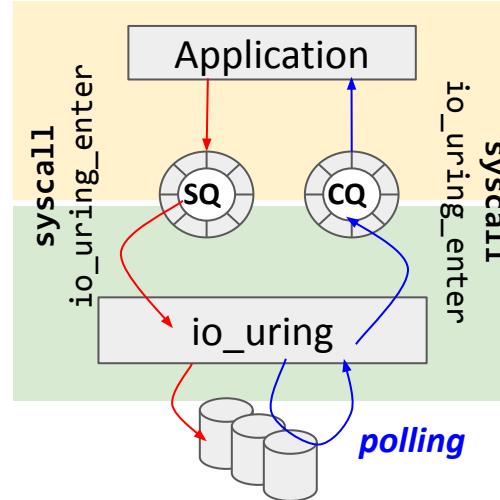
The three new Syscalls

1. **io_uring_setup:** This call is for creating the ring structure (queue-depth, I/O completion and notification modes)
 - a. Completion polling by the kernel on the device (IORING_SETUP_IOPOLL)
 - b. Kernel polling for submission (IORING_SETUP_SQPOLL, zero system call)
2. **io_uring_enter:** This call enters the kernel and tells it to process I/O requests (any type and extensible, not just storage I/O)
 - a. Networking, ZNS, Programmable storage and more
 - b. Replacement for the ioctl() call: a private interface between a device driver and application
3. **io_uring_register:** This call is for registering specific fd, buffers, file ranges that are being used frequently to put them on an optimized fast path

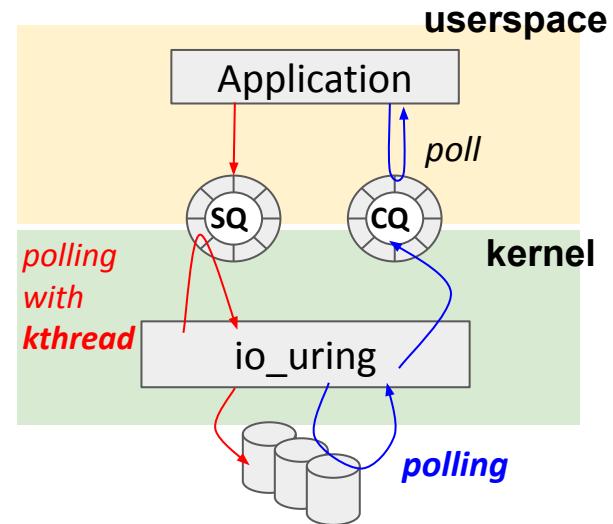
Three Modes of Operations



(a) `io_uring` (default)



(b) with completion polling



(c) with submission polling

Understanding Modern Storage APIs: A systematic study of libaio, SPDK, and io_uring

Diego Didona, Jonas Pfefferle,
 Nikolas Ioannou, Bernard Metzler
 IBM Research Europe
 Zurich, Switzerland
 {ddi,jp,no,bmft}@ibm.zurich.com

Animesh Trivedi
 VU Amsterdam
 Amsterdam, Netherlands
 a.trivedi@uva.nl

ABSTRACT

Recent high-performance storage devices have exposed software inefficiencies in existing storage stacks, leading to a new breed of I/O stacks. The newest storage API of the Linux kernel is `io_uring`. We perform one of the first in-depth studies of `io_uring` and compare its performance and disadvantages with the established `libaio` and `SPDK` APIs. Our key findings reveal that (i) polling design significantly impacts performance; (ii) with enough CPU cores `io_uring` can deliver performance close to that of `SPDK`; and (iii) performance scalability over multiple CPU cores and devices remains a challenge and necessitates a hybrid approach. Last, we provide design guidelines for developers of storage intensive applications.

ACM Reference Format:
 Diego Didona, Jonas Pfefferle, Nikolas Ioannou, Bernard Metzler and Animesh Trivedi. 2022. Understanding modern Storage APIs: A systematic study of `libaio`, `SPDK`, and `io_uring`. In *The 15th ACM International Systems and Storage Conference (SYSTOR '22)*, June 13–15, 2022, Haifa, Israel. ACM, New York, NY, USA, 8 pages. <https://doi.org/10.1145/3534056.3534945>

1 INTRODUCTION

Modern non-volatile memory (NVM) storage technologies, like Flash and Optane SSDs, can support up to single digit picosecond latencies and up to multi Gb/s bandwidth with millions of I/O operations per second (IOPS). CPU performance improvements have stalled over the past years due to various manufacturing and technical limitations [8].

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As a result, researchers have put considerable effort into identifying new CPU-efficient storage APIs, abstractions, designs, and optimizations [2, 11, 13, 15, 19, 22, 25, 26, 30, 31]. One specific API, `io_uring`, has drawn much attention from the community due to its versatile and high performance interface [5, 15, 16, 18, 27, 34]. `io_uring` was introduced in 2019 and has been merged in Linux v5.1. It brings together many well-established ideas from the high performance storage stack networking communities, such as asynchronous I/O, shared memory-mapped queues, and polling (Section 2, 10, 31, 32).

With the addition of `io_uring`, Linux now has multiple ways of accessing a storage device. In this paper, we look at Linux Asynchronous I/O (`libaio`) [6, 24], the Storage Performance Development Kit (SPDK) from Intel® [13], and `io_uring` [15, 17, 18]. These APIs have different parameters, deployment models, and characteristics, which make understanding their performance and limitations a challenging task. The main goal of this work is to provide insights into the behavior of recent stacks [7, 20, 33, 34]. However, to the best of our knowledge, there is no systematic study of these APIs that provides design guidelines for the developer of I/O intensive applications. There has also been an extensive body of work in studying system call overhead [29], implementing better interrupt management for I/O devices [30], leveraging polling for fast storage devices [38], using I/O speculation for picosecond-scale devices such as NVMe drives [35], and improving the performance of the Linux block layer in general. These studies are mostly orthogonal to ours, since they explore designing new storage stacks, while we focus on the performance characteristics of state-of-the-art APIs that are readily available in Linux.

Our main contributions include (i) a systematic comparison of `libaio`, `io_uring`, and `SPDK`; that evaluates their latency, IOPS, and scalability behaviors; (ii) a first-of-its-kind detailed evaluation of the different `io_uring` configurations; and (iii) design guidelines for high-performance applications using modern storage APIs. Our key findings reveal that:

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Zebin Ren and Animesh Trivedi. 2023. Performance Characterization of Modern Storage Stacks: POSIX I/O, `libaio`, `SPDK`, and `io_uring`. In Proceedings of the 3rd Workshop on Challenges and Opportunities of Efficient and Performant Storage Systems (CHEOPS '23). <https://doi.org/10.1145/3578353.3589545>

Performance Characterization of Modern Storage Stacks: POSIX I/O, `libaio`, `SPDK`, and `io_uring`

Zebin Ren
 z.ren@uva.nl
 Vrije Universiteit Amsterdam
 Amsterdam, Netherlands

Animesh Trivedi
 a.trivedi@uva.nl
 Vrije Universiteit Amsterdam
 Amsterdam, Netherlands

Abstract

Linux storage stack offers a variety of storage I/O stacks and APIs such as POSIX I/O, asynchronous I/O (bio), high-performance asynchronous I/O (emerging `io_uring`) or SPDK, the last of which completely bypasses the kernel. Despite their availability, there has not been a systematic study of their performance and overheads. In order to aid our understanding, in this work we systematically characterize performance, scalability, and microarchitectural properties of popular Linux I/O APIs on high-performance storage hardware (Intel Optane SSDs). Our characterization reveals that (1) I/O overheads of APIs are context-aware, with each API having a different polling and polling-free performance by 1.7x, but consuming 2.3x CPU instructions; (2) at high-b loads and low I/O, `io_uring` is more than an order of magnitude slower than SPDK; (3) at high-b loads, the benchmarking tool (`fio`) itself becomes a bottleneck; (4) state-of-practice Linux block I/O schedulers (BFQ, mq-deadline, and Kyber) introduce significant (up to 50%) overheads, and their use of global locks hinder their scalability. All artifacts from this work are available at <https://github.com/atlarege/Performance-Characterization-Storage-Stacks>.

CSC Concepts: → Software and its engineering → Secondary storage; Operating systems.

Keywords: Linux storage stack, `io_uring`, SPDK, Efficiency, Measurements

ACM Reference Format:

Zebin Ren and Animesh Trivedi. 2023. Performance Characterization of Modern Storage Stacks: POSIX I/O, `libaio`, `SPDK`, and `io_uring`. In *3rd Workshop on Challenges and Opportunities of Efficient and Performant Storage Systems (CHEOPS '23)*, May 8, 2023, Rome, Italy. ACM, New York, NY, USA, 11 pages. <https://doi.org/10.1145/3578353.3589545>



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1 Introduction

Modern storage devices such as Intel Optane SSDs can deliver millions of IOPS/I/O operations per second with single-digit microseconds (μsec) I/O access latencies [7, 16]. Meanwhile, the CPU performance has remained relatively stable as Moore's Law driven performance gains stall [29]. Consequently, the stalled CPU performance with high-performance storage hardware has exposed many previously hidden software overheads in the storage stack implementations, thus leading to a series of efforts to redesign and optimize the storage stack using I/O lock contention, switches, and other techniques. In this work, we focus on the context-awareness of `io_uring` and its performance by 1.7x, but consuming 2.3x CPU instructions; (2) at high-b loads and low I/O, `io_uring` is more than an order of magnitude slower than SPDK; (3) at high-b loads, the benchmarking tool (`fio`) itself becomes a bottleneck; (4) state-of-practice Linux block I/O schedulers (BFQ, mq-deadline, and Kyber) introduce significant (up to 50%) overheads, and their use of global locks hinder their scalability. All artifacts from this work are available at <https://github.com/atlarege/Performance-Characterization-Storage-Stacks>.

Beyond these optimizations, there have been many efforts to improve the user-kernel and user-storage APIs and abstractions. Linux supports two popular and widely used APIs called (synonymous) POSIX file I/O calls [12, 13] and an asynchronous API called `libaio` [3]. Both of these APIs interact via system calls (syscalls) with the Linux kernel which can have high overheads [22, 38, 55]. More recently, Linux developers have introduced a new API called `io_uring` [10, 41]. It takes an established idea of the high-performance networking domain (shared-memory queues, asynchronous I/O polling, shared I/O contexts) and applies them to storage in a unified manner [6, 62]. These advancements are now merged in the Linux storage stack (since v5.1 kernel version), and have shown to deliver high performance and CPU efficiency [22]. All of these APIs (POSIX, `libaio`, `io_uring`) work within the kernel.

The Linux kernel with its generic code execution, functionalities, and features can also introduce significant overheads [51] when leading to the creation of the user-space storage stacks [24, 34, 69, 74]. The Storage Performance Development Kit (SPDK) is one of the most popular and widely used user-space I/O libraries, which can deliver up to 10 million IOPS using a single CPU core [2]. However, user space I/O libraries lack many kernel-supported features such as fine-grained isolation, access control, file systems, multi-tenancy, and QoS support [48, 64].

In summary, over the past decade, the in-kernel and user-space I/O stacks have undergone a significant development phase. Despite sharing a common functional goal

Benchmarking Setup

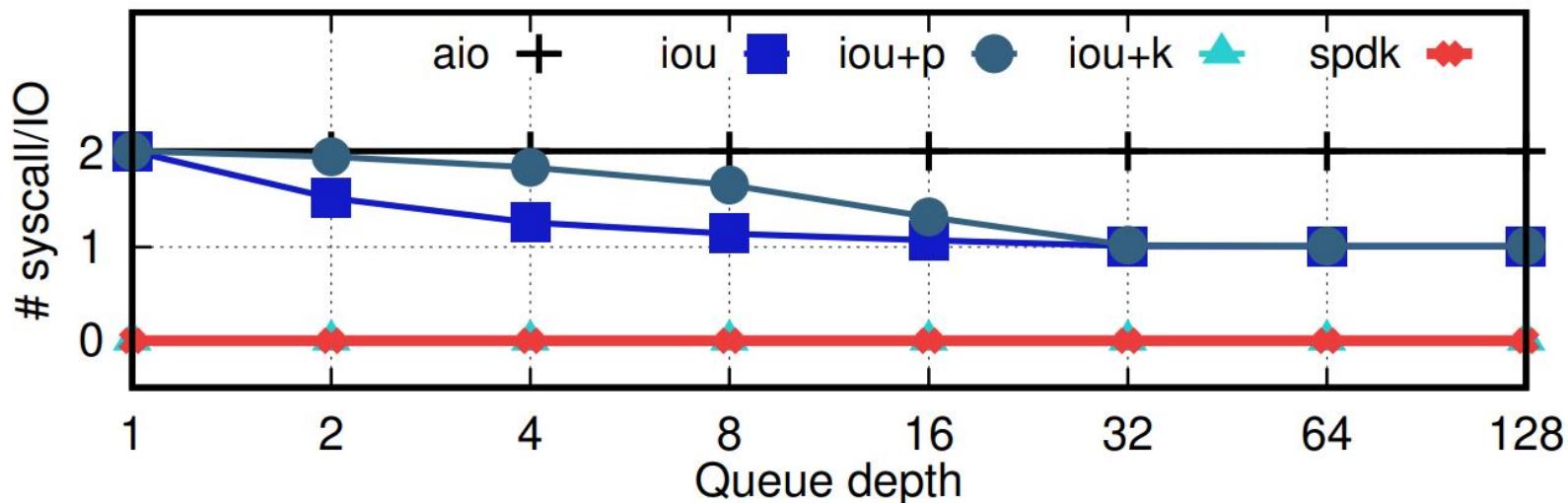
Setup 1 [Systor'22]:

- 2x Intel® Xeon® E5-2630 (Sandy Bridge), 10 cores/socket ⇒ 20 CPU cores
- 20 Intel® DC P3600 400GB NVMe Flash SSDs ⇒ ~6 Million IOPS

Setup 2 [CHEOPS'23]:

- 2x Intel® Xeon® Silver 4210R (Cascade Lake), 10 cores/socket ⇒ 20 CPU cores
- 7× Intel Corporation 900P NVMe Optane SSD ⇒ 4.2 Million IOPS

Number of System Calls

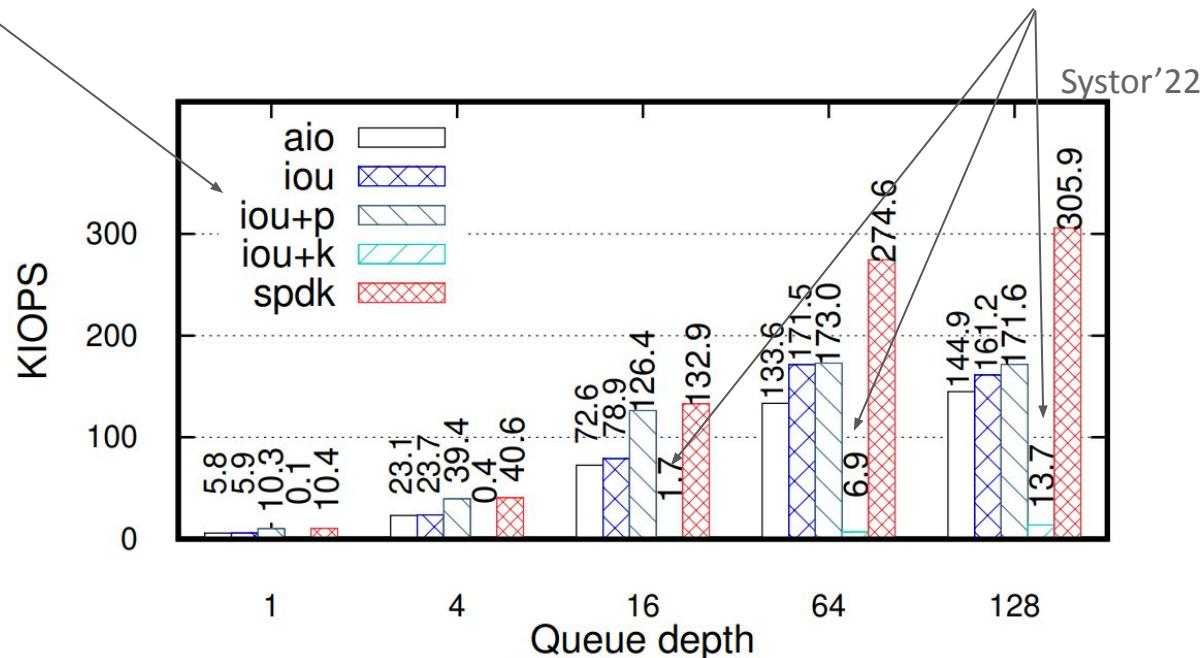


Doing I/O with zero system calls!

Results: Efficiency (single CPU core)

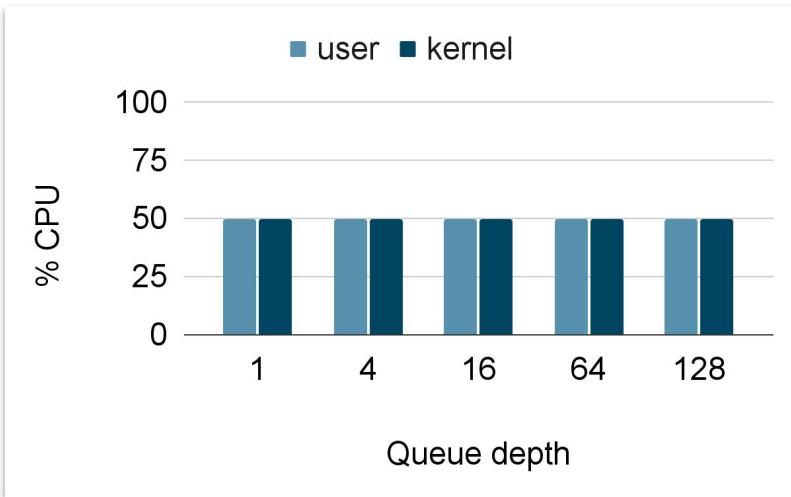
io_uring sits between libaio and SPDK

Performance collapses with the kernel polling



Analysis

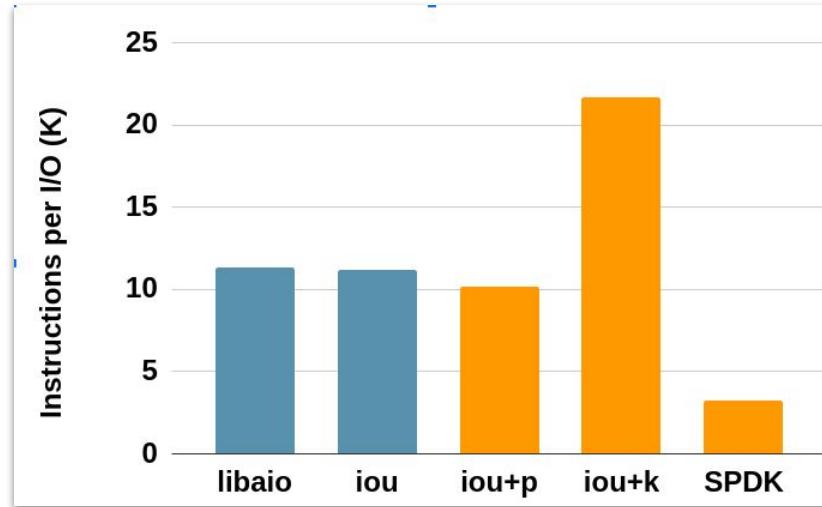
Systor'22



[Interesting] 8 milliseconds constant latency for all queue depths!

Poor scheduling, and CPU sharing - **Careful!**

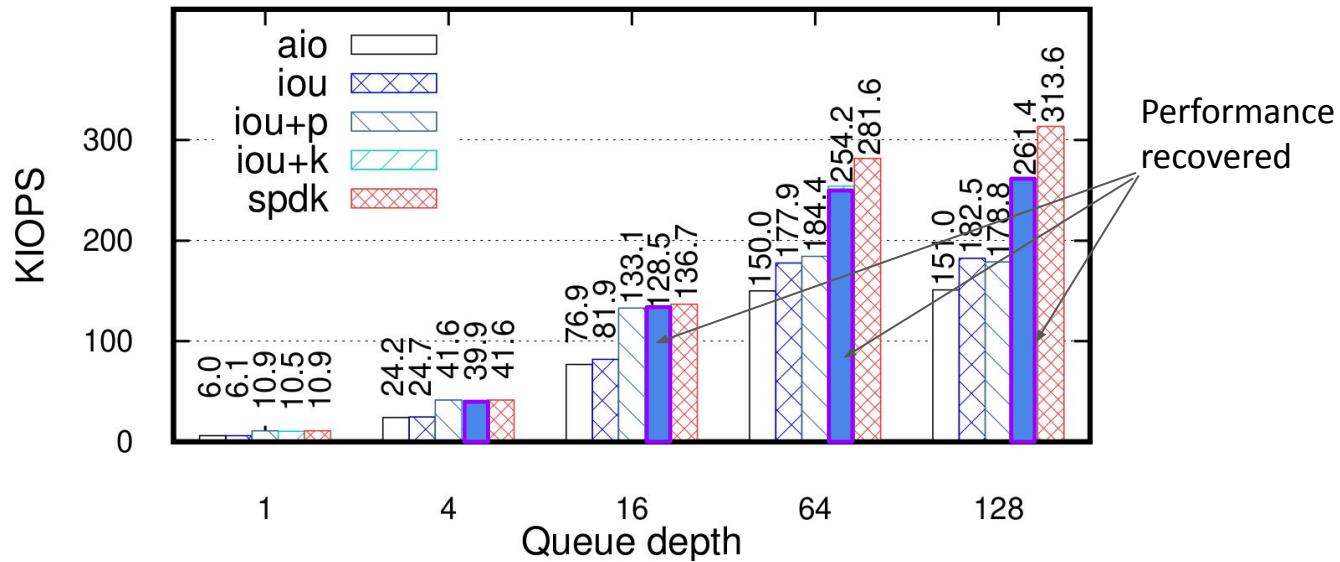
CHEOPS'23



SPDK is still 5x more efficient

Result: Efficiency with TWO CPU cores

Systor'22

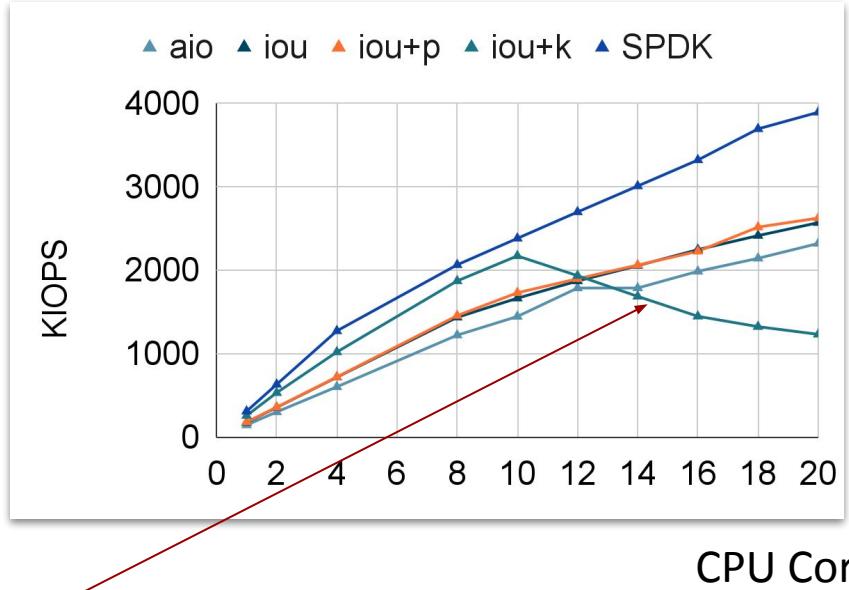


[aio < iou < iou with polling < iou with kernel poll < SPDK]

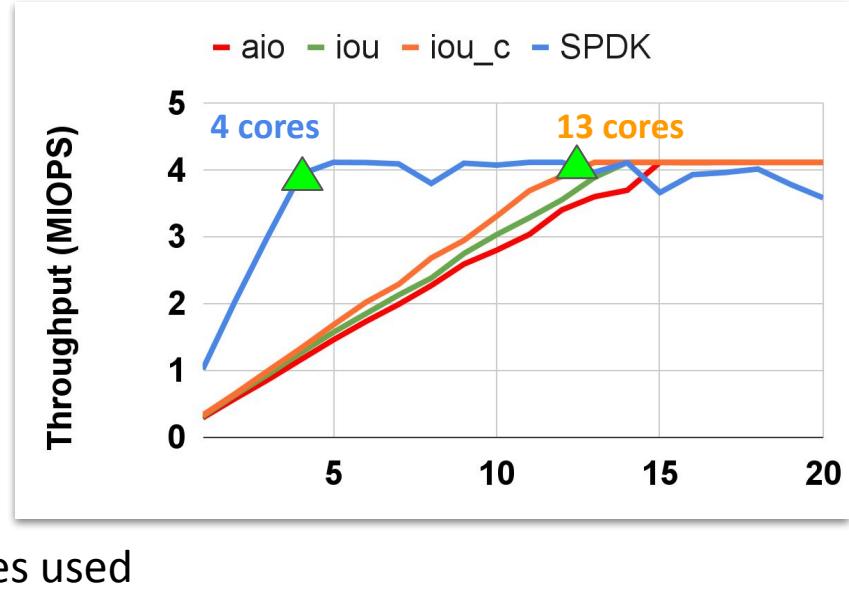
Normal service order can be resumed (**but** at the cost of 2x CPU cores)!

Results: Scalability

Systor'22



CHEOPS'23



io_uring kernel polling: Performance collapses when the number of poller CPU threads increases beyond the cores

CPU efficiency is still bad: 10x more CPU cores needed

io_uring : Programming Ecosystem

- liburing : <https://github.com/axboe/liburing>
 - 3x syscall based programming can be tricky, hence, a high(er)-level library

List of manual pages

- Active research in leveraging io_uring in DBs, key-value store, etc.
 - Applicability beyond storage as the “core” kernel-application interfacing API

What you should know from this lecture

What is CXL and what key problems does it solve

What is different types of CXL protocols, device types, and generational features

What does flash + CXL allow us to do

What is asynchronous and non-block I/O, and what different APIs support them

What is io_uring? What are the different operation completion modes it supports

What are the performance implications of these modes

The New(er) Triangle of Storage-Memory Continuum

To Conclude

Storage Research is fundamentally changing and reshaping what kind of systems we can build tomorrow

- Performance
- Abstractions
- Efficiency
- Programmability
- Cost
- Scalability

This course came out of this report ;)

Data Storage Research Vision 2025

Report on NSF Visioning Workshop held May 30–June 1, 2018

George Amvrosiadis[†], Ali R. Butt[¶], Vasily Tarasov[‡], Erez Zadok^{*}, Ming Zhao[§]

Irfan Ahmad, Remzi H. Arpacı-Dusseau, Feng Chen, Yiran Chen, Yong Chen, Yue Cheng,
Vijay Chidambaram, Dilma Da Silva, Angela Demke-Brown, Peter Desnoyers, Jason Flinn, Xubin He,
Song Jiang, Geoff Kuenning, Min Li, Carlos Maltzahn, Ethan L. Miller, Kathryn Mohror, Raju Rangaswami,
Narasimha Reddy, David Rosenthal, Ali Saman Tosun, Nisha Talagala, Peter Varman, Sudharshan Vazhkudai
Avani Waldani, Xiaodong Zhang, Yiying Zhang, and Mai Zheng.

[†]Carnegie Mellon University, [¶]Virginia Tech, [‡]IBM Research,
^{*}Stony Brook University, [§]Arizona State University

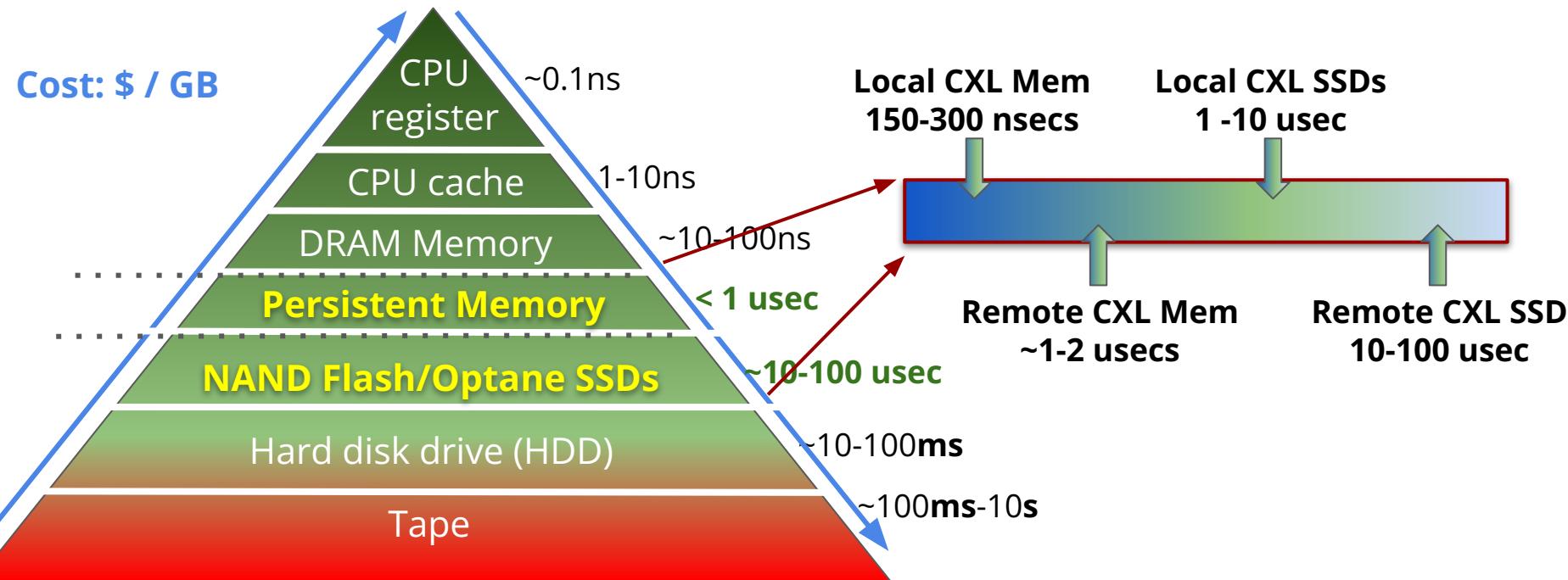
February 2019

Executive Summary

With the emergence of new computing paradigms (e.g., cloud and edge computing, big data, Internet of Things (IoT), deep learning, etc.) and new storage hardware (e.g., non-volatile memory (NVM), shingled-magnetic recording (SMR) disks, and kinetic drives, etc.), a number of open challenges and research issues need to be addressed to ensure sustained storage systems efficacy and performance. The wide variety of applications demand that the fundamental design of storage systems should be revisited to support application-specific and application-defined semantics. Existing standards and abstractions need to be reevaluated; new sustainable data representations need to be designed to support emerging applications. To take advantage of hardware advancements, new storage software designs are also necessary in order to maximize overall system efficiency and performance.

Therefore, there is an urgent need for a consolidated effort to identify and establish a vision for storage systems research and comprehensive techniques that provide practical solutions to the storage issues facing the information technology community. To address this need, the National Science Foundation's (NSF) "Visioning Workshop on Data Storage Research 2025" brought together a number of storage researchers from academia, industry, national laboratories, and federal agencies to develop a collective vision for future storage research, as well as to prioritize

The New(er) Triangle of Storage-Memory Continuum



Instead of discrete steps, it is a continuous spectrum now: Continuum

Further Reading - CXL (1 or 2)

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- CXL resources, <https://www.computeexpresslink.org/resource-library>
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- QEMU CXL setup, <https://www.qemu.org/docs/master/system/devices/cxl.html>
- How To Map a CXL Endpoint to a CPU Socket in Linux,
<https://stevescargall.com/blog/2022/12/27/how-to-map-a-cxl-endpoint-to-a-cpu-socket-in-linux/>

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