



## 1 Matplottoy

We build on top of the existing Matplotlib architecture [1] so that we can initially focus on the data to graphic transformations and rely on Matplotlib for the other graphical elements of the visualization and the rendering. For a primitive graph such as a bar, scatter, line, our path is: python

```
E = Section()
V = 'parameter': ('field': transformer)
fig, ax = plt.subplots()
artist = Q(E, V)
ax.add_artist(artist)
```

### 1.1 Data: $\mathcal{E}$

We propose a semantic markup of the fiber and connectivity that we will later use to check the constraints of the  $v$  and  $Q$ . python class FiberBundle:

```
def __init__(self, K, F):
    """K: 'tables': [] F: 'fieldname': (type, monoidaction)"""
    def is_section(section):
        """checks if a section is from a given fiberbundle: are values in F, are keys in K"""
    pass
```

We add a monoid field to the schema like structure of the fiber since the monoid actions are the constraints on the  $v$  and  $Q$ . We implement  $K$  using the triangulization scheme described in section ???. This means we expect data to be provided as tables where the name encodes the connectivity:

**vertex** - disconnected points

**edge** - 1D continuity along the edge

**face** - 2D continuity along the face

Nested continuity is encoded in the fiber. For example, one way to encode a movie is a 1D timeseries of Frame objects, where each Frame is a  $nm$  continuous array.

#### 1.1.1 Sections

As described in section ???, the data values are encode as the section of the fiber bundle. We implement this as as a wrapper class around a data container object of the form: python class Section: FB = FiberBundle(K, F)

```
def __init__(self,*args):passdef view(self,simplex="vertex"):convert data into atomic column order return fieldname:dat
```

The view function is the closest analog to  $\tau$ , as it returns a a data container type object. We specify field based top level indexing so that we can pair the fields with transformer  $\nu$  objects.

## 1.2 Encoding: $\mathcal{V}$

We implement  $\nu$  as encoder objects with an optional  $'\text{init}.\text{method that can be used to specify the range of target visual variables}'$ .

```
python class Encoder: def __init__(self,args):passdef validate(self,monoid):check if transform supports monoid action passdef convert(self,value):con
```

The validate method specifies the monoids for which this a valid  $\nu$  and checks against the specification in the fiber. The convert method converts a value from data space to an internalized normal form as described in table ??.

## 1.3 Graphic: $\mathcal{H}$

We inherit from the current Matplotlib artists for our  $Q$ , which is responsible for constructing a curried fully specified internal representation of the graphic. python class Q(BaseClass): required = optional = def \_\_init\_\_(self,data,\*args,kwags):check that required and optional visual parameters are passed in check that the While equation ?? specifies that the values of  $\mu$  can be generated before they are input to  $Q$ , we curry the opertaions of obtaining the data and performing the transforms to the draw method because that allows us to more easily propogate updates to the data to the screen.

## 1.4 Case Study: Iris(Penguins)