

● Synchronization (Cont.)

- 3 requirements for critical section: mutual exclusion, forward progress, Bounded waiting
- Classical implementation is a lock: $\text{lock}(L) \rightarrow \text{use/update data} \rightarrow \text{unlock}(L)$
- ▶ How would you implement a lock? Main problem is how to check & set atomically

② ~~Write (turn = 0)~~ Example w/ 2 threads w/ ids 0 and 1:

```
lock(x) {
  while (turn != tid);
  x = 1;
}
```

```
unlock(x) {
  x = 0;
  turn = 1 - tid;
}
```

← NOTE: x is really not necessary here

- This provides mutual exclusion - turn is either 0 or 1, so only one thread gets in.
- NOTE: we assume lock & unlock are used correctly (no unlock if not holding lock).
- But there is no bounded waiting - say turn = 0 initially, thread 0 gets it, releases it, now turn = 1 and thread 0 can't get the lock again ever, unless thread 1 gets it and releases it.
- BETTER LOCKING (THIS ACTUALLY WORKS):

flag[0] = flag[1] = 0;
turn = 0;
shared state

```
lock(x) {
  int other = 1 - tid;
  flag[tid] = 1;
  turn = other;
  while (flag[other]
    && turn == other);
}
```

```
unlock(x) {
  flag[tid] = 0;
}
```

▶ Let's make this easier (assume 1 CPU)...

WORKS BECAUSE:

lock(x); → disable interrupts
CS ... ← no interrupts (also syscalls) here
unlock(x); → enable interrupts

→ this provides mutual exclusion, forward progress, and bounded waiting

▶ With Few CPUs this will not work

- Disable interrupts just says "do not interrupt me on this CPU" - it does not impact stuff that is running on other CPUs. I.e. hardware
- Solution is to support special instructions in the computer architecture:

Example: TEST-AND-SET instruction:

← ATOMICALLY

→ if test is not true then set to be true ACROSS ALL CPUS!!

In hardware, this is usually done by locking the bus, so only 1 CPU can access the data for the test, then performing the check/set (not exactly cheap!).

COMSW4118-9-2

NOTE: we use busy waiting / spinning

10/3/2017

Now, we can implement as:

lock(x) {

while (TESTANDSET(x));

}

unlock(x) {

x = 0; ← assume assignment is atomic

}

where TEST-AND-SET(x) sets x to 1 if it is 0 and returns its old value.

SPINNING →

COMPARE-AND-SWAP() in textbook is similar in nature and also requires hardware support.

We use busy wait / spinning to wait for the lock above. If we have 4 cores and one thread has the lock on one and three threads are waiting for it on the other 3 cores (spinning in the while) we waste a lot of cycles.

With multiple locks, you may have a deadlock (ex: ABBA deadlock) or the philosophers problem dining

DeadLock conditions:

- Mutual exclusion - when one holds the lock, others can't get it
- Hold and wait - one has a lock and is waiting for another
- No preemption - one can't be forced to release lock it has
- Circular wait - like $A \rightarrow B \rightarrow C$

Rules to avoid deadlocks:

- Do not grab multiple locks
- If you must, grab them in the same order

Back to disabling interrupts - disabling them for the duration of the whole critical section is overkill and not necessary...

- say we disable them only for the duration of acquiring the lock...

Semaphore:

PCs: ← down
while (s <= 0);
s--;

V(s): ← up
s++;

AND USE A SEMAPHORE ?

Then we can implement lock/unlock as:

lock(x) {

disable interrupts;

while (s <= 0);

s--;

enable interrupts

}

unlock(x) {

disable interrupts;

s++;

enable interrupts;

}

BUT: This does not work well in practice: on a single processor, a thread can get a lock, then another thread would block forever waiting for the lock w/ interrupts disabled!