315.10 - Change of Vars in Multiple Integrals

Suppose x = x(u,v) & y = y(u,v) (so we're changing (x,y) > (u,v) ]

Def: The Jacobian of this trans formation is

$$\mathcal{J} = \det \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix} \qquad \text{In book} = \frac{\partial (x,y)}{\partial (u,v)}.$$

Ex: le x= rcos 0 & y= rsin G, then

= rcos20+rsim20

= r. [we assume voo]

Theorem: If changing from (x,y) to (u,v), then

Sf f(x/y) dA =  $\int \int f(x(u,u),y(u,v)) \int \int du dv$ ,

from  $\int \int f(x,y) dx dy$  where D' is the image of D under this dydx transformation.

transformation.

Ex: In polar, x=rcost y=rsint 151 if r>0

(x,y) > (r,o) Sf(x,y)dA = Sf(rcost,rsint) r drdt

In 3-var

· suppose x= x(u,v,w), y= y(u,v,w), Z= Z(u,v,w).

The Jacobian of (xy,z) +> (y,v,w) is

$$\int = \det \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \end{pmatrix} = \frac{\mathcal{O}(x, y, z)}{\mathcal{O}(u, v, w)} \text{ in bodc.}$$

Ex: In cylindrical,  $x \mapsto r\cos\theta$   $(x,y,z) \mapsto (r, \theta,z)$  $z \mapsto z$ 

$$\Rightarrow \int = det \begin{pmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial r} & \frac{\partial x}{\partial r} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial r} & \frac{\partial y}{\partial r} \end{pmatrix} = det \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix}$$

= coso | rcoso 0 | -- rsin 6 | sin 6 0 | + 0

= 
$$r\cos^2\theta + r\sin^2\theta = \Gamma.$$
 (>0 again)

Ex: In cylindrical; (x,y,z)+> (r,o,z) & 151 if r>0.

SSS f(x,y,z)dN = SSS f(roso,rsino,z) r drdbdz

Ex: Derive the rect > sphenical triple integral form.

sol X+> psin 0 cos 6 y+> psin 0 sin 6 z+> pcos 0

> J= det sin 0 sin 6 psin 0 cos 6 pcos 0 sin 6

cos 0 0 - psin 0 =  $sin \Phi \cos \theta$  |  $p \sin \Phi \cos \theta$  |  $p \sin \Phi \cos \theta \sin \theta$  |  $p \cos \Phi \sin \theta$  |  $p \cos \Phi \sin \theta$  |  $p \cos \Phi \sin \theta$  |  $p \sin \Phi \cos \theta \sin \theta$  |  $p \cos \Phi \cos \theta \sin \theta$  |  $p \cos \Phi \sin \theta$  |  $p \cos \Phi$  | p= sin B cos 6 [-p2 sin2 B cos 6] + p sin & sin 6 [-p sin2 \$ sin6 - p cos2\$ sin6] + pcospcos6 [- psint cost cost  $= -\rho^2 \sin^3 \Phi \left[\cos^2 \theta^{\dagger} \sin^2 \theta\right] + -\rho^2 \cos^2 \Phi \sin \Phi \left[\sin^2 \theta + \cos^2 \theta\right]$  $-p^2 \sin^3 \phi - p^2 \cos^2 \phi \sin \phi = -p^2 \sin \phi \left[ \sin^2 \phi + \cos^2 \phi \right]$ = - p2 sind. => |J| = e2 sind => <u>sprental</u>': SSSf(x,y,z)dV= SSSf(x(...),(y(...),z(...)) [02 sin dp d d d d ...