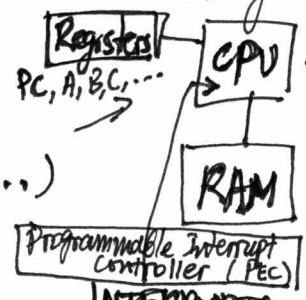
COMSW4118-4-1 9/14/2017

- Last time: fork(), exec() – to create/fork and exec; wait()/waitpid() ← copies file descriptors as well!
- exit() - kills the process and exits w/ return code. [read, write, open, close, getpid]
- **Pipes** - connections b/n different processes, created by a system call:
  `int pipe(int fd[2])` where fd[0] is to read and fd[1] is to write
  each process needs to close the end it is not using.
  NOTE: anonymous pipes like the above can only be used b/n parent and child.
- dup() takes a file descriptor and mirrors it into another one (duplicates it) either to the next available or, in the case of dup2() to a provided one closing it first, if necessary
- chdir() to change working directories

- How do the OS services provided (system calls) work behind the scenes?
  Going back to structure, the kernel is where the system calls are implemented.

APPS
—System calls—
KERNEL (OS)
HARDWARE (CPU...)

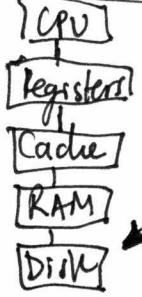
Taking a bottom-up view:



runs instruction in sequence has program counter (PC) to store next instruction address

Ex. Instructions: add, subtract, load...
Branch and Loop instructions change the PC to sth. diff. than ++PC.

Interrupting an interrupt? → depends on hardware; some allows only 1 interrupt, some allows nested ones.



← Memory Hierarchy
Slower, so we use interrupts when read done, so we can keep going meanwhile

- To stop what CPU is doing & take care of urgent request
- In hardware, b/n each instruction the CPU checks for interrupts
- If one is found, CPU stops, remembers where it left off (saving PC & whole CPU state) and processes the interrupt
- Once done, the PC & state are restored & CPU goes on.
- Examples: keyboard input, devices in general (primary source), mouse move, hard drive, etc.
- Devices interface w/ a Programmable Interrupt Controller (PIC) which actually forwards interrupts to the CPU.

- Interrupts get handled by an Interrupt Handler, code defined by the OS this is installed by the OS in a place where the hardware knows to find it.
  - The interrupt handler is software, hence it uses the CPU (PC, etc.)
  - Most interrupt handlers are short: need to work quickly to not interrupt for long.
  - The interrupt handler saves the state and subsequently restores it.
    - What if it gets interrupted while processing an interrupt? (it runs on CPU, CPU checks for interrupts) A lot of systems just do not allow this...