Jinwon Sohn

Reference

• Greedy Function approximation, Friedman, 2001.

• Elementary of Statistical Learning, Springer.

Numerical optimization

• In many problems, we can not obtain the closed solution for given equations.

For example, the coefficients of logistic regression.

• Ex)Solving,
$$\arg\max_{\beta_0,\beta_1} \prod_{i=1}^N \left(\frac{1}{1+e^{-(\beta_0+\beta_1x_i)}}\right)^{r_i} \left(1-\frac{1}{1+e^{-(\beta_0+\beta_1x_i)}}\right)^{1-r_i}$$

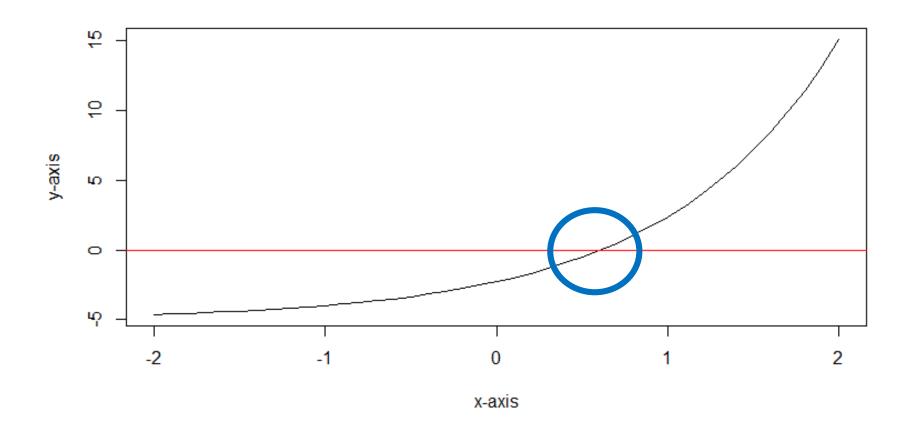
No closed solutions exist!

Newton's method

$$\bullet \ x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

•
$$x_{n+1} = x_n - \frac{f(x_n)(x_n - x_{n-1})}{f(x_n) - f(x_{n-1})}$$

Newton's method



Newton's method

- The solution might be local optimum which is the usual problem in numerical optimization.
 - > By using multiple initial points, we can bypass the problem

Other mathematical properties...

Gradient descent (or ascent)

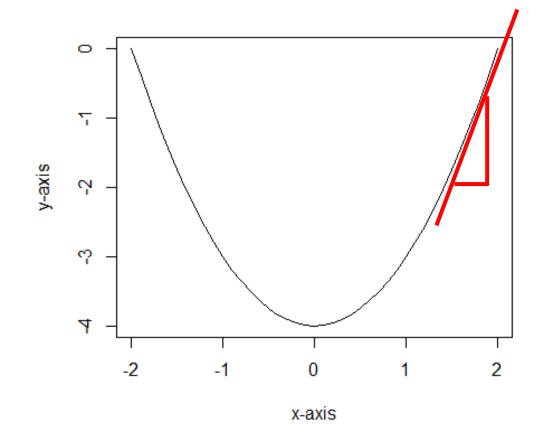
•
$$x_{n+1} = x_n - \alpha \frac{df}{dx_n}$$

• $\theta_{n+1} = \theta_n - \alpha \frac{dL}{d\theta_n}$

•
$$\theta_{n+1} = \theta_n - \alpha \frac{aL}{d\theta_n}$$

$$\bullet \ x_{n+1} = x_n - \alpha f'(x_n)$$

•
$$x_{n+1} = x_n - \alpha \frac{f(x_n) - f(x_{n-1})}{x_n - x_{n-1}}$$



Line search gradient descent

•
$$x_{n+1} = x_n - \alpha_n \frac{df}{dx_n}$$

•
$$\theta_{n+1} = \theta_n - \alpha_n \frac{dL}{d\theta_n}$$

where α_n is α minimize a function $L\left(x_n - \alpha \frac{df}{dx_n}\right)$.

Line search gradient descent

- $\theta_{n+1} = \theta_n \alpha_n \frac{dL}{d\theta_n}$
- $n \to \infty$, $\theta_n \to \theta^*$ (Solution!)
- $\theta^* = \sum_{n=0}^{\infty} \left(\theta_0 \alpha_n \frac{dL}{d\theta_n}\right)$ where θ_0 is initial value set normally as 0.
- $\theta^* \approx \sum_{n=0}^{N} \left(-\alpha_n \frac{dL}{d\theta_n} \right)$ for some large N.
- The term, $-\alpha_n \frac{dL}{d\theta_n}$, is called 'boost' or 'step'. We will see this later.

• An ensemble model composed of the sum of week models.

• A stump or simple linear regression model are kinds of week model.

In other word, the week model has the high bias.

Let's start!

So,

$$G_H(x) = \sum_{h=1}^{H} w_h g_h(x; \theta_h)$$

The learner, $G_H(x)$, averages the **week learners**, $g_h(x)$, with the weights w_h . In order to improve the performance of F(x), $\Theta = \{\theta_1, ..., \theta_H\}$ and $\omega = \{w_1, ..., w_H\}$ have to be optimized.

• Namely, the following loss function should be minimized with respect to Θ, ω .

$$\underset{\Theta,\omega}{\operatorname{arg\,min}} \sum_{i=1}^{N} L(y_i, G_H(x_i))$$

$$= \underset{\Theta,\omega}{\operatorname{arg\,min}} \sum_{i=1}^{N} L\left(y_i, \sum_{h=1}^{H} w_h g_h(x; \theta_h)\right)$$

• However, it requires intensive computation.

• Imagine what if we have to find the optimum values in $|\Theta| \times |\omega|$ -spaces.

• A simple alternative can approximate the loss function. We call "Forward Stagewise Additive Modeling".

- Optimize the parameters one by one by moving in the forward direction.
- Let $f_h(x) = f_{h-1}(x) + wg(x; \theta)$.
- Then, $f_h(x)$ will be decided by optimizing w and θ in terms of

$$\underset{w,\theta}{\arg\min} \sum_{i=1}^{N} L(y_i, f_h(x_i)), \qquad h = 1, 2, ..., H.$$

=
$$\arg\min_{w,\theta} \sum_{i=1}^{N} L(y_i, f_{h-1}(x_i) + wg(x_i; \theta)), h = 1, 2, ..., H.$$

- Let $L(y, f(x)) = (y f(x))^2$, squared loss.
- Let $f_0(x) = 0$, then
- $f_1(x)$ can be obtained by solving

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} L(y_i, f_0(x_i) + wg(x_i; \theta))$$

=

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} (y_i - wg(x_i; \theta))^2$$

• $f_2(x)$ can be obtained by solving

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} L(y_i, f_1(x_i) + wg(x_i; \theta))$$

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} (y_i - f_1(x_i) - wg(x_i; \theta))^2$$

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} (r_{1,i} - wg(x_i; \theta))^2$$
residual

• Denote these optimized parameters as w_1 and θ_1 .

• $f_3(x)$ can be obtained by solving

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} L(y_i, f_2(x_i) + wg(x_i; \theta))$$

$$\arg\min_{w,\theta} \sum_{i=1}^{N} (y_i - f_2(x_i) - wg(x_i; \theta))^2$$

$$\underset{w,\theta}{\operatorname{arg \, min}} \sum_{i=1}^{N} (y_i - f_1(x_i) - w_1 g(x_i; \theta_1) - w g(x_i; \theta))^2$$

$$\arg\min_{w,\theta} \sum_{i=1}^{N} (r_{1,i} - w_1 g(x_i; \theta_1) - w g(x_i; \theta))^2$$

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} (r_{2,i} - wg(x_i; \theta))^2 \qquad \text{residual}$$

• Denote these optimized parameters as w_2 and θ_2 .

• Thus, $f_H(x)$ can be obtained by solving

$$\underset{w,\theta}{\arg\min} \sum_{i=1}^{N} L(y_i, f_{H-1}(x_i) + wg(x_i; \theta))$$

$$\underset{w,\theta}{\operatorname{arg\,min}} \sum_{i=1}^{N} (r_{H-1,i} - wg(x_i; \theta))^2 \qquad \text{residual}$$

- $f_H(x) = f_{H-1}(x) + w_H g(x_i; \theta_H)$.
- Thus, the final model is $\sum_{h=1}^{H} f_h(x) = \sum_{h=1}^{H} w_H g(x_i; \theta_H)$.

AdaBoost

- Set $L(y, f(x)) = e^{(-yf(x))}$. 'exponential loss'.
- Set the base estimator $g_h = g(x; \theta_h)$ be a 'stump', decision tree with one depth. 'Boost'
- Weights of observations are considered. 'Adaptive!'
- If applying FSAM to above setting,
- then you can obtain following algorithm.
- Please, refer to the page 344 in ESL for the proof.

AdaBoost

- 1. Initialize the observation weight $w_i = \frac{1}{N}$, i = 1, ..., N.
- 2. For h = 1 to H:
 - (a) Fit a classifier g_h to the training data using weights w_i .
 - (b) Compute

$$err_h = \frac{\sum_i w_i I(y_i \neq g(x_i; \theta_h))}{\sum_i w_i}.$$

- (c) Compute $\alpha_h = \log((1 err_h)/err_h)$.
- (d) Set $w_i \leftarrow w_i e^{\alpha_h I(y_i \neq g(x_i; \theta_h))}$, i = 1, ..., N.
- 3. Output $G(x) = sign[\sum_{h} \alpha_{h} g(x; \theta_{h})]$

• Greedy Function Approximation, Friedman, 2001.

History...

• Consider previous steepest descent with line search algorithm.

•
$$\theta_{n+1} = \theta_n - \alpha_n \frac{dL}{d\theta_n}$$

- $\theta^* \approx \sum_{n=0}^N \left(-\alpha_n \frac{dL}{d\theta_n}\right) = \sum_{n=0}^N p_n$ for some large N.
- The increment, $p_n = -\alpha_n \frac{dL}{d\theta_n}$, is called 'boost' or 'step'.

• We can regard a function or classifier F(x) as a parameter, and optimize it numerically. This means that numerical optimization is used to estimate nonparametric function.

•
$$F_{h+1} = F_h - \alpha_h \frac{dL}{dF_h}$$

- $F^* \approx \sum_{h=0}^{H} \left(-\alpha_h \frac{dL}{dF_h} \right) = \sum_{h=0}^{H} f_h$ for some large H.
- The classifier is composed of many increment functions!

- Let $F_{m-1} = \sum_{h=0}^{m-1} f_h$.
- Then $F_m = F_{m-1} + f_m$ The increment f_m consists of $-\alpha_m \frac{dL}{dF_{m-1}}$ where $-\frac{dL}{dF_{m-1}}$ is the steepest gradient and α_m is found via the line search algorithm.

$$\alpha_m = arg \min_{\alpha} L\left(y, F_{m-1}(x) - \alpha \frac{dL}{dF_{m-1}}\right)$$

• The convergence steps or sequences of GB implicitly have the concept of Forward Stagewise Additive modeling.

• Since the negative gradients for each step are defined only at the specific data points, we have to construct models to generate the negative gradients.

• For *m*-step,

$$g_m(x; \theta_m) \approx -\frac{dL}{dF_{m-1}}$$

• In addition, the α_m come to be a weight parameter for the m-th model.

• So, the $F^*(x)$ can be approximated as,

$$F^* \approx \sum_{h=1}^{H} \alpha_h g_h(x; \theta_h)$$

- For example, set L_2 loss function for a GB model. set initial guess $f_0(x) = 0$ or $f_0(x) = \bar{y}$.
- Remember that the gradient of L_2 loss function is

$$\frac{dL_2}{dF(x)} = 2(y - F(x)).$$

• $F_1(x)$ can be obtained by solving

Step 1:
$$\theta_1 = arg \min_{\theta} \sum_{i=1}^{N} \left(-\frac{dL_2}{dF_0} - g(x_i; \theta) \right)^2$$

$$\theta_1 = arg \min_{\theta} \sum_{i=1}^{N} (-2(y_i - F_0(x_i)) - g(x_i; \theta))^2$$
Negative gradient
Step 2: $\alpha_1 = arg \min_{\alpha} \sum_{i=1}^{N} (y_i - F_0(x_i) - \alpha g(x_i; \theta_1))^2$
Step 3: $F_1(x) = F_0(x) + \alpha_1 g(x_i; \theta_1)$

• $F_2(x)$ can be obtained by solving

Step 3: $F_2(x) = F_1(x) + \alpha_2 g(x_i; \theta_2)$

Step 1:
$$\theta_2 = arg \min_{\theta} \sum_{i=1}^{N} \left(-\frac{dL_2}{dF_1} - g(x_i; \theta) \right)^2$$

$$\theta_2 = arg \min_{\theta} \sum_{i=1}^{N} (-2(y_i - F_1(x_i)) - g(x_i; \theta))^2$$

$$\theta_2 = arg \min_{\theta} \sum_{i=1}^{N} (-2(y_i - F_0(x_i) - \alpha_1 g(x_i; \theta_1)) - g(x_i; \theta))^2$$
Fitting on residuals!?

Step 2: $\alpha_2 = arg \min_{\alpha} \sum_{i=1}^{N} (y_i - F_1(x_i) - \alpha g(x_i; \theta_2))^2$

• $F_H(x)$ can be obtained by solving

Step 3: $F_H(x) = F_{H-1}(x) + \alpha_H g(x_i; \theta_H)$

Step 1:
$$\theta_{H} = arg \min_{\theta} \sum_{i=1}^{N} \left(-\frac{dL_{2}}{dF_{H-1}} - g(x_{i}; \theta) \right)^{2}$$

$$\theta_{H} = arg \min_{\theta} \sum_{i=1}^{N} (-2(y_{i} - F_{H-1}(x_{i})) - g(x_{i}; \theta))^{2}$$

$$\theta_{H} = arg \min_{\theta} \sum_{i=1}^{N} (-2(y_{i} - F_{H-2}(x_{i}) - \alpha_{H-1}g(x_{i}; \theta_{H-1})) - g(x_{i}; \theta))^{2}$$
Fitting on residuals!?

Step 2: $\alpha_{H} = arg \min_{\alpha} \sum_{i=1}^{N} (y_{i} - F_{H-1}(x_{i}) - \alpha g(x_{i}; \theta_{H}))^{2}$

- What is the significance of Gradient Boosting?
- Seemingly, it is equal to basic boosting in L_2 loss function.
- However, If we use L_1 , or Huber loss function, GB has a more general applications.
- That's why we call the boost(or step) as the negative gradient, not residual even in L_2 loss function.

• L_1 loss function and its derivative.

$$L_1 = \sum_{i=1}^{N} |y_i - F(x_i)|, \qquad \frac{dL_1}{dF(x)} = sign(y - F(x))$$

This loss function is robust to outliers.

- Huber loss function and its derivative please, refer to https://en.wikipedia.org/wiki/Huber_loss
- You can customize your own loss function.

• You should specify the size of tree for each increment.

• Heuristically, $4 \le d \le 8$.

• The depth, d, reflect the order of an interaction!

• If a tree has 3 depth, then the tree includes not only main effect, but also up to third interactions.

• In classification problem, use the following setting.

$$L(\{y_k, F(x_k)\}_1^K) = -\sum_{k=1}^K y_k \log p_k(x)$$

$$F_k(x) = \log p_k(x) - \frac{1}{K} \sum_{k=1}^K y_k \log p_k(x)$$

Extended Gradient Boosting

- Stochastic Gradient Booting
 - > Subsampled data without replacement is used to fit a increment function. This do lighter computations.
 - > A bit of resistance on overfitting
- Regularized Gradient Booting
 - > Charge penalties onto the number of trees.

$$F_m(x) = F_{m-1}(x) + \nu_{penalty} \alpha_m g(x_i; \theta_m)$$

XGBoost

• Gradient boosting needs burdensome computations which makes it difficult to apply GB models into Big data.

 T. Chen wrote in his paper how to improve computation ability by adjusting algorithms to build a tree.

Refer to "https://gentlej90.tistory.com/87"

LightGBM

• Structural difference.

 For more details, refer to https://towardsdatascience.com/catboost-vs-light-gbm-vs-xgboost-5f93620723db

CatBoost

• Feature engineering on categorical predictors.

 For more details, refer to https://towardsdatascience.com/catboost-vs-light-gbm-vs-xgboost-5f93620723db