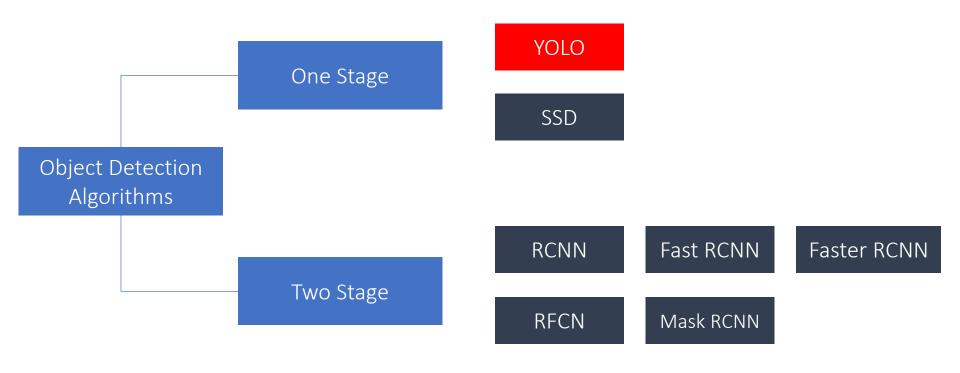
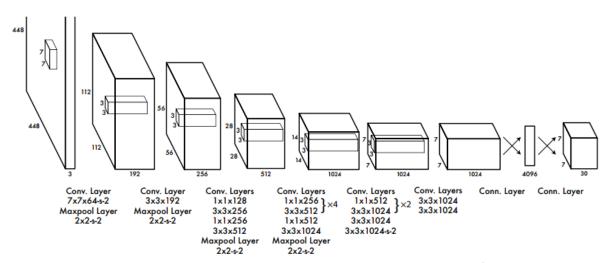
Overview of Algorithms

Object Detection algorithms can be classified into one- and two-stage algorithms.



Introduction

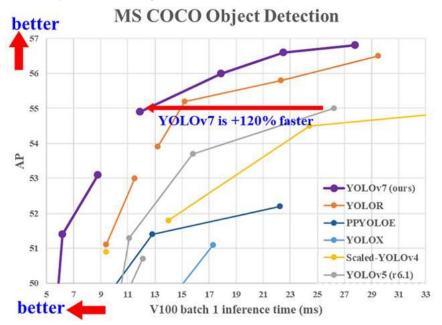
- YOLO...You only look once
- developed in 2016
- one-stage algorithm
- 24 CNN layers, 2 fully connected layers



Source: Redmon, Divvala, Girshick, Farhadi: "You Only Look Once: Unified, Real-Time Object Detection"

Why you should use YOLO?

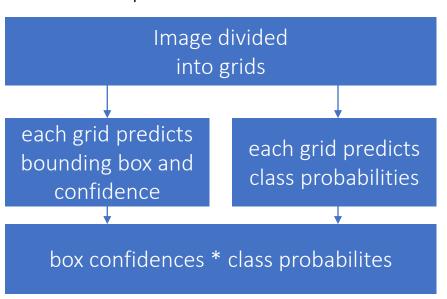
YOLOv7 outperforms many other algorithms in inference time.

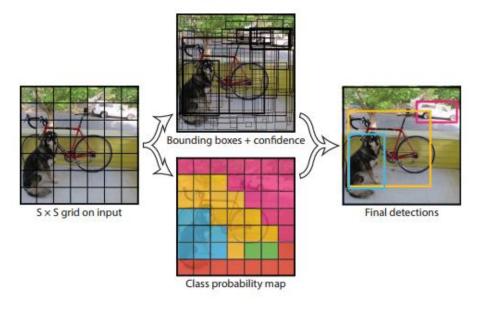


Source: Wang, Bochkovskiy, Liao: "YOLOv7: Trainable bag-of-freebies sets new state-of-the-art for real-time object detectors", July 2022

How does it work?

 one-stage: bounding boxes and classes predicted at the same time

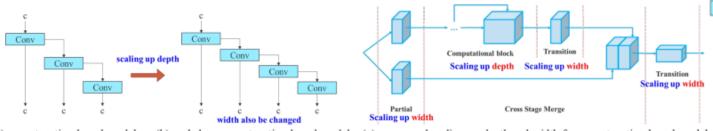




Source: Redmon, Divvala, Girshick, Farhadi: "You Only Look Once: Unified, Real-Time Object Detection"

Which changes are included in YOLOv7 compared to earlier versions?

- YOLOv7 authors applied changes to network, e.g.
 - Extended Efficient Layer Aggregation
 - considers required memory for layers and the distance for gradient to back-propage
 - Model Scaling
 - network depth and width are scaled and layers are concatenated



(a) concatenation-based model

(b) scaled-up concatenation-based model

(c) compound scaling up depth and width for concatenation-based model

c partial c

3x3, c, c

3x3, c, c

3x3, c, c

3x3, c, c

Stack in computational block

1x1, 4c, c

(c) ELAN [1]

Limitations

lower accuracy compared to slower algorithms like Fast RCNN



problems with small objects which appear in groups



Source: https://www.youtube.com/watch?v=yF1eJlLk7GI