

Operating Systems - Homework 1

[Github repo](#)

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1. File: subata_q1.c:

```
#include "kernel/types.h"
#include "kernel/stat.h"
#include "user/user.h"

int main(void) {
    int p_ptc[2], p_ctp[2];    // ptc = parent-to-child, ctp = child-to-parent
    char byte[1];             // char datatype has size of 1 byte
    int n = 3;                 // no. of times byte gets sent from each side
    int i;

    pipe(p_ptc); //child will read from p_ptc[0], parent will write to p_ptc[1]
    pipe(p_ctp); //parent will read from p_ctp[0], child will write to p_ctp[1]

    if (fork() == 0) {        // child
        close(p_ptc[1]);      // won't write to ptc pipe
        close(p_ctp[0]);     // won't read from ctp pipe

        for (i = 0; i < n; i++)
        {
            read(p_ptc[0], byte, 1);
            printf("child receives: %c\n", byte[0]);

            byte[0] = 'c';
            printf("child sends: %c\n", byte[0]);
            write(p_ctp[1], byte, 1);
        }

        close(p_ctp[1]);
        close(p_ptc[0]);

        sleep(1); //making sure everything is finished printing before exiting
        exit(0);
    } else {                  // parent
        close(p_ptc[0]);     // won't read from ptc pipe
        close(p_ctp[1]);    // won't write to ctp pipe

        for (i = 0; i < n; i++)
        {
            byte[0] = 'p';
            printf("parent sends: %c\n", byte[0]);
            write(p_ptc[1], byte, 1);    // byte sent to child
        }
    }
}
```

```

        read(p_ctp[0], byte, 1);
        printf("parent receives: %c\n", byte[0]);
    }

    close(p_ptc[1]);          // closing remaining pipe ends
    close(p_ctp[0]);

    wait(0);                  // waiting for child
}

exit(0);
}

```

Output:

```

parent sends: p
child receives: p
child sends: c
parent receives: c
parent sends: p
child receives: p
child sends: c
parent receives: c
parent sends: p
child receives: p
child sends: c
parent receives: c

```

2. File: subata_q2.c:

```

#include "kernel/types.h"
#include "kernel/stat.h"
#include "user/user.h"
#include "kernel/fcntl.h"

int main(int argc, char *argv[]) {
    int p[2];

    if (pipe(p) < 0) {
        printf("pipe creation failed\n");
        exit(0);
    }

    int pid = fork();
    if (pid == 0) {           // child
        close(p[0]);          // won't read from pipe
        countsyscalls(p[1]);  // passes p[1] to kernel to write to
        exec(argv[1], argv + 1); // execute the target program
        printf("exec failed\n");
    }
}

```

```

        exit(0);
    } else {
        // parent: read from pipe to count syscalls
        close(p[1]);
        // won't write to pipe

        uint64 buf[1];
        //
        int syscall_counter = 0;

        while (read(p[0], buf, sizeof(buf[0])) > 0) {
            syscall_counter++;
            // while pipe is being written to
        }
        printf("number of system calls made: %d\n", syscall_counter);
        close(p[0]);
        wait(0);
    }

    exit(0);
}

```

File: syscall.c:

```

void
syscall(void)
{
    int num;
    struct proc *p = myproc();

    num = p->trapframe->a7;
    if(num > 0 && num < NELEM(syscalls) && syscalls[num]) {

        // if calling program called countsyscalls
        if(p->syscall_pipe >= 0) {
            struct file *f = p->ofile[p->syscall_pipe];
            if (f) {
                uint64 counter_signal = 1;
                filewrite(f, counter_signal, sizeof(counter_signal));
            }
        }

        // Use num to lookup the system call function for num, call it,
        // and store its return value in p->trapframe->a0
        p->trapframe->a0 = syscalls[num]();
    } else {
        printf("%d %s: unknown sys call %d\n",
            p->pid, p->name, num);
        p->trapframe->a0 = -1;
    }
}

```

Output:

```
$ subata_q2 Myprog
Hello World!
number of system calls made: 15
$ subata_q2 subata_q1
parent sends: p
child receives: p
child sends: c
parent receives: c
parent sends: p
child receives: p
child sends: c
parent receives: c
parent sends: p
child receives: p
child sends: c
parent receives: c
number of system calls made: 121
$ subata_q2 wc
this is a test
for question 2
2 7 30
number of system calls made: 13
```

3. a.
 - Pipes automatically clean themselves up, as opposed to file redirection, where the shell would need to remove the temporary file that is created.
 - Pipes can handle arbitrarily long streams of data. With file redirection, the disk must have enough free space to store all the data.
 - Pipes allow for parallel execution of the different pipeline stages. With file redirection, the first program needs to finish before the next can start.
 - Pipes provide efficient inter-process communication. The reading and writing processes can communicate directly and without delay. With file redirection, there is no real-time communication so it is much less efficient.
- b. The main reason this code cannot be implemented in xv6 is that xv6 is a bare bones operating system with limited functionality, so it does not support the operations required.
 - xv6 has an `ls` command, but it doesn't have options like `-al`
 - xv6 doesn't have a `tr` command