

## Samuel Triest

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Education	<b>Carnegie Mellon University</b> <b>Degree(s):</b> M.S. in Robotics	<b>Fall 2020 - Spring 2022</b>
	<b>University of Rochester</b> <b>Degree(s):</b> B.S. in Computer Science, B.A. in Business, minor in Electrical Engineering <b>GPA:</b> 3.99/4.00 ( <i>Summa cum laude</i> ) <b>Advisors:</b> <a href="#">Thomas Howard</a> , <a href="#">Yuhao Zhu</a> <b>Distinctions:</b> Highest Honors in Research, Beta Gamma Sigma, Phi Beta Kappa <b>Relevant Coursework:</b> Machine Learning, Autonomous Mobile Robots, Robot Control, Computer Vision, Data Mining, Advanced Algorithms	<b>Fall 2016 - Spring 2020</b>
Technical Skills	<b>Programming Languages:</b> Python, C++, Java, C, SQL <b>Frameworks/Tools:</b> Pytorch, ROS, Tensorflow, Keras	
Research Experience	<b>Research Intern</b> <i>Dolan Lab</i> <sup>1</sup> , <i>Carnegie Mellon University</i> Advisor: <a href="#">John Dolan</a> Continuing work on trajectory generation for autonomous vehicles in dense traffic via deep reinforcement learning. Implemented algorithms based on hierarchical reinforcement learning and low-level controllers to generate highway merging behaviors in dense traffic.	<b>September 2019 - December 2019</b>
	<b>Robotics Institute Summer Scholar</b> <i>Dolan Lab, Carnegie Mellon University</i> Advisor: <a href="#">John Dolan</a> Researched reinforcement learning-based approaches to trajectory generation in autonomous vehicles, focusing on scenarios with high degree of interaction between vehicles. Developed algorithms for trajectory generation that combined traditional controllers and deep imitation learning and validated results on real-world highway data.	<b>June 2019 - August 2019</b>
	<b>Undergraduate Researcher</b> <i>Horizon Lab, University of Rochester</i> Advisor: <a href="#">Yuhao Zhu</a> Researched integration of optical and hardware elements into training of computer vision algorithms in resource-constrained environments. Implemented optical forward-modeling using point-spread functions, and implemented motivational experiments for optical-algorithmic co-design.	<b>October 2018 - May 2020</b>
Papers	<b>Samuel Triest</b> , Adam Villafior, John M. Dolan <a href="#">Ramp Merging Via Reinforcement Learning with Temporally-Extended Actions</a> <i>2020 IEEE Intelligent Vehicles Symposium</i>	
	<b>Samuel Triest</b> , Adam Villafior, John M. Dolan <a href="#">Learning Low-level Continuous Control for Ramp Merging in Dense Traffic</a> <i>2019 RISS Working Papers Journal</i>	
	<b>Samuel Triest</b> , Daniel Nikolov, Jannick Rolland, Yuhao Zhu <a href="#">Co-Optimization of Optics, Architecture and Computer Vision Algorithms</a> <i>WAX @ PLDI 2019</i>	

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<sup>1</sup>Now part of Argo AI Center for Autonomous Vehicle Research

<b>Theses</b>	<b>Samuel Triest</b> <a href="#">Unsupervised Reinforcement Learning in Environments with Strong Priors</a> <i>University of Rochester</i>	
<b>Presentations</b>	Robotics Institute Summer Scholars Research Showcase ( <a href="#">Poster</a> ) WAX @ PLDI 2019 ( <a href="#">Talk</a> ) University of Rochester Undergraduate Research Symposium (Talk) ACM Student Research Competition @ ASPLOS 2019 (Talk, <a href="#">Poster</a> )	Aug. 2019 June 2019 April 2019 April 2019
<b>Awards, Grants, Scholarships</b>	Award for Excellence in Undergraduate Research in Computer Science Honorable Mention, CRA Outstanding Undergraduate Researcher Award NSF REU Scholarship (NSF Award 1659774, CMU RISS) Gold Medalist, ACM Student Research Competition @ ASPLOS 2019 Dean's Scholarship (University of Rochester) Dean's List (University of Rochester, 6/6 eligible semesters)	May 2020 Dec. 2019 June 2019 April 2019 Sept. 2016-May 2020 Sept. 2016-May 2019
<b>Teaching and Professional Service</b>	<b>Teaching Assistant</b> Artificial Intelligence Algorithms Computer Architecture Business Information Systems	Spring 2018, Fall 2018 Fall 2018, Spring 2020 Spring 2019 Spring 2019
	<b>UR Robotics Club</b> Vice President President Lab Manager	May 2019 - May 2020 May 2018 - May 2019 May 2017 - May 2018
<b>Industry Experience</b>	<b>Product Management Intern</b> <i>Waterline Data</i> Conducted research and created POC for scheduling jobs using constraint satisfaction. Contributed several plugins for Waterline integration with third-party software. Expanded scope of Waterline's product demo, assisted with updating sandbox and demos for Microsoft Azure.	<b>Summer 2018</b>
	<b>Engineering Intern</b> <i>Waterline Data</i> Contributed test cases and automation to several product features. Created a utility to detect duplicate data. Leveraged existing APIs of the Waterline Data Catalog to determine the likelihood of data duplication between data resources using existing metadata and generate a report in Tableau.	<b>Summer 2017</b>
<b>Independent Study Projects</b>	<b><a href="#">Robotics Workshops</a></b> Implemented a series of workshop for the Robotics Club at the University of Rochester covering various algorithmic components of robotics, including kinematics, Markov Decision Processes, etc.	
	<b><a href="#">Domain-Specific Language for Graph Algorithms</a></b> Designed and provided theoretical motivation for a domain-specific language for graph algorithms based on highly composable parallel graph primitives. Implemented parallel versions of a representative set of graph algorithms (including BFS, SSSP, connected components, k-core decomposition) using this language.	