

All Models Are Wrong, but Some Are Interchangeably Right

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Abstract

Many tasks require practitioners to select machine learning (ML) models among many possible models that differ in terms of inductive biases, computational costs, and interpretability. At the same time, real-world datasets often contain underlying properties that are difficult to uncover but can significantly influence the predictive performances of the models. Overall, this raises an important question: **to what extent do different models agree in what they reveal about the underlying phenomena embedded in the dataset at hand?** In this work, we explore this question by analyzing the agreement between ML models using attributional post-hoc explainability methods. Specifically, we leverage Shapley-based feature-importance rankings to measure the similarity of explanations across diverse model families, both at a local (instance level) scale and at the global (feature level) scale. We interpret these post-hoc attributions as proxies for what ML models have learned from the data, and for the extent to which different models capture and agree on the same underlying phenomena. Our study covers 30 benchmark problems in regression and classification to provide a systematic comparison of 46 predictive ML models. We identify recurring agreement regimes in which models with very different architectures produce highly similar top-ranked explanations. We further identify model families that consistently exhibit such agreements. Additionally, our analysis uncovers systematic interactions between certain model families and the datasets or tasks they are applied to. Low-agreement regimes are associated with unstable explanations, meaning that both task and dataset characteristics are important factors to consider when selecting models. Finally, we find that some lightweight models can generate explanations that are effectively interchangeable with those of more complex architectures, while requiring fewer computational resources or less data. In this context, explanation agreement provides a practical criterion that supports automated XAI (AutoXAI) and model recommendation workflows.

1 Introduction

ML models are increasingly deployed in high-stakes decision-making pipelines, including healthcare, criminal justice, and credit lending, where understanding the rationale behind predictions is critical [Rudin, 2019]. In such contexts, it is no longer sufficient for a model to merely maximize predictive accuracy; it must also provide an auditable account of its reasoning [Lakkaraju and Rudin, 2017]. Yet, many state-of-the-art system such as deep neural networks and ensemble methods, remain opaque, raising concerns about trust, accountability, and regulatory compliance [Apley and Zhu, 2020]. Explainable Artificial Intelligence (XAI) has emerged to address this tension. Among existing techniques, SHapley Additive exPlanations (SHAP) have become a widely adopted framework for post-hoc feature attribution, offering a principled approach to interpreting complex models [Lundberg and Lee, 2017]. Implicit in much of this practice is the assumption that different model architectures yield meaningfully different explanations, making interpretability inherently model-dependent. However, recent work suggests that the presence of an explanation does not guarantee its reliability [Ribeiro *et al.*, 2016]. The field has shifted from a narrow focus on explanatory faithfulness toward the broader question of **explanatory consistency** [Rudin, 2019]. Central to this issue is the **Rashomon Effect**: multiple models can achieve similar predictive performance while relying on different internal decision mechanisms [Breiman, 2001]. This multiplicity can lead to contradictory explanations for the same task, a challenge often framed as the **disagreement problem** [Krishna *et al.*, 2022]. While prior studies have documented cases of disagreement, systematic empirical evidence across a broad spectrum of models remains limited.

In this work, we adopt a complementary perspective: rather than asking when explanations diverge, we ask **when they converge, and what such convergence implies about the relationship between data, models, and interpretability**. Specifically, we analyze the alignment of SHAP-based feature importance rankings across a diverse set of models. If explanations vary widely with model choice, interpretability must be treated as model-contingent. Conversely, if explanations remain stable across architectures, this suggests a form of descriptive robustness rather than model-specific variability.

To structure this analysis, we distinguish between **local**

88 and **global** explanations. Local explanations assign feature
89 importance to individual predictions, enabling instance-level
90 interpretability, whereas global explanations aggregate attri-
91 bution patterns across an entire dataset, capturing more sta-
92 ble, population-level insights [Minh *et al.*, 2022]. We also
93 contrast **post-hoc** explanations from black-box models with
94 **intrinsically interpretable** models, allowing us to assess
95 whether observed patterns are driven by model structure or
96 by the data itself [Bibal, 2020].

97 Experimentally, we conduct a large-scale study of SHAP-
98 based feature importance rankings across and quantify cross-
99 model alignment using Normalized Discounted Cumula-
100 tive Gain (NDCG), a standard metric for ranking similar-
101 ity [Järvelin and Kekäläinen, 2002]. Our results reveal a new
102 pattern: despite substantial architectural differences, many
103 models produce highly similar explanations. We identify
104 clusters of models with strongly aligned feature rankings,
105 indicating that in many cases, explanatory behavior is gov-
106 erned more by data structure than by model complexity. **To**
107 **our knowledge, this is the first systematic benchmark that**
108 **evaluates explanation agreement across a broad diversity**
109 **of model families and tasks under a unified ranking-based**
110 **metric.** Based on these findings, we introduce the notion of
111 **explanation interchangeability.** Two models are deemed inter-
112 changeable when their SHAP rankings exhibit high con-
113 sensus (around 90%) in instance-based feature rankings, in-
114 dicating that the identity of the most influential features is
115 largely insensitive to model choice under the considered ex-
116 plainer. This has important practical consequences: in many
117 settings, lightweight models yield explanations that are sta-
118 tistically indistinguishable from those of far more complex
119 ensembles while being dramatically cheaper to train and an-
120alyze. Consequently, heavy models often provide little addi-
121 tional interpretive value. This enables more principled model
122 selection for explanation-focused workflows, including the
123 identification of models that maximize explanatory consen-
124 sus while minimizing computational cost. This is particularly
125 relevant in regulated or resource-constrained settings, where
126 organizations must justify model behavior while minimizing
127 computational and operational costs

128 The contributions of this paper are threefold:

- 129 1. We present a large-scale systematic comparison of
130 SHAP-based feature importance rankings across 46 pre-
131 dictive models and 30 real-world datasets.
- 132 2. We highlight recurring regimes of **explanation inter-**
133 **changeability**, demonstrating that interpretability is fre-
134 quently driven more by data properties than by model
135 architecture.
- 136 3. We derive practical guidelines for selecting computa-
137 tionally efficient surrogate models that preserve expla-
138 nation reliability.

139 The remainder of this paper is organized as follows. Sec-
140 tion 2 reviews related work on XAI, explanation disagree-
141 ment, and the Rashomon effect. Section 3 describes the clas-
142 sification and regression benchmark datasets. Section 4 de-
143 tails our experimental protocol and cross-model NDCG anal-
144 ysis. Finally, Section 5 discusses the implications for robust
145 interpretability and outlines future research directions.

2 Motivations and background

This section positions our work on post-hoc explainability
147 and presents well-known sources of explanatory divergences,
148 such as the **disagreement problem** or the **Rashomon effect**.
149

2.1 Current Trends and Problematics in Black-Box AI

A central tension in contemporary ML concerns the relation-
152 ship between model expressivity, data availability, and in-
153 terpretability [Garouani *et al.*, 2024]. In low-data or noise-
154 dominated regimes, simple and inherently interpretable mod-
155 els, such as linear models or shallow decision trees, often pro-
156 vide a direct and intelligible mapping between inputs and out-
157 puts. Their explicit structure supports human understanding
158 and qualitative reasoning, but this transparency is frequently
159 obtained at the cost of limited representational power, re-
160duced predictive accuracy, or instability under small data per-
161 turbations. In contrast, highly expressive models with many
162 degrees of freedom, including multilayer perceptrons, deep
163 neural networks, and large ensemble methods, are specifically
164 designed to exploit large-scale datasets. These models can ap-
165 proximate complex, nonlinear decision boundaries and inter-
166 actions, thereby achieving superior predictive performance,
167 but they do so by encoding decision logic in high-dimensional
168 parameter spaces that are largely opaque to human interpre-
169 tation [Palar *et al.*, 2025]. This opposition reflects the episte-
170 mological divide described by [Breiman, 2001] between the
171 **data modeling** and **algorithmic modeling** cultures. Data
172 modeling relies on explicit assumptions about the stochas-
173 tic data-generating process, producing simple, interpretable
174 models that favor inference and explanatory insight over pre-
175 dictive accuracy. These models perform well with limited
176 data or strong prior knowledge but often struggle with com-
177 plex, high-dimensional phenomena. In contrast, algorithmic
178 modeling treats the mechanism as unknown, focusing on flexi-
179 ble, data-driven prediction. While powerful for large-scale
180 tasks, interpretability becomes a post-hoc concern rather than
181 an inherent property of the model, giving rise to **post-hoc**
182 **XAI**.

183 Importantly, this tension should not be interpreted as a uni-
184 versal or immutable trade-off between interpretability and ac-
185 curacy. Rather, it is strongly conditioned on the data regime,
186 the dimensionality of the feature space, and the inductive bi-
187 ases of the learning algorithm [Beckh *et al.*, 2021]. Recent
188 empirical evidence has challenged the widespread assump-
189 tion that black-box complexity is a prerequisite for high per-
190 formance in tabular and structured data settings. Large-scale
191 benchmarking studies [Christodoulou *et al.*, 2019] demon-
192 strate that transparent algorithms, such as logistic regression,
193 scoring systems, and rule-based models, often achieve pre-
194 dictive performance within approximately 5% of state-of-
195 the-art black-box methods across a wide range of medical
196 and tabular datasets [Peterson *et al.*, 2024]. These findings
197 suggest that, in many practical scenarios, the use of highly
198 opaque models is a default choice rather than a mathematical
199 necessity, and resonate with benchmarking suites that show
200 substantial variance across datasets and tasks [Olson *et al.*,
201 2017]. Notwithstanding, these results should be mitigated

in more extreme regimes characterized by massive datasets, high-dimensional feature spaces, and complex hierarchical structures. In such cases, deep learning and flexible model architectures are generally more fitted, while transparent models often fail to scale or to capture the relevant interactions because their simplicity makes them too rigid or sensitive to the curse of dimensionality. Still, in these cases, a shift in paradigm has emerged: rather than replacing black-box models, ML models are leveraged to extract intelligible, faithful, and stable explanations from underlying models whose complexity appears unavoidable [Moss *et al.*, 2022]. In that case, ML models are treated as **surrogate models** [Saves *et al.*, 2024] and have fueled the rapid development of fast-to-evaluate post-hoc explainability methods, with SHAP, LIME, or gradient-based approaches becoming de facto standards in applied ML [Sundararajan *et al.*, 2017].

Despite their theoretical appeal and growing adoption, post-hoc explanation methods have exposed a fundamental fragility in current XAI practice, commonly referred to as the **Disagreement Problem** [Krishna *et al.*, 2022]. Empirical studies reveal that different explanation techniques applied to the same trained model often produce conflicting feature rankings, and that even minor changes in model initialization, training data splits, or random seeds can result in substantially different explanations for models with indistinguishable predictive performance. This instability undermines the use of explanations as reliable scientific or decision-support tools and motivates rigorous analyses of explanation variability [Müller *et al.*, 2023]. Two primary sources of explanation variability can be distinguished. The first is method-driven variability, which arises from the explanation algorithm itself. Many post-hoc methods rely on stochastic sampling, surrogate fitting, or heuristic design choices, making them sensitive to hyperparameters such as kernel widths, baseline selection, sampling budgets, or neighborhood definitions; smoothing and aggregation strategies (e.g., SmoothGrad) mitigate but do not eliminate such sensitivity [Smilkov *et al.*, 2017]. The second, more fundamental source is model-driven variability, which is rooted in predictive multiplicity and formalized by the **Rashomon Effect**. As articulated in [Anderson, 2016] and empirically analyzed in [Müller *et al.*, 2023], the hypothesis space often contains a large set of models, referred to as the Rashomon set, that achieve near-identical empirical risk while relying on different combinations of features, interactions, or internal representations. When feature redundancy or multicollinearity is present, attributions can be arbitrarily partitioned among correlated predictors. This phenomenon has profound implications for explainability. Two models drawn from the Rashomon set may be fully interchangeable from a predictive standpoint, yet yield explanations that are descriptively incompatible. In such cases, explanations reflect the arbitrary outcome of the optimization process rather than a unique, data-driven relationship between inputs and outputs. In high-stakes contexts, this instability poses a critical risk: if retraining a model with a different random seed shifts the dominant explanatory factor from one variable to another, the resulting explanation cannot be interpreted as a robust insight, let alone a causal mechanism [Mehdiyev *et al.*, 2025]. Instead, it becomes an artifact of model selection

within a vast space of equally performant alternatives. Similarly, recent work on Shapley effects and dependence-aware attribution methods shows that, in the presence of correlated inputs, feature attributions are not uniquely defined because the underlying cooperative game depends on how feature dependence is modeled. While Shapley-based decompositions (including interaction or dividend-based formulations) provide a principled allocation of shared effects once a value function is specified, the choice of marginalization or conditioning, implicitly fixing a joint input distribution, ultimately determines how importance is assigned among correlated predictors; without such assumptions or an explicit causal model, attribution remains fundamentally underdetermined [Idrissi *et al.*, 2021].

Beyond variability, several additional problems constrain the operational utility of black-box explanations. First, computational and statistical costs are non-trivial: exact Shapley computations are combinatorial, and practical algorithms trade off bias, variance, and computational tractability, which harden large-scale deployment [Lundberg and Lee, 2017]. Second, many attribution methods implicitly rely on conditional expectation estimators; when these estimators are misspecified or when covariates are strongly dependent, attributions can be misleading unless dependence is explicitly modeled [Idrissi *et al.*, 2021]. Third, explanation fragility to small input perturbations or adversarial manipulations raises concerns about faithfulness and safety in operational systems [Smilkov *et al.*, 2017]. Finally, the evaluation of explanations is itself an open problem: while rank-based measures (Kendall’s τ , Spearman ρ , NDCG) and fidelity metrics are useful for cross-model comparison, no single metric captures human comprehensibility, causal validity, or task-specific utility simultaneously [Wang *et al.*, 2023]. The literature has responded with several converging strategies. Advocates of inherently interpretable models argue for preferring transparent models by design in high-stakes settings and have produced practical high-fidelity interpretable architectures and scoring systems [Caruana *et al.*, 2015]. Complementary lines of work pursue **regularization for explainability**, whereby training-time penalties encourage sparse, stable, or human-aligned representations so that post-hoc attributions become more consistent and meaningful [Plumb *et al.*, 2020]. Ensemble and consensus techniques quantify explanation uncertainty by aggregating attributions across model ensembles or across explainers and reporting agreement intervals or rank-consensus statistics [Levy *et al.*, 2025]. Surrogate-model workflows construct compact, interpretable proxies to summarize global behavior while reserving local post-hoc tools for detailed inspection. Dependence-aware attribution and causal conditioning operationalize this trade-off by explicitly encoding the priors or structural constraints that resolve attribution ambiguity: they formalize choices about marginalization, conditioning, or causal structure that effectively reduce the space of admissible explanations [Kennedy and O’Hagan, 2001]. In that sense, these methods are between the two strategies described above, aligning with interpretable-by-design and regularization-for-explainability approaches (which impose structural or sparsity priors during training) while remaining compatible with surrogate and

ensemble workflows [Rudin, 2019]. Practically, such priors should be elicited from domain knowledge and made explicit so their influence on attributions can be assessed and validated within a Bayesian or uncertainty quantification framework [Livet and Varenne, 2020; Wilhelm and Zweig, 2024]. Together with ensemble/consensus techniques that quantify explanation uncertainty and surrogate proxies that capture global behavior, dependence-aware attributions form a coherent toolbox for producing explanations that are both principled and practically actionable [Lakkaraju and Rudin, 2017]. Taken together, these trends indicate that black-box XAI is maturing: the field is shifting from single-method visualizations toward characterizing explanation distributions and their dependence on model choice, data regime, and estimation procedure [Apley and Zhu, 2020]. In practice, this encourages preferring interpretable-by-design models when stakes are high, evaluating explanations with multiple metrics and human-grounded protocols, accounting for dependence and causal structure, and reporting uncertainty or consensus rather than a single attribution vector [Löfström *et al.*, 2022].

Our study is situated within this evolving landscape. Motivated by the Rashomon-driven instability of attributions and the operational need for robust interpretability, we adopt an interchangeability perspective: we quantify consensus across model families using rank-based and top-weighted metrics and investigate the conditions under which explanations reflect genuine data signal versus model assumptions. This approach extends recent benchmarking and consensus work [Le *et al.*, 2023] and contributes operational criteria for trustworthy interpretation in regimes where predictive multiplicity is unavoidable. From an evaluation perspective, it is crucial to distinguish between **explanation fidelity** and **human interpretability**, two concepts often conflated in XAI [Doshi-Velez and Kim, 2017]. Fidelity measures how accurately an explanation reflects the behavior of the underlying predictive model, while interpretability captures the extent to which the explanation can be meaningfully understood and acted upon by a human. Post-hoc methods such as SHAP primarily optimize fidelity, producing local attributions that, in expectation, align with the model’s input–output mapping [Lundberg and Lee, 2017]. Yet, high-fidelity explanations are not necessarily stable, sparse, or cognitively tractable, especially under feature dependence or predictive multiplicity. Conversely, explanations designed for human interpretability, such as simplified rule lists or sparse scoring systems [Mehdiyev *et al.*, 2025], may trade off fidelity to individual black-box predictions. This tension motivates a shift from single-model explanations toward assessing robustness and consensus across families of near-optimal models, evaluating fidelity collectively rather than on a per-instance basis.

2.2 Mathematical Framework for Post-hoc Explainability

To systematically study how different ML models yield explanations, we formalize post-hoc interpretability in terms of feature attribution vectors. Let $\hat{f} : \mathcal{X} \rightarrow \mathbb{R}$ denote a predictive model trained on d features, and let $\mathbf{x} \in \mathcal{X}$ be an input instance. A post-hoc explainer assigns to each fea-

ture i a contribution $\phi_i(\mathbf{x}; \hat{f})$, capturing its influence on the model’s output. The resulting attribution vector for \mathbf{x} is $\mathbf{s}(\mathbf{x}; \hat{f}) = (\phi_1, \dots, \phi_d) \in \mathbb{R}^d$, which provides a compact representation of local explanations suitable for quantitative comparison across models.

Among post-hoc methods, SHAP stands out due to its theoretical foundations rooted in cooperative game theory. For a subset of features $S \subseteq \{1, \dots, d\}$, the SHAP value function is defined as $v_{\mathbf{x}}(S) = \mathbb{E}[\hat{f}(\mathbf{X}) \mid \mathbf{X}_S = \mathbf{x}_S]$, which represents the expected output of \hat{f} when features in S are fixed to their observed values, while others vary according to the underlying distribution. The SHAP attribution for feature i is computed as the average marginal contribution across all feature subsets: $\phi_i(\mathbf{x}) = \sum_{S \subseteq \{1, \dots, d\} \setminus \{i\}} \frac{|S|!(d-|S|-1)!}{d!} (v_{\mathbf{x}}(S \cup \{i\}) - v_{\mathbf{x}}(S))$, ensuring the additive decomposition: $\hat{f}(\mathbf{x}) = v_{\mathbf{x}}(\emptyset) + \sum_{i=1}^d \phi_i(\mathbf{x})$. Exact computation is combinatorial and often intractable; practical algorithms such as TreeSHAP, KernelSHAP, or Monte Carlo approximations introduce computational and statistical biases, and rely on explicit assumptions about background distributions or feature dependence [Apley and Zhu, 2020]. Variants such as dependence-aware Shapley and Shapley effects further formalize the role of correlations and conditional distributions, highlighting that explanations are only fully defined once these assumptions are specified.

Because feature attributions vary in scale across model architectures (e.g., logits in neural networks versus probability masses in tree ensembles), comparing raw attribution magnitudes is often misleading. Rank-based metrics therefore provide a more robust notion of agreement by emphasizing the consistency of top-ranked features.

Let $|S_i^{(k)}| \in \mathbb{R}^d$ denote the vector of absolute SHAP values for instance k under model M_i , and let $\pi_i^{(k)}$ be the ranking of features induced by sorting $|S_i^{(k)}|$ in decreasing order. Given two models M_i and M_j , the DCG of the ranking $\pi_i^{(k)}$ evaluated using relevance scores from

M_j is defined as $\text{DCG}(\pi_i^{(k)}, M_j) = \sum_{r=1}^d \frac{\text{rel}_{\ell}^{(k)}(r)}{\log_2(r+1)}$, where $\text{rel}_{\ell}^{(k)} = |S_j^{(k)}[\ell]|$ denotes the relevance of feature ℓ according to model M_j . The corresponding normalized score is obtained by dividing by the ideal DCG, i.e., the DCG obtained when ranking features according to M_j itself: $\text{NDCG}(|S_i^{(k)}|, |S_j^{(k)}|) = \frac{\text{DCG}(\pi_i^{(k)}, M_j)}{\text{DCG}(\pi_j^{(k)}, M_j)}$. To aggregate instance-level comparisons, we define the instance-averaged directional similarity between models M_i and M_j as $\rho_{ij}^{\text{NDCG}} = \frac{1}{n} \sum_{k=1}^n \left(\text{NDCG}(|S_i^{(k)}|, |S_j^{(k)}|) \right)$, where n is the number of test instances. Values of $\rho_{ij}^{\text{NDCG}} \approx 1$ indicate strong agreement in top-feature rankings, suggesting that the dominant explanatory patterns are driven by the underlying data rather than by model-specific properties. Note that ρ_{ij}^{NDCG} is directional and generally differs from ρ_{ji}^{NDCG} . This formalism allows us to operationalize the notion of **explanation interchangeability**. By representing models

430 through their attribution vectors $s(\mathbf{x}; \hat{f})$ and comparing them
431 using ρ_{ij}^{NDCG} , we can identify clusters of models within the
432 Rashomon set whose explanations are consistent despite ar-
433 chitectural differences. Such clusters correspond to scenar-
434 ios where the top-ranked features are largely dictated by the
435 structure of the data, revealing that interpretability often re-
436 flects stable, intrinsic properties of the data-generating pro-
437 cess rather than the choice of predictive model.

438 Moreover, this framework enables several practical in-
439 sights. First, it provides a principled metric for select-
440 ing a **centroid model** that maximizes explanatory consensus
441 within a family of high-performing predictors, reducing com-
442 putational cost without compromising interpretability. Sec-
443 ond, it quantifies conditions under which model interchange-
444 ability fails, for instance, in datasets with strong nonlinear in-
445 teractions, high feature redundancy, or when models have di-
446 vergent inductive biases. Finally, by formalizing the link be-
447 tween data structure, predictive multiplicity, and feature at-
448 tribution agreement, this approach grounds our subsequent ex-
449 perimental analysis, allowing us to systematically explore the
450 interplay between accuracy, explanation stability, and com-
451 putational efficiency across diverse ML architectures.

452 3 Datasets and ML models

453 To evaluate our approach, we selected 30 datasets from the
454 PMLB benchmark [Olson *et al.*, 2017], and removed dupli-
455 cate inputs. The ML models are given in Figure 1. We sepa-
456 rate the datasets according to their targets into regression
457 and classification tasks. These datasets cover a broad range
458 of applications, as well as combinations of categorical, ordi-
459 nal, and continuous features. The descriptions of the selected
460 datasets and models are given in the supplementary materials.
461 For each dataset, we use a random 70%/30% train/test split to
462 evaluate predictive performance and explanation agreement.
463 Every ML model comes with a k -folds cross validation of the
464 hyperparameter optimization to ensure a fair comparison be-
465 between the best versions of the ML for every dataset.

466 3.1 Classification

467 We evaluate 15 classification ML models (detailed in the sup-
468 plementary materials) on 15 classification datasets, covering
469 both binary and multi-class problems. These datasets span a
470 wide range of sizes, dimensionalities, and numbers of classes.
471 The number of instances ranges from 150 to nearly 50,000,
472 with feature dimensions varying from 5 to 61 and up to four
473 target classes. Handling explanations in multi-class settings
474 is inherently more complex than in binary classification or
475 regression because SHAP returns one attribution vector per
476 class for each instance. To maintain a consistent and tractable
477 experimental protocol across datasets and models, we adopt
478 a pragmatic strategy: for each instance, we retain only the
479 SHAP attributions associated with the class predicted by the
480 model. This enables the construction of a single explanation
481 matrix per dataset and simplifies the computation of global
482 agreement metrics between models. However, this simplifi-
483 cation increases the dependence of explanations on model
484 behavior and predictive accuracy rather than solely on the
485 underlying data distribution: misclassified instances are ex-
486 plained with respect to an incorrect class, and classes that are

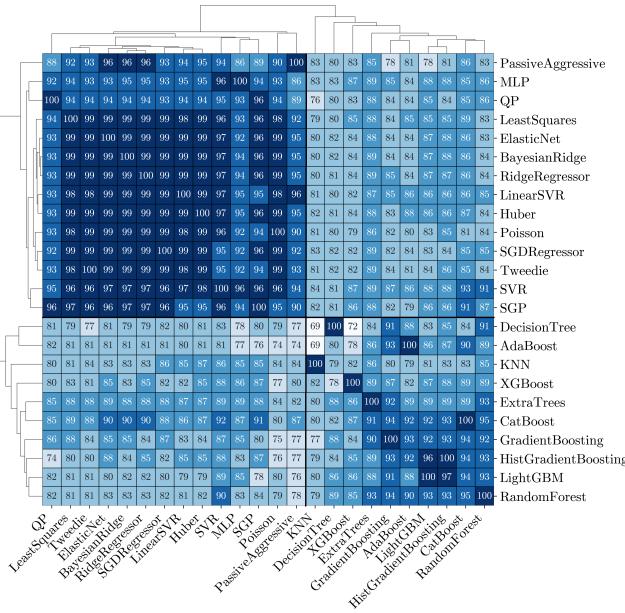
487 harder to predict tend to be underrepresented in global vi-
488 sualizations. To evaluate the robustness of our conclusions,
489 we experiment with 16 machine-learning models on the clas-
490 sification datasets and extend the analysis to the regression
491 cases, where explanations are single-output, and comparisons
492 are less prone to the bias introduced by predicted-class selec-
493 tion. For classification, GaussianNB, LightGBM, CatBoost,
494 and XGBoost proved prohibitively slow on several many-
495 class datasets. Furthermore, we removed four datasets from
496 the global analysis: Adult and Shuttle due to their large size
497 (over 48,000 instances), and cmc and wine, which caused fail-
498 ures or instability for multiple models.

499 3.2 Regression

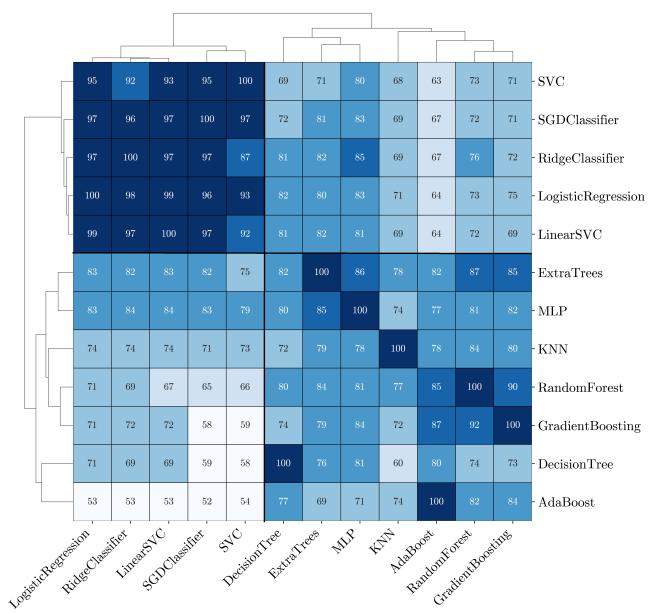
500 We evaluate 31 ML regression models over 15 Regression
501 test cases. We categorize these regression datasets by size ac-
502 cording to the number of samples that they contain: **small** (0
503 to 200 points), **medium** (500 to 4000 points), **big** (4000 to
504 10000), and **very big** (10000 to 40000). For medium datasets,
505 the RMTS and TabPFN models are too costly (more than 10^5
506 seconds) to be tested for more than a few hundred data points
507 or more than 5 variables. For big and very big datasets, we
508 cannot reasonably test the most computationally expensive
509 model. Therefore, we removed IDW, RBF, PCE, CIEL, and
510 KPLS. For very large datasets, we do not allow SVM to use a
511 RBF kernel, as the computing burden would be too great. All
512 the models and datasets operations are similarly seeded to al-
513 low for the replication of the results. To quantify the quality
514 of the explanations, we compute NDCG over each model’s
515 SHAP-value importance ranking in both the regression and
516 classification tasks [Burges *et al.*, 2005]. Note that these im-
517 portance values are limited to their absolute influence and that
518 other metrics taking into account the sign of the influence,
519 such as the Composition of Rank, Influence, and Accuracy
520 described in [Wang *et al.*, 2023], may lead to different results.

521 4 Experimental results

522 To quantify the quality and consistency of model explana-
523 tions, we compute the NDCG over each model’s SHAP-based
524 feature-importance ranking for both regression and classifi-
525 cation tasks [Burges *et al.*, 2005]. In practice, we rely on the
526 automatic option of the shap Python library [Lundberg and
527 Lee, 2019], which adaptively selects among seven approxi-
528 mation techniques instead of computing exact SHAP values.
529 We use NDCG instead of classical rank correlations because
530 it emphasizes agreement among top-ranked features, reflect-
531 ing practical interpretability where only a few features mat-
532 ter; similar trends are observed with Spearman. We empha-
533 size that these importance scores rely only on the absolute
534 magnitude of SHAP values; consequently, alternative met-
535 rics that also account for the direction of influence, such as
536 the Composition of Rank, Influence, and Accuracy proposed
537 in [Wang *et al.*, 2023], could lead to different conclusions.
538 As discussed in Section 2.2, the resulting NDCG matrices
539 are non-symmetric because the normalization depends on the
540 reference model used to compute the ideal ranking. Never-
541 theless, large discrepancies between ρ_{ij}^{NDCG} and ρ_{ji}^{NDCG} in-
542 dicate that two models rank features very differently, provid-



(a) Median agreements for Regression.



(b) Median agreement for Classification.

Figure 1: Median NDCG agreements for the 15 regression and 11 classification datasets.

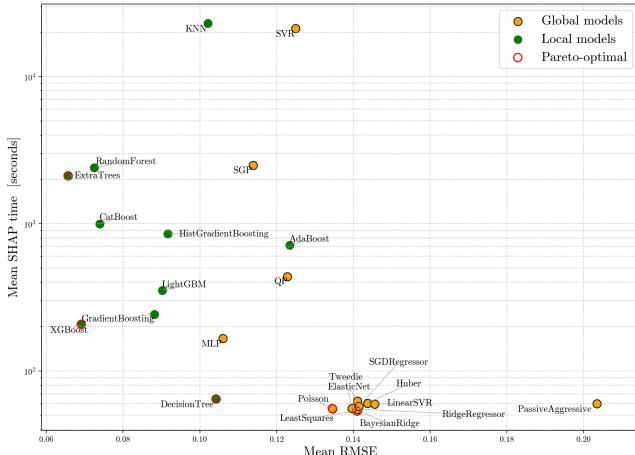
ing an additional implicit measure of model dissimilarity captured in our analyses. To ensure reproducibility, every model and data split is initialized with the same random seed. Figure 1 reports the pairwise median agreements computed on the benchmark problems’ validation sets. Supplementary materials and code are open-source and open-data on our online repository¹.

The SHAP-based NDCG analysis reveals two main subgroups of models. Each subgroup exhibits strong internal agreement and weaker inter-group similarity, suggesting two distinct families of ML models with different explanation patterns: broadly speaking, more **local** versus more **global** models. The first group, shown in the upper left, contains smooth models that perform well in familiar settings but struggle to generalize to broader, unseen patterns due to strong structural or parametric rigidities. Their SHAP explanations primarily reflect data tendencies and structural regularizations. For instance, this “global” group includes kernel-based models along with linear and quadratic models. In contrast, the second group, shown in the lower right, includes models that better capture complex relationships, but may also fit noisy data rather than the underlying mechanisms. Tree-based ensembles tend to be locally sensitive when their structural complexity is high, while neighborhood-based methods are locally sensitive to the sampled data. These results illustrate a practical manifestation of the **no free lunch theorem**: no single model is optimal across all datasets, and different inductive biases lead to systematically different explanation patterns [Lattimore and Hutter, 2013]. A finer-grain analysis is provided in the online Supplementary Material, where more models are considered, and the analysis is repeated for

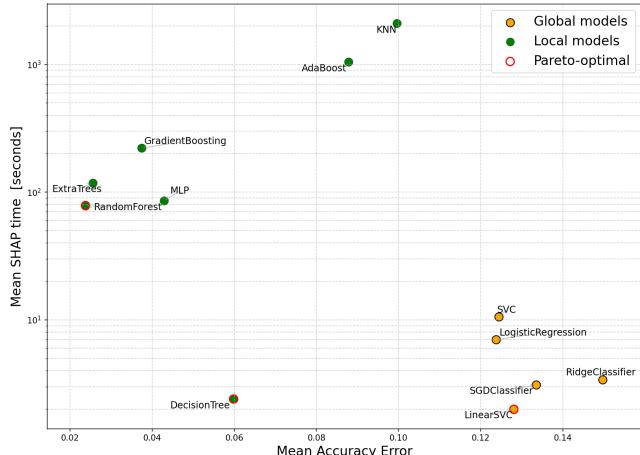
different dataset sizes. Notably, the first separation in the dendrogram — between the two largest blocks — explains roughly 30–60% of the total variance between the explanations of our 46 models, as shown by the dendograms adjacent to the NDCG similarity matrices [Cormack, 1971]. We emphasize that these are median results and that the level of agreement can vary across datasets. In the Supplementary Material, we further apply our methodology to a real-world problem, namely Schelling’s segregation model [Schelling, 1969], for both regression and classification tasks. In this setting, we observe stronger inter-group correlations and a clearer separation between model families. Taken together, these findings suggest that explanation choice and ML model selection should be tailored to the specific dataset and task, rather than relying on any single model, highlighting the importance of systematically evaluating multiple surrogates to obtain robust, informative explanations.

Following the discovery of these two groups of highly similar machine-learning models in terms of post-hoc SHAP explanations, Fig. 2 shows computational time versus RMSE for the models that ran in less than 10^5 seconds (time is plotted on a log scale for readability). Overall, the locally focused models such as ExtraTrees or Random Forest appear Pareto-optimal when high local precision is required, which is consistent with their propensity to overfit. Conversely, the Generalized Linear Model (Poisson) and the simple ordinary least-squares linear regression or Linear Support Vector Machine are Pareto-optimal choices when global trends must be captured quickly. Within the local group, models with lower median agreement also exhibit poorer accuracy and higher RMSE. Agreement is higher on simpler datasets than on more complex ones, suggesting a positive association between explanation agreement and predictive performances, even if the

¹Anonymous: <https://github.com/sub5716ijcai2026/RecoSHAP>



(a) Computational time versus RMSE for Regression datasets.



(b) Computational time versus Accuracy for Classification datasets.

Figure 2: Computational time versus errors for the 15 regression and 11 classification datasets.

607 DecisionTree is a good trade-off thanks to its ability to de-
 608 liver fast explanations. These findings offer practical guid-
 609 ance for selecting surrogate models in ML for post-hoc XAI,
 610 depending on whether regression precision, classification re-
 611 liability, uncertainty calibration, or interpretable explanations
 612 are the primary objectives. For instance, in our experiments,
 613 the nonlinear Support Vector Machine (SVM) explanations
 614 were 400 times slower to compute while exhibiting a simi-
 615 larity of about 95% compared to linear regression, yet they
 616 reduced RMSE by only about 14%. Hence, SVMs may be a
 617 suboptimal choice when explanation cost is a concern. These
 618 results can also be interpreted as a limitation of SHAP and an
 619 argument for alternative or complementary explanation meth-
 620 ods (e.g., LIME [Ribeiro *et al.*, 2016]) or for interpretable-
 621 by-design (ante-hoc) models, since SHAP often reflects ML
 622 models’ behavior more than the underlying data-generating
 623 mechanism [Retzlaff *et al.*, 2024].

624 5 Conclusions and Perspectives

625 We studied the extent to which post-hoc SHAP explanations
 626 agree across a wide range of machine-learning models and
 627 datasets using NDCG as a rank-based similarity measure.
 628 Our analysis reveals that explanations exhibit clear cluster-
 629 ing patterns, broadly separating models with global, smooth
 630 inductive biases from those driven by local, data-dependent
 631 behavior. The main dendrogram split explains a substan-
 632 tial fraction of explanation variance, supporting the practi-
 633 cal notion of **explanation interchangeability** within model
 634 families. We also observe a clear trade-off between pre-
 635 dictive accuracy and explanation cost: tree ensembles typi-
 636 cally achieve lower RMSE but require much more expensive
 637 SHAP computations, whereas simple parametric models are
 638 fast to explain but can underfit complex patterns. Crucially,
 639 we find that SHAP explanations often reflect the ML model
 640 as much as the underlying data-generating process. When
 641 multiple near-optimal models exist (Rashomon sets), explana-
 642 tions can be unstable across model classes, initializations,

643 or data splits, cautioning against treating any single attribu-
 644 tion as definitive evidence of causality. Overall, explanation
 645 agreement depends on both the model and the data: patterns
 646 are visible across tabular benchmarks and become clearer on
 647 structured problems like the Schelling model, underscoring
 648 the need to compare multiple surrogates rather than rely on
 649 a single one. Based on these findings, we recommend: (i)
 650 considering only well-adapted models given the problem and
 651 data at hand, (ii) preferring lightweight parametric models
 652 and using tree ensembles only when strong local predictive
 653 fidelity is required, or for assessing explanation stability via
 654 ensembles, and (iii) evaluating explanations jointly in terms
 655 of rank agreement, computational cost, accuracy, and robust-
 656 ness.

657 Our study opens new perspectives for research and fu-
 658 ture works should (i) validate these patterns on synthetic sys-
 659 tems with known mechanisms (e.g., Lotka–Volterra or SIR
 660 dynamics) and with other post-hoc methods, (ii) compare
 661 multiple explainers to disentangle model versus explainer ef-
 662 fects, (iii) incorporate human evaluation, (iv) develop auto-
 663 mated **explanation-aware** model recommendation systems
 664 (AutoXAI) that jointly optimize accuracy, cost, and stability,
 665 and (v) generalize these findings and methods for time-series
 666 or domain-specific problems. Complementary work such as
 667 EXPO [Plumb *et al.*, 2020] shows that training-time regu-
 668 larization can make models more explanation-friendly. Our
 669 results complement this by demonstrating that **ML model**
 670 **choice alone** can amplify or mitigate explanation variability,
 671 and that strong inter-model agreement can serve as a prac-
 672 tical signal of explanation robustness. In summary, no sin-
 673 gle model provides a uniquely correct explanation. Explan-
 674 ation interchangeability serves as a practical diagnostic: it
 675 reveals when inexpensive surrogate models produce explana-
 676 tions similar to those of complex models, and when explana-
 677 tions are unstable and require caution. Agreement between
 678 explanations reflects robustness across model choices under a
 679 fixed explainer, not access to ground-truth feature relevance.

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