



François Chollet



Keras creator

@fchollet

Follow



Here is the same dynamic RNN implemented in 4 different frameworks (TensorFlow/Keras, MXNet/Gluon, Chainer, PyTorch). Can you tell which is which?

```
class MyRNN(Block):  
    def __init__(self, units=32):  
        super(MyRNN, self).__init__()   
        self.units = units  
        with self.name_scope():  
            self.projection_1 = nn.Dense(units=units, activation='tanh')  
            self.projection_2 = nn.Dense(units=units, activation='tanh')  
  
    def forward(self, inputs):  
        outputs = []  
        state = zeros(shape=(inputs.shape[0], self.units))  
        for t in range(inputs.shape[1]):  
            x = inputs[:, t, :]  
            h = self.projection_1(x)  
            y = h + self.projection_2(state)  
            state = y  
            outputs.append(y)  
        return concat(outputs, dim=1)
```

```
class MyRNN(NNModule):  
    def __init__(self, units=32):  
        super(MyRNN, self).__init__()   
        self.units = units  
        self.projection_1 = layers.Dense(units=units, activation='tanh')  
        self.projection_2 = layers.Dense(units=units, activation='tanh')  
  
    def call(self, inputs):  
        outputs = []  
        state = zeros(shape=(inputs.shape[0], self.units))  
        for t in range(inputs.shape[1]):  
            x = inputs[:, t, :]  
            h = self.projection_1(x)  
            y = h + self.projection_2(state)  
            state = y  
            outputs.append(y)  
        return concatenate(outputs, axis=1)
```

```
class MyRNN(Module):  
    def __init__(self, units=32):  
        super(MyRNN, self).__init__()   
        self.units = units  
        self.projection_1 = layers.Linear(in_features=None, out_features=units)  
        self.projection_2 = layers.Linear(in_features=None, out_features=units)  
  
    def forward(self, inputs):  
        outputs = []  
        state = zeros(shape=(inputs.shape[0], self.units))  
        for t in range(inputs.shape[1]):  
            x = inputs[:, t, :]  
            h = tanh(self.projection_1(x))  
            y = h + tanh(self.projection_2(state))  
            state = y  
            outputs.append(y)  
        return stack(outputs, dim=1)
```

```
class MyRNN(Clone):  
    def __init__(self, units=32):  
        super(MyRNN, self).__init__()   
        self.units = units  
        with self.init_scope():  
            self.projection_1 = layers.Linear(in_size=None, out_size=units)  
            self.projection_2 = layers.Linear(in_size=None, out_size=units)  
  
    def forward(self, inputs):  
        outputs = []  
        state = zeros(shape=(inputs.shape[0], self.units))  
        for t in range(inputs.shape[1]):  
            x = inputs[:, t, :]  
            h = tanh(self.projection_1(x))  
            y = h + tanh(self.projection_2(state))  
            state = y  
            outputs.append(y)  
        return stack(outputs, axis=1)
```

9:03 AM - 16 Oct 2018

514 Retweets 1,572 Likes



<https://github.com/stsievert/talks>

I'm going to focus on the training libraries