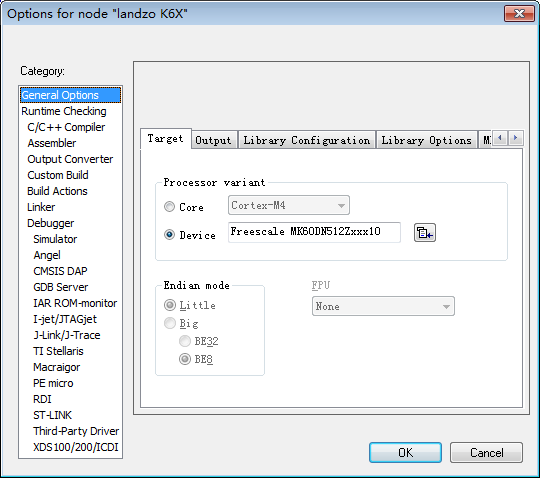
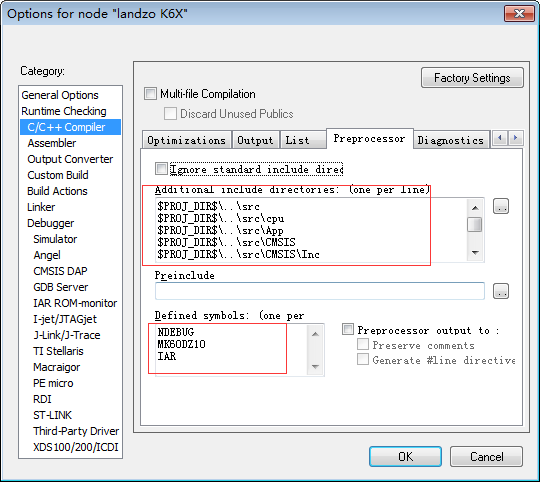
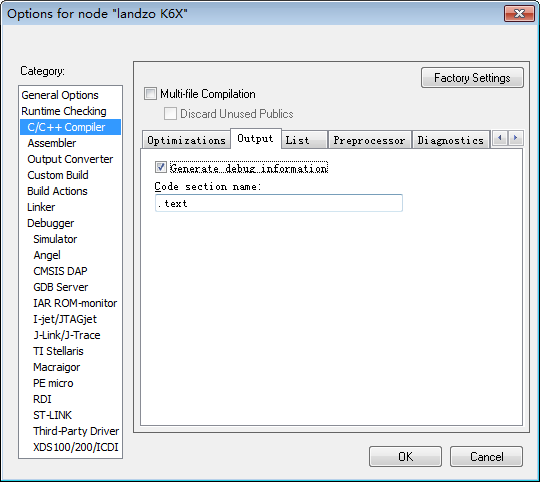
**K60 IAR环境的编译文件**

一、K60dn Flash RAM的配置：

1. 选芯片



1. 配置连接文件



$PROJ\_DIR$\..\src

$PROJ\_DIR$\..\src\cpu

$PROJ\_DIR$\..\src\App

$PROJ\_DIR$\..\src\CMSIS

$PROJ\_DIR$\..\src\CMSIS\Inc

$PROJ\_DIR$\..\src\Driver

$PROJ\_DIR$\..\src\Driver\adc

$PROJ\_DIR$\..\src\Driver\can

$PROJ\_DIR$\..\src\Driver\delay

$PROJ\_DIR$\..\src\Driver\dma

$PROJ\_DIR$\..\src\Driver\Flash

$PROJ\_DIR$\..\src\Driver\FTM

$PROJ\_DIR$\..\src\Driver\gpio

$PROJ\_DIR$\..\src\Driver\i2c

$PROJ\_DIR$\..\src\Driver\lptmr

$PROJ\_DIR$\..\src\Driver\PIT

$PROJ\_DIR$\..\src\Driver\SDHC

$PROJ\_DIR$\..\src\Driver\spi

$PROJ\_DIR$\..\src\Driver\system

$PROJ\_DIR$\..\src\Driver\uart

$PROJ\_DIR$\..\src\Driver\usb

$PROJ\_DIR$\..\src\Driver\Wdog

$TOOLKIT\_DIR$\inc

$TOOLKIT\_DIR$\inc\Freescale

$PROJ\_DIR$\..\src\landzo\Landzo\_CCD

$PROJ\_DIR$\..\src\landzo\Landzo\_Electromagnetism

$PROJ\_DIR$\..\src\landzo\Landzo\_GyroAccelerate

$PROJ\_DIR$\..\src\landzo\Landzo\_Key

$PROJ\_DIR$\..\src\landzo\Landzo\_MeasureSpeed

$PROJ\_DIR$\..\src\landzo\Landzo\_Motor

$PROJ\_DIR$\..\src\landzo\Landzo\_OLED

$PROJ\_DIR$\..\src\landzo\Landzo\_Predator

$PROJ\_DIR$\..\src\landzo\Landzo\_SD

$PROJ\_DIR$\..\src\landzo\Landzo\_ServoMotor

$PROJ\_DIR$\..\src\landzo\Landzo\_Calculation

$PROJ\_DIR$\..\src\landzo\Landzo\_Ultrasonic

$PROJ\_DIR$\..\src\landzo\Landzo\_1.44TFT

$PROJ\_DIR$\..\src\landzo\Landzo\_NRF24L01

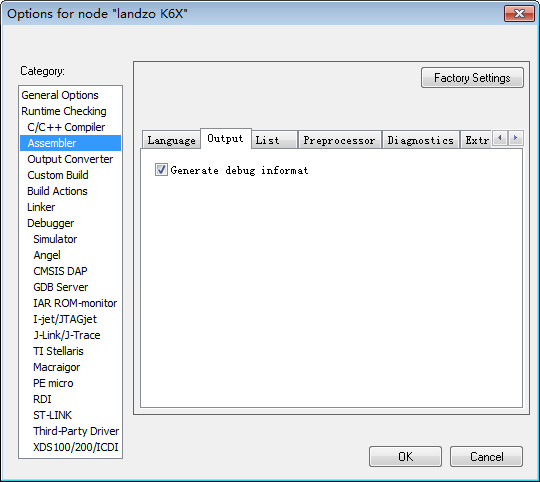
$PROJ\_DIR$\..\src\landzo\Landzo\_TFTLCD

NDEBUG

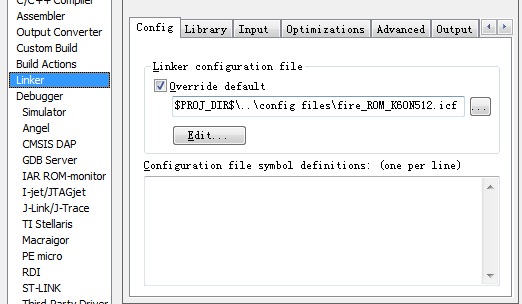
MK60DZ10

IAR

1. 配置输出



1. 配置link



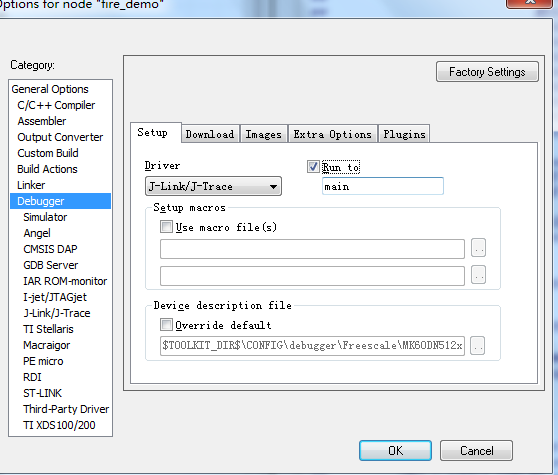
Flash配置

$PROJ\_DIR$\..\config files\linker\MK60xN512\_flash.icf

RAM 配置：

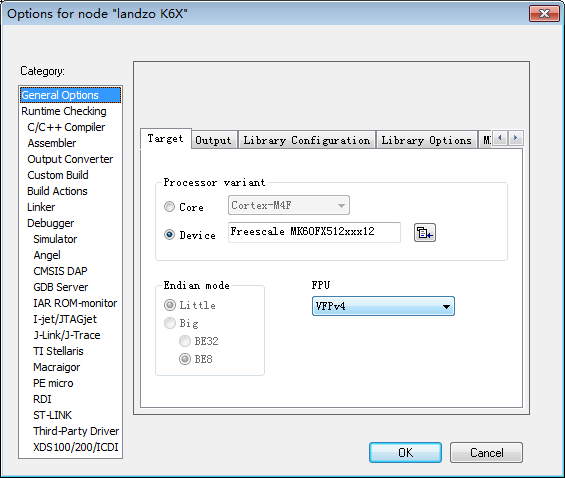
$PROJ\_DIR$\..\config files\linker\MK60xN512\_ram.icf

1. 配置下载器

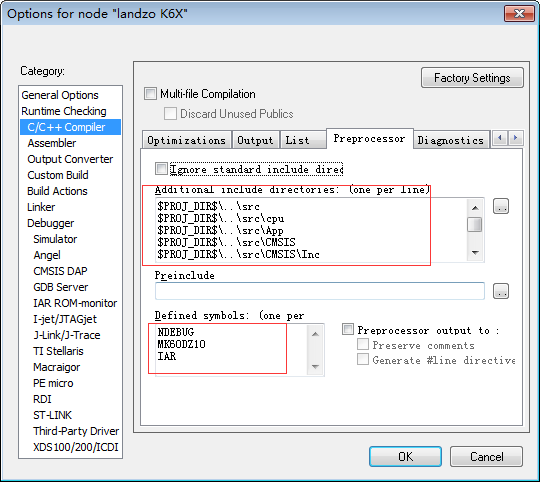
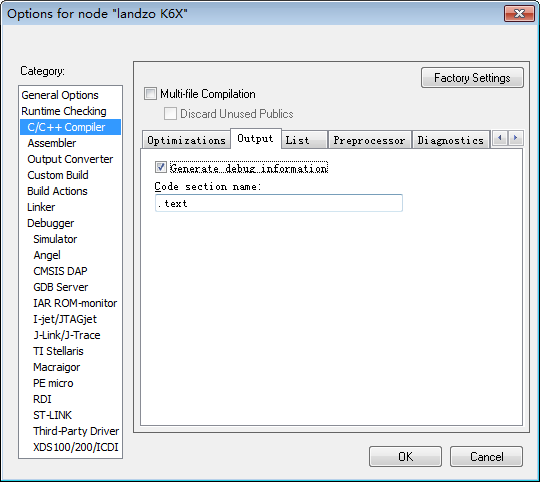


## 二、K60FX Flash RAM的配置：

1. 选芯片



1. 配置连接文件



$PROJ\_DIR$\..\src

$PROJ\_DIR$\..\src\cpu

$PROJ\_DIR$\..\src\App

$PROJ\_DIR$\..\src\CMSIS

$PROJ\_DIR$\..\src\CMSIS\Inc

$PROJ\_DIR$\..\src\Driver

$PROJ\_DIR$\..\src\Driver\adc

$PROJ\_DIR$\..\src\Driver\can

$PROJ\_DIR$\..\src\Driver\delay

$PROJ\_DIR$\..\src\Driver\dma

$PROJ\_DIR$\..\src\Driver\Flash

$PROJ\_DIR$\..\src\Driver\FTM

$PROJ\_DIR$\..\src\Driver\gpio

$PROJ\_DIR$\..\src\Driver\i2c

$PROJ\_DIR$\..\src\Driver\lptmr

$PROJ\_DIR$\..\src\Driver\PIT

$PROJ\_DIR$\..\src\Driver\SDHC

$PROJ\_DIR$\..\src\Driver\spi

$PROJ\_DIR$\..\src\Driver\system

$PROJ\_DIR$\..\src\Driver\uart

$PROJ\_DIR$\..\src\Driver\usb

$PROJ\_DIR$\..\src\Driver\Wdog

$TOOLKIT\_DIR$\inc

$TOOLKIT\_DIR$\inc\Freescale

$PROJ\_DIR$\..\src\landzo\Landzo\_CCD

$PROJ\_DIR$\..\src\landzo\Landzo\_Electromagnetism

$PROJ\_DIR$\..\src\landzo\Landzo\_GyroAccelerate

$PROJ\_DIR$\..\src\landzo\Landzo\_Key

$PROJ\_DIR$\..\src\landzo\Landzo\_MeasureSpeed

$PROJ\_DIR$\..\src\landzo\Landzo\_Motor

$PROJ\_DIR$\..\src\landzo\Landzo\_OLED

$PROJ\_DIR$\..\src\landzo\Landzo\_Predator

$PROJ\_DIR$\..\src\landzo\Landzo\_SD

$PROJ\_DIR$\..\src\landzo\Landzo\_ServoMotor

$PROJ\_DIR$\..\src\landzo\Landzo\_Calculation

$PROJ\_DIR$\..\src\landzo\Landzo\_Ultrasonic

$PROJ\_DIR$\..\src\landzo\Landzo\_1.44TFT

$PROJ\_DIR$\..\src\landzo\Landzo\_NRF24L01

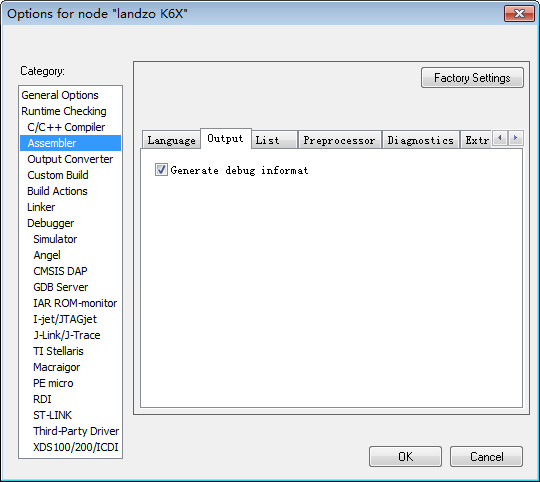
$PROJ\_DIR$\..\src\landzo\Landzo\_TFTLCD

NDEBUG

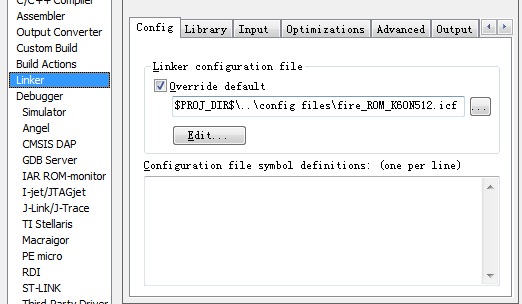
MK60DZ10

IAR

1. 配置输出



1. 配置link



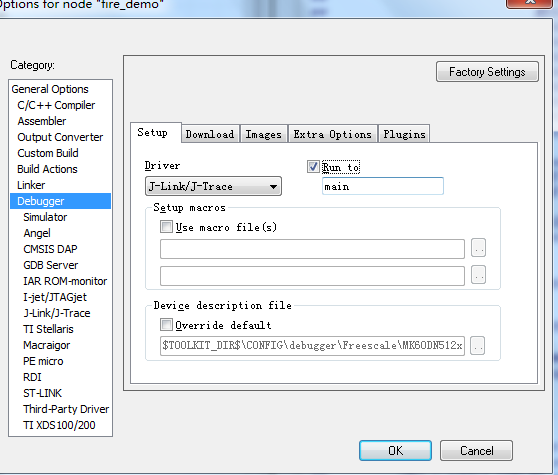
Flash配置

$PROJ\_DIR$\..\config files\linker\MK60xN512\_flash.icf

RAM 配置：

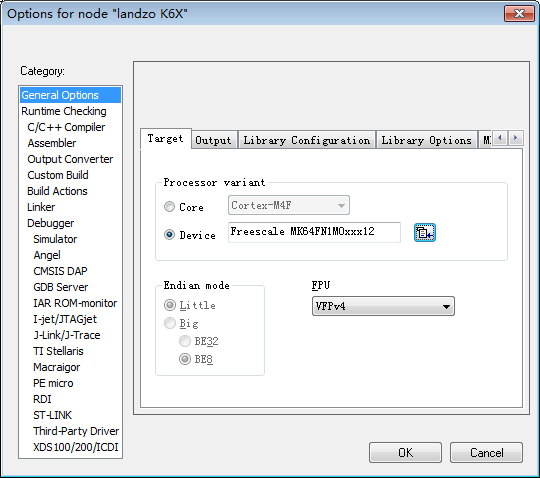
$PROJ\_DIR$\..\config files\linker\MK60xN512\_ram.icf

1. 配置下载器

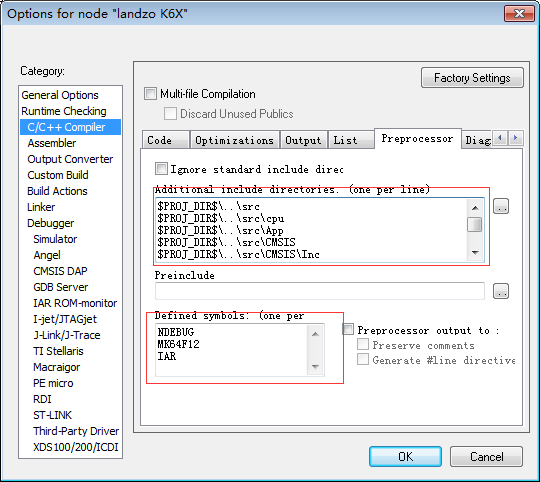
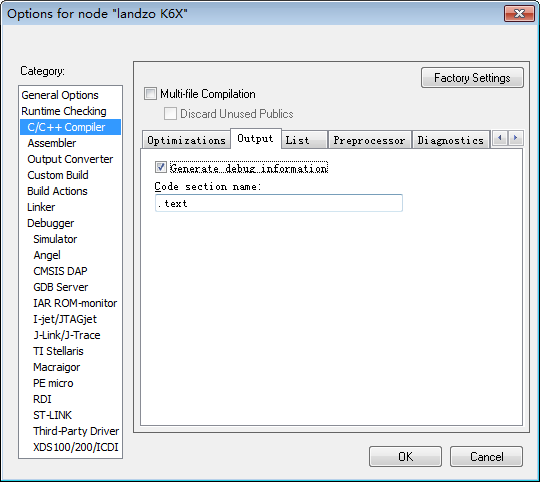


三、K64 Flash RAM的配置：

1. 选芯片



1. 配置连接文件



$PROJ\_DIR$\..\src

$PROJ\_DIR$\..\src\cpu

$PROJ\_DIR$\..\src\App

$PROJ\_DIR$\..\src\CMSIS

$PROJ\_DIR$\..\src\CMSIS\Inc

$PROJ\_DIR$\..\src\Driver

$PROJ\_DIR$\..\src\Driver\adc

$PROJ\_DIR$\..\src\Driver\can

$PROJ\_DIR$\..\src\Driver\delay

$PROJ\_DIR$\..\src\Driver\dma

$PROJ\_DIR$\..\src\Driver\Flash

$PROJ\_DIR$\..\src\Driver\FTM

$PROJ\_DIR$\..\src\Driver\gpio

$PROJ\_DIR$\..\src\Driver\i2c

$PROJ\_DIR$\..\src\Driver\lptmr

$PROJ\_DIR$\..\src\Driver\PIT

$PROJ\_DIR$\..\src\Driver\SDHC

$PROJ\_DIR$\..\src\Driver\spi

$PROJ\_DIR$\..\src\Driver\system

$PROJ\_DIR$\..\src\Driver\uart

$PROJ\_DIR$\..\src\Driver\usb

$PROJ\_DIR$\..\src\Driver\Wdog

$TOOLKIT\_DIR$\inc

$TOOLKIT\_DIR$\inc\Freescale

$PROJ\_DIR$\..\src\landzo\Landzo\_CCD

$PROJ\_DIR$\..\src\landzo\Landzo\_Electromagnetism

$PROJ\_DIR$\..\src\landzo\Landzo\_GyroAccelerate

$PROJ\_DIR$\..\src\landzo\Landzo\_Key

$PROJ\_DIR$\..\src\landzo\Landzo\_MeasureSpeed

$PROJ\_DIR$\..\src\landzo\Landzo\_Motor

$PROJ\_DIR$\..\src\landzo\Landzo\_OLED

$PROJ\_DIR$\..\src\landzo\Landzo\_Predator

$PROJ\_DIR$\..\src\landzo\Landzo\_SD

$PROJ\_DIR$\..\src\landzo\Landzo\_ServoMotor

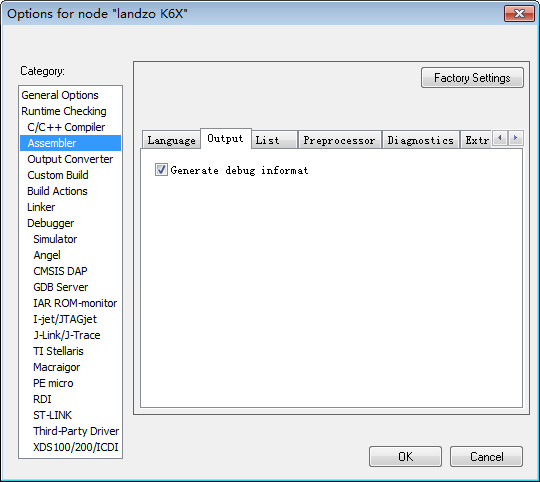
$PROJ\_DIR$\..\src\ landzo\Landzo\_Ultrasonic

NDEBUG

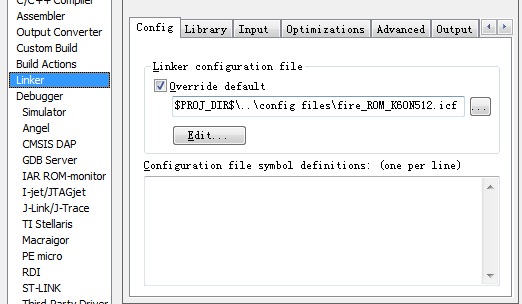
MK64F12

IAR

1. 配置输出



1. 配置link



Flash配置

$PROJ\_DIR$\..\config files\linker\MK60xN512\_flash.icf

RAM 配置：

$PROJ\_DIR$\..\config files\linker\MK60xN512\_ram.icf

1. 配置下载器

