PIT CHECKLIST		Matc	Match	Match	13 Match	Natch's	Azich Maic	a Mati	Jaki	Matc	Jaki	Match	n Match	` ₂
	Archive Robot Logs													=
Logs	Archive DS Logs													
	Review Startup Logs													_
Controls	Driver Joysticks													=
	Driver Controls													_
Health Check	Run Health Check													=
	Check results													_
	Plug in													=
Driver Station	Check free disk space													
	Check CAN utilization													
	ALL CHECK													=
	Time stamp Match end													
	Time stamp Match start													_

- 1. Jumper in
- 2. Check with drive team
- 3. Power on
- 4. Check limit switches
- 5. Position axis
- 6. Health check
- 7. Review results
- 8. Power down
- 9. REMOVE FLAG
- 10. Battery

		1 3				
PACKING LIST		Sagred				
	deepspace					
	thirdcoast					
	pyeye					
	Talon Firmware					
D 1	RoboRIO					
Release	GradleRIO					
	Shuffleboard config					
	Driver Station					
	WPILib version					
	Backup copy of all software releases (USB)					
	Driver Station (3)					
	Controller Case (2 Controller sets)					
	roboRIO wall wart					
	USB Stick					
Tools (Check Drive Team tools)	Metric measuring tape					
	Velcro measuring block					
	_					
	Digital protractor Ethernet switch and 120v inverter					
	DP - HDMI (2)					
	HDMI Cables (2)					
Cables	POE (2)					
Cablos	Ethernet short (4)					
	Ethernet extra long (1)					
	Ethernet 25ft (1)					
	Event Interlock (2)					
	roboRIO					
	Install on spare roboRIO					
C D	navX					
Spare Parts	RPi					
	Lifecam HD-3000					
	USB3 cables A and B					
	radio					
	DS version					
	Powerup/thirdcoast					
	roboRIO version					
	navX version					
Checks	CTRELib version					
CHOOK	Talon Firmware version					
	Drive team controller check					
	PDP Firmware Check					
	FMS Radio install					
	ALL CHECK					