

Least square problems:

Consider the system of equations $Ax = b$. In many applications inconsistent system arise. When a solution is demanded & none exists, the best one can do is to find x that makes Ax as close as possible to b .

Def: If A is an $m \times n$ matrix, $b \in \mathbb{R}^m$, a least-square solution of $Ax = b$ is an $\hat{x} \in \mathbb{R}^n$ such that

$$\|b - A\hat{x}\| \leq \|b - Ax\| \quad \forall x \in \mathbb{R}^n.$$

Theorem: The set of least-square solutions of $Ax = b$ coincides with the nonempty set of solutions of the normal equations $A^T A x = A^T b$.

Note: To find \hat{x} :

$$\hat{x} = (A^T A)^{-1} A^T b$$

Find a least-square solution of the inconsistent system $Ax = b$ for

$$1) \quad A = \begin{bmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 0 \\ 11 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 4 & 0 & 1 \\ 0 & 2 & 1 \end{bmatrix}_{2 \times 3} \begin{bmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{bmatrix}_{3 \times 2} = \begin{bmatrix} 17 & 1 \\ 1 & 5 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 4 & 0 & 1 \\ 0 & 2 & 1 \end{bmatrix}_{2 \times 3} \begin{bmatrix} 2 \\ 0 \\ 11 \end{bmatrix}_{3 \times 1} = \begin{bmatrix} 19 \\ 11 \end{bmatrix}$$

$$(A^T A)^{-1} = \frac{1}{84} \begin{bmatrix} 5 & -1 \\ -1 & 17 \end{bmatrix}$$

$$\hat{x} = (A^T A)^{-1} A^T b$$

$$= \frac{1}{84} \begin{bmatrix} 5 & -1 \\ -1 & 17 \end{bmatrix} \begin{bmatrix} 19 \\ 11 \end{bmatrix} = \frac{1}{84} \begin{bmatrix} 84 \\ 168 \end{bmatrix} = \underline{\underline{\begin{bmatrix} 1 \\ 2 \end{bmatrix}}}$$

$$2] \quad A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 3 \\ 8 \\ 2 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}_{3 \times 4} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix}_{4 \times 3} = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 0 \\ 2 & 0 & 2 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}_{3 \times 4} \begin{bmatrix} 1 \\ 3 \\ 8 \\ 2 \end{bmatrix}_{4 \times 1} = \begin{bmatrix} 14 \\ 4 \\ 10 \end{bmatrix}$$

The augmented matrix for $A^T A x = A^T b$

$$\begin{bmatrix} 4 & 2 & 2 & : & 14 \\ 2 & 2 & 0 & : & 4 \\ 2 & 0 & 2 & : & 10 \end{bmatrix}$$

$$R_2 \rightarrow 2R_2 - R_1$$

$$R_3 \rightarrow 2R_3 - R_1$$

$$\sim \begin{bmatrix} 4 & 2 & 2 & : & 14 \\ 0 & 2 & -2 & : & -6 \\ 0 & -2 & 2 & : & 6 \end{bmatrix}$$

$$R_3 \rightarrow R_3 + R_2$$

$$\sim \begin{bmatrix} 4 & 2 & 2 & : & 14 \\ 0 & 2 & -2 & : & -6 \\ 0 & 0 & 0 & : & 0 \end{bmatrix}$$

$$R[A^T A] = 2 \quad R[A^T A : A^T b] = 2 < \text{no. of unknowns.}$$

\therefore Infinite solutions.

$$4x_1 + 2x_2 + 2x_3 = 14$$

$$2x_2 - 2x_3 = -6$$

Let $x_3 = k$, $k \rightarrow$ arbitrary

$$2x_2 = -6 + 2x_3 = -6 + 2k$$

$$x_2 = -3 + k$$

$$4x_1 + 2(-3 + k) + 2k = 14$$

$$4x_1 - 6 + 4k = 14$$

$$4x_1 = 20 - 4k \Rightarrow x_1 = 5 - k$$

$$\lambda_1 = 5 - k \quad \lambda_2 = -3 + k \quad \lambda_3 = k$$

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$$\therefore \text{The solution } \vec{x} = \begin{bmatrix} 5 \\ -3 \\ 0 \end{bmatrix} + k \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} -3 \\ -1 \\ 0 \\ 2 \\ 5 \\ 1 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 6 & 2 & 2 & 2 \\ 2 & 2 & 0 & 0 \\ 2 & 0 & 2 & 0 \\ 2 & 0 & 0 & 2 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} -3 \\ -1 \\ 0 \\ 2 \\ 5 \\ 1 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 4 \\ -4 \\ 2 \\ 6 \end{bmatrix}$$

$$[A^T A : A^T b] = \begin{bmatrix} 6 & 2 & 2 & 2 & : & 4 \\ 2 & 2 & 0 & 0 & : & -4 \\ 2 & 0 & 2 & 0 & : & 2 \\ 2 & 0 & 0 & 2 & : & 6 \end{bmatrix}$$

$$R_2 \rightarrow 3R_2 - R_1 \quad R_3 \rightarrow 3R_3 - R_1 \quad R_4 \rightarrow 3R_4 - R_1$$

$$[A^T A : A^T b] \sim \begin{bmatrix} 6 & 2 & 2 & 2 & : & 4 \\ 0 & 4 & -2 & -2 & : & -16 \\ 0 & -2 & -4 & -2 & : & 2 \\ 0 & -2 & -2 & 4 & : & 14 \end{bmatrix}$$

$$R_3 \rightarrow 2R_3 + R_2$$

$$R_4 \rightarrow 2R_4 + R_2$$

$$[A^T A : A^T b] \sim \begin{bmatrix} 6 & 2 & 2 & 2 & : & 4 \\ 0 & 4 & -2 & -2 & : & -16 \\ 0 & 0 & 6 & -6 & : & -12 \\ 0 & 0 & -6 & 6 & : & 12 \end{bmatrix}$$

$$R_4 \rightarrow R_4 + R_3$$

$$[A^T A : A^T b] \sim \begin{bmatrix} 6 & 2 & 2 & 2 & : & 4 \\ 0 & 4 & -2 & -2 & : & -16 \\ 0 & 0 & 6 & -6 & : & -12 \\ 0 & 0 & 0 & 0 & : & 0 \end{bmatrix}$$

$$R[A^T A] = R[A^T A : A^T b] = 2 < \text{no of unknowns.}$$

\therefore Infinite solutions.

$$6x_1 + 2x_2 + 2x_3 + 2x_4 = 4$$

$$4x_2 - 2x_3 - 2x_4 = -16$$

$$6x_3 - 6x_4 = -12$$

let $x_4 = k$, $k \rightarrow$ arbitrary

$$6x_3 = -12 + 6k$$

$$x_3 = -2 + k$$

$$4x_2 = 2x_3 + 2x_4 - 16$$

$$= -4 + 2k + 2k - 16 = 4k - 20$$

$$x_2 = k - 5$$

$$6x_1 = 4 - 2x_2 - 2x_3 - 2x_4$$

$$= 4 - 2k + 10 + 4 - 2k - 2k$$

$$= -6k + 18$$

$$x_1 = -k + 3$$

$$\hat{x} = \begin{bmatrix} 3 \\ -5 \\ -2 \\ 0 \end{bmatrix} + k \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$4) \quad A = \begin{bmatrix} -1 & 2 \\ 2 & -3 \\ -1 & 3 \end{bmatrix} \quad b = \begin{bmatrix} 4 \\ 1 \\ 2 \end{bmatrix}$$

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$$A^T A = \begin{bmatrix} -1 & 2 & -1 \\ 2 & -3 & 3 \end{bmatrix}_{2 \times 3} \begin{bmatrix} -1 & 2 \\ 2 & -3 \\ -1 & 3 \end{bmatrix}_{3 \times 2} = \begin{bmatrix} 6 & -11 \\ -11 & 22 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} -1 & 2 & -1 \\ 2 & -3 & 3 \end{bmatrix}_{2 \times 3} \begin{bmatrix} 4 \\ 1 \\ 2 \end{bmatrix}_{3 \times 1} = \begin{bmatrix} -4 \\ 11 \end{bmatrix}$$

$$A^T A x = A^T b$$

$$\begin{bmatrix} 6 & -11 \\ -11 & 22 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -4 \\ 11 \end{bmatrix}$$

$$6x_1 - 11x_2 = -4$$

$$-11x_1 + 22x_2 = +11$$

$$\Rightarrow x_1 = 3 \quad x_2 = 2$$

$$\therefore \hat{x} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$