

Results for FULL (in 00:00:01.779):

SET_RCHD_AT:

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q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Alarm_Activation ]-> q1 = -(p0 =
CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), (p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Alarm_Deactivation ]-> q0 = -
(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Alarm_Deactivation ]-> q2 = -
(p0 = CS=0), (p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Be_Activation ]-> q0 = -(p0 =
CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Car_Moving ]-> q0 = -(p0 =
CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Car_Stopping ]-> q0 = -(p0 =
CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Car_Stopping ]-> q2 = -(p0 =
CS=0), (p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Ch_Sec_Deactivation ]-> q4 = -
(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Doors_Closing ]-> q0 = -(p0 =
CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Doors_Closing ]-> q2 = -(p0 =
CS=0), (p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) - [ Doors_Opening ]-> q0 = -(p0 =

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SET RCHD EXPECTED AT:

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q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) -[ Alarm_Activation ]-> q1 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), (p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) -[ Alarm_Deactivation ]-> q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) -[ Alarm_Deactivation ]-> q2 = -(p0 = CS=0), (p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) -[ Be_Activation ]-> q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) -[ Car_Moving ]-> q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) -[ Car_Stopping ]-> q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))
q0 = -(p0 = CS=0), -(p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1)) -[ Car_Stopping ]-> q2 = -(p0 = CS=0), (p1 = and(Tr=0, Mv=0, Do=0, Us=1, Lo=0, Gl=0, AC=0)), -(p2 = and(Tr=0, Lo=1, Do=0, Us=1))

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SET_UNRCHD_AS:

SET UNRCHD EXPECTED AS:

SET_UNRCHD_AT:

SET_UNRCHD_EXPECTED_AT:

TIME_ATS: 00:00:01.779