



$$\begin{aligned} \vec{x}_p &= \vec{x} - \vec{d} \\ x_p \text{ lies on } w \\ \therefore w^T x_p + b &= 0 \\ \Rightarrow w^T (\vec{x} - \vec{d}) + b &= 0 \\ \Rightarrow w^T (\vec{x} - \alpha \vec{w}) + b &= 0 \\ \Rightarrow \alpha &= \frac{w^T x + b}{w^T w} \\ \text{or, } \vec{d} &= \left(\frac{w^T x + b}{w^T w} \right) \cdot \vec{w} \end{aligned}$$

$$\begin{aligned} \|\vec{d}\|_2 &= \sqrt{\vec{d}^T \vec{d}} \\ &= \sqrt{\alpha^2 w^T w} = \alpha \sqrt{w^T w} = \frac{w^T x + b}{w^T w} \sqrt{w^T w} = \frac{w^T x + b}{\sqrt{w^T w}} \end{aligned}$$

$$\boxed{\|\vec{d}\|_2 = \frac{w^T x + b}{\|w\|_2}}$$

Margin of classifier $\gamma(w, b) = \min_{x \in D} \frac{w^T x + b}{\|w\|_2}$

Qim Find w which maximizes $\gamma(w, b)$, but not this so need a constraint $\forall_i y_i (w^T x_i + b) \geq 0$

$$\max_{w, b} \left[\min_{x \in D} \frac{w^T x + b}{w^T w} \right] \text{ with constraint}$$

$$\max_{w, b} \frac{1}{w^T w} \left[\min_{x \in D} w^T x + b \right]$$

Our hypothesis $\mathcal{H} = \{x: w^T x + b = 0\}$, rescale it such that

$$\min_{x \in D} w^T x + b = 1$$

so now, we are left with $\max_{w, b} \frac{1}{w^T w} \Rightarrow \min_{w, b} w^T w$ parabola with

Putting the two constraints together

$$\left. \begin{aligned} \forall_i y_i (w^T x_i + b) &\geq 1 \\ \min_{x \in D} w^T x + b &= 1 \end{aligned} \right\} \Leftrightarrow$$

$$\boxed{\begin{aligned} \Rightarrow \min_{w, b} w^T w &\text{ parabola with} \\ y_i (w^T x_i + b) &\geq 1 \text{ linear constraints} \end{aligned}}$$

Use: Quadratic problem solver