THE STRUCTURE OF PROBABILISTIC NETWORKS

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ABSTRACT

- 1. There is a growing realization among community ecologists that interactions between species vary in space and time. Yet, our current numerical framework to analyze the structure of interactions, largely based on graph-theoretical approaches, is unsuited to this type of data. Since the variation of species interactions holds much information, there is a need to develop
- 6 new metrics to exploit it.

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- 2. We present analytical expressions of key network metrics, using a probabilistic framework.

 Our approach is based on modeling each interaction as a Bernoulli event, and using basic calculus to express the expected value, and when mathematically tractable, its variance. We
- provide a free and open-source implementation of these measures.
- 3. We show that our approach allows to overcome limitations of both neglecting the variation of interactions (over-estimation of rare events) and using simulations (extremely high computational demand). We present a few case studies that highlight how these measures can be used.
 - 4. We conclude this contribution by discussing how the sampling and data representation of ecological network can be adapted to better allow the application of a fully probabilistic numerical framework.
- 18 Keywords: ecological networks, connectance, degree distribution, nestedness, modularity

Date: Mar. 2015.

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Introduction

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Ecological networks are an efficient way to represent biotic interactions between individuals, populations, or species. Historically, their study focused on describing their structure, with a particular attention on food webs (Dunne 2006) and plant-pollinator interactions (Jordano 1987; Bascompte *et al.*2003). The key result of this line of research was linking this structure to community or ecosystemlevel properties such as stability (McCann 2014), coexistence (Bastolla *et al.* 2009; Haerter *et al.*2014), or ecosystem functioning (Duffy 2002; Thébault Loreau 2003; Poisot 2012). To a large extent,
the description of ecological networks resulted in the emergence of questions about how functions
emerged from and properties of communities emerged from their structure, and this stimulated the
development of a rich methodological literature, defining a wide array of structural properties.

Given a network (i.e. a structure where nodes, most often species, are linked by edges, representing 11 ecological interactions) as input, measures of network structure return a property based on one or 12 several *units* from this network. Some of the properties are *direct* properties (they only require knowl-13 edge of the unit on which they are applied), whereas others are emergent (they require knowledge 14 of, and describe, higher-order structures). For example, connectance, the realized proportion of po-15 tential interactions, is a direct property of a network. The degree of a node (how many interactions 16 it is involved in) is a direct property of the node. The nestedness of a network (that is, the extent 17 to which specialists and generalists overlap), on the other hand, is an emergent property that is not 18 directly predictable from the degree of all nodes. Though the difference may appear to be seman-19 tics, establishing a difference between direct and emergent properties is important when interpreting 20 their values; direct properties are conceptually equivalent to means, in that they tend to be the first 21 moment of network units, whereas emergent properties are conceptually equivalent to variances or 22 other higher-order moments. 23

In the recent years, the interpretation of the properties of network structure (as indicators of the action of ecological or evolutionary processes) has been somewhat complicated by the observation that network structure varies through space and time. This happens because, contrary to a long-standing assumption of network studies, species from the same pool do not interact in a consistent way (Poisot

et al. 2012). Empirical and theoretical studies suggest that the network is not the right unit to understand this variation; rather, network variation is an emergent property of the response of ecological 2 interactions to environmental factors and chance events (???see Poisot et al. 2015 for a review). Interactions can vary because of local mismatching in phenology (Olesen et al. 2011; Vizentin-Bugoni et al. 2014; Maruyama et al. 2014), populations fluctuations preventing the interaction (Canard et al. 2014), or a combination of both (Chamberlain et al. 2014; Olito & Fox 2014). For example, Olito & Fox (2014) show that accounting for neutral (population-size driven) and trait-based effects allows the prediction of the cumulative change in network structure, but not of the change at the level of individual interactions. In addition, Carstensen et al. (2014) show that within a metacommunity, not all interactions are equally variable: some are highly consistent, whereas others are 10 extremely rare. These empirical results all point to the fact that species interactions cannot always 11 be adequately modeled represented as yes-no events; since it is well established that they do vary, it 12 is necessary to represent them as probabilities. To the question of *Do these two species interact?*, 13 we should substitute the question of How likely is it that they will interact?. This also requires the 14 considerable methodological adjustment of re-writing measures of network structure to account for 15 the fact that interactions are not consistent; in this paper, we re-develop a unified toolkit of measures 16 to characterize the structure of probabilistic interaction networks. 17

The current way of dealing with probabilistic interactions are either to ignore variability entirely or 18 to generate random networks. Probabilistic metrics are a mathematically rigorous alternative to both. 19 When ignoring the probabilistic nature of interactions (henceforth binary networks), every non-zero 20 element of the network is assumed to be 1. This leads to over-representation of some rare events, and 21 increases the number of interactions; as a result, this changes the estimated value of different network 22 properties, in a way that is not understood at all. Issues are most likely to arise for connectances 23 where the topological (Chagnon 2015) or permutational (Poisot & Gravel 2014) space of random 24 network is small, leading to over-replication or uncharacterized biases. An alternative is to consider 25 only the interactions above a given threshold, which leads to an under-representation of rare events 26 and decreases the effective number of interactions (in addition to the problem that there is no robust 27 criterion to decide on a treshold). More importantly, this introduces the risk of removing species that 28

- 1 establish a lot of interactions that each have a low probability. Taken together, these considerations
- 2 highlight the need to amend our current methodology for the description of ecological networks, in
- 3 order to give more importance to the variation of individual interactions current measures neglect
- 4 the variability of interactions, and are therefore discarding valuable ecological information. Because
- 5 the methodological corpus available to describe ecological networks had first been crafted at a time
- 6 when it was assumed that interactions were invariants, it is unsuited to address the questions that
- 7 probabilistic networks allow us to ask.
- 8 In this paper, we show that several direct and emergent core properties of ecological networks (both
- 9 bipartite and unipartite) can be re-formulated in a probabilistic context (Yeakel et al. 2012; ??? Poisot
- 10 et al. 2015); we conclude by showing how this methodology can be applied to exploit the information
- contained in the variability of networks, and to reduce the computational burden of current methods in
- 12 network analysis. We also provide a free and open-source (MIT license) implementation of this suite
- of measures in a library for the julia language, available at http://github.com/PoisotLab/ProbabilisticNe

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SUITE OF PROBABILISTIC NETWORK METRICS

Throughout this paper, we use the following notation. **A** is a matrix wherein A_{ij} is P(ij), *i.e.* the probability that species i establishes an interaction with species j. If **A** represents a unipartite network (e.g. a food web), it is a square matrix and contains the probabilities of each species interacting with all others, including itself. If **A** represents a bipartite network (e.g. a pollination network), it will not necessarily be square. We call S the number of species, and S and S and S not necessarily be square. We call S the number of species, and S and S not necessarily be square.

- Note that all of the measures defined below can be applied on a bipartite network that has been made
- 2 unipartite; the . The only bipartite-only measure is nestedness. The unipartite transformation of a
- 3 bipartite matrix **A** is the block matrix

(1)
$$\mathbf{B} = \begin{pmatrix} 0_{(R,R)} & \mathbf{A} \\ 0_{(C,R)} & 0_{(C,C)} \end{pmatrix},$$

where $0_{(C,R)}$ is a matrix of C rows and R columns (noted $C \times R$) filled with 0s, etc. Note that for centrality to be relevant in bipartite networks, this matrix should be made symmetric: $\mathbf{B}_{ij} = \mathbf{B}_{ji}$.

We will also assume that all interactions are independent (so that P(ij|kl) = P(ij)P(kl) for any species), and can be represented as a series of Bernoulli trials (so that $0 \le P(ij) \le 1$). A Bernoulli trial is simply the realization of a probability event, giving 1 with probability P(ij), and 0 else. The latter condition allows us to derive estimates for the *variance* (V(x) = P(1-p)), and expected values (E(X) = p). We can therefore estimate the variance of most properties, using the fact that the variance of additive independent events is the sum of their individual variances, and that the variance of multiplicative independent events is

(2)
$$\operatorname{var}(X_1 X_2 ... X_n) = \prod_{i} \left(\operatorname{var}(X_i) + [\operatorname{E}(X_i)]^2 \right) - \prod_{i} [\operatorname{E}(X_i)]^2$$

As a final note, all of the measures described below can be applied on the binary (0/1) versions of the 13 networks and will give the exact value of the non-probabilistic measure in which case they effectively 14 are the non-probabilistic version of the measure as usually calculated. This property is particularly 15 desirable as it allows our framework to be used on any network, whether they are represented in a 16 probabilistic or binary way. Nonetheless, this approach is different from using weighted networks, in 17 that it answers a completely different question. Probabilistic networks describe the probability that 18 any interaction will happen, whereas weighted networks describe the effect of the interaction when 19 it happens. Although there are several measures for quantitative networks (Bersier et al. 2002), 20 in which interactions happen but with different outcomes, these are not relevant for probabilistic 21

- 1 networks, which require to account for the fact that interactions are probabilistic event, *i.e.* they
- 2 display a variance that will cascade up to the network level. Actually, the weight of each interaction
- 3 is best viewed as a second modeling step, focusing only on the non-zero cases (i.e. the interactions
- 4 that are realized); this is similar to the method now frequently used in species distribution models,
- 5 where the species presence is modeled first, and its abundance second, using a (possibly) different
- 6 set of predictors (Boulangeat et al. 2012).

7 Direct properties.

8 Connectance and number of interactions. Connectance (or network density) is the proportion of

9 possible interactions that are realized, defined as $Co = L/(R \times C)$, where L is the total number

of interactions. As all interactions in a probabilistic network are assumed to be independent, the

11 expected value of L, is

$$\hat{L} = \sum A_{ij},$$

and $\hat{Co} = \hat{L}/(R \times C)$. Likewise, the variance of the number of interactions is $var(\hat{L}) = \sum (A_{ij}(1 - A_{ij}))$.

Node degree. The degree distribution of a network is the distribution of the number of interactions

15 established (number of successors) and received (number of predecessors) by each node. The ex-

16 pected degree of species *i* is

$$\hat{k}_i = \sum_j (A_{ij} + A_{ji})$$

The variance of the degree of each species is $\text{var}(\hat{k}_i) = \sum_j (A_{ij}(1-A_{ij}) + A_{ji}(1-A_{ji}))$. Note also that as expected, $\sum \hat{k}_i = 2\hat{L}$.

- 1 Generality and vulnerability. By simplification of the above, generality \hat{g}_i and vulnerability \hat{v}_i are
- 2 given by, respectively, $\sum_{j} A_{ij}$ and $\sum_{j} A_{ji}$, with their variances $\sum_{j} A_{ij} (1 A_{ij})$ and $\sum_{j} A_{ji} (1 A_{ji})$.

3 emergent Emergent properties.

- 4 Path length. Networks can be used to describe indirect interactions between species through the use
- of paths. The existence of a path of length 2 between species i and j means that they are connected
- 6 through at least one additional species k. In a probabilistic network, unless some elements are 0, all
- 7 pairs of species i and j are connected through a path of length 1, with probability A_{ij} . The expected
- 8 number of paths of length k between species i and j is given by

(5)
$$n_{ij}^{(k)} = \left(\mathbf{A}^k\right)_{ij},$$

9 where \mathbf{A}^k is the matrix multiplied by itself k times.

It is possible to calculate the probability of having at least one path of length k between the two species: this can be done by calculating the probability of having no path of length k, then taking the running product of the resulting array of probabilities. For the example of length 2, species i and j are connected through g with probability $A_{ig}A_{gj}$, and so this path does not exist with probability $1 - A_{ig}A_{gj}$. For any pair i, j, let \mathbf{m} be the vector such as $m_g = A_{ig}A_{gj}$ for all $g \notin (i, j)$ (Mirchandani 1976). The probability of not having any path of length 2 is $\prod (1 - \mathbf{m})$. Therefore, the probability of having a path of length 2 between i and j is

(6)
$$\hat{p}_{ij}^{(2)} = 1 - \prod_{7} (1 - \mathbf{m}).$$

- 1 In most situations, one would be interested in knowing the probability of having a path of length 2
- 2 without having a path of length 1; this is simply expressed as $(1 A_{ij})\hat{p}_{ij}^{(2)}$. One can, by the same
- 3 logic, generate the expression for having at least one path of length 3:

(7)
$$\hat{p}_{ij}^{(3)} = (1 - A_{ij})(1 - \hat{p}_{ij}^{(2)}) \left(1 - \prod (1 - \mathbf{m})\right) \prod_{x,y} \left((1 - A_{iy})(1 - A_{xj})\right),$$

- where **m** is the vector of all $A_{ix}A_{xy}A_{yj}$ for $x \notin (i,j), y \neq x$. This gives the probability of having
- at least one path from i to j, passing through any pair of nodes x and y, without having any shorter
- 6 path. In theory, this approach can be generalized up to an arbitrary path length, but it becomes rapidly
- 7 untractable.
- 8 Unipartite projection of bipartite networks. The unipartite projection of a bipartite network is ob-
- stained by linking any two nodes of one mode that are connected through at least one node of the
- other mode; for example, to plants are connected if they share at least one pollinator. It is readily
- obtained using the formula in the *Path length* section. This yields either the probability of an edge
- in the unipartite projection (of the upper or lower nodes), or if using the matrix multiplication, the
- 13 expected number of such nodes.
- 14 Nestedness. Nestedness is an important measure of (bipartite) network structure that tells the extent
- to which the interactions of specialists and generalists overlap. We use the formula for nestedness
- proposed by Bastolla et al. (2009). They define nestedness; this measure is a correction of NODF
- (Almeida-Neto et al. 2008) for ties in species degree. Nestedness for each margin of the matrix, is
- defined as $\eta^{(R)}$ and $\eta^{(C)}$ for, respectively, rows and columns. As per Almeida-Neto et al. (2008), we
- define a global statistic for nestedness as $\eta = (\eta^{(R)} + \eta^{(C)})/2$.
- 20 Nestedness, in a probabilistic network, is defined as

(8)
$$\eta^{\hat{R}} = \sum_{i < j} \frac{\sum_{k} A_{ik} A_{jk}}{\min(g_i, g_j)},$$

- where g_i is the expected generality of species i. The reciprocal holds for $\eta^{(C)}$ when using v_i (the
- vulnerability) instead of g_i .
- The values returned are within [0, 1], with $\eta = 1$ indicating complete nestedness.
- 4 Modularity. Modularity represents the extent to which networks are compartmentalized, i.e. the
- 5 tendency for subsets of species to be strongly connected together, while they are weakly connected
- to the rest of the network (Stouffer & Bascompte 2011). Modularity is measured as the proportion of
- 7 interactions between nodes of an arbitrary number of modules, as opposed to the random expectation.
- 8 Assuming a vector s which, for each node in the network, holds the value of the module it belongs to
- (an integer in [1, c]), Newman (2004) proposed a general measure of modularity, which is

$$Q = \sum_{m=1}^{c} \left(e_{mm} - a_m^2 \right)$$

10 , where c is the number of modules,

$$e_{mm} = \sum_{ij} \frac{\mathbf{A}_{ij}}{2c} \delta(\mathbf{s}_i, \mathbf{s}_j)$$

11 , and

$$a_m = \sum_n e_{mn}$$

12 ,

- with δ being Kronecker's function, returning 1 if its arguments are equal, and 0 otherwise. This
- formula can be *directly* applied to probabilistic networks. Modularity takes values in [0; 1], where 1
- indicates perfect modularity.
- 16 Centrality. Although node degree is a rough first order estimate of centrality, other measures are
- often needed. We derive the expected value of centrality according to Katz (1953). This measures
- measure generalizes to directed acyclic graphs (whereas other do not). For example, although eigen-
- vector centrality is often used in ecology, it cannot be measured on probabilistic graphs. Eigenvector

- centrality requires the matrix's largest eigenvalues to be real, which is not the case for all probabilistic
- 2 matrices. The measure proposed by Katz is a useful replacement, because it accounts for the paths
- 3 of all length between two species instead of focusing on the shortest path.
- 4 As described above, the expected number of paths of length k between i and j is $(\mathbf{A}^k)_{ij}$. Based on
- 5 this, the expected centrality of species i is

(9)
$$C_i = \sum_{j=1}^n \sum_{k=1}^\infty \alpha^k (\mathbf{A}^k)_{ji}.$$

- 6 The parameter $\alpha \in [0; 1]$ regulates how important long paths are. When $\alpha = 0$, only first-order
- 7 paths are accounted for (and the centrality is equal to generality). DG: to the degreeor generality?
- 8 the degree). When $\alpha = 1$, paths of all length are equally important. As C_i is sensitive to the size of
- 9 the matrix, we suggest normalizing by $C = \sum C$, so that

$$(10) C_i = \frac{C_i}{\mathbf{C}}.$$

- This results in the *expected relative centrality* of each node in the probabilistic network, which sums
- 11 to unity.
- 12 Species with no outgoing links. Estimating the number of species with no outgoing links (successors)
- can be useful when predicting whether, e.g., predators will go extinct. Alternatively, when prior
- information about traits are available, this can allows predicting the invasion success of a species in a
- novel community. A species has no successors if it manages *not* to establish any outgoing interaction,
- which for species i happens with probability

$$\prod_{j} (1 - A_{ij}).$$

1 The number of expected such species is therefore the sum of the above across all species:

(12)
$$\hat{PP} = \sum_{i} \left(\prod_{j} (1 - A_{ij}) \right).$$

and its variance is

(13)
$$\operatorname{var}(\hat{PP}) = \sum_{i} \left(\prod_{j} (1 - A_{ij}^{2}) - \prod_{j} (1 - A_{ij})^{2} \right)$$

- 3 Note that in a non-probabilistic context, species with no outgoing links would be considered primary
- 4 producers. This is not the case here: if interactions are probabilistic events, then e.g. a top predator
- 5 may have no preys, which do not mean it will not become a primary producer. For this reason, the
- 6 trophic position of the species may better be measured on the binary version of the matrix.
- 7 Species with no incoming links. Using the same approach as for the number of species with no out-
- 8 going links, the expected number of species with no incoming links is therefore

(14)
$$\hat{TP} = \sum_{i} \left(\prod_{j \neq i} (1 - A_{ji}) \right)$$

- 9 Note that we exclude self-interactions, as top-predators can, and often do, engage in cannibalism.
- 10 Number of species with no interactions. Predicting the number of species with no interactions (or
- whether any species will have at least one interaction) is useful when predicting whether species will
- be able to integrate into an existing network, for example. Note that from a methodological point of
- view, this can be a helpful a priori measure to determine whether null models of networks will have
- a lot of species with no interactions, and so will require intensive sampling.

1 A species has no interactions with probability

(15)
$$\prod_{i \neq i} (1 - A_{ij})(1 - A_{ji})$$

- 2 As for the above, the expected number of species with no interactions (free species) is the sum of this
- з quantity across all *i*:

(16)
$$\hat{FS} = \sum_{i} \prod_{j \neq i} (1 - A_{ij})(1 - A_{ji})$$

4 The variance of the number of species with no interactions is

(17)
$$\operatorname{var}(\hat{FS}) = \sum_{i} \left(A_{ij} (1 - A_{ij}) A_{ji} (1 - A_{ji}) + A_{ij} (1 - A_{ij}) A_{ji}^{2} + A_{ji} (1 - A_{ji}) A_{ij}^{2} \right)$$

- 5 Self-loops. Self-loops (the existence of an interaction of a species onto itself) is only meaningful in
- 6 unipartite networks. The expected proportion of species with self-loops is very simply defined as
- 7 Tr(A), that is, the sum of all diagonal elements. The variance is Tr(A \diamond (1 A)), where \diamond is the
- 8 element-wise product operation (Hadamard product).
- 9 Motifs. Motifs are sets of pre-determined interactions between a fixed number of species (Milo et
- 10 al. 2002; Stouffer et al. 2007), such as for example one predator sharing two preys. As there are an
- arbitrarily large number of motifs, we will illustrate the approach with only two examples.
- 12 The probability that three species form an apparent competition motif (one predator, two prey) where
- i is the predator, j and k are the prey, is

(18)
$$P(i, j, k \in \text{app. comp}) = A_{ij} (1 - A_{ji}) A_{ik} (1 - A_{ki}) (1 - A_{jk}) (1 - A_{kj})$$

- Similarly, the probability that these three species form an omnivory motif, in which i and j consume
- 2 k and i consumes j, is

(19)
$$P(i, j, k \in \text{omniv.}) = A_{ij}(1 - A_{ji})A_{ik}(1 - A_{ki})A_{jk}(1 - A_{kj})$$

3 The probability of the number of any motif m with three species in a network is given by

(20)
$$\hat{N}_{\mathbf{m}} = \sum_{i} \sum_{j \neq i} \sum_{k \neq j} P(i, j, k \in \mathbf{m})$$

- 4 It is indeed possible to have an expression of the variance of this value, or of the variance of any
- 5 three species forming a given motif, but their expressions become rapidly untractable and are better
- 6 computed than written.
- 7 **Network comparison.** The dissimilarity of a pair of (ecological) networks can be measured using
- 8 the framework set forth by Koleff et al. (2003). Measures of β -diversity compute the dissimilarity
- 9 between two networks based on the cardinality of three sets, a, c, and b, which are respectively the
- shared items, items unique to superset (network) 1, and items unique to superset 2 (the identity of
- which network is 1 or 2 matters for asymmetric measures). Supersets can be the species within each
- network, or the interactions between species. Following Poisot et al. (2012), the dissimilarity of
- two networks can be measured as either β_{WN} (all interactions), or β_{OS} (interactions involving only
- 14 common species), with $\beta_{OS} \leq \beta_{WN}$.
- 15 Within our framework, these measures can be applied to probabilistic networks. The expected values
- of \bar{a} , \bar{c} , and \bar{b} are, respectively, $\sum \mathbf{A}_1 \diamond \mathbf{A}_2$, $\sum \mathbf{A}_1 \diamond (1 \mathbf{A}_2)$, and $\sum (1 \mathbf{A}_1) \diamond \mathbf{A}_2$. Whether β_{OS} or β_{WN}
- is measured requires to alter the matrices A_1 and A_2 . To measure β_{OS} , one must remove all unique
- species; to measure β_{WN} , one must expand the two matrices so that they have the same species at the
- same place, and give a weight of 0 to the added interactions.

1 APPLICATIONS

In this section, we contrast the use of probabilistic measures to the current approaches of either using binary networks, or working with null models through simulations. When generating random net-3 works, what we call *Bernoulli trials* from here on, a binary network is generated by doing a Bernoulli trial with probability A_{ii} , for each element of the matrix. This generates networks that have only 0/15 interactions, and are realizations of the probabilistic network. This is problematic because higher order structures involving rare events will be under-represented in the sample, and because most naive approaches (i.e. not controlling for species degree) are likely to generate free species species with 8 no interactions, especially in sparsely connected networks frequently encountered in ecology (Milo et al. 2003; Poisot & Gravel 2014) – on the other hand, non-naive approaches (e.g. based on swaps 10 or quasi-swaps as explained in Jordano & Bascompte 2013) break the assumption of independence 11 between interactions. 12

Comparison of probabilistic networks. In this sub-section, we apply the above measures to a 13 bacteria-phage interaction network. Poullain et al. (2008) have measured the probability that 24 14 phages can infect 24 strains of bacteria of the *Pseudomonas fluorescens* species (group SBW25). 15 Each probability has been observed The (probabilistic) adjacency matrix was constructed by estimating 16 the probability of each phage-bacteria interaction though independent infection assays, and can take 17 values of 0, 0.5 (interaction is variable), and 1.0. We have generated a "Binary" network by setting 18 all interactions with a probability higher than 0 to unity, to simulate the results that would have been 19 obtained in the absence of estimates of interaction probability. 20

Measuring the structure of the Binary, Bernoulli trials, and Probabilistic network gives the following result (average, and variance when there is an analytical expression):

Measure	Binary	Bernoulli trials	Probabilistic
links	336	221.58 ± 57.57	221.52 ± 57.25
η	0.73	0.528	0.512
$\eta^{(R)}$	0.72	0.525	0.507

Measure	Binary	Bernoulli trials	Probabilistic
$\eta^{(C)}$	0.75	0.531	0.518
one consumer, two resources motif	<u>4784</u>	2089	2110
two consumers, one resource motif	<u>4718</u>	2116	2120

As these results show, transforming the probabilistic matrix into a binary one treating all interactions as having the same probability, *i.e.* removing the information about variability, (i) overestimates nestedness by ≈ 0.2 , and (ii) overestimates the number of links by 115.115, and (iii) underestimate the number of motifs (we have limited our analysis to the two following motifs: one consumer sharing two resources, and two consumers competing for one resource). For the number of links, both the probabilistic measures and the average and variance of 10^4 Bernoulli trials were in strong agreement (they differ only by the second decimal place). For the number of motifs, the difference was larger, but not overly so. It should be noted that, especially for computationally demanding operations such as motif-counting, the difference in runtime between the probabilistic and Bernoulli trials approaches

can be extremely important.

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Using Bernoulli trials had the effect of slightly over-estimating nestedness. The overestimation is 11 statistically significant from a purely frequentist point of view, but significance testing is rather mean-12 ingless when the number of replicates is this large and can be increased arbitrarily; what is important 13 is that the relative value of the error is small enough that Bernoulli trials are able to adequately re-14 produce the probabilistic structure of the network. It is not unexpected that Bernoulli trials are this 15 close to the analytical expression of the measures; due to the experimental design of the Poullain 16 et al. (2008) study, probabilities of interactions are bound to be high, and so variance is minimal 17 (most elements of A have a value of either 0 or 1, and so their individual variance is 0 – though their 18 confidence interval varies as a function of the number of observations from which the probability is 19 derived). Still, despite overall low variance, the binary approach severely mis-represents the structure 20 of the network. 21

- Null-model based hypothesis testing. In this section, we analyse 59 pollination networks from the
- 2 literature using two usual null models of network structure, and two models with intermediate con-
- 3 straints. These data cover a wide range a situations, from small to large, and from densely to sparsely
- 4 connected networks. They provide a good demonstration of the performance of probabilistic metrics.
- 5 Data come from the *InteractionWeb Database*, and were queried on Nov. 2014.
- 6 We use the following null models. First (Type I, Fortuna & Bascompte (2006)), any interaction
- between plant and animals happens with the fixed probability P = Co. This model controls for con-
- 8 nectance, but removes the effect of degree distribution. Second, (Type II, Bascompte et al. (2003)),
- 9 the probability of an interaction between animal i and plant j is $(k_i/R + k_j/C)/2$, the average of
- the richness-standardized degree of both species. In addition, we use the models called Type III in
- and out (Poisot et al. 2013), that use the row-wise and column-wise probability of an interaction
- respectively, as a way to understand the impact of the degree distribution of upper and lower level
- 13 species.
- Note that these null models will take a binary network, and through some rules turn it into a prob-
- 15 abilistic one. Typically, this probabilistic network is used as a template to generate Bernoulli trials
- and measure some of their properties, the distribution of which is compared to the empirical network.
- 17 This approach is computationally inefficient (Poisot & Gravel 2014), especially using naive models
- 18 (Milo et al. 2003), and as we show in the previous section, can yield biased estimates of the true
- 19 average of nestedness (and presumably other properties).
- 20 We measured the nestedness of the 59 (binary) networks, then generated the random networks under
- 21 the four null models, and calculated the expected nestedness using the probabilistic measure. For
- each null model i, the difference $\Delta_N^{(i)}$ in nestedness N is expressed as $\Delta_N^{(i)} = N \mathcal{N}^{(i)}(N)$, where
- 23 $\mathcal{N}^{(i)}(N)$ is the nestedness of null model *i*. Our results are presented in Figure 1.
- There are two striking results. First, empirical data are consistently *more* nested than the null expec-
- tation, as evidenced by the fact that all Δ_N values are strictly positive. Second, this underestimation
- 26 is *linear* between null models I and II(in that it does not depends on how nested the empirical network
- 27 is), although null model II is always closer to the nestedness of the empirical network (which makes

- sense, since null model II incorporates the higher order constraint of respecting the degree distribu-
- 2 tion of both levels). That the nestedness of the null model probability matrix is so strongly determined
- 3 by the nestedness of the empirical networks calls for a closer evaluation of how the results of null
- 4 models are interpreted (especially since Bernoulli simulations networks generated using Bernoulli
- 5 trials revealed a very low variance in the simulated their nestedness).
- There is a strong, and previously unaccounted for, circularity in this approach: empirical networks are compared to a null model which, as we show, has a systematic bias *and* a low variance (in simulationsthe properties of the networks it generates), meaning that differences in nestedness that
- 9 are small (thus potentially ecologically irrelevant) have a good chance of being reported as signifi-
- cant. Interestingly, models III in and III out made overall fewer mistakes at estimating nestedness –
- 11 resp. respectively 0.129 and 0.123, compared to resp. 0.219 and 0.156 for model I and II. Although
- the error is overall sensitive to model type (Kruskal-Wallis $\chi^2 = 35.80$, d.f. = 3, $p \le 10^{-4}$), the three
- pairs of models that where significantly different after controlling for multiple comparisons are I and
- II, I and III in, and I and III out (model II is not different from either models III in or out).

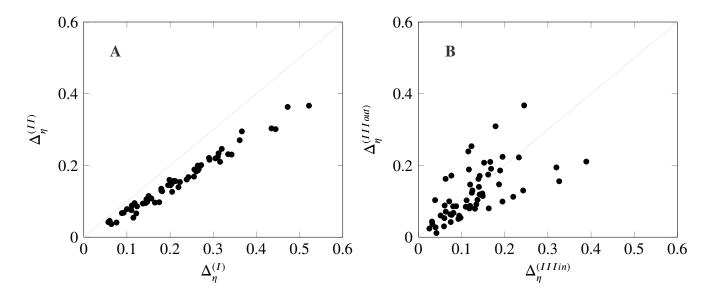


FIGURE 1. Results of the null model analysis of 59 plant-pollination networks. A. There is a consistent tendency for (i) both models I and II to estimate less nestedness than in the empirical network, although null model II yields more accurate estimates. B. Models III in and III out also estimate less nestedness than the empirical network, but neither has a systematic bias. For each null model i, the difference $\Delta_{\eta}^{(i)}$ in nestedness η is expressed as $\Delta_{\eta}^{(i)} = \eta - \mathcal{N}^{(i)}(\eta)$, where $\mathcal{N}^{(i)}(\eta)$ is the nestedness of null model i.

In short, this analysis reveals that (i) the null expectation of a network property under randomization scenarios can be obtained through the analysis of the probabilistic matrix, instead of the analysis of 2 simulated Bernoulli networks; (ii) Different different models have different systematic biases, with models of the type III performing overall better for nestedness than any other models. This can be explained by the fact that nestedness of a network, as expressed by Bastolla et al. (2009), is the average of a row-wise and column-wise nestedness. These depend on the species degree, and as such should be well predicted by models III. The novelty of this approach is that, instead of having to evaluate the measure for thousands of replicates, an *unbiased* estimate of its mean can be obtained in a fraction of the time using the measures described here. This is particularly important since, as demonstrated by Chagnon (2015), the generation of null randomization is subject to biases in the 10 range of connectance where most ecological networks are. Our approach is essentially a bias-free, 11 time-effective way of estimating the expected value of a network property. 12

IMPLICATIONS FOR DATA COLLECTION DISCUSSION

13

Understanding the structure of ecological networks, and whether it relates to ecosystem properties, is emergent as a key challenge for community ecology. A proper estimation of this structure requires tools that address all forms of complexity, the most oft-neglected yet pervasive of which is the fact that interactions are variable. By developing these metrics, we allow future analyses of network structure to account for this phenomenon. There are two main considerations highlighted by this methodological development. First, in what way are probabilistic data independent; second, what are the implications for data collection.

Non-independance of interactions. We developed and presented a set of measures to quantify the expected network structure, using the probability that each interaction is observed or happens, in a way that do not require time-consuming simulations. Our framework is set up in such a way that the probabilities of interactions are considered to be independent. This is an over-simplification of the ecological reality, where different interactions are known to have effects on one another (Golubski & Abrams 2011; Sanders & Veen 2012; Ims *et al.* 2013). Yet we feel that, as a first approximation, this assumption is reasonable. There is a strong methodological argument for which the non-independance

- of interactions cannot currently be robustly accounted for: analytical expectations for non-independent
- 2 Bernoulli events require to know the full dependence structure. Not only does it severely limits the
- 3 ability to provide measures of network structure, it requires a far more extensive sampling that what
- 4 is needed to obtain an estimate of the probability of interactions one by one.
- 5 Estimates of interaction probabilities. Estimating interaction probabilities based on species abun-
- 6 dances (Olito & Fox 2014; Canard et al. 2014) do not , for example, yield independent probabili-
- 7 ties: changing the abundance of one species changes all probabilities in the network. They are not
- 8 Bernoulli events either, as the sum of all probabilities derived this way sums to unity. On the other
- 9 hand, "cafeteria experiments" (in which individuals from two species are directly exposed to one
- another to observe whether or not an interaction occurs) give truly independent probabilities of in-
- teractions; even a simple criteria, such as the frequency of interactions when the two species are put
- together, is a way of estimating probability. Using the approach outline by (???outlined by Poisot
- 13 et al. (2015), both sources of information (species abundance, trait distribution, and the outcome of
- experiments) can be combined to estimate the probability that interactions will happen in empirical
- communities. This effort requires improved communications between scientists collecting data and
- scientists developing methodology to analyze them.
- 17 Another way to obtain approximation of the probability of interactions is to use spatially replicated
- sampling. Some studies (Tylianakis et al. 2007; Olito & Fox 2014; Carstensen et al. 2014; Trø-
- 19 jelsgaard et al. 2015) surveyed the existence of interactions at different locations, and a simple ap-
- 20 proach of dividing the number of observations of an interaction by the number of co-occurence of
- 21 the species involved will provide a (somewhat crude) estimate of the probability of this interaction.
- 22 This approach requires extensive sampling, especially since interactions are harder to observe than
- species (Poisot et al. 2012; Gilarranz et al. 2014), yet it enables the re-analysis of existing datasets
- 24 in a probabilistic context.
- 25 Understanding the structure of ecological networks, and whether it relates to ecosystem properties,
- 26 is emergent as a keychallenge for community ecology. A proper estimation of this structure requires
- 27 tools that address all forms of complexity, the most oft-neglected yet pervasive of which is the fact

- 1 that interactions are variable. By developing these metrics, we allow future analyses of network
- 2 structure to account for this phenomenon
- 3 Implications for data collection. An important development is that, when estimating probabilities
- 4 from observational data, it becomes possible to have an estimate of how robust the sampling is. How
- 5 completely a networks is sampled is a key, yet an often overlooked one, driver of some measures of
- 6 structure (Nielsen & Bascompte 2007; Chacoff et al. 2011). The probabilistic approach allows to
- 7 estimate the *confidence interval* of the interaction probability, knowing the number of samples used
- 8 for the estimation. Assuming normally distributed observational error (this can be generalized for
- 9 other structure of error), the confidence interval around a probability p estimated from n samples is

$$\epsilon = z\sqrt{\frac{1}{n}p(1-p)}$$

For a 95% confidence interval, $z \approx 1.96$. If an interaction is estimated to happen at p = 0.3, its 95%

confidence interval is [0; 0.74] when estimated from four samples, [0.01; 0.58] when estimated from

ten, and [0.21; 0.38] when estimated from a hundred. This points out to a fundamental issue with

the sampling of networks: a correct estimate of the probability of interaction from observational data

14 is tremendously difficult to achieve, and the development of predictive models should be a research

priority since it partly alleviates this difficulty.

16 **Implementation.** We provide these measures in a free and open-source (MIT license) library for

17 the julia language, available at http://github.com/PoisotLab/ProbabilisticNetwork.jl.

18 The code can be cited using the following DOI: **TODO**. A user guide, and API reference, can be

found at http://probabilisticnetworkjl.readthedocs.org/en/latest/. The code library

20 undergoes automated testing and coverage analysis, the results of which can be accessed from the

21 GitHub page given above.

22 **Acknowledgements:** This work was funded by a CIEE working group grant to TP, DG, and DBS. TP

23 is funded by a starting grant from the Université de Montréal, and a Discovery grant from NSERC.

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