# Operating Systems: Project 1 - Parallel Process Scheduling

#### **DUE DATES:**

Milestone 1: First Come First Serve, Due: Friday Feb 19th, 11:59 AM (right before class)

Milestone 2: Round Robin, Due: Wednesday Feb 24th, 11:59 AM (right before class)

Milestone 3: Completion of process scheduling program and analysis of algorithms

Due: Friday March 4th, 11:59 AM (right before class)

#### 1. Introduction:

This project will expose you to the simplicity and beauty of CPU scheduling algorithms. You are to implement a virtual multicore system capable of scheduling tasks from the ready queue.

# 2. Objectives:

- Understand the creation and use of a CMake project
- Implement process scheduling algorithms
- Understand the performance trade-offs for various scheduling algorithms
- Exposure and usage of basic thread system calls

## 3. Requirements:

### <u>Undergraduate</u>

Implement a 1-4 core virtual system capable of running First Come First Served (FCFS) and Round Robin (RR) scheduling algorithms.

#### Graduate

Implement an 1-N core virtual system capable of running First Come First Served (FCFS) and Round Robin (RR) scheduling algorithms.

#### Details

#### Input Data, Process Scheduling

Configuration files will be provided for your program. The binary file format is provided further below. We have provided unit tests that verify various parts of your

implementation. Your schedulers will need to track metadata such as average latency, average wall clock time, and total run time.

# **Core Count and Configuration**

Your program, *process\_analysis*, will accept configuration information from the command line. The first argument will be the name of the PCB file, and the remaining arguments will be the core configurations. In this example, the PCB file to be loaded is pcbs.bin, and there are three cores enabled, two with RR scheduling and one with FCFS scheduling.

./process\_analysis pcbs.bin RR FCFS RR

# **Technical Specifications:**

Process Control Block File Format:

32-bit unsigned N

32-bit unsigned burst\_time[N]

Statistics to be computed include:

- 1. float Average Latency
- 2. float Average Wall-Clock
- 3. unsigned long Total Clock Time

# **Terminology and Concepts**

<u>burst time</u>: is the runtime of the process through our virtual CPU.

arrival time: is the time the process becomes into our ready queue.

<u>latency time</u>: is the time between arrival and the first time the process runs on the CPU. <u>wall clock time</u>: is the time a process takes to complete (from arrival to completion).

# **Additional Specifications:**

#### **Binary Configuration File Format**

- number of process control blocks burst times (32-bit unsigned)
- first process burst time
- second process burst time
- •
- N process's burst time

The PCB file will be composed of N 32-bit integers. Each integer is the burst time of a process in the ready queue. N will be the first integer in the file.

#### Resources:

- Please refer to class notes and posted slides from the textbook.
- Additionally, the unit tests supplied with the starter code as well as select learning module code are invaluable resources.
- The Linux/Unix programmer's manual, accessible through the "man pages" of your VM

#### Milestone 1:

Note: Each of the following dyn\_array\_t\* ready\_queue is a structure wrapped array of type Process Control Block. If you need guidance on the usage of dyn\_array, review the documentation in the dyn\_array header as well as the test examples in the test directory.

bool **first\_come\_first\_serve** (dyn\_array\_t\* ready\_queue, ScheduleResult\_t\* result);

#### Milestone 2:

bool **round\_robin** (dyn\_array\_t\* *ready\_queue*, ScheduleResult\_t\* *result*);

#### Final Milestone:

**Note:** You need to update your previous code because race conditions can arise. Thus any access to the ready\_queue dyn\_array object will need to be gated by locks (mutex).

```
dyn_array_t* load_process_control_blocks (const char* input_file); void* first_come_first_serve_worker (void* input); void* round_robin_worker (void* input);
```

For the above process scheduling algorithms use your book, online resources, and class notes for implementation. **You do not need** to implement any low level context switching, the real linux ready queue, or CPU driver.

You are required to fill in a new file in the source directory (src) called: analysis.c

To allow your new analysis.c to be built, you must update the CMakeLists.txt.

Your analysis.c program will need to read in from the command line PCBs.bin file (generated from the test file) <schedule algorithm> <schedule algorithm> ... <N>. The number of schedule parameters depends, if you are undergraduate or graduate. Please check the document for additional details!

At the beginning of your analysis.c file you need to call init\_lock(). To set up the mutex located in the process\_scheduling.c source file.

You are required to pthread your thread worker functions first\_come\_first\_serve\_workerand round\_robin\_worker to call their respective schedule algorithms. You will need to create a structure that packages a schedule result and a reference to the dyn\_array (look in the process\_scheduling.h)

The flow of the analysis program is:

- 1. load process control blocks from binary file passed at the command line into a dyn\_array (this is your ready queue).
- 2. allocate an array of schedule results for the number of schedule algorithms requested.
- 3. allocate an array of pthread\_t for the number of schedule algorithms requested.
- 3. Create/Spawn pthreads based on the number of schedule algorithms requested at the command line for their respective algorithms.
- 4. Join spawned threads when they complete their work
- 5. clean up any allocations
- 6. Report your times in the readme file

## **Additional Process Scheduling Notes:**

The clock time starts at zero and increments until the ready queue is empty.

Lastly, each scheduling function fills out a Schedule Result structure that contains average wall clock time, and average latency time, and total clock time used for verification and analysis.

You are required to run four tests and report the timings in your readme:

- 1 FCFS Core
- 1 RR Core
- 1 FCFS and 1 RR core
- 2 FCFS and 2 RR cores

# Graduates will be expected to do the following extra tests:

- 3 FCFS and 2 RR cores
- 2 FCFS and 4 RR cores

Your analysis program should be run with the *time* command as follows: time ./process\_analysis PCB.bin FCFS RR

# **Rubric:**

# Milestone 1:

50% points for passing unit tests50% For correct implementation of FCFS

## Milestone 2:

50% points for passing unit tests 50% For correct implementation of RR

#### **Final Milestone:**

50% points for passing unit tests25% For correct PCB loading and threading25% For scheduling runtime analysis and correct CMake project creation

## For all milestones:

Insufficient Parameter Validation -20% of rubric score
Insufficient Error Checking -20% of rubric score
Insufficient Block and Inline Comments -20% of rubric score
Submission compiles with warnings (with -Wall -Wextra -Wshadow) -80%
Submission does not compile -90% of rubric score