

# rejectionsampling

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## 1 Rejection Sampling

First, consider the case for a continuous probability distribution: Let  $X$  be a random variable with density  $f$ . The function  $F$  is continuous and only takes positive values on  $[a, b]$  except for 0. Since continuity holds, we can determine the maximum. The goal of this method is to generate a random variable with such density. A random point is generated from the uniform distribution on a rectangle. If it is below  $f$ , it is accepted; otherwise, it is rejected. Executing the algorithm involves generating a random variable  $X$  with density  $f$ . A random variable  $Y$  is efficiently generated with density  $g$ . Importantly,  $Y$  should take values from the same set as  $X$ . A constant  $c$  is determined such that:

$$\sup_{x \in \mathbb{R}} \frac{f(x)}{g(x)} = c \leq \infty.$$

Ideally:

$$\sup_{x \in \mathbb{R}} \frac{f(x)}{g(x)} \leq c \leq \infty.$$

If  $U \leq \frac{f(Y)}{c \cdot g(Y)}$ , then  $X$  is returned as  $Y$ . If not, another  $Y$  will be generated again. In the example below, the distribution Semicircle(1) with Uniform(-1,1) is presented, and two probability density functions (PDFs), `semicircle_pdf` and `uniform_pdf`, are defined. When the range of  $x$  extends beyond  $[-1, 1]$ , the PDF value is set to 0. The generator is tested by calling the `test_generator` function. The case for a discretize probability distribution: Let CDF,  $F$  for  $X$ :

$$F(x) = \sum_{i \leq j} p(x_i)$$

Discrete random variables can be generated by slicing up the interval  $(0, 1)$  into subintervals which define a partition of  $(0, 1)$ :

$$(0, F(x_1)), (F(x_1), F(x_2)), \dots, (F(x_{k-1}), 1)$$

generating random variables  $U$  from a uniform distribution on the interval  $(0, 1)$  and determining the subinterval into which  $U$  falls. A realization of a discrete random variable  $X$  is generated according to the given formula:

$$(X = i) = p_i, \quad i = 1, 2, \dots, n.$$

It is possible to generate another random variable  $Y$  with a distribution defined by the formula:

$$\mathbb{Y}(Y = i) = q_i, \quad i = 1, 2, \dots, n.$$

Then, a random variable  $U$  is generated from the uniform distribution  $\mathcal{U}(0,1)$ , such that  $U$  is independent of  $Y$ . If  $U$  is evaluated to satisfy the condition  $U \leq \frac{pY}{c \cdot q_y}$ , where  $c = \max_i \frac{p_i}{q_i}$ , then  $X$  is set to be equal to  $Y$ . Otherwise, we go back to the beginning of the algorithm and generate  $Y$  again.

In the example below, rejection sampling is used for a discrete probability distribution. The Bernoulli distribution  $\mathcal{B}e(\frac{1}{4})$  with Uniform(0,1) is chosen. In the code, two probability mass functions (PMFs) are defined: `bernoulli_pmf` and `uniform_pmf`. The `bernoulli_pmf(x)` function returns the PMF value based on the input  $x$ :  $\frac{3}{4}$ ,  $\frac{1}{4}$ , and zero for  $x = 0$ ,  $x = 1$ , and any other value respectively. Similarly, the `uniform_pmf(x)` function returns the PMF value based on the input  $x$ :  $\frac{1}{2}$  for  $x = 0$  or  $x = 1$ , and zero for any other value. Then, the generator is tested by calling the `test_generator` function.