## HW #13; date: Oct. 17, 2017MATH 110 Linear Algebrawith Professor Stankova

- 5.1 # 1 (a) False. Take  $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ . It only has one distinct eigenvalue, which is 0. (b) True. Every nonzero scalar multiple of an eigenvector is an eigenvector. (c) True. Take  $\begin{pmatrix} 2 & 1 \\ 2 & 0 \end{pmatrix}$  over the field  $\mathbb{Z}/3\mathbb{Z}$ . The characteristic polynomial is  $(2-t)t-2=-(t^2+t+2)=0$ . One can check that t=0,1,2 are not solutions to this equation (modulo 3). For a less exotic example, also the rotation by 90 degrees matrix in  $\mathbb{R}^2$  has no eigenvalues  $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ . (d) False. They can certainly be zero. (e) False. See answer to part b. (f) False. Take  $\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ . 1 and 2 are eigenvectors but 3 is not. (g) False. Take  $T:P(\mathbb{R})\to P(\mathbb{R})$  ( $P(\mathbb{R})$  means real-valued polynomials) defined by T(f)=5f. 5 is an eigenvalue. (h) True. If we put the basis of eigenvectors into the columns of a matrix Q, then  $QAQ^{-1}$  is diagonal. (i) True. Say $P^{-1}AP=B$ . Then if  $\lambda$  is an eigenvalue of A with eigenvector v, then  $P^{-1}v$  is an eigenvector of B with eigenvalue  $\lambda$ . (j) False. See previous sentence. (k) False. Take  $\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ .  $e_1$  and  $e_2$  are eigenvectors but  $e_1+e_2$  is not.
- $5.1 \ \# \ 2\text{b,d,f} \ \text{(b) Since} \ T(3+4x) = -6 8x = -2(3+4x) \ \text{and} \ T(2+3x) = -6 9x = -3(2+3x), \ \text{we}$  have  $[T]_{\beta} = \begin{pmatrix} -2 & 0 \\ 0 & -3 \end{pmatrix}$  and since this is diagonal, the basis is a basis of eigenvectors. (d)  $T(x-x^2) = 4 + 4x + 4x^2 = 2(x-x^2) 2(-1+x^2) + (-1-x+x^2), \ T(-1+x^2) = 2 2x^2 = -2(-1+x^2), \ \text{and} \ T(-1-x+x^2) = -3x 3x^2 = -(x-x^2) + 2(-1+x^2) 2(-1-x+x^2). \ \text{So,}$   $[T]_{\beta} = \begin{pmatrix} 2 & 0 & -1 \\ -2 & -2 & 2 \\ 1 & 0 & -2 \end{pmatrix}, \ \text{not diagonal, so not a basis of eigenvectors.} \ \text{(f) Since} \ T\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = -3\begin{pmatrix} -3 & 0 \\ -3 & 0 \end{pmatrix}, T\begin{pmatrix} -1 & 2 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 2 \\ 0 & 0 \end{pmatrix}, T\begin{pmatrix} 1 & 0 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 2 & 0 \end{pmatrix}, T(\begin{pmatrix} -1 & 0 \\ 0 & 2 \end{pmatrix}) = \begin{pmatrix} -1 & 0 \\ 0 & 2 \end{pmatrix}, \ \text{we}$  have  $[T]_{\beta} = \begin{pmatrix} -3 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ , so it is a basis of eigenvectors.
  - 5.1 # 3b,c (b)  $\det(tI-A)=(t-1)(t-2)(t-3)$ , so the eigenvalues are 1, 2, 3. The eigenvectors are bases for N(A-I), N(A-2I), N(A-3I), so  $(1,1,-1)^t, (1,-1,0)^t, (1,0,-1)^t$  respectively. Since there are three such vectors for different eigenvalues, they must form a basis. The matrix is  $Q=\begin{pmatrix}1&1&1\\1&-1&0\\-1&0&-1\end{pmatrix}.$  (c) The characteristic polynomial  $\det(tI-A)=(t-i)(t+i)-2=t^2-1,$

so the eigenbalues are t = 1, -1. The corresponding eigenvectors are  $(-1, i-1)^t$  and  $(-1, i+1)^t$  respectively. These form a basis and  $Q = \begin{pmatrix} -1 & -1 \\ i-1 & i+1 \end{pmatrix}$ .

- 5.1 # 4a,e,j (a) The eigenvalues are 3, 4. The eigenvectors are (3,5) and (1,2) respectively. (e) Written in the standard basis, this gives a matrix  $\begin{pmatrix} 1 & 3 & 9 \\ 1 & 3 & 4 \\ 0 & 0 & 2 \end{pmatrix}$ . The characteristic polynomial is  $(2-\lambda)((1-\lambda)(3-\lambda)-3)=-\lambda(2-\lambda)(4-\lambda)$ , so the eigenvectors are  $\lambda=0,2,4$ . The corresponding eigenvalues are  $(3,-1,0)^t$ ,  $(3,13,-4)^t$ ,  $(1,1,0)^t$ , so the corresponding eigenbasis is  $\beta=\{3-x,3+13x-4x^2,1+x\}$ . (j) In the standard basis,  $\begin{pmatrix} 3 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 \\ 2 & 1 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ . The characteristic polynomial is  $(3-t)(-t^3+t)=t(3-t)(1-t)(1+t)$ , so the eigenvalues are -1,0,1,3. The corresponding eigenvectors are  $\begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}$ ,  $\begin{pmatrix} 2 & 5 \\ 0 & -3 \end{pmatrix}$ ,  $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ ,  $\begin{pmatrix} 4 & 1 \\ 3 & 0 \end{pmatrix}$ .
  - 5.1 #8 (a) Suppose that T is not invertible. Then there is a nonzero vector  $x \in N(T)$ . Then T(x) = 0x, so it is a eigenvector with eigenvalue zero. Conversely, suppose that T(x) = 0x for nonzero x. Then  $x \in N(T)$  is nonzero, so T is not invertible. (b) Suppose that  $T(x) = \lambda x$ , so that  $\lambda^{-1}T(x) = x$ . Then  $T^{-1}(x) = T^{-1}(\lambda^{-1}T(x)) = \lambda^{-1}T^{-1}(T(x)) = \lambda^{-1}(x)$ . By reciprocity of inverses, the converse follows. (c) Take  $T = L_A$  and the same proofs go through.
  - 5.1 #9 The determinant of an upper triangular matrix is the product of the entries on the diagonal. If A is upper triangular with diagonal entires  $d_1, \ldots, d_n$ , then A tI is also upper triangular with diagonal entries  $d_1 t, \ldots, d_1 t$ , so the determinant  $\det(A tI) = (d_1 t) \cdots (d_n t)$ , so the eigenvalues are  $d_1, \ldots, d_n$ .
  - 5.1 #10 (a) Let  $\beta = \{b_1, \ldots, b_n\}$ . Then  $\lambda I_V(b_i) = \lambda b_i$ , so  $[\lambda I_V]_{\beta} e_i = [\lambda I_V]_{\beta} [b_i]_{\beta} = \lambda [b_i]_{\beta} = \lambda e_i$ , proving the claim. (b)  $\chi(t) = (\lambda t)^n$ , where  $n = \dim(V)$  (c) It is already diagonal, and the diagonal entries are all  $\lambda$ .
  - 5.1 #11 (a) Suppose  $PAP^{-1} = \lambda I$ . Then  $A = P^{-1}\lambda IP = \lambda P^{-1}IP = \lambda I$ . (b) Since a diagonalizable matrix is similar to a diagonal matrix with its eigenvalues on the diagonal, the result follows from part (a). (c) The characteristic polynomial is  $(1-t)^2$ , so the matrix has only one eigenvalue: 1. By part (b), if this matrix were diagonalizable it would be a scalar matrix, since it is not a scalar matrix it is not diagonalizable.
  - 5.1 #14 Since  $\det(B) = \det(B^t)$  for any B,  $\det(A tI) = \det((A tI)^t) = \det(A^t tI^t) = \det(A^t tI)$ .
  - 5.1 #15 (a) We proceed by induction. For m=1 the result is immediate, since  $T^1x=Tx=\lambda x=\lambda^1 x$ . Assume that  $T^{m-1}x=\lambda^{m-1}x$ . Then  $T^mx=T(T^{m-1}x)=T(\lambda^{m-1}x)=\lambda^{m-1}Tx=\lambda^{m-1}\lambda=\lambda^m$ . (b) Take  $T=L_A$ .
  - 5.1 #17 (a) Take  $A = (a_{ij})$ ; if  $T(A) = A^t = \lambda A$ , then  $a_{ji} = \lambda a_{ij}$ . Swapping i, j we have  $a_{ij} = \lambda a_{ji}$ , so  $a_{ji} = \lambda^2 a_{ji}$ . This must be true for all  $a_{ij}$ , so  $\lambda^2 = 1$ , so  $\lambda = \pm 1$ . (b) The symmetric matrices have eigenvalue 1 (since  $T(A) = A^t = A$  if A is symmetric), and the skew-symmetric matrices

have eigenvalue 
$$-1$$
 (since  $T(A) = A^t = -A$ ). (c)  $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  (d) The

first n basis vectors are diagonal matrices with a 1 on the ith diagonal entry. The next  $\frac{n(n-1)}{2}$  basis vectors are symmetric, with a 1 in the i, jth entry and a 1 in the j, ith entry and zeroes elsewhere. The next  $\frac{n(n-1)}{2}$  basis vectors are skew symmetric, with a 1 in the i, jth entry and a -1 in the j, ith entry and zeroes elsewhere.

5.1 #18 (a) We want to find c such that  $\det(A+cB) = \det(AB^{-1}+cI) \det(B) = 0$ .  $\det(AB^{-1}+cI) = \det_{AB^{-1}}(-c)$ . Since the characteristic polynomial of  $AB^{-1}$  is a polynomial of degree n (Theorem 5.3), it has a complex root, i.e. a value c such that  $\operatorname{char}_{AB^{-1}}(-c) = 0$ .

(b) 
$$A = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}, B = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

- 5.1 #20 Since  $\det(A tI)|_{t=0} = \det(A)$ , and  $f(0) = a_0$ , it follows that  $\det(A) = a_0$ . Then apply problem 8.
- 5.1 # 21 (a) We use mathematical induction.

Base case, n = 1: The statement is obviously true for a  $1 \times 1$  matrix.

Inductive Step: To induct, we expand by cofactors the first row:  $(a_{11}-t)f_1(t)-a_{12}f_2(t)\pm a_{1n}f_n(t)$ . By induction,  $f_1(t)=(a_{22}-t)\cdots(a_{nn}-t)+q(t)$  where  $\deg(q)=n-3$ . Thus,  $(a_{11}-t)f_1(t)=(a_{11}-t)\cdots(a_{nn}-t)+(a_{11}q(t)-tq(t))$ , and  $\deg(a_{11}q(t)-tq(t))\leq n-2$ . To complete the proof, it suffices to show that the  $f_i(t)$  for  $i\neq 1$  are degree  $\leq n-2$ . However, this is clear; when we delete the first row and any column that is not the first column, we delete two entries which are linear in t. The resulting cofactor has only n-2 entries involving t, which are linear in t. The monomials in the cofactor expansion are products of distinct entries of A, so in particular this cofactor must have degree  $\leq n-2$ , and we are finished. (b) Using (a), since  $\deg(q) \leq n-2$ , the  $t^{n-1}$ -coefficient of  $\det(A-tI)$  is the same as the  $t^{n-1}$ -coefficient of  $(a_{11}-t)\cdots(a_{nn}-t)$ . Using Vieta's formula, we find that  $(-1)^{n-1}a_{n-1}=a_{11}+\cdots+a_{nn}=\operatorname{tr}(A)$ .

5.1 #22 (a) It suffices to show that if  $T(x) = \lambda x$  and  $S(x) = \mu x$ , then  $(T+S)(x) = (\lambda + \mu)x$ , and also to show that if  $T(x) = \lambda x$  then  $T^m(x) = \lambda^m x$ , since every polynomial in T is the sum of powers of T. The first statement simply follows from linearity, and the second we've done earlier. (b) Take  $T = L_A$ . (c)  $A = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix}$ , so  $g(T) = 2A^2 - A + 1 = \begin{pmatrix} 7 & 4 \\ 6 & 9 \end{pmatrix}$ , so  $g(T)(2,3)^t = (26,39)^t$ . On the other hand, g(4) = 13, and g(4) = 13, and g(4) = 13, and g(4) = 13.