# 2018 Ajou3

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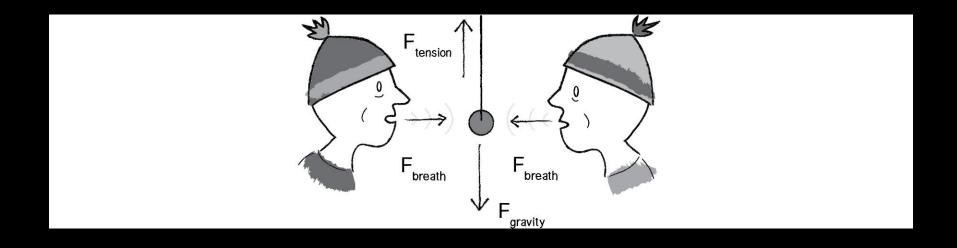
#### Forces and Newton's Laws of Motion

- A force is a vector that causes an object with mass to accelerate.
- 힘은 질량 있는 객체가 가속도를 갖게 하는 벡터.

#### Newton's First Law

• 다른 힘의 영향을 받지 않는다면 가만히 있는 물체는 계속 가만히 있고, 움직이는 물체는 같은 속도와 방향으로 계속 움직인다.

## Newton's First Law



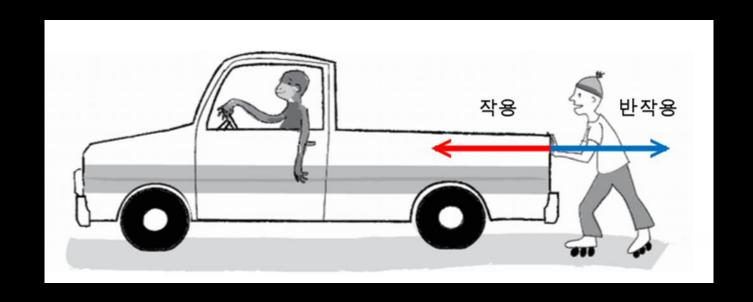
### Newton's First Law

• An object's PVector velocity will remain constant if it is in a state of equilibrium.

#### Newton's Third Law

- 어떤 물체에 힘을 주면 반대 방향으로도 같은 힘이 일어난다.
- Forces always occur in pairs.
- The two forces are of equal strength, but in opposite directions.

### Newton's Third Law



### Newton's Third Law

• A라는 물체가 B라는 물체에 PVector f라는 힘을 준다면 B도 A에 PVector.mult(f,-1)만큼의 힘을 주어야 한다.

Force equals mass times acceleration.

$$F = ma$$

$$a = F/m$$

- The acceleration of an object is equal to force.
- Location is adjusted by velocity, and velocity by acceleration.
- Acceleration was where it all began.
- Force is truly where it all begins.

```
class Mover {
   PVector location;
   PVector velocity;
   PVector acceleration;
}
```

```
void applyForce(PVector force) {
//Newton's second law at its simplest.
//But this function has problem.
//What's that?
 acceleration = force;
mover.applyForce(wind);
mover.appyForce(gravity);
```

### Force Accumulation

velocity.add(acceleration);
 void applyForce(PVector force) {
 acceleration.add(force);
 }

#### Force Accumulation

```
if (mousePressed) {
   PVector wind = new PVector(0.5,0);
   mover.applyForce(wind);
}
```

Since we're adding all the forces together at any given moment, we have to make sure that we clear acceleration (i.e. set it to zero) before each time update() is called.

#### Force Accumulation

```
void update() {
 velocity.add(acceleration);
 location.add(velocity);
 acceleration.mult(0);// 가속도를 0으로
}
```

## Dealing with Mass

```
class Mover {
   PVector location;
   PVector velocity;
   PVector acceleration;
   float mass;
}
```

## Dealing with Mass

```
Mover() {
    location = new
        PVector(random(width),random(height));
    velocity = new PVector(0,0);
    acceleration = new PVector(0,0);
    mass = 10.0;
}
```

## Creating Forces

- Make up a force.
- Model a force

#### Gravity on Earth and Modeling a Force

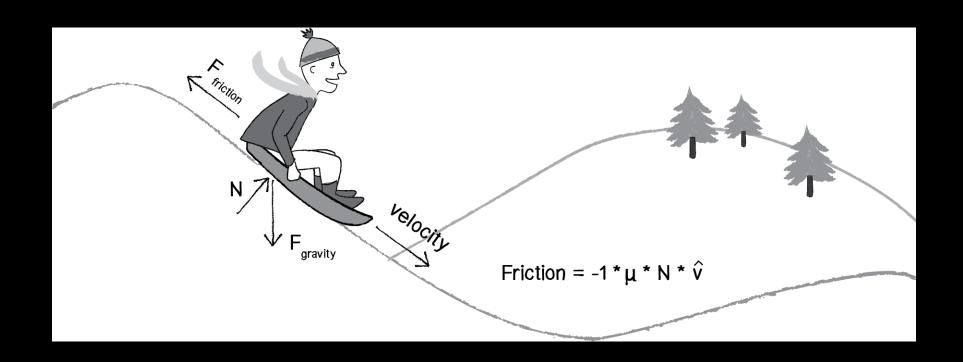
```
for (int i = 0; i < movers.length; i++) {
   PVector wind = new PVector(0.001,0);
   float m = movers[i].mass;
        //Scaling gravity by mass to be more accurate
   PVector gravity = new PVector(0,0.1*m);
   movers[i].applyForce(wind);
   movers[i].applyForce(gravity);
   movers[i].update();
   movers[i].display();
   movers[i].checkEdges();
```

### Reference

```
void applyForce(PVector force) {
//Making a copy of the PVector before //using it!
   PVector f = force.get();
   f.div(mass);
   acceleration.add(f);
}
```

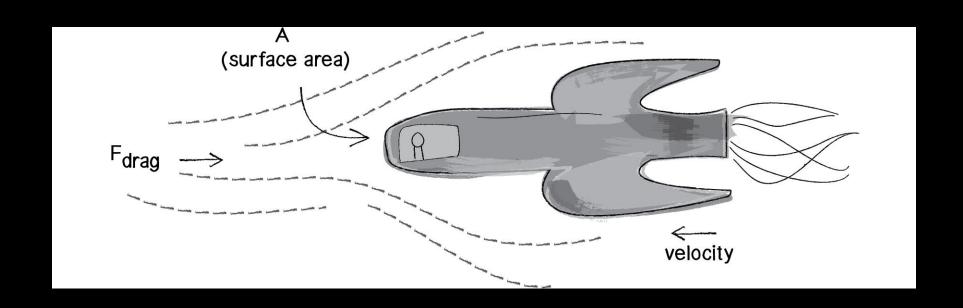
## Test

- 마찰력
  - 흩어지는 힘으로 물체가 움직일 때 전체 에너지를 감소 시키는 힘
- static friction
- kinetic friction



```
PVector friction = velocity.get();
friction.normalize();
friction.mult(-1);
```

```
• µ * N
• μ : coefficient of friction
• N : Normal force
float c = 0.01;
float normal = 1;
float frictionMag = c*normal;
PVector friction = velocity.get();
friction.mult(-1);
friction.normalize();
friction.mult(frictionMag);
```

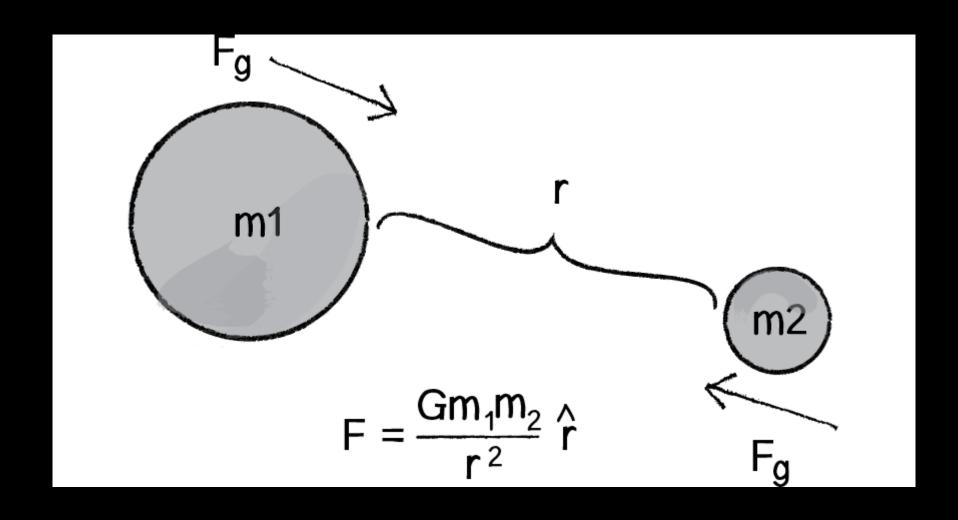


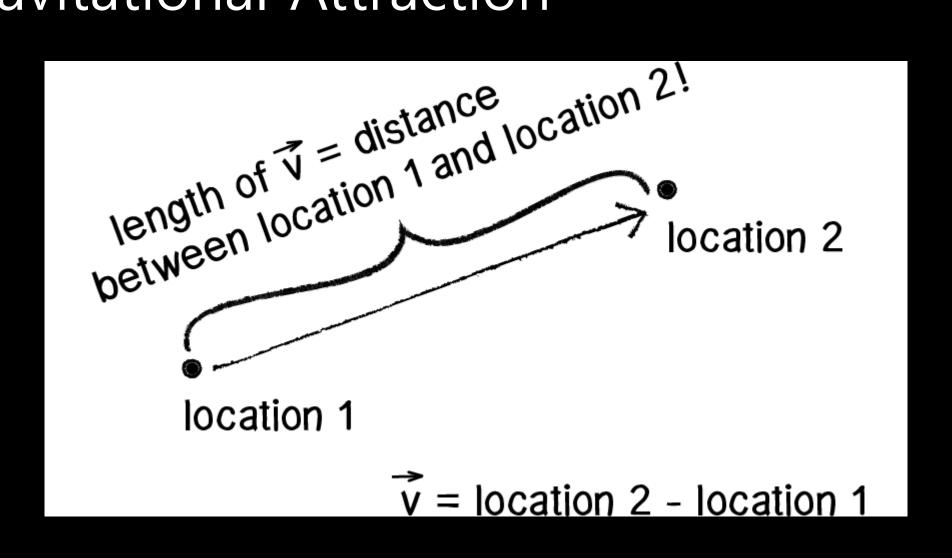
$$F_d = -rac{1}{2}
ho v^2 A C_d \overset{\wedge}{v}$$

Fd = 저항력 P = 액체밀도 V = 객체의 속력 A = 액체와 닿는 앞쪽 면적 Cd = 저항 계수 V^ = 속도의 방향 단위 벡터

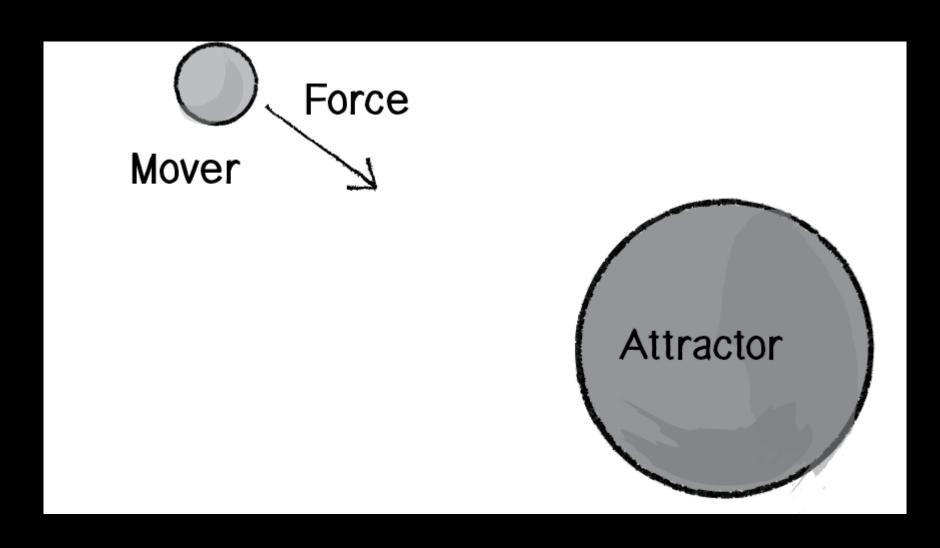
magnitude is speed squared \* coefficient of drag
$$F_{drag} = \|\mathbf{v}\|^2 * \mathbf{c}_d * \hat{\mathbf{v}} * -1$$
direction is opposite of v (velocity)

```
float c = 0.1;
float speed = v.mag();
float dragMagnitude = c * speed * speed;
PVector drag = velocity.get();
drag.mult(-1);
drag.normalize();
drag.mult(dragMagnitude);
```





```
PVector force = PVector.sub(location1,location2);
float distance = force.magnitude();
float m = (G * mass1 * mass2) / (distance * distance);
force.normalize();
force.mult(m);
```



#### Attractor

- Attractor is simple object that doesn't move.
- We just need a mass and a location.

## Break...

• CU..