# Math 2000-B Handout 9: Diagonalizability and Similar Matrices

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## **Exercise 1.**

- (a) A is a  $4 \times 4$  matrix with three eigenvalues. One eigenspace is one-dimensional, and one of the other eigenspaces is two-dimensional. Is it possible that A is not diagonalizable? Justify your answer.
- (b) A is a 7  $\times$  7 matrix with three eigenvalues. One eigenspace is two-dimensional, and one of the other eigenspaces is three-dimensional. Is it possible that A is not diagonalizable? Justify your answer.

#### **■ Exercise 2**.

- (a) Construct a nonzero  $2 \times 2$  matrix that is invertible but not diagonalizable.
- (b) Construct a nondiagonal  $2 \times 2$  matrix that is diagonalizable but not invertible.

# **■ Exercise 3**.

Verify the following statements. The matrices are square.

- (a) if A is both diagonalizable and invertible, then so is  $A^{-1}$ .
- (b) If A is invertible and similar to B, then B is invertible and  $A^{-1}$  is similar to  $B^{-1}$ .
- (c) If A is similar to B, then  $A^2$  is similar to  $B^2$ .
- (d) If B is similar to A and C is similar to A, then B is similar to C.
- (e) If A is diagonalizable and B is similar to A, then B is also diagonalizable.
- (f) If  $B = P^{-1}AP$  and  $\vec{\mathbf{x}}$  is an eigenvector of A corresponding to an eigenvalue  $\lambda$ , then  $P^{-1}\vec{\mathbf{x}}$  is an eigenvector of B corresponding also to  $\lambda$ .

#### **■ Exercise 4**.

Define  $T: \mathbb{R}^3 \to \mathbb{R}^3$  by  $T(\vec{x}) = A\vec{x}$ , where A is a  $3 \times 3$  matrix with eigenvalues 5 and -2. Does there exist a basis  $\mathscr{B}$  for  $\mathbb{R}^3$  such that the  $\mathscr{B}$ -matrix for T is a diagonal matrix? Discuss.

## **■ Exercise 5**.

Let V be a vector space with a basis  $\mathscr{B} = \{\vec{\mathbf{b}}_1, \vec{\mathbf{b}}_2, \dots, \vec{\mathbf{b}}_n\}$  and let W be the same space as V with a basis  $C = \{\vec{\mathbf{c}}_1, \vec{\mathbf{c}}_2, \dots, \vec{\mathbf{c}}_n\}$ , and let I be the identity transformation  $I: V \to W$ . Find the matrix for I relative to  $\mathscr{B}$  and  $\mathscr{C}$ . This is called the change-of-coordinates matrix from  $\mathscr{B}$  to  $\mathscr{C}$ .