The sem-sfe manual

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1 Structure of the project

The tool is divided into multiple modules, namely:

- sem-sfe-algorithm,
- sem-sfe-cli,
- sem-sfe-common,
- sem-sfe-pg,
- sem-sfe-mu-ald.

Module sem-sfe-algorithm is the core of the project, it contains an implementation of the local algorithm for verifying solutions of systems of fixpoint equations, over complete lattices. Module sem-sfe-cli is a command line

interface. Modules sem-sfe-pg and sem-sfe-mu-ald both use the local algorithm. Modules sem-sfe-pg and sem-sfe-mu-ald both use the local algorithm. They take as input some specification language and some verification logic. Then, they translate this input to a system of fixpoint equations, and generate the correct symbolic \exists -moves for their respective operators, after which they call the local algorithm to solve the verification problem, and the output is passed to sem-sfe-cli to be printed. Module sem-sfe-common exposes a common interface that sem-sfe-pg and sem-sfe-mu-ald use to provide their results to the command line interface module, it avoids circular dependency.

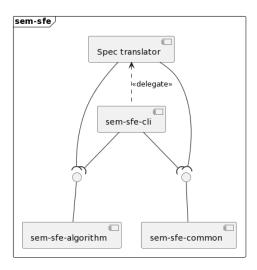


Figure 1: An informal component diagram of sem-sfe.

Figure 1 represents how the various modules of sem-sfe are related. In the diagram, Spec translator represents both sem-sfe-pg and sem-sfe-mu-ald. From the diagram we understand that sem-sfe-algorithm offers an interface, represented by the ball notation, which is accessed by every other module. The sem-sfe-common crate exposes a trait, represented in the diagram as an interface, via the ball notation. The goal of this trait is to uniform the results computed by Spec translator, so that sem-sfe-cli can easily access and print them via the same common interface. Spec translator module is used by sem-sfe-cli: the former takes as input a specification file and some verification logic, and provides to the latter the results of the computation.

2 Installation

You should first have a working installation of Rust and Cargo, 1.73 and above. This project has not been tested with versions of Rust below 1.73.

To compile this project download it from this repository, and run cargo build -r from the terminal emulator. The compiled executable should be located in sem-sfe/target/release.

3 Usage

This application is a command line interface. An invocation of sem-sfe looks like this:

```
sem-sfe-cli [OPTIONS] <COMMAND>
```

where [OPTION] is a list of flags and <COMMAND> is the name of the type of input we are going to feed to the tool.

There are 2 possible options, which can be enabled:

- -n or -normalize If enabled, the underlying system of fixpoint equations is normalized during the preprocessing phase.
- -e or -explain A flag that makes the program print useful information to stdout: the underlying system of fixpoint equations, and the composed symbolic ∃-moves.

A <COMMAND> string is one of the following: debug, pg, mu-ald, followed by their respective inputs. We are going to introduce these commands in the next sections.

3.1 The debug command

The debug command has the following structure:

```
sem-sfe-cli [OPTIONS] debug <ARITY>\
<FIX_SYSTEM> <BASIS> <MOVES_SYSTEM> <ELEMENT_OF_BASIS> <INDEX>
```

<ARITY> A path to a file containing definitions of functions. The file must be formatted as follows: each line contains a string of characters and a natural number. The string represents the name of a function, which is going to be used in the system of fixpoint equations. The natural

- number represents the arity of the function. The names and and or can be declared, but will be ignored.
- <FIX_SYSTEM> A path to a file containing the definition of a system of fixed point equations. A function must be an either an and or or function, or it must be specified in the arity file. We give a precise grammar specification in section Input grammar specification.
- **<BASIS>** A path to a file containing all the elements of the basis. Each new line must contain a string, which is an element of the basis.
- <MOVES_SYSTEM> A path to a file containing the symbolic ∃-moves for the system of fixpoint equations. There must be a symbolic ∃-move for all possible combinations of functions introduced in the file, and basis elements introduced in the file. We give the grammar specification in section Input grammar specification.
- **<ELEMENT_OF_BASIS>** The element of the basis which we want to verify is part of the solution of the system of fixpoint equations.
- <INDEX> A number representing the equation, and thus the variable which we want to check is above, with respect to some ordering, the basis element.

3.1.1 Input grammar specification

We now give the grammar, in EBNF form, for systems of fixpoint equations, symbolic \exists -moves, a basis and the arity specification.

```
 \langle eq\_list\rangle \ ::= \ \langle eq\rangle \ \langle eq\_list\rangle \ ; \ | \ \langle eq\rangle \ ; 
 \langle eq\rangle \ ::= \ \langle id\rangle \ = \max \ \langle or\_exp\_eq\rangle \ | \ \langle id\rangle \ = \min \ \langle or\_exp\_eq\rangle 
 \langle atom\rangle \ ::= \ \langle id\rangle \ | \ (\ \langle or\_exp\_eq\rangle \ ) \ | \ \langle custom\_exp\_eq\rangle 
 \langle and\_exp\_eq\rangle \ ::= \ \langle atom\rangle \ (\text{and} \ \langle atom\rangle)^* 
 \langle or\_exp\_eq\rangle \ ::= \ \langle and\_exp\_eq\rangle \ (\text{or} \ \langle and\_exp\_eq\rangle)^* 
 \langle custom\_exp\_eq\rangle \ ::= \ \langle op\rangle \ (\ \langle or\_exp\_eq\rangle \ (,\ \langle or\_exp\_eq\rangle)^* \ ) 
 \langle id\rangle \ ::= \ " \ (\text{a C-style identifier}) \ " 
 \langle op\rangle \ ::= \ " \ (\text{any ASCII string}) \ "
```

The grammar above represents a system of fixpoint equations. Notice that the syntactic category and_exp_eq has a higher precedence than or_exp_eq , this way we enforce the precedence of the operator \land over \lor . Tokens id and op are strings, the latter represents the name of an operator provided by the user. If the goal is to parse μ -calculus formulae, op would accept for example strings such as "diamond", or "box". Note that all operators are expressed in terms of a function, except for and and or, which are conveniently already provided, and are infix. A C-style identifier respects the following regex pattern $[a-zA-Z_{-}][a-zA-Z0-9_{-}]*$.

```
 \langle sym\_mov\_list\rangle \ ::= \ \langle sym\_mov\_eq\rangle \ \langle sym\_mov\_list\rangle \ ; \ | \ \langle sym\_mov\_eq\rangle \ ; 
 \langle sym\_mov\_eq\rangle \ ::= \ \text{phi} \ (\ \langle id\rangle \ ) \ (\ \langle num\rangle \ ) \ = \ \langle disjunction\rangle 
 \langle conjunction\rangle \ ::= \ \langle atom\rangle \ (\text{and} \ \langle atom\rangle)^* 
 \langle disjunction\rangle \ ::= \ \langle conjunction\rangle \ (\text{or} \ \langle conjunction\rangle)^* 
 \langle atom\rangle \ ::= \ [\ \langle id\rangle \ , \ \langle num\rangle \ ] \ | \ \text{true} \ | \ \text{false} \ | \ (\ \langle disjunction\rangle \ ) 
 \langle id\rangle \ ::= \ " \ (\ a \ C\text{-style} \ identifier \ ) \ " 
 \langle num\rangle \ ::= \ \mathbb{N}
```

The grammar above represents the symbolic \exists moves for some operators. Note that, similarly to what we did for the grammar of systems of fixpoint equations, the conjunction operator has a greater precedence than the disjunction operator.

We now give the grammar of a basis: it is simply a list of strings, separated by the new-line character n.

```
\langle basis \rangle \ ::= \ \langle basis\_elem \rangle \ \backslash n \ \langle basis \rangle \ | \ \langle basis\_elem \rangle \langle basis\_elem \rangle \ ::= \ " \ ( \ any \ ASCII \ string \ ) \ "
```

Follows the grammar specification of a file containing the name of the operators and their arity.

```
\langle arity \rangle ::= \langle op\_name \rangle \langle num \rangle \n \langle arity \rangle | \langle op\_name \rangle \langle num \rangle
\langle op\_name \rangle ::= " ( a C-style identifier ) " \langle num \rangle ::= \mathbb{N}
```

3.2 The mu-ald command

The mu-ald command calls the sem-sfe-mu-ald module. It produces a fixpoint system and a list of symbolic \exists -moves from the given labelled transition system, and μ -calculus formula.

```
sem-sfe-cli [OPTIONS] mu-ald <LTS_ALD> <MU_CALC_FORMULA> <STATE>
```

- <LTS_ALD> A path to a file describing a labelled transition system in the Aldebaran format, from the CADP toolset. The following link contains a description of the grammar: https://www.mcrl2.org/web/user_manual/tools/lts.html.
- <MU_CALC_FORMULA> A path to a file containing a μ -calculus formula. The grammar is described in section Mu-calculus formulae.
- **<STATE>** A string which represents a state. Since the Aldebaran specification uses natural numbers as nodes' names, the state must be a number as well. We want to verify whether if it satisfies the property described by the μ -calculus formula.

3.2.1 Mu-calculus formulae

We want to parse the following syntax.

$$A ::= a \mid true \mid \neg a$$

$$\varphi ::= \mathbf{t} \mid \mathbf{f} \mid x \mid \varphi \lor \varphi \mid \varphi \land \varphi \mid \mu x. \varphi \mid \nu x. \varphi \mid \langle A \rangle \varphi \mid [A] \varphi$$

With $a \in Act$ and $x \in PVar$. We designed a grammar that avoids, as much as possible, left recursion. The following EBNF grammar describes a μ -calculus formula.

```
 \langle atom \rangle \; ::= \; \mathsf{tt} \; | \; \mathsf{ff} \; | \; ( \langle mu\_calc \rangle \; ) \; | \; \langle id \rangle 
 \langle modal\_op \rangle \; ::= \; \langle \langle label \rangle \; > \langle atom \rangle \; | \; [ \; \langle label \rangle \; ] \; \langle atom \rangle 
 \langle conjunction \rangle \; ::= \; \langle modal\_op \rangle \; (\&\& \; \langle modal\_op \rangle) 
 \langle disjunction \rangle \; ::= \; \langle conjunction \rangle \; ( | | \; \langle conjunction \rangle) 
 \langle fix\_op \rangle \; ::= \; \mathsf{mu} \; \langle id \rangle \; . \; \langle disjunction \rangle \; | \; \mathsf{nu} \; \langle id \rangle \; . \; \langle disjunction \rangle 
 \langle mu\_calc \rangle \; ::= \; \langle fix\_op \rangle \; | \; \langle disjunction \rangle 
 \langle label \rangle \; ::= \; \mathsf{true} \; | \; \langle id \rangle \; | \; \langle id \rangle 
 \langle id \rangle \; ::= \; \mathsf{"} \; ( \; \mathsf{a} \; \mathsf{C}\text{-style} \; \mathsf{identifier} \; ) \; \mathsf{"}
```

Moreover, we designed this grammar to respect some standard conventions: modal operators [a] and $\langle a \rangle$ bind stronger than \vee , \wedge , and the fixpoint operators capture everything after the . character. The consequence is that a formula $\mu x(([a]x) \vee \nu y(\langle a \rangle y \wedge f))$ can be written as $\mu x.[a]x \vee \nu y.\langle a \rangle y \wedge f$, minimizing the use of parenthesis. Whenever we wish to add to a modal operator anything other than the syntactic categories t, f or $x \in PVar$, parenthesis must be used, this is due to the inherent limitations of the type of parser we used. This is expressed by the rule $\langle atom \rangle$.

3.3 The pg command

The pg command uses the sem-sfe-pg module, to build a system of fixed point equations and the symbolic \exists -moves from a parity game, and verify whether if the given node is winning for player \exists (or player 0, or player Even).

This is a typical command for the pg command:

```
sem-sfe-cli [OPTIONS] pg <GAME_PATH> <NODE>
```

<GAME_PATH> A path to a file containing a PGSolver file specification.

<NODE> A string which must refer to the name of the node, if specified in the input file, or to the id of a node.

4 Examples and performance considerations

In this section we show two examples of executions of sem-sfe. We solve the same two examples with the tools Oink [1] and mCRL2 [2]. We use them to to highlight our tool's performance. Every command is run on the same machine. We are going to show an example with a parity game, and one using the μ -calculus.

We use the following parity game, the same as in in Figure ??.

```
parity 4;
0 6 1 4,2 "Africa";
4 7 1 0 "Antarctica";
1 5 1 2,3 "America";
3 6 0 4,2 "Australia";
2 8 0 3,1,0,4 "Asia";
```

We want to know whether player \exists wins from node Antarctica, to do that we run the following command.

```
> cargo run -r -- pg tests/parity_games/test_03.gm Antarctica
```

File test_03.gm contains the game specification. The command cargo run -r compiles and run sem-sfe in release mode, which creates an optimised executable. The compilation might take a few seconds. Then, aside from the compilation messages, the output is the following.

```
Preprocessing took: 0.000022963 sec.
Solving the verification task took: 0.000010881 sec.
Result: Player 1 wins from vertex Antarctica
```

Before running the local algorithm there is a preprocessing phase. The preprocessing phase encompasses extracting the fixpoint system from the specification, generating, and composing the symbolic \exists -moves. In the case of parity games the preprocessing phase consists in extracting, the system of fixpoint equations, and composing the moves. Symbolic \exists -moves for conjunction and disjunction, the only operators appearing in this instance, are provided by default. In the case of the sem-sfe-mu-ald, the preprocessing phase is comprised of extracting the system of fixpoint equations from the μ -calculus formula, generating the symbolic moves for each operator, and composing them into the symbolic \exists -moves for the system.

We solve the same parity game, on the same machine, with Oink, via the following command.

> oink tests/parity_games/test_03.gm -p

The output of the command is shown below.

```
Γ
    0.00] parity game with 5 nodes and 11 edges.
0.00] parity game reindexed
Γ
    0.00] parity game renumbered (4 priorities)
Γ
    0.00] no self-loops removed.
Г
    0.00] 2 trivial cycles removed.
    0.00] preprocessing took 0.000017 sec.
Γ
0.00] solved by preprocessor.
Γ
    0.00] total solving time: 0.000033 sec.
0.00] current memory usage: 4.62 MB
Γ
    0.00] peak memory usage: 4.75 MB
```

[0.00] won by even: America Asia Australia

[0.00] won by odd: Africa Antarctica

In this very simple example sem-sfe performance are on par with Oink's, even thought Oink finds the global solution, instead of just a winner from a node.

We provide another example, this time we verify a property on a mCRL2 specification. We use the "Gossips" example from the tutorial of mCRL2, which can be found at the following link: https://www.mcrl2.org/web/user_manual/tutorial/gossip/index.html. In order to use such specification in sem-sfe, we convert it to a labelled transition system in the Aldebaran format, using the tool ltsconvert, from mCRL2's toolset. We want to check deadlock liveness.

```
> cargo run -r -- mu-ald tests/example_mucalc/gossips.aut \
  tests/example_mucalc/deadlock-liveness 0
```

We pass as input to the command line interface the Aldebaran specification file, gossips.aut, and the file containing the μ -calculus formula. We want to perform local model checking from state 0 of the labelled transition system.

```
Preprocessing took: 0.02513744 sec. Solving the verification task took: 0.000013575 sec. Result: The property is satisfied from state 0
```

To do the same with mCRL2, we run the following commands. We first need to translate the mCRL2 specification the to .1ps, which is a file format used internally by mCRL2.

> mcrl22lps gossip.mcrl2 gossip.lps

The command below takes a μ -calculus formula, in <code>gossip.mcf</code>, and the file we just generated <code>gossip.lps</code>, and builds a type of system of boolean fixpoint equations, called parameterised boolean equation system. This process took 0.014746 seconds to finish.

> lps2pbes --formula=gossip.mcf gossip.lps gossip.pbes --timings Finally, we solve the model-checking task, via the following command.

> pbes2bool -rjittyc gossip.pbes --timings

Below we show the output printed after the execution.

true

- tool: pbes2bool timing: instantiation: 1.397916

solving: 0.002444 total: 1.424587

Just as in the previous case, we remind that the solution provided by mCRL2 is global: there is no deadlock configuration in the whole system. In sem-sfe we only verify that there is no deadlock from state 0. Here sem-sfe shows measurably better performance.

References

- [1] T. van Dijk, 'Oink: An implementation and evaluation of modern parity game solvers', in *Tools and algorithms for the construction and analysis of systems*, D. Beyer and M. Huisman, Eds., Cham: Springer International Publishing, 2018, pp. 291–308.
- [2] J. F. Groote and M. R. Mousavi, *Modeling and Analysis of Communicating Systems*. The MIT Press, 2014. doi: 10.7551/mit-press/9946.001.0001.