

MATEMATIČKA ANALIZA 2

Meduispit (26.4.2021.)
- RJEŠENJA ZADATAKA -

1. (a) Kažemo da je funkcija $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ NEPREKIDNA u točki (x_0, y_0) ako postoji limes $\lim_{(x,y) \rightarrow (x_0, y_0)} f(x,y)$ i vrijedi:

$$\lim_{(x,y) \rightarrow (x_0, y_0)} f(x,y) = f(x_0, y_0).$$

(b) Promotrimo ponašanje sljedećih dviju restrikcija od f :

$$\lim_{x \rightarrow 0} f(x, x^3) = \lim_{x \rightarrow 0} \frac{x^4}{4x^4 + 3x^4} = \lim_{x \rightarrow 0} \frac{x^4}{7x^4} = \frac{1}{7},$$

$$\lim_{x \rightarrow 0} f(x, 0) = \lim_{x \rightarrow 0} \frac{x \cdot 0}{4x^4 + 3 \cdot 0} = \lim_{x \rightarrow 0} 0 = 0.$$

2. način: polarne koord.

$$\lim_{r \rightarrow 0} \frac{r^2 \cos \varphi \sin \varphi}{4r^4 \cos^4 \varphi + 3r^{\frac{4}{3}} \sin^{\frac{4}{3}} \varphi}$$
$$= \lim_{r \rightarrow 0} \frac{r^{\frac{2}{3}} \cos \varphi \sin \varphi}{4r^{\frac{8}{3}} \cos^4 \varphi + 3 \sin^{\frac{4}{3}} \varphi}$$

\Rightarrow limes ovisi o φ

Budući da se dobivene vrijednosti razlikuju, ne postoji limes od f u $(0,0)$ pa f u toj točki nije neprekidna.

(c) TOČNO

Ako je f diferencijabilna u (x_0, y_0) , onda postoje $\frac{\partial f}{\partial x}(x_0, y_0), \frac{\partial f}{\partial y}(x_0, y_0) \in \mathbb{R}$ te vrijedi

$$f(x_0 + \Delta x, y_0 + \Delta y) = f(x_0, y_0) + \frac{\partial f}{\partial x}(x_0, y_0) \Delta x + \frac{\partial f}{\partial y}(x_0, y_0) \Delta y + o(\Delta x, \Delta y), (*)$$

gdje

$$\lim_{(\Delta x, \Delta y) \rightarrow (0,0)} \frac{o(\Delta x, \Delta y)}{\sqrt{(\Delta x)^2 + (\Delta y)^2}} = 0. \quad (**)$$

Nb, zbog (**) mora vrijediti i $\lim_{(\Delta x, \Delta y) \rightarrow (0,0)} o(\Delta x, \Delta y) = 0$ pa puštanjem

(*) na limes kada $(\Delta x, \Delta y) \rightarrow (0,0)$ dobivamo

$$\lim_{(\Delta x, \Delta y) \rightarrow (0,0)} f(x_0 + \Delta x, y_0 + \Delta y) = f(x_0, y_0)$$

$$\Leftrightarrow \lim_{(x,y) \rightarrow (x_0, y_0)} f(x,y) = f(x_0, y_0),$$

tj. f je neprekidna u (x_0, y_0) .

(d) Prema (c) podzadatku, funkcija iz (b) nije diferencijabilna. Naime, ta funkcija nije diferencijabilna u $(0,0)$ jer u toj točki nije neprekidna.

2. (a) Definiramo funkciju

$$F(x,y,z) = x^2 + y^2 + z^2 - 2x + 4y - 6z + 5.$$

Budući da je

$$\frac{\partial F}{\partial z}(x,y,z) = 2z - 6$$

i posebno,

$$\frac{\partial F}{\partial z}(1,-2,0) = -6 \neq 0,$$

prema teoremu o implicitnoj funkciji, z se može izraziti kao funkcija varijabli x i y na nekoj okolini točke $(1,-2)$.

(b) Vektor normale tangencijalne ravnine na zadanu plohu u točki (x,y,z) je jednak

$$\nabla F(x,y,z) = (2x-2, 2y+4, 2z-6)$$

i prema uvjetu zadatka taj vektor mora biti kolinearan s vektorom normale ravnine $x-2y+2z=3$, tj. mora postojati $\lambda \in \mathbb{R}$ takav da

$$(2x-2, 2y+4, 2z-6) = \lambda(1, -2, 2)$$

$$\Rightarrow x = \frac{1}{2}(\lambda+2), \quad y = \frac{1}{2}(-2\lambda-4) = -\lambda-2, \quad z = \frac{1}{2}(2\lambda+6) = \lambda+3$$

Budući da tražene točke moraju ležati na plohi

$$\frac{1}{4}(\lambda+2)^2 + (\lambda+2)^2 + (\lambda+3)^2 - (\lambda+2) - 4(\lambda+2) - 6(\lambda+3) + 5 = 0$$

$$5(\lambda^2+4\lambda+4) + 4(\lambda^2+6\lambda+9) - 20(\lambda+2) - 24(\lambda+3) + 20 = 0$$

$$9\lambda^2 - 36 = 0$$

$$\lambda^2 = 4$$

$$\lambda_1 = 2$$

$$\lambda_2 = -2$$

$$(x,y,z) = (2, -4, 5)$$

$$(x,y,z) = (0, 0, 1)$$

3. (a) USMJERENA DERIVACIJA funkcije f u točki $T_0 \in \mathbb{R}^2$ u smjeru vektora $\vec{v} \in V^2$ je broj

$$\frac{\partial f}{\partial \vec{v}}(T_0) = \lim_{h \rightarrow 0} \frac{f(T_0 + h \vec{v}_0) - f(T_0)}{h},$$

gdje je $\vec{v}_0 = \frac{1}{\|\vec{v}\|} \vec{v}$ jedinični vektor u smjeru vektora \vec{v} .

Definirajmo funkciju

$$g(h) := f(T_0 + h \vec{v}_0).$$

Tada iz definicije usmjerene derivacije slijedi

$$\frac{\partial f}{\partial \vec{v}}(T_0) = \lim_{h \rightarrow 0} \frac{g(h) - g(0)}{h} = g'(0).$$

S druge strane, uz $T_0 = (x_0, y_0)$ i $\vec{v}_0 = v_{0x} \vec{i} + v_{0y} \vec{j}$ te stavljanjem

$$x(h) := x_0 + h v_{0x}, \quad y(h) := y_0 + h v_{0y},$$

vidimo da je

$$g(h) = f(x(h), y(h))$$

pa $g'(0)$ možemo računati i koristeći lancano pravilo:

$$\begin{aligned} g'(0) &= \frac{\partial f}{\partial x}(x(0), y(0)) \cdot \frac{dx}{dh}(0) + \frac{\partial f}{\partial y}(x(0), y(0)) \cdot \frac{dy}{dh}(0) \\ &= \frac{\partial f}{\partial x}(T_0) v_{0x} + \frac{\partial f}{\partial y}(T_0) v_{0y} \end{aligned}$$

$$\Rightarrow \frac{\partial f}{\partial \vec{v}}(T_0) = \nabla f(T_0) \cdot \vec{v}_0$$

(b) Uočimo da treba izračunati usmjerenu derivaciju funkcije f u točki T_1 u smjeru vektora $\overrightarrow{T_1 T_2}$. Imamo:

$$\frac{\partial f}{\partial x}(x, y) = 6xy - 2y + 5 \quad \Rightarrow \quad \frac{\partial f}{\partial x}(T_1) = 15,$$

$$\frac{\partial f}{\partial y}(x, y) = 3x^2 - 2x - 3 \quad \Rightarrow \quad \frac{\partial f}{\partial y}(T_1) = 5,$$

$$\vec{v} = \overrightarrow{T_1 T_2} = 3\vec{i} - 4\vec{j} \quad \Rightarrow \quad \vec{v}_0 = \frac{1}{\|\vec{v}\|} \vec{v} = \frac{3}{5}\vec{i} - \frac{4}{5}\vec{j}$$

$$\Rightarrow \frac{\partial f}{\partial \vec{v}}(T_1) = \nabla f(T_1) \cdot \vec{v}_0 = 15 \cdot \frac{3}{5} + 5 \cdot \left(-\frac{4}{5}\right) = 5$$

(c) Treba odrediti smjer u kojem f najbrže pada iz točke T_1 . To je u smjeru

$$-\nabla f(T_1) = -15\vec{i} - 5\vec{j}$$

te usmjerena derivacija u tom smjeru iznosi

$$-\|\nabla f(T_1)\| = -\sqrt{15^2 + 5^2} = -5\sqrt{10}.$$

(d) Tražimo smjer u kojem je usmjerena derivacija od f u T_1 jednaka nuli.

Iz

$$\frac{\partial f}{\partial \vec{v}}(T_1) = \nabla f(T_1) \cdot \vec{v}_0 = 0$$

vidimo da je $\vec{v} \perp \nabla f(T_1)$ pa je traženi smjer

$$\vec{v} = 5\vec{i} - 15\vec{j}.$$

4. (a) Lagrangeova funkcija:

$$L(x, y, \lambda) = e^{x^2+xy+y^2} + \lambda(x^2+y^2-2)$$

Tražimo njene stacionarne točke:

$$\begin{cases} \frac{\partial L}{\partial x}(x, y, \lambda) = e^{x^2+xy+y^2} \cdot (2x+y) + 2\lambda x = 0 \\ \frac{\partial L}{\partial y}(x, y, \lambda) = e^{x^2+xy+y^2} \cdot (x+2y) + 2\lambda y = 0 \\ \frac{\partial L}{\partial \lambda}(x, y, \lambda) = x^2+y^2-2 = 0 \end{cases}$$

Zbrajanjem prve dviju jednačbi slijedi

$$e^{x^2+xy+y^2} \cdot 3(x+y) + 2\lambda(x+y) = 0$$

$$\Rightarrow (x+y)(3e^{x^2+xy+y^2} + 2\lambda) = 0,$$

odakle dobivamo dva slučaja:

$$1^\circ x+y=0 \Rightarrow x=-y$$

Uvrštavanjem u treću jednačbu slijedi

$$y^2+y^2-2=0$$

$$y^2 = 1$$

$$y_1 = 1$$

$$x_1 = -1$$

$$e^{2-1} \cdot (-2+1) - 2\lambda = 0$$

$$\Rightarrow \lambda_1 = -\frac{1}{2}e$$

$$y_2 = -1$$

$$x_2 = 1$$

$$e^{2-1} \cdot (2-1) + 2\lambda = 0$$

$$\Rightarrow \lambda_2 = -\frac{1}{2}e$$

\Rightarrow stacionarne točke su $T_1(-1, 1, -\frac{1}{2}e)$ i $T_2(1, -1, -\frac{1}{2}e)$

$$2^\circ 3e^{x^2+xy+y^2} + 2\lambda = 0 \Rightarrow 2\lambda = -3e^{x^2+xy+y^2}$$

Uvrštavanjem u npr. prvu jednačbu dobivamo

$$e^{x^2+xy+y^2} \cdot (2x+y) - 3e^{x^2+xy+y^2} x = 0 \quad | : e^{x^2+xy+y^2} > 0$$

$$\Rightarrow -x+y=0 \Rightarrow x=y$$

Sada iz treće jednačbe sledi

$$y^2 + y^2 - 2 = 0$$

$$y^2 = 1$$

$$y_3 = 1$$

$$x_3 = 1$$

$$e^{2+1} \cdot (2+1) + 2\lambda = 0$$

$$\lambda_3 = -\frac{3}{2}e^3$$

$$y_4 = -1$$

$$x_4 = -1$$

$$e^{2+1} \cdot (-2-1) - 2\lambda = 0$$

$$\lambda_4 = -\frac{3}{2}e^3$$

\Rightarrow stacionarne tačke su $T_3(1, 1, -\frac{3}{2}e^3)$ i $T_4(-1, -1, -\frac{3}{2}e^3)$

Ispitujemo karakter dobivenih tačaka:

$$\frac{\partial^2 L}{\partial x^2}(x, y, \lambda) = e^{x^2+xy+y^2} (2x+y)^2 + e^{x^2+xy+y^2} \cdot 2 + 2\lambda$$

$$\frac{\partial^2 L}{\partial y^2}(x, y, \lambda) = e^{x^2+xy+y^2} (x+2y)^2 + e^{x^2+xy+y^2} \cdot 2 + 2\lambda$$

$$\frac{\partial^2 L}{\partial x \partial y}(x, y, \lambda) = e^{x^2+xy+y^2} (2x+y)(x+2y) + e^{x^2+xy+y^2}$$

$$\Rightarrow d^2 L(T) = \frac{\partial^2 L}{\partial x^2}(T)(dx)^2 + 2\frac{\partial^2 L}{\partial x \partial y}(T) dx dy + \frac{\partial^2 L}{\partial y^2}(T)(dy)^2$$

Diferencijal uvjeta: $x^2 + y^2 = 2 \quad /d \Rightarrow 2x dx + 2y dy = 0 \Rightarrow x dx + y dy = 0$

U stacionarnim tačkama imamo:

$$d^2 L(T_{1,2}) = (e^{2-1} \cdot 1^2 + e^{2-1} \cdot 2 - e)(dx)^2 + 2(e^{2-1} \cdot (-1) + e^{2-1}) dx dy + (e^{2-1} \cdot 1^2 + e^{2-1} \cdot 2 - e)(dy)^2$$

$$= 2e(dx)^2 + 2e(dy)^2 > 0 \text{ za } (dx, dy) \neq (0, 0) \Rightarrow T_{1,2} \text{ uvjetni lokalni minimumi}$$

$$f(T_1) = f(T_2) = e$$

$$d^2 L(T_{3,4}) = (e^{2+1} \cdot 3^2 + e^{2+1} \cdot 2 - 3e^3)(dx)^2 + 2(e^{2+1} \cdot 3^2 + e^{2+1}) dx dy + (e^{2+1} \cdot 3^2 + e^{2+1} \cdot 2 - 3e^3)(dy)^2$$

$$= 8e^3(dx)^2 + 20e^3 dx dy + 8e^3(dy)^2 = \left[\begin{array}{l} \text{iz diferencijala uvjeta} \\ dx + dy = 0 \Rightarrow dy = -dx \end{array} \right]$$

$$= 16e^3(dx)^2 - 20e^3(dx)^2$$

$$= -4e^3(dx)^2 < 0 \text{ za } (dx, dy) \neq (0, 0)$$

$\Rightarrow T_{3,4}$ uvjetni lokalni maksimumi

$$f(T_3) = f(T_4) = e^3$$

(b) Budući da je funkcija f neprekidna, a skup $\{(x,y) \in \mathbb{R}^2 : x^2 + y^2 \leq 2\}$ omeđen i zatvoren, ona na tom skupu mora postizati minimum i maksimum.

Kandidati za točke ekstreme su tzv. kritične točke:

1) točke ekstreme od f na rubu skupa, tj. na kružnici $x^2 + y^2 = 2$

Iz (a) podzadatke znamo da su to točke $T_{1,2,3,4}$.

2) stacionarne točke od f unutar skupa (ako postoje)

Računamo:

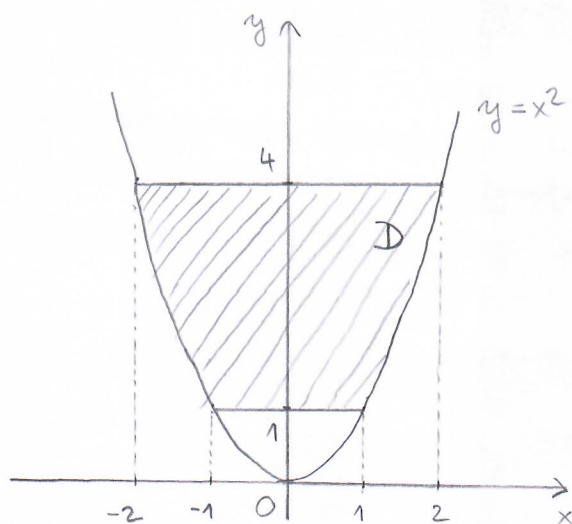
$$\begin{cases} \frac{\partial f}{\partial x}(x,y) = e^{x^2+xy+y^2}(2x+y) = 0 & | : e^{x^2+xy+y^2} > 0 \\ \frac{\partial f}{\partial y}(x,y) = e^{x^2+xy+y^2}(x+2y) = 0 & | : e^{x^2+xy+y^2} > 0 \end{cases}$$

$$\Rightarrow \begin{cases} 2x+y=0 \\ x+2y=0 \end{cases} \Rightarrow (x,y) = (0,0)$$

$T_5(0,0)$ je jedina stacionarna točka od f i nalazi se unutar skupa

Budući da je $f(T_5) = e^0 = 1$, $f(T_{1,2}) = e$ i $f(T_{3,4}) = e^3$, slijedi da f u $(0,0)$ postiže globalni minimum, dok u $(1,1)$ i $(-1,-1)$ postiže globalni maksimum na zadanom skupu.

5.



(a)

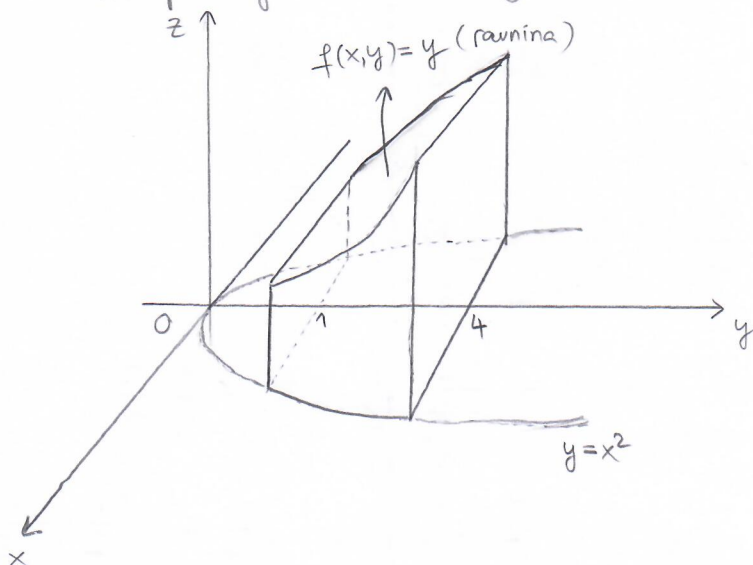
$$I = \iint_D y \, dx \, dy = \int_1^4 \int_{-\sqrt{y}}^{\sqrt{y}} y \, dx \, dy =$$

$$= \int_{-2}^{-1} \int_{x^2}^4 y \, dy \, dx + \int_{-1}^1 \int_{x^2}^4 y \, dy \, dx + \int_1^2 \int_{x^2}^4 y \, dy \, dx$$

$$I = \int_1^4 \int_{-\sqrt{y}}^{\sqrt{y}} y \, dx \, dy = \int_1^4 y \cdot \left(x \Big|_{-\sqrt{y}}^{\sqrt{y}} \right) dy = \int_1^4 2y\sqrt{y} \, dy$$

$$= 2 \int_1^4 y^{\frac{3}{2}} \, dy = 2 \cdot \frac{1}{\frac{5}{2}} y^{\frac{5}{2}} \Big|_1^4 = \frac{4}{5} \cdot (2^5 - 1) = \frac{124}{5}$$

(b) Gornjim je integralom izražen volumen ispod grafa funkcije $f(x,y)=y$ na području D u xOy ravni:



6. (a)
$$\iiint_V f(x,y,z) dx dy dz = \iiint_{V'} f(x(u,v,w), y(u,v,w), z(u,v,w)) |J| du dv dw,$$

gdje V' preslika područja V po preslikavanju

$$(u,v,w) \mapsto (x(u,v,w), y(u,v,w), z(u,v,w)),$$

a J Jacobijan tog preslikavanja

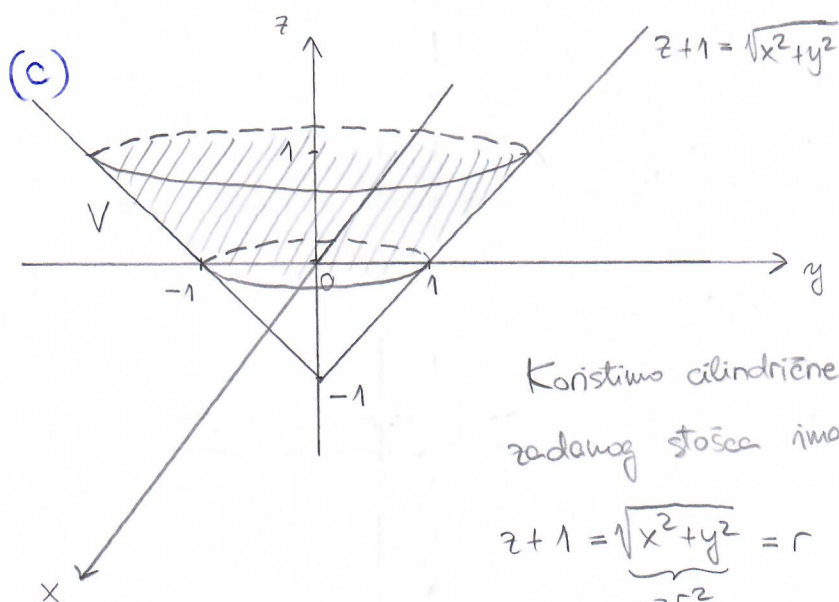
$$J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}.$$

(b) Cilindrične koordinate:

$$x = r \cos \varphi, \quad y = r \sin \varphi, \quad z = z, \quad r \geq 0, \quad \varphi \in [0, 2\pi], \quad z \in \mathbb{R}.$$

Jacobijan je prema (a) podzadatku jednak

$$J = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \varphi} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \varphi} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \varphi} & \frac{\partial z}{\partial z} \end{vmatrix} = \begin{vmatrix} \cos \varphi & -r \sin \varphi & 0 \\ \sin \varphi & r \cos \varphi & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1 \cdot r \cdot (\underbrace{\cos^2 \varphi + \sin^2 \varphi}_{=1}) = r$$



Koristimo cilindrične koordinate. U točkama
zadanog stošca imamo

$$z+1 = \underbrace{\sqrt{x^2+y^2}}_{=r^2} = r \Rightarrow z = r-1$$

Rächnung:

$$\iiint_V y^2 dV = \left[\begin{array}{l} \text{Cylindrische Koordinate:} \\ x = r \cos \varphi \quad \varphi \in [0, 2\pi] \\ y = r \sin \varphi \quad z \in [0, 1] \\ z = z \quad r \in [0, z+1] \end{array} \quad \begin{array}{l} |z| = |r| = r \\ \text{für } r \geq 0 \end{array} \right]$$

$$= \int_0^{2\pi} \int_0^1 \int_0^{z+1} r^2 \sin^2 \varphi \cdot r dr dz d\varphi = \int_0^{2\pi} \int_0^1 \sin^2 \varphi \left(\frac{1}{4} r^4 \Big|_0^{z+1} \right) dz d\varphi$$

$$= \frac{1}{4} \int_0^{2\pi} \int_0^1 \sin^2 \varphi (z+1)^4 dz d\varphi = \frac{1}{4} \int_0^{2\pi} \sin^2 \varphi \left(\frac{1}{5} (z+1)^5 \Big|_0^1 \right) d\varphi$$

$$= \frac{1}{4} \cdot \frac{1}{5} (2^5 - 1^5) \int_0^{2\pi} \sin^2 \varphi d\varphi = \frac{31}{20} \int_0^{2\pi} \frac{1}{2} (1 - \cos 2\varphi) d\varphi$$

$$= \frac{31}{20} \left(\frac{1}{2} \left(\varphi - \frac{1}{2} \sin 2\varphi \right) \Big|_0^{2\pi} \right) = \frac{31}{20} \cdot \frac{1}{2} \cdot (2\pi - 0 - \underbrace{\frac{1}{2} \sin 4\pi + \frac{1}{2} \sin 0}_{=0})$$

$$= \frac{31}{20} \cdot \frac{1}{2} \cdot 2\pi = \frac{31\pi}{20}$$

2. način:

$$\begin{aligned} & \int_0^{2\pi} \sin^2 \varphi d\varphi \int_0^1 r^3 dr \int_0^1 dz + \int_0^{2\pi} \sin^2 \varphi d\varphi \int_1^2 r^3 dr \int_{r-1}^1 dz \\ &= \pi \cdot \frac{1}{4} \cdot 1 + \pi \int_1^2 r^3 (2-r) dr \\ &= \frac{\pi}{4} + \pi \left(\frac{r^4}{2} - \frac{r^5}{5} \right) \Big|_1^2 = \frac{\pi}{4} + \frac{13\pi}{10} = \frac{31\pi}{20} \end{aligned}$$